# МИНОБРНАУКИ РОССИИ САНКТ-ПЕТЕРБУРГСКИЙ ГОСУДАРСТВЕННЫЙ ЭЛЕКТРОТЕХНИЧЕСКИЙ УНИВЕРСИТЕТ «ЛЭТИ» ИМ. В.И. УЛЬЯНОВА (ЛЕНИНА) Кафедра МО ЭВМ

## ОТЧЕТ

по лабораторной работе №2 по дисциплине «Организация ЭВМ и систем» Тема: Изучение режима адресации и формирования исполнительного адреса.

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# Цель работы.

Изучить работу режимов адресации. Найти и исправить ошибки при компиляции программы. Зафиксировать содержимое используемых регистров и ячеек памяти.

### Задание.

Лабораторная работа 2 предназначена для изучения режимов адресации, использует готовую программу lr2\_comp.asm на Ассемблере, которая в автоматическом режиме выполняться не должна, так как не имеет самостоятельного функционального назначения, а только тестирует режимы адресации. Поэтому ее выполнение должно производиться под управлением отладчика в пошаговом режиме. В программу введен ряд ошибок, которые необходимо объяснить в отчете по работе, а соответствующие команды закомментировать для прохождения трансляции. Необходимо составить протокол выполнения программы в пошаговом режиме отладчика по типу таблицы 1 предыдущей лабораторной работы и подписать преподавателя. На защите студенты должны уметь объяснить результат выполнения каждой команды с учетом используемого вида адресации. Результаты, полученные с помощью отладчика, не являются объяснением, а только должны подтверждать ваши объяснения.

# Выполнение работы.

Вариант 4

vec1 12,11,10,9,5,6,7,8

vec2 -40,-50,40,50,-20,-30,20,30

matr 5,6,7,8,-8,-7,-6,-5,1,2,3,4,-4,-3,-2,-1

Создаем файл lb2\_comp.asm в соответствии с кодом из методического пособия. Меняем оригинальные значения массивов vec1, vec2 и matr в соответствии с вариантом №4 из файла lr2.dat.

```
D:\>masm_LB2_COMP.ASM
Microsoft (R) Macro Assembler Version 5.10
Copyright (C) Microsoft Corp 1981, 1988. All rights reserved.
Object filename [LB2_COMP.OBJ]:
Source listing [NUL.LST1: 1b2 comp.lst
Cross-reference [NUL.CRF]:
LB2_COMP.ASM(50): error A2052: Improper operand type
LB2_COMP.ASM(59): warning A4031: Operand types must match
LB2_COMP.ASM(64): warning A4031: Operand types must match
LB2_COMP.ASM(65): error A2055: Illegal register value
LB2_COMP.ASM(89): error A2046: Multiple base registers
LB2_COMP.ASM(90): error A2047: Multiple index registers
LB2_COMP.ASM(98): error A2006: Phase error between passes
 47784 + 459476 Bytes symbol space free
     2 Warning Errors
     5 Severe Errors
```

Рисунок 1 — результат трансляции файла lb2\_comp.asm

1) mov mem3, [bx]

LB2\_COMP.ASM(50): error A2052: Improper operand type

Вызвана ошибка, так как на месте источника и приемника стоят ячейки памяти.

2) mov cx,vec2[di]

LB2\_COMP.ASM(59): warning A4031: Operand types must match

Попытка записать в регистр размера двух байтов данных размером в 1 байт(так как vec2 определялась директивой DB)

3) mov cx,matr[bx][di]

LB2\_COMP.ASM(64): warning A4031: Operand types must match

Попытка записать в регистр размера двух байтов данных размером в 1 байт(так как matr определялась директивой DB)

4) mov ax,matr[bx\*4][di]

LB2\_COMP.ASM(65): error A2055: Illegal register value

Недопустимое значение регистра

5) mov ax,matr[bp+bx]

LB2\_COMP.ASM(89): error A2046: Multiple base registers

Попытка использовать несколько базовых регистров для адресации

6) mov ax,matr[bp+di+si]

LB2\_COMP.ASM(90): error A2047: Multiple index registers

Попытка превышения количества индексных регистров для адресации

7) Main ENDP

LB2\_COMP.ASM(98): error A2006: Phase error between passes

Комментируем строки содержащие ошибки и удачно транслируем программу без ошибок. Был создан диагностический файл lb2.lst и объектный файл lb2\_fix.obj. Соберем lb2\_fix.exe. Запустим его в отладчике.

- (CS) = 1A0A
- (DS) = 19F5
- (ES) = 19F5
- (SS) = 1A05
- (CX) = 00B0
- (BP) = 0000
- (DX) = 0000

Адрес	Символический код	16-ричный	Содержимое регист	ров и ячеек памяти
Команды	команды	код команды	до выполнения.	После выполнения
0000	Push DS	1E	(AX) = 0000	(AX) = 0000
			(DX) = 0000	(DX) = 0000
			(CX) = 00B0	(CX) = 00B0
			(BX) = 0000	(BX) = 0000
			(DI) = 0000	(DI) = 0000 (DS) =
			(DS) = 19F5	19F5
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0018	(SP) = 0016
			(IP) = 0000	(IP) = 0001

			Stack +0 0000	Stack +0 19F5
0001	Sub AX, AX	2BC0	(AX) = 0000	(AX) = 0000
	,		(DX) = 0000	(DX) = 0000
			(CX) = 00B0	(CX) = 00B0
			(BX) = 0000	(BX) = 0000
			(DI) = 0000	(DI) = 0000 (DS) =
			(DS) = 19F5	19F5
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0016	(SP) = 0016
			(IP) = 0001	(IP) = 0003
			Stack +0 19F5	Stack +0 19F5
0003	Push AX	50	(AX) = 0000	(AX) = 0000
			(DX) = 0000	(DX) = 0000
			(CX) = 00B0	(CX) = 00B0
			(BX) = 0000	(BX) = 0000
			(DI) = 0000	(DI) = 0000 (DS) =
			(DS) = 19F5	19F5
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0016	(SP) = 0014
			(IP) = 0003	(IP) = 0004
			Stack +0 19F5	Stack +0 0000
				Stack +2 19F5
0004	Mov Ax,1A07	B8071A	(AX) = 0000	(AX) = 1A07
			(DX) = 0000	(DX) = 0000
			(CX) = 00B0	(CX) = 00B0
			(BX) = 0000	(BX) = 0000
			(DI) = 0000	(DI) = 0000
			(DS) = 19F5	(DS) = 19F5
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0004	(IP) = 0007
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0007	Mov DS, AX	8ED8	(AX) = 1A07	(AX) = 1A07
			(DX) = 0000	(DX) = 0000
			(CX) = 00B0	(CX) = 00B0
			(BX) = 0000	(BX) = 0000
			(DI) = 0000	(DI) = 0000
			(DS) = 19F5	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0007	(IP) = 0009
			Stack +0 0000	Stack +0 0000

			Stack +2 19F5	Stack +2 19F5
0009	Mov AX, 01F4	B8F401	(AX) = 1A07	(AX) = 01F4
	,		(DX) = 0000	(DX) = 0000
			(CX) = 00B0	(CX) = 00B0
			(BX) = 0000	(BX) = 0000
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0009	(IP) = 000C
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
000C	Mov CX, AX	8BC8	(AX) = 01F4	(AX) = 01F4
			(DX) = 0000	(DX) = 0000
			(CX) = 00B0	(CX) = 01F4
			(BX) = 0000	(BX) = 0000
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 000C	(IP) = 000E
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
000E	Mov BL, 24	B324	(AX) = 01F4	(AX) = 01F4
			(DX) = 0000	(DX) = 0000
			(CX) = 01F4	(CX) = 01F4
			(BX) = 0000	(BX) = 0024
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 000E	(IP) = 0010
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0010	Mov BH, CE	B7CE	(AX) = 01F4	(AX) = 01F4
			(DX) = 0000	(DX) = 0000
			(CX) = 01F4	(CX) = 01F4
			(BX) = 0024	(BX) = CE24
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0010	(IP) = 0012

			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0012	Mov [0002], FFCE	C7060200C	(AX) = 01F4	(AX) = 01F4
			(DX) = 0000	(DX) = 0000
		EFF	(CX) = 01F4	(CX) = 01F4
			(BX) = CE24	(BX) = CE24
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0012	(IP) = 0018
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0018	Mov BX, 0006	BB0600	(AX) = 01F4	(AX) = 01F4
			(DX) = 0000	(DX) = 0000
			(CX) = 01F4	(CX) = 01F4
			(BX) = CE24	(BX) = 0006
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0018	(IP) = 001B
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
001B	Mov [0000], AX	A30000	(AX) = 01F4	(AX) = 01F4
			(DX) = 0000	(DX) = 0000
			(CX) = 01F4	(CX) = 01F4
			(BX) = 0006	(BX) = 0006
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014 (IP) = 001B	(SP) = 0014 (IP) = 001E
			Stack +0 0000	Stack +0 0000
0015	Mov AI [DV]	D 4 0 7	Stack +2 19F5 (AX) = 01F4	Stack +2 19F5 (AX) = 011F
001E	Mov AL, [BX]	BA07	(DX) = 0000	(DX) = 011F (DX) = 0000
			(CX) = 0000	(CX) = 0000 (CX) = 01F4
			(BX) = 0006	(CX) = 01F4 (BX) = 0006
			(DI) = 0000	(DI) = 0000
			(DI) = 0000 (DS) = 1A07	(DI) = 0000 (DS) = 1A07
			(CS) = 1A07	(CS) = 1A0A
			(ES) = 140A	(ES) = 19F5
			(ES) = 19FS (SP) = 0014	(SP) = 19F3
			(31) - 0014	(Sr) = 0014

			(IP) = 001E	(IP) = 0020
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0020	Mov AL, [BX+03]	BA4703	(AX) = 011F	(AX) = 0122
	, ,		(DX) = 0000	(DX) = 0000
			(CX) = 01F4	(CX) = 01F4
			(BX) = 0006	(BX) = 0006
			(DI) = 0000	(DI) = 0000
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0020	(IP) = 0023
			Stack +0 0000	Stack +0 0000
0000	NA CIV [DIV 00]	00 4500	Stack +2 19F5	Stack +2 19F5
0023	Mov CX, [BX+03]	8B4F03	(AX) = 0122	(AX) = 0122
			(DX) = 0000	(DX) = 0000
			(CX) = 01F4	(CX) = 2622
			(BX) = 0006	(BX) = 0006
			(DI) = 0000 (DS) = 1A07	(DI) = 0000 (DS) = 1A07
			(CS) = 1A07	(CS) = 1A0A
			(ES) = 170A (ES) = 19F5	(ES) = 140A (ES) = 19F5
			(SP) = 1515	(SP) = 1515
			(IP) = 0014	(IP) = 0026
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0026	Mov DI, 0002	BF0200	(AX) = 0122	(AX) = 0122
0020	1,10, 51, 0002	210200	(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0006	(BX) = 0006
			(DI) = 0000	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0026	(IP) = 0029
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0029	Mov AL,	BA850E00	(AX) = 0122	(AX) = 01CE
	[000E+D1]		(DX) = 0000	(DX) = 0000
	[000E+DI]		(CX) = 2622	(CX) = 2622
			(BX) = 0006	(BX) = 0006
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5

			(CD) 001.4	(CD) 0014
			(SP) = 0014	(SP) = 0014
			(IP) = 0029	(IP) = 002D
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
002D	Mov BX, 0003	BB0300	(AX) = 01CE	(AX) = 01CE
			(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0006	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 002D	(IP) = 0030
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0030	Mov AL,	8A811600	(AX) = 01CE	(AX) = 01FF
0050	1110,	011011000	(DX) = 0000	(DX) = 0000
	[0016+BX+DI]		(CX) = 2622	(CX) = 2622
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 19F5	(ES) = 19F5
			(SP) = 0014	(SP) = 0014
			(IP) = 0030	(IP) = 0034
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0034	Mov AX, 1A07	B8071A	(AX) = 01FF	(AX) = 1A07
0034	MOV AA, 1AU/	D00/1A	(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 2022	(BX) = 2022
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DI) = 0002 (DS) = 1A07
			` ′	(CS) = 1A0A
			(CS) = 1A0A	(ES) = 1A0A (ES) = 19F5
			(ES) = 19F5	
			(SP) = 0014	(SP) = 0014
			(IP) = 0034	(IP) = 0037
			Stack +0 0000	Stack +0 0000
000=	16 70 4**	OF CO	Stack +2 19F5	Stack +2 19F5
0037	Mov ES, AX	8EC0	(AX) = 1A07	(AX) = 1A07
			(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A

			T	1
			(ES) = 19F5	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(IP) = 0037	(IP) = 0039
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0039	Mov AX, ES:[BX]	268B07	(AX) = 1A07	(AX) = 00FF
			(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(IP) = 0039	(IP) = 003C
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
003C	Mov AX, 0000	B80000	(AX) = 00FF	(AX) = 0000
			(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(IP) = 003C	(IP) = 003F
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
003F	Mov ES, AX	8ECO	(AX) = 0000	(AX) = 0000
			(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 0000
			(SP) = 0014	(SP) = 0014
			(IP) = 003F	(IP) = 0041
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0041	Push DS	1E	(AX) = 0000	(AX) = 0000
			(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07

			(60)	(60) (10)
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 0000	(ES) = 0000
			(SP) = 0014	(SP) = 0012
			(IP) = 0041	(IP) = 0042
			Stack +0 0000	Stack +0 1A07
			Stack +2 19F5	Stack +2 0000
				Stack +4 19F5
0042	Pop ES	07	(AX) = 0000	(AX) = 0000
00.1	- op = 0		(DX) = 0000	(DX) = 0000
			(CX) = 2622	(CX) = 2622
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 0000	(ES) = 1A07
			(SP) = 0012	(SP) = 17107
			(SP) = 0012 (IP) = 0042	(IP) = 0014
			Stack +0 1A07	Stack +0 0000
			Stack +0 1A07 Stack +2 0000	Stack +0 0000 Stack +2 19F5
				Stack +2 19F5
00.40	1.6 021 70 5721	202 1777	Stack +4 19F5	(437) 0000
0043	Mov CX, ES:[BX-	268B4FFF	(AX) = 0000	(AX) = 0000
	01]		(DX) = 0000	(DX) = 0000
	01)		(CX) = 2622	(CX) = FFCE
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(IP) = 0043	(IP) = 0047
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
0047	Xchg AX, CX	91	(AX) = 0000	(AX) = FFCE
			(DX) = 0000	(DX) = 0000
			(CX) = FFCE	(CX) = 0000
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(IP) = 0047	(IP) = 0048
			Stack +0 0000	Stack +0 0000
00.40	Ma DI 0000	DECOC	Stack +2 19F5	Stack +2 19F5
0048	Mov DI, 0002	BF0200	(AX) = FFCE	(AX) = FFCE
			(DX) = 0000	(DX) = 0000
			(CX) = 0000	(CX) = 0000

			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(IP) = 0048	(IP) = 004B
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
004B	Mov ES:[BX+DI],	268901	(AX) = FFCE	(AX) = FFCE
00.2	1,10, 20,[211 21],		(DX) = 0000	(DX) = 0000
	AX		(CX) = 0000	(CX) = 0000
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(IP) = 004B	(IP) = 004E
			Stack +0 0000	Stack +0 0000
			Stack +2 19F5	Stack +2 19F5
004E	Moy DD CD	8BEC	(AX) = FFCE	(AX) = FFCE
004E	Mov BP, SP	ODEC	(DX) = 0000	(DX) = 0000
			(CX) = 0000	(CX) = 0000
			(BX) = 0000	` ′
			(DI) = 0002	(BX) = 0003 (DI) = 0002
				' '
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0014
			(BP) = 0000	(BP) = 0014
			(IP) = 004E	(IP) = 0050
			Stack +0 0000	Stack +0 0000
	- 1 500007		Stack +2 19F5	Stack +2 19F5
0050	Push [0000]	FF360000	(AX) = FFCE	(AX) = FFCE
			(DX) = 0000	(DX) = 0000
			(CX) = 0000	(CX) = 0000
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0014	(SP) = 0012
			(BP) = 0014	(BP) = 0014
			(IP) = 0050	(IP) = 0054
			Stack +0 0000	Stack +0 01F4
			Stack +2 19F5	Stack +2 0000

				Stack +4 19F5
0054	Push [0002]	FF360200	(AX) = FFCE	(AX) = FFCE
			(DX) = 0000	(DX) = 0000
			(CX) = 0000	(CX) = 0000
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0012	(SP) = 0010
			(BP) = 0014	(BP) = 0014
			(IP) = 0054	(IP) = 0058
			Stack +0 01F4	Stack +0 FFCE
			Stack +2 0000	Stack +2 01F4
			Stack +4 19F5	Stack +4 0000
			Stack 1 151 5	Stack +6 19F5
0058	Mov BP, SP	8BEC	(AX) = FFCE	(AX) = FFCE
0030	WIOV DI, SI	ODLC	(DX) = 0000	(DX) = 0000
			(CX) = 0000	(CX) = 0000
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0010	(SP) = 0010
			(BP) = 0014	(BP) = 0010
			(IP) = 0058	(IP) = 005A
			Stack +0 FFCE	Stack +0 FFCE
			Stack +2 01F4	Stack +2 01F4
			Stack +4 0000	Stack +4 0000
			Stack +6 19F5	Stack +6 19F5
005A	Mov DX, [BP+02]	8B5602	(AX) = FFCE	(AX) = FFCE
00511	1,10, 2,11, [21 02]	023002	(DX) = 0000	(DX) = 01F4
			(CX) = 0000	(CX) = 0000
			(BX) = 0003	(BX) = 0003
			(DI) = 0002	(DI) = 0002
			(DS) = 1A07	(DS) = 1A07
			(CS) = 1A0A	(CS) = 1A0A
			(ES) = 1A07	(ES) = 1A07
			(SP) = 0010	(SP) = 0010
			(BP) = 0010	(BP) = 0010
			(IP) = 005A	(IP) = 005D
			Stack +0 FFCE	Stack +0 FFCE
			Stack +2 01F4	Stack +2 01F4
			Stack +4 0000	Stack +4 0000
			Stack +6 19F5	Stack +6 19F5
005D	Ret Far 0002	CA0200	(AX) = FFCE	(AX) = FFCE
ענטט	11Ct 1 at 0002	UA0200	(1111) 1101	(222) 1100

(DX) = 01F4	(DX) = 01F4
(CX) = 0000	(CX) = 0000
(BX) = 0003	(BX) = 0003
(DI) = 0002	(DI) = 0002
(DS) = 1A07	(DS) = 1A07
(CS) = 1A0A	(CS) = 01F4
(ES) = 1A07	(ES) = 1A07
(SP) = 0010	(SP) = 0016
(BP) = 0010	(BP) = 0010
(IP) = 005D	(IP) = FFCE
Stack +0 FFCE	Stack +0 19F5
Stack +2 01F4	
Stack +4 0000	
Stack +6 19F5	

Разработанный программный код см. в приложении А.

# Выводы.

В ходе выполнения работы были изучены режимы адресации и формирования исполнительного адреса.

#### ПРИЛОЖЕНИЕ А

# ИСХОДНЫЙ КОД ПРОГРАММЫ

Название файла: lb2\_fix.asm

```
; Программа изучения режимов адресации процессора IntelX86
EOL EQU '$'
ind EQU 2
n1 EQU 500
n2 EQU -50
; Стек программы
AStack SEGMENT STACK
     DW 12 DUP(?)
AStack ENDS
; Данные программы
DATA SEGMENT
; Директивы описания данных
mem1 DW 0
mem2 DW 0
mem3 DW 0
vec1 DB 12,11,10,9,5,6,7,8
vec2 DB -40, -50, 40, 50, -20, -30, 20, 30
matr DB 5,6,7,8,-8,-7,-6,-5,1,2,3,4,-4,-3,-2,-1
DATA ENDS
; Код программы
CODE SEGMENT
     ASSUME CS:CODE, DS:DATA, SS:AStack
; Головная процедура
Main PROC FAR
     push DS
     sub AX, AX
     push AX
     mov AX, DATA
     mov DS, AX
; ПРОВЕРКА РЕЖИМОВ АДРЕСАЦИИ НА УРОВНЕ СМЕЩЕНИЙ
; Регистровая адресация
     mov ax, n1
     mov cx, ax
     mov bl, EOL
     mov bh, n2
; Прямая адресация
     mov mem2, n2
     mov bx, OFFSET vec1
     mov mem1, ax
; Косвенная адресация
     mov al, [bx]
     ;mov mem3, [bx]
```

```
; Базированная адресация
     mov al, [bx]+3
     mov cx,3[bx]
; Индексная адресация
     mov di, ind
     mov al, vec2[di]
     ;mov cx,vec2[di]
; Адресация с базированием и индексированием
     mov bx,3
     mov al,matr[bx][di]
     ;mov cx,matr[bx][di]
     ;mov ax,matr[bx*4][di]
; ПРОВЕРКА РЕЖИМОВ АДРЕСАЦИИ С УЧЕТОМ СЕГМЕНТОВ
 Переопределение сегмента
; ----- вариант 1
     mov ax, SEG vec2
     mov es, ax
     mov ax, es:[bx]
     mov ax, 0
; ----- вариант 2
     mov es, ax
     push ds
     pop es
     mov cx, es:[bx-1]
     xchg cx, ax
; ----- вариант 3
     mov di,ind
     mov es:[bx+di],ax
; ----- вариант 4
     mov bp, sp
     ;mov ax,matr[bp+bx]
     ;mov ax,matr[bp+di+si]
; Использование сегмента стека
     push mem1
     push mem2
     mov bp, sp
     mov dx,[bp]+2
     ret 2
Main ENDP
CODE ENDS
     END Main
```

### Название файла: LB2.lst

```
#Microsoft
                   (R)
                           Macro
                                     Assembler
                                                   Version
                                                              5.10
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                              ĐŪ ÑŪ ĐŸĐ³ÑŪ Đ°ĐŒĐŒĐ°
                                                   ĐŽĐ·ÑI ÑI ĐụĐœĐŽÑI
Ñ ĐµĐ¶ĐžĐ
                         Ι
                         ntelX86
                              EOL EQU '$'
      = 0024
     = 0002
                              ind EOU 2
     = 01F4
                              n1 EQU 500
      =-0032
                              n2 EOU -50
                         ; Đ¡Ñ-еа Đ¿ÑŪ ĐŸĐ³ÑŪ Đ°ĐŒĐŒÑŪ
      0000
                         AStack SEGMENT STACK
      0000
           000C[
                                  DW 12 DUP(?)
            ????
                     1
      0018
                         AStack ENDS
                         0000
                         DATA SEGMENT
                              Đũ ĐŽÑũ еаÑ-ĐŽĐ²Ñũ
                                                   ПпĐŽÑ·Đ°ĐœĐŽÑŪ
ЎаĐœĐœÑ
                         ΠÑΠ
      0000
           0000
                              mem1 DW 0
      0002
           0000
                              mem2 DW 0
      0004
           0000
                              mem3 DW 0
           0C 0B 0A 09 05 06
                              vec1 DB 12,11,10,9,5,6,7,8
      0006
           07 08
      000E
           D8 CE 28 32 EC E2
                              vec2 DB -40, -50, 40, 50, -20, -30, 20, 30
           14 1E
      0016
           05 06 07 08 F8 F9
                              matr DB 5,6,7,8,-8,-7,-6,-5,1,2,3,4,-
4, -3, -2, -1
           FA FB 01 02 03 04
           FC FD FE FF
      0026
                         DATA ENDS
                         ; ĐŪ ĐŸĐŽ Đ¿ÑŪ ĐŸĐ³ÑŪ Đ°ĐŒĐŒÑŪ
      0000
                         CODE SEGMENT
                              ASSUME CS:CODE, DS:DATA, SS:AStack
                         Main PROC FAR
      0000
      0000
           1E
                              push DS
           2B C0
                                   sub AX, AX
      0001
      0003
           50
                              push AX
           B8 ---- R
                              mov AX, DATA
      0004
           8E D8
                                   mov DS, AX
      0007
```

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0009 B8 01F4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  mov ax, n1
                                                                                                        000C
                                                                                                                                                                                    8B C8
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  mov cx, ax
                                                                                                        000E B3 24
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  mov bl, EOL
                                                                                                        0010 B7 CE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  mov bh, n2
                                                                                                                                                                                                                                                                                                                                                                                                                                                       ; D = \tilde{N} = \tilde
                                                                                                                                                                                                                                                                                                                                                     (R)
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                                                                                        #Microsoft
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 1-2
                                                                                                        0012 C7 06 0002 R FFCE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              mov mem2, n2
                                                                                                        0018 BB 0006 R
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        mov bx, OFFSET vec1
                                                                                                        001B A3 0000 R
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      mov mem1, ax
                                                                                                                                                                                                                                                                                                                                                                                                                                                       ; \partial \mathbb{D} \partial \tilde{\mathbf{N}} \cdot \partial^2 \partial \mathbf{\mu} \partial \hat{\mathbf{n}} \partial 
                                                                                                        001E 8A 07
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov al, [bx]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          mov mem3, [bx]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       Đị аĐ·ĐŽÑ ĐŸĐ²Đ°ĐœĐœĐ°Ñ
аĐŽÑ ĐµÑ·Đ°Ñ ĐŽÑ
                                                                                                        0020 8A 47 03
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov al, [bx]+3
                                                                                                        0023 8B 4F 03
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              mov cx,3[bx]
                                                                                                                                                                                                                                                                                                                                                                                                                                                       ; Đũ ĐœĐŽĐμаÑ·ĐœĐ°Ñũ аĐŽÑũ ĐμÑ·Đ°Ñũ ĐŽÑũ
                                                                                                        0026 BF 0002
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov di,ind
                                                                                                        0029
                                                                                                                                                                                                  8A 85 000E R
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov al, vec2[di]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      mov cx,vec2[di]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 D = D \times N = 
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баĐ·ĐŽÑ ĐŸĐ²Đ°ĐœĐŽĐµĐ
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                                                                                                        002D
                                                                                                                                                                                           BB 0003
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov bx, 3
                                                                                                                                                                                       8A 81 0016 R
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov al,matr[bx][di]
                                                                                                        0030
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        mov cx,matr[bx][di]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          mov ax,matr[bx*4][di]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           Đ Đ Đ Đ Đ Đ Đ Đ Đ Đ
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                       ----- Đ²Đ°ÑŪОаĐœÑ- 1
                                                                                                        0034 B8 ---- R
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          mov ax, SEG vec2
                                                                                                        0037
                                                                                                                                                                                                      8E C0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov es, ax
                                                                                                        0039 26: 8B 07
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          mov ax, es:[bx]
                                                                                                        003C B8 0000
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                mov ax, 0
```

```
; ----- \theta^2\theta^\circ\tilde{N} \theta\check{z}\theta^\circ\theta\tilde{N} 2
                8E C0
        003F
                                                 mov es, ax
        0041
                1E
                                          push ds
        0042
                07
                                          pop es
                26: 8B 4F FF
        0043
                                                 mov cx, es:[bx-1]
        0047
                91
                                          xchg cx, ax
                                   ; ----- \theta^2\theta^\circ\tilde{N} \theta^\star\tilde{D} \theta^\star\tilde{D} \theta^\star\tilde{D} \theta^\star\tilde{D}
        0048
                BF 0002
                                                  mov di,ind
        004B
                26: 89 01
                                          mov es:[bx+di],ax
                                    ; ----- \theta^2\theta^\circ\tilde{N} \theta\check{z}\theta^\circ\theta\tilde{N} 4
        004E 8B EC
                                                 mov bp, sp
                                          mov ax,matr[bp+bx]
                                          mov ax,matr[bp+di+si]
                                                            \tilde{N} \cdot \partial \mu \partial^3 \partial E \partial \mu \partial E \tilde{N} - \partial^\circ \tilde{N}
                                   ·Ñ-еаа
        0050 FF 36 0000 R
                                                  push mem1
       #Microsoft
                           (R)
                                       Macro
                                                     Assembler
                                                                        Version
                                                                                         5.10
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                                                                                         Page
1-3
        0054
              FF 36 0002 R
                                                  push mem2
        0058
                8B EC
                                                  mov bp, sp
        005A 8B 56 02
                                                  mov dx,[bp]+2
        005D
               CA 0002
                                                  ret 2
                                   Main ENDP
        0060
                                   CODE ENDS
        0060
                                          END Main
      #Microsoft
                            (R)
                                                     Assembler
                                                                        Version
                                                                                         5.10
                                       Macro
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                                                                                         Symb
ols-1
       Segments and Groups:
                            Name
                                                 Length
                                                                 Align
                                                                              Combine
Class
       ASTACK . . . . . . . .
                                                         0018 PARA STACK
                                                         0060 PARA NONE
       DATA . . . . . . .
                                                         0026 PARA NONE
       Symbols:
                            Name
                                                 Type Value
                                                                        Attr
                                                                       0024
       E0L
                                                         NUMBER
       IND
                                                         NUMBER
                                                                       0002
              . . . . . . . . . . . . . . .
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	MAIN									F PRO	C	0000	CODE	Length
=	0060													
	MATR									L BYT	Έ	0016	DATA	
	MEM1									L WOR	RD.	0000	DATA	
	MEM2									L WOR	2D	0002	DATA	
	MEM3									L WOR	RD.	0004	DATA	
	N1 .									NUMBE	R	01F4		
	N2 .									NUMBE	R	-0032		
											_			
	VEC1										_	0006		
	VEC2									L BYT	E	000E	DATA	
												_		
	@CPU													
		@FILENAME								TEXT	LB2_	FIX		
	@VERS	SIC	N							TEXT	510			

100 Source Lines

100 Total Lines

19 Symbols

47806 + 459454 Bytes symbol space free

0 Warning Errors
0 Severe Errors