



$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^T = \begin{bmatrix} 0.3 & 0.7 \end{bmatrix}$$

$$W_1 = \begin{bmatrix} w_1 & w_2 \\ w_3 & w_4 \end{bmatrix} = \begin{bmatrix} 0.1 & 0.2 \\ 0.3 & 0.4 \end{bmatrix}$$

$$B_1 = \begin{bmatrix} b_1 & b_2 \end{bmatrix} = \begin{bmatrix} 0.5 & 0.6 \end{bmatrix}$$

$$W_2 = \begin{bmatrix} w_5 \\ w_6 \end{bmatrix} = \begin{bmatrix} 0.7 \\ 0.8 \end{bmatrix}$$

$$B_2 = \begin{bmatrix} b_3 \end{bmatrix} = \begin{bmatrix} 0.9 \end{bmatrix}$$

$\Theta_{ij}$ ,  $i$  is the # of the hidden unit and  $j$  is # of the input

$h_i$ ,  $i$  is the # of the hidden unit

$$h_d = a \left[ \Theta_{d0} + \sum_{i=1}^{D_i (\# \text{ inputs})} \Theta_{di} x_i \right], \quad y_j = \phi_{j0} + \sum_{d=1}^D \phi_{jd} h_d$$

$$h_1 = a [\Theta_{10} + \Theta_{11} x_1 + \Theta_{12} x_2]$$

$$h_2 = a [\Theta_{20} + \Theta_{21} x_1 + \Theta_{22} x_2]$$

$$y_0 = \phi_{10} + \phi_{01} h_1 + \phi_{02} h_2$$

$$\text{So, } h_1 = a[b_1 + w_1 x_1 + w_2 x_2]$$

$$h_2 = a[b_2 + w_3 x_1 + w_4 x_2]$$

$$\Rightarrow h_1 = a[0.5 + 0.1 \cdot 0.3 + 0.3 \cdot 0.7] = a[0.74]$$

$$h_2 = a[0.6 + 0.2 \cdot 0.3 + 0.4 \cdot 0.7] = a[0.94]$$

$$\Rightarrow h_1 = \frac{1}{1 + e^{-0.74}} \approx 0.677$$

$$h_2 = \frac{1}{1 + e^{-0.94}} \approx 0.719$$

So,

$$O_0 = a[y_0] = a[\phi_{10} + \phi_{01} h_1 + \phi_{02} h_2]$$

$$\Rightarrow y_0 = b_3 + w_5 h_1 + w_6 \cdot h_2 = 0.9 + 0.7 \cdot (0.677) + 0.8(0.719)$$

$$\Rightarrow y_0 = 1.941$$

$$O_0 = a[1.941] = \frac{1}{1 + e^{-1.941}} \approx 0.874$$

$$\text{error} = \frac{1}{2} (0.874 - 1)^2 \approx 0.00788 //$$



