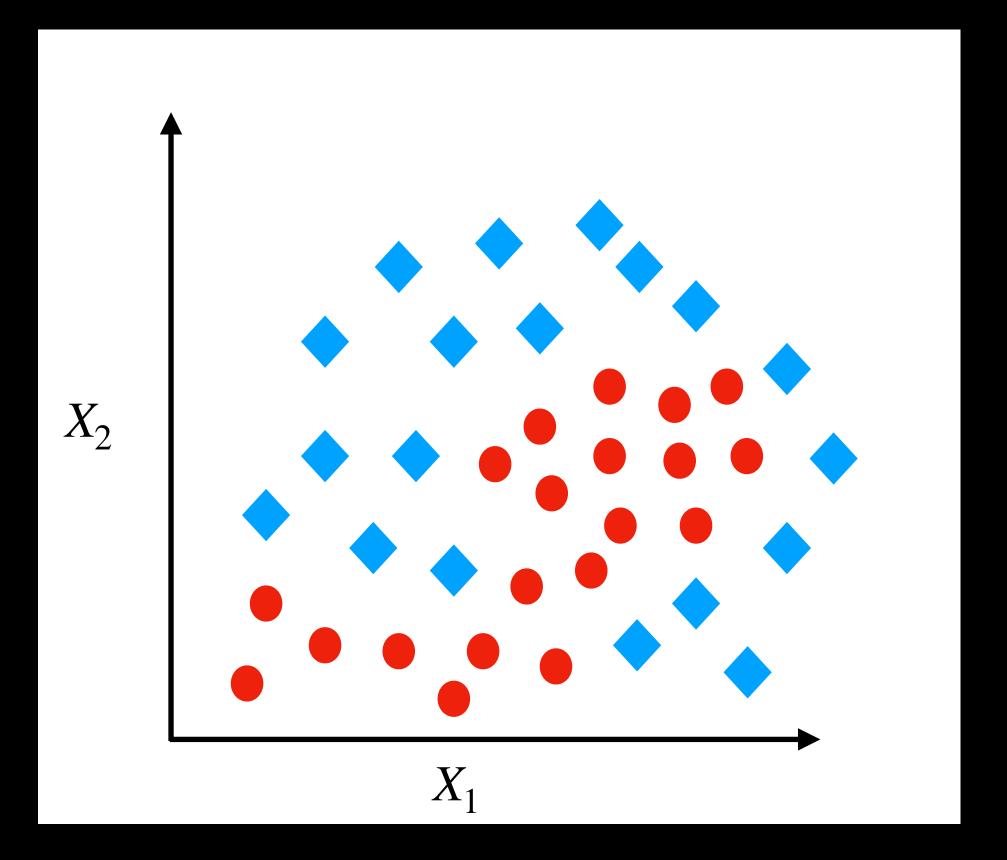
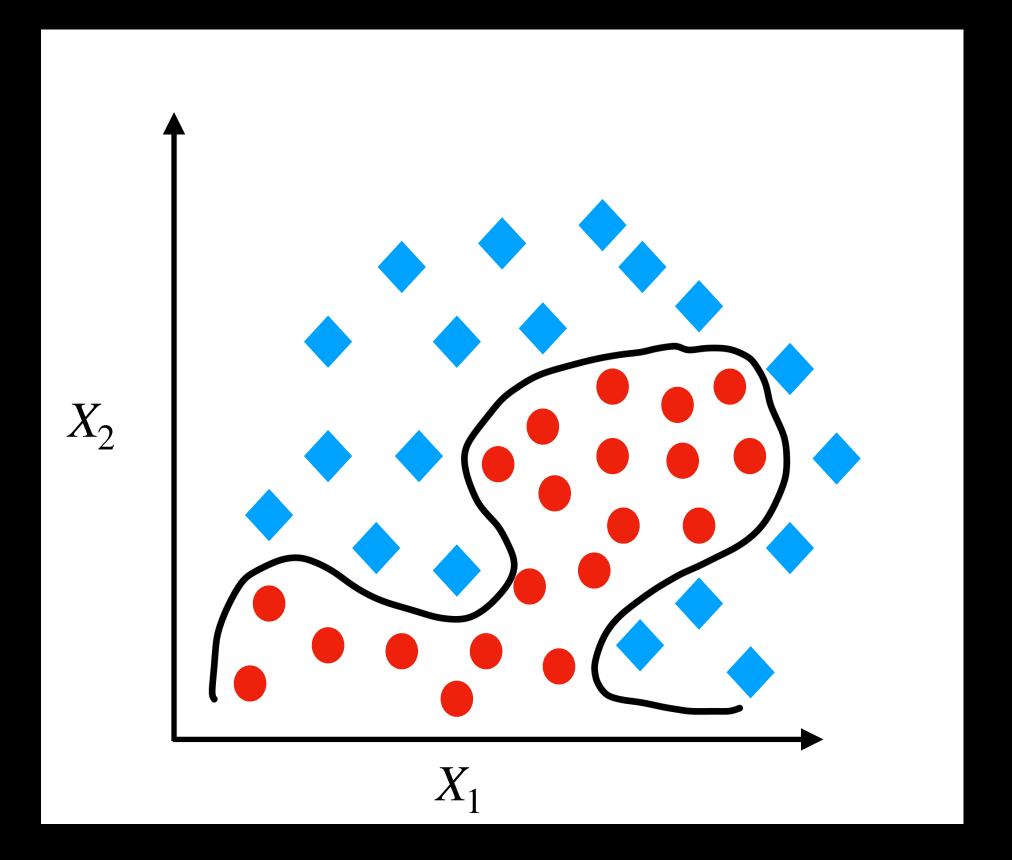
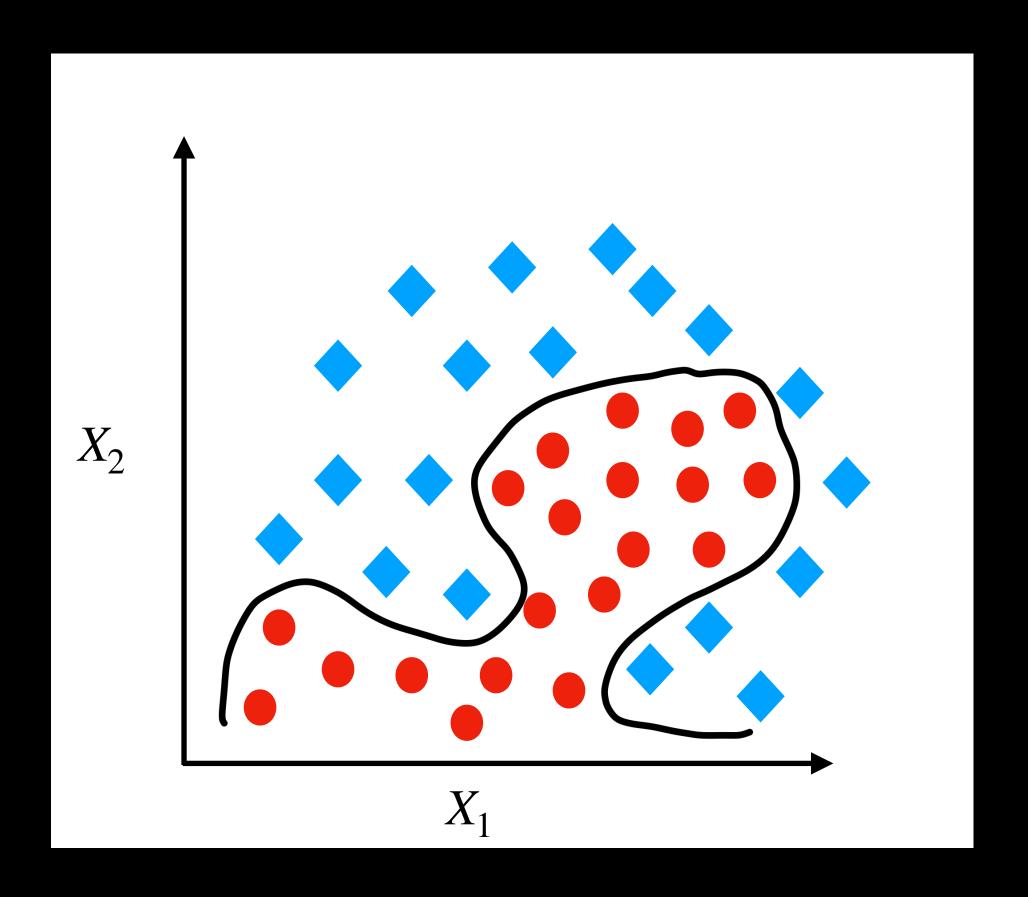
#### Neural Networks

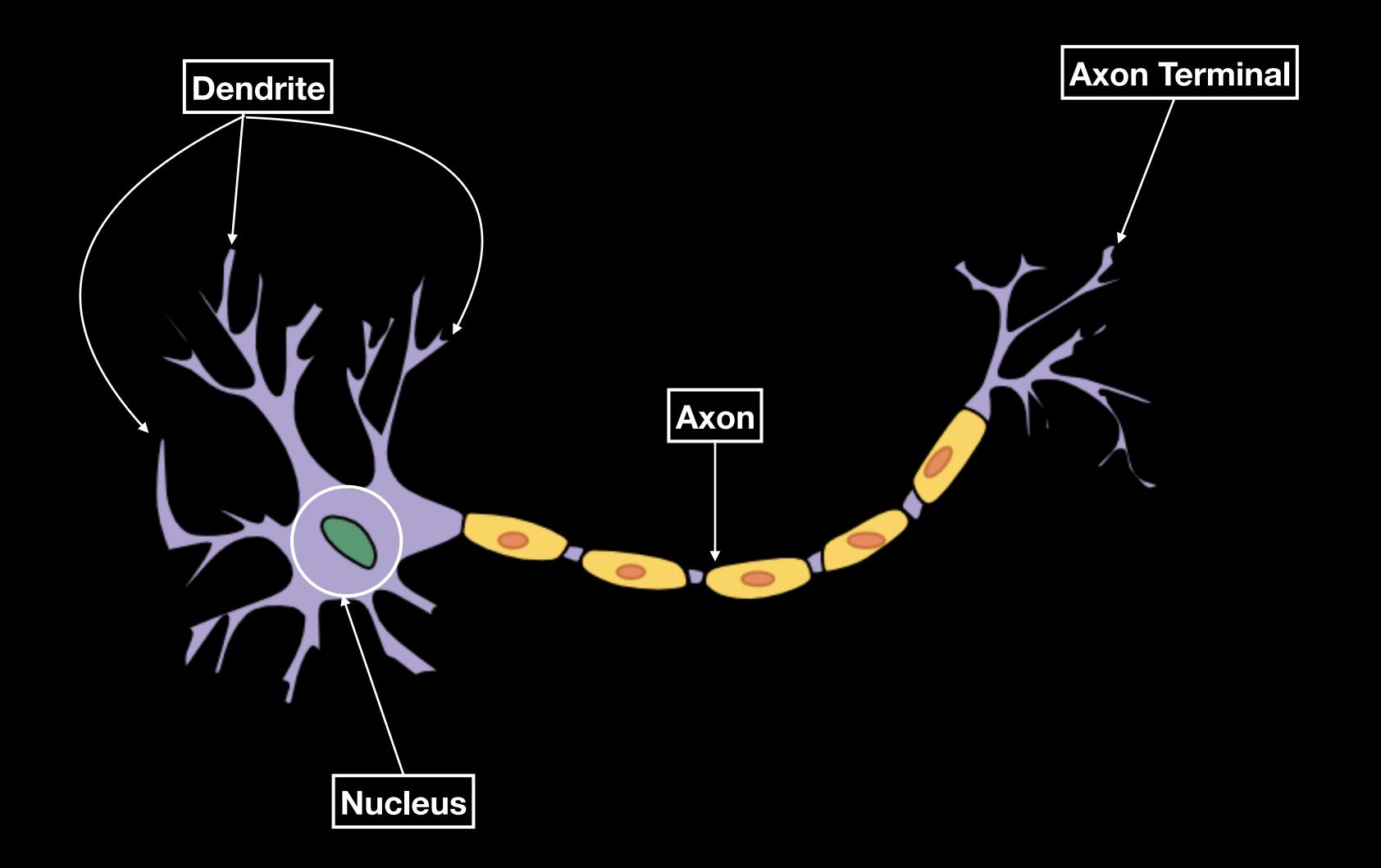


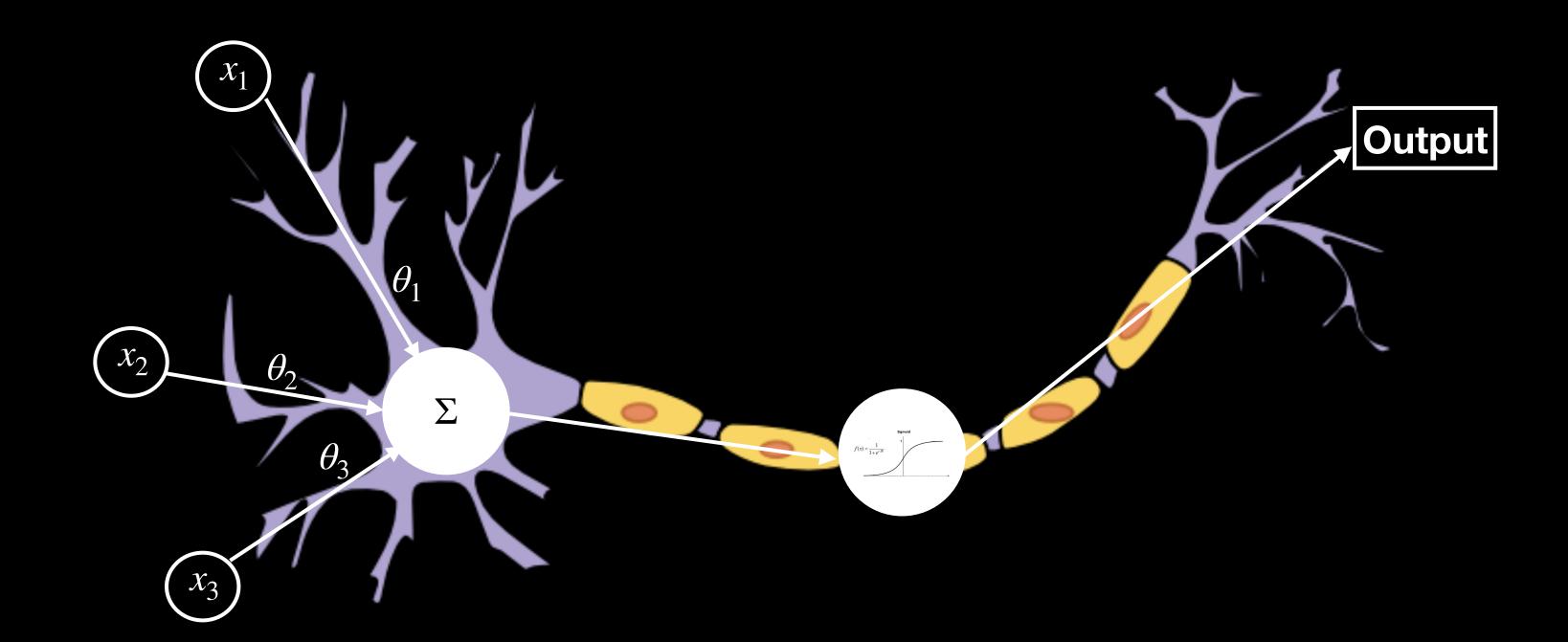


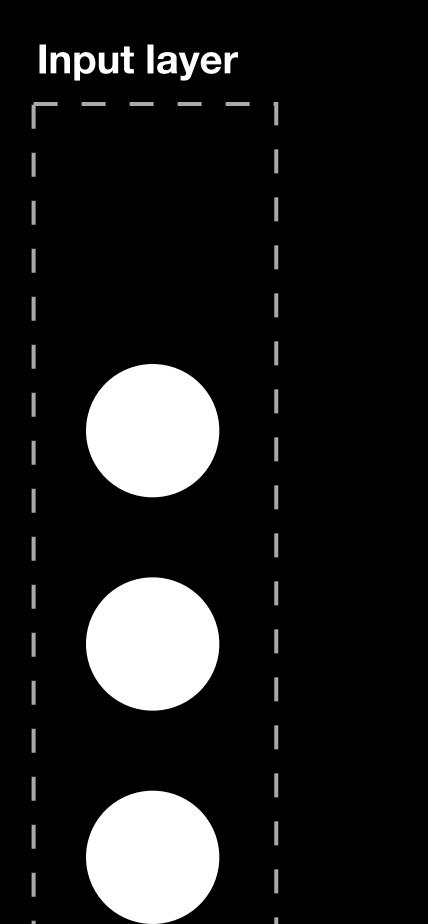


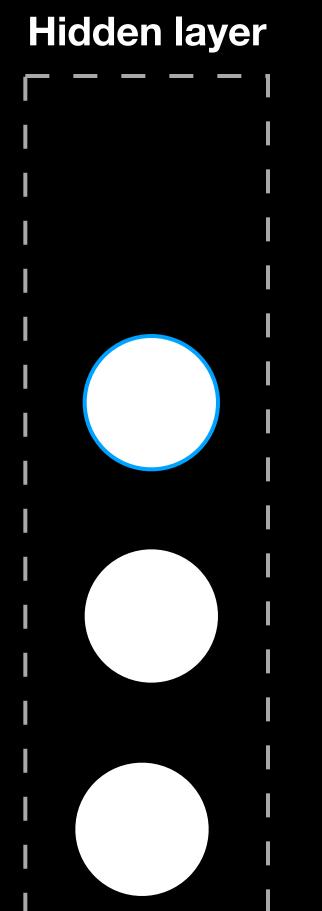
$$y = aX_1 + bX_2 + cX_1X_2 + fX_1^3X_2^4 + \dots$$

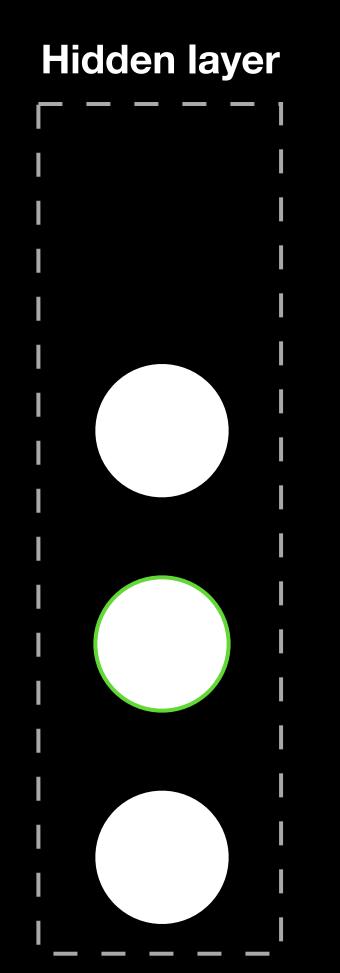


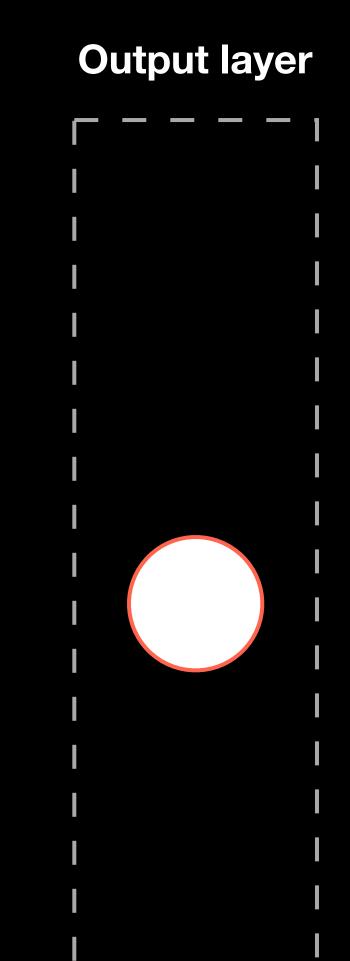




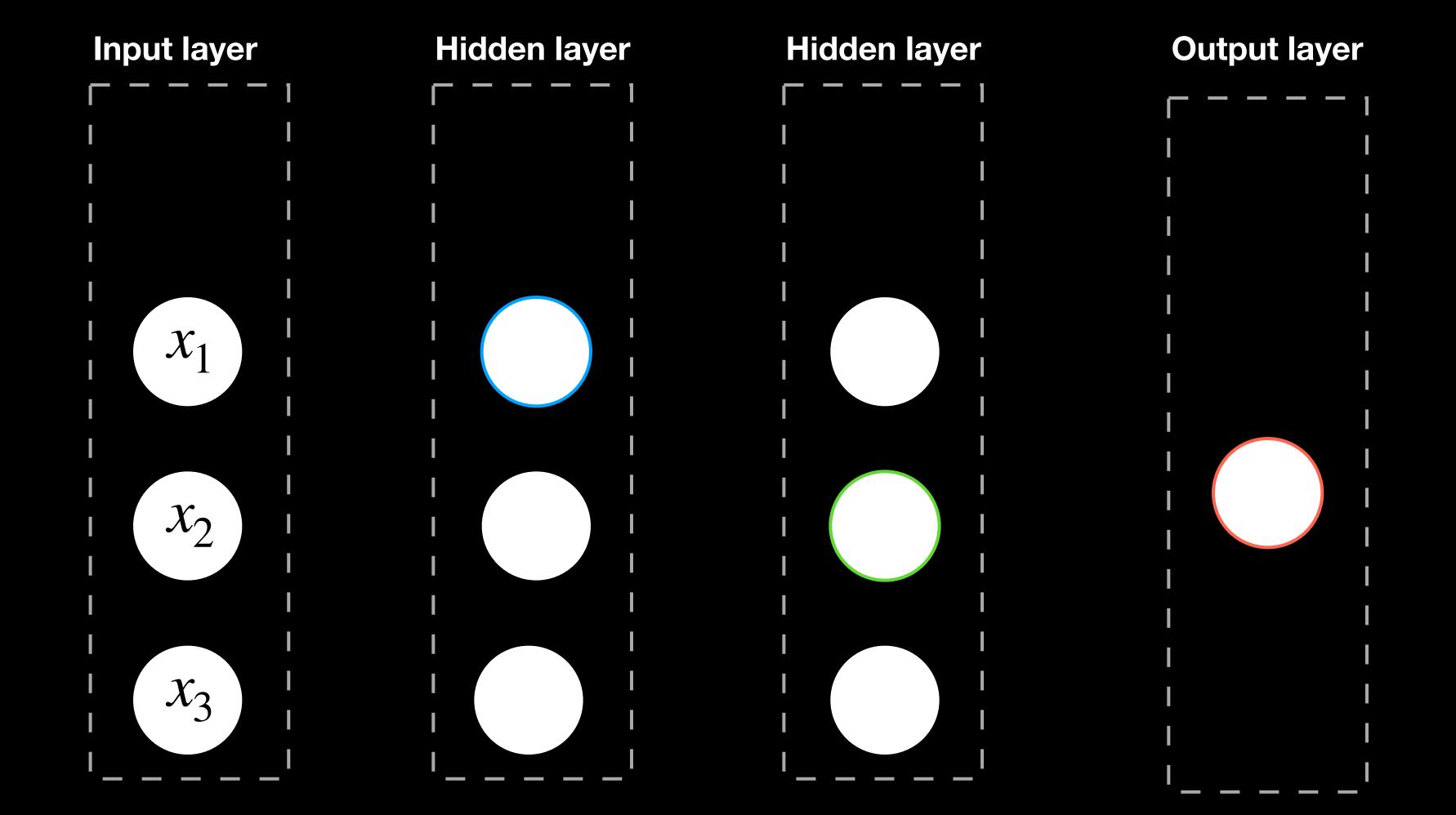




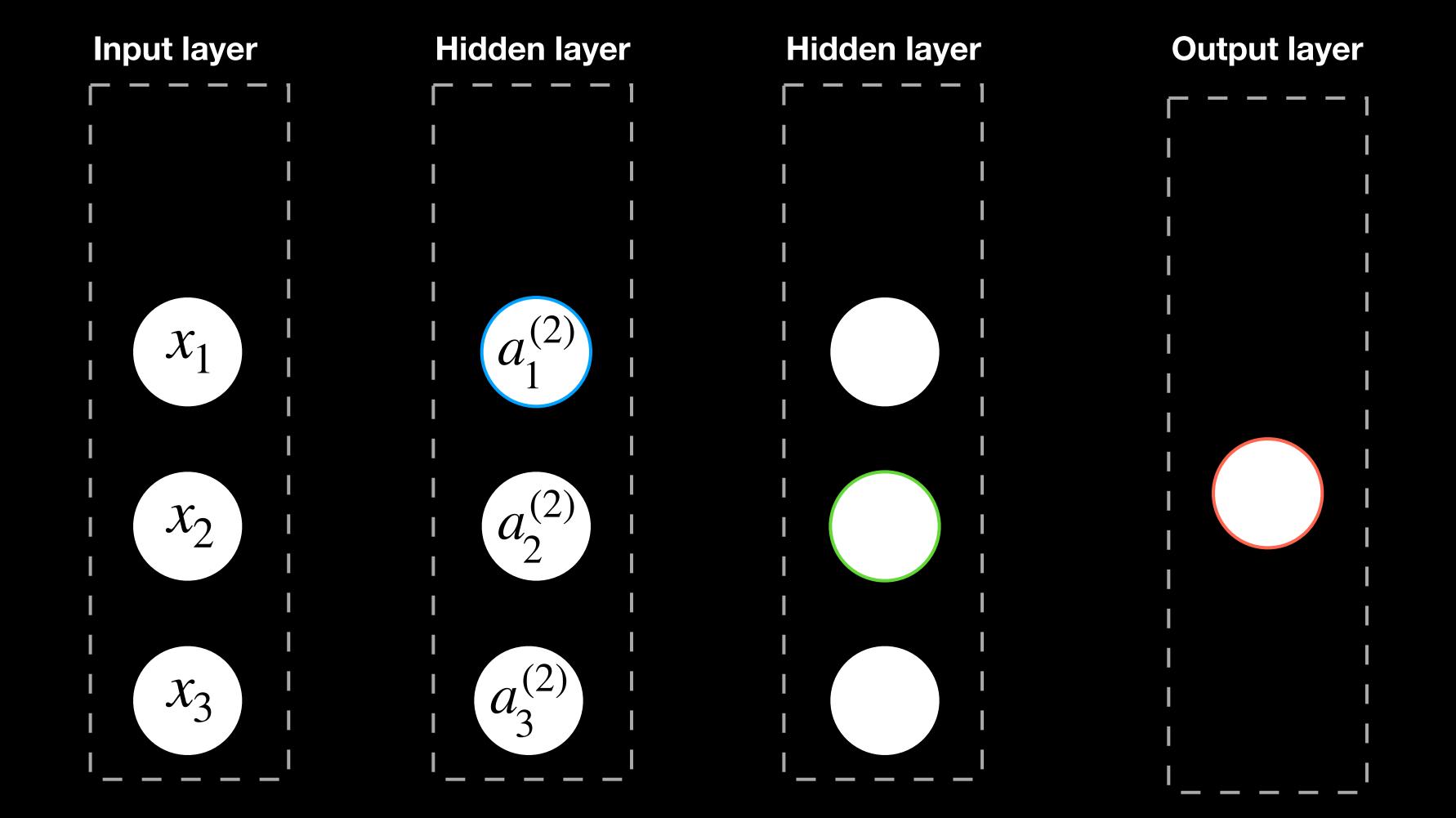




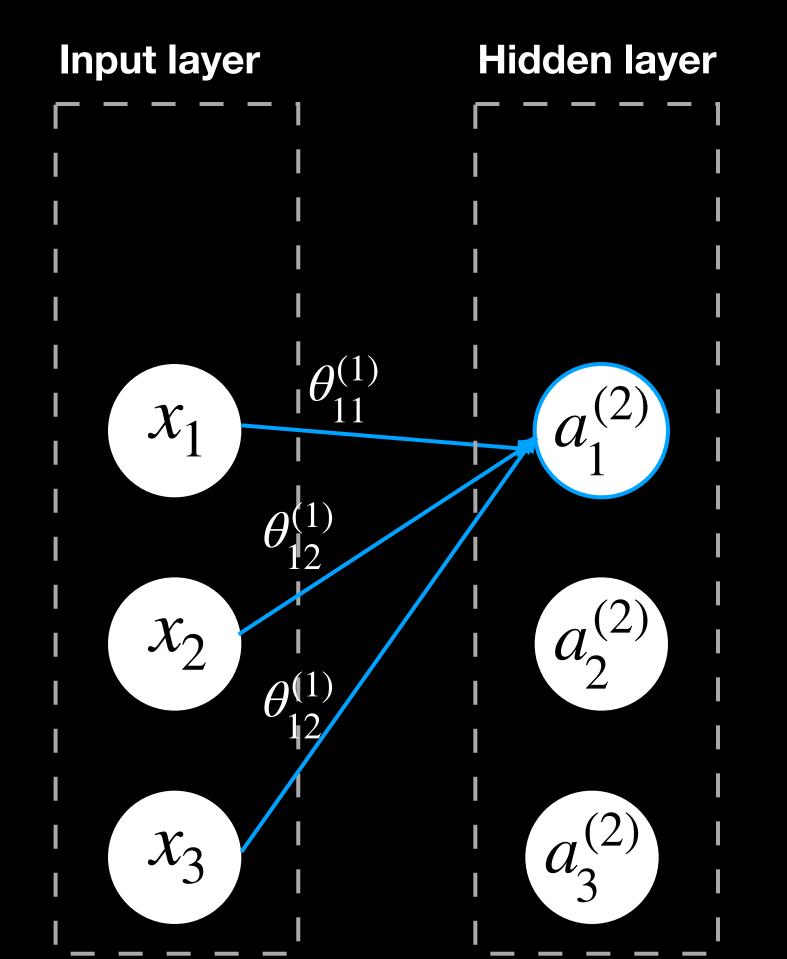
$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

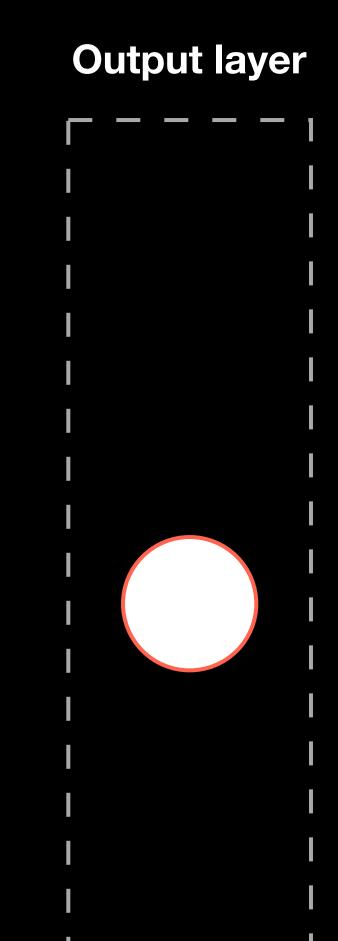


$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

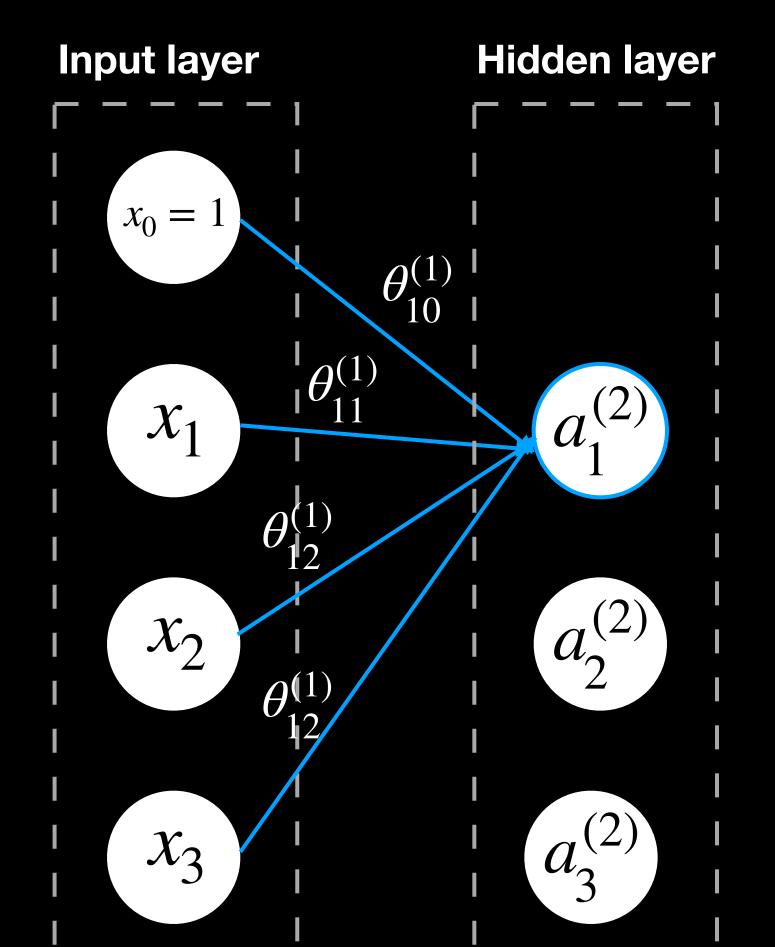


$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$





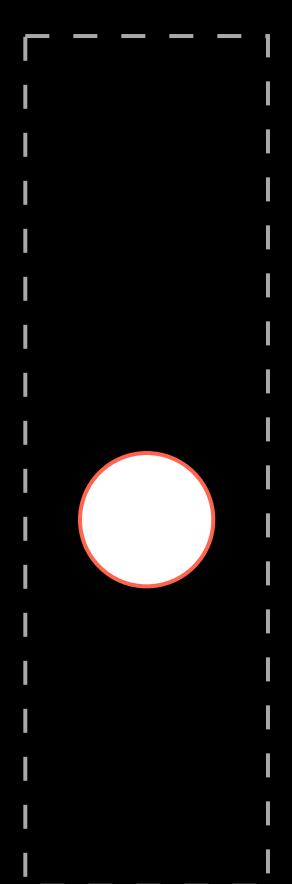
$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$



$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

#### Output layer

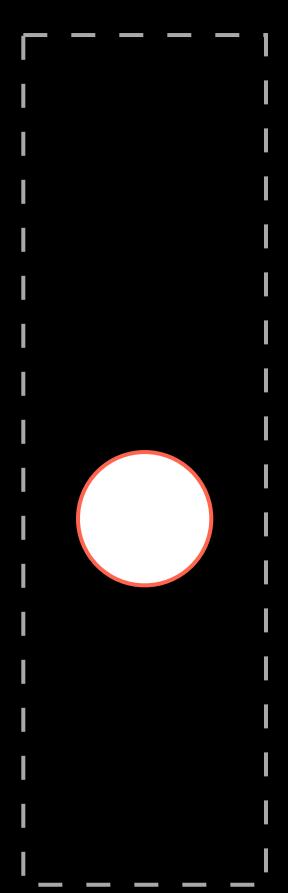


$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

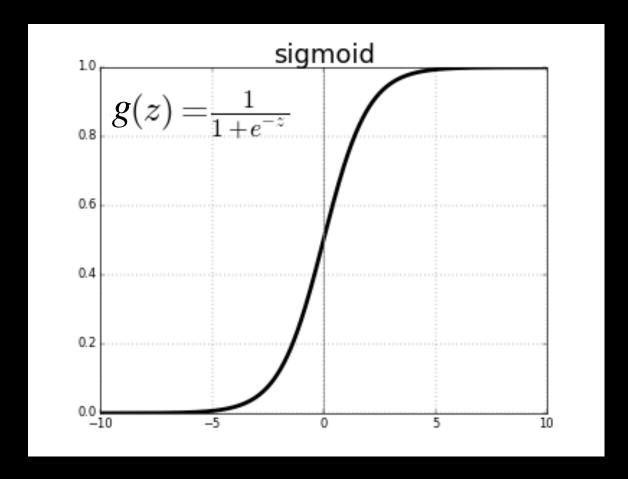
Input layer Hidden layer

$$x_0 = 1$$
 $x_0 = 1$ 
 $x_0 =$ 

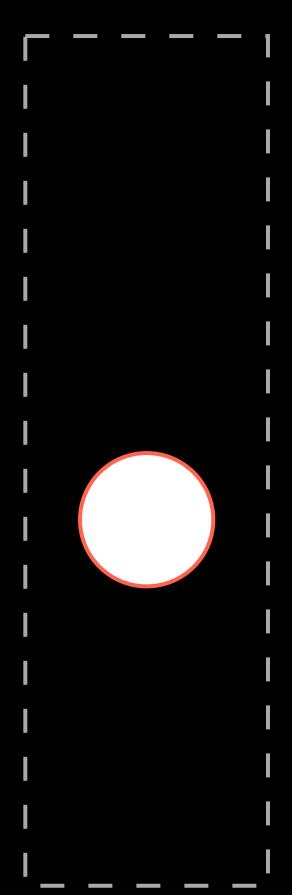
$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$



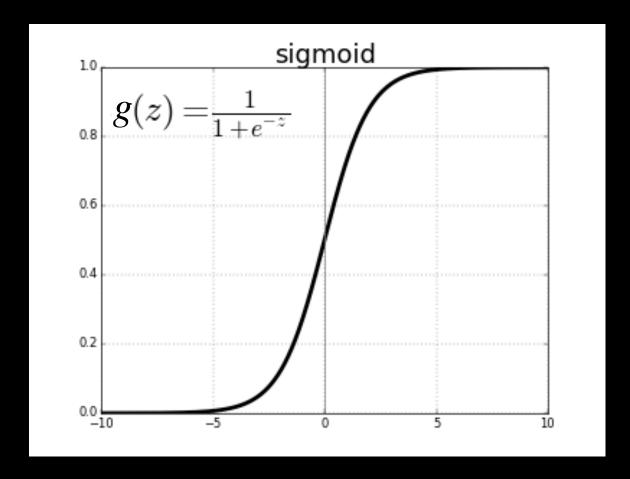
$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$



$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

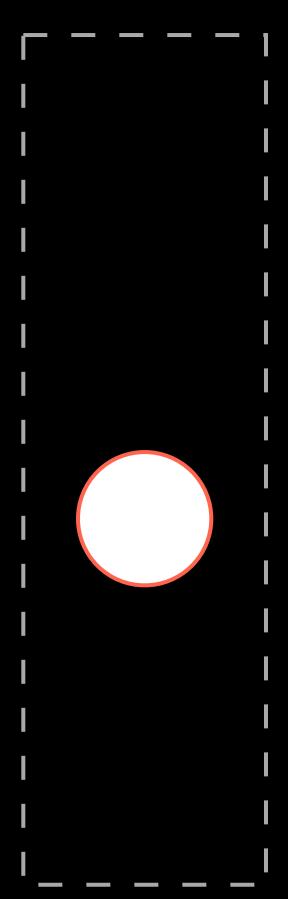


$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

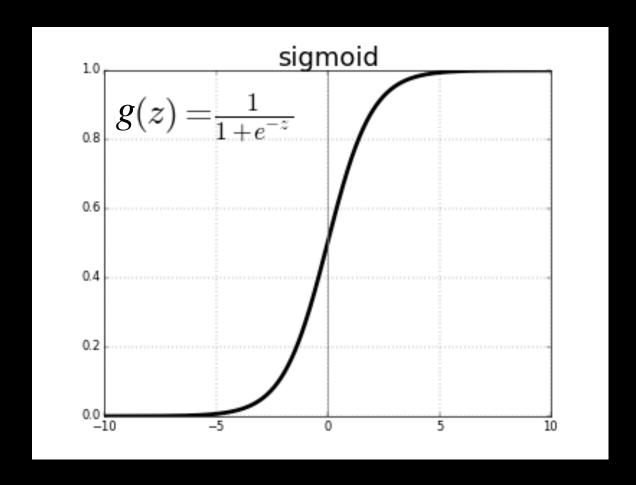


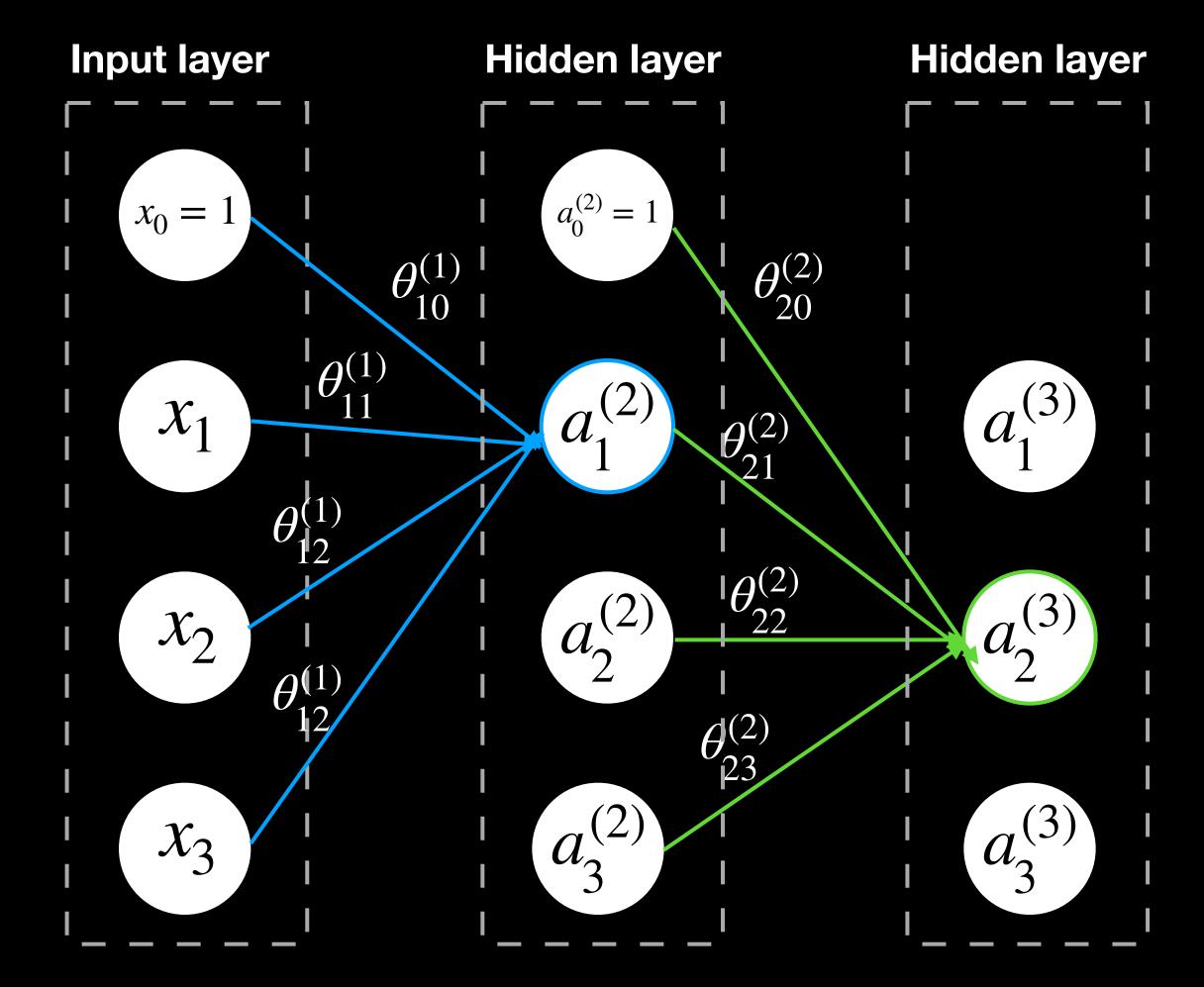
Input layer Hidden layer Hidden layer 
$$x_0 = 1$$
  $x_0 = 1$   $x_0 =$ 

$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

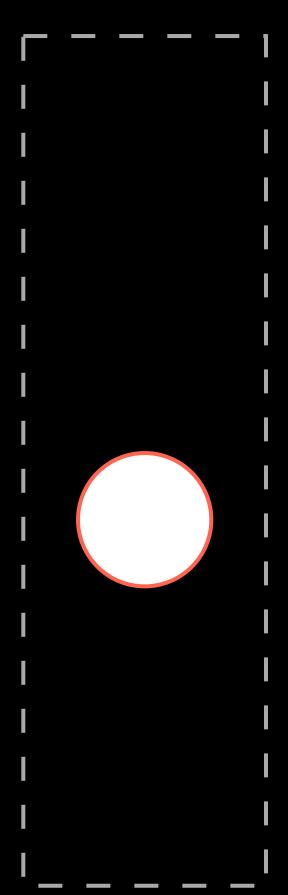


$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

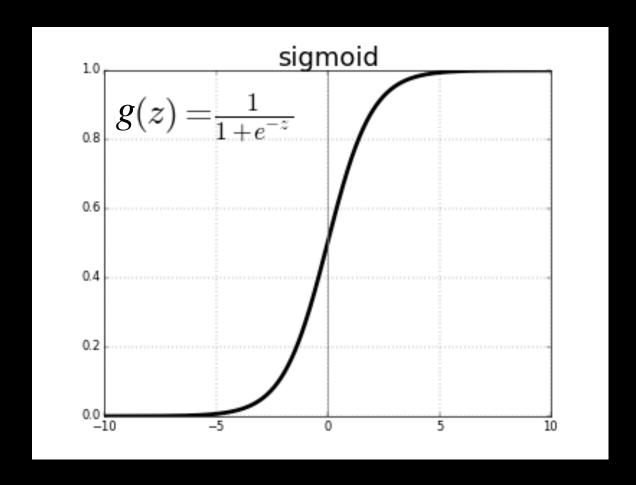




$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$



$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

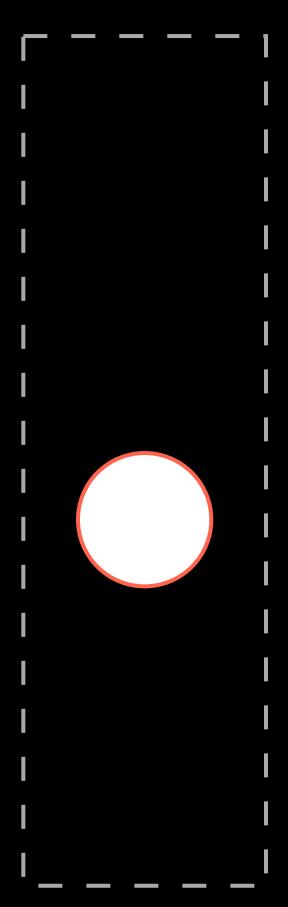


Input layer Hidden layer Hidden layer 
$$x_0 = 1$$
  $a_0^{(2)} = 1$   $a_0^{(2)} =$ 

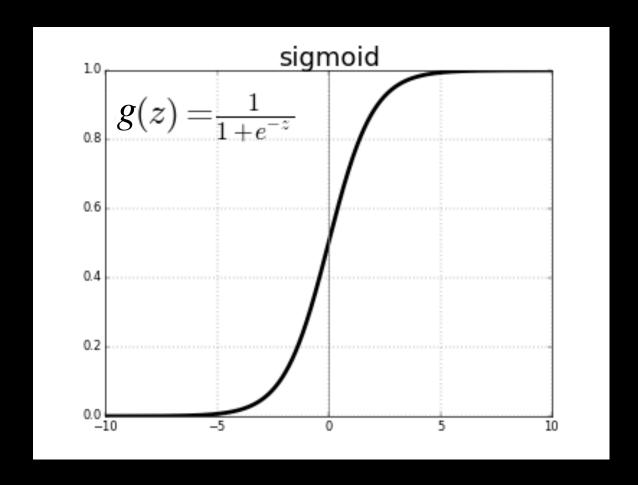
$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

$$a_2^{(3)} = g\left(\theta_{20}^{(2)}a_0^{(2)} + \theta_{21}^{(2)}a_1^{(2)} + \theta_{22}^{(2)}a_2^{(2)} + \theta_{23}^{(2)}a_3^{(2)}\right) = g\left(z_2^{(3)}\right)$$

#### Output layer



$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

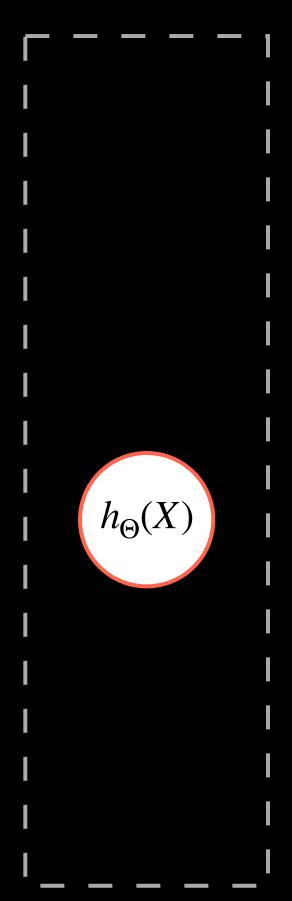


Input layer Hidden layer Hidden layer 
$$x_0 = 1$$
 |  $a_0^{(2)} = 1$  |  $a_0^{(2)} = 1$ 

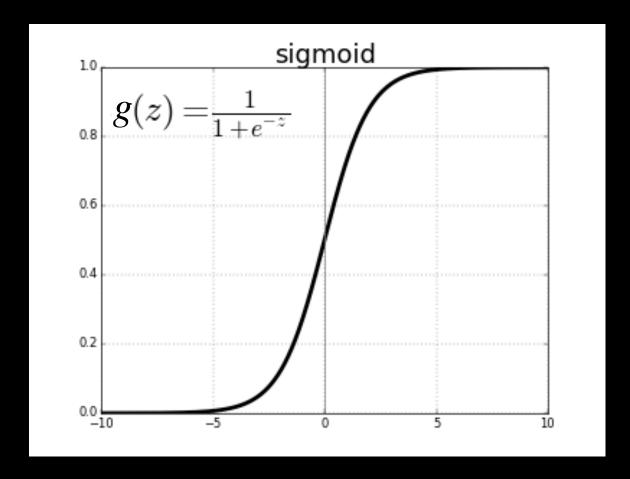
$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

$$a_2^{(3)} = g\left(\theta_{20}^{(2)}a_0^{(2)} + \theta_{21}^{(2)}a_1^{(2)} + \theta_{22}^{(2)}a_2^{(2)} + \theta_{23}^{(2)}a_3^{(2)}\right) = g\left(z_2^{(3)}\right)$$

#### Output layer



$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

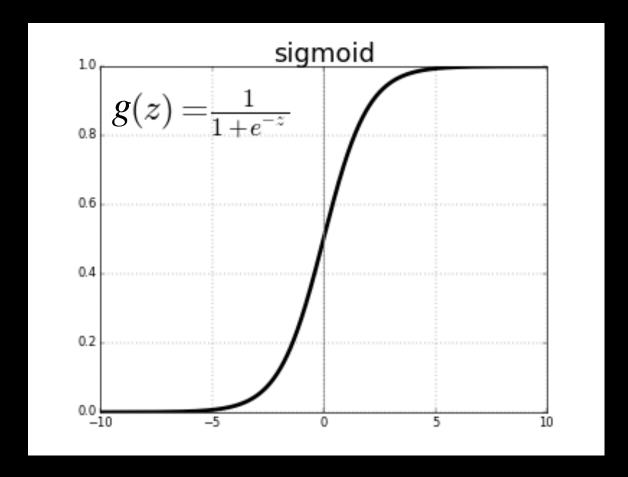


Input layer Hidden layer Hidden layer Output layer 
$$x_0 = 1$$
  $x_0 = 1$   $x_0$ 

$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

$$a_2^{(3)} = g\left(\theta_{20}^{(2)}a_0^{(2)} + \theta_{21}^{(2)}a_1^{(2)} + \theta_{22}^{(2)}a_2^{(2)} + \theta_{23}^{(2)}a_3^{(2)}\right) = g\left(z_2^{(3)}\right)$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

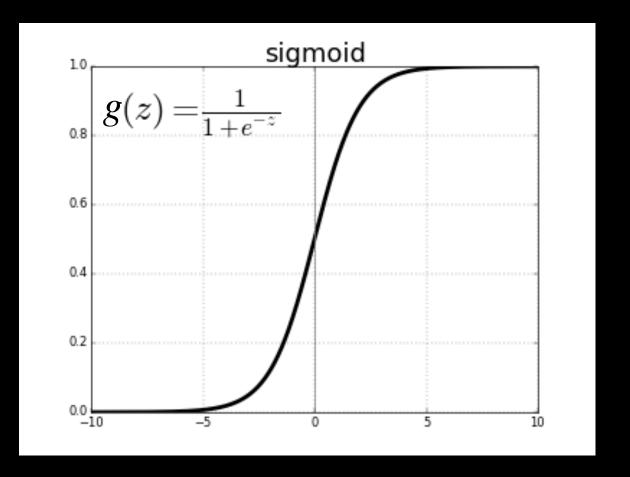


Input layer Hidden layer Hidden layer Output layer 
$$x_0 = 1$$
  $x_0 = 1$   $x_0$ 

$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

$$a_2^{(3)} = g\left(\theta_{20}^{(2)}a_0^{(2)} + \theta_{21}^{(2)}a_1^{(2)} + \theta_{22}^{(2)}a_2^{(2)} + \theta_{23}^{(2)}a_3^{(2)}\right) = g\left(z_2^{(3)}\right)$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$



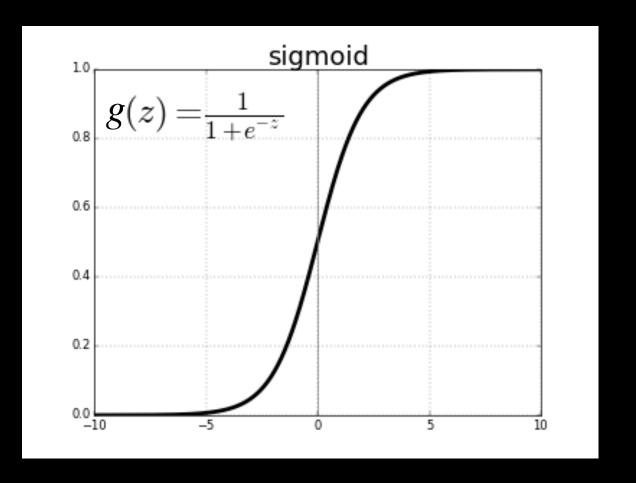
Input layer Hidden layer Hidden layer Output layer 
$$x_0 = 1$$
  $x_0 = 1$   $x_0$ 

$$a_1^{(2)} = g\left(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3\right) = g\left(z_1^{(2)}\right)$$

$$a_2^{(3)} = g\left(\theta_{20}^{(2)}a_0^{(2)} + \theta_{21}^{(2)}a_1^{(2)} + \theta_{22}^{(2)}a_2^{(2)} + \theta_{23}^{(2)}a_3^{(2)}\right) = g\left(z_2^{(3)}\right)$$

$$h_{\Theta}(X) = g\left(\theta_{10}^{(3)}a_0^{(3)} + \theta_{11}^{(3)}a_1^{(3)} + \theta_{12}^{(3)}a_2^{(3)} + \theta_{13}^{(3)}a_3^{(3)}\right) = g\left(z^{(4)}\right)$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

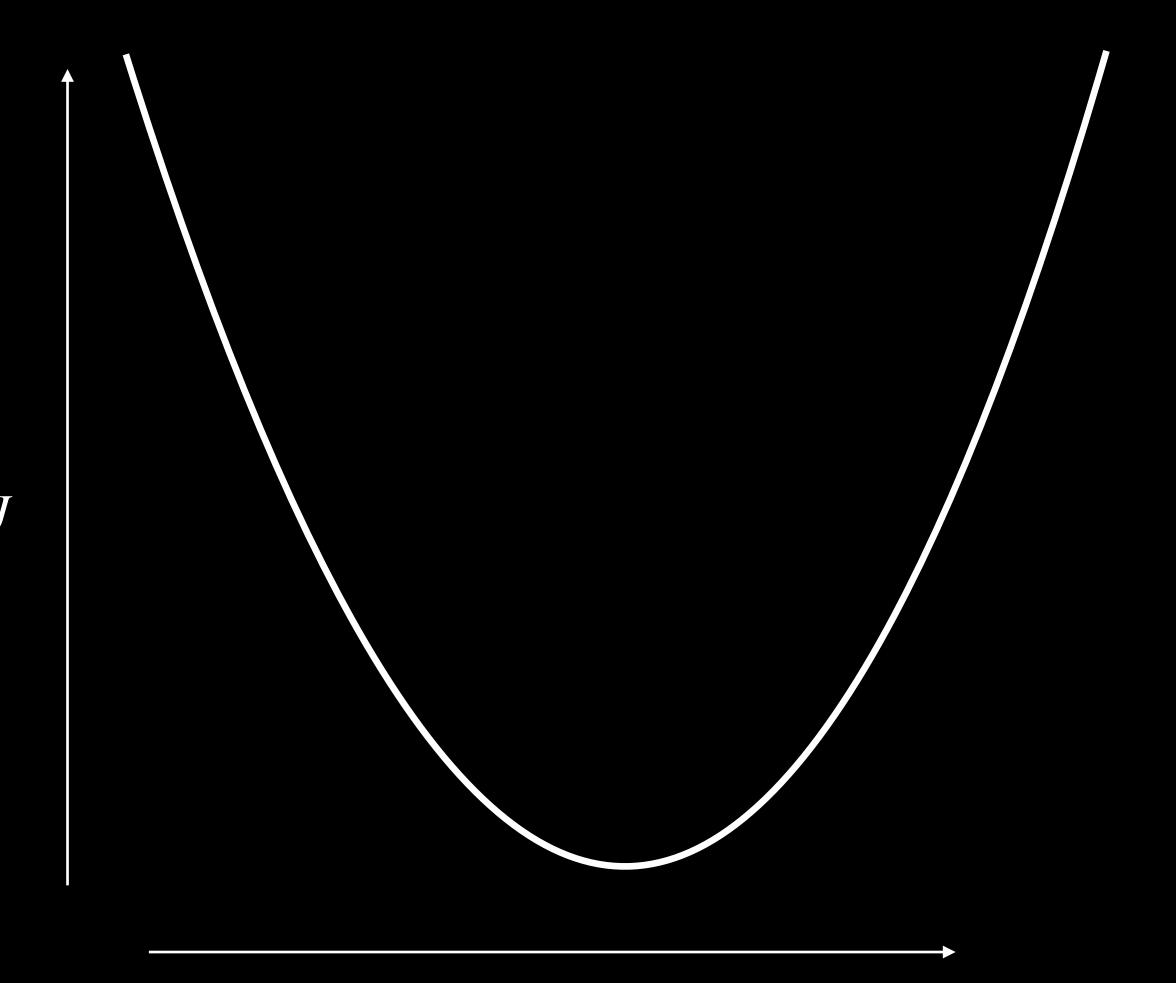


#### Cost Function

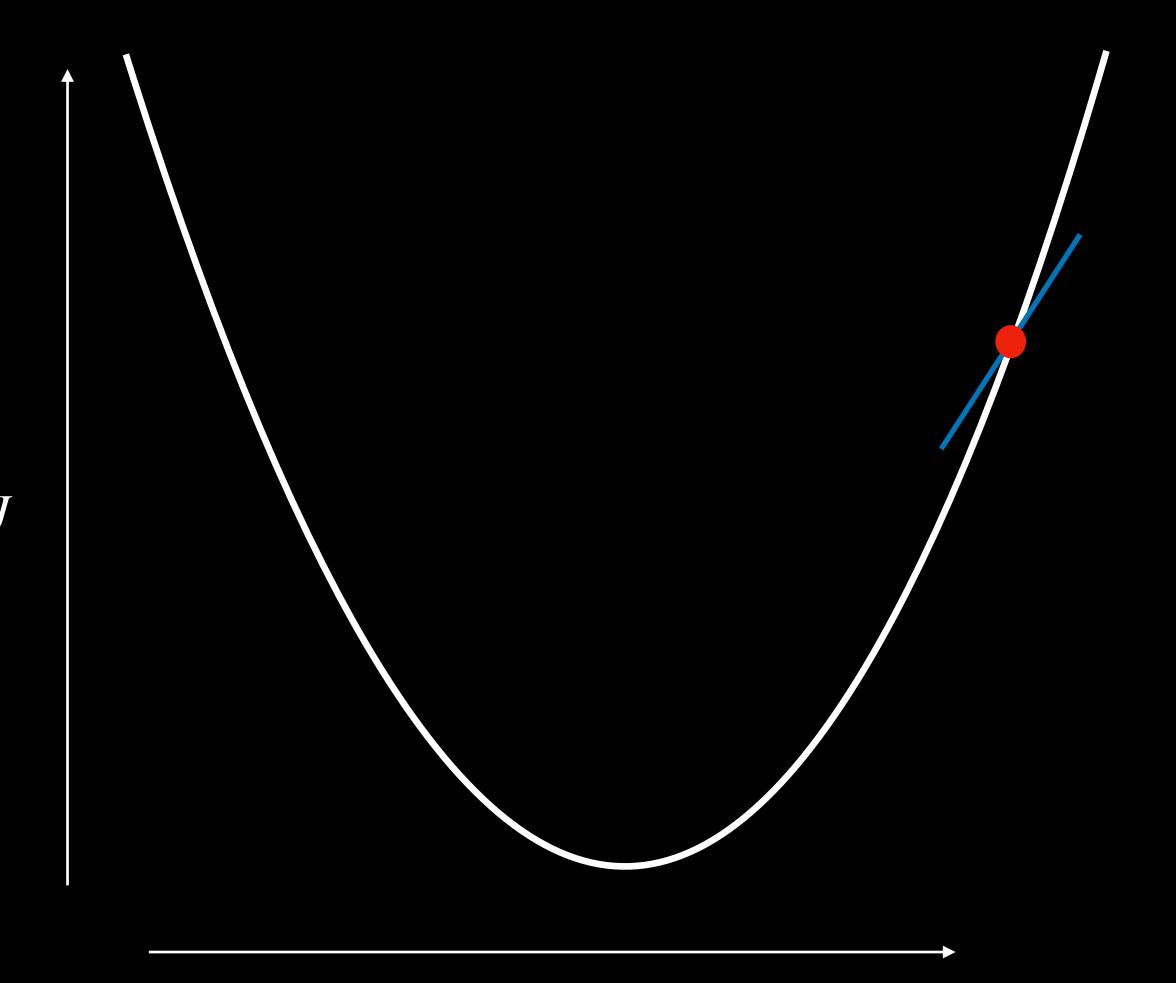
$$J(\Theta) = -\frac{1}{m} \left[ \sum_{i=1}^{m} \sum_{k=1}^{K} y_k^{(i)} \log \left( h_{\Theta} \left( x^{(i)} \right) \right)_k + \left( 1 - y_k^{(i)} \right) \log \left( 1 - h_{\Theta} \left( x^{(i)} \right) \right)_k \right] + \frac{\lambda}{2m} \sum_{l=1}^{K-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} \left( \theta_{ji}^{(l)} \right)^2$$

- *m* is the number of inputs
- *K* is the number of classes
- L is the number of layers in network
- $s_l$  is the number of units in the layer l (not including bias unit)
- $\lambda$  is the regularisation parameter

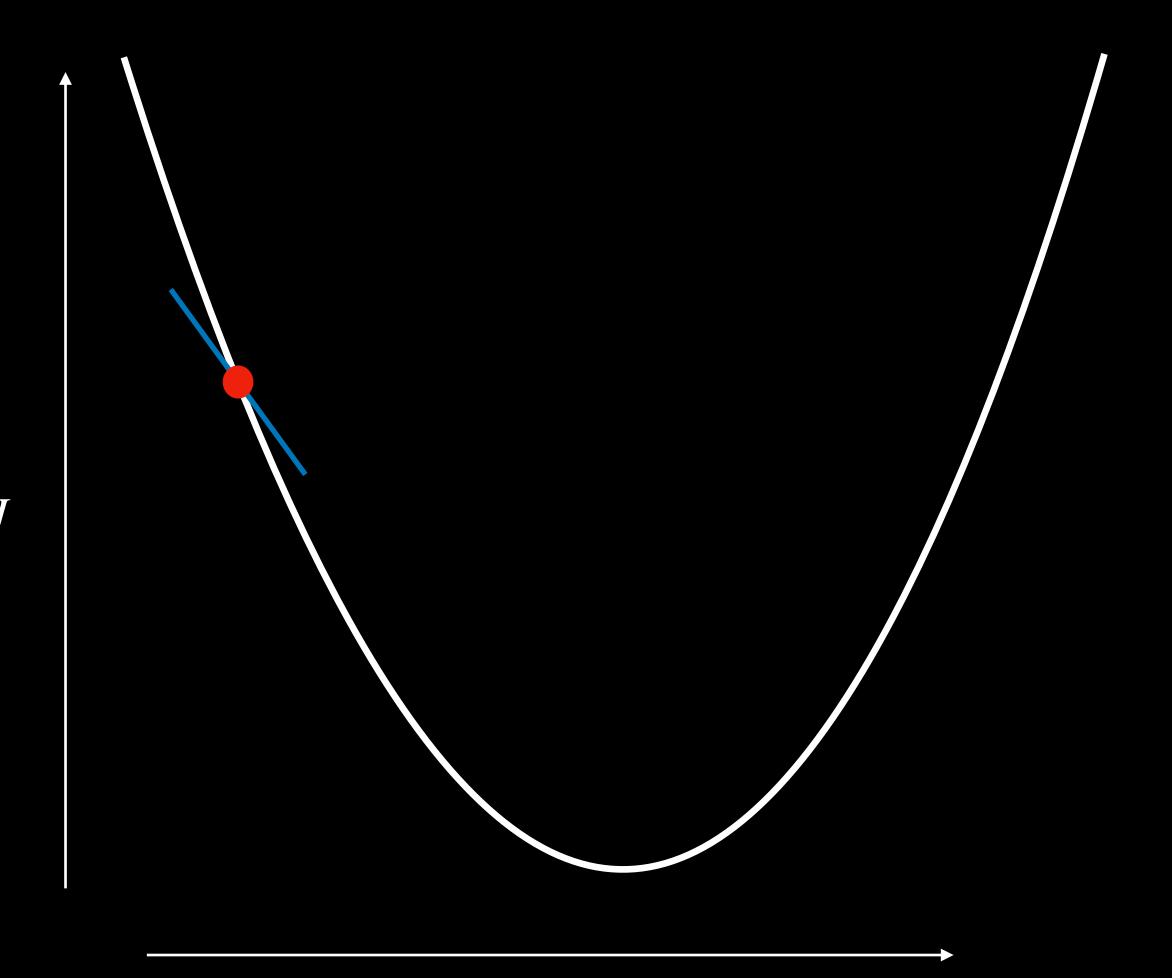
- Gradient Decent:
  - + Calculate  $\frac{\delta}{\delta\theta_i}J$
  - + Update  $\theta_i$  as:  $\theta_i := \theta_i \alpha \frac{\delta}{\delta \theta_i} J$
  - $\star$  Recalculate J



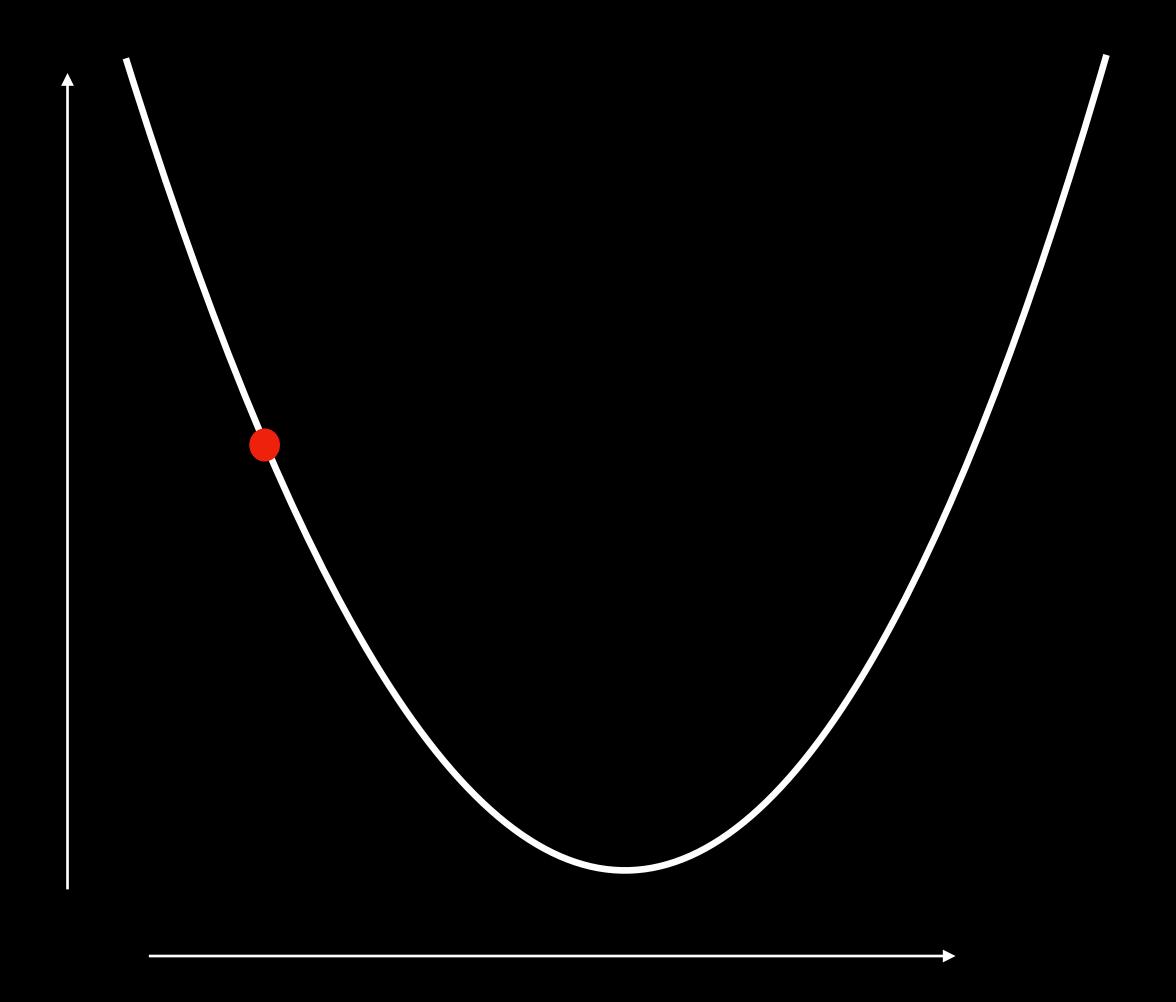
- Gradient Decent:
  - + Calculate  $\frac{\delta}{\delta\theta_i}J$
  - + Update  $\theta_i$  as:  $\theta_i := \theta_i \alpha \frac{\delta}{\delta \theta_i} J$
  - $\star$  Recalculate J



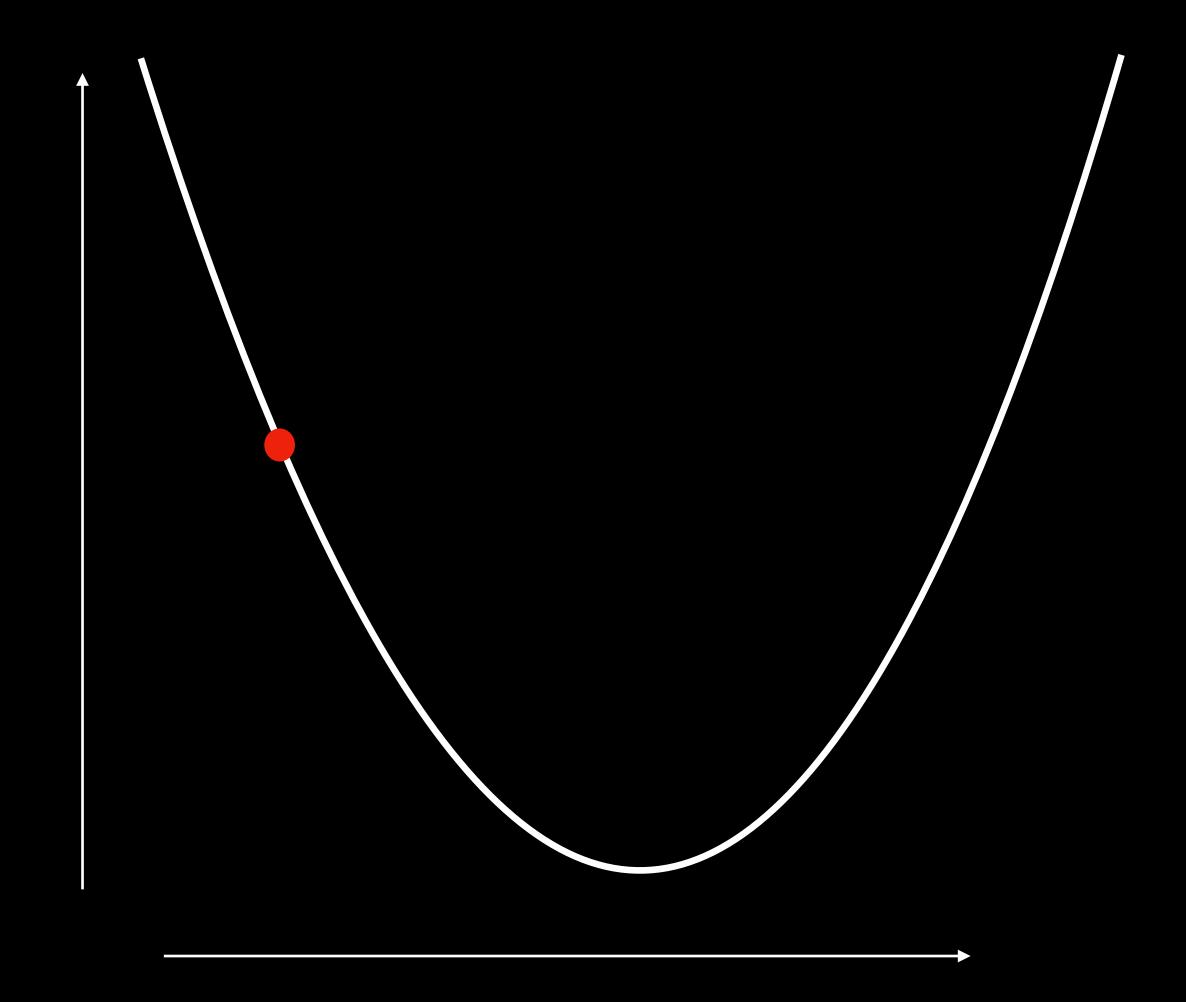
- Gradient Decent:
  - + Calculate  $\frac{\delta}{\delta\theta_i}J$
  - + Update  $\theta_i$  as:  $\theta_i := \theta_i \alpha \frac{\delta}{\delta \theta_i} J$
  - \* Recalculate J



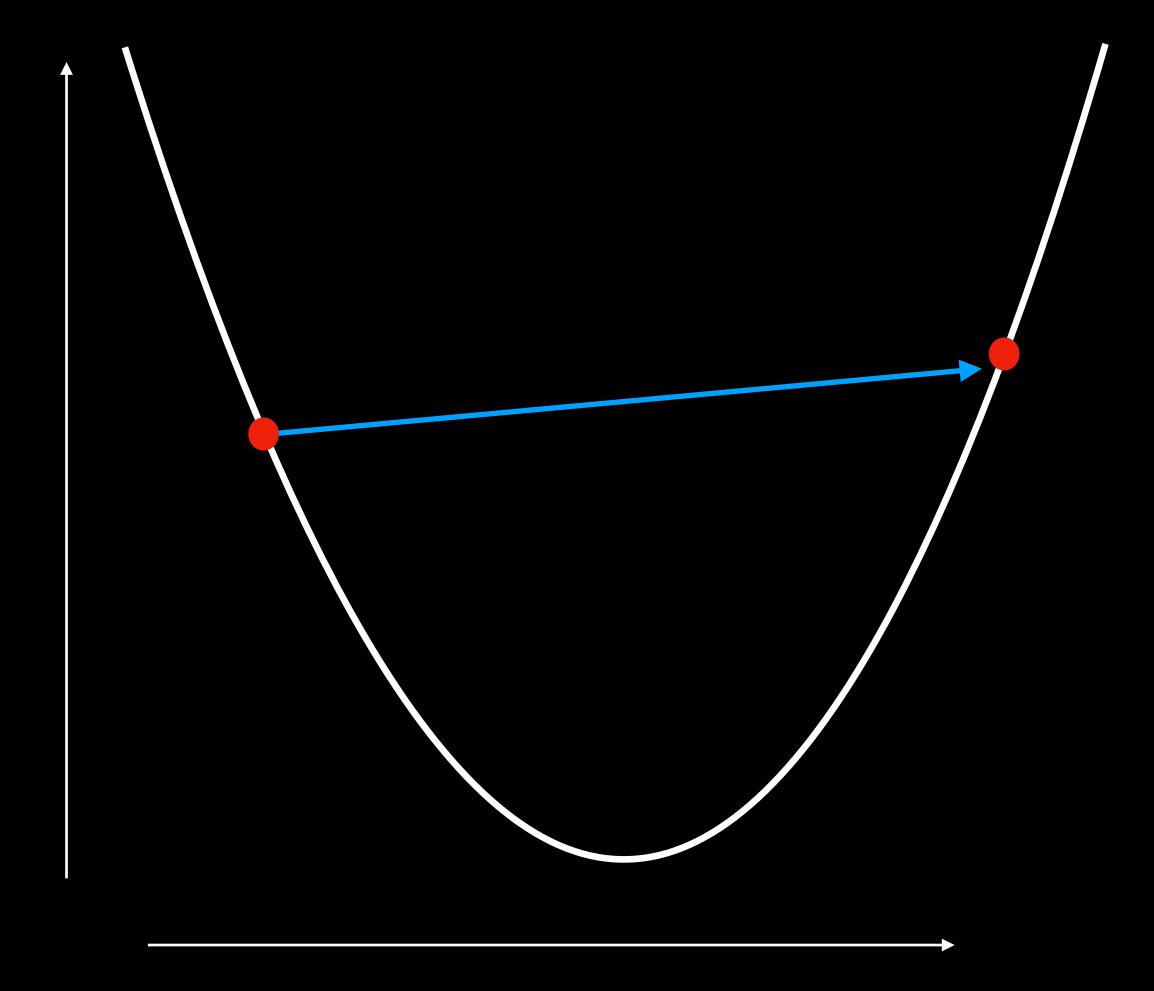
$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$



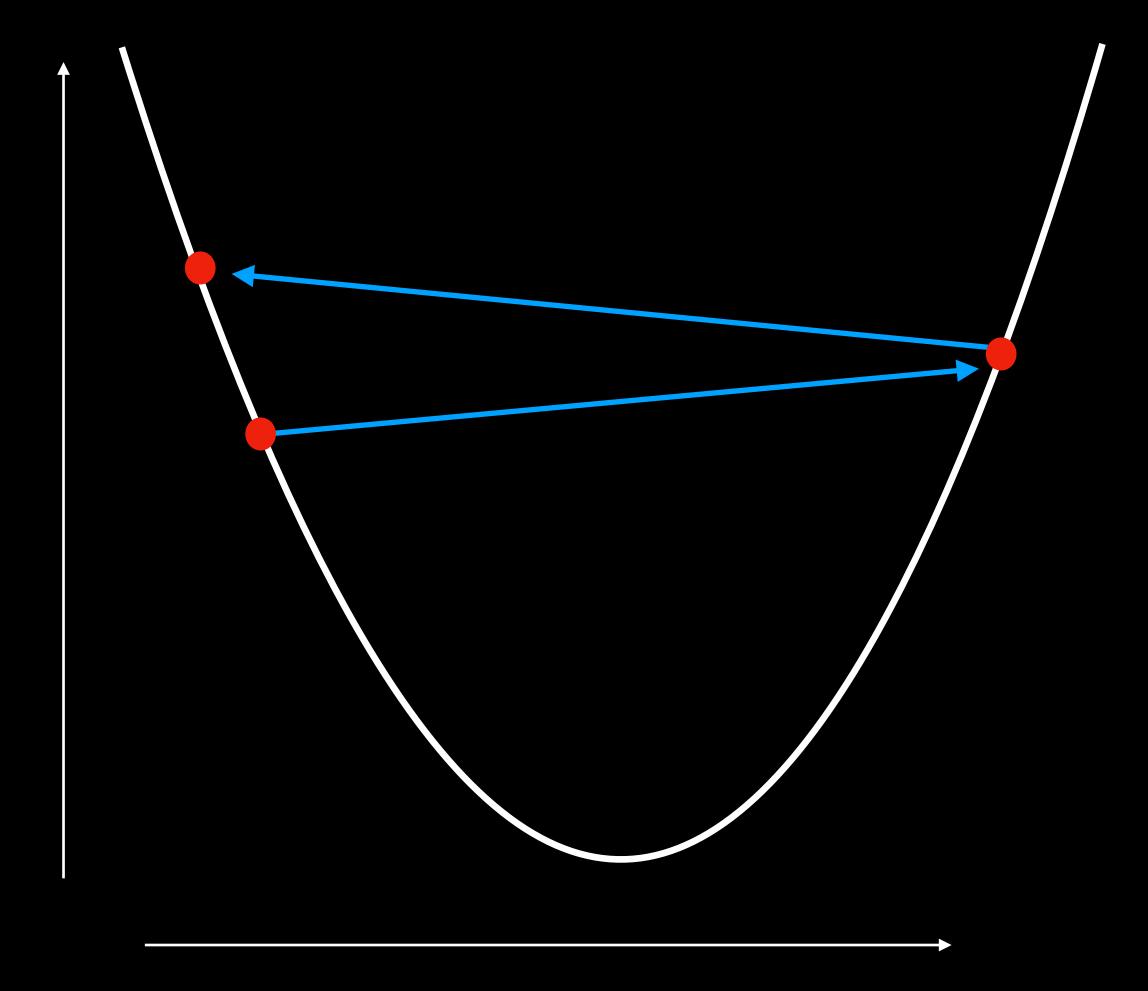
$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$



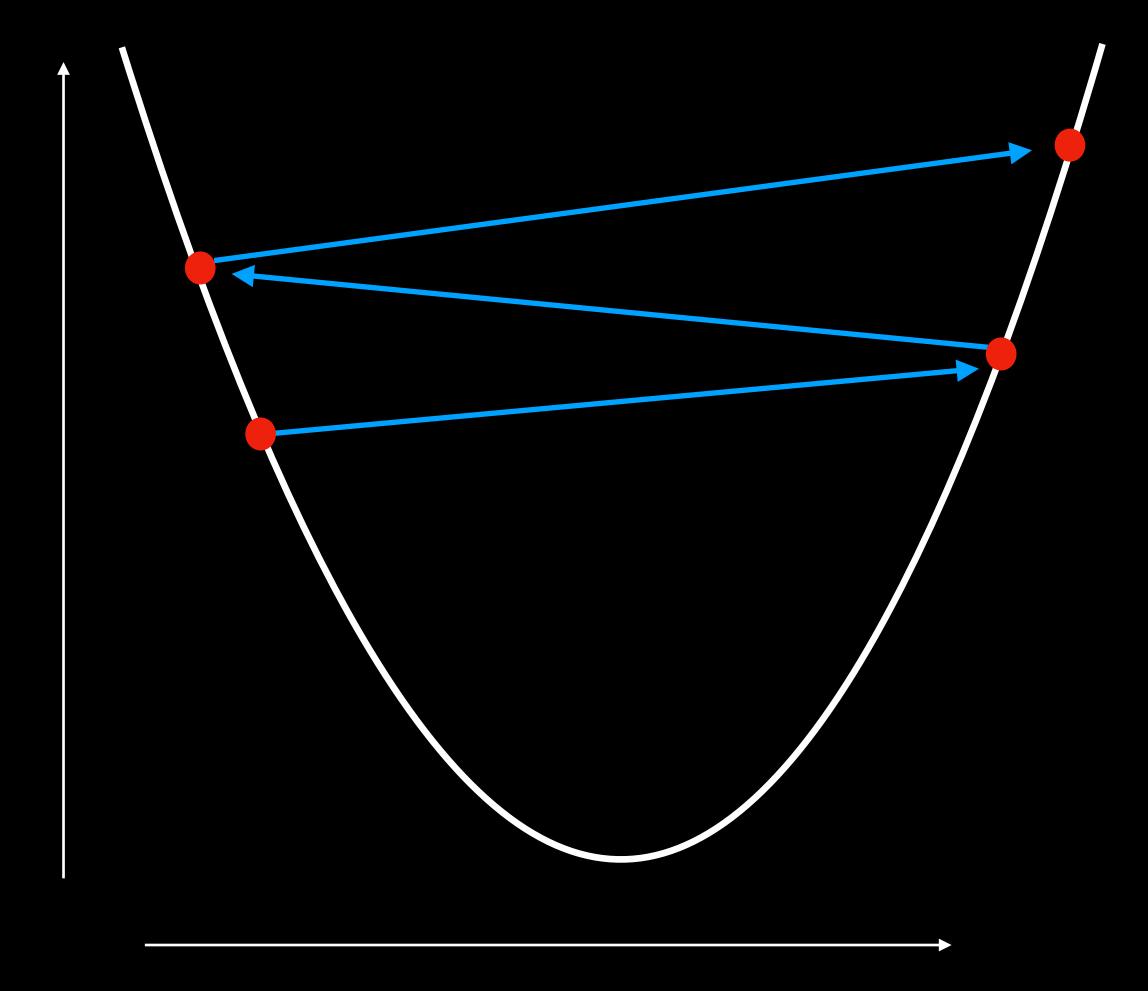
$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$



$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$

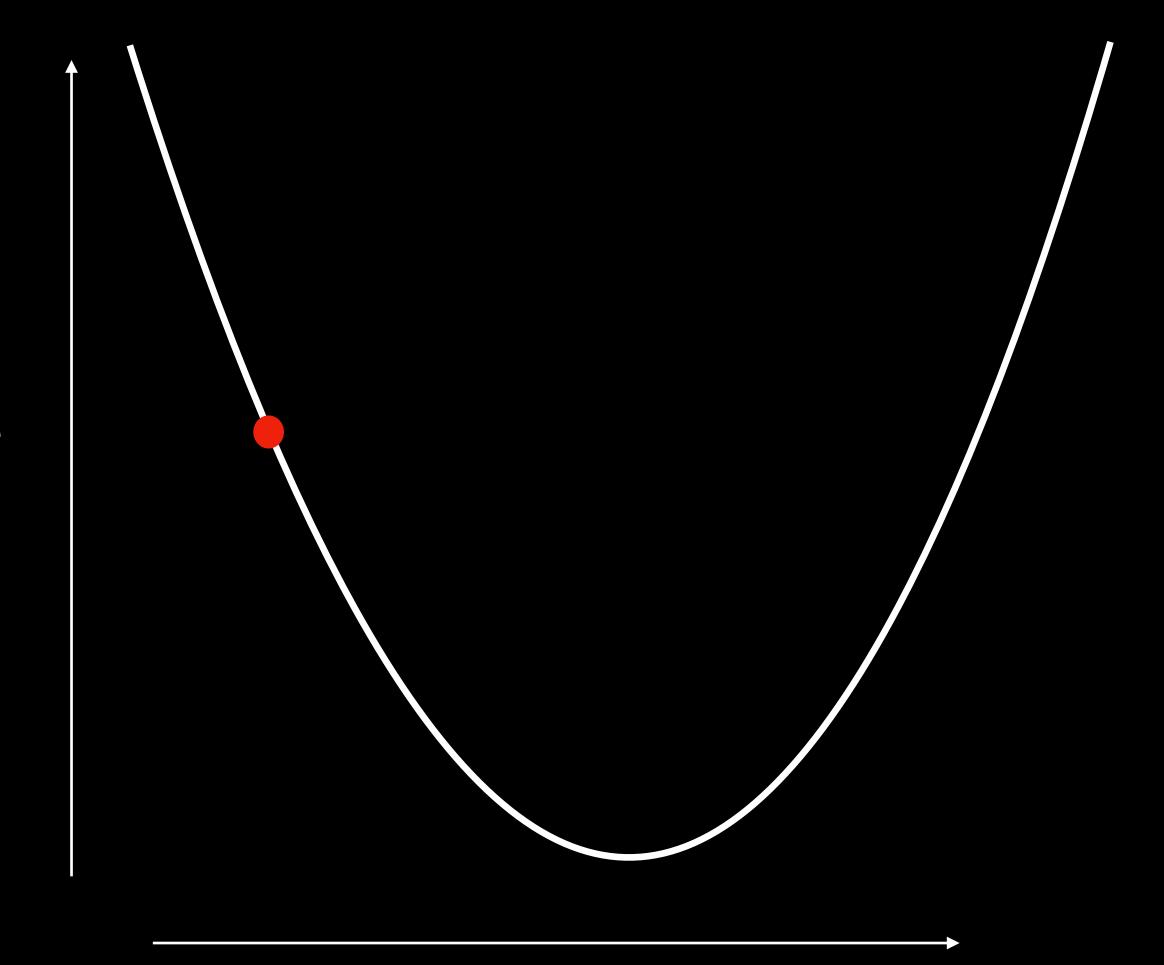


$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$



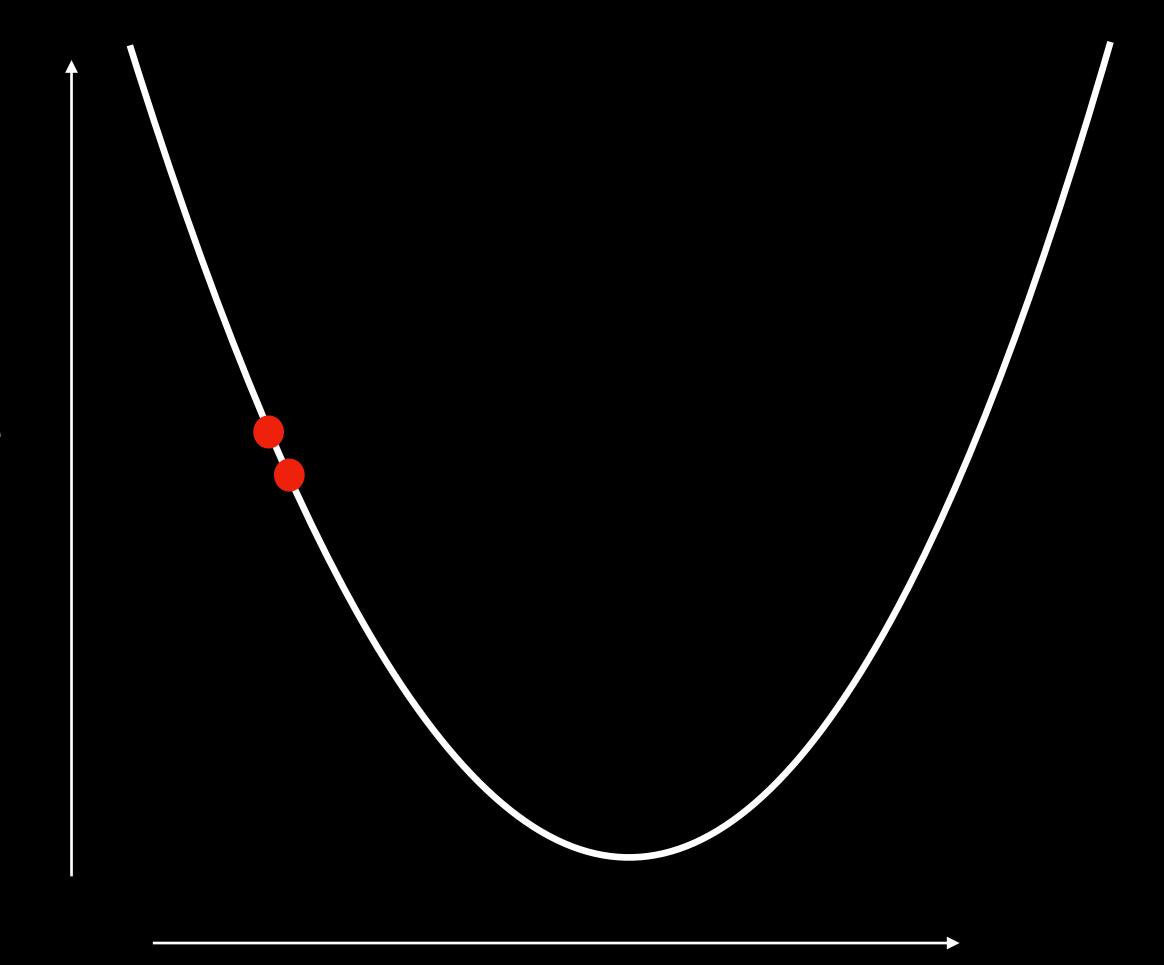
$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$

- If  $\alpha$  too large end up diverging
- If  $\alpha$  too small can take too long to converge



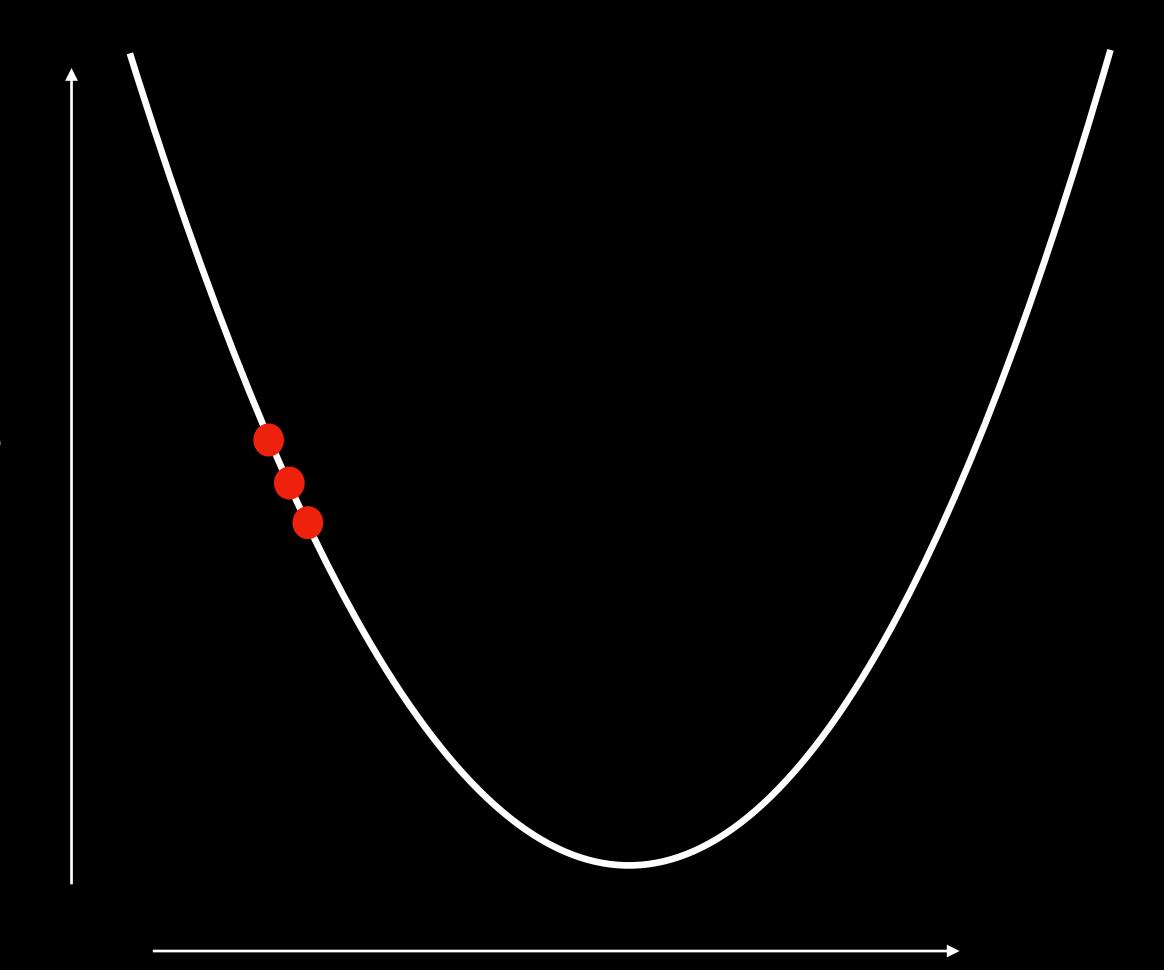
$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$

- If  $\alpha$  too large end up diverging
- If  $\alpha$  too small can take too long to converge



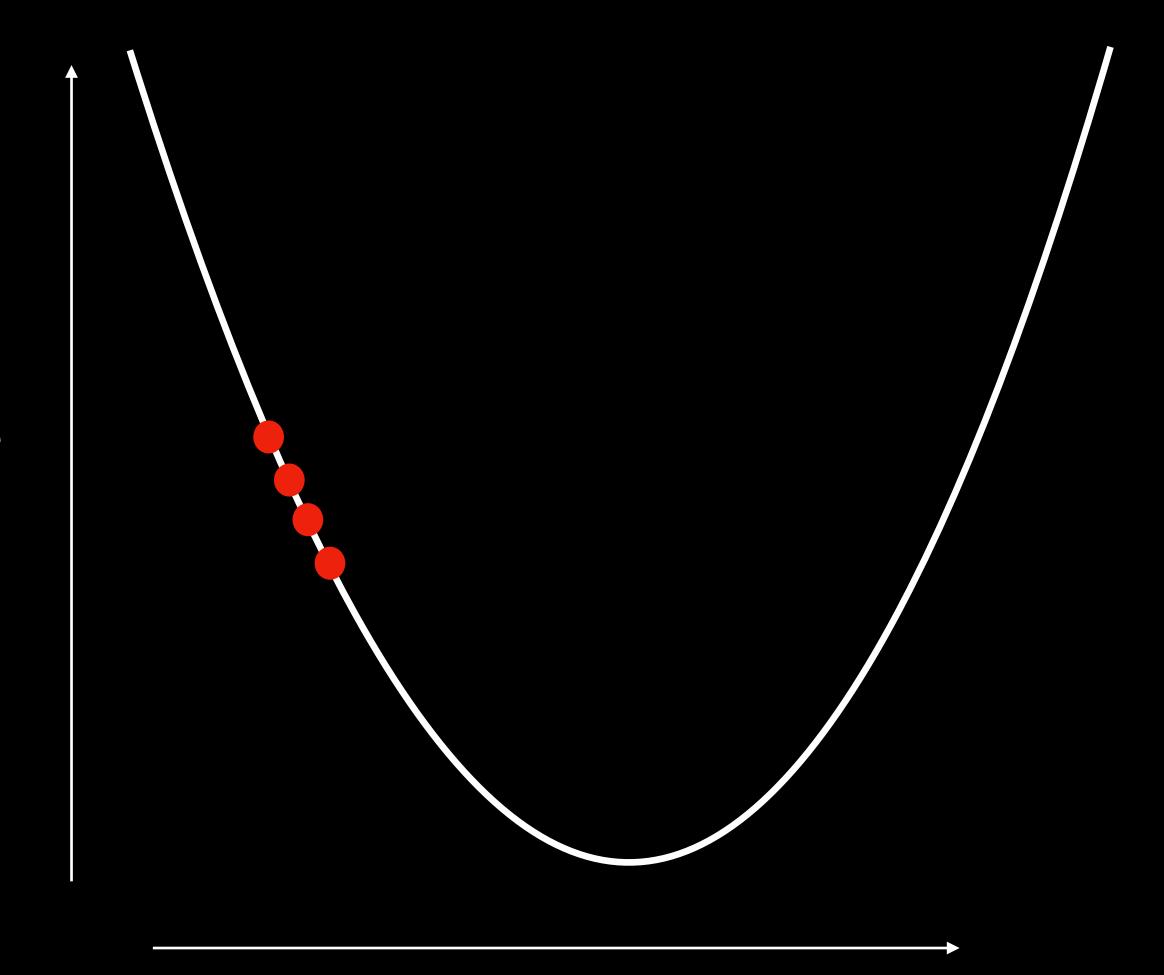
$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$

- If  $\alpha$  too large end up diverging
- If  $\alpha$  too small can take too long to converge



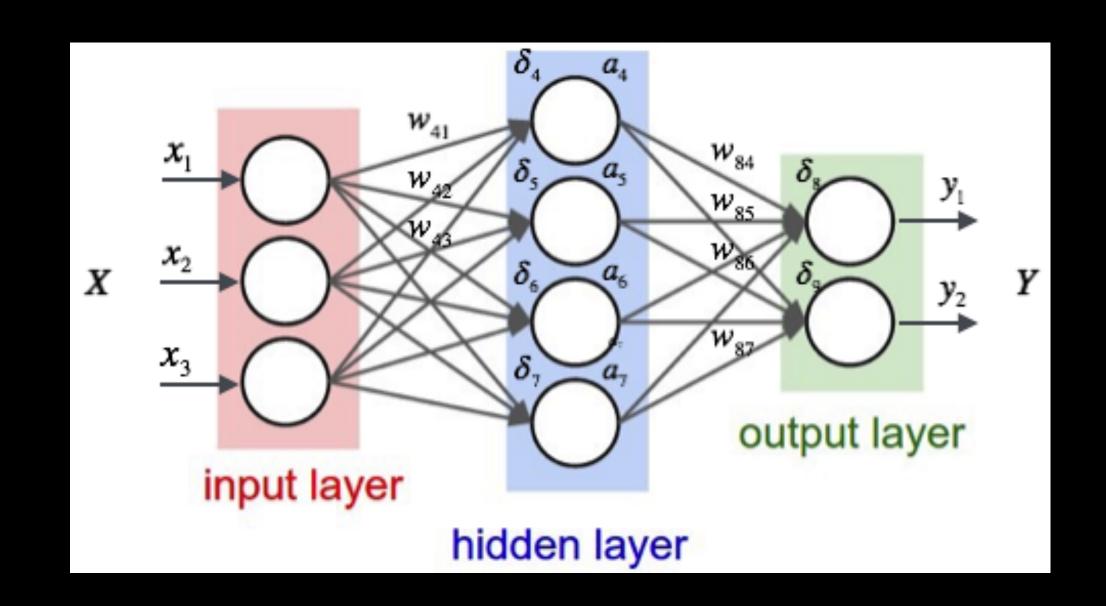
$$\theta_i := \theta_i - \alpha \frac{\delta}{\delta \theta_i} J$$

- If  $\alpha$  too large end up diverging
- If  $\alpha$  too small can take too long to converge



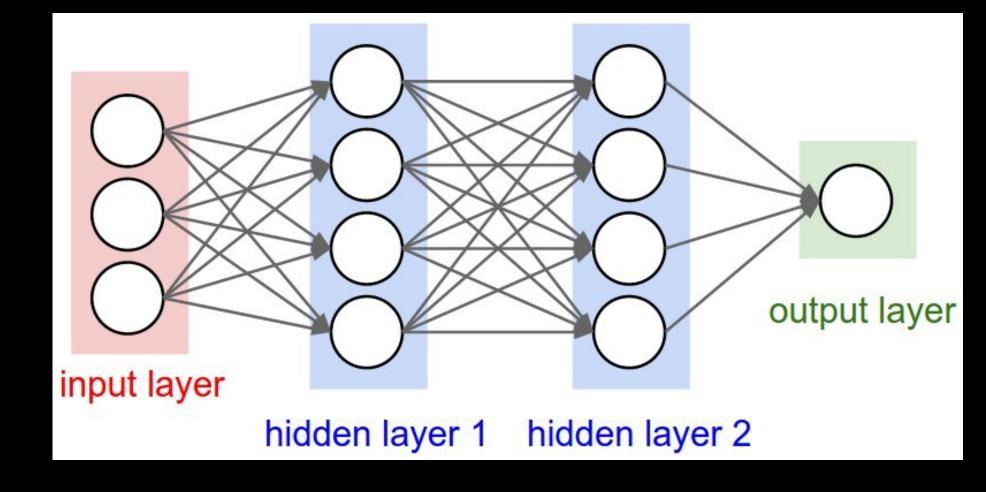
#### Gradient descent with NN

- Forward Propgation to calculate J
- Backward propagation:
  - Working backwards from output calculate the 'error' on each node.
  - Use this to calculate  $\frac{\delta}{\delta \theta_i} J$  and update  $\theta_i$
- Repeat



https://github.com/keras-team/keras/tree/master/examples

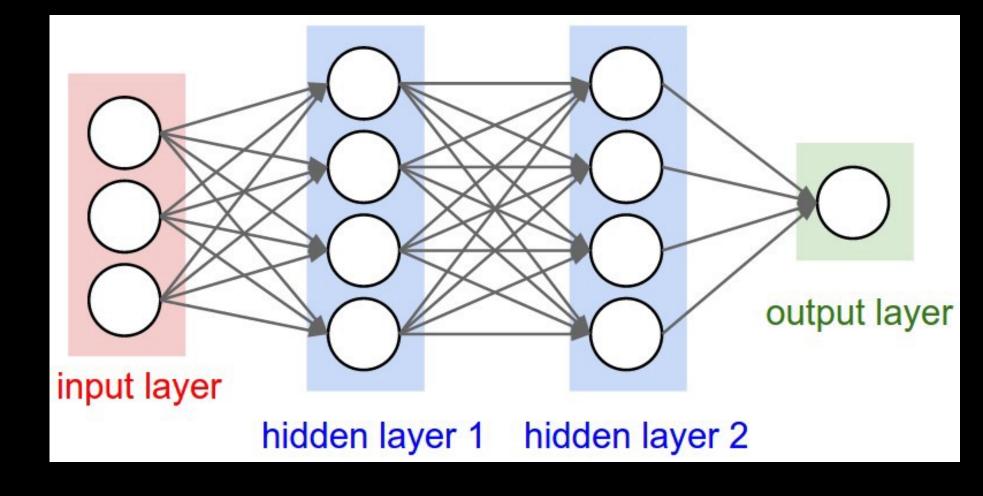
https://keras.io/



```
In [4]: import keras
        from keras.datasets import mnist
                                                                                            ReLU
        from keras.models import Sequential
                                                                                 R(z) = max(0, z)
        from keras.layers import Dense, Dropout
        from keras.optimizers import RMSprop
        model = Sequential()
        model.add(Dense(512, activation='relu'
                                                 input_shape=(784,)))
        model.add(Dropout(0.2))
        model.add(Dense(512, activation='relu'))
        model.add(Dropout(0.2))
        model.add(Dense(num_classes, activation='softmax'))
        model.summary()
        model.compile(loss='categorical_crossentropy',
                      optimizer=RMSprop(),
                      metrics=['accuracy'])
```

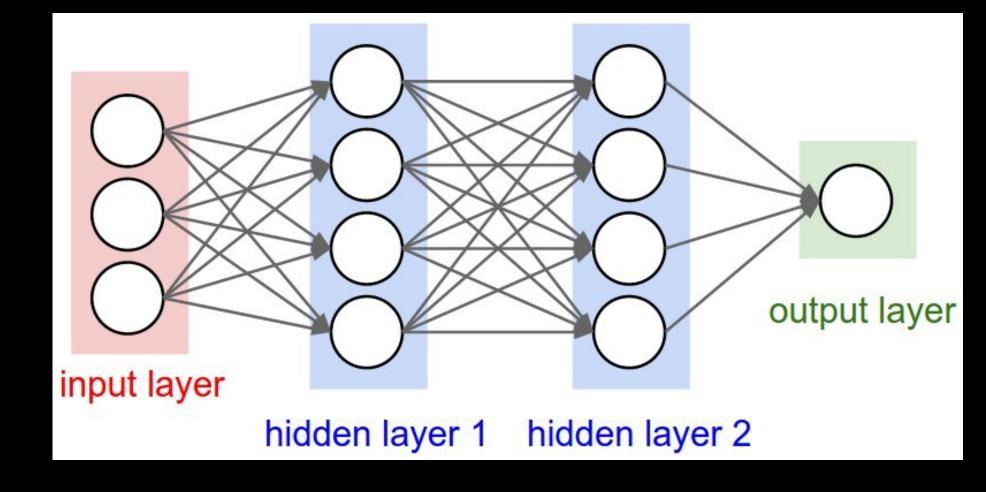
https://github.com/keras-team/keras/tree/master/examples

https://keras.io/



https://github.com/keras-team/keras/tree/master/examples

https://keras.io/



: 0.9743

: 0.9768

: 0.9793

: 0.9778

: 0.9784

Epoch 7/20

c: 0.9812

c: 0.9825

Epoch 8/20

Epoch 3/20

Epoch 4/20

Epoch 5/20

Epoch 6/20

```
In [5]:
  history = model.fit(x_train, y_train,
         batch_size=batch_size,
                   history = model.fit(X_train,y_train,epochs = 50,validation_split=0.10,class_weight=class_weight)
         epochs=epochs,
         verbose=1,
         validation_data=(x_test, y_test))
  Train on 60000 samples, validate on 10000 samples
  Epoch 1/20
  : 0.9509
  Epoch 2/20
  : 0.9743
  Epoch 3/20
  : 0.9768
  Epoch 4/20
  : 0.9793
  Epoch 5/20
  : 0.9778
  Epoch 6/20
  : 0.9784
  Epoch 7/20
  c: 0.9812
  Epoch 8/20
```

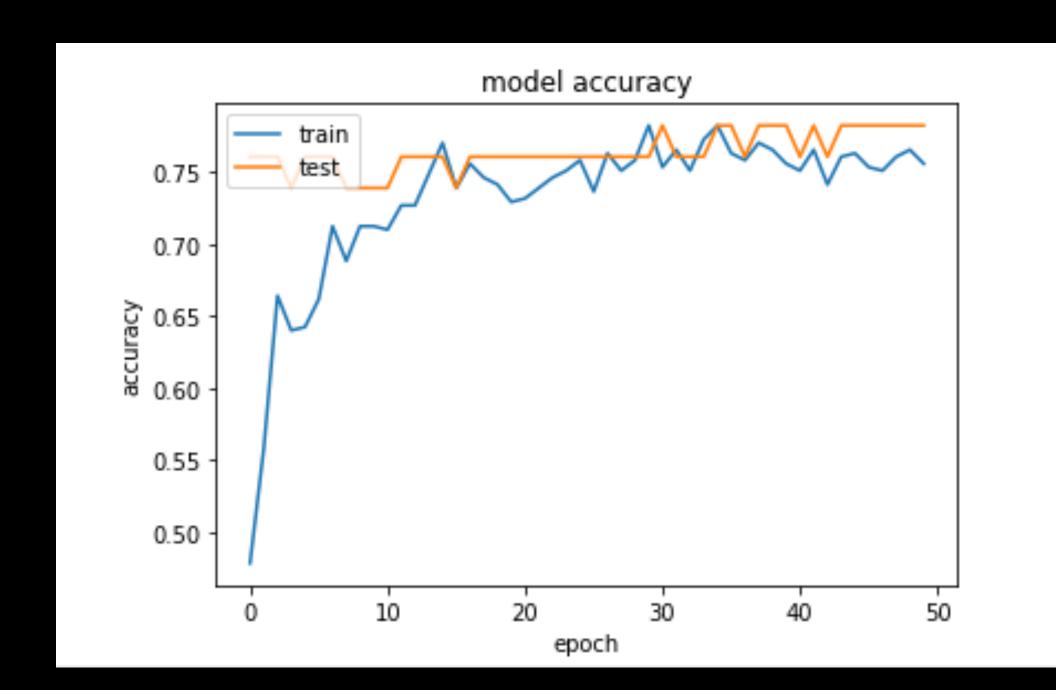
c: 0.9825

```
In [5]:
  history = model.fit(x_train, y_train,
         batch_size=batch_size,
                   history = model.fit(X_train,y_train,epochs = 50,validation_split=0.10,class_weight=class_weight)
         epochs=epochs,
         verbose=1,
         validation_data=(x_test, y_test))
  Train on 60000 samples, validate on 10000 samples
  Epoch 1/20
  : 0.9509
  Epoch 2/20
  : 0.9743
  Epoch 3/20
  : 0.9768
  Epoch 4/20
  : 0.9793
  Epoch 5/20
  : 0.9778
  Epoch 6/20
  : 0.9784
  Epoch 7/20
  c: 0.9812
  Epoch 8/20
  c: 0.9825
```

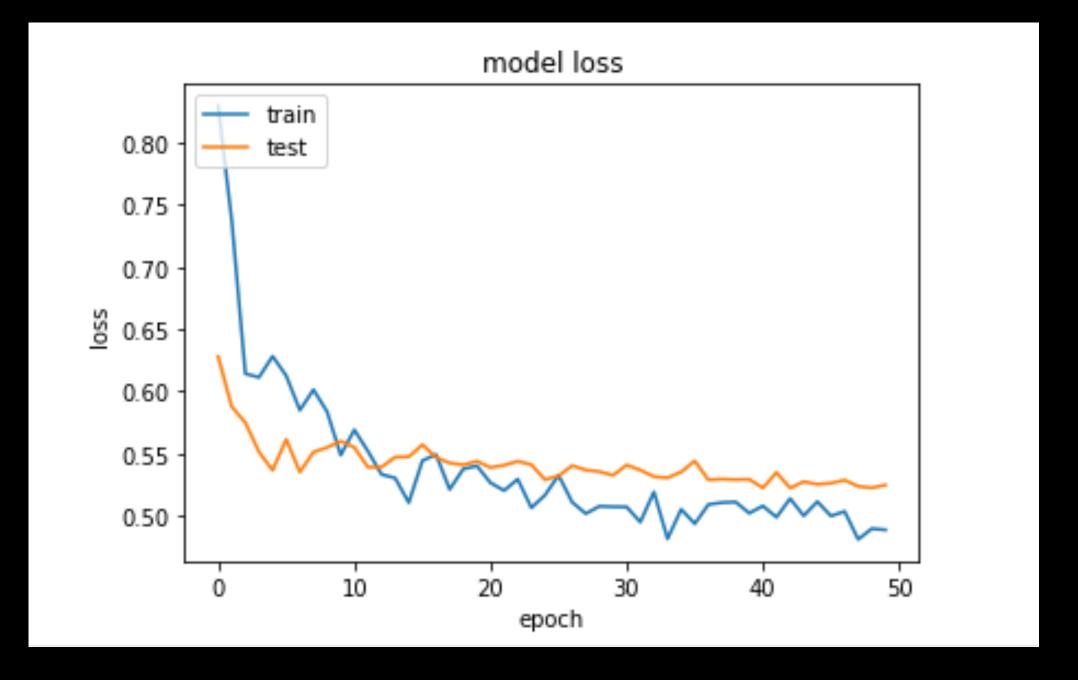
```
In [6]: score = model.evaluate(x_test, y_test, verbose=0)
    print('Test loss:', score[0])
    print('Test accuracy:', score[1])

Test loss: 0.11100612514
    Test accuracy: 0.9832
```

```
In [18]: plt.plot(history.history['acc'])
   plt.plot(history.history['val_acc'])
   plt.title('model accuracy')
   plt.ylabel('accuracy')
   plt.xlabel('epoch')
   plt.legend(['train', 'test'], loc='upper left')
   plt.show()
```



```
# summarize history for loss
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```



#### Useful references

- Free coursera course: <a href="https://www.coursera.org/learn/machine-learning">https://www.coursera.org/learn/machine-learning</a>
- Keras documentation: <a href="https://keras.io/">https://keras.io/</a>
- Previous NN hack night: <a href="https://github.com/JBCA-MachineLearning/Typhoons-and-Hurricanes-Hacknight">https://github.com/JBCA-MachineLearning/Typhoons-and-Hurricanes-Hacknight</a>
- More info on activation functions: <a href="https://medium.com/the-theory-of-everything/understanding-activation-functions-in-neural-networks-9491262884e0">https://medium.com/the-theory-of-everything/understanding-activation-functions-in-neural-networks-9491262884e0</a>