

# lab10

June 13, 2024

## 0.1 Lab 10

Kacper Szot, Jakub Rękas ### Zadanie 1 Dane jest równie różniczkowe

$$\frac{du}{dx} = \cos(\omega x)$$

dla  $x \in \Omega$ ,

gdzie  $x, \omega, u \in \mathbb{R}$

$\Omega = \{x \mid -2\pi \leq x \leq 2\pi\}$  to dziedziną szukanego rozwiązania

$u(\cdot)$  to poszukiwana funkcja Warunek początkowy

$$u(0) = 0.$$

Analityczne rozwiązanie równania z warunkiem początkowym przybiera następującą postać:

$$u(x) = \frac{1}{\omega} \sin(\omega x).$$

```
[ ]: import torch
import torch.nn as nn
import numpy as np
import matplotlib.pyplot as plt
```

```
[ ]: def exact_solution(x, w0):
    "Defines the analytical spectral bias problem"
    return (1/w0) * np.sin(w0 * x)
```

```
[ ]: device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
print(torch.cuda.device_count())
print(torch.cuda.current_device())
print(device)

class FCN(nn.Module):
    "Defines a fully-connected network in PyTorch"
    def __init__(self, N_INPUT, N_OUTPUT, N_HIDDEN, N_LAYERS):
        super().__init__()
        activation = nn.Tanh
```

```

self.fcs = nn.Sequential(*[
    nn.Linear(N_INPUT, N_HIDDEN),
    activation()])
self.fch = nn.Sequential(*[
    nn.Sequential(*[
        nn.Linear(N_HIDDEN, N_HIDDEN),
        activation()]) for _ in range(N_LAYERS-1)])
self.fce = nn.Linear(N_HIDDEN, N_OUTPUT)
def forward(self, x):
    x = self.fcs(x)
    x = self.fch(x)
    x = self.fce(x)
    return x

```

```

1
0
cuda

```

```
[ ]: torch.manual_seed(123)
```

```
[ ]: <torch._C.Generator at 0x79c8505c1f70>
```

```

[ ]: # train the PINN
def train(pinn, w0, test_points, train_steps=50001, train_points=3000):
    x_boundary = torch.tensor(0., device=device).view(-1, 1).requires_grad_(True) #
    x_physics = torch.linspace(-2*np.pi, 2*np.pi, train_points, device=device).
    ↪view(-1, 1).requires_grad_(True) #
    x_test = torch.linspace(-2*np.pi, 2*np.pi, test_points, device=device).view(-1, 1)
    u_exact = exact_solution(x_test.cpu(), w0)
    optimiser = torch.optim.Adam(pinn.to(device).parameters(), lr=0.001)
    losses = []
    for i in range(train_steps):
        optimiser.zero_grad()

        # compute boundary loss
        u = pinn(x_boundary) #
        loss1 = (torch.squeeze(u))**2

        # compute physics loss
        u = pinn(x_physics) #
        dudx = torch.autograd.grad(u, x_physics, torch.ones_like(u), ↪
    ↪create_graph=True)[0] #
        loss2 = torch.mean((dudx - torch.cos(x_physics*w0))**2)
        loss = loss1 + loss2
        losses.append(loss.cpu().detach().numpy())

        # backpropagate joint loss, take optimiser step

```

```

loss.backward()
optimiser.step()

#plot the result as training progresses
if i % 10000 == 0:
    u = pinn(x_test).detach()
    plt.figure(figsize=(6,2.5))
    plt.plot(x_test.cpu()[0], u_exact[0], label="Exact solution",
↳color="tab:grey")
    plt.plot(x_test.cpu()[0], u.cpu()[0], label="PINN solution",
↳color="tab:green")
    plt.title(f"Training step {i}")
    plt.legend()
    plt.show()

plt.title("loss function")
plt.yscale("log")
plt.xlabel('Iteration')
plt.ylabel('Loss')
plt.plot(losses)
plt.show()

```

(a) Przypadek  $\omega = 1$ .

2 warstwy ukryte, 16 neuronów w każdej warstwie

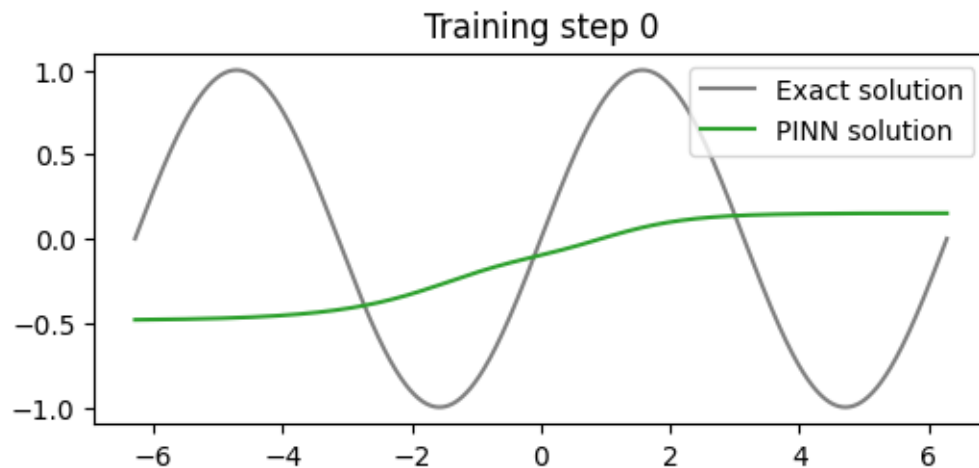
liczba punktów treningowych: 200

liczba punktów testowych: 1000

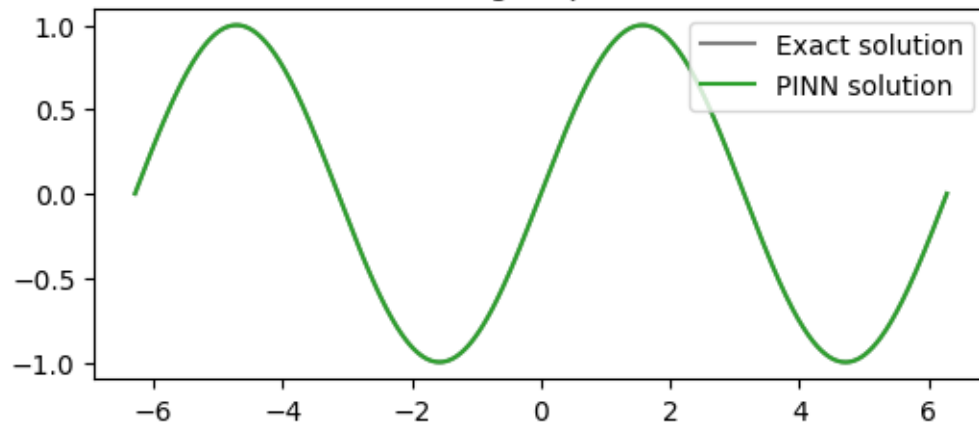
```

[ ]: #zadanie 1 model a
pinn = FCN(1,1,16,2)
train(pinn=pinn,w0=1,test_points=1000,train_points=200)

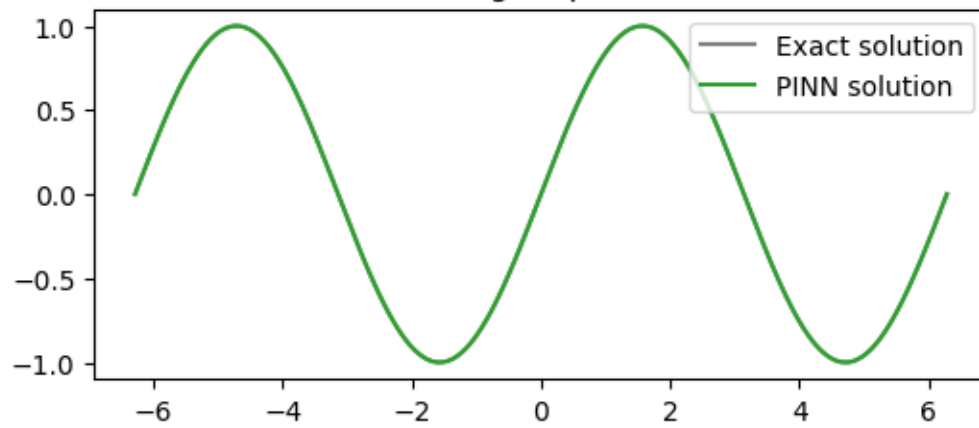
```



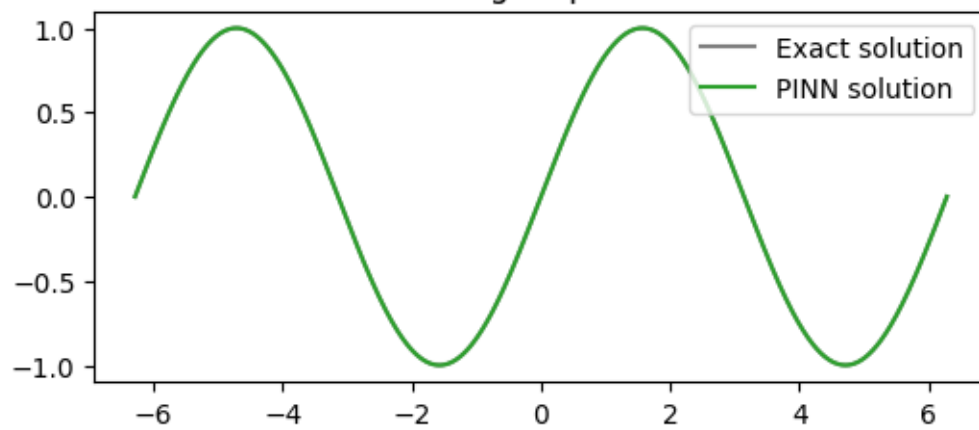
Training step 10000

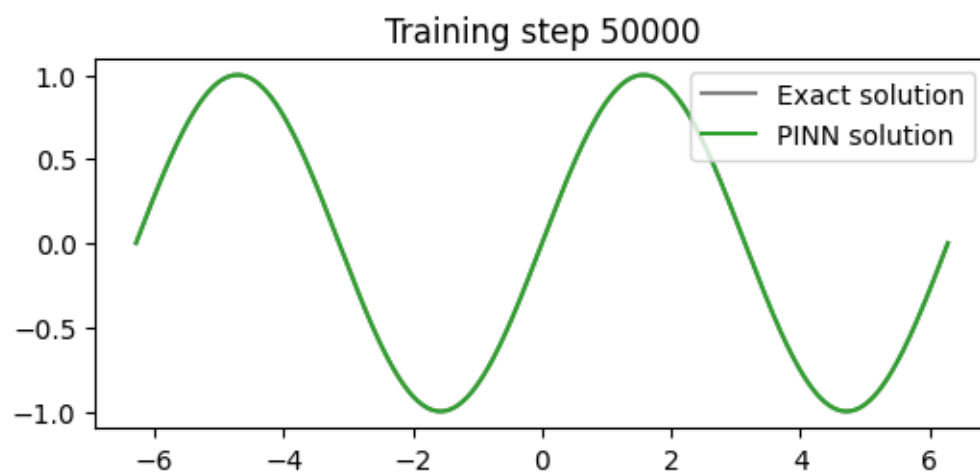
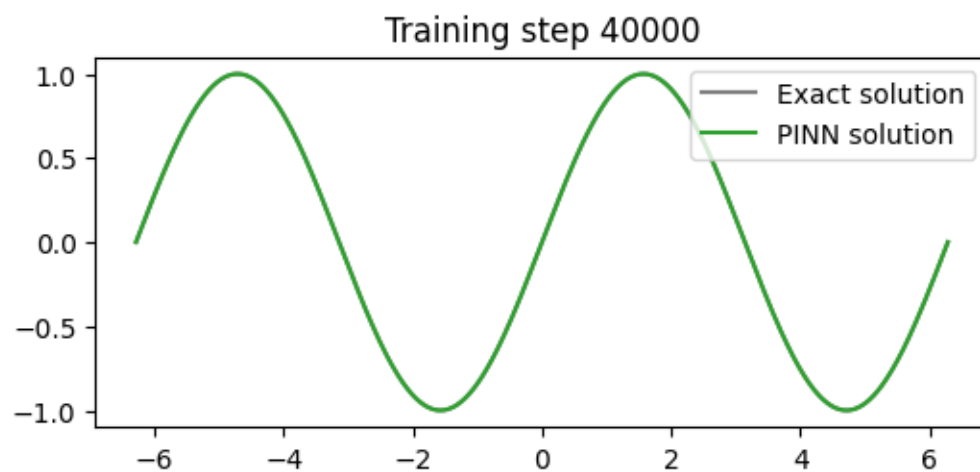


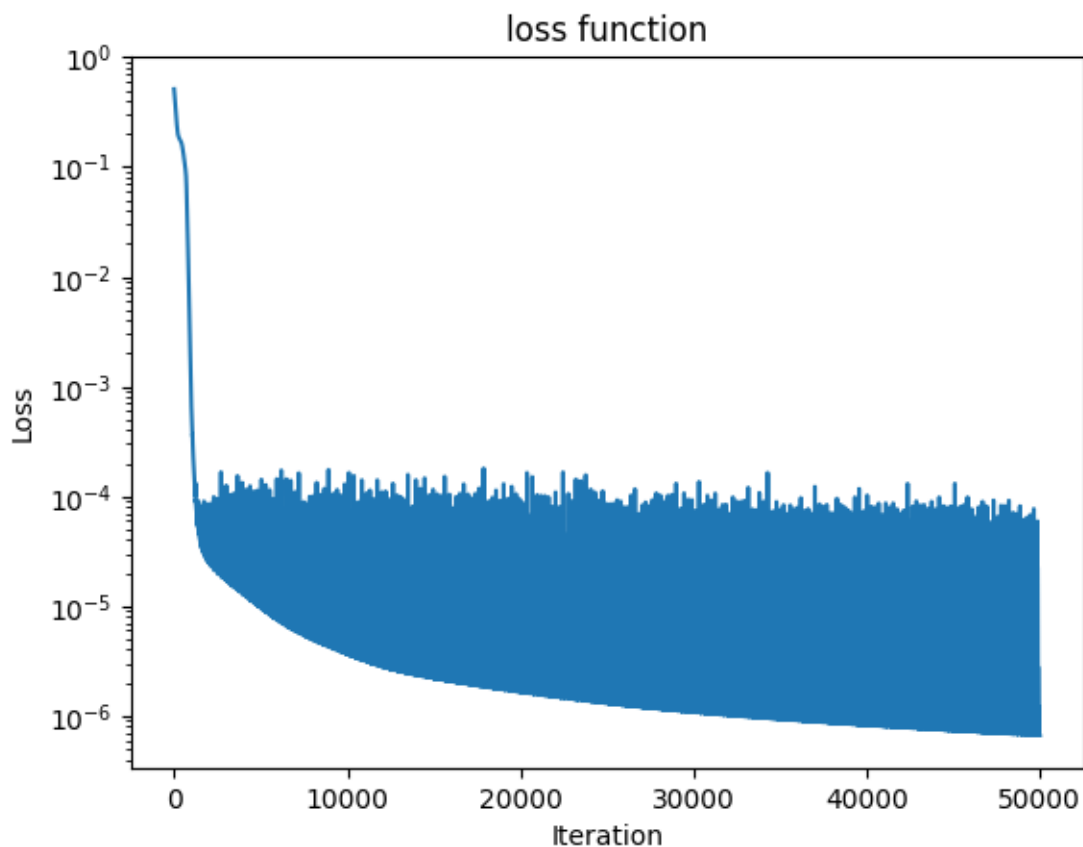
Training step 20000



Training step 30000



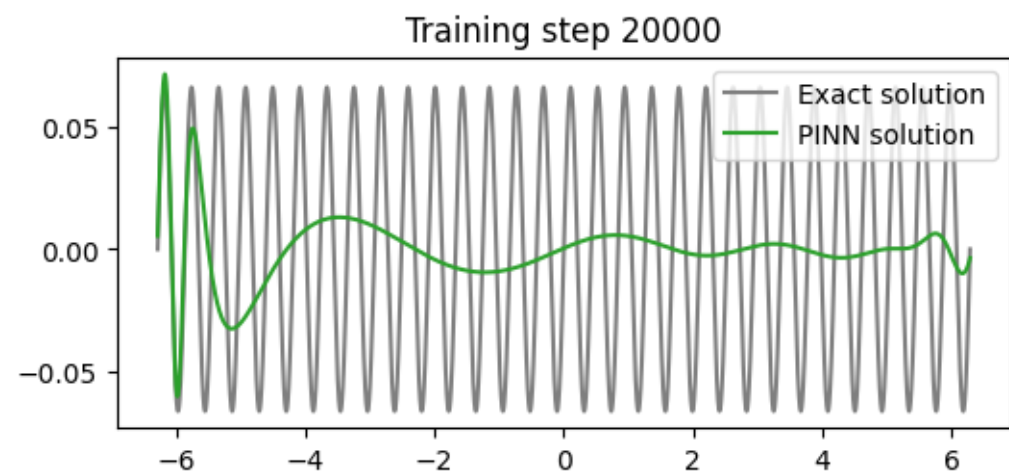
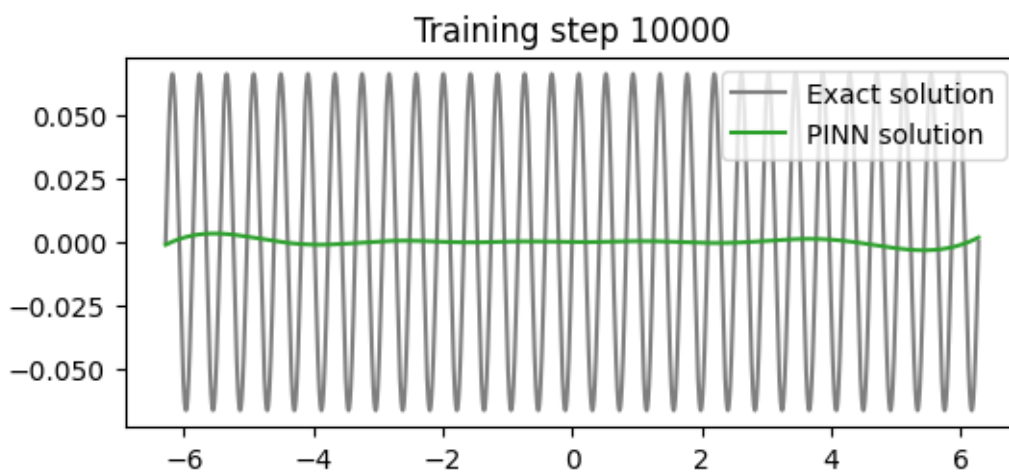
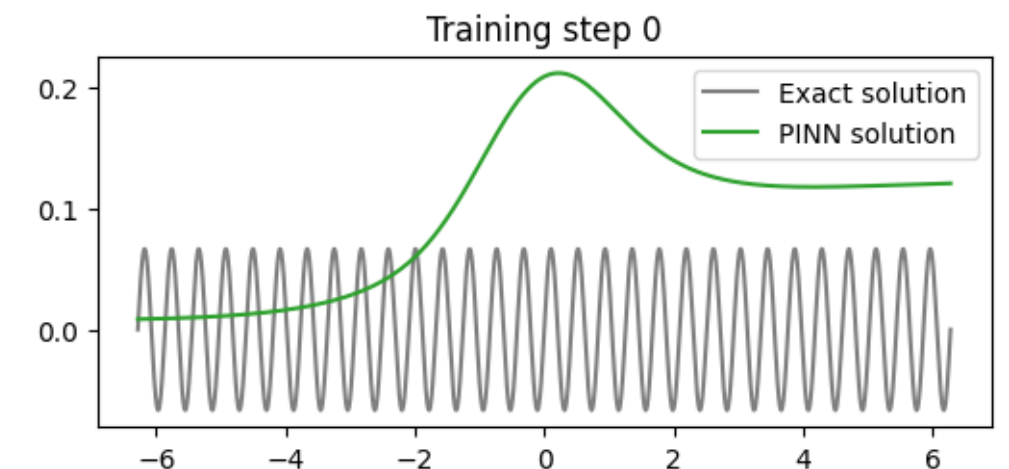


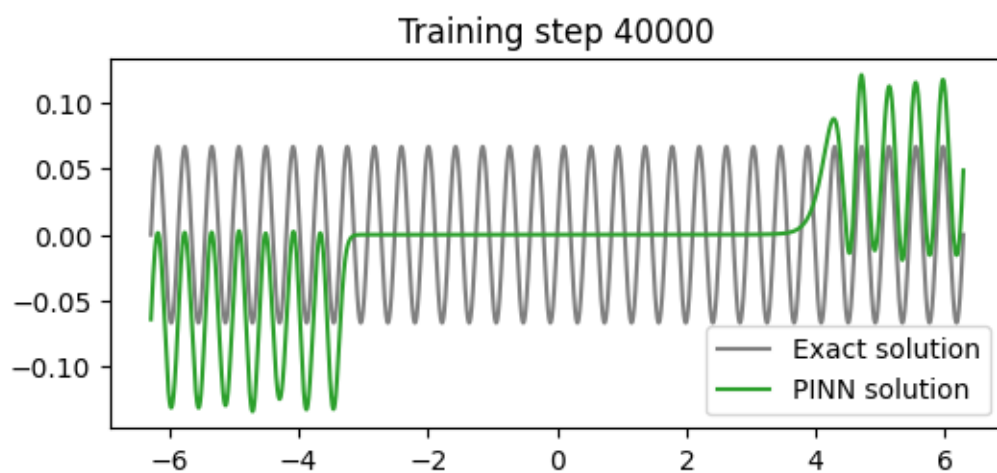
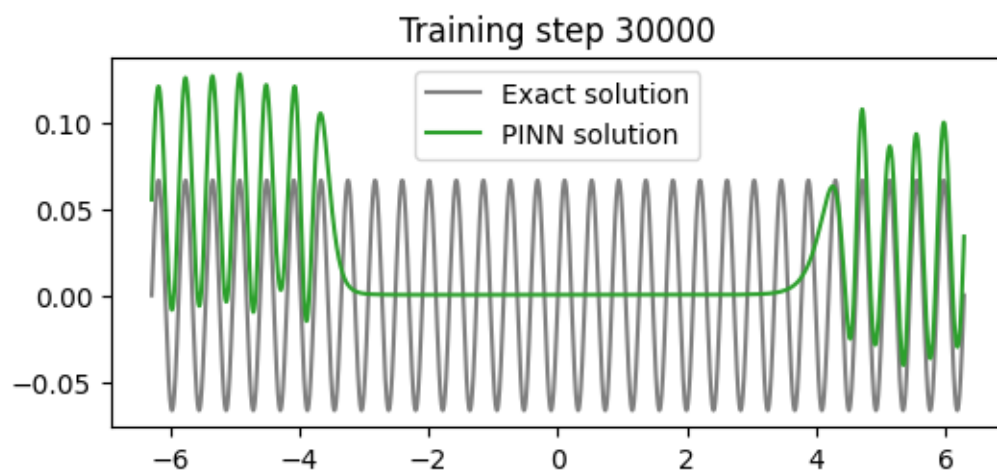


Sieć mimo małych rozmiarów, realatywnie szybko osiąga zbierczość i dobre wyniki.

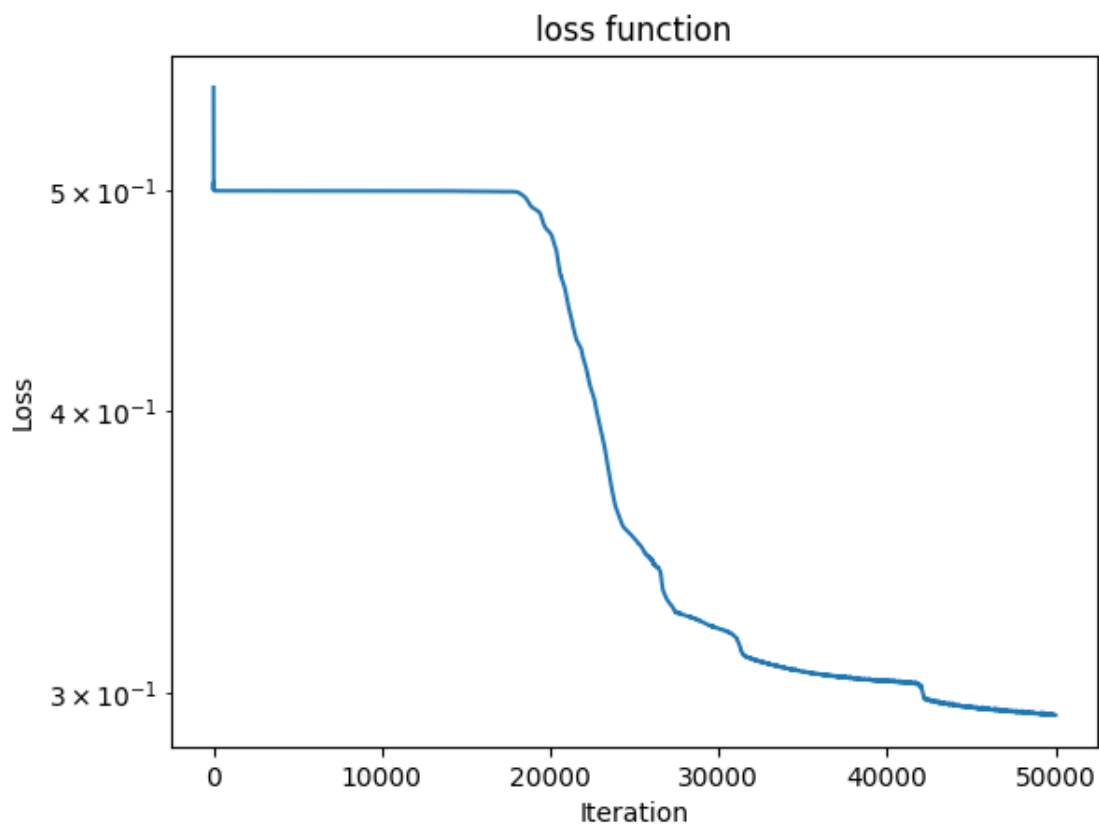
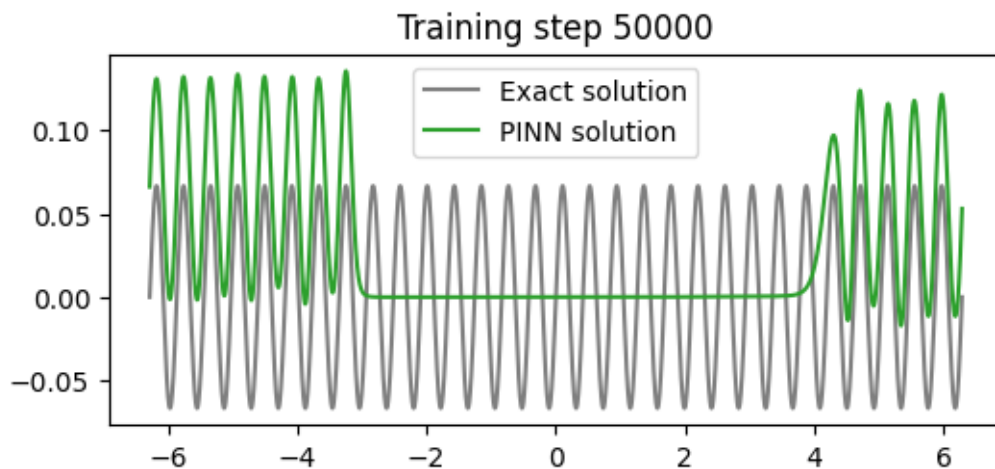
- (b) Przypadek  $\omega = 15$ . 2 warstwy ukryte, 16 neuronów w każdej warstwie  
 liczba punktów treningowych: 3000  
 liczba punktów testowych: 5000

```
[ ]: #zadanie 1 podpunkt b model b
pinn = FCN(1,1,16,2)
train(pinn=pinn,w0=15,test_points=5000,train_points=3000)
```







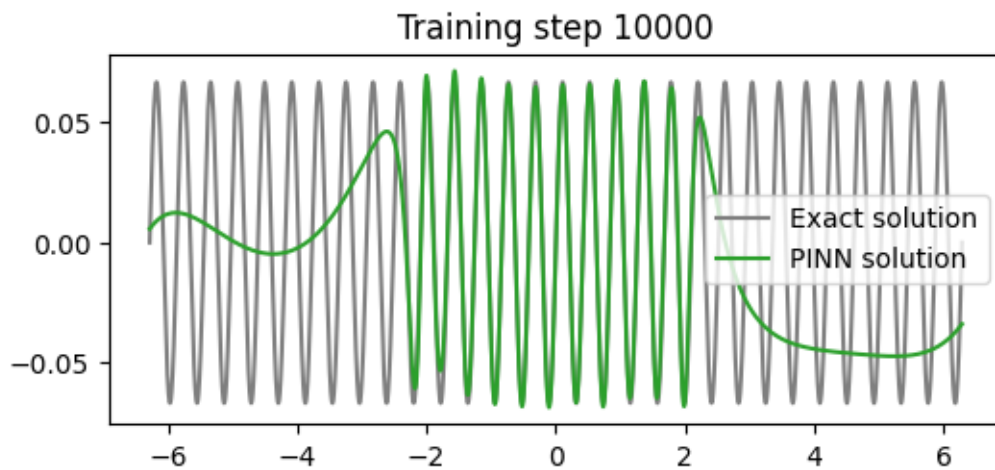
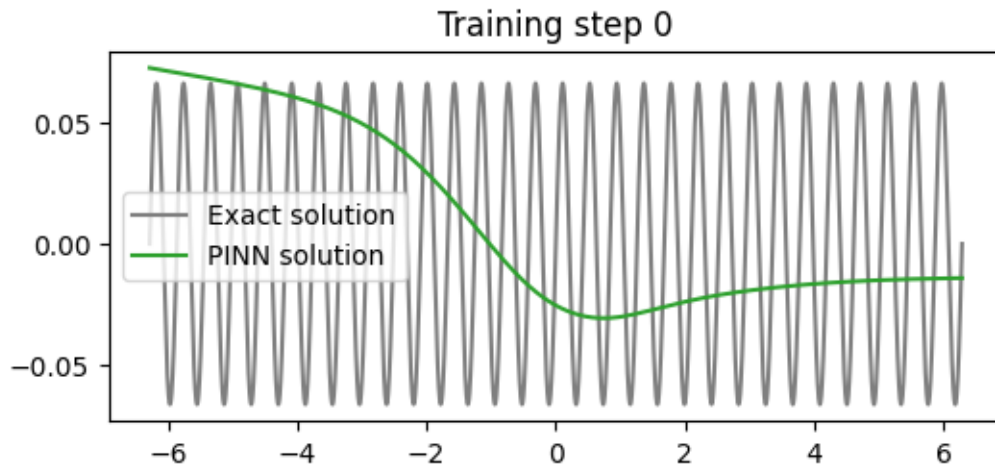


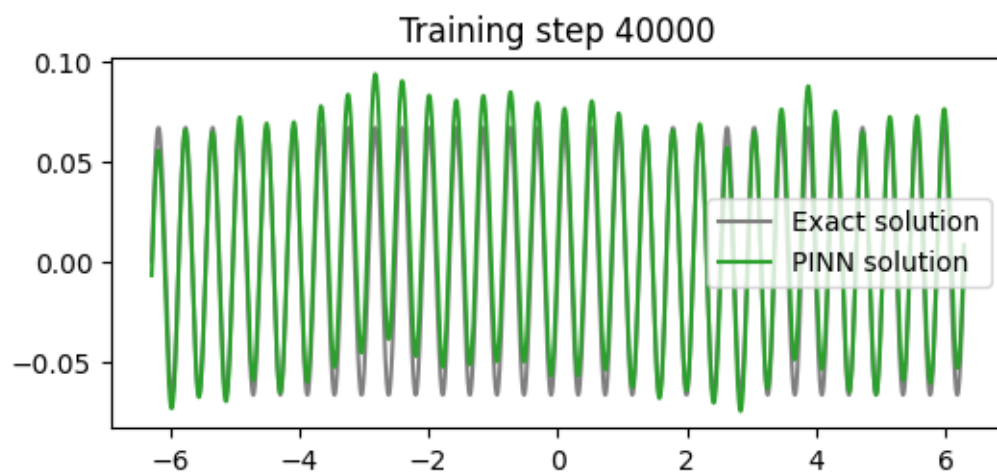
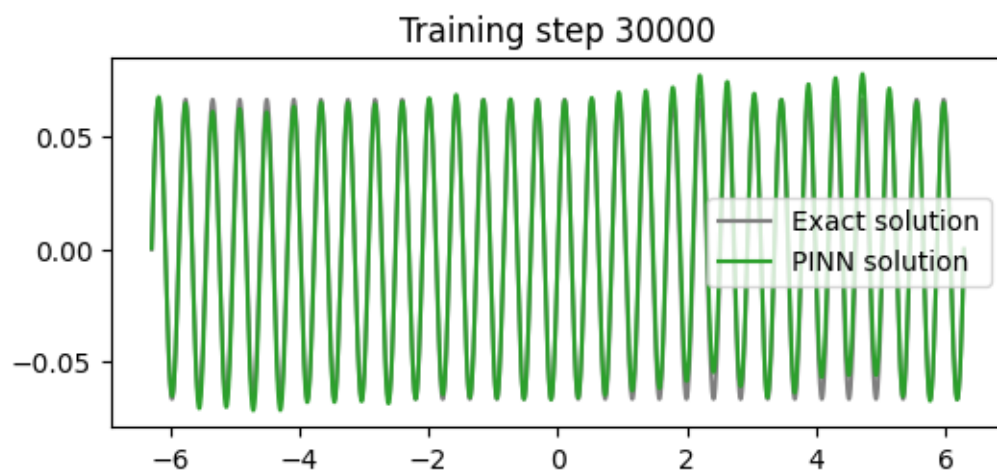
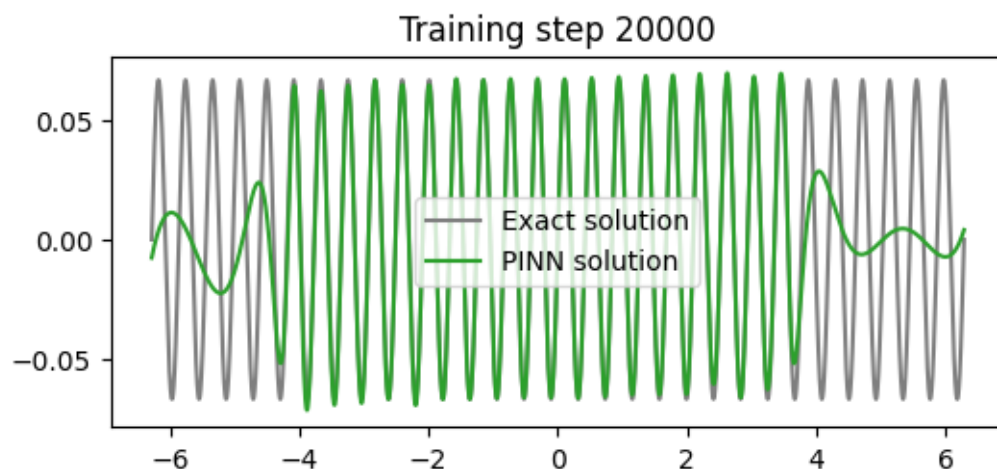
Małej sieci neuronowej nie udaje się osiągnąć zadowalających wyników w trakcie 50000 iteracji dla wysokiej częstotliwości.

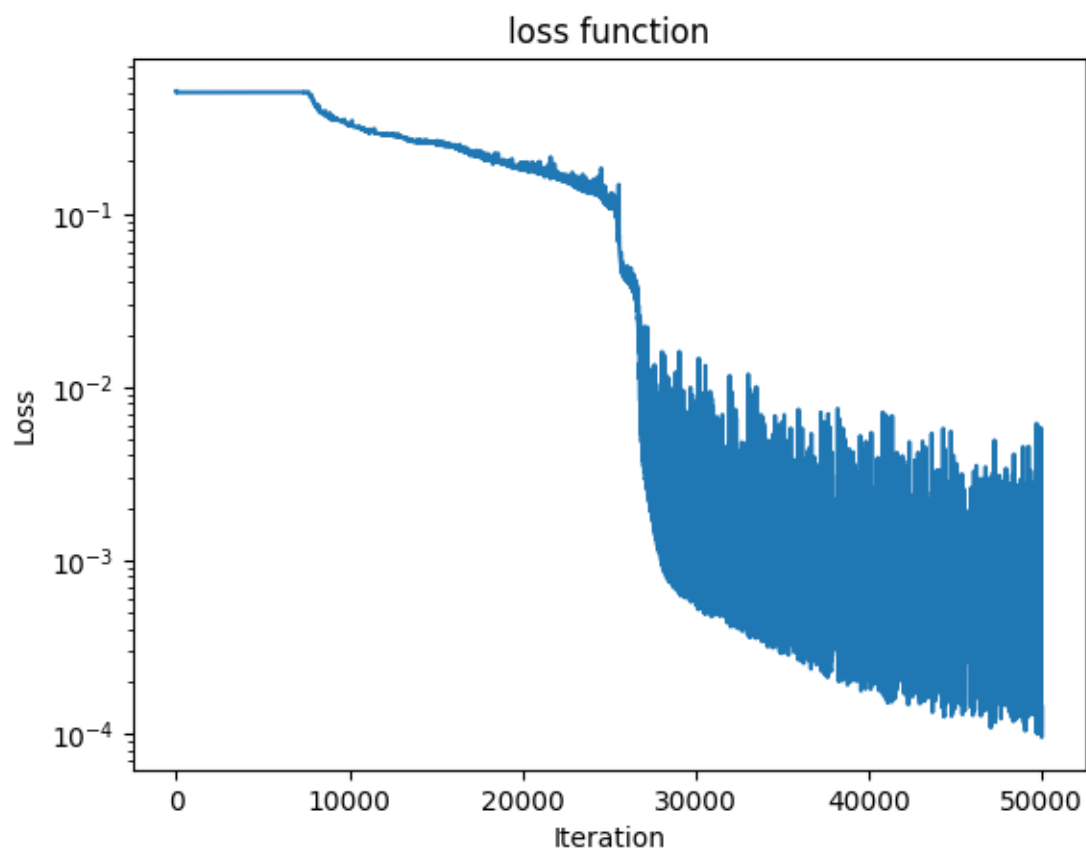
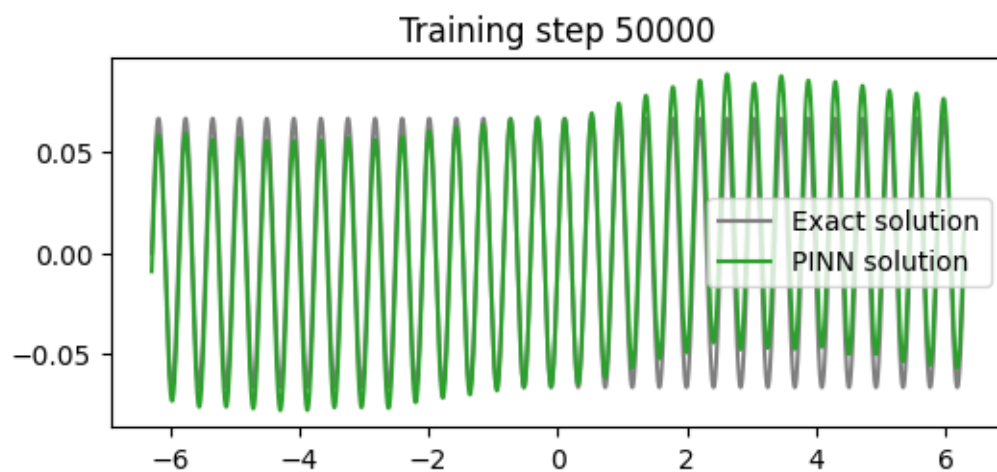
- (b) Przypadek  $\omega = 15$ . 4 warstwy ukryte, 64 neuronów w każdej warstwie  
liczba punktów treningowych: 3000

liczba punktów testowych: 5000

```
[ ]: #zadanie 1 podpunkt b model c
pinn = FCN(1,1,64,4)
train(pinn=pinn,w0=15,test_points=5000,train_points=3000)
```





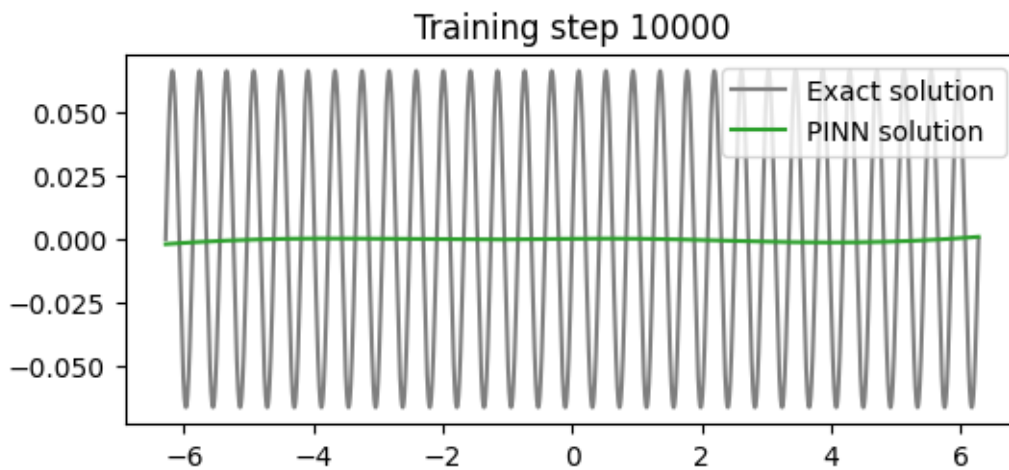
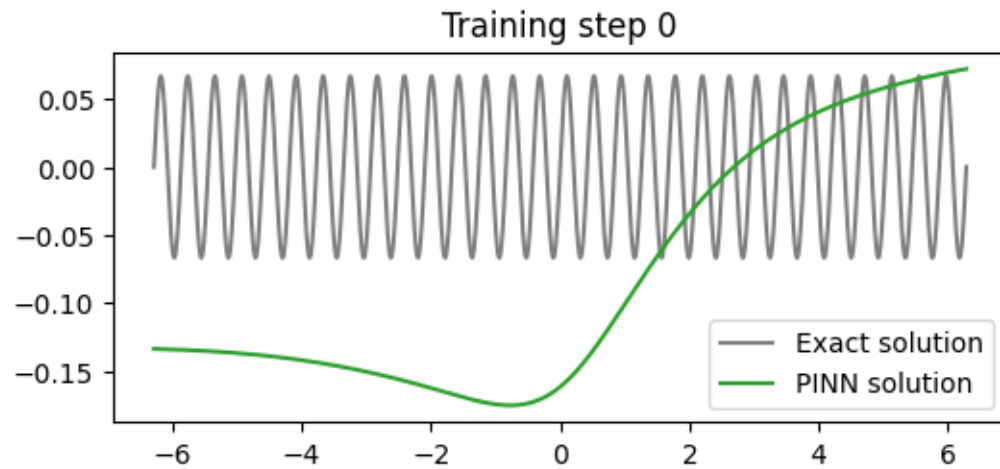


Sieci neuronowej udaje się osiągnąć zadowalających wyników w trakcie 50000 iteracji dla wysokiej

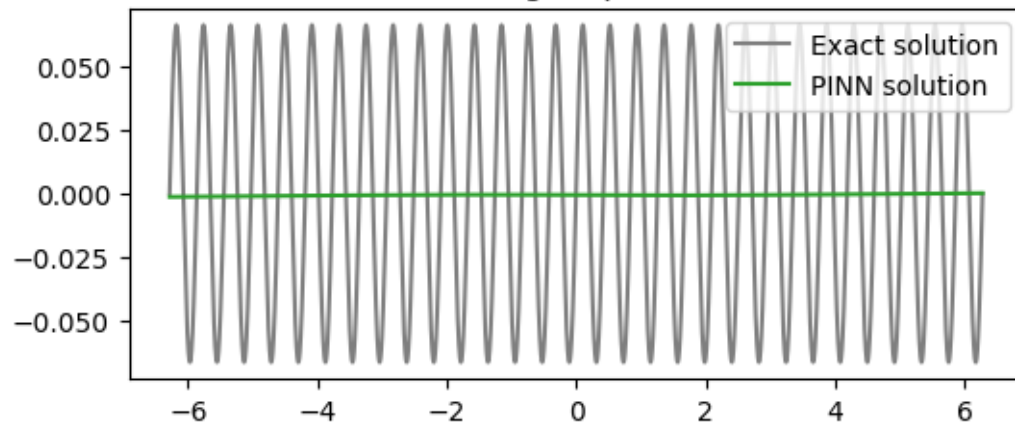
częstotliwości.

- (b) Przypadek  $\omega = 15$ . 5 warstw ukryte, 128 neuronów w każdej warstwie  
liczba punktów treningowych: 3000  
liczba punktów testowych: 5000

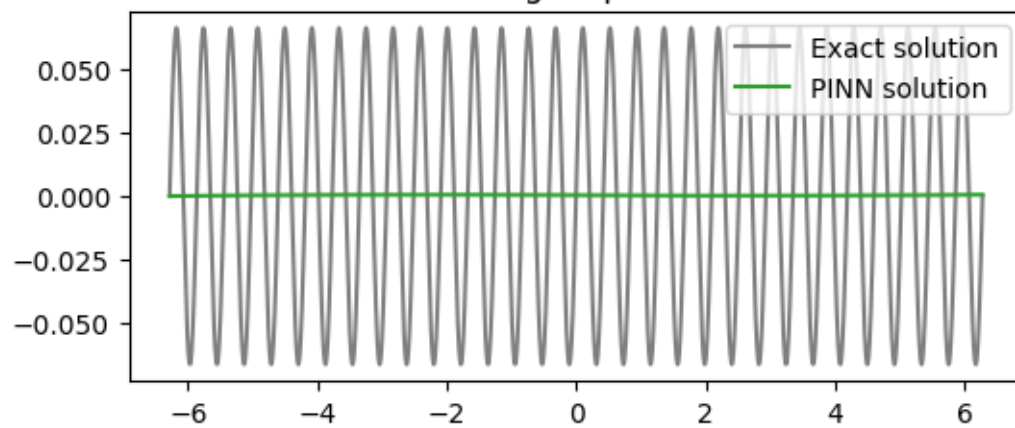
```
[ ]: #zadanie 1 podpunkt b model c
pinn = FCN(1,1,128,5)
train(pinn=pinn,w0=15,test_points=5000,train_points=3000)
```



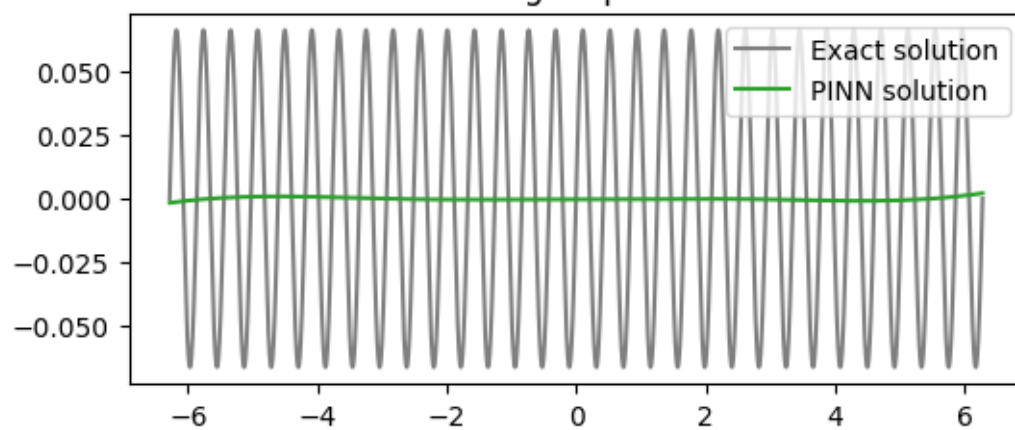
Training step 20000

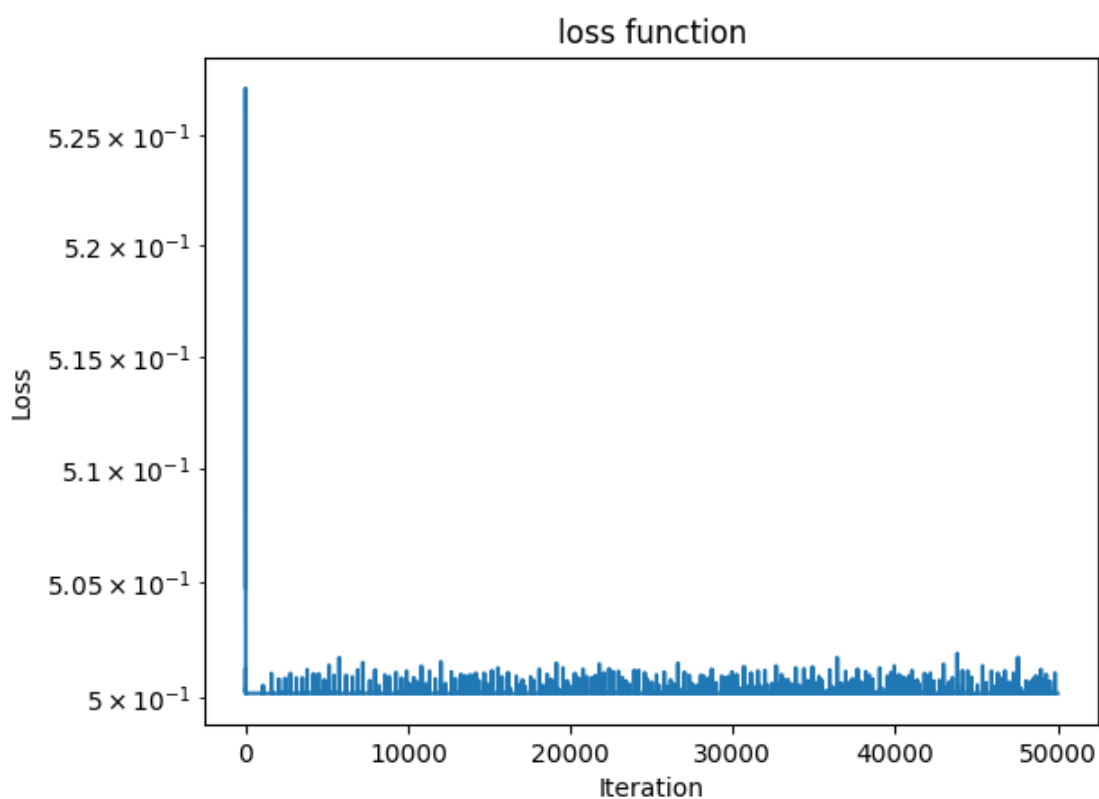
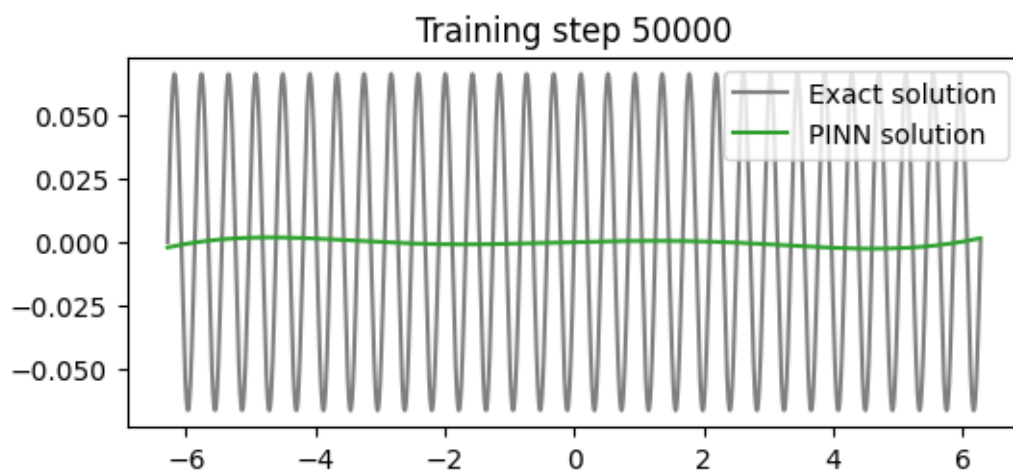


Training step 30000



Training step 40000





Dużej sieci neuronowej nie udaje się osiągnąć zadowalających wyników w trakcie 50000 iteracji dla wysokiej częstotliwości, prawdopodobnie 50000 to zbyt mało iteracji.

- (c) 4 warstwy ukryte, 64 neuronów w każdej warstwie  
 liczba punktów treningowych: 3000  
 liczba punktów testowych: 5000  
 Aby zagwarantować spełnienie warunku  $\hat{u}(0) = 0$  wprowadzamy  $\hat{u}(x) = \tanh(\omega x) \cdot NN(x)$

```
[ ]: # zadanie 1 podpunkt c
# zastosowanie  $u = \tanh(w_0, x) \cdot NN(x;0)$ 
def train_using_tanh_in_output(pinn, w0, test_points,
    ↪train_steps=50001, train_points=3000):
    x_boundary = torch.tensor(0., device=device).view(-1,1).requires_grad_(True) #
    x_physics = torch.linspace(-2*np.pi, 2*np.pi, train_points, device=device).
    ↪view(-1,1).requires_grad_(True) #
    x_test = torch.linspace(-2*np.pi, 2*np.pi, test_points, device=device).view(-1,1)
    u_exact = exact_solution(x_test.cpu(), w0)
    losses=[]
    optimiser = torch.optim.Adam(pinn.to(device).parameters(), lr=0.001)
    for i in range(train_steps):
        optimiser.zero_grad()
        # compute physics loss
        u = torch.tanh(x_physics*w0) * pinn(x_physics) #
        dudx = torch.autograd.grad(u, x_physics, torch.ones_like(u),
    ↪create_graph=True)[0] #
        loss2 = torch.mean((dudx - torch.cos(x_physics*w0))**2)
        loss = loss2
        losses.append(loss.cpu().detach().numpy())

        # backpropagate joint loss, take optimiser step
        loss.backward()
        optimiser.step()

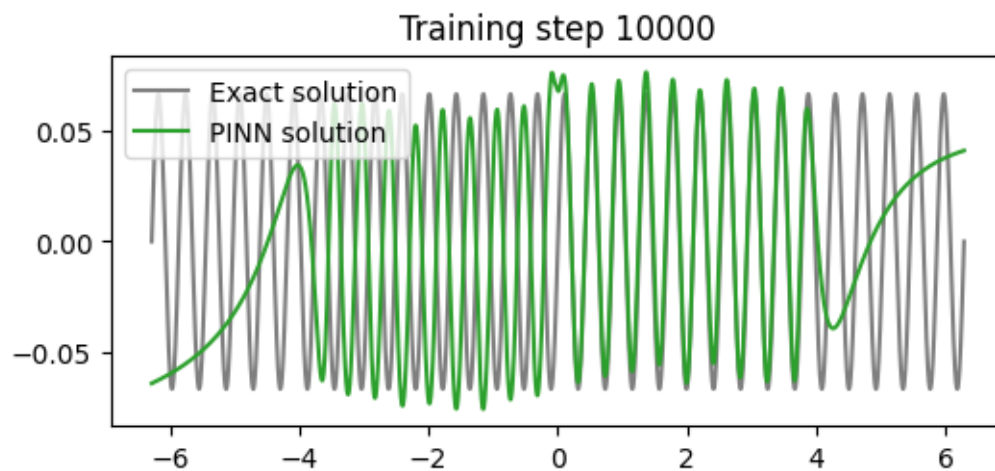
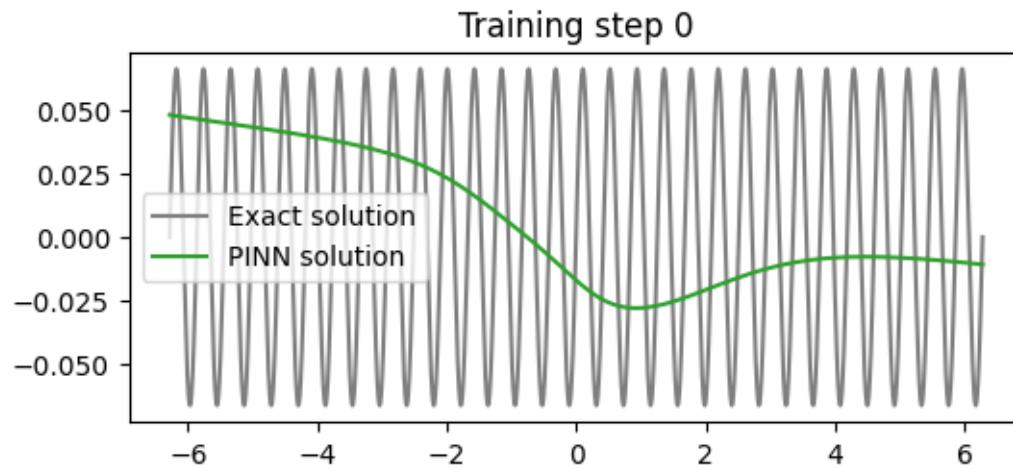
        #plot the result as training progresses
        if i % 10000 == 0:
            u = pinn(x_test).detach()
            plt.figure(figsize=(6,2.5))
            plt.plot(x_test.cpu()[ :,0], u_exact[:,0], label="Exact solution",
    ↪color="tab:grey")
            plt.plot(x_test.cpu()[ :,0], u.cpu()[ :,0], label="PINN solution",
    ↪color="tab:green")
            plt.title(f"Training step {i}")
            plt.legend()
            plt.show()
    plt.title("loss function")
    plt.yscale("log")
    plt.xlabel('Iteration')
    plt.ylabel('Loss')
    plt.plot(losses)
```



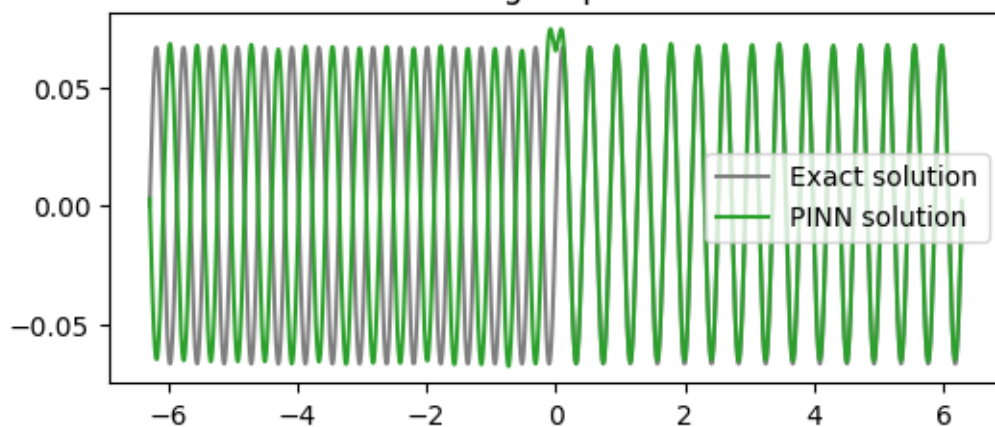
```
plt.show()
```

```
pinn = FCN(1,1,64,4)
```

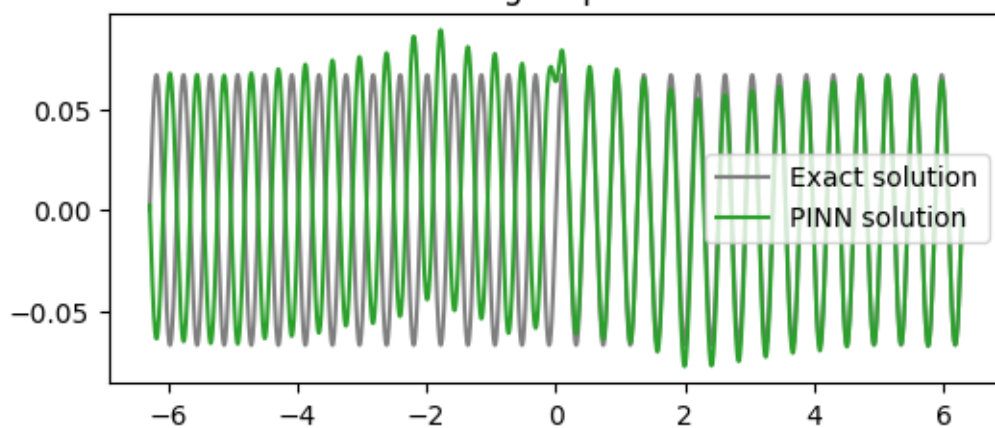
```
train_using_tanh_in_output(pinn=pinn,w0=15,test_points=5000,train_points=3000)
```



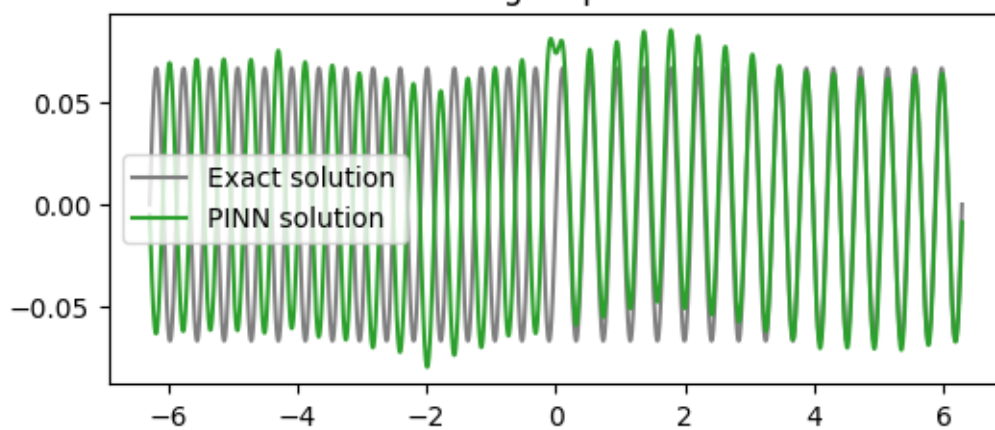
Training step 20000

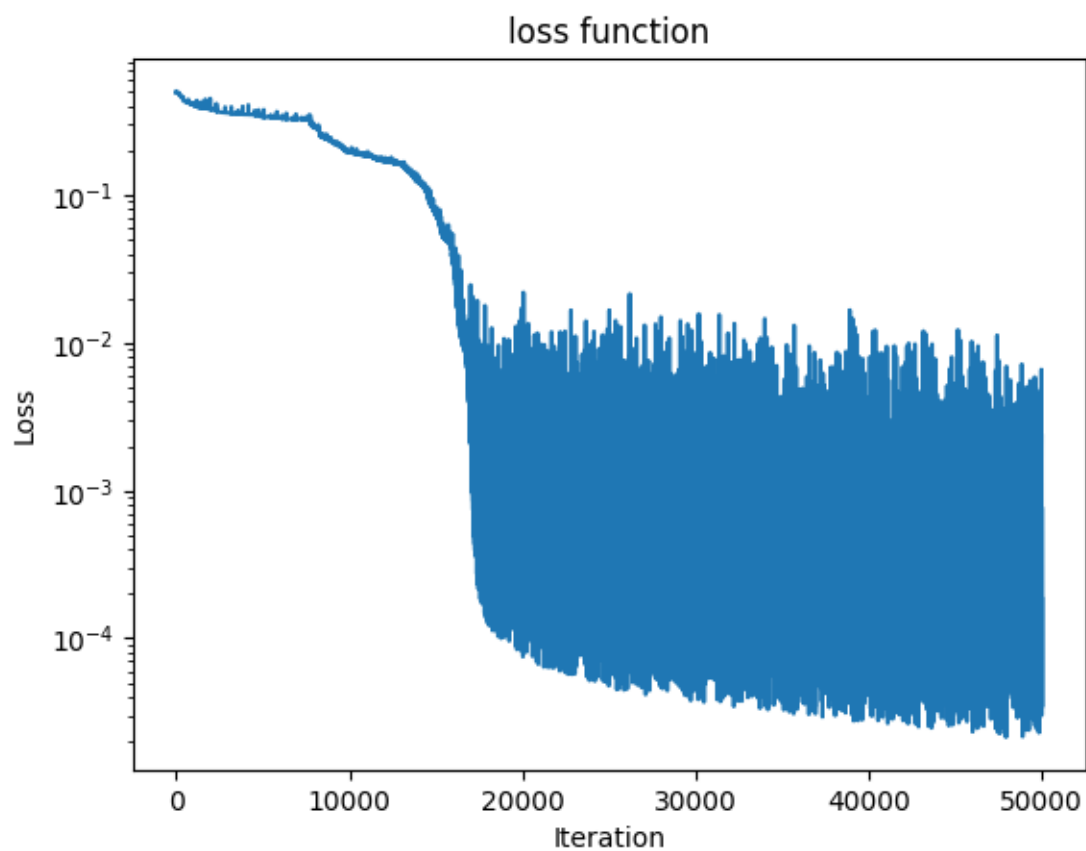
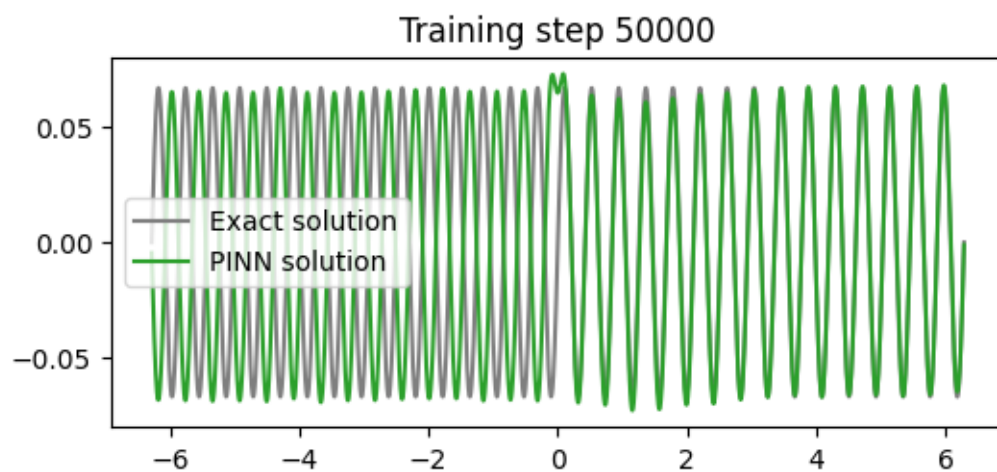


Training step 30000



Training step 40000





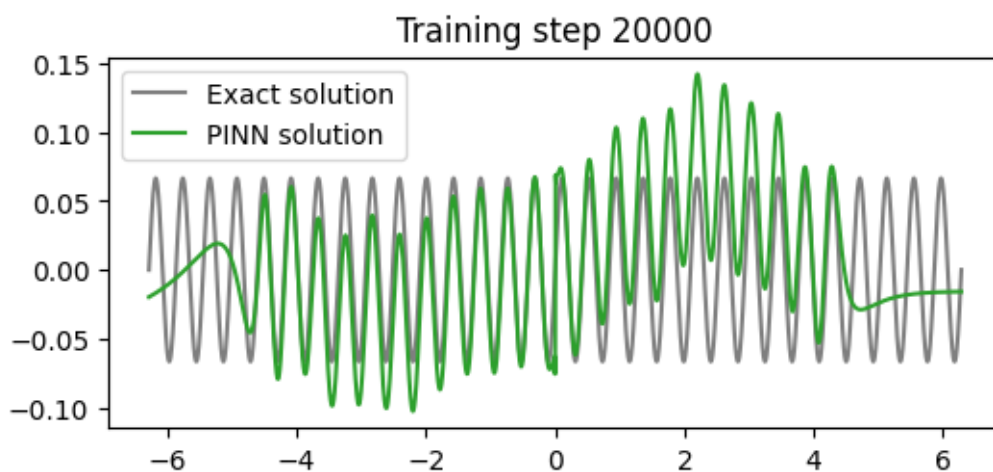
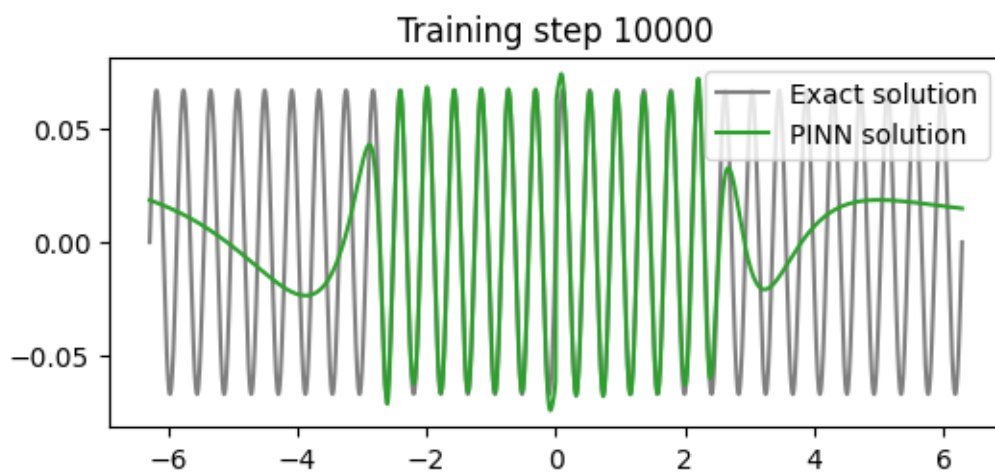
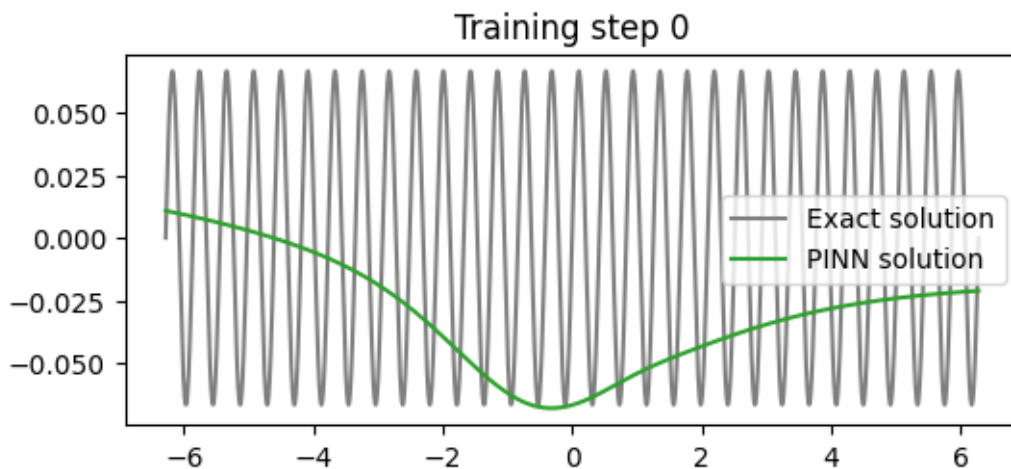
Po 50000 iteracjach można zauważyć, że sieć osiągnęła zbieżność dla  $x = 0$  natomiast nie dla  $x$

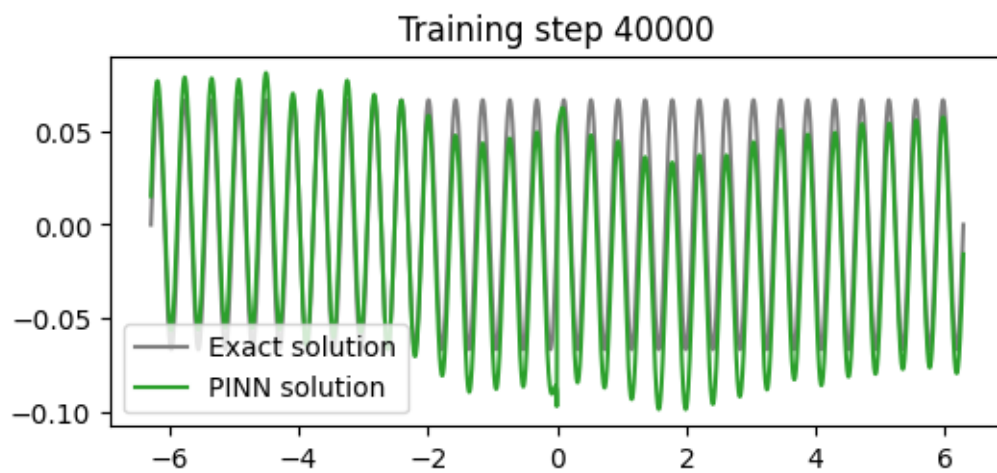
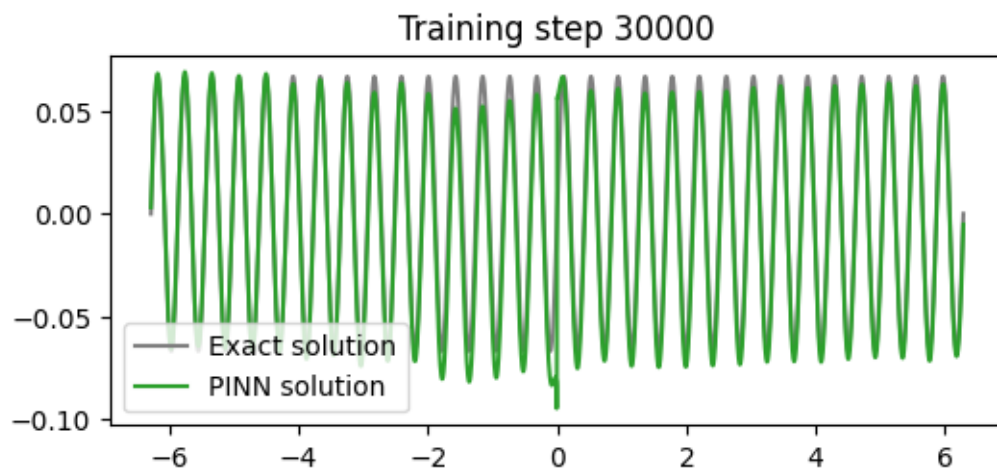
$x < 0$ , gdyż  $\tanh$  jest ujemny dla takich  $x$ , w celu naprawienia tego problemu ustalmy  $\hat{u}(x) = |\tanh(\omega x)| \cdot NN(x)$

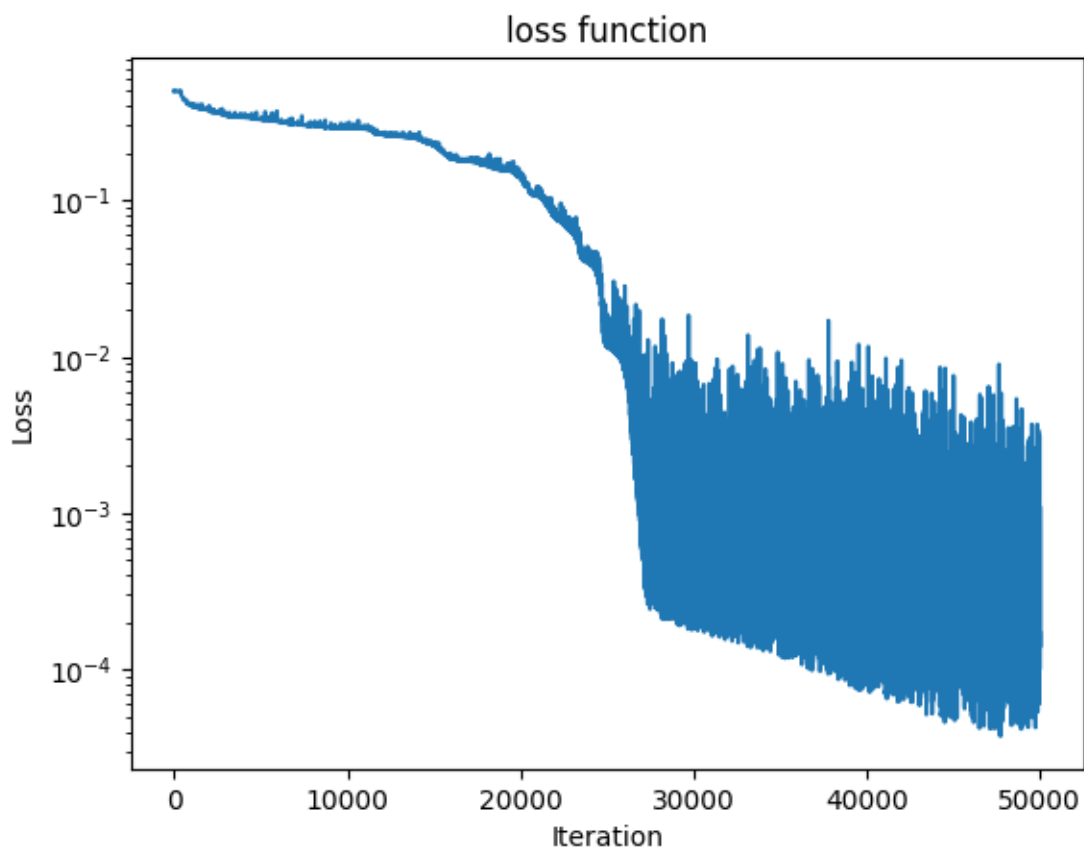
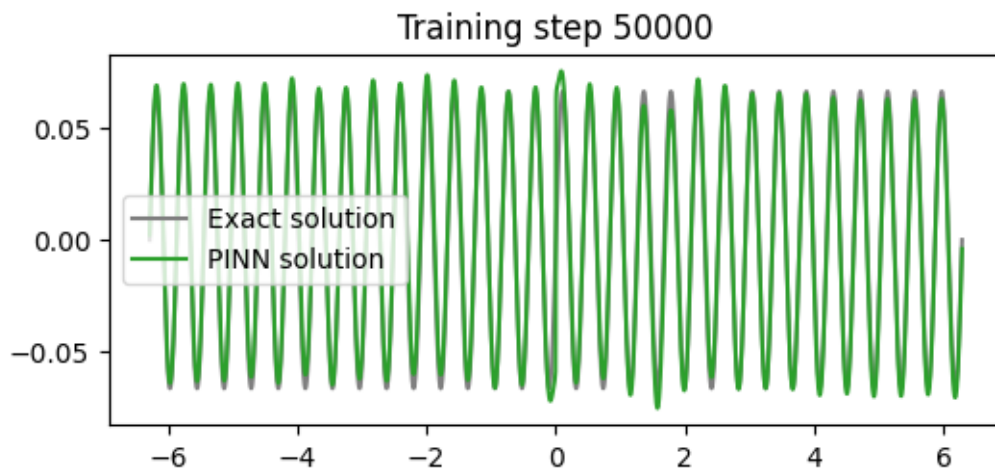
```
[ ]: # zadanie 1 podpunkt c
# zastosowanie  $u = |\tanh(\omega x)| \cdot NN(x; 0)$ 
def train_using_absolute_tanh_in_output(pinn, w0, test_points,
    ↪train_steps=50001, train_points=3000):
    x_boundary = torch.tensor(0., device=device).view(-1, 1).requires_grad_(True) #
    x_physics = torch.linspace(-2*np.pi, 2*np.pi, train_points, device=device).
    ↪view(-1, 1).requires_grad_(True) #
    x_test = torch.linspace(-2*np.pi, 2*np.pi, test_points, device=device).view(-1, 1)
    u_exact = exact_solution(x_test.cpu(), w0)
    optimiser = torch.optim.Adam(pinn.to(device).parameters(), lr=0.001)
    losses = []
    for i in range(train_steps):
        optimiser.zero_grad()
        # compute physics loss
        u = abs(torch.tanh(x_physics*w0)) * pinn(x_physics) #
        dudx = torch.autograd.grad(u, x_physics, torch.ones_like(u),
    ↪create_graph=True)[0] #
        loss2 = torch.mean((dudx - torch.cos(x_physics*w0))**2)
        loss = loss2
        losses.append(loss.cpu().detach().numpy())
        # backpropagate joint loss, take optimiser step
        loss.backward()
        optimiser.step()

        #plot the result as training progresses
        if i % 10000 == 0:
            u = pinn(x_test).detach()
            plt.figure(figsize=(6, 2.5))
            plt.plot(x_test.cpu()[:, 0], u_exact[:, 0], label="Exact solution",
    ↪color="tab:grey")
            plt.plot(x_test.cpu()[:, 0], u.cpu()[:, 0], label="PINN solution",
    ↪color="tab:green")
            plt.title(f"Training step {i}")
            plt.legend()
            plt.show()
    plt.title("loss function")
    plt.yscale("log")
    plt.xlabel('Iteration')
    plt.ylabel('Loss')
    plt.plot(losses)
    plt.show()

pinn = FCN(1, 1, 64, 4)
train_using_absolute_tanh_in_output(pinn=pinn, w0=15, test_points=5000, train_points=3000)
```







Tym razem sieć daje poprawną odpowiedź dla całej dziedziny.

- (d) 4 warstwy ukryte, 64 neuronów w każdej warstwie  
liczba punktów treningowych: 3000

liczba punktów testowych: 5000

Wagi pierwszej warstwy ukrytej zostały zainicjalizowane cechami Fouriera

```
[ ]: # podpunkt d
from torch.nn import functional as F
class FourierLayer(nn.Linear):
    def __init__(self, N_INPUT, N_HIDDEN):
        super().__init__(N_INPUT, N_HIDDEN)
        self.N_INPUT = N_INPUT
        self.N_HIDDEN = N_HIDDEN
        self.weight = torch.nn.Parameter(self._initialize_weights())

    def _initialize_weights(self):
        weights = np.zeros((self.N_HIDDEN, self.N_INPUT))
        for i in range(self.N_HIDDEN):
            for j in range(self.N_INPUT):
                if j % 2 == 0:
                    weights[i, j] = np.sin(2 ** (j+i) * np.pi)
                else:
                    weights[i, j] = np.cos(2 ** (j+i) * np.pi)
        weights = torch.tensor(weights, dtype=torch.float32)
        return weights

class FCN_fourier_variant(nn.Module):
    "Defines a fully-connected network in PyTorch with Fourier-initialized_
    ↪first layer"
    def __init__(self, N_INPUT, N_OUTPUT, N_HIDDEN, N_LAYERS):
        super().__init__()
        activation = nn.Tanh

        self.fcs = nn.Sequential(*[
            nn.Linear(N_INPUT, N_HIDDEN),
            activation()])

        # Pierwsza warstwa ukryta
        self.ffch = nn.Sequential(
            FourierLayer(N_HIDDEN, N_HIDDEN),
            activation()

        )

        # Warstwy ukryte dalesze
        self.fch = nn.Sequential(*[
            nn.Sequential(
                nn.Linear(N_HIDDEN, N_HIDDEN),
```



```

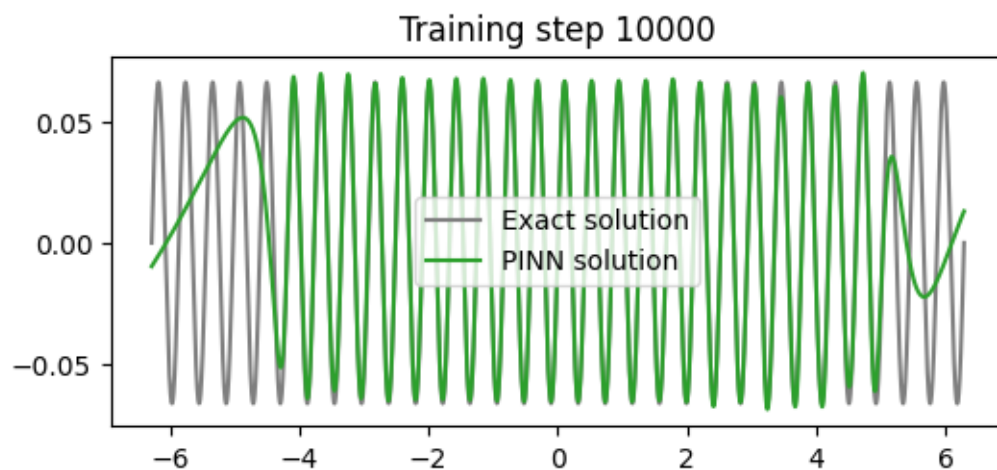
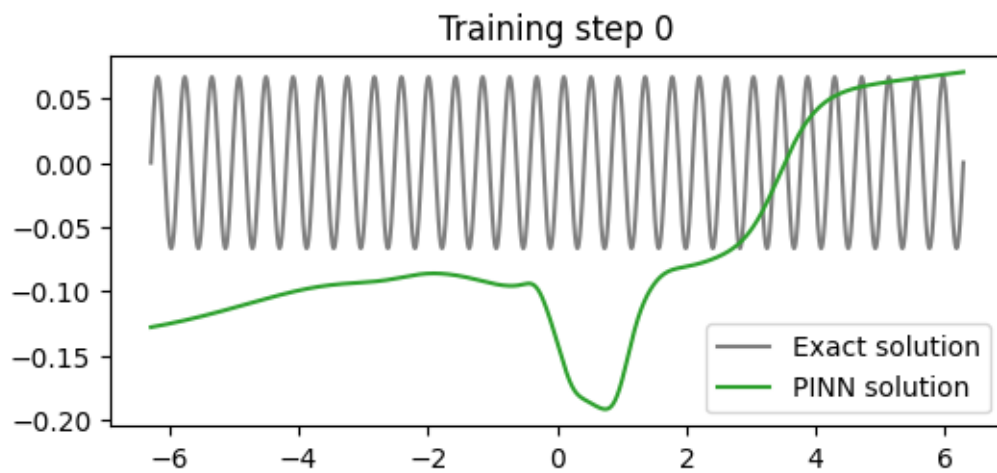
        activation()
    ) for _ in range(N_LAYERS-2)
])

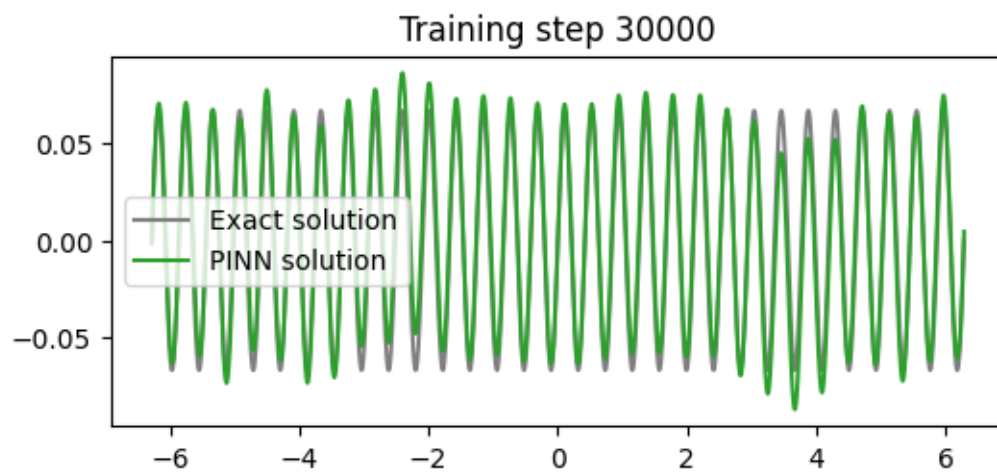
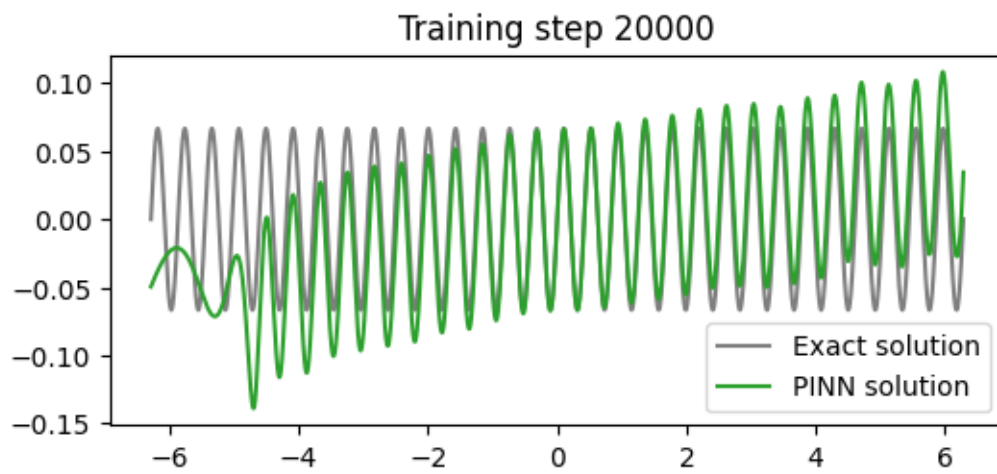
# Warstwa końcowa
self.fce = nn.Linear(N_HIDDEN, N_OUTPUT)

def forward(self, x):
    x = self.fcs(x)
    x = self.ffch(x)
    x = self.fch(x)
    x = self.fce(x)
    return x

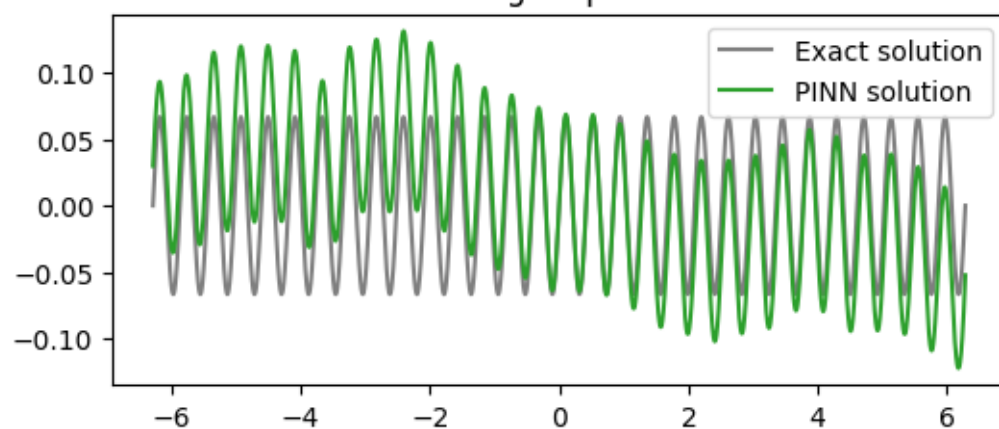
pinn = FCN_fourier_variant(1,1,64,4)
train(pinn=pinn,w0=15,test_points=5000,train_points=3000,train_steps=100001)

```

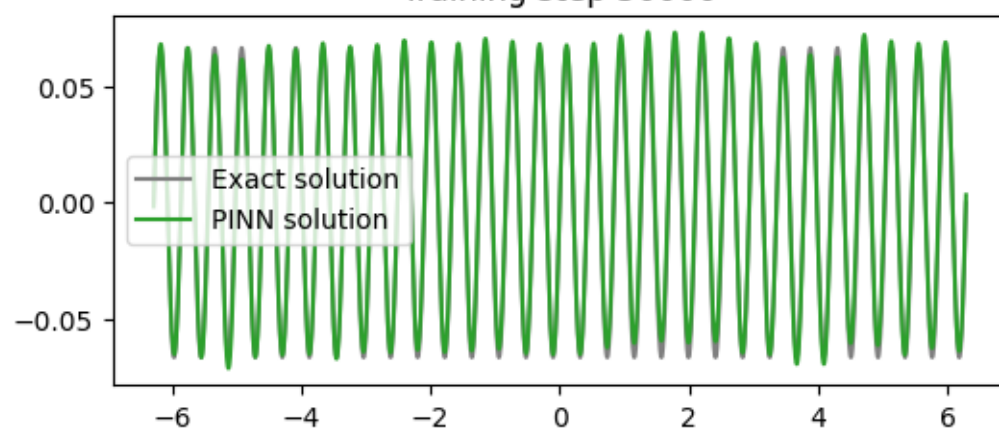




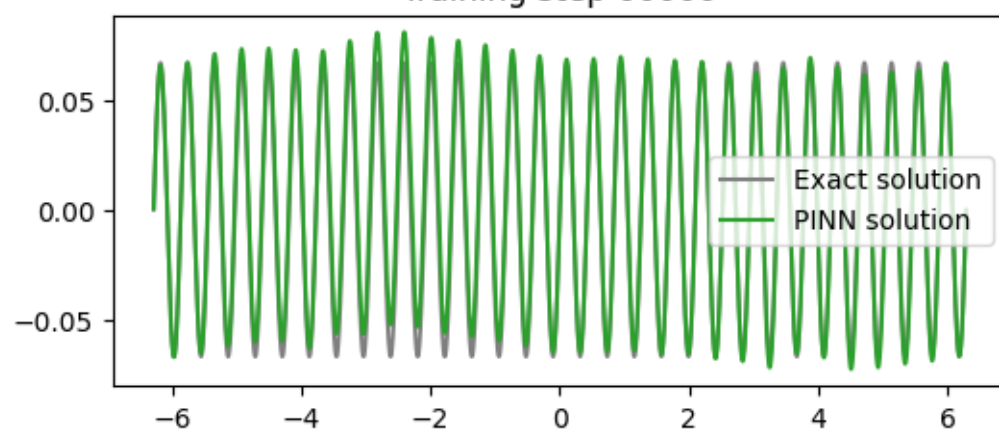
Training step 40000

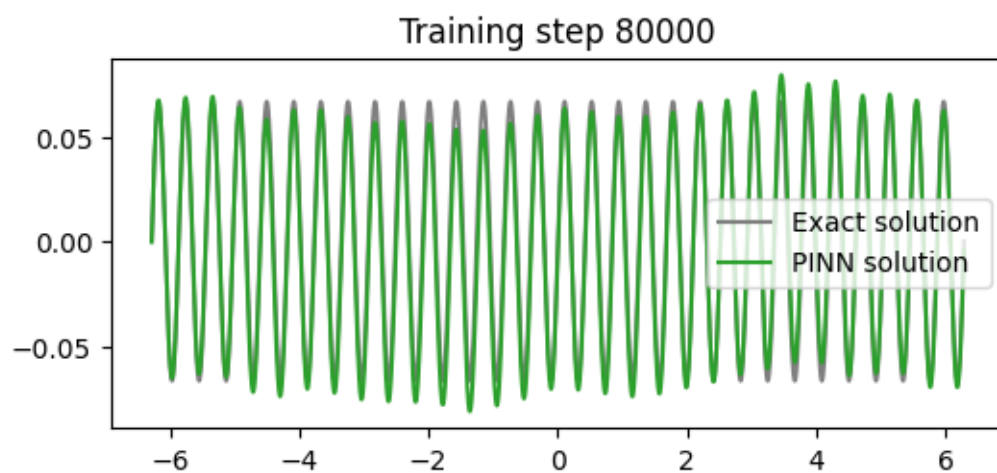
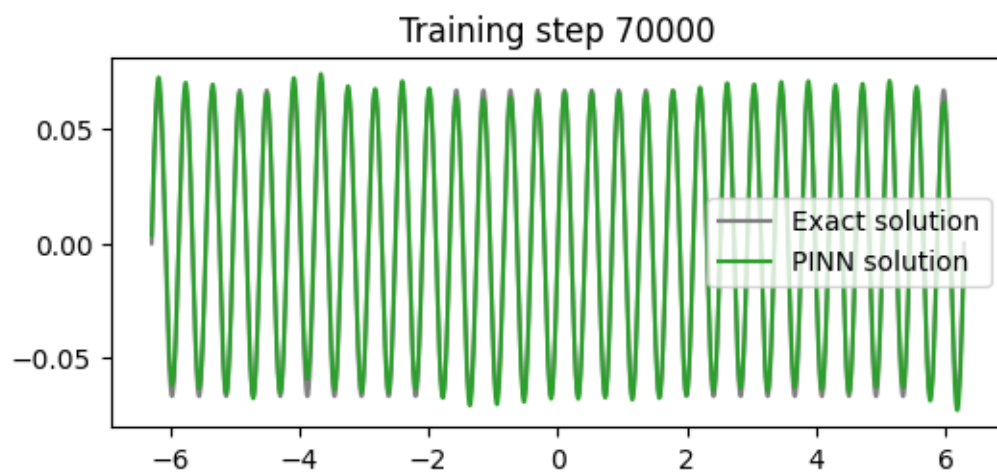


Training step 50000

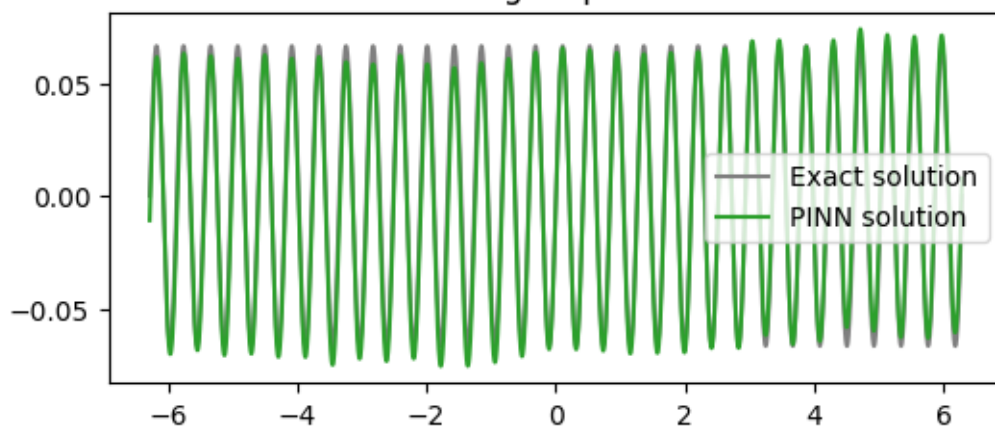


Training step 60000

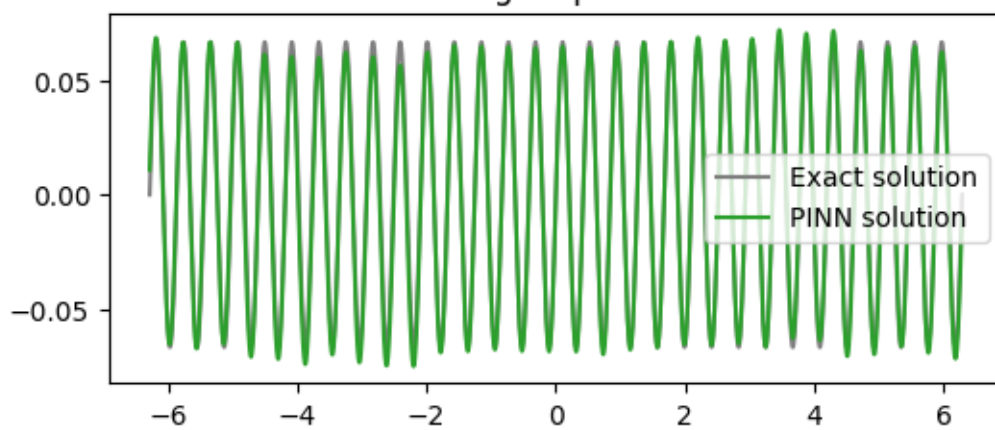


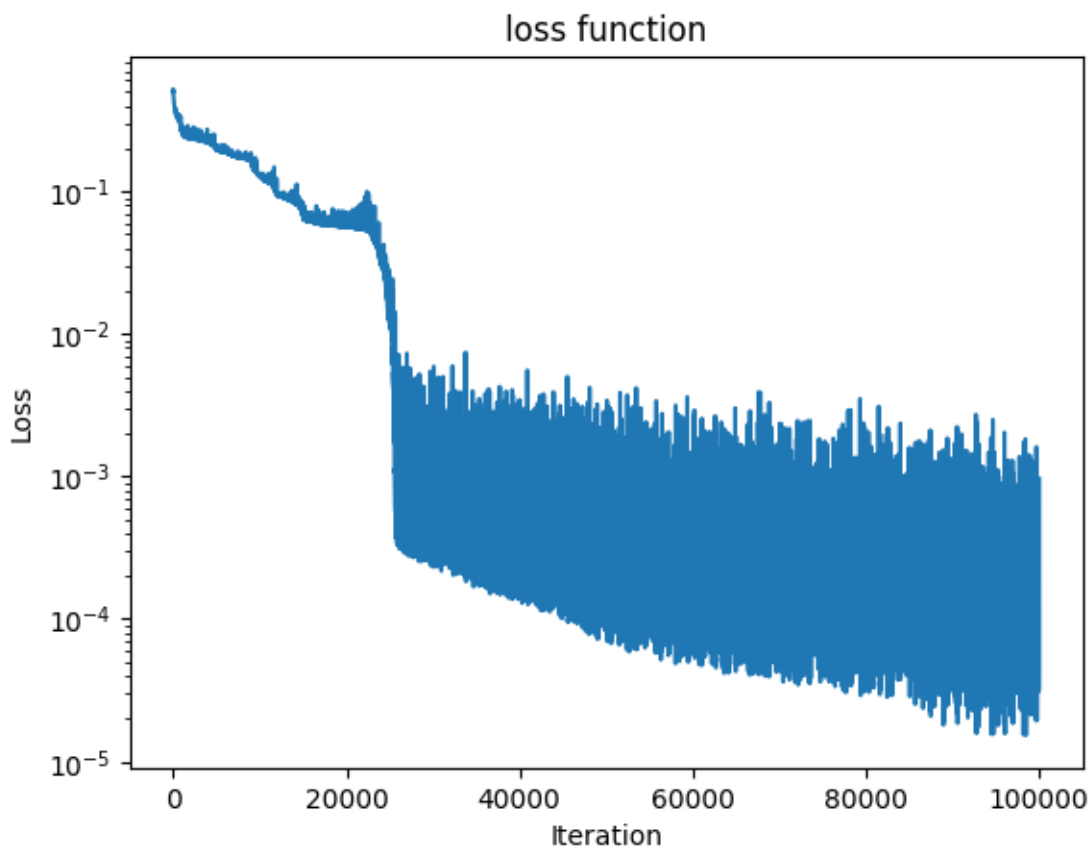


Training step 90000



Training step 100000





Sieć osiąga zadowalające wyniki już po 30000 iteracji.

**Wnioski** Bardzo małe sieci dają poprawne wyniki dla niskich wartości  $\omega$ , dla wyższych częstotliwości, nie udaje im się to.

Najlepszy stosunek wielkości do jakości wyników oferują sieci o 4 warstwach ukrytych i 64 neuronach na warstwie.