```
Coordinate system: -- default --
Density = 0.00 grams per cubic millimeter
Mass = 628.03 grams
Volume = 628033.25 cubic millimeters
Surface area = 125655.19 square millimeters
Center of mass: ( millimeters )
         X = -46.75
         Y = -25.54
         Z = -12.46
Principal axes of inertia and principal moments of inertia: ( grams * square millimeters )
Taken at the center of mass.
          Ix = (0.94, 0.20, 0.29)
                                         Px = 1125552.60
          ly = (0.34, -0.38, -0.86)
                                         Py = 6258891.12
          Iz = (-0.06, 0.90, -0.43)
                                         Pz = 6587015.49
Moments of inertia: ( grams * square millimeters )
Taken at the center of mass and aligned with the output coordinate system. (Using positive tensor notation.)
         Lxx = 1753097.01 Lxy = 956319.52
                                                  Lxz = 1385161.40
         Lyx = 956319.52
                              Lyy = 6330124.30 Lyz = 416985.12
         Lzx = 1385161.40 Lzy = 416985.12
                                                   Lzz = 5888237.90
Moments of inertia: ( grams * square millimeters )
Taken at the output coordinate system. (Using positive tensor notation.)
```

Ixz = 1750894.48

Ixy = 1706082.24

Izx = 1750894.48 Izy = 616792.92 Izz = 7670233.32

lyy = 7799974.25 lyz = 616792.92

Mass properties of UpperArm7 Configuration: Default

Ixx = 2260174.33

lyx = 1706082.24