EE360C: Lab 1

Joshua Dong (jid295)

February 28, 2016

1. Algorithm Analysis

a) bounds

The runtime is $O(n^3)$. The outer loop loops in quadratic time. Adding the entries from A[i] to A[j] is bounded above by n. Since |j-i| is dominated by n, adding the entries is also bounded below by a factor of n. Then we can conclude that the runtime is $\Theta(n^3)$.

b) algorithm

Since we recompute so many values, we could clearly be more efficient by using a memoization approach. For example:

```
\begin{array}{l} \mathbf{for}\ i \leftarrow 1..n\ \mathbf{do} \\ \mathbf{for}\ j \leftarrow i+1..n\ \mathbf{do} \\ \mathbf{if}\ j = i+1\ \mathbf{then} \\ B[i,j] = A[i] + A[j] \\ \mathbf{else} \\ B[i,j] = B[i,j-1] + A[j] \\ \mathbf{end}\ \mathbf{if} \\ \mathbf{end}\ \mathbf{for} \\ \mathbf{end}\ \mathbf{for} \end{array}
```

c) runtime

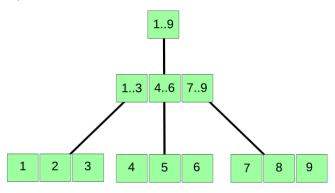
The runtime is $O(n^2)$ since we still loop over a quadratic number of elements, but we do not require O(n) for each iteration of the loop.

2. Decision Trees

a) heavy ball

Trinary search would find the ball in two rounds: first weigh two thirds of the balls, one third on each side. If they are equal, then repeat the algorithm with the unweighed group. If they are not equal, then repeat the algorithm with the heavier group.

b) decision tree



3. Heap

Suppose we implement a breadth-first search:

```
\begin{aligned} Results &\coloneqq \text{empty list} \\ Queue &\coloneqq \text{empty queue} \\ Queue &\leftarrow \text{root} \\ \textbf{while } Queue \text{ not empty } \textbf{do} \\ Current &\leftarrow Queue \\ \textbf{for } Child \in \text{children of } Current \textbf{ do} \\ \textbf{if } Child \leq \text{VALUE } \textbf{then} \\ Results &\leftarrow Child \\ Queue &\leftarrow Child \\ \textbf{end if} \\ \textbf{end for} \\ \textbf{end while} \end{aligned}
```

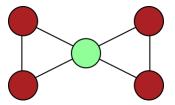
Then our time complexity would be O(n), where n is the number of elements in the heap.

4. Graphs

a) counterexample



b) counterexample



5. Graphs

T never produces a cyclic graph, because trees by definition have no cycles. If G is cyclic, then T cannot be equal to G since a cyclic graph cannot have the same edges as an acyclic graph. Then we have shown that if a G is cyclic, then the depth-first and breadth-first tree generated from a node u in G differs from G. The contrapositive of this statement is that if the depth-first search tree is the same as the breadth-first search tree for a graph G, then G is acyclic.

Suppose T is both a depth-first search tree and a breadth-first search tree rooted at u of a connected graph G. Then G is acyclic. Since G is connected, T has every vertex of G. Suppose G has an edge e not contained in T. By definition of a finite tree, adding an edge to T would create a cycle. But G is acyclic, so e is not in G, contradiction. Then no edge in G is not in T, which is what we sought to prove.