Homework 4

Josh Cohen

```
In [96]: import numpy as np
import sympy as sym
%matplotlib notebook
from matplotlib import pyplot as plt
from scipy.optimize import minimize
from IPython.display import Image
```

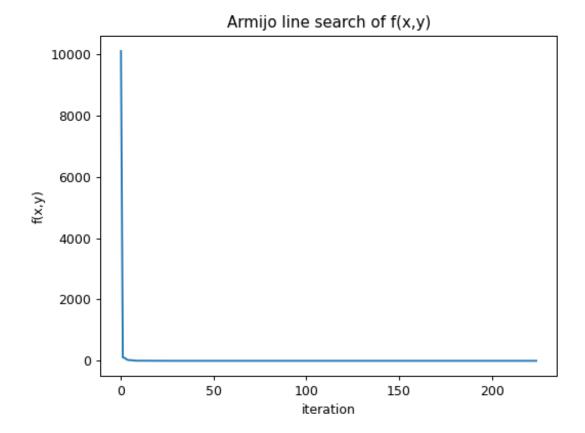
Probelm 1

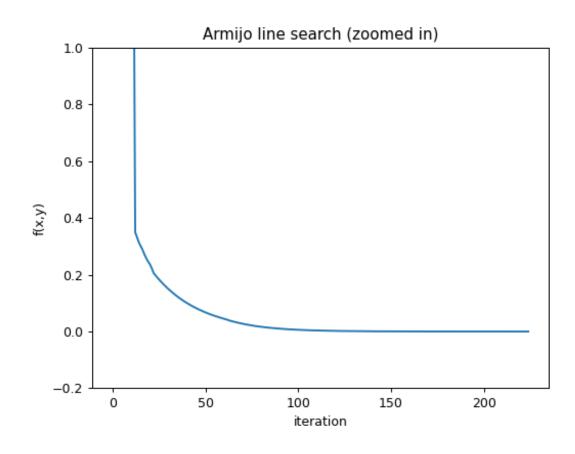
Design an Armijo linesearch function that takes a function, its derivative, a test point x, and a descent direction z that then returns the new x that satisfies the sufficient descrease property.

Using a starting guess of $x=[10,10]^T$, $\alpha=0.4$, $\beta=0.7$, minimize $f(x,y)=x^2=100y^2$. Turn in solution for (x,y) and plot evaluation of the function at every iteration .

```
In [66]: alpha = 0.4
beta = 0.7
x, y, z0, z1, gamma = sym.symbols('x y z_0 z_1 gamma')
z = sym.Matrix([z0, z1])
q = sym.Matrix([x, y])
f = sym.Matrix([1,100]).T * sym.Matrix([x**2, y**2])
Df = f.jacobian(q)
local_quad = sym.lambdify([z, q], Df.dot(z) + z.dot(z))
Df_lam = sym.lambdify([q], Df)
f_lam = sym.lambdify([q], f)
f.shape
suff_compare = sym.lambdify([q, z, gamma], f + alpha * gamma * Df * z
)
```

```
In [70]: #determine how to choose z based on local quad model
# ans = minimize(local_quad, [0,0], ([10,10]))
# init_z = ans.x
q_test = np.array([10, 10])
z_i = np.array([0,0])
eps = 10e-3
vals = np.zeros(250)
```





```
In [81]: q_test
Out[81]: array([3.57438757e-03, 3.36587785e-05])
```

The armijo linesearch solution for the (x,y) evaluates to [3.57438757e - 03, 3.36587785e - 05]

Probelm 2

```
In [197]: Image("2_a.jpg")

Out[197]:

Howeverk # 44

2 a) $\frac{1}{2}(\text{X}) = \text{V.}^T \text{X} \text{V}_1 + 10 \text{V.}^T \text{X} \text{V}_2

\text{compate directional derivative}

\[
\text{Df(X).} = \frac{1}{26}[\text{V.}^T \text{X} + \text{E}^2] \text{X} + \text{E}^2] \text{X} + \text{E}^2] \text{V.}_2

\]

\[
= [\text{V.}^T \text{Z}^T \text{X} + \text{E}^2] \text{V.}_1 + \text{V.}_1 \text{V.}_2 \text{E}^2] \text{Z} \text{V.}_2

\]

\[
= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_1 \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

\]

\[
= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_1 \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

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= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_1 \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

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= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_1 \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

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= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_1 \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

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= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_1 \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

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= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

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= [\text{V.}^T \text{Z}^T \text{X} \text{V.}_1 + \text{V.}_1 + \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{X}^T \text{Z} \text{V.}_2

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= [\text{V.}^T \text{Z} \text{V.}_1 + \text{V.}_2 \text{V.}_2 + \text{IOV.}_2^T \text{V.}_2 + \text{IOV.}_2^T \text{V.}_2 + \text{IOV.}_2^T \text{V.}_2 + \text{IOV.}_2^T \t
```

b). Compute the gradient of $abla f \in \mathbb{R}^{2x2}$

```
In [110]: z0, z1, z2, z3, x0, x1, x2, x3, v0, v1 = sym.symbols('z_0 z_1 z_2 z_3 x_0 x_1 x_2 x_3 v_0 v_1')

Z = sym.Matrix([[z0, z1],[z2, z3]])
X = sym.Matrix([[x0, x1],[x2, x3]])
v1 = sym.Matrix([1, 0])
v2 = sym.Matrix([0, 1])

q = sym.Matrix([x0, x1, x2, x3])

f = (v1.T * (X.T * X) * v1) + 10 * v2.T * X.T * X * v2
```

The gradient of f is the output of the above cell

Probelm 3

Use the Armijo line search to compute the minimizer in \mathbb{R}^{2x2} of f starting with an inital guess of $X=\begin{bmatrix}1&1\\1&1\end{bmatrix}$.

Turn in a solution for X and a plot for f(x,y) evaluated at every step

```
In [175]: alpha = 0.4
          beta = 0.7
          # grad f norm lam = sym.lambdify([q], grad f.norm())
          Df dot z = v1.T * (Z.T * X + X.T * Z) * v1 + 10 * v2.T * (Z.T * X + X)
In [183]:
          .T * Z) * v2
          #lambdify the local quadratic search we are going to minimize for z
          local quad = sym.lambdify([z, q], Df dot z + sym.Matrix([Z[0] * Z[0]
          + Z[1] * Z[1] + Z[2] * Z[2] + Z[3] * Z[3]))
          #actually dont think we need this
          Df lam = sym.lambdify([z,q], Df dot z)
          f lam = sym.lambdify([X], f)
          #lambidfy sufficient decrease comparitor
          suff decr = sym.lambdify([z, q, gamma], f + alpha * gamma * Df dot z)
In [185]:
          x_{guess} = np.array([1,1,1,1])
          z i = np.array([0,0,0,0])
          eps = 10e-3
          vals = np.zeros(250)
In [187]:
          iter count = 0
          vals[iter count] = f lam(x guess)
          while(grad f norm lam(x guess) > eps):
              iter count += 1
              z_i = minimize(local_quad, z_i, (x_guess)).x
              n = 0
              gam = beta**n
              while np.linalg.norm(f_lam(x_guess + gam * z_i)) > np.linalg.norm
          (suff decr(z i, x guess, gam)):
                  n += 1
                  gam = beta**n
              x_guess = x_guess + gam * z_i
              vals[iter count] = f lam(x guess)
```

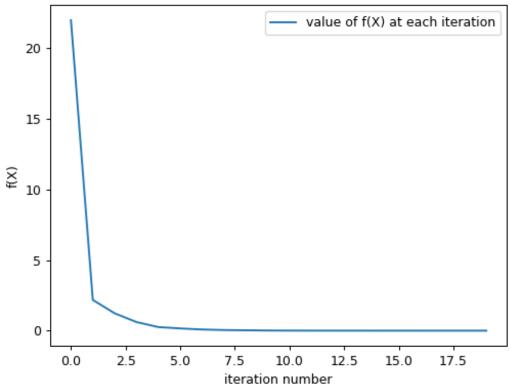
```
In [188]: x_guess

Out[188]: array([0.00227922, 0.00022507, 0.00227922, 0.00022507])

In [190]: vals = vals[:iter_count]

In [196]: plt.figure()
    plt.plot(np.arange(iter_count), vals)
    plt.xlabel("iteration number")
    plt.ylabel("f(X)")
    plt.title("Armijo line search of f(X)")
    plt.legend(["value of f(X) at each iteration"])
    plt.show()
```

Armijo line search of f(X)



```
Therefore my solution is X = \begin{bmatrix} 0.00227922 & 0.00022507 \\ 0.00227922 & 0.00022507 \end{bmatrix} .
```

```
In [ ]:
```