

# MA5233 Computational Mathematics

## Lecture 4: QR Factorisation

Simon Etter



2019/2020

# QR Factorisation

## QR factorisation

- ▶ An alternative way solve linear systems.
- ▶ A basic building block in many more advanced algorithms.

## Outline

- ▶ QR factorisation: definition and applications.
- ▶ Algorithms:
  - ▶ Gram-Schmidt orthogonalisation
  - ▶ Householder reflection
  - ▶ Givens rotation
- ▶ `qr()` in Julia.
- ▶ Complexity and stability.

# QR Factorisation

## QR factorisation

Any  $A \in \mathbb{K}^{m \times n}$  can be written as  $A = QR$ , where

- ▶  $Q \in \mathbb{K}^{m \times m}$  is orthogonal ( $Q^H Q = I$ ), and
- ▶  $R \in \mathbb{K}^{m \times n}$  is upper triangular ( $R(i, j) = 0$  for  $i > j$ ).

$Q$  and

## Applications

- ▶ Solve linear systems (assuming  $m = n$ ):

$$QRx = b \iff x = R^{-1}Q^H b.$$

- ▶ Determine orthogonal basis (see next slide).

# QR Factorisation

## Key property of QR factorisation

$Q$  factor provides an orthogonal basis for range of  $A$ .

More precisely:

$$A[:, 1] = Q[:, 1] R[1, 1],$$

$$A[:, 2] = Q[:, 1] R[1, 2] + Q[:, 2] R[2, 2],$$

$$A[:, 3] = Q[:, 1] R[1, 3] + Q[:, 2] R[2, 3] + Q[:, 3] R[3, 3]$$

...

Conclusion:  $\text{span } A[:, 1 : k] = \text{span } Q[:, 1 : k]$ .

# QR Factorisation

## Illustration of QR decomposition

Case  $m > n$ :

$$\left( \begin{array}{c} \text{gray rectangle} \end{array} \right) = \left( \begin{array}{c|c} \text{gray square} & \text{red rectangle} \end{array} \right) \left( \begin{array}{c} \text{gray triangle} \\ \text{white rectangle} \end{array} \right)$$

Case  $m < n$ :

$$\left( \begin{array}{c} \text{gray rectangle} \end{array} \right) = \left( \begin{array}{c} \text{gray square} \end{array} \right) \left( \begin{array}{c} \text{gray triangle} \\ \text{gray rectangle} \end{array} \right)$$

Red part of  $Q$  factor is redundant since it gets multiplied by zeros in  $R$ .  
QR factorisation without red part is known as “thin” QR.

# QR Factorisation

## **Algorithms for computing the QR factorisation**

- ▶ Gram-Schmidt orthogonalisation
- ▶ Householder reflections
- ▶ Givens rotations

All of these have strengths and weaknesses.  
We next go through each of them.

# QR Factorisation

## Gram-Schmidt theorem

Let  $q_1, \dots, q_k \in \mathbb{K}^n$  be orthonormal and  $a_{k+1} \in \mathbb{K}^n$  be linearly independent of the  $q_k$ . Then,

$$\tilde{q}_{k+1} := a_{k+1} - \sum_{\ell=1}^k q_{\ell}^H a_{k+1} q_{\ell}$$

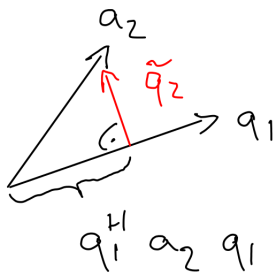
is orthogonal to  $q_1, \dots, q_k$ .

*Proof.*

$$q_{\ell}^H \tilde{q}_{k+1} = q_{\ell}^H a_{k+1} - q_{\ell}^H q_{\ell} q_{\ell}^H a_{k+1} = 0.$$

# QR Factorisation

## Gram-Schmidt theorem, pictorial version





# QR Factorisation

## QR factorisation via Gram-Schmidt theorem

Rewrite Gram-Schmidt formula

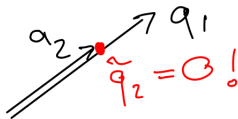
$$\tilde{q}_{k+1} = a_{k+1} - \sum_{\ell=1}^k q_{\ell}^H a_{k+1} q_{\ell}$$

in the form

$$a_{k+1} = \underbrace{\|q_{k+1}\|_2}_{R[k+1,k+1]} q_{k+1} + \sum_{\ell=1}^k \underbrace{q_{\ell}^H a_{k+1}}_{R[\ell,k+1]} q_{\ell}.$$

# QR Factorisation

**Breaking the Gram-Schmidt algorithm**



# QR Factorisation

## Classical Gram-Schmidt

$$\tilde{q}_{k+1}^{(0)} := a_{k+1}, \quad \tilde{q}_{k+1}^{(\ell+1)} := \tilde{q}_{k+1}^{(\ell)} - q_{\ell}^H a_{k+1} q_{\ell}$$

## Modified Gram-Schmidt

$$\tilde{q}_{k+1}^{(0)} := a_{k+1}, \quad \tilde{q}_{k+1}^{(\ell+1)} := \tilde{q}_{k+1}^{(\ell)} - q_{\ell}^H \tilde{q}_{k+1}^{(\ell)} q_{\ell}$$

Modified Gram-Schmidt is more numerically stable.

# QR Factorisation

## Example

Classical Gram-Schmidt:

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & \varepsilon & 0 \\ 0 & 0 & \varepsilon \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & \varepsilon_{\text{mach}} \varepsilon^{-1} & \varepsilon_{\text{mach}} \varepsilon^{-1} \\ 1 & \varepsilon_{\text{mach}} \varepsilon^{-1} & \varepsilon_{\text{mach}} \varepsilon^{-1} \\ 0 & 1 & \varepsilon_{\text{mach}} \varepsilon^{-2} \\ 0 & 0 & 1 \end{pmatrix}$$

Modified Gram-Schmidt:

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & \varepsilon & 0 \\ 0 & 0 & \varepsilon \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & \varepsilon_{\text{mach}} \varepsilon^{-1} & \varepsilon_{\text{mach}} \varepsilon^{-1} \\ 1 & \varepsilon_{\text{mach}} \varepsilon^{-1} & \varepsilon_{\text{mach}} \varepsilon^{-1} \\ 0 & 1 & \varepsilon_{\text{mach}}^2 \varepsilon^{-2} \\ 0 & 0 & 1 \end{pmatrix}$$

# QR Factorisation

## Householder reflection theorem

Assume  $u \in \mathbb{K}^n$  such that  $\|u\| = 1$ . Then,

$$Q := I - 2vv^H$$

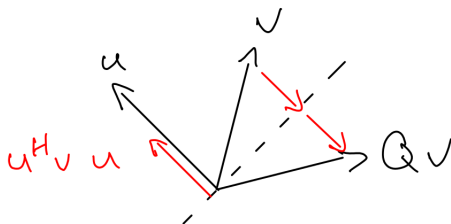
is an orthogonal matrix, and  $Q^2 = I$ .

*Proof.*

$$Q^H Q = Q^2 = (I - 2vv^H)(I - 2vv^H) = I - 4vv^H + 4v(v^H v)v^H = I.$$

# QR Factorisation

**Householder reflection theorem, pictorial version**



# QR Factorisation

## QR factorisation via Householder reflections

Idea: choose  $u$  such that  $Qa_1 = \pm\alpha e_1$ . Then,

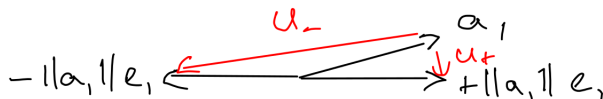
$$Q \begin{pmatrix} x & x & x \\ x & x & x \\ x & x & x \end{pmatrix} = \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & x & x \end{pmatrix}.$$

How to find  $Q = I - 2uu^H$ ?

# QR Factorisation

## Determining Householder $u$

- ▶ Reflections preserve length; hence  $\alpha = \|a_1\|$ .
- ▶  $a_1 - u u^H a_1 = \pm \|a_1\| e_1$  implies  $u \propto a_1 \mp \|a_1\| e_1$ .
- ▶ Choose  $Qa_1 = -\text{sign}(a_{11}) \|a_1\| e_1$  to avoid cancellation in  $u$ .  
 $a_{11}$  denotes first component of  $a_1$ .





# QR Factorisation

## Givens rotation

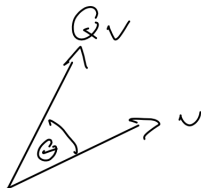
$$Q := \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \quad \text{represents a rotation by } \theta.$$

## Example

$$\begin{bmatrix} \cos 90^\circ & \sin 90^\circ \\ -\sin 90^\circ & \cos 90^\circ \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 0 \\ -a_1 \end{bmatrix}$$

# QR Factorisation

## Serious example



## QR factorisation via Givens rotation

Similar idea as in Householder case:

$$\begin{pmatrix} x & x & x \\ x & x & x \\ x & x & x \end{pmatrix} \rightarrow \begin{pmatrix} x & x & x \\ 0 & x & x \\ x & x & x \end{pmatrix} \rightarrow \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & x & x \end{pmatrix} \rightarrow \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & 0 & x \end{pmatrix}$$

# QR Factorisation

## QR factorisation in Julia

`F = qr(A, pivot=Val(false))` computes “factorisation object”.

- ▶ Access factors through `F.Q`, `F.R`, `F.p` (vector) and `F.P` (matrix).
- ▶ `F.Q * F.U == A[:,F.p] == A * F.P`.
- ▶ `x = F\b` computes solution.

## Computational cost of QR factorisation

$\mathcal{O}(mn \min\{m, n\})$  floating-point operations.

## Stability of Householder QR factorisation

$Q, R$  computed by Householder QR satisfy

$$QR = A + \delta A \quad \text{where} \quad \frac{\|\delta A\|}{\|A\|} = \mathcal{O}(\varepsilon_{\text{mach}}).$$

Hence, Householder QR factorisation is backwards stable.

# QR Factorisation

## References and further reading

- ▶ G. H. Golub and C. F. Van Loan. *Matrix Computations*. Johns Hopkins University Press (1996),
- ▶ L. N. Trefethen and D. Bau. *Numerical Linear Algebra*. Society for Industrial and Applied Mathematics (1997),
- ▶ J. W. Demmel. *Applied Numerical Linear Algebra*. Society for Industrial and Applied Mathematics (1997),  
doi:10.1137/1.9781611971446
- ▶ N. J. Higham. *Accuracy and Stability of Numerical Algorithms*. Society for Industrial and Applied Mathematics (2002),  
doi:10.1137/1.9780898718027