

vik

a scientific colour map - www.fabiocrameri.ch/vik

Crameri (2018)

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Characteristics

- Perceptually uniform 🗸
- Perceptually ordered ✔
- Colour-vision-deficiency (CVD) friendly ✔
- Readable as black and white print ✔
- Diverging
- Light centred; no black

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Contributors

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- Alexis Plunder Wider compatibility of .xml format contact
- Krister Stræte Karlsen User instruction for use with python contact
- Philippe Rivière Conversion instruction for d3 contact
- Emilia Plotly versions contact
- Thomas Lin Pedersen The 'scico' package for use with R contact
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- Chad Greene MatLab file exchange version contact
- Sean Trim Conversion to .pal format contact
- George Edward Campbell Conversion to .lut format contact
- Kirstie Wright User instruction for use with Petrel contact
- Jennifer Levett Conversion to SKUA-GOCAD .xcmap format contact

Acknowledgement

Please acknowledge the free use of the colour map.

e.g., "The perceptually uniform colour map *vik* is used in this study to prevent visual distortion of the data (Crameri 2018a,b)."

Crameri, F. (2018a), Scientific colour-maps. Zenodo. http://doi.org/10.5281/zenodo.1243862

Crameri, F. (2018b), Geodynamic diagnostics, scientific visualisation and StagLab 3.0, Geosci. Model Dev., 11, 2541-2562, doi:10.5194/gmd-11-2541-2018

Instructions

Using the .mat Format (MatLab)

Load the colour map into MatLab, either by adding the .mat file to the MatLab search path and using the command:

```
load('vik.mat');
```

or by specifying the full file path to the .mat file:

```
load('~/work/Colormaps/vik.mat');
```

Then use it, for example, with:

```
figure(1)
colormap(vik)
colorbar
```

Using the file-exchange app (MatLab)

A convenient MatLab package provided by Chad Greene containing the full scientific colour-map suite is available on MatLab file exchange.

Using the .cpt Format (GMT)

The file vik.cpt can be resampled for a given z-value range with the Generic Mapping Tools (GMT; http://gmt.soest.hawaii.edu/) command "makecpt".

For example to resample for an array from -2000 to 2000 in 100 increments you could generate a new file with:

```
$makecpt -Cvik.cpt -T-2000/2000/100 > vik_resampled.cpt
```

Using the .ct Format (VisIt)

The file vik.ct can imported to Vislt by placing the .ct file in the .visit directory, which can be found on macOS under e.g.,:

```
/Applications/VisIt.app/Contents/Resources/ ...
... 2.12.3/darwin-x86_64/resources/colortables
```

The colour map should appear in the built-in list after Vislt has been restarted.

Using the .mat Format (Mathematica)

The function call <code>ColorMapSuite["name", i = -1]</code> returns a lambda function whose ith argument is used to define color (see the Manual for <code>ColorFunction</code> for details). "name" should be replaced with the name (in quotes) of the color scheme, e.g. "vik". Be sure to set the variable <code>ColorMapSuitePath</code> to the path where your ColorMapSuite is installed.

General rules are:

- 1D plots of 1D functions/data: no (default) argument i suffices
- 2D plots of 2D functions/data: no (default) argument i suffices
- 3D plots of 2D functions/data: use *i* = 3
- 3D plots of 3D functions/data: use i = 4 (results might be worse than default Mathematica color functions, possibly due to lack of surface normal mapping)

```
ContourPlot[Sin[x] Sin[y], {x, 0, 2 Pi},
{y, 0, 2 Pi}, ColorFunction -> ColorMapSuite["vik"]]
```

Using the .xml Format (QGIS)

Load the colour map into QGIS in:

```
Settings > Style manager > Import/Export > Import symbol(s) > select the xxx_QGIS.
xml file.
```

Using the .xcmap format (SKUA-GOCAD)

```
To import a colormap into a SKUA-GOCAD project, navigate to 
File > Import > GOCAD Resources > Colormaps.
```

Alternatively, for advanced users, to include a colormap as a resource in all new projects, insert the .xcmap text into the *colormaps.xml* file located in */Gocad/lib/app-defaults.

Using the .txt Format (Python)

Step 1: Load colour map data

Load the colour map data into Python using numpy.loadtxt():

```
import numpy as np
cm_data = np.loadtxt("vik.txt")
```

Step 2: Set up colour map

Use <code>matplotlib.colors.LinearSegmentedColormap()</code> to create a colour map that can be used with matplotlib.

```
from matplotlib.colors import LinearSegmentedColormap
vik_map = LinearSegmentedColormap.from_list('vik', cm_data)
```

Complete example:

```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import LinearSegmentedColormap

cm_data = np.loadtxt("vik_RGB(0-1).txt")
vik_map = LinearSegmentedColormap.from_list('vik', cm_data)

x = np.linspace(0, 100, 100)[None, :]
plt.imshow(x, aspect='auto',cmap=vik_map)
plt.axis('off')
plt.show()
```

Using the .py Format (plotly)

Plotly versions of the scientific colour maps are provided by Emilia are available at https://github.com/empet/scientific-colorscales.

The plotly scientific colour maps (see the file scicolorscales.py) were created by converting the provided .py file of each colour map.

Direct applications and some scientific tests are illustrated in this Jupyter Notebook: http://nbviewer.jupyter.org/github/empet/scientific-colorscales/blob/master/Tests-for-scientific-colorscales.ipynb.

Using the .xml format (d3)

An instruction to convert the .xml format to d3's internal representation is provided by Philippe Rivière at https://beta.observablehq.com/@fil/colormaps.

Using the .pal format (Gnuplot)

Launch the Gnuplot shell and load the specific .pal file (e.g., batlow) into Gnuplot with:

```
user@computer gnuplot
gnuplot> load "batlow.pal"
```

Using the .lut format (ImageJ/Fiji)

The .lut colour-map file (e.g., *batlow.lut*) can be imported to ImageJ or Fiji by placing it in the *luts* folder (to reveal folder location in Fiji: File > Show Folder > LUTs). Upon restart of ImageJ, the scientific colour map(s) should then be available under Image > Lookup Tables.

Alternatively, the colour-map .lut file may be applied using either (a) File > Open , (b)

File > Import > LUT , or (c) drag and drop the .lut file onto the ImageJ window. To view available LUTs: Image > Color > Display LUTs .

Using the .alut format (Petrel)

To import colour maps, select the templates pane and colour tables folder.

Then select the folder to import into (or insert a new folder) and right click import on selection.

Select colour tables (alut files) (*.alut) to view and select all suitable colour maps for import.

Select default settings trim colour control points and trim opacity control points and finally use as any other colour table within Petrel.

Using the scico package (R)

scico (https://travis-ci.org/thomasp85/scico; pronounced as "psycho") is a small package developed by Thomas Lin Pedersen that provides access to the scientific colour maps within R. It provides scales for ggplot2 without requiring ggplot2 to be installed.

scico can be installed from CRAN with install.packages('scico'). If you want the development version then install directly from GitHub:

```
# install.packages("devtools")
devtools::install_github("thomasp85/scico")
```

For further details and user instructions are included in a README file within scico.

Using the .gpl format (GIMP/Inkscape)

To import the .gpl palettes, launch GIMP and go to Windows > Dockable Dialogs > Palettes to open the Palettes dialog. Then right-click anywhere on the list of palettes and select Import Palette. In the *Import a New Palette* dialog, select the *Palette file* radio button and then the button just to the right of the folder icon.

Then, navigate to and select the desired .gpl file in the corresponding folder. Clicking the *Import* button will add the scientific colour map to the existing list of palettes.

Software with built-in versions

StagLab 3.0 and later

GMT 6.0 and later

TopoToolbox 2.2 and later

SubMachine

Geoscience ANALYST 2.80 and later

References

Included colour-map diagnostics are based on:

 Kovesi (2015), Good Colour Maps: How to Design Them, CoRR, abs/1509.03700, http://arxiv.org/abs/1509.03700 and related MatLab functions available at https://www.peterkovesi.com/matlabfns/index.html#colour.

For further details see:

 Crameri, F. (2018), Geodynamic diagnostics, scientific visualisation and StagLab 3.0, Geosci. Model Dev. Discuss., <u>doi:10.5194/gmd-2017-328</u>

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