



SCHOOL OF COMPUTER AND
COMMUNICATION SCIENCES

ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

Computer Vision Laboratory
Unseen Spacecraft Pose Estimation

Baseline implementation of a generalizable 6DoF object
pose estimator with target models included

Bachelor's Thesis in Computer Science

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Semester: Fall 2023

I hereby confirm that I am the sole author of the written work here enclosed and that I have compiled it in my own words. Parts excepted are corrections of form and content by the advisors.

Lausanne, Switzerland, 05.01.24

Jérémy Chaverot

Acknowledgments

Before we dive into the real subject, I would like to make a few acknowledgements. First and foremost I must thank my advisors Andrew Price and Chen Zhao for accepting my request to take part in a semester project under their guidance. I am grateful to have been able to practice my skills with them, and can only hope that the feeling is mutual. Moreover I would also like to thoroughly thank my friends and family for supporting me in my academic journey, despite a rather unstable start in my studies.

Abstract

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