Mixture of Gaussians

CS229: Machine Learning
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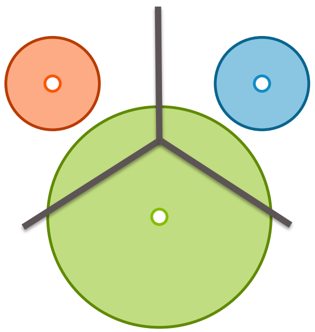
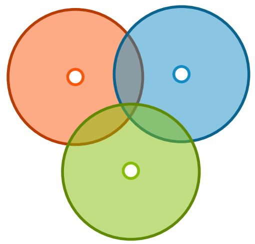
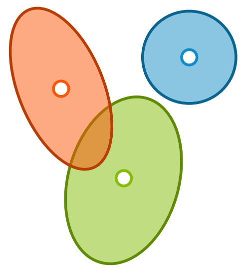
Failure modes of k-means



disparate cluster sizes

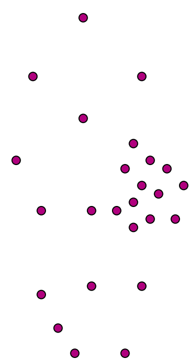


overlapping clusters



different shaped/oriented clusters

(One) bad case for k-means



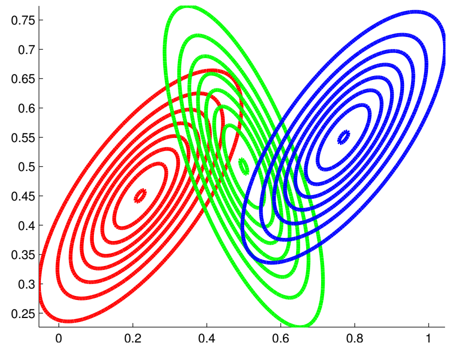
- Clusters may overlap
- Some clusters may be “wider” than others

Gaussians in *m* Dimensions

$$P(\mathbf{x}) = \frac{1}{(2\pi)^{m/2}\, |\Sigma|^{1/2}} \exp\left[-\frac{1}{2}\left(\mathbf{x}-\mu\right)^T \Sigma^{-1}\left(\mathbf{x}-\mu\right)\right]$$

Suppose You Have a Gaussian For Each Class

$$\frac{1}{(2\pi)^{m/2}\ |\Sigma|^{1/2}}\exp\left[-\frac{1}{2}(\mathbf{x}-\mu)^T\Sigma^{-1}(\mathbf{x}-\mu)\right]$$



Gaussian Bayes Classifier

- You have a Gaussian over **x** for each class y=i:

$$\frac{1}{(2\pi)^{m/2}\,|\Sigma|^{1/2}}\exp\left[-\frac{1}{2}(\mathbf{x}-\mu)^T\,\Sigma^{-1}(\mathbf{x}-\mu)\right]$$

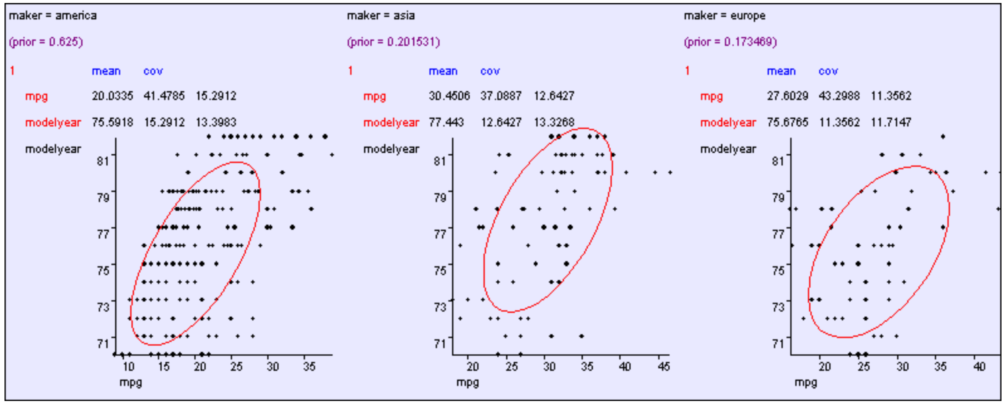
- But you need probability of class y=i given **x**:

- Thank you Bayes Rule!!

$$P(y=i\,|\,\mathbf{x})=\frac{p(\mathbf{x}\,|\,y=i)P(y=i)}{p(\mathbf{x})}$$

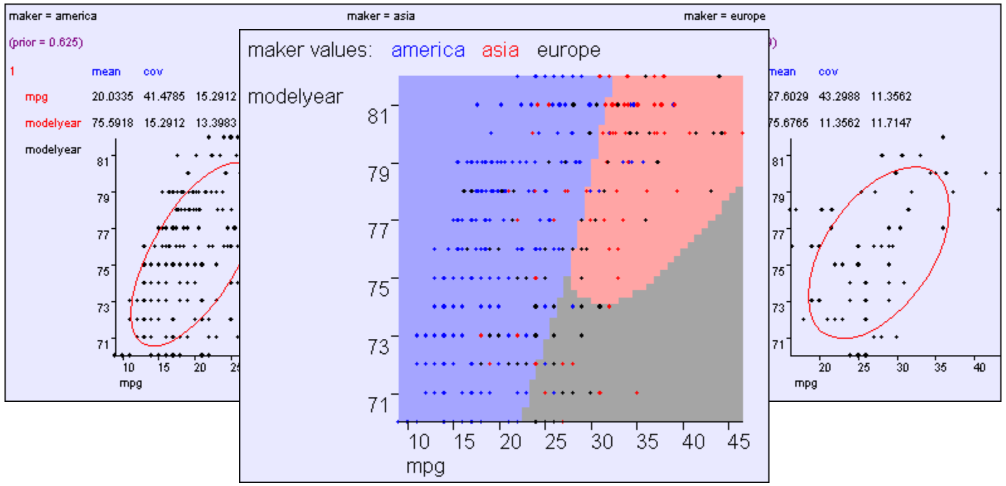
Learning modelyear , mpg ---> maker

$$\Sigma = \begin{pmatrix} \sigma_1^2 & \sigma_{12} & \cdots & \sigma_{1m} \\ \sigma_{12} & \sigma_2^2 & \cdots & \sigma_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1m} & \sigma_{2m} & \cdots & \sigma_m^2 \end{pmatrix}$$



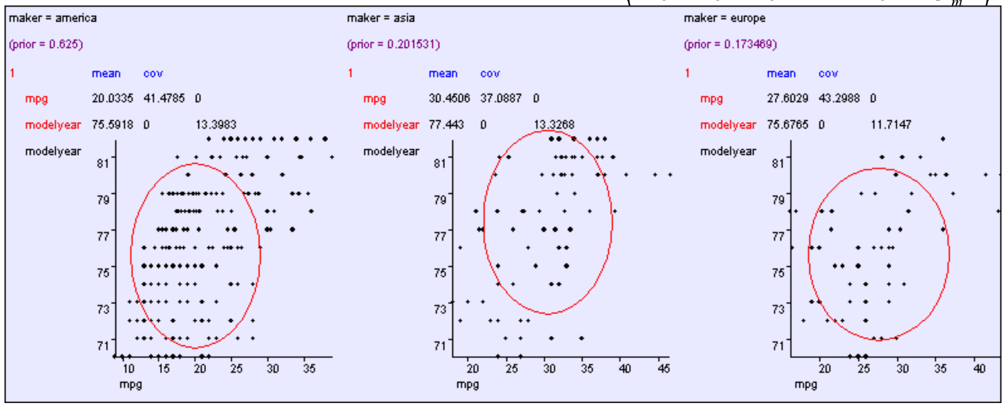
General: $O(m^2)$ parameters

$$\Sigma = \begin{pmatrix} \sigma_1^2 & \sigma_{12} & \cdots & \sigma_{1m} \\ \sigma_{12} & \sigma_2^2 & \cdots & \sigma_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1m} & \sigma_{2m} & \cdots & \sigma_m^2 \end{pmatrix}$$



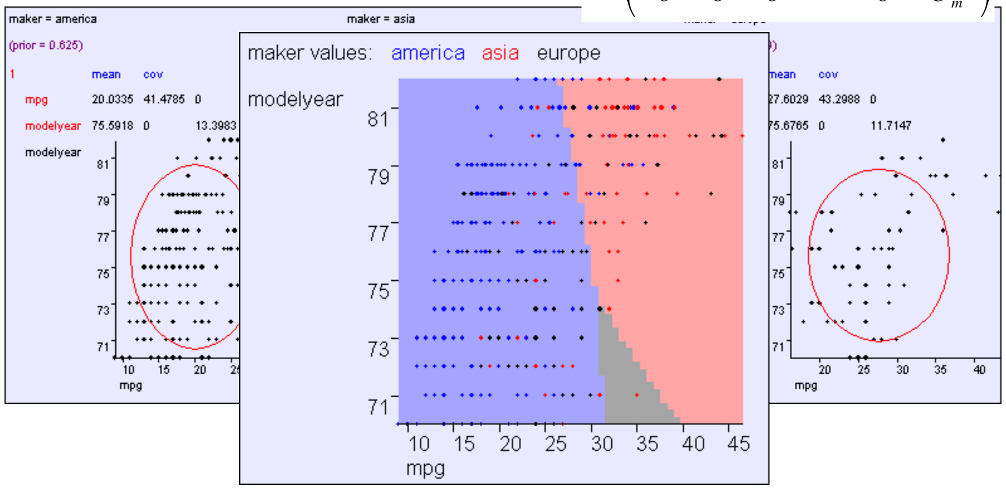
Aligned: *O(m)* parameters

$$\Sigma = \begin{pmatrix} \sigma_1^2 & 0 & 0 & \cdots & 0 & 0 \\ 0 & \sigma_2^2 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \sigma_3^2 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \sigma_{m-1}^2 & 0 \\ 0 & 0 & 0 & \cdots & 0 & \sigma_m^2 \end{pmatrix}$$



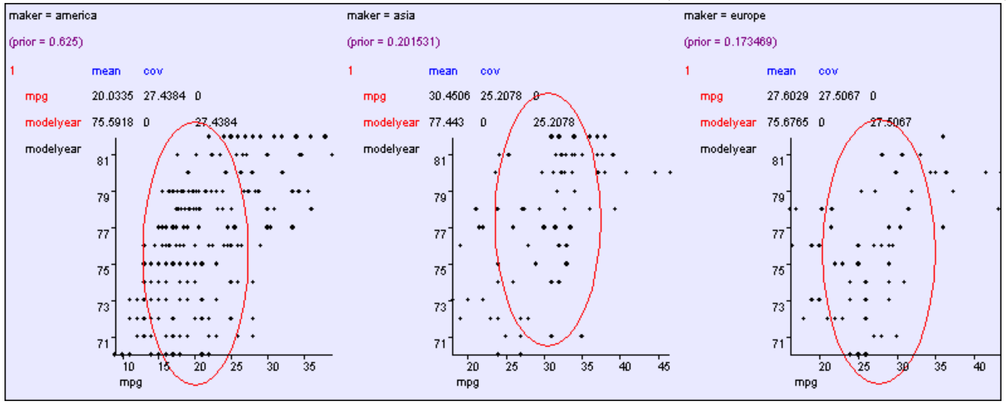
Aligned: *O(m)* parameters

$$\Sigma = \begin{pmatrix} \sigma_1^2 & 0 & 0 & \cdots & 0 & 0 \\ 0 & \sigma_2^2 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \sigma_3^2 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \sigma_{m-1}^2 & 0 \\ 0 & 0 & 0 & \cdots & 0 & \sigma_m^2 \end{pmatrix}$$



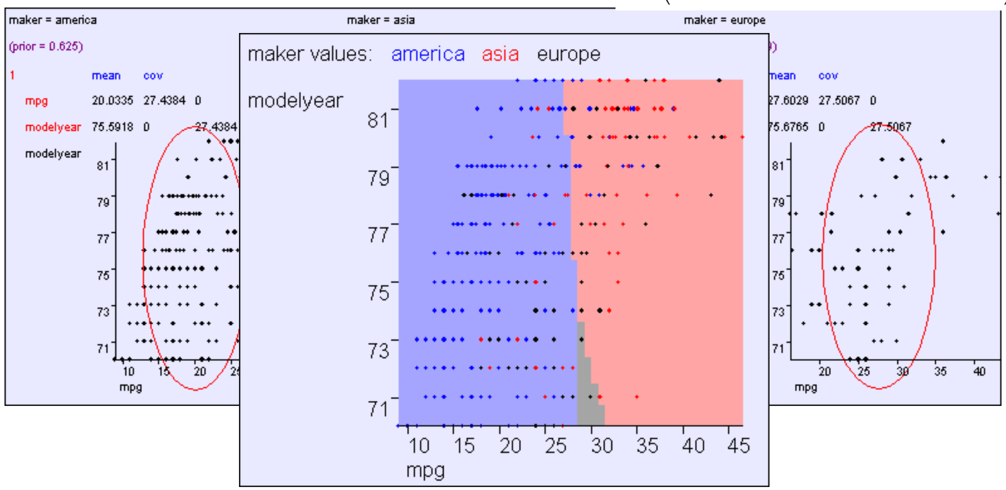
Spherical: *O(1)* cov parameters

$$\Sigma = \begin{pmatrix} \sigma^2 & 0 & 0 & \cdots & 0 & 0 \\ 0 & \sigma^2 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \sigma^2 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \sigma^2 & 0 \\ 0 & 0 & 0 & \cdots & 0 & \sigma^2 \end{pmatrix}$$



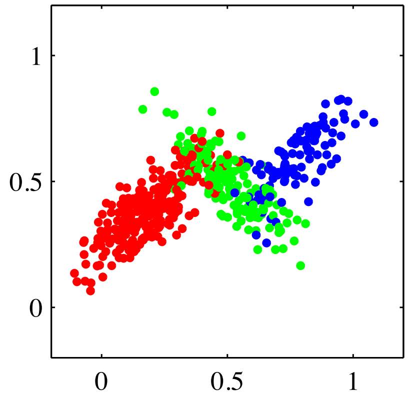
Spherical: *O(1)* cov parameters

$$\Sigma = \begin{pmatrix} \sigma^2 & 0 & 0 & \cdots & 0 & 0 \\ 0 & \sigma^2 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \sigma^2 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \sigma^2 & 0 \\ 0 & 0 & 0 & \cdots & 0 & \sigma^2 \end{pmatrix}$$



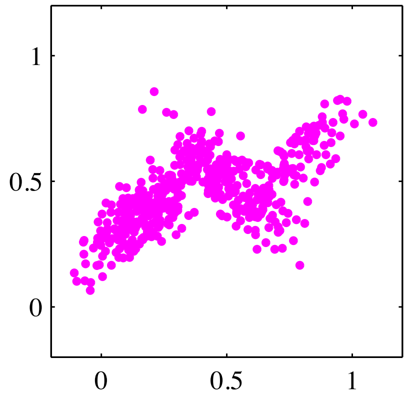
Clustering our Observations

- Imagine we have an assignment of each x^i to a Gaussian



Complete data labeled by true cluster assignments

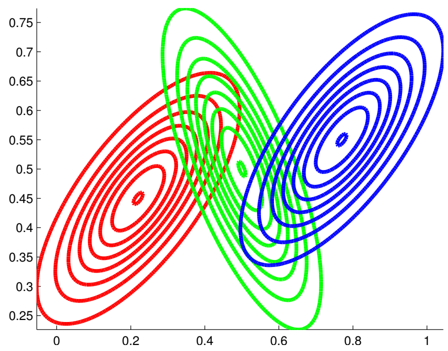
Our actual observations



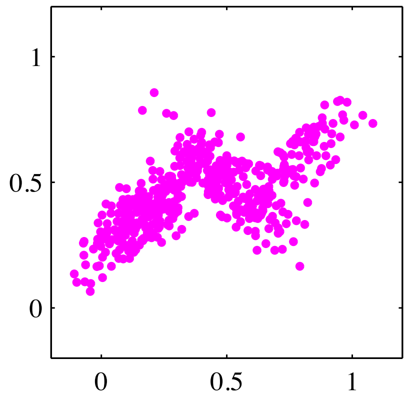
Density as Mixture of Gaussians

- Approximate with density with a mixture of Gaussians

Mixture of 3 Gaussians



Our actual observations

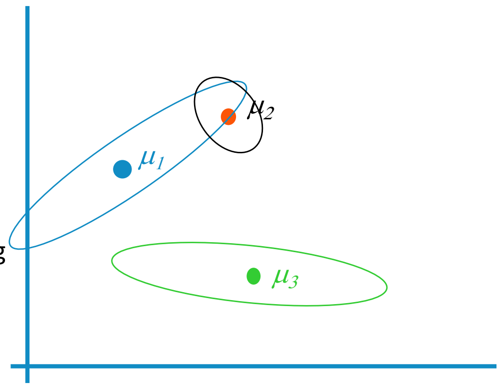


The General GMM assumption

- There are k components
- Component *i* has an associated mean vector μ_i
- Each component generates data from a Gaussian with mean μ_i and covariance matrix Σ_i

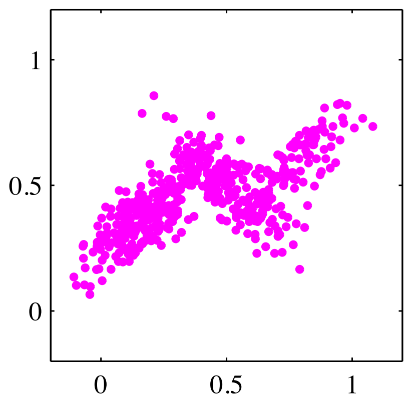
Each data point is generated according to the following recipe:

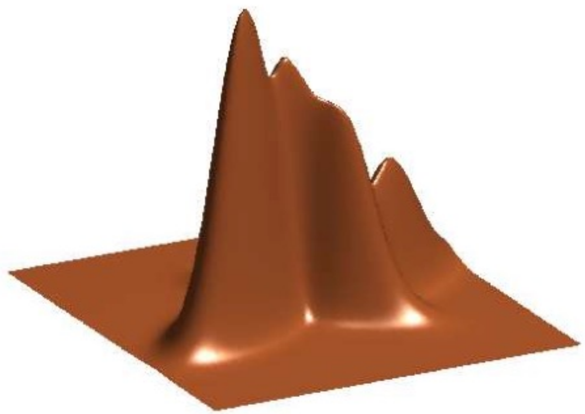
1. Pick a component at random: Choose component i with probability *P(z=i)*
2. Datapoint ~ N(μ_i, Σ_i)



Density Estimation

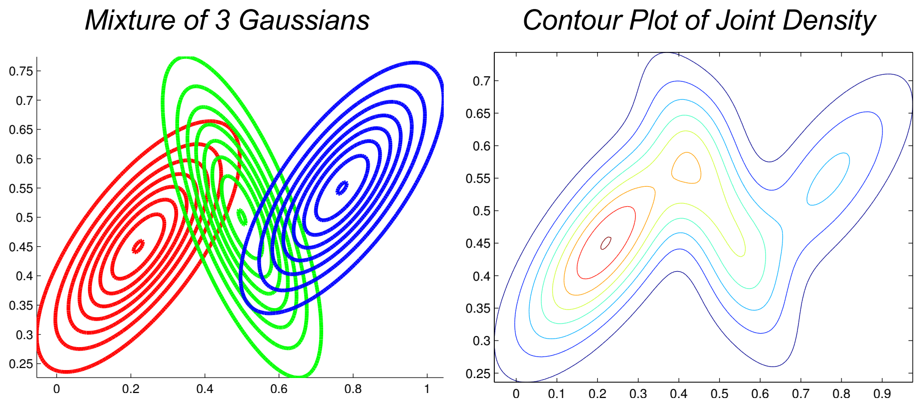
- Estimate a density based on $x^1,\ldots,x^N$





Density as Mixture of Gaussians

- Approximate density with a mixture of Gaussians



Summary of GMM Components

- Observations $x^i \in \mathbb{R}^d, \quad i = 1, 2, \ldots, N$
- Hidden cluster labels $z_i \in \{1, 2, \ldots, K\}, \quad i = 1, 2, \ldots, N$
- Hidden mixture means $\mu_k \in \mathbb{R}^d, \quad k = 1, 2, \ldots, K$
- Hidden mixture covariances $\Sigma_k \in \mathbb{R}^{d \times d}, \quad k = 1, 2, \ldots, K$
- Hidden mixture probabilities $\pi_k, \quad \sum_{k=1}^{K} \pi_k = 1$

Gaussian mixture marginal and conditional likelihood **:**

$$p(x^i|\pi, \mu, \Sigma) = \sum_{z^i=1}^{K} \pi_{z^i} \; p(x^i|z^i, \mu, \Sigma)$$

$$p(x^i|z^i, \mu, \Sigma) = \mathcal{N}(x^i|\mu_{z^i}, \Sigma_{z^i})$$