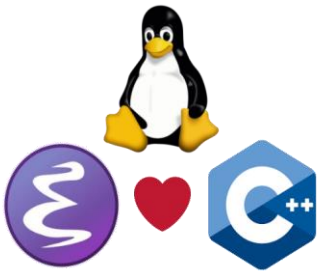
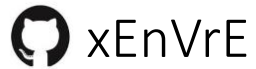




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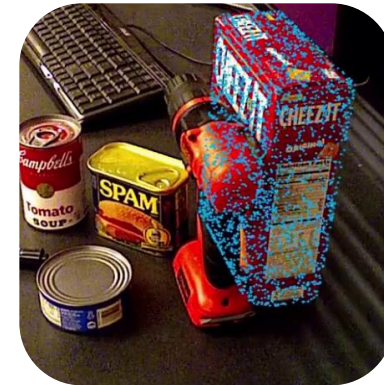
Research interests

- Multimodal object perception
- 6D object pose tracking
- Deep network-aided tracking
- Bayesian and Gaussian filtering

MSc in Robotics and Automation Engineering

*“Object localization using vision and touch:
experiments on the iCub humanoid robot”*

BSc in Computer Engineering



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HUMANOID SENSING AND PERCEPTION



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