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SCHOOL OF COMPUTER AND COMMUNICATION SCIENCES

ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

Computer Vision Laboratory
Unseen Spacecraft Pose Estimation

Baseline implementation of a generalizable 6DoF object
pose estimator with target models included

Bachelor's Thesis in Computer Science

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I hereby confirm that I am the sole author of the written work here enclosed and that I have compiled it in my own words. Parts excepted are corrections of form and content by the advisors.

Lausanne, Switzerland, 05.01.24   Jérémy Chaverot

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