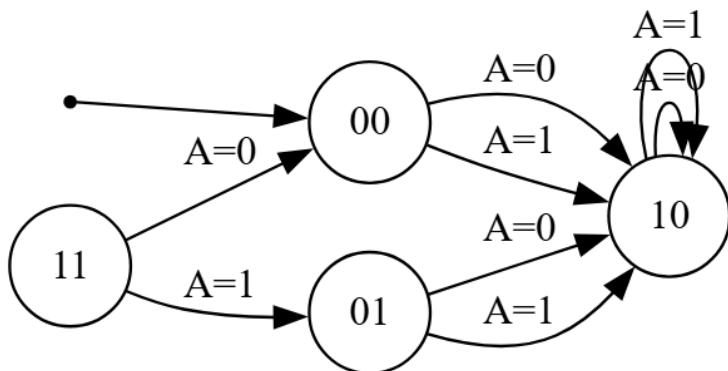
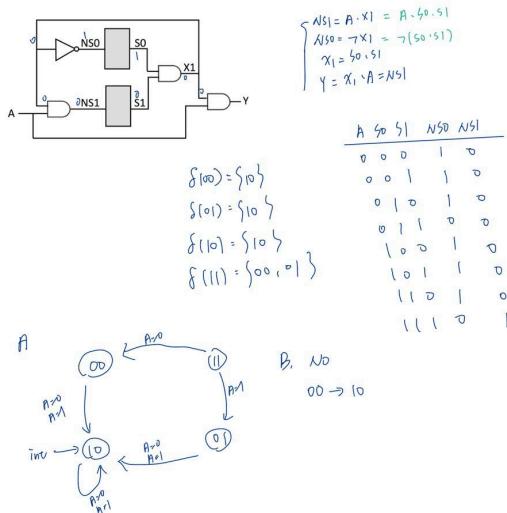


ECE 622 Lab 1

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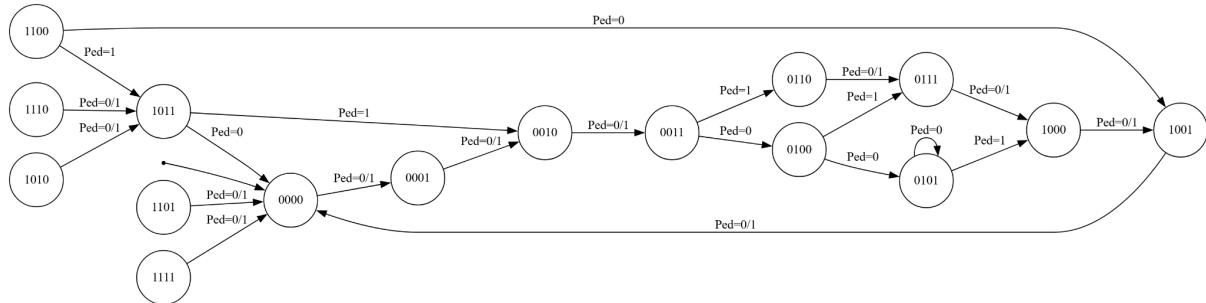
A.1

ex1: use the following method to draw ex1 transition state graph



stoplight1: write a testbench for stoplight module, used to test all state transitions and display the results based on changes in ped

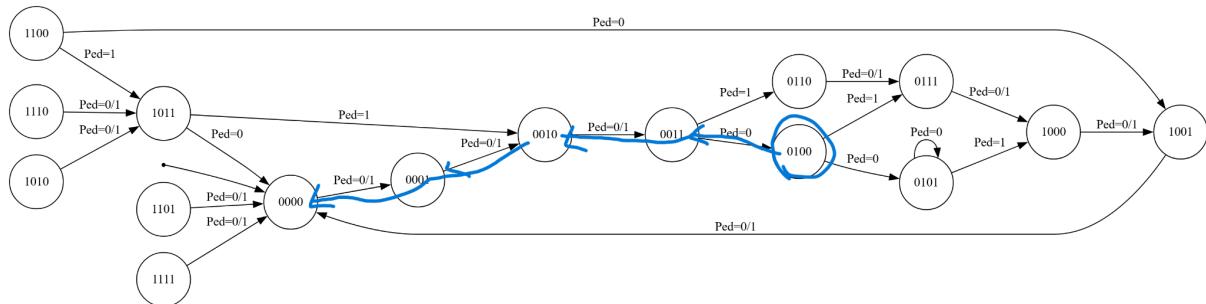
S=0000	Ped=0	\rightarrow	0001	Ped=1	\rightarrow	0001
S=0001	Ped=0	\rightarrow	0010	Ped=1	\rightarrow	0010
S=0010	Ped=0	\rightarrow	0011	Ped=1	\rightarrow	0011
S=0011	Ped=0	\rightarrow	0100	Ped=1	\rightarrow	0110
S=0100	Ped=0	\rightarrow	0101	Ped=1	\rightarrow	0111
S=0101	Ped=0	\rightarrow	0101	Ped=1	\rightarrow	1000
S=0110	Ped=0	\rightarrow	0111	Ped=1	\rightarrow	0111
S=0111	Ped=0	\rightarrow	1000	Ped=1	\rightarrow	1000
S=1000	Ped=0	\rightarrow	1001	Ped=1	\rightarrow	1001
S=1001	Ped=0	\rightarrow	0000	Ped=1	\rightarrow	0000
S=1010	Ped=0	\rightarrow	1011	Ped=1	\rightarrow	1011
S=1011	Ped=0	\rightarrow	0000	Ped=1	\rightarrow	0010
S=1100	Ped=0	\rightarrow	1001	Ped=1	\rightarrow	1011
S=1101	Ped=0	\rightarrow	0000	Ped=1	\rightarrow	0000
S=1110	Ped=0	\rightarrow	1011	Ped=1	\rightarrow	1011
S=1111	Ped=0	\rightarrow	0000	Ped=1	\rightarrow	0000



A.2

ex1: according to transition state graph 00 will never reach target state 11

stoplight1: 0000(ped=0/1) \rightarrow 0001(ped=0/1) \rightarrow 0010(ped=0/1) \rightarrow 0011(ped=0) \rightarrow 0100



A.3 (not sure : should we add initial state?)

ex1:

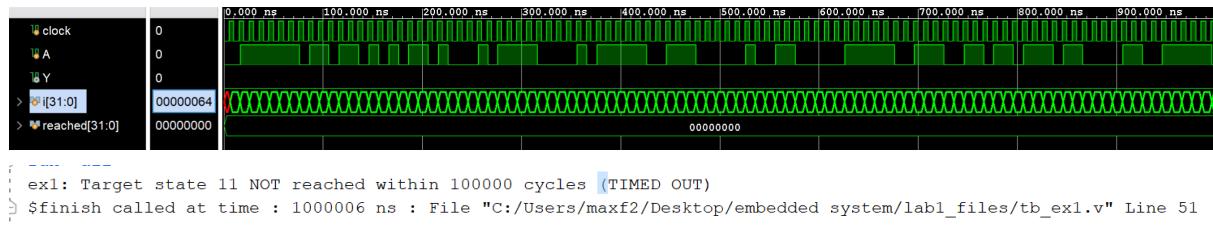
A	B
1	1
2	1
3	1
4	1
5	1
6	1
7	1
8	1
9	1
10	1
11	1
12	1
13	1
14	1
15	1
16	1
17	1
18	1
19	1
20	1

stoplight1:

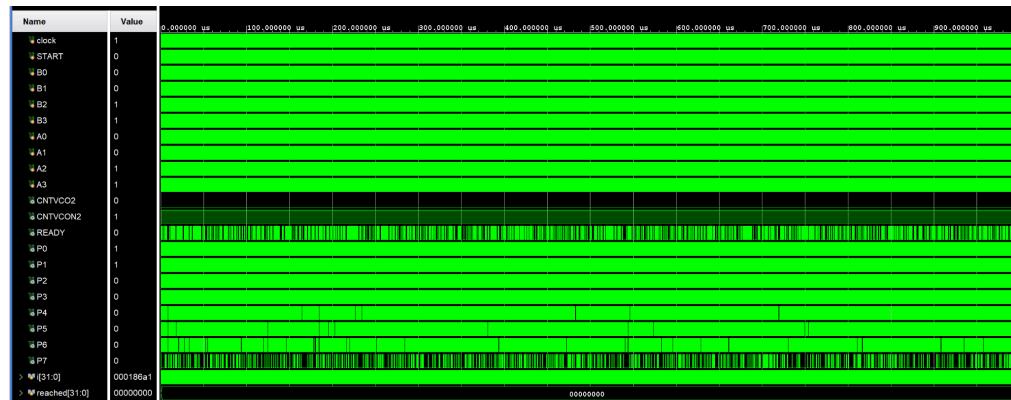
1	1
2	2
3	3
4	5
5	7
6	8
7	9
8	9
9	9
10	9
11	9
12	9
13	9
14	9
15	9
16	9
17	9
18	9
19	9
20	9

A.4

ex1: initial state will never reach target state

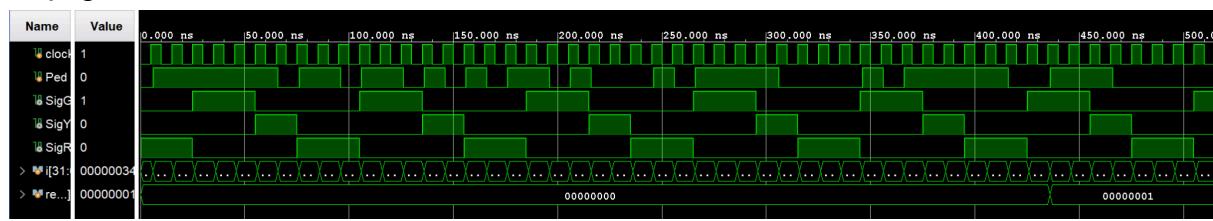


ex2:initial state will never reach target state



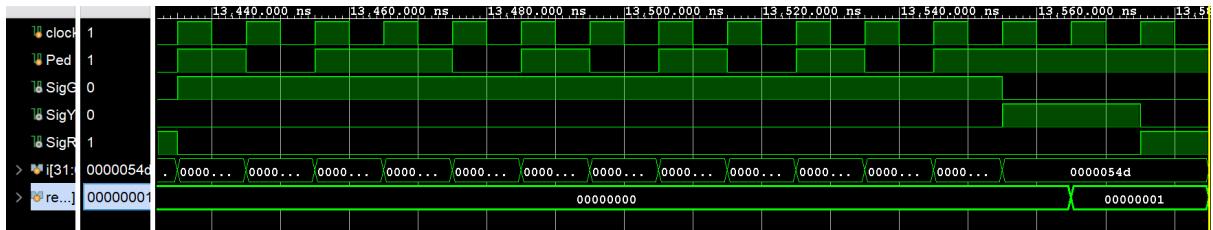
```
# run 100ns
INFO: [USF-XSim-96] XSim completed. Design snapshot 'tb_ex2_behav' loaded.
INFO: [USF-XSim-97] XSim simulation ran for 1000ns
launch_simulation: Time (s): cpu = 00:00:03 ; elapsed = 00:00:10 . Memory (MB): peak = 29
run -all
ex2: Target state 11111111111111 NOT reached within 100000 cycles (TIMED OUT)
```

stoplight1:



```
INFO: [USF-XSim-97] XSim simulation ran for 1000ns
launch_simulation: Time (s): cpu = 00:00:03 ; elapsed = 00:00:10 . Memory (MB): peak = 2562.023 ; gain = 0.000
) ERROR: [Common 17-180] Spawn failed: No error
) run -all
stoplight1: Target state 0100 REACHED at cycle 52
) $finish called at time : 516 ns : File "C:/Users/maxf2/Desktop/embedded system/labl_files/tb_softwarelight1.v" Line 39
```

stoplight2:



```
INFO: [USF-XSim-96] XSim completed. Design snapshot 'tb_stoplight2_behav' loaded.  
INFO: [USF-XSim-97] XSim simulation ran for 1000ns  
) launch_simulation: Time (s): cpu = 00:00:12 ; elapsed = 00:00:11 . Memory (MB): peak = 2658.184 ; gain = 0.000  
) run -all  
stoplight2: Target state 01000 REACHED at cycle 1357  
) $finish called at time : 13585 ns : File "C:/Users/maxmf2/Desktop/embedded system/lab1 files/tb_stoplight2.v" Line 41
```

stoplight1 testbench

```

`timescale 1ns/1ps
2
3 module tb_stoplight1;
4   reg clock, Ped;
5   wire SigG, SigY, SigR;
6   integer i;
7   integer reached;
8
9   stoplight1 spotlight1 (
10     .clock(clock),
11     .Ped(Ped),
12     .SigG(SigG),
13     .SigY(SigY),
14     .SigR(SigR)
15 );
16
17 initial clock = 0;
18 always #5 clock = ~clock;
19
20 initial begin
21   reached = 0;
22   Ped = 0;
23   spotlight1.S3 = 0;
24   spotlight1.S2 = 0;
25   spotlight1.S1 = 0;
26   spotlight1.S0 = 0;
27
28   for (i = 1; i <= 100000; i = i + 1) begin
29     Ped = $random % 2;
30     @(posedge clock);
31
32     // Target:0100
33     if (spotlight1.S3 === 0 && spotlight1.S2 === 1 && spotlight1.S1 === 0 && spotlight1.S0 === 0) begin
34       $display("stoplight1: Target state 0100 REACHED at cycle %0d", i);
35       reached = 1;
36       @(posedge clock);
37       @(posedge clock);
38       $finish;
39     end
40   end
41
42   if (reached == 0)
43     $display("stoplight1: Target state 0100 NOT reached within 100000 cycles (TIMED OUT)");
44
45   $finish;
46 end
47
48 endmodule

```

A.5

The result for stoplight1 is consistent with the result from A.2. We know that stoplight1 will reach the target state 0100 in A.2 and A.4 simulation shows the same result.

C

ex1:

1		1
2		1
3		1
4		1
5		1
6		1
7		1
8		1
9		1
10		1
11		1
12		1
13		1
14		1
15		1
16		1
17		1
18		1
19		1
20		1

ex5:

1		8
2		14
3		18
4		22
5		26
6		28
7		28
8		28
9		28
10		28
11		28
12		28
13		28
14		28
15		28
16		28
17		28
18		28
19		28
20		28