MA5233 Computational Mathematics

Lecture 6: Sparse Matrices

Simon Etter



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```
Example
julia > n = 100_000
       A = Tridiagonal(
           fill(-1.0,n-1),
           fill(2.0,n),
           fill(-1.0,n-1)
       b = rand(100_000)
       @time A \ b;
  0.011402 seconds (...)
julia > n = 10_000
       A = rand(n,n)
       b = rand(n)
       @time A \ b;
  8.071135 seconds (...)
```

First matrix is 10x bigger, yet $A\b$ is roughly 1000x faster. How is this possible?

Outline

- ► LU factorisation of triangular matrices
- ▶ Poisson equation in two dimensions
- ► General sparse matrix formats
- ► Sparse matrices in Julia
- ► Eigenvalues and -vectors of two-dimensional Laplacian.

Theorem

LU factorisation of tridiagonal matrix is tridiagonal.

Proof sketch.

$$\begin{pmatrix} x & x \\ x & x & x \\ & x & x \end{pmatrix} = \begin{pmatrix} 1 \\ x & 1 \\ & & 1 \end{pmatrix} \begin{pmatrix} x & x \\ & x & x \\ & x & x \end{pmatrix}$$
$$= \begin{pmatrix} 1 \\ x & 1 \\ & x & 1 \end{pmatrix} \begin{pmatrix} x & x \\ & x & x \\ & & x \end{pmatrix}$$

Corollary

LU factorisation of tridiagonal matrix takes $\mathcal{O}(n)$ FLOP instead of $\mathcal{O}(n^3)$.

Corollary of corollary

One-dimensional Poisson equation can be solved very efficiently!

Discretising the two-dimensional Poisson equation

Functions:

▶ Introduce mesh $\Omega_n \times \Omega_n$ where

$$\Omega_n := \{ x_k := \frac{k}{n+1} \mid k = 0, \dots, n+1 \}.$$

- ▶ Replace function f(x, y), with vector of point-values $f(x_{k_1}, x_{k_2})$.
- ▶ Use *lexicographical ordering* to arrange these point values as vector:

$$f_{k_1+n(k_2-1)}:=f(x_{k_1},x_{k_2}).$$

Example for lexicographical ordering

| 1 | 5 | 9 | 13 |
|---|---|----|----|
| 2 | 6 | 10 | 14 |
| 3 | 7 | 11 | 15 |
| 4 | 8 | 12 | 16 |

Discretising the two-dimensional Poisson equation

Derivatives:

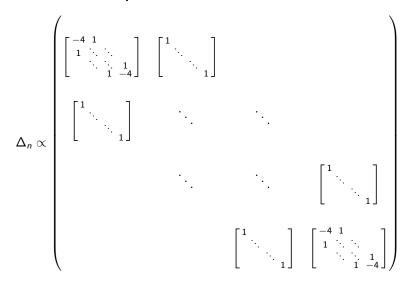
$$\frac{\partial^2 u}{\partial x^2} \longrightarrow (n+1)^2 \left(u_{i+1} - 2u_i + u_{i-1} \right)$$

$$\frac{\partial^2 u}{\partial y^2} \longrightarrow (n+1)^2 \left(u_{i+n} - 2u_i + u_{i-n} \right)$$

Laplacian now becomes

$$\begin{split} \Delta_n \big(i_1 + n \, (i_2 - 1), j_1 + n \, (j_2 - 1) \big) &= \dots \\ &= (n + 1)^2 \left\{ \begin{aligned} -4 & \text{if } |i_1 - j_1| = 0 \text{ and } |i_2 - j_2| = 0, \\ 1 & \text{if } |i_1 - j_1| = 0 \text{ and } |i_2 - j_2| = 1, \\ 1 & \text{if } |i_1 - j_1| = 1 \text{ and } |i_2 - j_2| = 0, \\ 0 & \text{otherwise} \end{aligned} \right. \end{split}$$

Two-dimensional Laplacian matrix



Observation

Two-dimensional Laplacian is no longer tridiagonal. This will complicate both the data structures and algorithms.

Common data structures for sparse matrices

- Coordinate list
- ► Compressed sparse column (CSC)

Coordinate list format

Three vectors i, j, v of length nnz (number of nonzeros) such that

```
A = zeros(n,n)
for k = 1:nnz
    A[i[k],j[k]] = v[k]
end
```

Example

Properties

- Convenient to assemble sparse matrix.
- ► A bit wasteful since *j* contains many repeated entries.

Compressed sparse column (CSC) format

```
Three vectors p,i,v with
    length(p) == n+1, length(i) == length(v) == nnz
such that

A = zeros(n,n)
for j = 1:n
    for k = p[j]:p[j+1]-1
        A[i[k],j] = v[k]
    end
end
```

CSC is the format most commonly used in practice.

Example

$$A = \begin{pmatrix} 0.2 & & & \\ 0.6 & & 0.7 \\ & 0.6 & 1.0 \end{pmatrix} \longrightarrow \begin{array}{c} p = (& 1 & 3 & 4 & 6 &)^{T} \\ i = (& 1 & 2 & 3 & 2 & 3 &)^{T} \\ v = (& 0.2 & 0.6 & 0.6 & 0.7 & 1.0 &)^{T} \end{array}$$

Sparse matrices in Julia

- Sparse matrix tools are provided by the SparseArrays package.
 Type using SparseArrays before calling any of the functions listed below.
- Assemble a sparse matrix: sparse(i,j,v)
 See section on coordinate lists above for meaning of i,j,v.
- Extract i,j,v from sparse matrix A: i,j,v = findnz(A)
- Sparse identity matrix: sparse(I, (n,n))
- ► Sparse matrix of zeros: spzeros(n,n)
- ► Convert to full matrix: Matrix(A)

Assembling the 2d Laplacian matrix, the tedious way

See laplacian_2d_tedious() in 6_sparse_matrices.jl.

Assembling the 2d Laplacian matrix, the clever way

2d Laplacian operator is given by $\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$.

Let us imitate this in the discrete case: $\Delta_n = \Delta_n^{(2,1)} + \Delta_n^{(2,2)}$ where

$$\begin{split} \Delta_n^{(2,1)}\big(i_1+n(i_2-1),j_1+n(j_2-1)\big) &= \dots \\ &= (n+1)^2 \begin{cases} -2 & \text{if } |i_1-j_1|=0 \text{ and } |i_2-j_2|=0, \\ 1 & \text{if } |i_1-j_1|=1 \text{ and } |i_2-j_2|=0, \\ 0 & \text{otherwise,} \end{cases} \end{split}$$

$$\Delta_n^{(2,2)}ig(i_1+n\,(i_2-1),j_1+n\,(j_2-1)ig)=\dots \ =(n+1)^2egin{cases} -2 & ext{if }|i_1-j_1|=0 ext{ and }|i_2-j_2|=0, \ 1 & ext{if }|i_1-j_1|=0 ext{ and }|i_2-j_2|=1, \ 0 & ext{otherwise.} \end{cases}$$

$$\Delta_{n}^{(2,2)} \propto \begin{bmatrix} \begin{bmatrix} 1 & & & & & & \\ & \ddots & & & & & \\ & & 1 \end{bmatrix} & & \ddots & & \ddots & \\ & & & \ddots & & \ddots & & \\ & & & \ddots & & \ddots & & \begin{bmatrix} 1 & & \\ & \ddots & & & \\ & & & 1 \end{bmatrix} & & \\ & & & \begin{bmatrix} 1 & & & \\ & & 1 \end{bmatrix} & \begin{bmatrix} -2 & & & \\ & \ddots & & \\ & & & -2 \end{bmatrix} \end{pmatrix}$$

Kronecker product of matrices

$$A \otimes B := egin{pmatrix} A[1,1] B & \cdots & A[1,n] B \\ \vdots & \ddots & \vdots \\ A[n,1] B & \cdots & A[n,n] B \end{pmatrix}$$

2d Laplacian $\Delta_n^{(2)}$ can be expressed in terms of 1d $\Delta_n^{(1)}$ as

$$\Delta_n^{(2)} = \Delta_n^{(1)} \otimes I + I \otimes \Delta_n^{(1)}.$$

See laplacian_2d_clever() in 6_sparse_matrices.jl for how to do this in Julia.

General rule

If A,B are "one-dimensional" operators, then $A\otimes B$ is the "two-dimensional" operator which applies A in one dimension and B in the other dimension.

Be careful about which operator applies to which dimension.

Kronecker product of matrices

$$a \otimes b := \begin{pmatrix} a[1] \ b \\ \vdots \\ a[n] \ b \end{pmatrix}$$

Theorem

$$(A \otimes B) (a \otimes b) = (Aa) \otimes (Bb)$$

Proof. Straightforward but tedious computations.

Eigenvalues and -vectors of 2d Laplacian

Assume λ_{ℓ} , u_{ℓ} are eigenpairs of $\Delta_n^{(1)}$.

Then, eigenpairs of $\Delta_n^{(2)}$ are given by

$$\lambda_{\ell_1,\ell_2} := \lambda_{\ell_1} + \lambda_{\ell_2}, \qquad u_{\ell_1,\ell_2} := u_{\ell_1} \otimes u_{\ell_2}.$$

Proof.

$$\begin{split} \Delta_n^{(2)} u_{\ell_1,\ell_2} &= \left(\Delta_n^{(1)} \otimes I + I \otimes \Delta_n^{(1)}\right) \left(u_{\ell_1} \otimes u_{\ell_2}\right) \\ &= \left(\Delta_n^{(1)} u_{\ell_1}\right) \otimes u_{\ell_2} + u_{\ell_1} \otimes \left(\Delta_n^{(1)} u_{\ell_2}\right) \\ &= \lambda_{\ell_1} u_{\ell_1} \otimes u_{\ell_2} + \lambda_{\ell_2} u_{\ell_1} \otimes u_{\ell_2} \\ &= \left(\lambda_{\ell_1} + \lambda_{\ell_2}\right) u_{\ell_1} \otimes u_{\ell_2} \\ &= \left(\lambda_{\ell_1} + \lambda_{\ell_2}\right) u_{\ell_1,\ell_2}. \end{split}$$