操作系统研讨课

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Lecture 2 A Simple Kernel

2018.09.26



Schedule

- Project 1 due
- Project 2 assignment



Project 1 Due

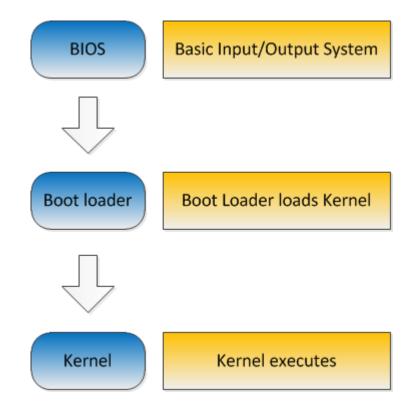
- P1 due
 - We test Tasks 2 and 3 for P1 due
 - Please compile your code, running the code on your board, and show the results to TA
 - Answer any questions we may ask

Project 1 Due

- P1 submission
 - Submit a compressed package named as "StudentNo.-YourName-P1"
 - Please includes
 - Source code
 - README to simply describe your code, e.g. which file is your work or how to run your code
 - Design document covering the questions in the design document template
 - Do not forget to submit before 23:55 TONIGHT



Booting procedure





- Requirements
 - Write a simple kernel (non-preemptive)
 - Start a set of user processes and kernel threads
 - Perform context switches between processes and threads
 - Provide non-preemptive kernel support with context switch
 - Support basic mutex to allow BLOCK state of processes/threads



- Requirements (Cont.)
 - Write a simple kernel (preemptive)
 - Provide preemptive kernel support with clock interrupt handler and priority based scheduling
 - Support system calls



- A set of multiple tasks
 - Program codes under the *test* directory in start-code
 - Please refer to test.c for different groups of tasks
 - Fixed number of tasks for each test group
 - Allocate per-task state statically in main.c
 - STRONGLY suggest to first read the codes of different tasks to understand what they do



- Process Control Block (PCB/TCB)
 - A data structure in OS kernel containing the information to manage a particular process/thread
 - Normally, kept in an area of memory protected from normal user access



- Process Control Block (PCB/TCB)
 - Process status
 - Status of a process when it is suspended
 - Contents of registers, stack pointers etc.
 - Process scheduling info
 - e.g. priority



- Start a task(process/thread)
 - Task type
 - User Process
 - Use faked SYSCALL to call kernel functions
 - But, in this project compiled with the kernel and share the same address with the kernel
 - Kernel thread
 - Task entry point
 - Function addresses
 - Please refer to task_info structure in start-code



- Start a task (process/thread)
 - Each task is associated with a PCB
 - Initialize PCB
 - Which registers should be set?
 - Where is the task located?
 - How to setup stack? Stack size?
 - Where is the PCB located?



Start a task

- Possible memory layout
- Decide your own STACK_MIN and STACK_MAX

kseg1 Unmapped Uncachable 0xE000 0000

STACK_MAX

STACK_MIN

0xA083 0000 (process3 addr.)

0xA082 0000 (process2 addr.)

0xA081 0000 (process1 addr.)

0xA080 026C (kernel entry addr.)

0xA080 0200 (kernel loaded addr.)

0xA080 0030 (bootblock exec addr.)

0xA080 0000 (bootblock loaded addr.)

0xA000 0000



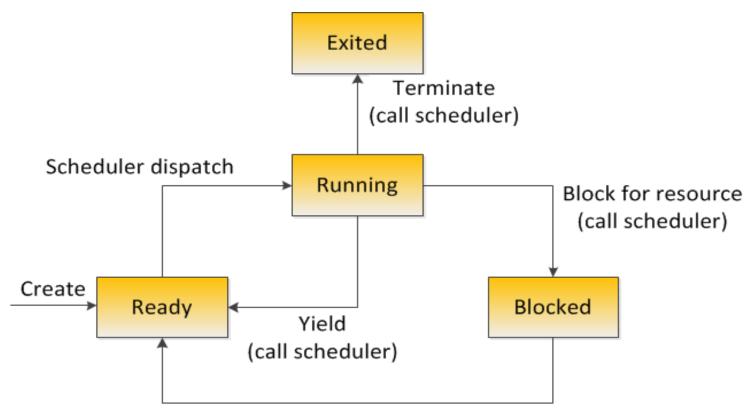
- Start a task
 - Scheduler: single task vs. multi-tasks
 - How to organize tasks being scheduled?
 - How to select the next task?
 - FIFO



- Start a task
 - Scheduler: first task vs. the following ones
 - do_scheduler()
 - Locate the PCB of the first task
 - Restore PCB
 - When the scheduler is invoked?
 - Non-preemptive kernel
 - Preemptive kernel



Scheduler (non-preemptive kernel)





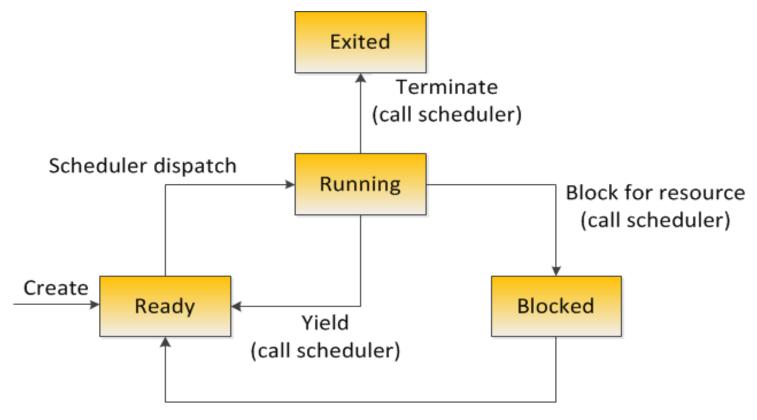
Yield

- An action to force a processor to release control of the current running thread
- Place the current running thread to the end of the running queue
- In this project, we call do_scheduler() to execute yield

- Context switch
 - Save PCB
 - What kind of things to save
 - Registers → Memory
 - Restore PCB
 - Memory → Registers
 - do_scheduler()

- Create machine image
 - Combine binary of kernel, tasks together into a machine image using createimage in your P1

Mutex lock

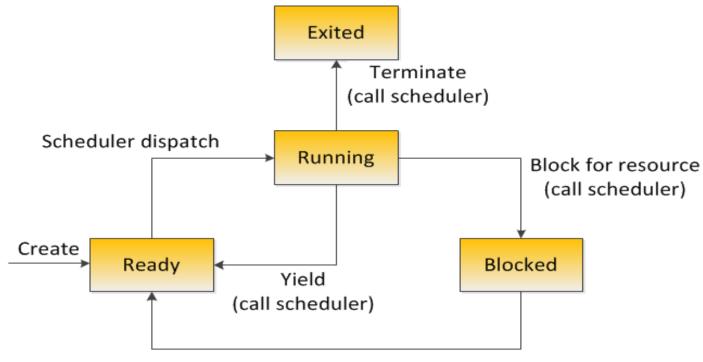




- Mutex lock
 - What if no thread currently holds the lock?
 - What if the lock is currently held?
 - Implement lock-related functions
 - Manage tasks that do not acquire the lock
 - Same queue vs. different queues?



- Problems of Non-Preemptive kernel
 - How about the throughput of the operating system?





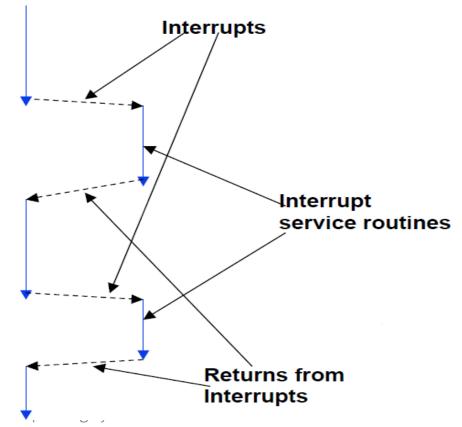
- Interrupt & Exception
 - A signal to the processor emitted by HW or SW indicating an event requiring immediate process
 - The processor responds by suspending its current running task, saving its state, and executing interrupt/exception handler
 - After the interrupt/exception handler finishes, the processor resumes normal activities



Interrupt & Exception

Normal execution

Normal execution with interrupt

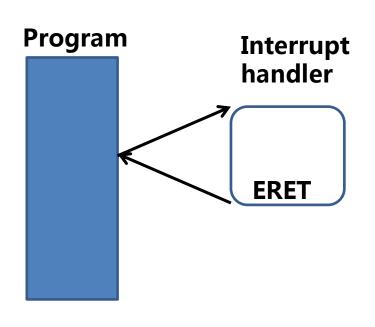




- Hardware interrupt
 - A change in execution caused by an external event outside the processor
 - Clock for timesharing
 - I/O devices: disk, network, keyboard etc.
- Software interrupt
 - System calls: a user-programmed interrupt
- We do not handle other exceptions here
 - Segment fault, Overflow, Page fault etc.



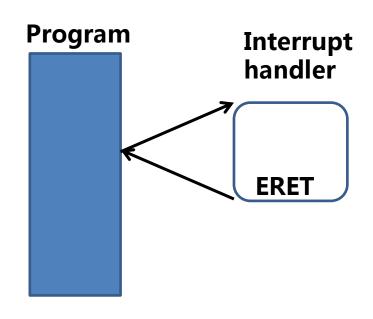
- Handling interrupt
 - Save context
 - Determine what caused interrupt
 - Invoke specific routine based on type of interrupt
 - Restore context
 - Return from interrupt



- Handling interrupt
 - What if interrupt occurs while in interrupt handler?
 - ENTER_CRITICAL
 - Disable interrupt before actually handling the interrupt
 - Setting a label to indicate the interrupt is disabled
 - LEAVE_CRITICAL
 - Do not forget to re-enable interrupt after handling the interrupt



- Handling interrupt
 - ENTER_CRITICAL
 - Save context
 - Determine what caused interrupt
 - Invoke specific routine based on type of interrupt
 - LEAVE_CRITICAL
 - Restore context
 - Return from interrupt



- Tips on implementing interrupt handler
 - Coprocessor 0 (CP0) registers
 - Status register
 - IE bit: 1 enable interrupt; 0 disable
 - IM7 ~ IM0: control enable/disable different interrupts
 - IM7 bit: 1: enable Clock interrupt; 0: disable

	31	28	27	26	25	24	23	22	21	20	19 16	15 8	7 5	4 3	2	1	0
CU (cu3:cu0)		U :cu0)	0	FR	0	NO- FDIV	NO- FSQR	BEV	0	SR	0	IM7-IM0	0	KSU	ERL	EXL	IE
												8					



- Tips on implementing interrupt handler
 - Coprocessor 0 (CP0) registers
 - Status register
 - Refer to the initialization of interrupts in start code
 - Pay attention to the initialization of the register in YOUR PCB
 - We handle clock interrupt and syscall in this project



- Tips on implementing interrupt handler
 - Coprocessor 0 (CP0) registers
 - Cause register
 - EXCCODE: Exception type
 - Hardware interrupt / software interrupt
 - IP7 ~ IP0: indicating the interrupt type
 - IP7 bit: 1: Clock interrupt

31	30	29 28 2	27 16	15 8	7	6 2	1	0
BD	0	CE	0	IP7~IP0	0	Exc-	0	
						Code		
1	1	2	12	8	1	5	2	_



- Tips on implementing interrupt handler
 - Operate CP0 registers
 - mfc0: move from Coprocessor 0
 - Loads data from a CP0 register into a CPU register
 - mtc0: move to Coprocessor 0
 - Stores data into a CP0 register
 - Use MIPS registers
 - \$k0, \$k1



- Tips on implementing interrupt handler
 - Coprocessor 0 (CP0): read-modify-write
 - Read the cp0 register into a CPU register
 - Modify the contents of the CPU register
 - Write the modified value back to the cp0 register
 - e.g. mfc0 k0, CP0_STATUS mtc0 k0, CP0_STATUS



- Tips on implementing interrupt handler
 - What do you do in the clock interrupt handler?
 - How to deal with normal tasks?
 - How to deal with sleeping tasks?



- Process sleep()
 - Blocking sleep
 - Block the task when it calls sleep()
 - Use a separate queue to keep sleeping tasks
 - Wake up the task
 - When the timing reaches sleeping threshold of the task
 - About timing
 - A global counter recording the number of ticks
 - The counter increases in each clock interrupt
 - We provide wall time calculation functions in time.c



- Scheduler
 - Round robin
 - Priority based
 - Fairness
 - Think about what kind of information should be included in PCB if you want to do the above scheduler

- Step by step
 - Task 0: PLEASE read the guiding book and start code CAREFULLY
 - Task 1: start a set of kernel threads and support context switch as a nonpreemptive kernel
 - Task 2: implement mutex lock to support BLOCK state

- Step by step
 - Task 3: implement a clock interrupt handler and priority based scheduler
 - Task 4: support syscalls and implement sys_sleep



- Requirement for design review (40 points)
 - What is PCB? What are included in PCB?
 - What need to be done for initializing tasks?
 - When is context switching in this project? What need to be done for context switching?
 - How do you manage blocked tasks?



- Requirement for design review (40 points, cont.)
 - What is the workflow for handling interrupt (for both clock interrupt and syscalls)?
 - How do you implement the priority based scheduler?
 - When do you wake up the sleeping task?



- Requirement for developing (60 points)
 - Start tasks and set PCBs: 5
 - Execute context switch without errors: 20
 - Implement the mutex lock: 5
 - Implement clock interrupt handler and syscall handler 20
 - Implement blocking sleep 5
 - Implement a priority-based scheduler 5



- Bonus (1 point)
 - Support one thread to acquire multiple locks (at least two)
 - Support more than two threads to acquire a single lock
 - Design your own test cases and show the results



- P2 schedule
 - P2 design review: 10th Oct.
 - No class on 17th Oct.
 - P2 due: 24th Oct.
- Final reminder
 - 重要的事情说三遍
 - Start early
 - Start early
 - Start early

