M.EEC041 - Digital Systems Design

2021/2022

Laboratory project 1 - V1.0

18 April 2022

Due date: October 22, 14h (guidelines for submission TBA)

1. Introduction

This project consists in implementing a sequential calculator of the square root for 32-bit unsigned integer numbers. The circuit must be built as a synthesizable Verilog module implementing the logic diagram shown in figure 1. The interface of the module is:

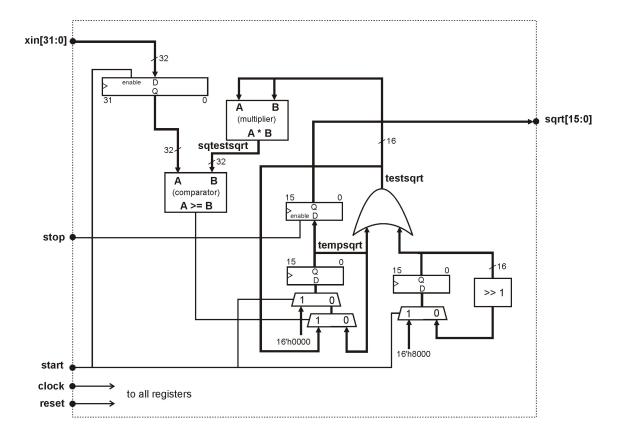


Figure 1 - RTL diagram of the sequential square root calculator.

2. Functional description

This circuit implements a sequential square root calculator for 32-bit integer numbers, producing the result as a 16-bit integer. The integer square root result is truncated to nearest integer not greater than the square root of xin. The function implemented by this circuit is functionally equivalent to the C code below:

```
unsigned int xin, sqrtx;
sqrtx = (int) sqrt( (double) xin);
```

The algorithm builds the result iteratively from the most significant bit to the least significant bit. Iteration i decides whether the bit b_i is one or zero by comparing the square of a tentative result with that bit set (signals **testsqrt** and **sqtestsqrt==(testsqrt)^2**) with the input argument **xin**. If **xin** is greater than **sqtestsqrt** then bit b_i is set to one, otherwise it is reset back to zero.

To execute a square root calculation, the input **start** must be set high during one clock cycle to load the input argument into the input register. Then the iterative process proceeds for 16 clock cycles. At the end of the iterative process, one additional clock is necessary with the input **stop** high to load the output register.

3. Implementation of the RTL code [40%]

The system must be implemented as a <u>behavioral Verilog synthesizable module</u> using a single clock signal for all registers, active in the positive (rising) edge and a global synchronous reset, active high. The activation of the reset signal must set all the registers to zero.

4. Verification and automation of testbench [30%]

To verify this model you must adapt the testbench given and implement a convenient verification program to verify the functionality of your code. The task **execsqrt** already included in the testbench implements the correct sequence of signals **start** and **stop** to perform calculation. You should improve the testbench in order to automate the verification procedure.

5. Additional developments [10%+10%+10%]

- **5.1** Modify your module using one parameter **NBITSIN** to configure the number of bits for the operand **xin** (and consequently for the result). The external controller that sequences the activation of the **start** and **stop** signals will use the same parameter to generate the appropriate timing for those signals, as the number of clock cycles is related to the number of bit of the result. The number of bits specified for the operand **xin** must be even and between 4 and 64.
- **5.2** The iterative process implemented by this circuit truncates the integer result to the floor of the square root of **xin** (the nearest integer not larger than the real value of **sqrt(xin)**. Modify your design to include a rounding mechanism, according to the following rules and considering at most 4 bits for representing internally the fractional part of the result:
 - Round down if the fractional part of the square root is less than 0.5 (0.1000b)
 - Round up if the fractional part is greater or equal to 0.5625 (0.1001b)
 - Round to the nearest even integer if the 4-bit fractional part is equal to 0.5 (0.1000b)

Examples:

```
sqrt(12) = 3.4641 -> round down to 3

sqrt(13) = 3.6056 -> round up to 4

sqrt(1057) = 32.512 = 10000.1000... -> round down to 32

sqrt(4291) = 65.506 = 100001.1000... -> round up to 66
```

5.3 Build a sequential controller to generate the signals start and stop, according to the number of bit of the input operand specified by the parameter **NBITSIN**. The sequential controller must receive a single clock pulse in input **run** to start one calculation and generate the 3 output signals **start**, **stop** and **busy**, implementing the timing diagram shown in figure 2 (this is for a 16-bit output result)

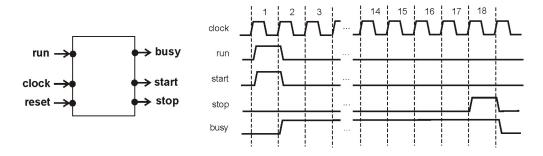


Figure 2 - Timing diagram for the sequential controller.