

SCHOOL OF COMPUTER AND COMMUNICATION SCIENCES

ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

Computer Vision Laboratory Unseen Spacecraft Pose Estimation

Baseline implementation of a generalizable 6DoF object pose estimator with target models included

Bachelor's Thesis in Computer Science

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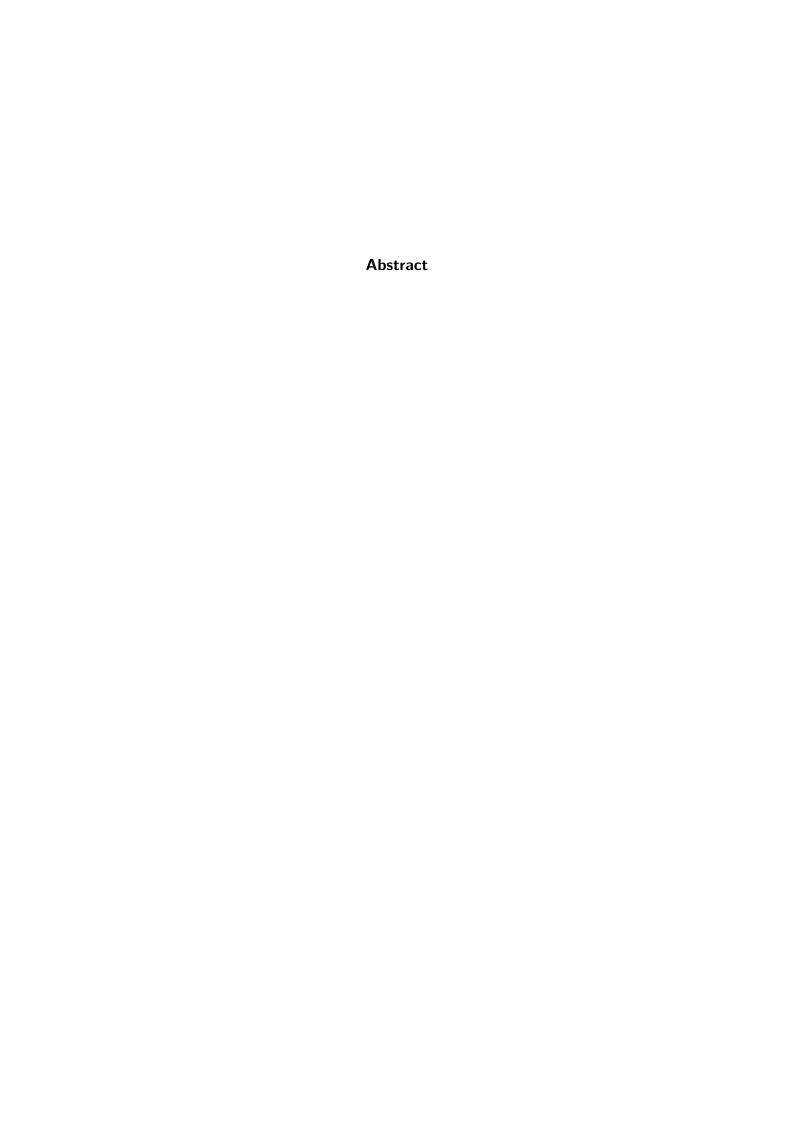
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2 Scientific papers review

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Abbreviations

