Ejercicio: Hallar la matrit asociada a la transformación T de una simetría axial respecto a la recta y = 3x.

$$A = \begin{pmatrix} -\frac{4}{5} & \frac{3}{5} \\ \frac{3}{5} & \frac{4}{5} \end{pmatrix} \qquad \Rightarrow \qquad T(x,y) = \begin{pmatrix} -\frac{4x+3y}{5} & \frac{3x+4y}{5} \\ \frac{3}{5} & \frac{4}{5} & \frac{3}{5} \end{pmatrix}$$

Ejercicio: Hallar la matrit asociada a la transformación T de una proyección ortogonal respecto a la recta y=3x.

$$\vec{v}_{\perp} = \begin{pmatrix} 3 \\ -3 \\ 1 \end{pmatrix}$$

$$\vec{v} = \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} = \vec{v}$$

$$\vec{v}_{\perp} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$T \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix} \Rightarrow T \begin{pmatrix} 1 \\ 3 \end{pmatrix} = T \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 3T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$T \begin{pmatrix} -3 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow T \begin{pmatrix} -3 \\ 1 \end{pmatrix} = -3T \begin{pmatrix} 1 \\ 0 \end{pmatrix} + T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{3}{10} & \frac{9}{10} \\ \frac{1}{10} & \frac{1}{10} \\ \frac{3}{10} & \frac{9}{10} \end{pmatrix} = \begin{pmatrix} \frac{4}{10} & \frac{3}{10} \\ \frac{1}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} & \frac{9}{10} \end{pmatrix}$$

$$A = \begin{pmatrix} \frac{1}{10} & \frac{3}{10} \\ \frac{3}{10} & \frac{9}{10} \end{pmatrix} \rightarrow T(x, y) = \begin{pmatrix} \frac{x+3y}{10} & \frac{3x+9y}{10} \end{pmatrix}$$

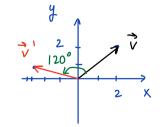
Hallar la matriz asociada a la transformación T, la cual efectua en 12° una rotación de 120° en sentido antihorario. Calcular T(2,2)

$$A = \begin{pmatrix} \cos \theta - \sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} \cos (120^{\circ}) - \sin (120^{\circ}) \\ \sin (120^{\circ}) & \cos (120^{\circ}) \end{pmatrix} = \begin{pmatrix} -\cos (60^{\circ}) - \sin (60^{\circ}) \\ \sin (60^{\circ}) - \cos (60^{\circ}) \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} - \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} - \frac{1}{2} \end{pmatrix}$$

CALC. EN GRADOS 1

9 (°)	0	30	45	60	90
O (rad)	0	<del>1T</del> 6	<del>#</del>	77	7/2
Sen O	0	1 2	1/2	<u>V3</u> 2	1
w5 B	1	<u>Z</u>	<u>√2</u>	1/2	O
tau O	0	<del>\(\frac{1}{3}\)</del>	1	√3	8

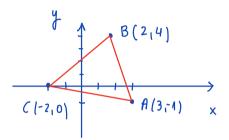
$$T(z_1 z) = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} z \\ z \end{pmatrix} = \begin{pmatrix} -1 - \sqrt{3} \\ \sqrt{3} - 1 \end{pmatrix}$$



$$T(2,2) \approx (-2^{1}+3,0^{1}+3)$$

Ejercicio: Aplicar a la figura la transformación T, cuya matriz asociada

es 
$$A = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$$
. Representar la figura transformada.

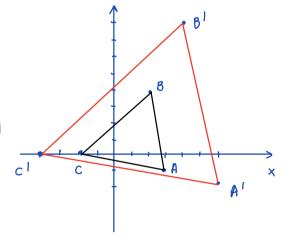


Dilatación con K = 2:

$$A' = T(3,-4) = 2(3,-4) = (6,-2)$$

$$B^{1} = T(2,4) = (4,8)$$

$$C' = + (-2,0) = (-4,0)$$



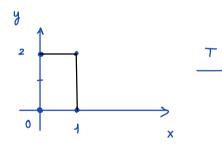
Ejercicio: Trazar la imagen del rectangulo myos vértices son los

transformaciones:

a) 
$$T(x,y) = (x+y,y)$$

a) 
$$T(x,y) = (x+y,y)$$
 b)  $T(x,y) = (x,y+2x)$ 

a) Destitamiento cortante en la dirección del ye x con factor K = 1:



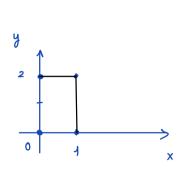
$$\top (0,0) = (0,0)$$

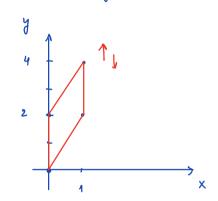
$$T(1,2) = (3,2)$$

$$T(0,2) = (2,2)$$

$$T(1,0) = [1,0]$$

b) Destitamiento cortante un la dirección del eje y con factor K=2:





$$T(0,0) = (0,0)$$

$$T(0,2) = (0,2)$$

$$T(1,0) = (1,2)$$

Ejercicio: Consideramos una transformación lineal  $T: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$  que consiste en una rotación de ángulo  $\frac{1}{6}$  respecto al eje x en sentido antihororio y, a continuación, una dilatación con  $K=\frac{9}{2}$ . Hallar la expresión de T y T(2,0,1).

$$A = A_{T_2} \cdot A_{T_1} = \frac{9}{2} \stackrel{?}{\cancel{Z}} \cdot A_{T_1} = \begin{pmatrix} \frac{9}{2} & 0 & 0 \\ 0 & -\frac{9\sqrt{3}}{4} & \frac{9}{4} \\ 0 & -\frac{9}{4} & -\frac{9\sqrt{3}}{4} \end{pmatrix}$$
dilatecine retains

$$A_{T_1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sec \theta \\ 0 & \sec \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \frac{2\pi}{6} & -\sec \frac{2\pi}{6} \\ 0 & \sec \frac{2\pi}{6} & \cos \frac{2\pi}{6} \end{pmatrix} = \begin{pmatrix} CALC. EN RAD \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{\sqrt{3}}{2} & \frac{1}{2} \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} \end{pmatrix}$$

$$A_{T_{2}} = \begin{pmatrix} K & 0 & 0 \\ 0 & K & 0 \\ 0 & 0 & K \end{pmatrix} = K \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = K \cdot \Sigma = \frac{1}{2} \Sigma$$

$$T(x,y,z) = \left(\frac{q}{2}x_1 - \frac{q\sqrt{3}}{4}y + \frac{q}{4}z_1 - \frac{q}{4}y - \frac{q\sqrt{3}}{4}z\right)$$

$$T(2_10_11) = \left(9_1 \frac{9}{4}_1 - \frac{913}{4}\right)$$

Ejercicio: Determinar la transformación  $T: \mathbb{R}^2 \to \mathbb{R}^2$  que realiza primero una rotación de  $\theta = \frac{\pi}{4}$  (seutido antihorario) y después un deslizamiento cortante un la dirección del eje x. A demás, se verifica que :  $T(-3\sqrt{2}, \sqrt{2}) = (2,-2)$ .

$$A = A_{T_2} \cdot A_{T_1} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \frac{r_2}{2} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1+k & -1+k \\ 1 & 1 \end{pmatrix}$$

$$\text{dest. rot.}$$

$$A_{T_1} = \begin{pmatrix} \cos \theta & -\sec \theta \\ \sec \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} \cos \frac{\pi}{4} & -\sec \frac{\pi}{4} \\ \sec \frac{\pi}{4} & \cos \frac{\pi}{4} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} &$$

$$A_{T_2} = \begin{pmatrix} 1 & K \\ 0 & 1 \end{pmatrix}$$

$$T(-3\sqrt{2},\sqrt{2}) = (2,-2)$$

$$A \cdot \begin{pmatrix} -3\sqrt{2} \\ \sqrt{2} \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \end{pmatrix} \longrightarrow \frac{\sqrt{2}}{2} \cdot \begin{pmatrix} 1+\kappa & -1+\kappa \\ 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} -3\sqrt{2} \\ \frac{2}{2} \\ \frac{2}{2} \end{pmatrix} = \frac{2\times 2}{2\times 1}$$

$$= 1. \begin{pmatrix} 1+\kappa & -1+\kappa \\ 1 & 1 \end{pmatrix} - \begin{pmatrix} -3 \\ 1 \end{pmatrix} = \begin{pmatrix} -3-3\kappa-1+\kappa \\ -2 \end{pmatrix} = \begin{pmatrix} -4-2\kappa \\ -2 \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ -2 \end{pmatrix} \qquad 2\kappa = -6 \rightarrow \boxed{\kappa = -3}$$

$$= -2 = -2 \quad \checkmark$$

$$A_{\top} = \frac{\sqrt{2}}{2} \begin{pmatrix} -2 & -4 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -\sqrt{2} & -2\sqrt{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix}$$

$$T(x,y) = \left(-\sqrt{2} \cdot x - 2\sqrt{2} \cdot y + \frac{\sqrt{2}}{2} \cdot x + \frac{\sqrt{2}}{2} \cdot y\right)$$

Ejercicio: Obtener la matriz asociada a la transformación lineal  $T: \mathbb{R}^2 \to \mathbb{R}^2$  tal que primero aplica una rotación de ángulo  $\frac{4\pi}{3}$  y a continuación realiza una simetría respecto al eje y. En caso de existir, encontrar un vector  $\vec{u}$  de  $\mathbb{R}^2$  perteneciente al subespació  $U = L \{(1, -\sqrt{3})\}$  tal que  $T(\vec{u}) = (-10, 0)$ .

$$A_{T_1} = \begin{pmatrix} \cos \frac{4\pi}{3} & -\sin \frac{4\pi}{3} \\ \sin \frac{4\pi}{3} & \cos \frac{4\pi}{3} \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

$$A_{T_2} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$A = A_{T_2} \cdot A_{T_1} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{-1}{2} \end{pmatrix}$$

$$T(x,y) = \left(\frac{x - \sqrt{3}y}{2} - \frac{\sqrt{3}x - y}{2}\right)$$

Come 
$$\vec{u} \in U$$
:  $\vec{u} = \alpha (1 - \sqrt{3}) = (\alpha - \alpha \sqrt{3}) = (-5, 5\sqrt{3})$ 

$$A \cdot \vec{n} = \vec{n} \qquad \longrightarrow \qquad \left( \begin{array}{cc} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{array} \right) \cdot \left( \begin{array}{c} \alpha \\ -\alpha \sqrt{3} \end{array} \right) = \left( \begin{array}{c} -10 \\ 0 \end{array} \right)$$

$$\frac{1}{2}\alpha + \frac{3}{2}\alpha = -10$$

$$-\frac{\sqrt{3}}{2}\alpha + \frac{\sqrt{3}}{2}\alpha = 0$$

$$2\alpha = -10$$

$$2\alpha = -10$$

$$2 = -5$$