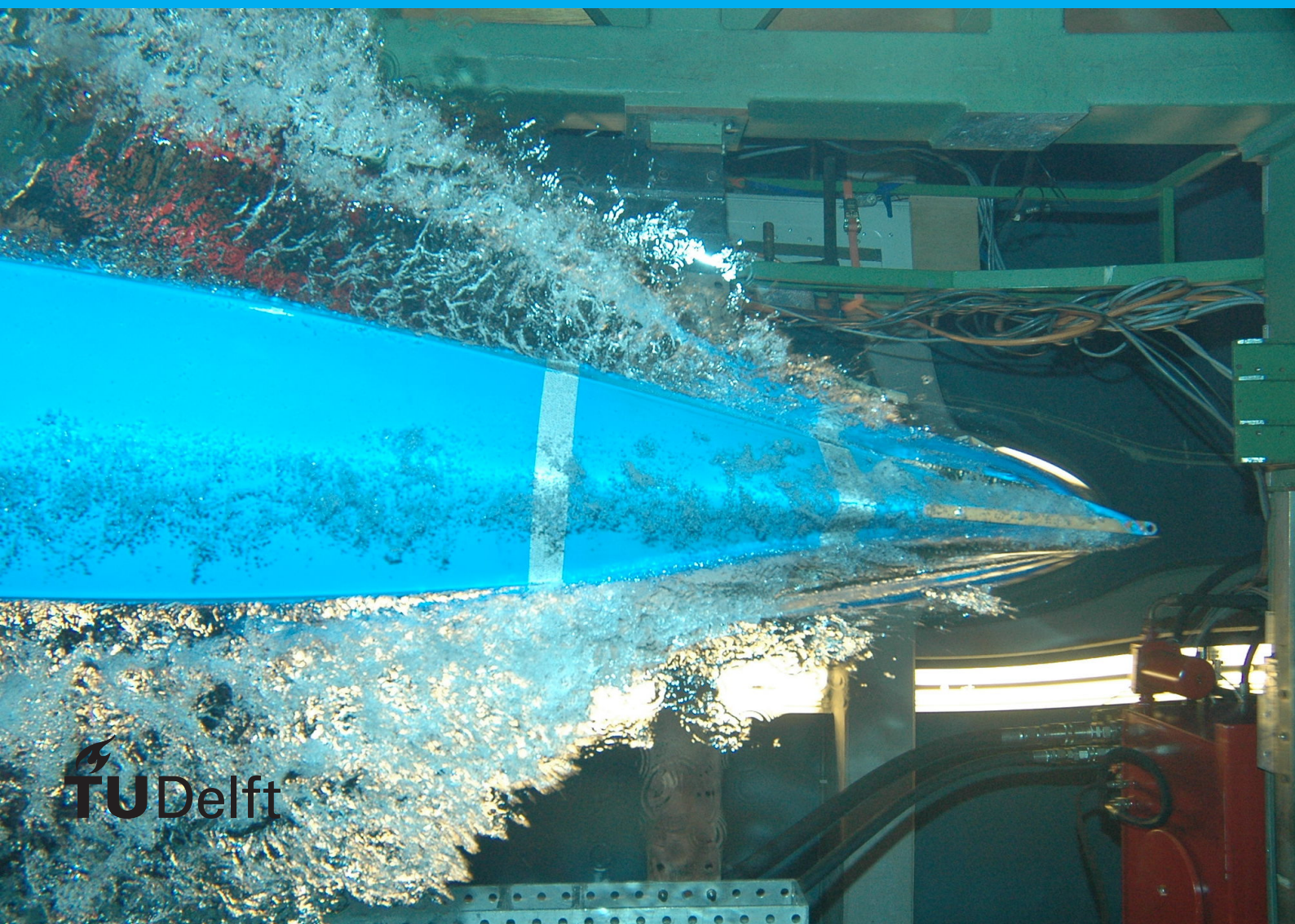


A FSK-decoder in GNU Radio

J.B Miog



A FSK-decoder in GNU Radio

by

J.B Miog

.

Student number: 4336313
Date: April 2016

An electronic version of this report and the project files are available at
<https://github.com/JBmiog/ET4394-Wireless-Networking>.

Contents

1	Background	1
2	Transmitter side	3
3	Receiver side	5
3.1	Graphical view of the signal	5
	Bibliography	11

Background

The transceiver module that is being used has been build by the author in order to fulfill the degree of bachelor of applied sciences in 2013. The transceiver module is designed at, and currently produced by, T-Minus engineering B.V. It contains two chips, an Atmega Arduino compatible micro controller and a transceiver chip, the Murata TRC105. The module can be connected to a computer via USB, after which a Arduino sketch can be uploaded.

At the moment, this transceiver is used by ESA during the CanSat competition, in which multiple high-school teams create mini satellites the size of a soda can. The mini satellites are launched in a rocket, up to a height of 1,5 kilometer. Then, the satellites are decoupled and should open a parachute to safely land. During descending, measurements are being done by the satellite. In order to simulate a space mission as good as possible, the data of the measurements is to be wireless transmitted during the 'mission'.

While the teams on the ground aim Yagi antenna's on their CanSat's to receive the signal, every once in a while, they don't succeed in receiving anything, while the CanSat is thought to be transmitting.

The goal of this project is to build a receiver which can listen to the channels of each team simultaneously. After receiving, the data has to be decoded. In order to receive in such a wide spectrum, an SDR will be used.

2

Transmitter side

Two transceivers will be used during this project, both are set to transmitting mode only. They are named 'Buenos aires' and 'Pijnacker' respectively. The transmitter settings are show in the table below.

	Tx Freq	Deviation	Mode	Tx Data	baudrate	Tx power
Pijacker	432.9mHz	+/- 20kHz	FSK	'Pijnacker'	1200 symb/sec	-8dBm
Buenos Aires	433.62	+/- 20kHz	FSK	'Buenos Aires'	1200 symb/sec	-8dBm

The signal that will be transmitted will contain a preamble of 4 bytes (0xAA). This is followed by the transmitter identifiers, which are the same for both modules. The identifier is "TMCS" (0x54, 0x4D, 0x43, 0x53), followed by a node address byte (0XX).

3

Receiver side

In order to receive both nodes simultaneously, an Ezcap DVB-T FM DAB receiver is used, which contains the RTL2832 chip. The SDR dongle is connected to the computer by USB2.0, and the I&Q data is imported using the GNU-Radio software.

3.1. Graphical view of the signal

First, figure 3.1 is obtained to measure the frequency offset. The left signal is produced by pijnacer, and should be at center frequency 432.990 MHz, but as we can see, it is actually received at 432.964 MHz. The difference is caused by the initial offsets of the transmitters, and the frequency offset of the VCO in the SDR.

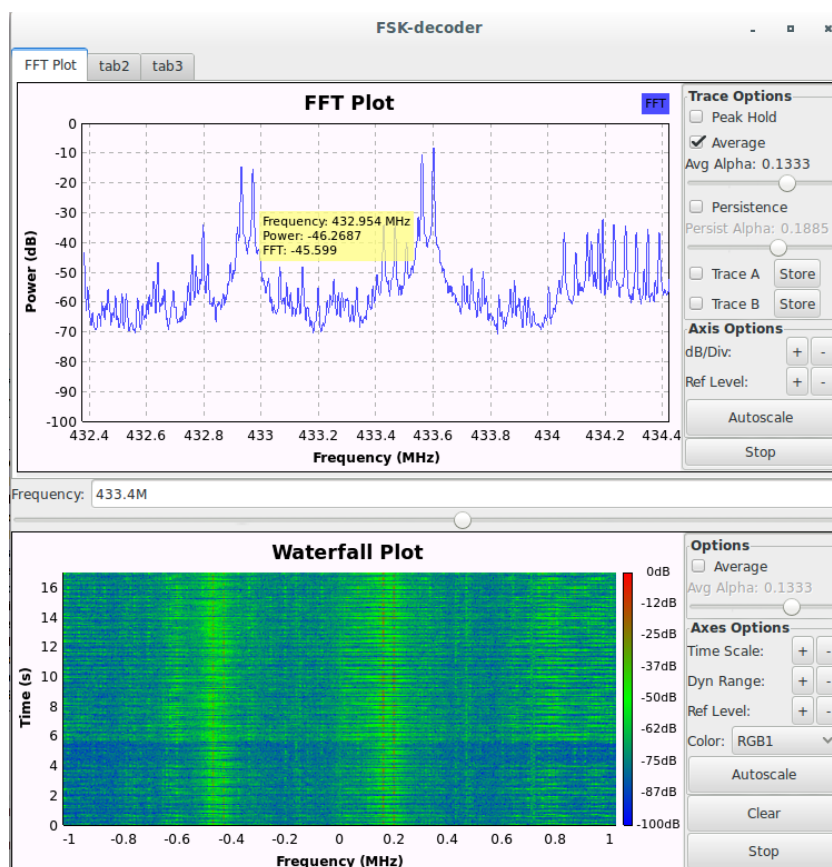


Figure 3.1: a gnu-radio capture of the frequency spectrum

In order to build the decoder efficiently, the FSK_capture_to_file.grc is build, which contains a simple

data sink block. The sampling frequency is set to 2.048 MSPS, which results in $2.048\text{MSPS}/1200\text{baud} \approx 1706\text{samples/symbol}$. This is useful to know in order to perform a correct clock recovery later on.

The input data is measured with a center frequency 433.4. We'll take a graphical look at the recorded signal of both transmitters using the GNU radio flowchart depicted in 3.2

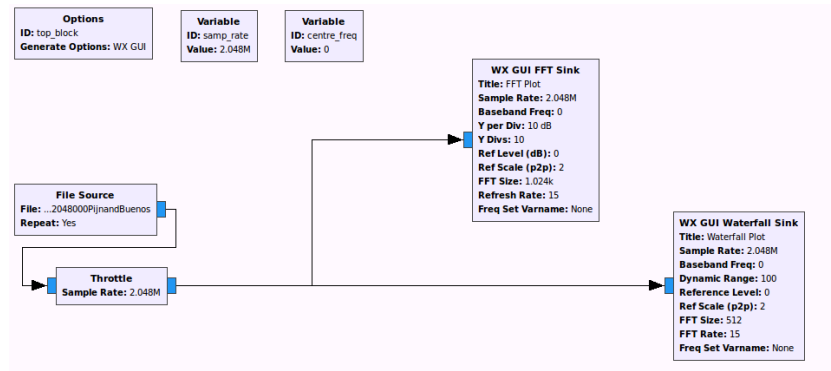


Figure 3.2

We expect that Pijnacker transmitting frequency is now $433.4 - 432.950 = 450\text{ kHz}$ below the current center frequency. Which is roughly shown in 3.3.

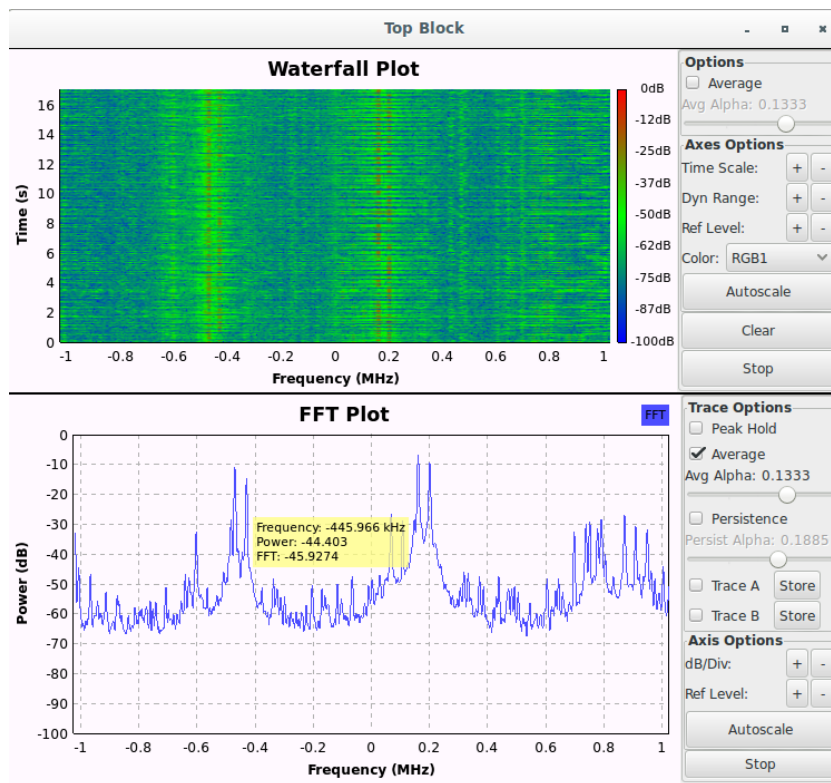
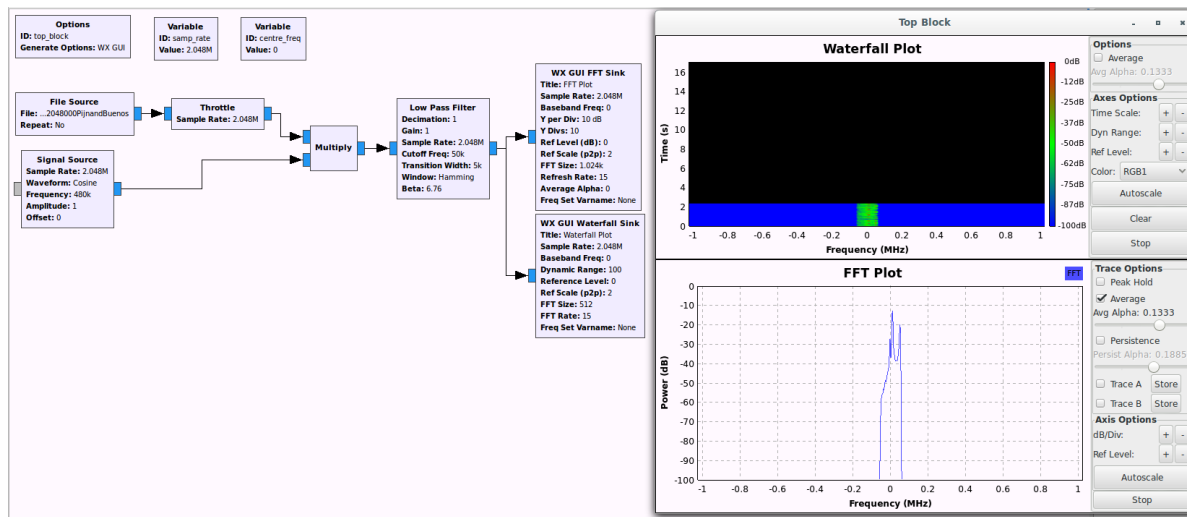


Figure 3.3: replay of signal

Once we replay the saved data using the file source block, the frequency of Pijnacker is at -450kHz, which can be seen in figure 3.3.

In order to decode the signal, the frequency is increased using a multiplier and an addition signal source block, with a frequency of 470 kHz. This sets the '0' at +30kHz, and the '1' at 50 kHz. Then, the signal is passed through a low pass filter. The flowchart and the results are depicted in ??.

From this point, we could use the GFSK decode block already available in the GNU-radio toolbox. However, this block only supports binary data output which is unfortunately not easy readable. To gain a better



understanding in the underlying principles, it is decided to use a quadrature demodulator, and look decode the signal in a binary AM fashion. After adding the quadrature demodulator, another low pas filter is used. with a cutt-off frequency of 1200 hertz. As the baudrate is 1200 symbols a second, and each symbol represents a binary '1' or a binary '0', we know that a signal representing a bit in AM can never be at a frequency higher than 1200 hertz. However, the filter is not infinitely steep, and therefor the cutoff frequency is set to 1100 hertz with a 800 hertz transition width.

The flowchart and the output up to this point are depicted in figure 3.4.

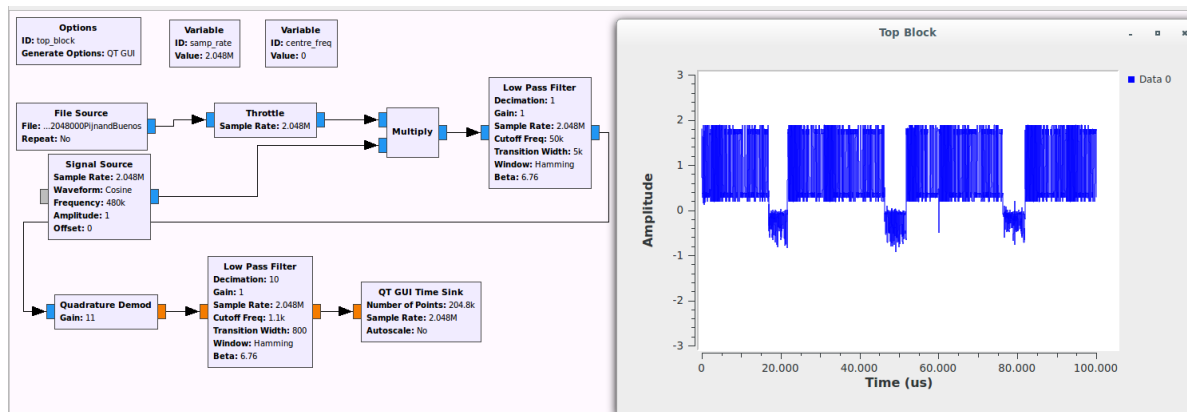


Figure 3.4: Qaudrature demodulation with noise

To get rid of the noise in between the data frames, a simple threshold detector is used. The output of the threshold detector is multiplied with the output of the second low pass filer. Again, the flowchart and the result are depicted in 3.5

In order to recover the clock signal from the preamble, a Muller and Mueller clock recovery block ($Clock_{recovery_M}$) block is available in the toolbox. This block is not well documented, but the mailing list of gnu-radio provided the information necessary: [1]

Omega: this is the expected number of samples per symbol (SPS) which is 1706 Gain omega: Control loop value indicating how fast adjustment in the omega value can be made. Mu: Initial estimate of the phase of the sample. Gain mu: Control loop value indicating how fast adjustment in the mu value can be made. Omega Relative Limit: Percentage of maximal allowed omega deviation.

The output, after the clock recover block is show in 3.6. Each positive value corresponds to a '1' being detected, a negative value corresponds to a '0' being detected.

In order to clip the amplitude of this output to a '0' or a '1', the binary slicer is used. After the data is appropriately visible, we can add tags using the "correlate access code" tag block which we provide with the

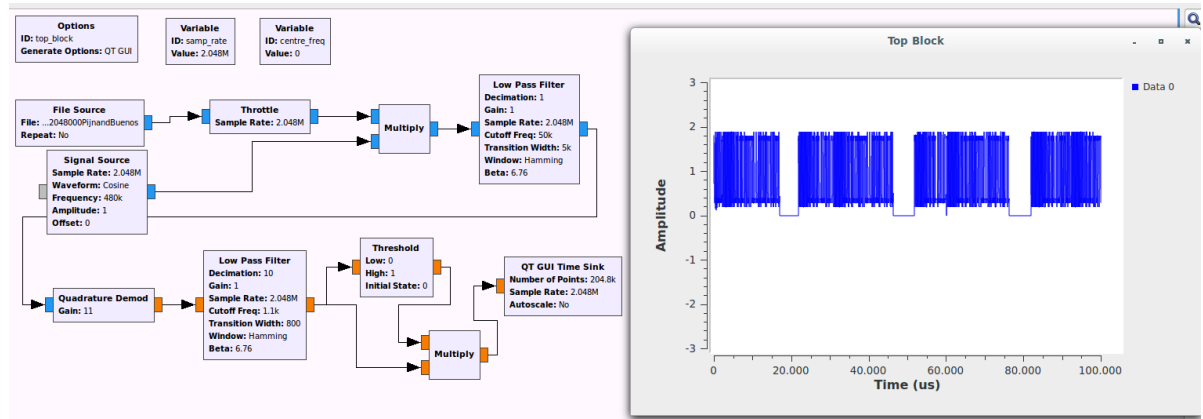


Figure 3.5: inter packet noise removed

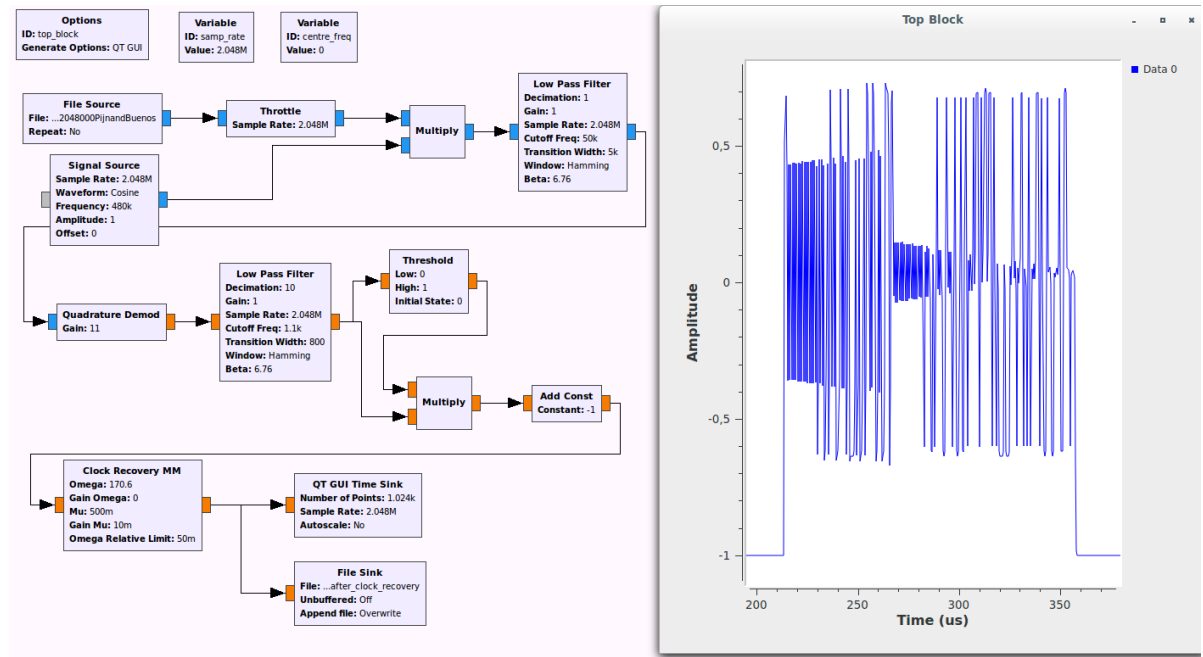


Figure 3.6: data after clock recovery

binary representation of "TMCS". For convenience, the time raster sink block is added to display the data in a longer run. The output of this block is shown in the bottom graph in 3.7. Yellow represents a '1' bit detected, and in white the detection of a '0' bit is visible. Unfortunately, the default background color is also yellow. Note that the completely yellow block at the end actually indicates data that is not yet received. The graph on the top shows the tags as small red triangles. These are placed upon the bit stream by the correlate access block.

At this point, also the data is stored in the tagged file sink. The documentation of this block is unclear where the obtained files are actually located, but does specify that each block after a tag detection creates a new file. As this is not eligible for our goal, the author has decided to use the file obtained in fig 3.6 and write a own script in python to detect the preamble, and further decode the message offline.

The python script "fsk_decode_to_char" also implements a binary slicer, appends the '0' and '1' to a string, and searches this string for the data, which it extracts, converts to ascii characters, and outputs as data.

The script skips the first two characters of the transmitted data. It is expected that this is due to the node identifier, as this is not yet taken into account.

[here i'll input the script, and the script output]

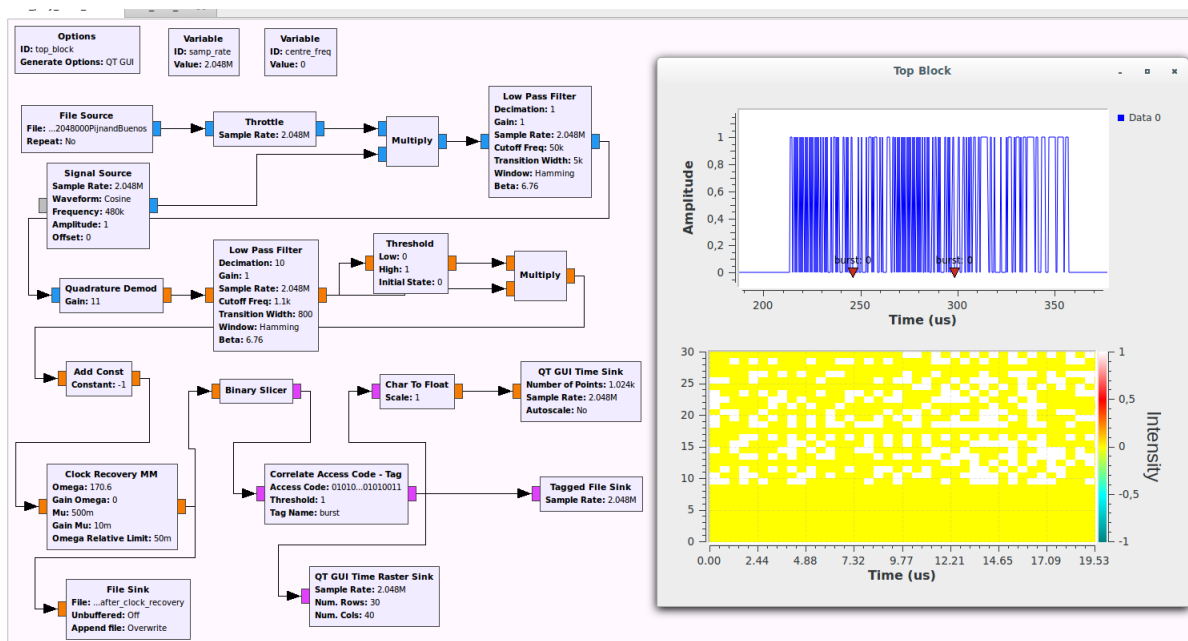


Figure 3.7: data after clock recovery, with amplitude correction and preamble tagging

Bibliography

- [1] Burst fsk receiver clock synchronization problems. URL <https://lists.gnu.org/archive/html/discuss-gnuradio/2015-12/msg00075.html>.