

Mandatory Exercise 2

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Exercise 1

7.1

We are to prove that the following conditions are satisfied for $V_h = H_0^1$ and $Q_h = L^2$

$$a(u_h, v_h) \leq C_1 \|u_h\|_{V_h} \|v_h\|_{V_h}, \quad \forall u_h, v_h \in V_h \quad (7.14)$$

$$b(u_h, q_h) \leq C_2 \|u_h\|_{V_h} \|q_h\|_{Q_h}, \quad \forall u_h \in V_h, q_h \in Q_h \quad (7.15)$$

$$a(u_h, u_h) \geq C_3 \|u_h\|_{V_h}^2, \quad \forall q_h \in Q_h \quad (7.16)$$

First we look at condition (7.14)

$$a(u_h, v_h) = \int_{\Omega} \nabla u_h : \nabla v_h \, dx = \langle \nabla u, \nabla v \rangle \leq |\langle \nabla u, \nabla v \rangle| \quad (1)$$

$$\leq \|\nabla u\|_{L^2} \cdot \|\nabla v\|_{L^2} \quad (2)$$

Next we look at condition (7.15)

$$\begin{aligned} b(u_h, q_h) &= \int_{\Omega} \nabla \cdot u_h \, q \, dx \leq \sqrt{\int_{\Omega} (\nabla \cdot u_h \, q)^2 \, dx} \leq \|\nabla \cdot u_h \, q\|_{L^2} \quad (3) \\ &\leq \|q\|_{L^2} \|\nabla \cdot u_h\|_{L^2} \geq \frac{1}{2} (|u_h|_{H^1}^2 + C \|u_h\|_{L^2}^2) \\ &= C_3 \|u_h\|_{H^1}^2 \end{aligned}$$

Finally we look at condition (7.16)

$$\begin{aligned} a(u_h, u_h) &= \int_{\Omega} \nabla u_h : \nabla u_h \, dx = \int_{\Omega} (\nabla u_h)^2 \, dx = |u_h|_{H^1}^2 \quad (4) \\ &= \frac{1}{2} (|u_h|_{H^1}^2 + |u_h|_{H^1}^2) \geq \frac{1}{2} (|u_h|_{H^1}^2 + C \|u_h\|_{L^2}^2) \\ &= C_3 \|u_h\|_{H^1}^2 \end{aligned}$$

7.6

We are to implement the Stokes problem using $u = (\sin(\pi y), \cos(\pi x))$, $p = \sin(2\pi x)$ and $f = -\Delta u - \nabla p$, and test whether the approximation

$$\|u - u_h\|_1 + \|p - p_h\|_0 \leq Ch^k \|u\|_{k+1} + Dk^{l+1} \|p\|_{l+1}$$

where k and l are the polynomial degree of velocity and pressure.

The following program checks if the approximation holds

```
from dolfin import *
import matplotlib.pyplot as plt
import numpy as np
import sys
set_log_active(False)

plt.figure(1)
plt.figure(2)
for i in [[4,3], [4,2], [3,2], [3,1]]:
    print('P%d-P%d' % (i[0], i[1]))
```

```

hvals = []
UE = []
PE = []
for N in [2, 4, 8, 16, 32, 64]:
    h = 1./N
    hvals.append(h)
    mesh = UnitSquareMesh(N,N)
    V = VectorFunctionSpace(mesh, 'Lagrange', i[0])
    Q = FunctionSpace(mesh, 'Lagrange', i[1])

    W = MixedFunctionSpace([V, Q])

    u, p = TrialFunctions(W)
    v, q = TestFunctions(W)

    f = Expression(("pow(pi,2)*sin(pi*x[1]) - 2*pi*cos(2*pi*x[0])", \
                    "pow(pi,2)*cos(pi*x[0])"))

    u_ex = Expression(("sin(pi*x[1])", "cos(pi*x[0])"))
    p_ex = Expression("sin(2*pi*x[0])")

    bc_u = DirichletBC(W.sub(0), u_ex, "on_boundary")
    bc_p = DirichletBC(W.sub(1), p_ex, "on_boundary")
    bc = [bc_u, bc_p]

    a = inner(grad(u), grad(v))*dx + div(u)*q*dx + div(v)*p*dx
    L = inner(f, v)*dx

    up_ = Function(W)
    A, b = assemble_system(a, L, bc)
    solve(a == L, up_, bc)

    u_, p_ = up_.split(True)

    Uerr = errornorm(u_ex, u_, norm_type='h1', degree_rise=1)
    UE.append(Uerr)
    Perr = errornorm(p_ex, p_, norm_type='l2', degree_rise=1)
    PE.append(Perr)

Ur = []
Pr = []
for j in range(1, len(UE)):
    Uconv = np.log(UE[j-1]/UE[j])/np.log(hvals[j-1]/hvals[j])
    Ur.append(Uconv)
    Pconv = np.log(PE[j-1]/PE[j])/np.log(hvals[j-1]/hvals[j])
    Pr.append(Pconv)
    print('h = %f    r_U = %f    r_P = %f' % (hvals[j], Uconv, Pconv))

plt.figure(1)
label = 'P%d-P%d' % (i[0], i[1])
plt.loglog(hvals, UE, label=label)
plt.figure(2)
label = 'P%d-P%d' % (i[0], i[1])
plt.loglog(hvals, PE, label=label)
print('\n')

plt.figure(1)
plt.legend(loc='upper left')
plt.savefig('Velocity_convergence_P%d-P%d.png' % (i[0], i[1]))

plt.figure(2)
plt.legend(loc='upper left')
plt.savefig('Pressure_convergence_P%d-P%d.png' % (i[0], i[1]))

```

7.7

Exercise 2

We are looking at the topic of 'locking', and are considering the following problem on the unit square domain $\Omega = (0, 1)^2$:

$$-\mu\Delta\mathbf{u} - \lambda\nabla\nabla \cdot \mathbf{u} = f \text{ in } \Omega \quad (5)$$

$$\mathbf{u} = \mathbf{u}_e \text{ on } \partial\Omega \quad (6)$$

where $\mathbf{u}_e = \left(\frac{\partial\phi}{\partial y}, -\frac{\partial\phi}{\partial x}\right)$, $\phi = \sin(\pi xy)$ and $\nabla \cdot \mathbf{u}_e = 0$.

a)

We are to derive an expression for f . We do this by looking at equation (1) using the exact solution \mathbf{u}_e . Seeing as $\Delta \cdot \mathbf{u}_e = 0$, equation (1) reduces to

$$-\mu\Delta\mathbf{u}_e = f \quad (7)$$

We look at the Laplacian term

$$\Delta\mathbf{u}_e = \nabla^2\mathbf{u}_e = (\nabla^2u, \nabla^2v) = \left(\frac{\partial^2u}{\partial x^2} + \frac{\partial^2u}{\partial y^2}, \frac{\partial^2v}{\partial x^2} + \frac{\partial^2v}{\partial y^2}\right) \quad (8)$$

where u and v are the components of \mathbf{u}_e . We get

$$\nabla^2\mathbf{u}_e = \left(\frac{\partial}{\partial x}[-\pi\cos(\pi xy) - \pi^2xy\sin(\pi xy)] + \frac{\partial}{\partial y}[-\pi^2x^2\sin(\pi xy)], \quad (9)$$

$$\frac{\partial}{\partial x}[\pi^2y^2\sin(\pi xy)] + \frac{\partial}{\partial y}[-\pi\cos(\pi xy) + \pi^2xy\sin(\pi xy)]\right) \\ = \left(-\pi^2y\sin(\pi xy) - \pi^2y\sin(\pi xy) - \pi^3xy^2\cos(\pi xy) - \pi^3x^3\cos(\pi xy), \quad (10)$$

$$\pi^3y^3\cos(\pi xy) + \pi^2x\sin(\pi xy) + \pi^2x\sin(\pi xy) + \pi^3x^2y\cos(\pi xy)\right) \\ = \left(-\pi^2[2y\sin(\pi xy) + \pi x(x^2 + y^2)\cos(\pi xy)], \quad (11)$$

$$\pi^2[2x\sin(\pi xy) + \pi y(x^2 + y^2)\cos(\pi xy)]\right)$$

Inserting this into equation (3) gives us

$$f = \mu \left(\pi^2[2y\sin(\pi xy) + \pi x(x^2 + y^2)\cos(\pi xy)], \quad (12) \right. \\ \left. -\pi^2[2x\sin(\pi xy) + \pi y(x^2 + y^2)\cos(\pi xy)] \right)$$

b)

Next we want to compute the numerical error for $\lambda = 1, 100, 10000$ at $h = 8, 16, 32, 64$ for polynomial order 1 and 2.

The following code computes and outputs the numerical error

```

from dolfin import *
import sys
set_log_active(False)

lvals = [1., 100., 10000.]
nvals = [8,16,32,64]

for i in [0,1]:
    print("P%d Elements\n" % (i+1))
    for l in lvals:
        for N in nvals:

            mesh = UnitSquareMesh(N,N)

            h = 1.0/N

            V = VectorFunctionSpace(mesh, 'Lagrange', i+1)
            V_1 = VectorFunctionSpace(mesh, 'Lagrange', i+1)

            u = TrialFunction(V)
            v = TestFunction(V)

            u_ex = interpolate(Expression(("pi*x[0]*cos(pi*x[0]*x[1])",\
                                           "-pi*x[1]*cos(pi*x[0]*x[1])")),V_1)

            bc = DirichletBC(V, u_ex, "on_boundary")
            bcs = [bc]

            mu = 1.

            f = interpolate(Expression(("mu * pow(pi,2) \
                                         * (2 * x[1] * sin(pi*x[0]*x[1]) \
                                         + pi * x[0] * (pow(x[0],2) + \
                                         pow(x[1],2)) * cos(pi*x[0]*x[1]))"
                                         , "-mu * pow(pi,2) * \
                                         (2 * x[0] * sin(pi*x[0]*x[1]) + pi * x[1] \
                                         * (pow(x[0],2) + pow(x[1],2)) * \
                                         cos(pi*x[0]*x[1]))"), mu=mu),V_1)

            a = mu*inner(grad(u),grad(v))*dx + 1*inner(div(u),div(v))*dx
            L = dot(f,v)*dx
            u_ = Function(V)

            solve(a == L, u_, bcs)

            err = errornorm(u_, u_ex, norm_type='l2', degree_rise=1)
            print('h = %f    lambda = %-5d    error = %e' % (h, l, err))

        print

```

The output from the program is listed below

P1 Elements		
h = 0.125000	lambda = 1	error = 3.665490e-02
h = 0.062500	lambda = 1	error = 9.893346e-03
h = 0.031250	lambda = 1	error = 2.523885e-03
h = 0.015625	lambda = 1	error = 6.342241e-04
h = 0.125000	lambda = 100	error = 2.909305e-01
h = 0.062500	lambda = 100	error = 1.624590e-01
h = 0.031250	lambda = 100	error = 6.039903e-02
h = 0.015625	lambda = 100	error = 1.756415e-02
h = 0.125000	lambda = 10000	error = 4.379122e-01
h = 0.062500	lambda = 10000	error = 4.551903e-01
h = 0.031250	lambda = 10000	error = 4.327456e-01
h = 0.015625	lambda = 10000	error = 3.518862e-01
P2 Elements		
h = 0.125000	lambda = 1	error = 6.622818e-04
h = 0.062500	lambda = 1	error = 4.404308e-05
h = 0.031250	lambda = 1	error = 2.810815e-06
h = 0.015625	lambda = 1	error = 1.769528e-07
h = 0.125000	lambda = 100	error = 1.425217e-02
h = 0.062500	lambda = 100	error = 1.477785e-03
h = 0.031250	lambda = 100	error = 1.154063e-04
h = 0.015625	lambda = 100	error = 7.836387e-06
h = 0.125000	lambda = 10000	error = 2.981601e-02
h = 0.062500	lambda = 10000	error = 7.169928e-03
h = 0.031250	lambda = 10000	error = 1.576881e-03
h = 0.015625	lambda = 10000	error = 2.721675e-04