# SORTES - Clock

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#### 1 User Documentation

Two buttons allow the user to interact with the device. The bottommost is **button 1** and is used to browse trough a items such as numbers or menu items. The topmost is **button 2** and is generally used to confirm your selection or to enter configuration mode.

#### 1.1 Configuration Mode

To enter configuration mode from regular mode (i.e. the clock is displayed) press **button 2**. A menu will display allowing you to change the current time and alarm or quit configuration mode. When the devices powers on, you will automatically enter configuration mode since the current time has not been set. This means you will not have to press **button 2** to enter configuration mode.

#### 1.2 Setting the Clock

To configure the current time, press **button 2** to enable configuration mode if not yet enabled. Press **button 1** until **Set time?** is displayed. Confirm this choice by pressing **button 2**. You will be able to configure the clock in 3 simple steps respectively setting the hours, minutes and seconds. Use **button 1** to increase the value of each property. The input will automatically wrap around when the maximum value is reached. For example, pressing button 1 when the current hour value is 23 will yield a value of 0. Confirm each input value by pressing button 2. When all values are set you will return to the configuration menu.

#### 1.3 Setting the Alarm

Configuring the alarm is almost identical to configuring the current time. Press **button 2** to enter configuration mode, navigate to **Set alarm?** by pressing **button 1** and press **button 2** once more. Follow the steps mentioned above to configure the alarm time as desired.

## 2 System Documentation

We provided a makefile to compile the source code. Run the following command:

\$ make clock

To deploy the clock.hex file to the PIC a shell script is available. The script will start tftp and wait for input from the user.

```
$ ./deploy.sh
```

Enter the following command but do not press return just yet. Reset the PIC and wait for the corresponding LED on the router to light up, then press return.

```
put clock.hex
```

When all of this succeeds, you'll see something like this. The amount of time and bytes may differ.

### 3 System Design

#### 3.1 Specifications

The program provides an configurable clock with alarm function. At startup the user can set the clock and optionally the alarm using two button on the device. Once the time is set an orange led blinks each half a second. When the current time equals the alarm time an alarm goes of. This means two red LEDs start blinking one second on, one second of during the next 30 seconds. During operation both the alarm and time can be adjusted. Setting an alarm does not influence the current time.

#### 3.2 Structural Choices

#### 3.2.1 Timer

To effectively measure time we are using a hardware timer provided by the PIC. This timer will interrupt when its buffer overflows. We prefer this method over working with software delays because of it's increase in accuracy. Software timers are more easily influenced by (possible unknown) software implementations (i.e. arithmetics).

The timer can be operated in either 8 or 16 bit mode. This marks the length of its buffer and thus the delay between a software interrupt arises. Operating in 16 bit mode opposed to 8 bit may increase accuracy between interrupts but on the other hand might introduce a too rough granularity. A software counter is used to count the amount of interrupts between the elapse of one second. Empirical testing has shown us that this last effect is indeed a problem. Therefore, we have increased the amounts of interrupts and have chosen to operate the timer in 8 bit mode.

#### 3.2.2 Buttons

Buttons are too implemented using interrupts. When a button is pressed a dummy register is set to true. The registers are only accessed using a "read-and-clear" operation. This ensures that every button press is read atomically. The alternative is reading the actually register. This approach requires a certain delay between two read operations to ensure a single press is not interpreted as more than one. Our approach does not have this problem. The disadvantage however consists of the impossibility to press a button continuously e.g. for increasing a value without releasing the button.

#### 3.2.3 Time Structure

Storing the current time can be done in a number of ways. We could've kept a counter of nano- or milliseconds since the beginning of time, the start of the device or since midnight. We chose for a different approach in order to save space. A structure with 3 fields (hours, minutes and seconds) is used to store the current time. This had the additional advantage of introducing a certain level of abstraction. Furthermore, this structure also represents the time of the alarm.

#### 3.3 Calibration

In order to calibrate our clock we needed to find out how many interrupts occur over the course of one second. At first instance, when we were still using the 16 bit timer, we found that the correct value was between 96 en 97 interrupts per second. This meant our counting system was to course-grained. This is when we switched to operating the timer in 8 bit mode, allowing more interrupts to occur.

Using a binary search to obtain the optimal value, we found that !!!X!!! interrupts correspond to one second.

#### 3.4 Technical Peculiarities

If you want to make use of button 1 you need to set register "INTCON3bits.INT3F". For button 2 instead you need to use the register "INTCON3bits.INT1F". This is also poorly documented.

For using structures malloc() is needed (which is included in the C library for the PIC16) but what is not included is actually creating the stack. That's why you have to manually assign space for the stack. How this is done can be seen on line 7 of listing 6 on page 17.

Another headache was setting the correct size of the stack. Sometimes the stack was too large, sometimes it was too small. In both cases it caused the time structure to represent garbage. Fortunately this was fairly easy visible when displaying the current time. Adjusting the size on the other hand was not, reasoning didn't seem to get us anywhere so we ended up using trail and error to determine a workable amount.

#### A Source Code

Listing 1: strings header file

```
#define HOURS "Hours:"
#define MINUTES "Minutes:"
#define SECONDS "Seconds:"
#define CM_STRING "Choose mode:"
#define CM_QUIT_STRING "Quit config mode."
#define CM_ALARM_STRING "Set alarm?"
```

```
#define SM_ALARM_STRING "Set alarm:"
#define CM_CLOCK_STRING "Set clock?"
#define SM_CLOCK_STRING "Set clock:"
```

Listing 2: clock body file

```
// SDCC specific defines.
2 | #define ___18F97J60
3 #define ___SDCC___
4 #define THIS_INCLUDES_THE_MAIN_FUNCTION
6 #define OVERFLOW CYCLES
                             93
 #define CONFIG_MODE_QUIT -1
8 #define CONFIG_MODE_ALARM
  #define CONFIG_MODE_CLOCK
#include <stdlib.h>
12 #include <stdio.h>
#include "../Include/HardwareProfile.h"
#include "../Include/LCDBlocking.h"
17 #include "strings.h"
18 | #include "time.h"
19 | #include "clockio.h"
void init(void);
void init_config(void);
void init_time(time t, char *);
void toggle_second_led(void);
 void toggle_alarm_led(void);
  // Clock time
29 time _time;
31 // Alarm time
32 time _alarm;
34 // State indicators
```

```
int alarm_going_off;
  // Counters
  int alarm_counter;
  int overflow_counter;
  // Dummy button registers
  int but1_pressed;
  int but2_pressed;
  // Flags for marking mode.
  int config_called;
  int config_mode_on;
  int time_update_needed;
49
  /**
50
    * Initializes the program and main loop for checking
51
       for configuration input and updating the LCD.
    */
  int main(void) {
    // Initialize variables.
    init();
    // Initialize configuration mode.
57
    init_config();
    // Do first display update.
    display_update(_time);
    while(1){
       if(time_update_needed) {
         time_update_needed = 0;
63
           display_update(_time);
64
65
       if(config_called) {
         config_called =0;
         init_config();
71
72
   * Start the configuration mode.
```

```
This mode is only for setting the alarm or clock.
    */
76
   void init_config(void) {
77
     // -1 is quit, 0 is alarm , 1 is clock.
     int choice = CONFIG_MODE_ALARM;
     static char *choice string = CM ALARM STRING;
     config_mode_on = 1;
81
     display_line(CM_STRING, choice_string);
82
     while(1){
83
       if (read_and_clear(&but2_pressed)) {
84
          //Configure the selected config mode.
         switch(choice) {
            case CONFIG_MODE_ALARM:
              LCDErase();
              init_time(_alarm, SM_ALARM_STRING);
              display_line(CM_STRING, choice_string);
90
              break;
91
            case CONFIG_MODE_CLOCK:
              LCDErase();
              init_time(_time, SM_CLOCK_STRING);
              TOCONbits.TMROON = 1;
95
              display_line(CM_STRING, choice_string);
96
              break;
97
            default:
98
              LCDErase();
              config_mode_on = 0;
              return;
          }
102
       if (read_and_clear(&but1_pressed)) {
104
          //Cycle trough the config modes.
         switch(choice) {
106
            //For the alarm.
107
            case CONFIG_MODE_QUIT:
              LCDErase();
109
              choice = CONFIG MODE ALARM;
110
              choice_string = CM_ALARM_STRING;
111
              display_line(CM_STRING, choice_string);
112
              break:
113
            //For the clock.
114
```

```
case CONFIG_MODE_ALARM:
115
              LCDErase();
116
              choice = CONFIG_MODE_CLOCK;
117
              choice_string = CM_CLOCK_STRING;
              display_line(CM_STRING, choice_string);
119
              break;
120
            //For quiting.
121
            case CONFIG_MODE_CLOCK:
              LCDErase();
              choice =CONFIG_MODE_QUIT;
124
              choice_string = CM_QUIT_STRING;
              display_line(CM_STRING, choice_string);
126
              break;
127
128
129
130
131
132
133
     * Sets the given timer with what the user inputs.
134
135
   void init_time(time t, char *mode) {
136
     int h, m, s;
137
     h = get_input(24, HOURS,
                                   mode, &but1_pressed, &
138
        but2_pressed);
     m = get_input(60, MINUTES, mode, &but1_pressed, &
139
         but2_pressed);
     s = get_input(60, SECONDS, mode, &but1_pressed, &
140
         but2_pressed);
     time_set(t,h,m,s);
141
142
143
144
    * Toggle the first (red) LED.
145
146
   void toggle_second_led(void) {
147
     LED0 IO^=1;
148
149
  /**
151
```

```
* Toggle the second and third (orange) LEDs.
152
    */
153
   void toggle_alarm_led(void) {
154
     LED1_IO^=1;
     LED2_IO^=1;
156
157
158
159
    * Handles the high priority interupts.
160
       Currently both buttons and ticks have high
161
        priority.
    */
162
   void highPriorityInterruptHandler (void) __interrupt
163
     // Button 2 causes an interrupt
164
     if (INTCON3bits.INT1F == 1) {
165
     if(!config_mode_on) {
166
        config_called =1;
167
     } else {
        but2\_pressed = 1;
169
170
     if(BUTTON0_IO);
171
        INTCON3bits.INT1F = 0;
172
     }
173
174
     // Button 1 causes an interrupt
175
     if(INTCON3bits.INT3F == 1){
       but1_pressed = 1;
177
        if (BUTTON1_IO);
178
        INTCON3bits.INT3F = 0;
179
     }
180
181
     // Timer 0 causes an interrupt
182
     if(INTCONbits.TMR0IF == 1) {
183
        overflow_counter++;
184
        if(overflow counter == OVERFLOW CYCLES/2) {
185
          toggle_second_led();
186
        }else if(overflow_counter == OVERFLOW_CYCLES) {
187
          if (time_equals(_alarm,_time)) {
188
            alarm_going_off = 1;
189
```

```
190
          if (alarm_going_off) {
191
             alarm_counter++;
192
             toggle_alarm_led();
             if(alarm_counter==30) {
194
               alarm_going_off =0;
195
               alarm_counter = 0;
196
             }
197
          }
198
          overflow_counter = 0;
199
          toggle_second_led();
          add_second(_time);
201
          if(!config_called && !config_mode_on) {
202
             time_update_needed = 1;
203
204
205
        INTCONbits.TMR0IF = 0;
206
208
209
    /**
210
     * Inintializes all kinds of settings.
211
212
   void init(void) {
213
      // Initialize LCD
214
      LCDInit();
215
216
      // Initialize time
217
      _time = time_create();
218
      _alarm = time_create();
219
220
      // Enable buttons
221
      BUTTON0\_TRIS = 1;
222
      BUTTON1\_TRIS = 1;
223
      // Enable interrupts
226
      INTCONbits.GIE = 1;
      INTCONbits.PEIE = 1;
227
      RCONbits.IPEN = 1;
228
229
```

```
// Disable timer
230
     T0CONbits.TMR0ON = 0;
231
232
     // Empty timer: high before low (!)
     TMR0H = 0x00000000;
234
     TMROL = 0x00000000;
235
236
     // Enable 16-bit operation
237
     TOCONbits.TO8BIT = 0;
238
239
     // Use clock as clock source
     TOCONbits.TOCS = 0;
242
     // Unassign prescaler
243
     TOCONbits.PSA = 1;
244
245
     // Enable timer and interrupts
246
     INTCONbits.TMR0IE = 1;
248
     // Enable button interrupts
     INTCON3bits.INT1IE = 1;
250
     INTCON3bits.INT3IE = 1;
251
252
     // Enable leds
253
     LED0\_TRIS = 0;
254
     LED1\_TRIS = 0;
255
     LED2\_TRIS = 0;
     LED3\_TRIS = 0;
257
258
     // Disable all LED but backlight
259
     LED0_IO = 0;
260
     LED1_IO = 0;
261
     LED2_IO = 0;
262
     LED3_IO = 1;
     // INITIALIZE OUR OWN VARIABLES.
266
     // State indicators
     alarm_going_off = 0;
267
268
     // Counters
269
```

```
alarm_counter = 0;
270
     overflow_counter = 0;
271
272
     // Dummy button registers
     but1_pressed = 0;
     but2\_pressed = 0;
275
276
     // FLAGS FOR MARKING MODE.
277
     config_called = 0;
278
     config_mode_on = 0;
279
     time_update_needed =0;
```

Listing 3: clockio header file

```
#ifndef ___CLOCKIO_H_
  #define ___CLOCKIO_H_
  #define ___18F97J60
  #define ___SDCC___
  // Defines for easy use of the LCD.
 #define START_FIRST_LINE 0
  #define START_SECOND_LINE 16
11 // INCLUDES
 #include <stdlib.h>
  #include <stdio.h>
#include "../Include/HardwareProfile.h"
  #include "../Include/LCDBlocking.h"
  #include "time.h"
 void display_string(BYTE pos, char* text);
  void display_update(time t);
void display_line(char *top, char *bottom);
  int get_input(int maxvalue, char *text, char *mode,
     int * btn_next, int *btn_confrm);
 char* to_double_digits(int value);
```

```
int read_and_clear(int *variable);

#endif
```

Listing 4: clockio body file

```
#include "clockio.h"
2
   /**
    * Displays the given string at the given position on
       the LCD.
  void display_string(BYTE pos, char* text) {
                 1 = strlen(text);
    BYTE
               max = 32-pos;
                *d = (char*) &LCDText[pos];
    char
    const char *s = text;
    size_t
                 n = (1 < max) ?1: max;
    if (n != 0)
       while (n-- != 0) *d++ = *s++;
    LCDUpdate();
14
16
    * Updates the display and prints the current time.
    */
  void display_update(time t) {
    char display_line[32];
21
    time_print(t, display_line);
22
    display_string(0, display_line);
24
25
   /**
    * Display strings on first and second line of LCD
       display.
28
  void display_line(char *top, char *bottom) {
    display_string(START_FIRST_LINE, top);
    display_string(START_SECOND_LINE, bottom);
```

```
33
   /**
34
    * Gets the desired value for the given setting.
35
   int get_input(int maxvalue, char *text, char *mode,
      int * btn_next, int *btn_confrm) {
    BYTE length = strlen(text);
38
     int value = 0;
39
     display_line(mode, text);
40
    while(1){
41
       if(read_and_clear(btn_confrm)){
         LCDErase();
         return value;
44
45
       if (read_and_clear(btn_next)) {
46
         value = (++value)%maxvalue;
47
       display_string(START_SECOND_LINE + length + 1,
          to_double_digits(value));
51
  /**
53
    * Returns a pointer to a string of the double digit
       representation of the given value.
  char* to_double_digits(int value) {
     static char buffer[3];
57
     sprintf(buffer, "%02d", value);
    return buffer;
59
60
61
    * Returns whether the given int represents true and
       sets it to false.
64
  int read_and_clear(int *variable) {
65
     if(*variable) {
       *variable = 0;
67
       return 1;
```

```
69 }
70 return 0;
71 }
```

#### Listing 5: time header file

```
#ifndef ___NTIME_H_
#define ___NTIME_H_
struct time_struct;
typedef struct time_struct *time;
time time_create();
void time_set(time t, int hours, int minutes, int
   seconds);
int set_hours(time t, int value);
int set_minutes(time t, int value);
int set_seconds(time t, int value);
void add_second(time t);
void add_minute(time t);
void add_hour(time t);
void time_print(time t, char* str);
int time_equals(time t1, time t2);
#endif
```

#### Listing 6: time body file

```
#include "time.h"

#include <stdio.h>
#include <stdlib.h>
#include <malloc.h>

unsigned char _MALLOC_SPEC heap[56];

struct time_struct {
   int hours;
```

```
int minutes;
    int seconds;
12
  } ;
13
  time time_create(){
       time t = (time)malloc(sizeof (struct time_struct))
       time_set(t, 0, 0, 0);
17
       return t;
18
19
  void time_set(time t, int hours, int minutes, int
      seconds) {
22
    set_hours(t,hours);
    set_minutes(t, minutes);
23
    set_seconds(t, seconds);
24
25
  int set_hours(time t, int value) {
     int overflow = value/24;
    t->hours = value%24;
    return overflow;
30
31
32
  int set_minutes(time t, int value) {
    int overflow = value/60;
    t->minutes = value%60;
    return overflow;
37
38
  int set_seconds(time t, int value) {
39
    int overflow = value/60;
    t->seconds = value % 60;
    return overflow;
  void add_second(time t) {
     if (set_seconds(t,t->seconds + 1) != 0)
       add_minute(t);
47
48
```

```
49
  void add_minute(time t) {
     if(set_minutes(t,t->minutes + 1) != 0)
51
       add_hour(t);
54
  void add_hour(time t) {
55
    set_hours(t,t->hours + 1);
56
57
58
  void time_print(time t, char* str){
    sprintf(str, "%02d:%02d:%02d", t->hours, t->minutes,
         t->seconds);
61
62
  int time_equals(time t1, time t2){
63
     if(t1->seconds != t2->seconds)
      return 0;
    if(t1->minutes != t2->minutes)
       return 0;
    if(t1->hours != t2->hours)
       return 0;
69
    return 1;
70
71
```