

Overview

30 September 2019 10:23

Course Homepage

https://bb.imperial.ac.uk/webapps/blackboard/content/listContent.jsp?course_id=_17446_1&content_id=_1582918_1

Maths C

Vector Calculus

https://bb.imperial.ac.uk/webapps/blackboard/content/listContent.jsp?course_id=_17446_1&content_id=_1582939_1

Numerical Analysis

https://bb.imperial.ac.uk/webapps/blackboard/content/listContent.jsp?course_id=_17446_1&content_id=_1582936_1

Book(s)

[Advanced Modern Engineering Mathematics GlynJames](#)
[ADVANCED ENGINEERING MATHEMATICS BY ERWIN ERESZIG1](#)

Youtube links

Complex analysis:

<https://www.youtube.com/playlist?list=PLHjOMouVJ7UXj9RqccYzktIz9DQdE6l66>

Aims:

Introduce the students to concepts of Vector Calculus and Numerical Analysis required for the second and later years of their Electrical and Electronic Engineering course.

Learning Outcomes:

At the end of the course, the students will be able to

1. Understand the notation used to describe scalar and vector fields;
2. Visualise scalar and vector fields;
3. Carry out mathematical operations on scalar and vector fields;
4. Differentiate and integrate scalar and vector fields;
5. Solve partial differential equations involving scalar and vector fields;
6. Understand the notation and methods used in numerical analysis;
7. Understand the derivation of Euler's, Heun's, midpoint, Runge-Kutta, finite differences methods;
8. Understand the error analysis underpinning some of these methods;
9. Apply these methods to the solution of ordinary and partial differential equations, including error analysis;
10. Implement and visualise the solutions using Matlab.

Syllabus:

1. Scalar Fields, Partial Differential Equations, Vector Fields, Integrals, Differential Operators.
2. ODE methods: Euler's, Heun's, midpoint, Runge-Kutta. Finite differences method for ODE and PDE. Error Analysis. Implementation with Matlab.

From <http://intranet.ee.ic.ac.uk/electricalengineering/eecourses_t4/course_content.asp?c=EE2-08C&s=l2#start>

$$\nabla = \text{'gradient operator'} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

$$\nabla \phi(x, y, z) = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$$

$\nabla \phi$ is a vector giving the direction of most rapid change in ϕ .

$$\operatorname{div} \underline{B} = \nabla \cdot \underline{B} = \frac{\partial B_1}{\partial x} + \frac{\partial B_2}{\partial y} + \frac{\partial B_3}{\partial z}$$

$\operatorname{div} \underline{B}$ is a scalar - it expresses how vector \underline{B} changes spatially through the 6 faces of a 3D box

$$\nabla \cdot \underline{B} \neq \underline{B} \cdot \nabla$$

$$\operatorname{curl} \underline{B} = \nabla \times \underline{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_1 & B_2 & B_3 \end{vmatrix} = \hat{i} [B_{3y} - B_{2z}] - \hat{j} [B_{3x} - B_{1z}] + \hat{k} [B_{2x} - B_{1y}]$$

The curl expresses how much swirl is in a vector field

Identities

$$\operatorname{curl}(\nabla \psi) = \nabla \times \nabla \psi = 0$$

$$\operatorname{div}(\operatorname{curl} \underline{B}) = \nabla \cdot (\nabla \times \underline{B}) = 0$$

For two scalars: ψ, ϕ

$$\nabla(\phi \psi) = \psi \nabla \phi + \phi \nabla \psi$$

For vector \underline{B} and scalar ψ

$$\operatorname{div}(\psi \underline{B}) = \psi \operatorname{div} \underline{B} + (\nabla \psi) \cdot \underline{B}$$

$$\operatorname{curl}(\psi \underline{B}) = \psi \operatorname{curl} \underline{B} + (\nabla \psi) \times \underline{B}$$

The max value of $D_x f(x)$ is given by $\|\nabla f(x)\|$ and occurs in the direction given by $\nabla f(x)$

 and occurs in the direction given by ∇f

$$\text{Proof: } D_{\underline{u}} f = \nabla f \cdot \underline{u} = \|\nabla f\| \|\underline{u}\| \cos \theta \quad \begin{array}{l} \text{= 1 as } \underline{u} \text{ is unit vector} \\ \text{which has magnitude 1} \end{array}$$

$$= \|\nabla f\| \cos \theta$$

$\theta = 0 \rightarrow \cos \theta = 1 \quad \begin{array}{l} \text{→ } \theta \text{ is the angle} \\ \text{between } \nabla \text{ and } \underline{u} \end{array}$

$$\max[\|\nabla f\| \cos \theta] = \|\nabla f\|$$

At this point, the angle between ∇ and $\underline{u} = 0$
 i.e. the vector \underline{u} is pointing in the same direction as the gradient ∇

$$\begin{array}{c} \text{scalar field} \xrightarrow{\text{grad}} \text{vector field} \xrightarrow{\text{div}} \text{scalar field} \\ \text{scalar field} \xrightarrow{\text{grad}} \text{vector field} \xrightarrow{\text{curl}} \text{vector field} \\ \text{vector field} \xrightarrow{\text{div}} \text{scalar field} \xrightarrow{\text{grad}} \text{vector field} \\ \text{vector field} \xrightarrow{\text{curl}} \text{vector field} \xrightarrow{\text{div}} \text{scalar field} \\ \text{vector field} \xrightarrow{\text{curl}} \text{vector field} \xrightarrow{\text{curl}} \text{vector field}. \end{array}$$

Fact

- (a) For any scalar field f we have $\text{curl}(\text{grad}(f)) = \nabla \times (\nabla(f)) = 0$.
- (b) For any vector field \mathbf{u} we have $\text{div}(\text{curl}(\mathbf{u})) = \nabla \cdot (\nabla \times \mathbf{u}) = 0$.

Max Rate of Change

$$D_{\underline{u}} f = \nabla f \cdot \underline{u} = \|\nabla f\| \|\underline{u}\| \cos \theta$$

$$= \|\nabla f\| \cos \theta$$

The max rate of change \propto when $\cos \theta = 1$

- The unit vector is parallel to the gradient
- The max value is $\|\nabla f\|$ — magnitude of the gradient
- The gradient points in the direction of max rate of change
- Magnitude of gradient is max rate of change

Line Integrals of Scalar Fields (γ)

$$\int_C \gamma(x, y, z) ds \leftarrow \text{general formula}$$

$$ds = \sqrt{\dot{x}^2 + \dot{y}^2} dt \quad \begin{cases} \text{where } x, y \text{ denotes} \\ \dot{x}/dt, \dot{y}/dt \end{cases}$$

Example $\int_C x^2 y ds$ where C is the arc of $x^2 + y^2 = 1$ in the first quadrant

1. Parametrise:

$$\begin{aligned} x &= \cos t & y &= \sin t & ds &= \sqrt{\cos^2 t + \sin^2 t} dt = 1 \cdot dt = dt \\ \dot{x} &= -\sin t & \dot{y} &= \cos t & 0 \leq t \leq \pi/2 \end{aligned}$$

2. Substitute into formula & solve

$$\int_C x^2 y ds = \int_0^{\pi/2} \cos^2 t \sin t dt = \left[-\frac{\cos^3 t}{3} \right]_0^{\pi/2} = \frac{1}{3}$$

Line Integrals of Vector Fields

$$\int_C \underline{F}(x, y, z) \cdot d\underline{r} = \int_C (F_1 dx + F_2 dy + F_3 dz) \quad (\text{General formula})$$

Example: Find $\int_C \underline{F} \cdot d\underline{r}$ where $\underline{F} = x^2 y \hat{i} + (x-z) \hat{j} + xy \hat{k}$ and C is $y = x^2$ in plane $z=2$ from $(0, 0, 2) \rightarrow (1, 1, 2)$

1. Substitute into formula

$$\int_C (x^2 y dx + (x-z) dy + xy dz)$$

2. Find ways to remove variables / simplify

If we are in plane $z=2$ then $dz = 0$

If $y = x^2$ $dy = 2x dx$ so we try to get integral in terms of x and dx only

$$\int_C (x^2 \cancel{x^2} dx + (x-2) \cancel{2x} dx + xy \cancel{0}) = \int_C (x^4 dx + (2x^2 - 4x) dx)$$

3. Find limits & solve

$(0, 0, 2) \rightarrow (1, 1, 2)$ we choose the x values as we are dx

$$\int_0^1 (x^4 + 2x^2 - 4x) dx = \left[\frac{x^5}{5} + x^3 - 2x \right]_0^1 = -17/15$$

\int_0^L

0

Independence of Path

1. $\int_C \underline{E} \cdot d\underline{s}$ is independent of path if

$$\text{curl } \underline{E} = 0$$

2. If C is a closed path

$$\oint_C \underline{E} \cdot d\underline{s} = 0$$

Change of Variables

$$\iint_R f(x, y) dA = \iint f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

$$J_{u,v}(x, y) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

Example: $\iint_R (x - 3y) dA$ where R is the region with vertices $(0, 0)$, $(2, 1)$, $(1, 2)$ using

1. Find the jacobian:

$$J_{u,v}(x, y) = \begin{vmatrix} 2 & 1 \\ 1 & 2 \end{vmatrix} = 4 - 1 = 3$$

$$x = 2u + v \quad y = u + 2v$$

2. Sub v and u into the expression

$$x - 3y = 2u + v - 3u - 6v = -u - 5v \rightarrow \iint (-u - 5v) |B| du dv$$

3. Find limits

$$\text{Vertices: } (0, 0), (2, 1), (1, 2) \rightarrow$$

Find eq of each line

$$\textcircled{1} \Rightarrow y = 3 - x$$

$$\textcircled{2} \Rightarrow y = 2x$$

$$\textcircled{3} \Rightarrow y = \frac{1}{2}x$$

Sub u, v into these equations ($y = u + 2v$ $x = 2u + v$)

$$\textcircled{1} \Rightarrow u + 2v = 3 - 2u - v \rightarrow 3u = 3 - 3v \rightarrow u = 1 - v$$

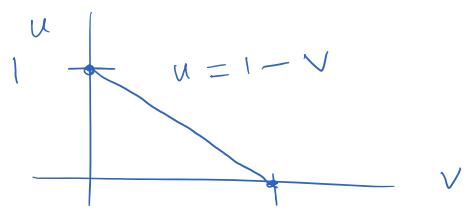
$$\textcircled{2} \Rightarrow u + 2v = 4u + 2v \rightarrow 3u = 0 \rightarrow u = 0$$

$$\textcircled{3} \Rightarrow u + 2v = u + \frac{1}{2}v \rightarrow \frac{3}{2}v = 0 \rightarrow v = 0$$

4. Substitute into Integral

$$3 \iint_0^{1-v} (-u - 5v) du dv$$

we integrate w.r.t u first, which varies between 0 and $1-v$ then w.r.t v , which varies between 0 and 1.



5. Integrate outer, then inner Expressions

$$3 \int_0^1 \left[-\frac{u^2}{2} - 5vu \right]_0^{1-v} dv = 3 \int_0^1 \left[-\frac{(1-v)^2}{2} - 5v(1-v) \right] dv$$

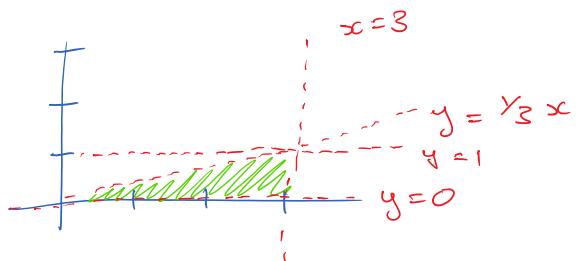
$$\begin{aligned}
 3 \int_0^1 \left[-\frac{u^2}{2} - 5vu \right]_0^1 du &= 3 \int_0^1 \left[-\frac{1-v^2}{2} - 5v(1-v) \right] du \\
 &= 3 \int_0^1 \left(-\frac{(1-2v+v^2)}{2} - 5v + 5v^2 \right) du = 3 \int_0^1 \left(\frac{9}{2}v^2 - 4v - \frac{1}{2} \right) du \\
 &= 3 \left[\frac{3}{2}v^3 - 2v^2 - \frac{1}{2}v \right]_0^1 = 3 \left[\frac{3}{2} - 2 - \frac{1}{2} \right] = 3[-1] = -3
 \end{aligned}$$

Changing Order of Integration

Example: $\iint_{3y \leq x} e^{x^2} dx dy$

1. Set the inner limits = first variable of integration, and outer to

the second
 $\int_{0=y}^{1=y} \int_{3y=x}^{3=x}$
 $0=y$ $3y=x$



2. Graph these lines/lower \uparrow

3. Find the new limits from the graph

In this case lower limit $y=0$, and the upper limit = line $y=y_3 x$

Then for the outer integral the lower limit $x=0$ and

upper limit $x=3$

So the integral becomes:

$$\iint_0^3 e^{x^2} dy dx$$

4. Integrate \square

$$\int_0^3 \left[e^{x^2} y \right]_0^{y_3 x} dx = \int_0^3 \frac{1}{3} x e^{x^2} dx \quad \begin{aligned} u &= x^2 \\ du &= 2x dx \\ x=0 &\quad u=0 \\ x=3 &\quad u=9 \end{aligned}$$

$$\rightarrow \frac{1}{3} \int_0^3 \frac{1}{2} e^u du = \frac{1}{6} \left[e^u \right]_0^9 = \boxed{\frac{1}{6} e^9}$$

Line integrals

16 October 2019 11:55

Line Integrals

Line Integrals are the same as normal integrals, but we integrate over a curve in a space/ plane.

- This means we must represent a curve by a parametric representation:

$$\underline{r}(t) = [x(t), y(t), z(t)] = x\hat{i} + y\hat{j} + z\hat{k} \quad a \leq t \leq b$$

- This is the 'path of integration', from $\underline{r}(a)$ to $\underline{r}(b)$
- If A and B coincide then the path is closed.

The line integral is defined by:

$$\begin{aligned} \int_C \underline{F}(\underline{r}) \cdot d\underline{r} &= \int_a^b \underline{F}(\underline{r}(t)) \cdot \underline{r}'(t) dt \\ &= \int_a^b (F_1 x' + F_2 y' + F_3 z') dt \end{aligned}$$

↙ dot product
↙ scalar due to
dot product

A closed path is denoted by: \oint_C

The line integral may be split up

$$\int_C \underline{F} \cdot d\underline{r} = \int_{C_1} \underline{F} \cdot d\underline{r} + \int_{C_2} \underline{F} \cdot d\underline{r}$$

Example: Line Integral on a Plane

$$\underline{F}(\underline{r}) = -y\hat{i} - xy\hat{j} \quad C = \text{circular arc } r=1 \text{ in 1st quadrant}$$

1. Parameterise into t variable, we are using a circle

$$\text{so } C \Rightarrow \underline{r}(t) = \cos t \hat{i} + \sin t \hat{j} \quad 0 \leq t \leq \pi/2$$

$x(t) = \cos t \quad y(t) = \sin t$

2. Substitute

$$F(r(t)) = -\sin t \mathbf{i} - \sin t \cos t \mathbf{j}$$

$$r'(t) = -\sin t \mathbf{i} + \cos t \mathbf{j}$$

$$\int_0^{\pi/2} (-\sin t, -\sin t \cos t) \cdot (-\sin t, \cos t) dt$$

$$\int_0^{\pi/2} \sin^2 t - \sin t \cos^2 t dt$$

3. Solve

$$u = \cos t \quad t = \frac{\pi}{2}, u = 0 \quad t = 0, u = 1$$

$$\int_0^{\pi/2} \frac{1}{2}(1 - \cos 2t) dt + \int_1^0 u^2 du$$

$$\frac{1}{2} \left[t - \frac{1}{2} \sin 2t \right]_0^{\pi/2} + \left[\frac{u^3}{3} \right]_1^0$$

$$\frac{1}{2} \left[\frac{\pi}{2} \right] + \left[-\frac{1}{3} \right] = \underline{\underline{\frac{\pi}{4} - \frac{1}{3}}}$$

Example: Line Integral in Space

$$F(\mathbf{r}) = z \mathbf{i} + x \mathbf{j} + y \mathbf{k} \quad C = \text{helix} \quad r(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + 3t \mathbf{k}$$

1. Parametrize

From $r(t)$, we know $x(t) = \cos t \quad y(t) = \sin t \quad z(t) = 3t$
 $r'(t) = (-\sin t, \cos t, 3)$

2. Substitute

$$\int_0^{2\pi} (3t, \cos t, \sin t) \cdot (-\sin t, \cos t, 3) dt$$

3. Solve

$$\int_0^{2\pi} -3t \sin t + \cos^2 t + 3 \sin t \ dt$$

$$u = t \quad v = -\cos t \\ u' = 1 \quad v' = \sin t$$

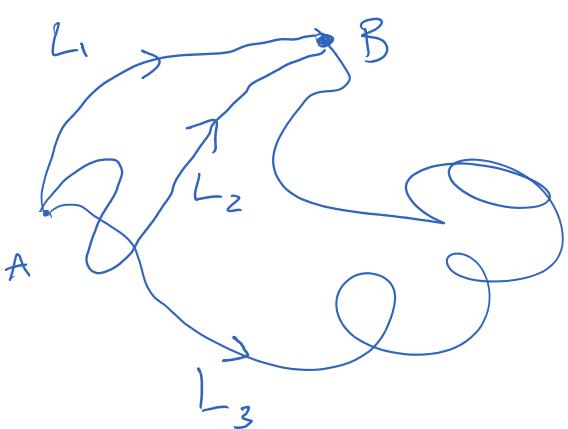
$$-3 \left[-t \cos t \Big|_0^{2\pi} + \int_0^{2\pi} \cos t \ dt \right] + \int_0^{2\pi} \frac{1}{2} \cos 2t + 1 \ dt + 3 \left[-\cos t \Big|_0^{2\pi} \right]$$
$$6\pi - 3 \left[\sin t \Big|_0^{2\pi} \right] + \frac{1}{2} \left[-\frac{1}{2} \sin 2t + t \right]_0^{2\pi} + 3 \left[-\cos t \Big|_0^{2\pi} \right]$$

$$6\pi - 0 + \frac{1}{2}(2\pi) + 0 = 6\pi + \pi = 7\pi$$

Path Independence

A line integral is path independent if for every start & endpoints A, B, the line integral evaluates to the same value for all paths

i.e. No matter what path you take,
if you start at A and end at B
the line integral value is the same



all = the same value

For a domain D, path independence holds if:

$$\textcircled{1} \quad \underline{F} = \text{grad } f$$

\textcircled{2} Integration around closed curves $C = 0$

$$\textcircled{3} \quad \text{curl } \underline{F} = \underline{0}$$

$$\textcircled{1} \quad \underline{F} = \text{grad } f \Rightarrow F_1 = \frac{\partial f}{\partial x}, \quad F_2 = \frac{\partial f}{\partial y}, \quad F_3 = \frac{\partial f}{\partial z}$$

$$\int_A^B (F_1 dx + F_2 dy + F_3 dz) = f(B) - f(A)$$

Example: Show $\int_C (2x dx + 2y dy + 4z dz)$ is path independent & find the value from $(0, 0, 0)$ to $(2, 2, 2)$

$$\underline{F} = (2x, 2y, 4z) = \text{grad } f$$

$$f = x^2 + y^2 + 2z^2 \quad \frac{\partial f}{\partial x} = F_1 = 2x \quad \frac{\partial f}{\partial y} = 2y = F_2 \quad \frac{\partial f}{\partial z} = F_3 = 4z$$

so independent so

$$\int_C \underline{F} d\underline{x} = f(B) - f(A) = (4+4+8) - (0+0+0) = 16$$

Double integrals

16 October 2019 14:18

The double integral of $f(x, y)$ over the region R is:

$$\iint_R f(x, y) \, dx \, dy = \iint_R f(x, y) \, dA$$

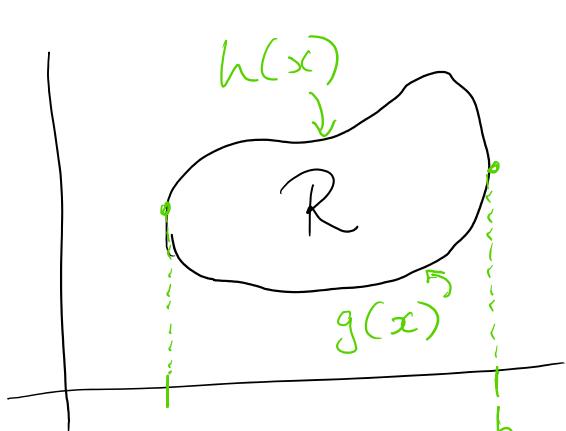
Evaluation by two successive Integrations

$$\iint_R f(x, y) \, dx \, dy = \int_a^b \left[\int_{g(x)}^{h(x)} f(x, y) \, dy \right] dx$$

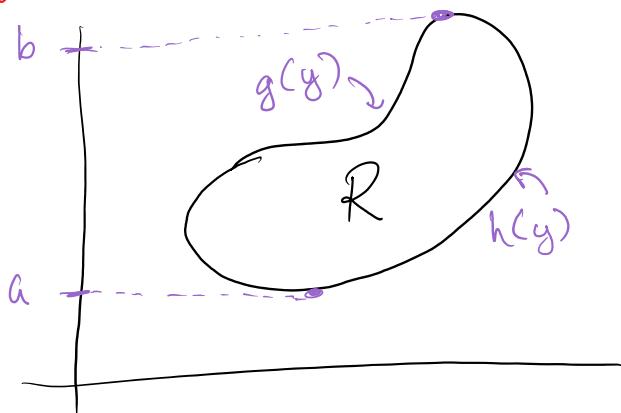
$h(x)$ and $g(x)$ represent the boundary curve of R .

- the result of the inner integral will be a function of x (due to limits).

$$= \int_a^b \left[\int_{g(y)}^{h(y)} f(x, y) \, dx \right] dy$$



↑ finding limits
for $dy \, dx$
generally



↑
for $dx \, dy$

Right = top Top = top
Left = bottom Bottom = Bottom (limits)

Change of variables (Jacobian)

$$\iint_{x,y} f(x, y) \, dx \, dy = \iint_{u,v} f(r(u, v), u(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du \, dv$$

$$\iint_R f(x, y) dx dy = \iint_K f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

this can also be written

$$f_{u,v}(x, y) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

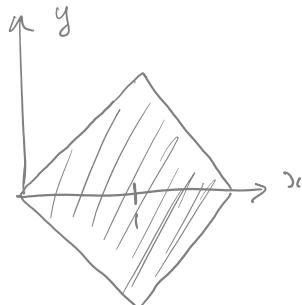
the two lines are 'absolute value' lines

Example: evaluate $\iint_R (x^2 + y^2) dx dy$

1. (If not given) find transformation

$$x+y=u \quad x-y=v$$

$$x = \frac{1}{2}(u+v) \quad y = \frac{1}{2}(u-v)$$



2. Find the Jacobian $\Rightarrow \begin{vmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{vmatrix} = -\frac{1}{4} - \frac{1}{4} = -\frac{1}{2}$

this will just be $\frac{1}{2}$
in integral as we take
 $|\frac{1}{2}| = \frac{1}{2}$

3. Sub into formula

$$\frac{1}{2} \iint_0^2 \left[\frac{1}{2}(u+v) \right]^2 + \left[\frac{1}{2}(u-v) \right]^2 du dv$$

$$= \frac{1}{8} \iint_0^2 u^2 + v^2 + 2uv + u^2 + v^2 - 2uv du dv$$

$$= \frac{1}{4} \iint_0^2 u^2 + v^2 du dv = \frac{8}{3}$$

Often we use polar coordinates $x = r \cos \theta \quad y = r \sin \theta$

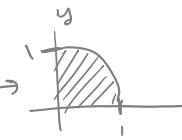
$$\text{where } J_{r,\theta}(x, y) = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta \\ = r(\cos^2 \theta + \sin^2 \theta) \\ = r \cdot 1 = r$$

$$\iint_R f(x, y) dx dy = \iint_D f(r \cos \theta, r \sin \theta) r dr d\theta$$

$$\iint_R f(x, y) dx dy = \iint_{R^*} f(r \cos \theta, r \sin \theta) r dr d\theta$$

Example : Polar coordinates

$f(x, y) = 1 \rightarrow$ mass density \rightarrow Find the total mass



$$\begin{aligned} M &= \iint_R dx dy = \iint_{R^*} r dr d\theta = \int_0^{\pi/2} \left[\frac{r^2}{2} \right]_0^1 d\theta = \int_0^{\pi/2} \frac{1}{2} d\theta \\ &= \left[\frac{1}{2} \theta \right]_0^{\pi/2} = \frac{\pi}{4} \end{aligned}$$

using formula above.

Integral Theorems

16 October 2019 19:16

Greens Theorem

Greens Theorem transforms double integrals into line integrals
& vice versa

$$\iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \oint_C (F_1 dx + F_2 dy)$$

Example: $F_1 = y^2 - 7y$ $F_2 = 2xy + 2x$ for circle $x^2 + y^2 = 9$

$$\begin{aligned} & \iint_R \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} dx dy = \iint_R (2y+2) - (2y-7) dx dy \\ &= \iint_R 9 dx dy = 9 \iint dx dy = 9\pi \leftarrow \text{LHS} \end{aligned}$$

RHS: $\underline{\Gamma}(t) = (\cos t, \sin t)$ $\underline{\Gamma}'(t) = (-\sin t, \cos t)$

$$F_1 = \sin^2 t - 7 \sin t \quad F_2 = 2 \cos t \sin t + 2 \cos t$$

$$\oint_C (F_1 x' + F_2 y') dt = \int_0^{2\pi} 7 \sin^2 t - \sin^3 t + 2 \cos^2 t \sin t + 2 \cos^3 t dt$$

↑
change of variables

$$= 7 \int_0^{2\pi} \sin^2 t - \int_0^{2\pi} \sin^3 t + 2 \int_0^{2\pi} \cos^2 t \sin t + 2 \int_0^{2\pi} \cos^3 t$$

↑
 $u = \cos t$
 $du = -\sin t dt$ ← we same sub

$$= 7 \int \frac{1 - \cos 2t}{2} + \int 1 - u^2 du - 2 \int u^2 + 2 \int \frac{\cos 2t + 1}{2}$$

$$= \frac{7}{2} \left[t - \frac{1}{2} \sin 2t \right]_0^{2\pi} + \left[\cos t - \frac{1}{3} \cos^3 t \right]_0^{2\pi} - 2 \left[\frac{1}{3} \cos^3 t \right]_0^{2\pi} + \left[\frac{1}{2} \sin 2t + t \right]_0^{2\pi}$$

$$= 7\pi + 0 - 0 + 2\pi = 9\pi$$

The area A enclosed by circle C

$$A = \iint_A 1 \, dx \, dy = \oint_C x \, dy = - \oint_C y \, dx = \frac{1}{2} \oint_C (-y \, dx + x \, dy)$$

$$x = x(u, v) \quad y = y(u, v)$$

$$A' = \iint_{A'} du \, dv = \oint_{C'} u \, dv = \oint_{C'} u \left(\frac{\partial v}{\partial x} \, dx + \frac{\partial v}{\partial y} \, dy \right)$$

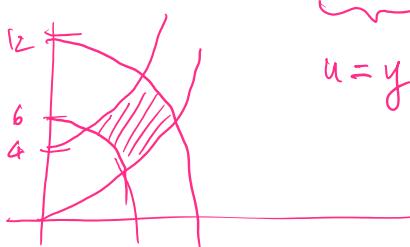
etc

$$\iint_A \left(\frac{\partial u \partial v}{\partial x \partial y} - \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} \right) \, dx \, dy$$

Jacobian

Example: $\iint xy \, dx \, dy$ over region bounded by

$$y = x^2 + 4, \quad y = x^2, \quad y = 6 - x^2, \quad y = 12 - x^2 \quad y \geq 0, \quad x \geq 0$$



$$u = y + x^2$$

$$v = y - x^2$$

$$J(x, y)_{(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{bmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{bmatrix}^{-1}$$

$$\frac{\partial u}{\partial x} = 2x, \quad \frac{\partial u}{\partial y} = 1 \quad \frac{\partial v}{\partial x} = -2x, \quad \frac{\partial v}{\partial y} = 1$$

$$\Rightarrow [2x + 2x]^{-1} = \frac{1}{4x} \quad y = (u+v)/2$$

$$\Rightarrow \iint_{A'} xy \frac{1}{4x} \, du \, dv = \frac{1}{4} \iint_{A'} y \, du \, dv = \frac{1}{8} \iint_{A'} (u+v) \, du \, dv$$

$$u \Rightarrow 6 \rightarrow 12$$

$$v \Rightarrow 4 \rightarrow 4$$

$$\frac{1}{8} \int_4^{12} dv \int_4^{12} (u+v) \, du = \frac{1}{8} \int_4^{12} \left[\frac{u^2}{2} + vu \right]_4^{12} \, dv$$

$$\begin{aligned}
 & \frac{1}{8} \int_0^4 dv \int_6^{12} (u+v) du = \frac{1}{8} \int_0^4 \left[\frac{u^2}{2} + vu \right]_6^{12} du \\
 &= \frac{1}{8} \int_0^4 [(72+12v) - (18+6v)] du \\
 &= \frac{1}{8} \int_0^4 54 + 6v du = \frac{1}{8} [54v + 3v^2]_0^4 \\
 &= \frac{1}{8} [216 + 48] = \frac{264}{8} = 8 \sqrt{\frac{264}{4}} = 33
 \end{aligned}$$

Surface Integrals

We may integrate over two types of Surfaces:

$$\begin{array}{ll}
 a) \iint_S f(x, y, z) dS & b) \iint_S \underline{F}(r) \cdot \underline{n} dS = \iint_S \underline{F}(r) \cdot d\underline{S} \\
 \text{Scalar field} & \text{Vector fields}
 \end{array}$$

$$\iint_S \underline{F}(r) \cdot d\underline{S} = \iint_A \left(P \frac{\partial z}{\partial x} - Q \frac{\partial z}{\partial y} + R \right) dx dy$$

$$\iint_S f(x, y, z) dS = \iint_A f(x, y, z(x, y)) \sqrt{1 + \left(\frac{\partial z}{\partial x} \right)^2 + \left(\frac{\partial z}{\partial y} \right)^2} dx dy$$

Example

Evaluate $\iint_S (x+y+z) dS$ $\Rightarrow x^2+y^2+z^2=1$ in Ist quad

x	y	z	
$\frac{\partial z}{\partial x} = -x$	$\frac{\partial z}{\partial y} = -y$	$\frac{\partial z}{\partial x} = -x$	$\frac{\partial z}{\partial y} = -y$

$$z = \sqrt{1 - y^2 - x^2}$$

$$\frac{\partial z}{\partial x} = \frac{-x}{\sqrt{1 - y^2 - x^2}}$$

$$\frac{\partial z}{\partial y} = \frac{-y}{\sqrt{1 - y^2 - x^2}}$$

$$\iint x \cdot y + \sqrt{1 - y^2 - x^2} \quad \underline{\text{etc}}$$

Exercises

24 October 2019 16:41

Glyn James

Find total diff $u(x, y) = x^y$

$$\frac{\partial u}{\partial x} = yx^{y-1} \quad \frac{\partial u}{\partial y} = x^y \ln x$$

$$du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy = yx^{y-1} dx + x^y \ln x dy$$

- Find grad f for $f(r) = 3x^2 + 2y^2 + z^2$ at $(1, 2, 3)$
calculate the directional derivative at $(1, 2, 3)$ in
the direction of $\mathbf{u} = \frac{1}{3}(2, 2, 1)$

$$\frac{\partial f}{\partial x} = 6x \quad \frac{\partial f}{\partial y} = 4y \quad \frac{\partial f}{\partial z} = 2z$$

$$\text{grad } f = 6x\mathbf{i} + 4y\mathbf{j} + 2z\mathbf{k}$$

$$\text{grad } f(1, 2, 3) = 6\mathbf{i} + 8\mathbf{j} + 6\mathbf{k}$$

$$\text{directional derivative} = (6, 8, 6) \cdot \left(\frac{2}{3}, \frac{2}{3}, \frac{1}{3}\right)$$

$$= 4 + \frac{16}{3} + \frac{6}{3} = \frac{34}{3}$$

- Find max rate of change of f at $(1, 2, 3)$ and
direction.

Max rate of change occurs in the direction parallel
to grad f at $(1, 2, 3) \Rightarrow (6, 8, 6)$

$$\underline{\mathbf{u}} = \frac{1}{\sqrt{36+64+36}} (6, 8, 6) = \frac{1}{2\sqrt{34}} (6, 8, 6)$$

$$= \frac{1}{\sqrt{34}} (3, 4, 3)$$

max rate of $f(r)$ is $|\text{grad } f|$

$$|\text{grad } f| = \sqrt{36+64+36} = 2\sqrt{34}$$

- $2z = x^2 + y^2$ find $\underline{\mathbf{u}}$ at $(1, 3, 5)$ obtain eq of
normal and the tangent plane to the surface at
 $(1, 3, 5)$

$$f = x^2 + y^2 - 2z \quad \text{grad } f = (2x, 2y, -2)$$

$$\text{at } (1, 3, 5) \rightarrow = (2, 6, -2)$$

$$\underline{u} = \frac{1}{\sqrt{4+36+4}} (2, 6, -2) = \frac{1}{\sqrt{44}} (1, 3, -1)$$

eq of line in direct of normal is:

$$\frac{x-1}{1} = \frac{y-3}{3} = \frac{z-5}{-1}$$

eq of tangent plane

$$(1)(x-1) + 3(y-3) + (-1)(z-5) = 0$$

$$x + 3y - z = 5$$

Notes for test revision

28 October 2019 13:26

Question type	Solution
Plot the vector fields	<p>Follow until pattern is spotted</p> <ol style="list-style-type: none"> 1. Find values along the axes 2. Find along $y=\pm x$ 3. Find along $y=\pm 2x$ or $1/2 x$
Find $\nabla(\phi)$ Find $\text{grad}(\phi)$	$\nabla(\phi) = \mathbf{i} \frac{\partial \phi}{\partial x} + \mathbf{j} \frac{\partial \phi}{\partial y} + \mathbf{k} \frac{\partial \phi}{\partial z}$
Find $\text{div}(\phi)$	$\text{div}(\phi) = \nabla \cdot \phi = \frac{\partial \phi_1}{\partial x} + \frac{\partial \phi_2}{\partial y} + \frac{\partial \phi_3}{\partial z}$
Find $\text{curl}(\phi)$	$\text{curl}(\phi) = \nabla \times \phi = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \phi_1 & \phi_2 & \phi_3 \end{vmatrix}$
Find directional derivative	$\nabla(\phi(p_1, p_2, p_3))$ (e.g. find $\text{del}(\phi)$ and substitute the point given)
Max rate of change at point P	Find $ \nabla(\phi(p_1, p_2, p_3)) $
Direction of max rate of change at point P	<ol style="list-style-type: none"> 1. Find $\nabla(\phi)$ 2. Normalise the vector of $\nabla(\phi)$ at point P to unit vector
Unit normal to the surface $\phi(x, y, z)$ at point P	<ol style="list-style-type: none"> 1. Vector normal to surface = $\nabla(\phi)$ 2. Normalise for unit normal
Equation of the normal to the surface $\phi(x, y, z)$ at point P	<ol style="list-style-type: none"> 1. Find vector normal = $\nabla(\phi)$ call this v. 2. Equation of the normal line is found from P and step 1: 3. $\frac{x - P_1}{v_1} = \frac{y - P_2}{v_2} = \frac{z - P_3}{v_3}$
Equation of the tangent plane to the surface at point P	<ol style="list-style-type: none"> 1. Find vector normal 2. Equation of tangent plane: $3. (v_1)(x - P_1) + (v_2)(y - P_2) + (v_3)(z - P_3) = 0$
Change of coordinates	

Test notes

09 November 2019 12:09

- Divergence is always a scalar

$$\text{Dow} = \nabla \cdot \mathbf{f} = \frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z}$$

$$\text{curl} = \nabla \times \mathbf{f} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_1 & f_2 & f_3 \end{vmatrix}$$

- Conservative vector field: we can express the vector field in terms of the scalar field ϕ

$$\text{Path definition: } \int_a^b \underline{F}(\underline{r}(t)) \cdot \underline{r}'(t) dt = \int_A^B \underline{F}(\underline{r}(t)) \cdot d\underline{r}$$

$$\text{Closed path: } \oint_C \underline{F}(\underline{r}(t)) \cdot d\underline{r}$$

Parametrization: Boxes / cylinders / etc \Rightarrow Polar
 Straight lines / curves $\Rightarrow t \rightarrow$ find from
 $0 \leq t \leq 1$
 $x_i \rightarrow x_1$
 $y_i \rightarrow y_2$

- If vector field is conservative:

$$- E_x = \frac{\partial \phi}{\partial x} \quad E_y = \frac{\partial \phi}{\partial y} \quad E_z = \frac{\partial \phi}{\partial z}$$

$$- E_x dx + E_y dy + E_z dz = d\phi$$

$$- \int_C E_x dx + E_y dy + E_z dz = \int_C d\phi$$

$$- \int_C d\phi = \phi(B) - \phi(A)$$

- Double Integrals: $\int_a^b \int_{g_2(x)}^{g_1(x)} f(x, y) dy dx$ order doesn't matter w.r.t. limits set

$$- \text{Change of Variables: } \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

$$\Rightarrow \iint f(x, y) dx dy = \iint f(x(u, v), y(u, v)) J(x, y) du dv$$

\Rightarrow Polar - Cartesian Relationship:

$$\iint f(x, y) dx dy \rightarrow \iint f(r \cos \theta, r \sin \theta) r dr d\theta$$

- Green's Theorem: $\oint_C \underline{F} \cdot d\underline{r} = \iint_R (\nabla \times \underline{F}) \cdot \underline{k} dA$

Also written as

$$= \oint_C F_1 dx + F_2 dy = \iint_R \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} dx dy$$

unit vector $\underline{k} = 1$

• Surface Integrals & Fluxes :

$$\iint_E ds = \iint_D \sqrt{1 + \left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2} dx dy$$

'Projection of the surface on the x,y plane'

$$\iint_S f(x, y, z) \, dS = \iint_D f(\Sigma(u, v)) \left| \frac{\partial \Sigma}{\partial u} \times \frac{\partial \Sigma}{\partial v} \right| du \, dv$$

$$r(u,v) = x(u,v)i + y(u,v)j + z(u,v)k$$

and

$$\iint_S dS = \iint_D |\underline{r}_u \times \underline{r}_v| du dv$$

↑ Normal vector associated with
element of surface area

① is the domain which features the projection onto plane.
 (or x, y, \dots etc)

$$\text{Fluxes} : \Phi = \iint \mathbf{E} \cdot \hat{\mathbf{n}} dS =$$

$$f(x,y,z) = z - g(x,y)$$

$$\nabla f \text{ is normal to } f = c \text{ given } \hat{n} = \frac{\nabla f}{\|\nabla f\|}$$

to surface given by $f(x, y, z) = 0$, so we have normal vector to surface

- Parametrized surfaces:

$$\vec{n} = \frac{\underline{r}_u \times \underline{r}_v}{|\underline{r}_u \times \underline{r}_v|} \quad \text{and} \quad \iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{E} \cdot (\underline{r}_u \times \underline{r}_v) dA$$

YouTube notes

11 November 2019 18:55

Curve Parametric Equations

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

(ellipse)

$$\begin{aligned} x &= a \cos t \\ y &= b \sin t \\ 0 &\leq t \leq 2\pi \end{aligned}$$

$$x^2 + y^2 = r^2$$

(circle)

$$\begin{aligned} x &= r \cos t \\ y &= r \sin t \\ 0 &\leq t \leq 2\pi \end{aligned}$$

$$y = f(x)$$

$$x = t \quad y = f(t)$$

$$x = f(y)$$

$$y = t \quad x = f(t)$$

$$(x_0, y_0, z_0)$$

$$\rightarrow (x_1, y_1, z_1)$$

$$\begin{aligned} x &= (1-t_0)x_0 + tx_1, \\ y &= (1-t_0)y_0 + ty_1, \\ z &= (1-t_0)z_0 + tz_1, \\ 0 &\leq t \leq 1 \end{aligned}$$

Cylindrical Coordinates: (r, θ, z)

$$x = r \cos \theta \quad y = r \sin \theta \quad z = z$$

$$r^2 = x^2 + y^2 \quad z = z \quad \tan \theta = y/x$$

r is distance from origin to projection on $x-y$ plane

~~eg.~~ it doesn't travel up z plane (is flat)

Spherical Coordinates: (ρ, θ, ϕ)

$$(x = \rho \cos \theta, y = \rho \sin \theta, z = \rho \sin \phi)$$

$$\Rightarrow x = \rho \sin \phi \cos \theta \quad y = \rho \sin \phi \sin \theta \quad z = \rho \cos \phi$$

$$\Rightarrow \rho^2 = x^2 + y^2 + z^2 \quad \tan \theta = y/x \quad \cos \phi = z/\rho$$

Gradient Vector & Stuff

∇f is orthogonal to vector/surface f
 at point (x_0, y_0, z_0)

'normal'

- find tangent plane & normal line to $f(x, y, z) = a$

1. $\nabla F(x, y, z)$

2. $\nabla F(x_0, y_0, z_0) = (a, b, c)$

3. $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$ (tangent plane)

4. $\underline{r}(t) = (x_0, y_0, z_0) + t(a, b, c)$ (normal line)

Double Integrals

Polar coordinates : $dA = r dr d\theta$

Cylindrical coords : $dV = r dz dr d\theta$

Spherical coords : $dV = \rho^2 \sin\phi d\rho d\theta d\phi$

Change of Variables

Something

02 January 2020 13:08

1. Show satisfies Laplace:

$$u_{xx} + u_{yy} = 0$$

2. find conjugate v :

- step 1
- $u_x = v_y \quad u_y = -v_x$
- integrate v_y & v_x
- solve $A(x)$ & $B(y)$
- final v

3. find $f(z)$

- step 1 & 2
- $f(z) = u + iv$ (sub)

Planes

$$ax + by + cz = d$$

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

Equivalent

To find eq of a plane:

1. Find a point and a normal vector
- 1. (a, b, c)
from plane equation
will be normal
2. finding 2 vectors
from points / or given
and taking cross product

Partial Derivatives

$$f_x = \frac{\partial f}{\partial x} \quad f_{xy} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x}$$

Order is opposite ↑

Remember:

$$\boxed{f = f_{\text{first}}}$$

eg first letter is done
first, so $f_{xy} \rightarrow \frac{\partial}{\partial x} \rightarrow \frac{\partial}{\partial y}$

Total Differential

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy \quad \leftarrow \text{doesn't need to be diff wrt } dz, dw, \dots$$

$$z = e^{x^2+y^2} \tan(2x)$$

$$\frac{\partial}{\partial x} = 2xe^{x^2+y^2} \tan 2x + e^{x^2+y^2} 2 \tan 2x$$

$$\frac{\partial}{\partial y} = 2ye^{x^2+y^2} \tan 2x$$

$$dz = (2xe^{x^2+y^2} \tan 2x + 2e^{x^2+y^2} \tan 2x) dx + (2ye^{x^2+y^2} \tan 2x) dy$$

Chain Rule

$$\frac{dy}{dt} = \frac{dx}{dt} \frac{dy}{dx}$$

$$z = f(x, y) \quad x = g(t) \quad y = h(t)$$

$$\frac{dz}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

$$z = xe^{xy} \quad x = t^2 \quad y = t^{-1}$$

$$\frac{dx}{dt} = 2t$$

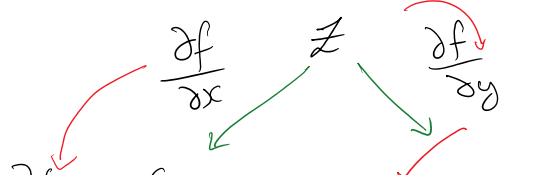
$$\frac{dy}{dt} = -t^{-2}$$

$$\frac{\partial f}{\partial x} = e^{xy} + yxe^{xy}$$

$$\frac{\partial f}{\partial y} = xe^{xy}$$

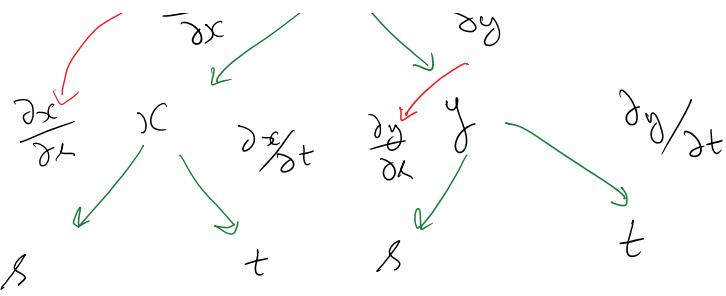
$$\frac{dz}{dt} = (e^{xy} + yxe^{xy})(2t) + (xe^{xy})(-t^{-2})$$

Free Diagram:

1. $\frac{\partial f}{\partial x}$ 2. $\frac{\partial f}{\partial y}$

Tree Diagram

$$\begin{aligned} z &= f(x, y) \\ x &= g(s, t) \\ y &= h(s, t) \end{aligned}$$



$$\text{for } \frac{dz}{dx} \rightarrow \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s}$$

$$\frac{dy}{dx} = -\frac{F_x}{F_y}$$

$$F_x = \frac{\partial}{\partial x}(f(x, y))$$

$$F_y = \frac{\partial}{\partial y}(f(x, y))$$

$$\text{find } \frac{dy}{dx} \text{ for } x \cos(3y) + x^3 y^5 - 3x + e^{xy} = 0$$

$$F_x = \cos(3y) + 3x^2 y^5 - 3 + y e^{xy}$$

$$F_y = -3x \sin(3y) + 5x^3 y^4 + x e^{xy}$$

$$\frac{dy}{dx} = -\frac{F_x}{F_y}$$

Lecture 1 - Vector Calculus: Gradient, Divergence and Curl

07 October 2019 19:00

The Nabla ∇ is the differential operator

Which can be written like this:

$$f(x, y, z) = 2x^2y^2 + yz - x \quad *$$

$$\nabla = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$$

$$\nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle \quad //$$

So the differential of function f is the derivative of the function with respect to each of its variables

$$* = \left\langle 4x^2y^2 - 1, 4x^2y + z, y \right\rangle$$

Which in this example would be this

Divergence

The divergence of vector F is equal to the vector F dot product with the differential operator, which is the same as the sum of the differential of the i expression with respect to x , j with respect to y , and k with respect to z .

$$\text{div } F = \nabla \cdot F = P_x + Q_y + R_z //$$

$$= \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \cdot \langle P, Q, R \rangle$$

So for this example

* if $F = \langle x^2 + y^2, y^2 + z^2, x^2 + z^2 \rangle$

$$\frac{\partial}{\partial x}(x^2 + y^2) = 2x \quad \frac{\partial}{\partial y}(y^2 + z^2) = 2y$$

$$\frac{\partial}{\partial z}(x^2 + z^2) = 2z$$

We compute each i, j, k component derivative,

$$\nabla \cdot F = 2x + 2y + 2z$$

Curl

The curl of a vector F is defined as the cross product of the vector F and the derivative function

$$\text{curl } F = \nabla \times F = //$$

We use a matrix to find the calculations needed, where P, Q and R are just the expressions in the i, j and k components of the vector

$$\begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \quad \boxed{\langle R_y - Q_z, P_z - R_x, Q_x - P_y \rangle}$$

Using the vector F from before and taking the derivatives from the step above gives the following

* $\text{curl } F = \langle 0 - 2z, 0 - 2x, 0 - 2y \rangle$
 $= \langle -2z, -2x, -2y \rangle$

And then simplify to complete the curl

following

And then simplify to complete the curl.

The directional derivative:

If f is a differentiable function of x and y , then it has a directional derivative in the direction of any unit vector, it is defined by this function (can be extended for more variables but using 2 in this example).

Example: find the directional derivative of $f(x, y)$ at $(2, 1)$ given by the angle theta

1. Find the unit vector

- a. If given a non-normal vector, normalise it by dividing by the length

2. Find the differential of $f(x, y, z)$

3. Substitute the differential and normal vector into the equation

4. Simplify and solve

$$= \langle -2z, -2x, -2y \rangle$$

$$\boxed{D_u f = \nabla f \cdot u}$$

$$f(x, y, z) = x^3 - xy^2 - z \text{ at } (1, 1, 0)$$

$$v = 2i - 3j + 6k$$

$$u = \frac{1}{\sqrt{2^2 + 3^2 + 6^2}} (2, -3, 6)$$

$$= \frac{1}{7} (2, -3, 6)$$

$$\nabla f(x, y, z) = (f_x, f_y, f_z)$$

$$= (3x^2 - y^2, -2xy, -1)$$

$$\nabla f(1, 1, 0) = (2, -2, 1)$$

$$D_u f(1, 1, 0) = \nabla f(1, 1, 0) \cdot u$$

$$= (2, -2, 1) \cdot \frac{1}{7} (2, -3, 6)$$

$$= \frac{1}{7} (4 + 6 - 6) = 4/7$$

$$\begin{aligned} & \left[\frac{dx}{dt} \right] i + \left[\frac{dy}{dt} \right] j + \left[\frac{dz}{dt} \right] k = T \\ \frac{\partial \phi}{\partial t} &= \frac{\partial \phi}{\partial x} \left[\frac{dx}{dt} \right] + \frac{\partial \phi}{\partial y} \left[\frac{dy}{dt} \right] + \frac{\partial \phi}{\partial z} \left[\frac{dz}{dt} \right] = 0 \end{aligned}$$

$$\boxed{\nabla \phi \cdot T = 0}$$

$$T^2 = 4(x^2 + y^2) \text{ at } (1, 0, 2)$$

$$\phi = 4(x^2 + y^2) - z^2 = 0$$

$$\begin{aligned} \nabla \phi(x, y, z) &= \frac{\partial \phi}{\partial x} i + \frac{\partial \phi}{\partial y} j + \frac{\partial \phi}{\partial z} k \\ &= 4(2x) i + 4(2y) j + (-2z) k \end{aligned}$$

$$= 8x\hat{i} + 8y\hat{j} - 2z\hat{k}$$

$$\nabla f(1, 0, 2) = 8\hat{i} - 4\hat{k}$$

$$\underline{u} = \frac{1}{\sqrt{8^2 + 4^2}} (8\hat{i} - 4\hat{k}) = \frac{1}{\sqrt{80}} (2\hat{i} - \hat{k})$$

(a) $D_{\vec{u}}f(2, 0)$ where $f(x, y) = xe^{xy} + y$ and \vec{u} is the unit vector in the direction of $\theta = \frac{2\pi}{3}$.

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$$\underline{u} = (\cos(\frac{2\pi}{3}), \sin(\frac{2\pi}{3})) = (-\frac{1}{2}, \frac{\sqrt{3}}{2})$$

$$\nabla = (\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}) = ((e^{xy} + xy e^{xy}), (x^2 e^{xy} + 1))$$

$$D_{\underline{u}} f(x, y) = (-\frac{1}{2})(e^{xy} + xy e^{xy}) + (\frac{\sqrt{3}}{2})(x^2 e^{xy} + 1)$$

$$D_{\underline{u}} f(2, 0) = (-\frac{1}{2})(1+0) + (\frac{\sqrt{3}}{2})(4+1)$$

$$= -\frac{1}{2} + \frac{5\sqrt{3}}{2}$$

$$= \frac{5\sqrt{3} - 1}{2}$$

(b) $D_{\vec{u}}f(x, y, z)$ where $f(x, y, z) = x^2z + y^3z^2 - xyz$ in the direction of $\vec{v} = \langle -1, 0, 3 \rangle$.

Screen clipping taken: 09/10/2019 22:05

$$\underline{u} = \frac{1}{\sqrt{(-1)^2 + 0^2 + 3^2}} (-1, 0, 3) = \left(-\frac{1}{\sqrt{10}}, 0, \frac{3}{\sqrt{10}}\right)$$

$$\nabla = (2xz - yz), (3y^2z^2 - xz), (x^2 - xy)$$

$$D_{\underline{u}} f(x, y, z) = \left(-\frac{1}{\sqrt{10}}\right)(2xz - yz) + 0 + \left(\frac{3}{\sqrt{10}}\right)(x^2 - xy + 2y^3z)$$

$$D_{\underline{u}} f(x, y, z) = \frac{1}{\sqrt{10}}(3x^2 - 3xy - 2xz + yz + 6y^3z)$$

 The max value of $D_{\underline{u}} f(x)$ is given by $\|\nabla f(x)\|$
and occurs in the direction given by $\nabla f(x)$ 

 Proof: $D_{\underline{u}} f = \nabla f \cdot \underline{u} = \|\nabla f\| \|\underline{u}\| \cos \theta = 1$ as \underline{u} is unit vector which has $\|\underline{u}\| = 1$

Proof: $D_u f = \nabla f \cdot u = \|\nabla f\| \|u\| \cos \theta$ which has magnitude 1
 $= \|\nabla f\| \cos \theta$

$\theta = 0 \rightarrow \cos \theta = 1 \quad \rightarrow \theta \text{ is the angle between } \nabla \text{ and } u$

$\max [\|\nabla f\| \cos \theta] = \|\nabla f\|$

At this point, the angle between ∇ and $\underline{u} = 0$
 i.e. the vector \underline{u} is pointing in the same
direction as the gradient ∇