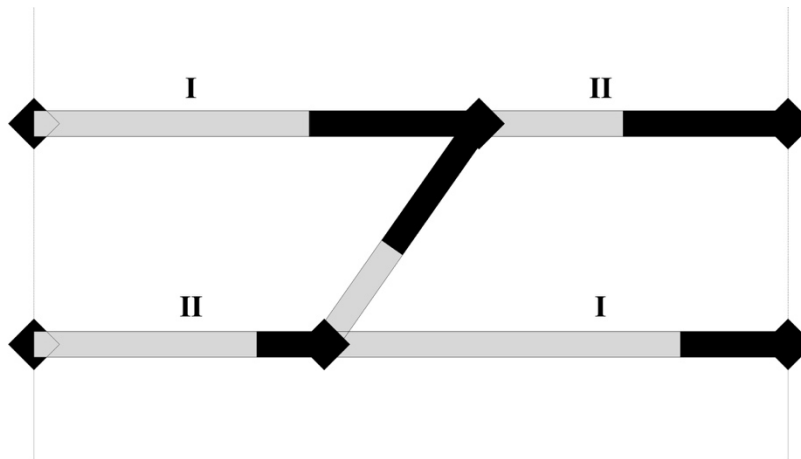


26-05-16

# PROPOSED ASSUMPTION FOR THE ORDER OF DEFORMATION PROBLEM

## 1. WHEN DO THE CURRENT ASSUMPTIONS FAIL?

Let us consider the most simple structure containing a connection and in particular the order of deformation depicted.

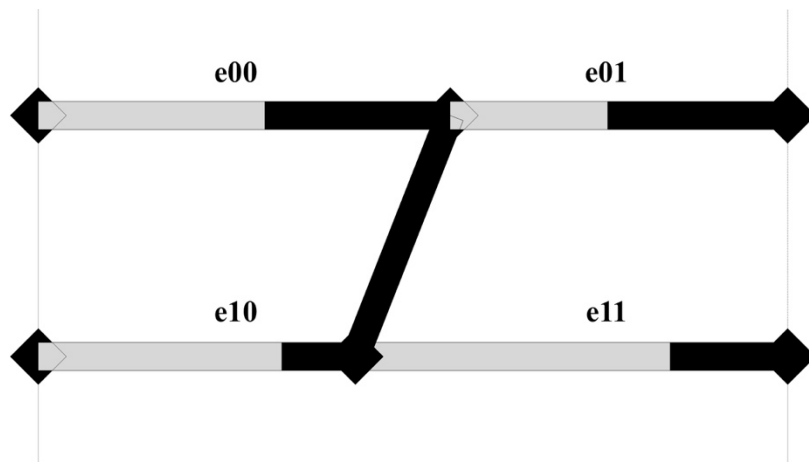


This possible solution comes directly from combinatorics: it's one out of the 4 possibilities.

In order to understand, if this solution is meaningful or should be discarded, we have to test it, deformation step after deformation step.

### A. First deformation step

- i. We start deforming as much as we can the components marked with I (i.e. e00 and e11).



- ii. The connection deforms completely and prevents a further deformation of the other components.

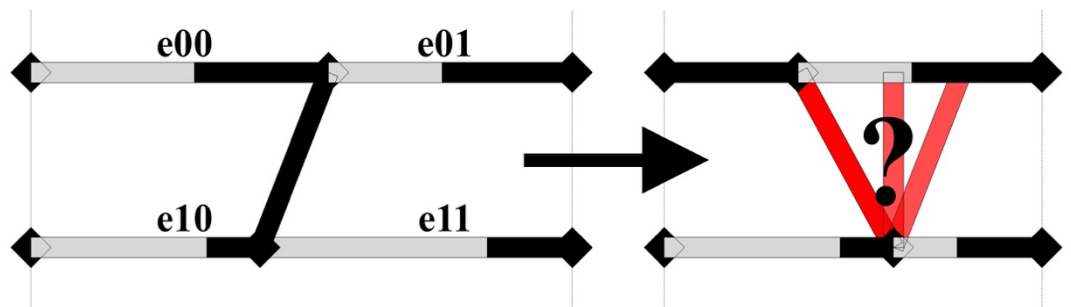
### B. The next deformation step

- i. Here comes the problem: the next deformation step isn't defined, if we bear in mind the following assumptions:

- *only one component per loadpath can deform at the same time,*
- *weaker components deform first,*
- *a component cannot deform partially and then re-start deforming,*
- *a connection cannot stretch.*

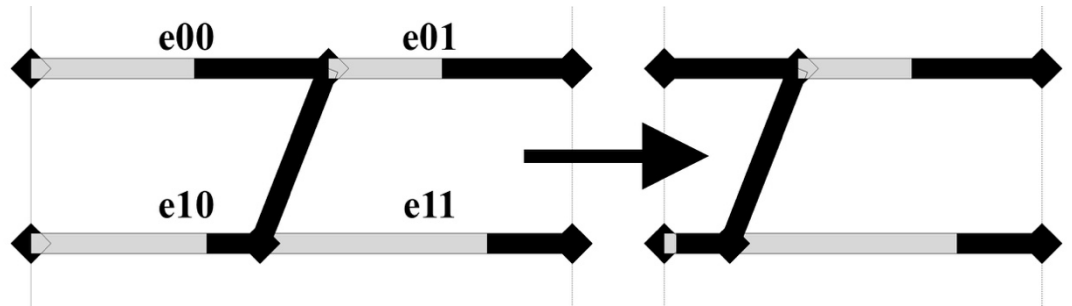
- ii. Analysis of the possible next deformation steps:

*Case 1: deformation of e00 and e11*



*The connection should deform even more and then elongate if needed, but this doesn't make sense, since the connection has become rigid after the first deformation step.*

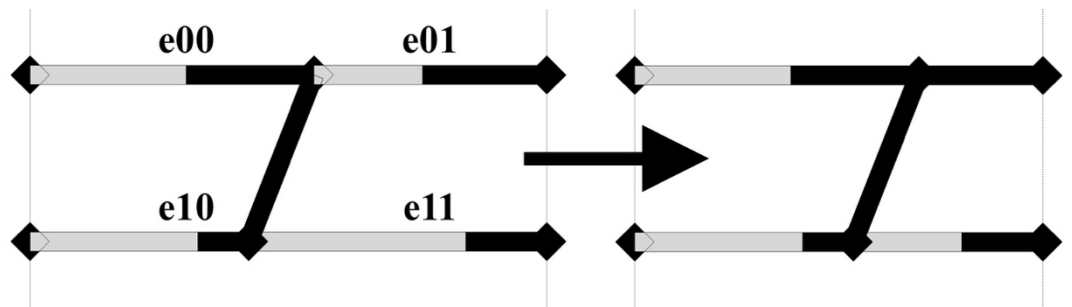
Case 2: deformation of  $e_{00}$  and  $e_{10}$



$e_{10}$  deforms instead of  $e_{11}$ , this doesn't make sense, since  $e_{11}$  is weaker than  $e_{10}$ .

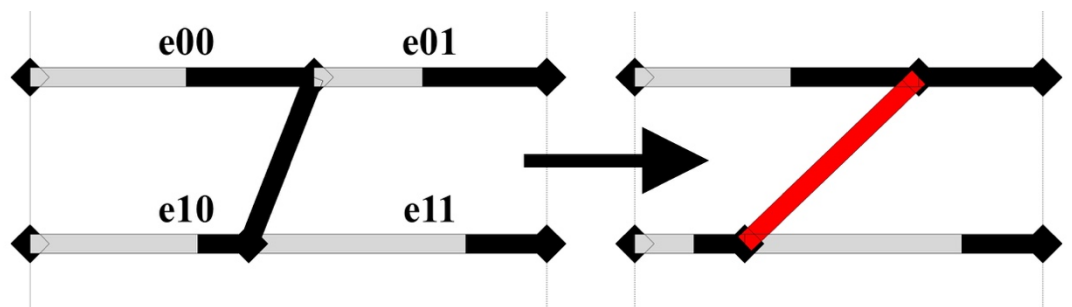
Furthermore, since the deformation of  $e_{11}$  doesn't continue after the first deformation step,  $e_{11}$  will remain undeformed at the end of the process, according to the 3<sup>rd</sup> assumption, and the structure depicted on the right will be considered completely deformed.

Case 3: deformation of  $e_{01}$  and  $e_{11}$



Same as case 2.

Case 4: deformation of  $e_{10}$  and  $e_{01}$



The connection should stretch, against the 4<sup>th</sup> assumption.

- iii. Considering that all the possible next deformation step are not satisfactory, we've come to a deadlock.

## 2. A POSSIBLE SOLUTION

### A. How to overcome the deadlock

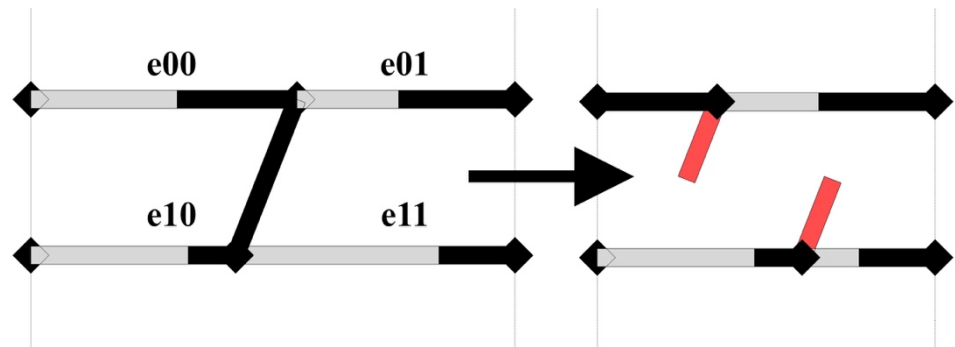
A good idea to go beyond the deadlock might be to ignore the presence of the connection as in case 1.

Another idea might be to work around the 3<sup>rd</sup> assumption and allow components to re-deform after a deadlock.

### B. Two practical ways

#### i. The connection breaks

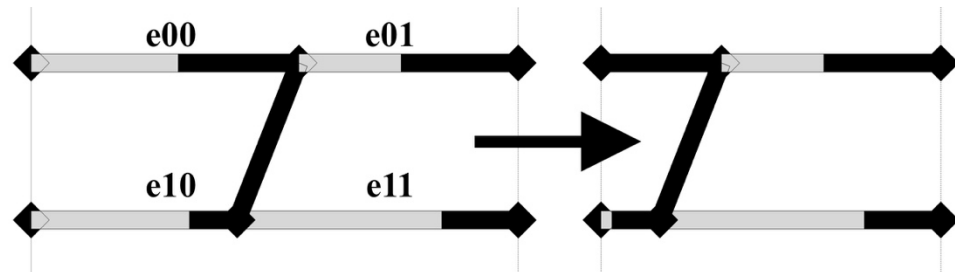
*If the connection breaks, e00 and e11 will simply keep on deforming*



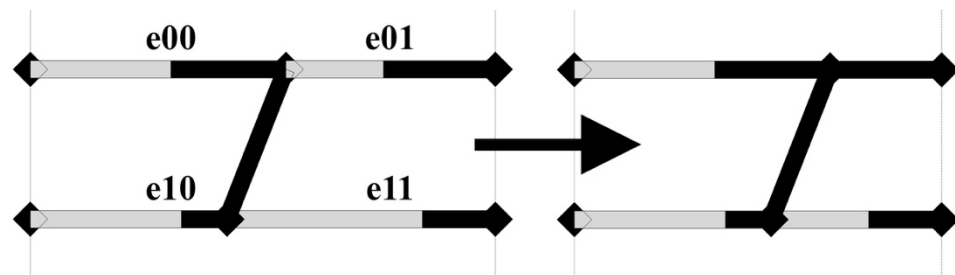
#### ii. The connection doesn't break

*If the connection doesn't break, the deadlock will be considered as the initial configuration of a new problem with 2 possible solutions:*

- *either e00 and e10 deform first*



- *or e01 and e11 deform first*



### 3. PRACTICAL IMPLEMENTATION

#### A. How to discriminate between breakable and unbreakable connections?

##### i. Deformable ratio criterion

*One way to discriminate between breakable and unbreakable connections might be considering:*

- *breakable those with a deformable ratio of 1*
- *unbreakable all the others*

*This appears to be reasonable to us, because completely deformable components, have no length after a complete deformation and therefore are probably used to model the weakest components.*

##### ii. Other criteria

Other criteria may be found in the future and one can classify them as:

- *Criteria based on the characteristics of the connection itself (as the proposed "Deformable-ratio criterion")*
- *Criteria based on the characteristics of the structure as a whole (e.g. disposition of masses, characteristics of neighbour components, ...)*
- *Criteria based on the particular deformation history*

#### B. Using a flag to store the breakable/unbreakable information

##### i. Convenient for us

The easiest way to keep track of this information is adding an attribute to the Connection class in our code. The data to store is a simple boolean:  
`self.breakable = True/False`

##### ii. Versatile for you

The value of the flag will be:

- *directly read from the .xml, if you want to explicitly define it*
- *computed based on the deformable ratio criterion, if not specified in the .xml*
- *computed based on an other criterion: in case in the future you come up with a particular sophisticated criterion, it will be easy to extend our code and adapt its mode of operation to you needs*