# MA5233 Computational Mathematics

Lecture 7: Sparse LU Factorisation

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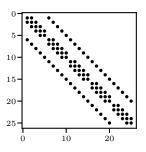
#### Recap from previous lectures

Poission equation in 1D:

- Tridiagonal system of equations.
- ▶ LU factorisation can be performed in  $\mathcal{O}(n)$  operations and memory.

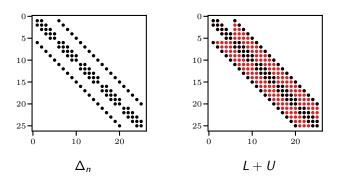
Poission equation in 2D:

- More complicated sparsity pattern.
- Can LU factorisation still be done efficiently?



#### Bad news

- ▶ LU factors have more nonzero entries than original matrix.
- ightharpoonup These extra entries in L, U are called *fill-in*.
- Fill-in significantly increases the memory consumption and workload of sparse LU factorisation.



#### Aim for this lecture

- Understand how fill-in arises.
- Find ways to reduce fill-in as much as possible.

### **Terminology**

Let A = sparse(i,j,v) = LU be a sparse matrix with coordinate-list vectors i,j,v. We introduce the following terms.

- $\triangleright$  Structure of A: the vectors i, j but not v.
- ► Structurally nonzero fill-in entries: entries L[i,j], U[i,j] which are nonzero for some v.

In the following, all statements of the form  $A[i,j] \neq 0$  are meant in the structural sense.

### Example

Consider

- $ightharpoonup A_1$  and  $A_2$  have the same structure.
- ▶  $L_2[4,3] = 0$  is structurally nonzero since  $L_1[4,3] \neq 0$ .

#### Graph of a sparse matrix $A \in \mathbb{K}^{n \times n}$

Graph G(A) := (V(A), E(A)) defined by

$$V(A) := \{1, \ldots, n\}, \qquad E(A) := \{j \to i \mid A[i, j] \neq 0\}.$$

Note transpose in E(A): entry A[i,j] corresponds to edge  $j \rightarrow i$ .

### Path in G = (V, E)

Ordered sequence  $k_0, \ldots, k_p \in V$  such that  $k_{q-1} \to k_q \in E$  for all q. Number of edges p is called the length of the path.

#### **Example**

$$A = \begin{pmatrix} 1 & \bullet & & \\ & 2 & & \bullet \\ \bullet & & 3 & \\ & & \bullet & 4 \end{pmatrix} \qquad G(A) = \underbrace{1}_{R} \underbrace{2}_{A} \underbrace{3}_{A} \underbrace{4}_{A}$$

 $2 \rightarrow 1 \rightarrow 3$  is a path of length 2.

#### Path theorem for matrix powers

$$A^p[i,j] \neq 0 \iff \exists \text{ path } j \rightarrow i \text{ of length } p.$$

Proof.

$$A^{p}[i,j] = \sum_{k_{p-1}} \dots \sum_{k_1} A[i,k_{p-1}] \dots A[k_a,k_{a-1}] \dots A[k_1,j].$$

Each term is nonzero iff  $j \to k_1 \to \ldots \to k_{p-1} \to i$  is a path in G(A).

#### **Example (continued)**

$$A^2 = \begin{pmatrix} 1 & \bullet & \bullet \\ & 2 & \bullet & \bullet \\ \bullet & \bullet & 3 \\ \bullet & \bullet & 4 \end{pmatrix} \qquad G(A) = \underbrace{1 \quad 2 \quad 3}_{\bullet} \underbrace{3}_{\bullet} \underbrace{4}_{\bullet}$$

 $A^2[4,1] \neq 0$  because  $1 \rightarrow 3 \rightarrow 4$  is a path of length 2 in G(A).  $A^2[2,1] = 0$  because  $1 \rightarrow 3 \rightarrow 4 \rightarrow 2$  is a path of length 3 in G(A).

#### Path theorem for matrix inverses

$$A^{-1}[i,j] \neq 0 \iff \exists \text{ path } j \rightarrow i.$$

Proof.

- ▶  $A^{-1} = p(A)$  for polynomial p(x) interpolating  $\frac{1}{x}$  on eigenvalues of A.
- ▶ Hence entry (i,j) of  $A^{-1} = \sum_{p=0}^{n-1} c_p A^p$  is nonzero if there is a path  $j \to i$  of arbitrary length.

#### **Example (continued)**

$$A^{-1} = \begin{pmatrix} 1 & \bullet & \bullet & \bullet \\ \bullet & 2 & \bullet & \bullet \\ \bullet & \bullet & 3 & \bullet \\ \bullet & \bullet & \bullet & 4 \end{pmatrix} \qquad G(A) = \underbrace{1}_{A} \underbrace{2}_{A} \underbrace{3}_{A} \underbrace{4}_{A}$$

 $A^{-1}[2,1] \neq 0$  because  $1 \rightarrow 3 \rightarrow 4 \rightarrow 2$  is a path in G(A).

#### Corollaries of path theorem

- ▶ If G(A) is connected (there exists a path between any pair of vertices), then  $A^{-1}$  is dense.
- ▶ If G(A) is disconnected, i.e.  $A = \begin{pmatrix} A_{11} & 0 \\ 0 & A_{22} \end{pmatrix}$ , then  $A^{-1} = \begin{pmatrix} A_{11}^{-1} & 0 \\ 0 & A_{22}^{-1} \end{pmatrix}$ .
- ▶ Inverse of upper/lower triangular matrix is upper/lower triangular.

#### Fill path

Path  $i \to k_1 \to \ldots \to k_p \to j$  in G(A) such that  $k_1, \ldots, k_p < \min\{i, j\}$ .

#### Fill Path Theorem

$$(L+U)[i,j] \neq 0 \quad \iff \quad \exists \text{ fill path } j \to i.$$

### **Example (continued)**

$$L+U=\begin{pmatrix}1&\bullet&&\\&2&&\bullet\\&\bullet&3&\\&\bullet&4\end{pmatrix}\qquad G(A)=\underbrace{1}_{2}\underbrace{3}_{4}\underbrace{3}_{4}$$

$$L[3,2] \neq 0$$
 because  $2 \rightarrow 1 \rightarrow 3$  is a fill path in  $G(A)$ .  $L[4,1] = 0$  because  $1 \rightarrow 3 \rightarrow 4$  is not a fill path in  $G(A)$ .

#### Lemma

Let  $i, j \in \{1, ..., n\}$  and set  $\ell := \{1, ..., \min\{i, j\} - 1\}$ . Then,

$$U[i,j] = A[i,j] - A[i,\ell] A[\ell,\ell]^{-1} A[\ell,j]$$
 for  $i \le j$ ,  

$$U[j,j] L[i,j] = A[i,j] - A[i,\ell] A[\ell,\ell]^{-1} A[\ell,j]$$
 for  $i \ge j$ .

*Proof.* Block LU factorisation with  $\bar{r} := \{\min\{i, j\}, \dots, n\}$ :

$$\begin{pmatrix} A[\ell,\ell] \ A[\ell,\bar{r}] \\ A[\bar{r},\ell] \ A[\bar{r},\bar{r}] \end{pmatrix} = \begin{pmatrix} I \\ A[\bar{r},\ell] \ A[\ell,\ell]^{-1} \ I \end{pmatrix} \begin{pmatrix} A[\ell,\ell] \\ A[\bar{r},\bar{r}] - A[\bar{r},\ell] \ A[\ell,\ell]^{-1} \ A[\ell,\bar{r}] \end{pmatrix}.$$

Let 
$$L_1 U_1 = A[\ell, \ell], L_2 U_2 = A[\bar{r}, \bar{r}] - A[\bar{r}, \ell] A[\ell, \ell]^{-1} A[\ell, \bar{r}].$$

Full factorisation is then given by

$$\begin{pmatrix} A[\ell,\ell] \ A[\ell,\bar{r}] \\ A[\bar{r},\ell] \ A[\bar{r},\bar{r}] \end{pmatrix} = \begin{pmatrix} L_1 \\ A[\bar{r},\ell] \ A[\ell,\ell]^{-1} L_1 \ L_2 \end{pmatrix} \begin{pmatrix} U_1 \ L_1^{-1} \ A[\ell,\bar{r}] \\ U_2 \end{pmatrix}.$$

Claim follows by noting that  $L[i,j] = L_2[i,j]$  and  $U[i,j] = U_2[i,j]$  have the given form.

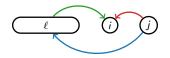
#### Fill Path Theorem (repeated from previous slide)

$$(L+U)[i,j] \neq 0 \iff \exists \text{ fill path } j \rightarrow i.$$

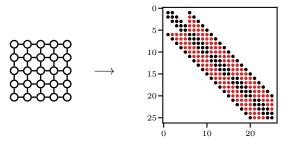
*Proof.* Follows immediately from

$$U[i,j] = A[i,j] - A[i,\ell] A[\ell,\ell]^{-1} A[\ell,j]$$
 for  $i \le j$ ,  

$$U[j,j] L[i,j] = A[i,j] - A[i,\ell] A[\ell,\ell]^{-1} A[\ell,j]$$
 for  $i \ge j$ .



**Corollary for 2d Laplacian**  $(n \times n \text{ grid}, N := n^2 \text{ degrees of freedom})$ 



#### Memory consumption:

- $\triangleright$   $\mathcal{O}(n)$  fill-in per column.
- ▶ Hence,  $\mathcal{O}(n^3) = \mathcal{O}(N^{3/2})$  fill-in overall.

### Floating-point operations (FLOPs)

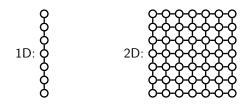
- $\triangleright$   $\mathcal{O}(n)$  subdiagonal entries to eliminate per column.
- ▶ Each elimination takes  $\mathcal{O}(n)$  FLOPs.
- ▶ Hence,  $\mathcal{O}(n^4) = \mathcal{O}(N^2)$  FLOPs overall.

#### **Observations**

Amount of fill-in depends on

- physical dimension of problem, and
- ordering of rows and columns.

Can we permute the matrix to reduce fill-in?

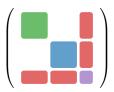


#### **Algorithm 1** Nested dissection ordering

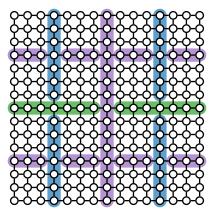
- 1: Partition the vertices into three sets  $V_1$ ,  $V_2$ ,  $V_{\text{sep}}$  such that every path from  $V_1$  to  $V_2$  visits at least one vertex in  $V_{\text{sep}}$ .
- 2: Arrange the vertices in the order  $V_1, V_2, V_{\text{sep}}$ , where  $V_1$  and  $V_2$  are ordered recursively according to the nested dissection algorithm.

#### Consequences:

- ▶ No fill-in between  $V_1$  and  $V_2$ !
- ▶ Some fill-in between  $V_1 / V_2$  and  $V_{\text{sep}}$  (red blocks below).



### Separators for 2d mesh



# Complexity of LU factorisation with nested dissection ordering Observations:

- ▶ Diagonal block associated with  $V_{\text{sep}}$  is dense.
- ▶ Factorising this block costs  $\mathcal{O}(|V_{\text{sep}}|^3)$ .

The following can be shown for 2D and 3D meshes (see references):

- The overall runtime of LU factorisation with nested dissection ordering is dominated by factorisation of largest separator.
- ▶ Nested dissection is asymptotically optimal: no other ordering can outperform nested dissection in the big-O sense.

### Complexity of LU factorisation

	Runtime	Memory
d=1	$\mathcal{O}(N)$	$\mathcal{O}(N)$
d = 2	$\mathcal{O}(N^{3/2})$	$\mathcal{O}(N \log(N))$
d = 3	$\mathcal{O}(N^2)$	$\mathcal{O}(N^{4/3})$

Runtime entries follow immediately from the observation

$$\begin{split} d &= 1 &\implies |V_{\mathsf{sep}}| = \mathcal{O}\big(1\big), \\ d &= 2 &\implies |V_{\mathsf{sep}}| = \mathcal{O}\big(n\big) = \mathcal{O}\big(N^{1/2}\big), \\ d &= 3 &\implies |V_{\mathsf{sep}}| = \mathcal{O}\big(n^2\big) = \mathcal{O}\big(N^{2/3}\big). \end{split}$$

### Approximate Minimum Degree (AMD) ordering

- Finding good separators can be challenging in practice.
- ▶ AMD is another commonly used ordering which is often easier to compute but equally effective.

#### Sparse algorithms in Julia

Most functions (e.g. +,\*,\,lu()) are overloaded to automatically exploit sparsity.

#### Fill-in and pivoting

Recall: LU factorisation of general invertible matrix A requires

pivoting to ensure numerical stability.

Bad news: pivoting may undo the effect of fill-in-reducing orderings. Good news: some classes of matrices provably do not need pivoting.

#### Matrices which do not require pivoting

- Column-wise diagonally dominant matrices:  $|A[j,j]| \ge \sum_{i \ne j} |A[i,j]|$ . Column-wise largest pivot will always be on diagonal.
- Symmetric positive definite (SPD) matrices:  $A = A^T$  and  $v^T A v > 0$ . Stability of Gaussian elimination is guaranteed.

### References and further reading

- ► T. A. Davis. Direct Methods for Sparse Linear Systems. Society for Industrial and Applied Mathematics (2006), doi:10.1137/1.9780898718881
- ► I. S. Duff, A. M. Erisman, and J. K. Reid. *Direct Methods for Sparse Matrices*. Oxford University Press (2017), doi:10.1093/acprof:oso/9780198508380.001.0001
- ► Fill-in on 2D and 3D meshes:

https://sites.cs.ucsb.edu/~gilbert/cs219/cs219Spr2013/Notes/fill.pdf