EPFL

SCHOOL OF COMPUTER AND COMMUNICATION SCIENCES

ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

Computer Vision Laboratory
Unseen Spacecraft Pose Estimation

Baseline solution by implementing a machine learning
framework with target models included

Bachelor's Thesis in Computer Science

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I hereby confirm that I am the sole author of the written work here enclosed and that I have compiled it in my own words. Parts excepted are corrections of form and content by the advisors.

Lausanne, Switzerland, 05.01.24   Jérémy Chaverot

Acknowledgments

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Rely more on the 3D model (for now only the size), would optimize for symmetric and irregular shaped spacecrafts

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Limitations Acknowledgments My personal contribution

Abbreviations

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