

# Mastering Machine Learning for Spatial Prediction II

Model selection and interpretation, uncertainty

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### **Objectives** ...

- Know 2 ways of ...
  - of model selection
  - of model interpretation
  - computation of uncertainty
- Learn why we do model selection (or not)
- Learn that ML != black box
- Learn why we need uncertainty and how to validate your prediction intervals

#### **Overview**

#### **Model Selection**

- linear regression
- with lasso
- with covariate importance

#### Model interpretation

- partial residual plots
- partial dependence plot
- partial dependence maps

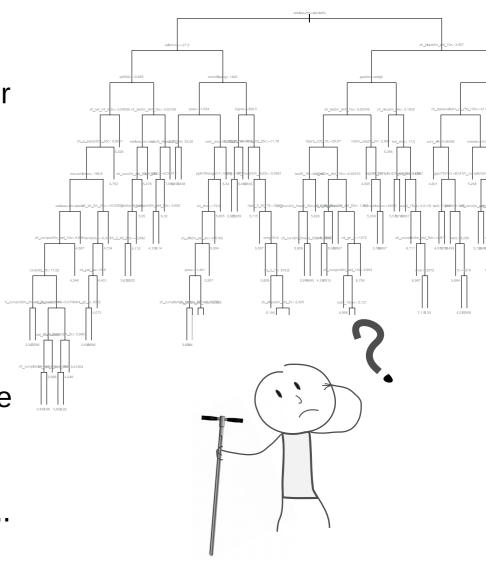
#### Uncertainty

- non-parametric bootstrap
- model-based bootstrap
- evaluation

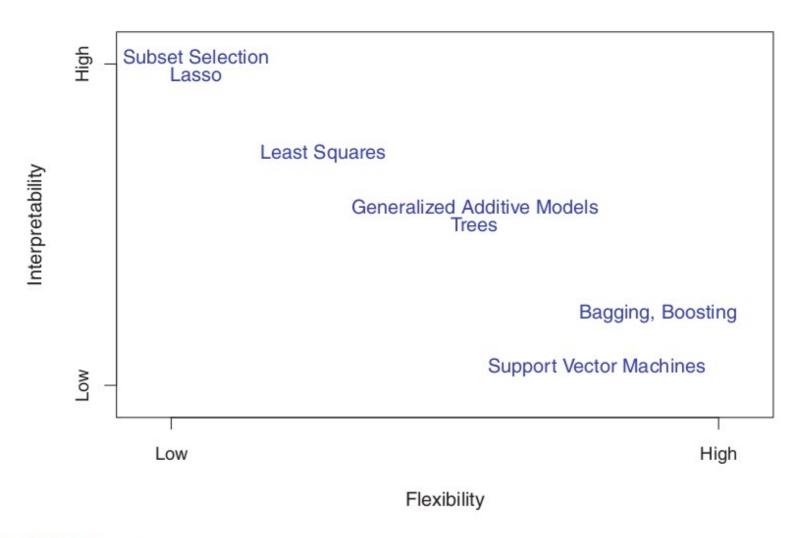
# Is there a reason for model selection? Or is it enough to do model building?

**Model selection** = reduce the inital covariate set **Model building** = find relationships between covariates and response

- Model interpretation
- Better just use relevant covariates for prediction
- Computational effort for predictions (just prepare 12 instead of 300 rasters)
- Maybe reduce effort for future data collection and modelling on same topic
- \* However, theoretical statisticians do not recommenced selection, because it is often biased, difficult to find the true model..
- ★ We might loose prediction accuracy...



### Model flexibility vs. model complexity



**FIGURE 2.7.** A representation of the tradeoff between flexibility and interpretability, using different statistical learning methods. In general, as the flexibility of a method increases, its interpretability decreases.

## **Model selection – strategies**

 Ask a domain expert that is familiar with the topic of your modelling problem



- Remove n worst covariates
- Stepwise addition or removal (see later)
- Test all possible models
- Shrinkage (e.g. by boosting or lasso, see later).

### Model selection for linear regression

Usually used for linear models (e. g. OLS):

#### Forward selection

- Start with a model with just an intercept
- Try all possible covariates and add the one that results in the best fit (e.g. R<sup>2</sup>)
- Add covariates until increase in R<sup>2</sup> is only very small (threshold) or evaluate the gained models by cross validation.

#### Backward elimination

- Fit the full model with all covariates
- Remove the covariate that will cause the smallest decrease in R<sup>2</sup>
- Continue removing until the drop in R2 gets too big (threshold) or evaluate the fitted models by cross validation

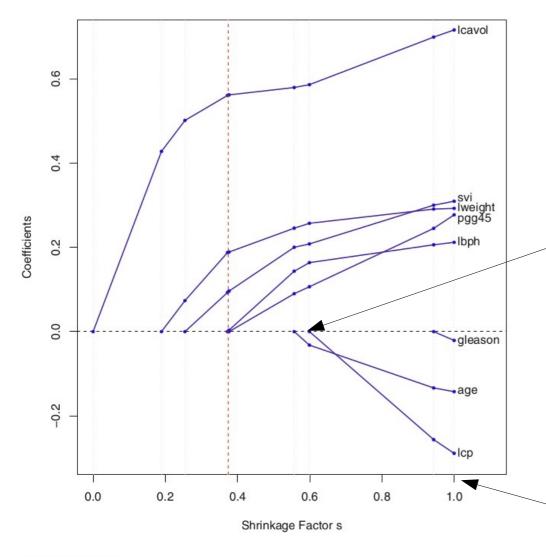
### Model selection for linear regression

Evaluation of forward and backward selection:

- Straightforward, easy to understand
- Follows a selection path, hence much more efficient and less arbitrary than best subset selection
- ★ Binary selection: A covariate is either in or out. Being in by e.g. 30 % is not possible.
- Multi-collinearity, unstable fits!
  We need to remove correlated covariates beforehand.
- Likely overfits the data, biased model selection.
  Most often does not find true model.
- ★ We can not fit p > n
- → Possible solution: regularization / shrinkage with e.g. lasso.

#### **Model selection with lasso**





Path of coefficients for increasing tuning parameter

Coefficient becomes 0, meaning the covariate is removed from the model

**FIGURE 3.10.** Profiles of lasso coefficients, as the tuning parameter t is varied. Coefficients are plotted versus  $s = t/\sum_{1}^{p} |\hat{\beta}_{j}|$ . A vertical line is drawn at s = 0.36, the value chosen by cross-validation. Compare Figure 3.8 on page 65; the lasso profiles hit zero, while those for ridge do not. The profiles are piece-wise linear, and so are computed only at the points displayed; see Section 3.4.4 for details.

With lambda = 1, there is no shrinkage, and we have the normal ordinary least squares linear model fit

# Covariate selection for random forest (or boosted trees)

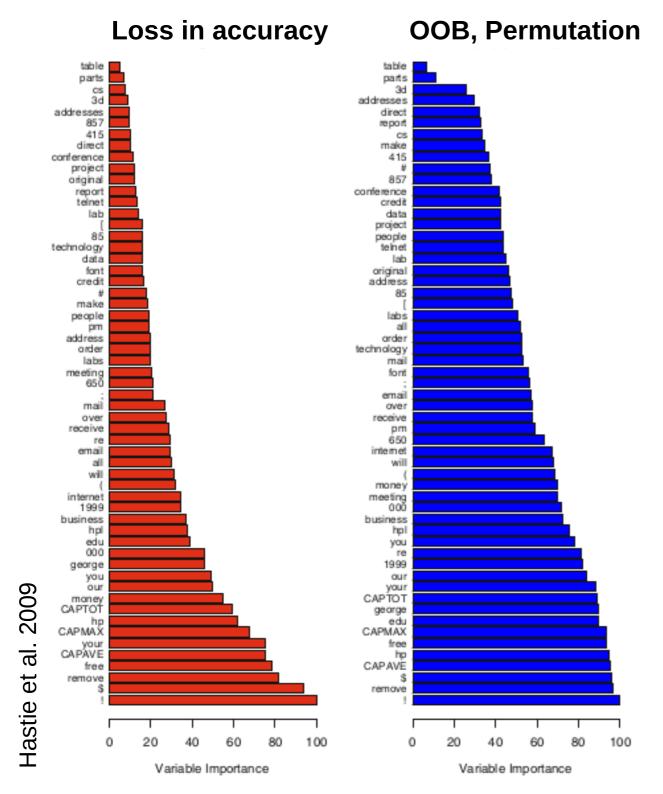
What again was this out-of-bag (OOB) error?

For each observation  $z_i = (x_i, y_i)$ , construct its random forest predictor by averaging only those trees corresponding to bootstrap samples in which  $z_i$  did not appear.

Hastie et al. 2009, p. 593

#### 2 types of covariate importance:

- Mean decrease in accuracy (type=1 in importance()): oriented on fitting the data. How much do we reduce error by using this covariate at this split?
  - → this importance is used for boosted trees.
- Mean decrease in node impurity (type=2 in importance()), permutation based, oriented on predictions: How much worse do OOB predictions get if we randomly permutate a covariate?
  - → removing a covariate is not the same, other correlated covariate could replace its "predictive capacity"



**Selection**, very simple:

Recursive backward elimination

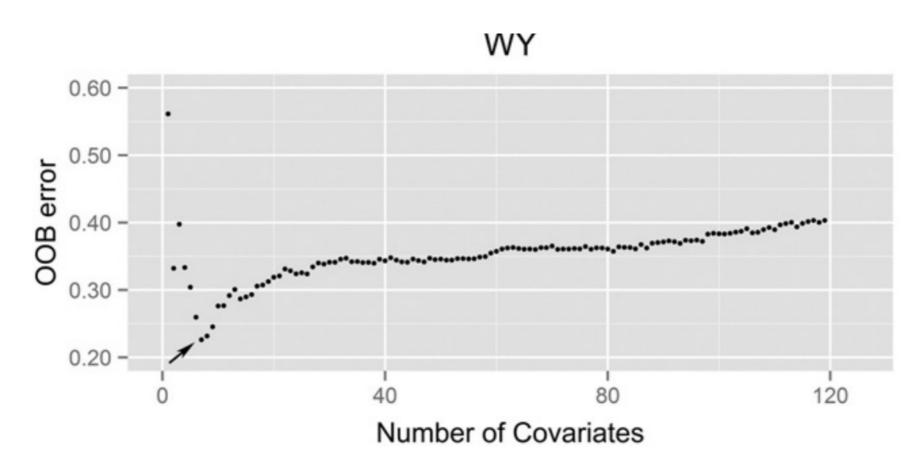
- 1) Remove covariate(s) with lowest importance
- 2) Refit random forest with remaining

Find optimum number of covariates by minimizing OOB error.

#### Problem:

Correlated covariates remain, because of randomisation at each split (m<sub>try</sub>). Interpretation needs to account for that.

# **Covariate selection for random forest** (or boosted trees)



#### **Model selection with random forest**

- Straightforward approach
- Easy to implement
- From my experience: efficient (meaning a lot of covariates are removed)
- Correlated covariates remain in the model
- Artefacts in predictions possible
- Stability unclear?(Small changes in covariate or response values might change result drastically)
- Biased?(maybe biased as other backward elimination methods)
- Time consuming (iterative method, no paralell computing possible)
- **★** Possibly: A lot of effort for a small result

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## Covariate interpretation for any model

#### Partial residual plots (see e.g. Wikipedia)

Regression based methods, plot *Residuals* of full model plus the covariate effect  $\hat{\beta}_i X_i$  against the values of covariate  $X_i$ 

Residuals + 
$$\hat{\beta}_i X_i$$
 versus  $X_i$ 

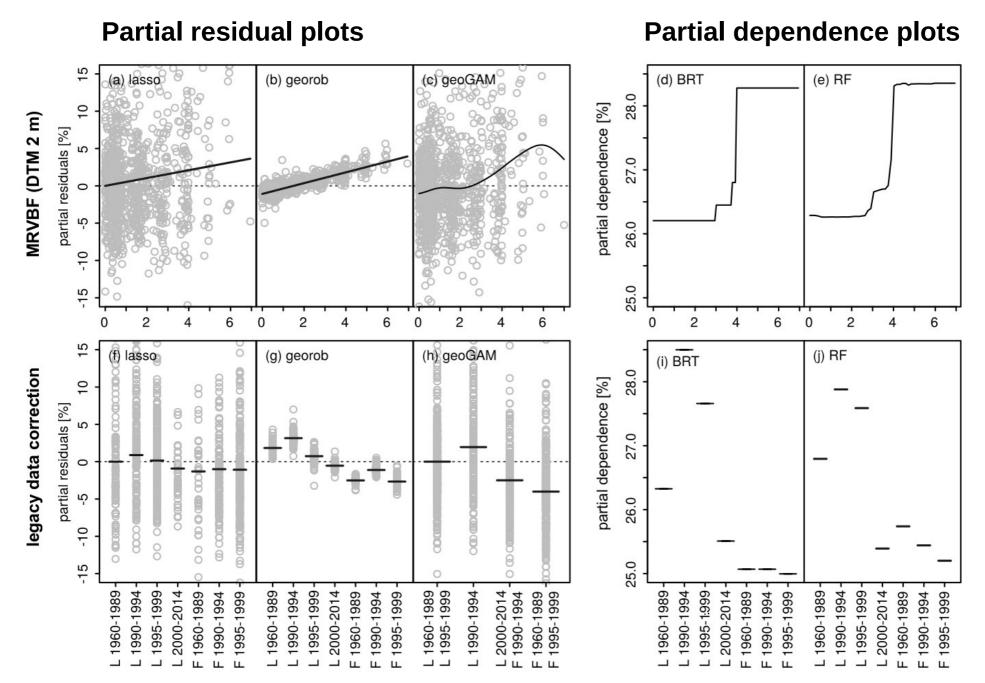
#### Partial dependence plots Hastie et al. 2009, chapt. 10.13.2

Any "black box" learning model, dependence of covariate on response after *accounting* (not *ignoring*) for the effects of all other covariates. Approximation of function by:

$$\bar{f}_{\mathcal{S}}(X_{\mathcal{S}}) = \frac{1}{N} \sum_{i=1}^{N} f(X_{\mathcal{S}}, x_{i\mathcal{C}}),$$

**Take care with interpretation:** If many covariates it is difficult to choose which to interpret. If collinearity in data set, covariates might replace each other ...

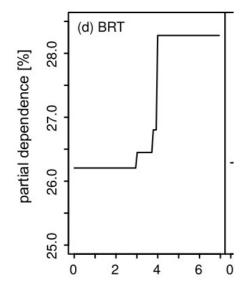
### Covariate interpretation for any model



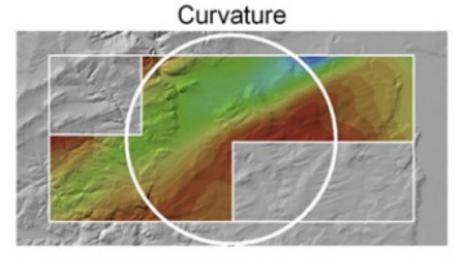
Nussbaum et al. 2017b

# **Spatial covariate** interpretation

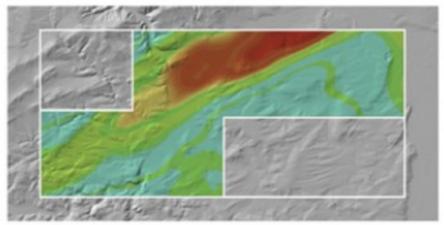
Create maps from relationship:



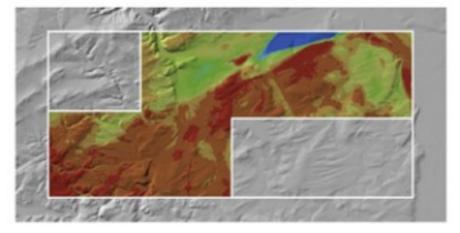
Original covariate



Partial dependence



Local importance



Behrens et al. 2014

#### **Overview**

#### **Model Selection**

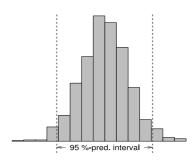
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## Confidence intervals vs. prediction intervals

#### **Confidence intervals**

Intervals of confidence for the estimate of a population <u>mean</u>. Considers uncertainty in our <u>estimation</u> of  $\beta$  (based on standard error of coefficient).

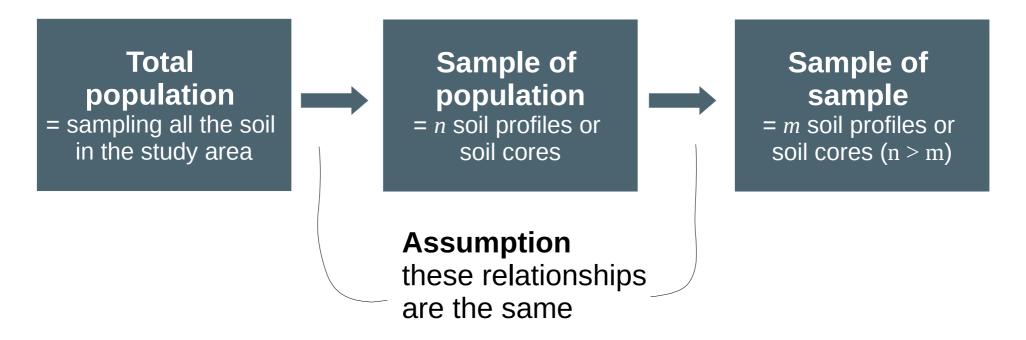
$$y = X \hat{\beta} + \epsilon$$

#### **Prediction intervals**

Intervals of confidence for the estimate of a <u>new observation</u>. Considers uncertainty estimated  $\beta$  <u>and</u> the variation the model does not account for (based on standard error of coefficient and residual error).

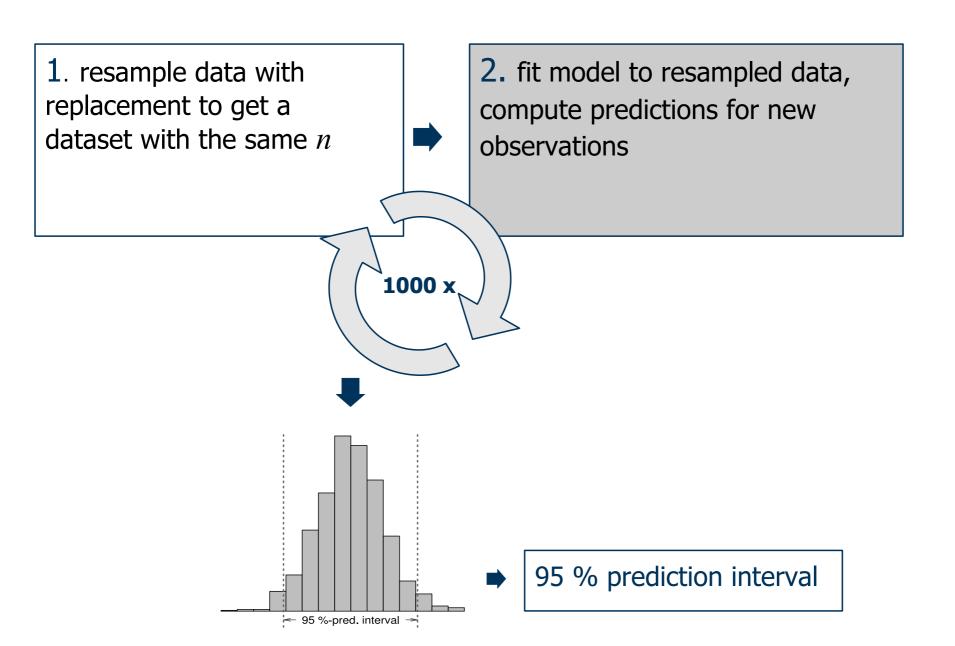
$$y = X \hat{\beta} + \epsilon$$

### Non-parametric bootstrap – idea



- Idea: by resampling our sample many times (e.g. 1000x)
  we can approximate properties of the distribution of the
  total population.
- Useful to
  - create model ensemblesbagging = boostrap aggregation
  - estimate uncertainty for any model

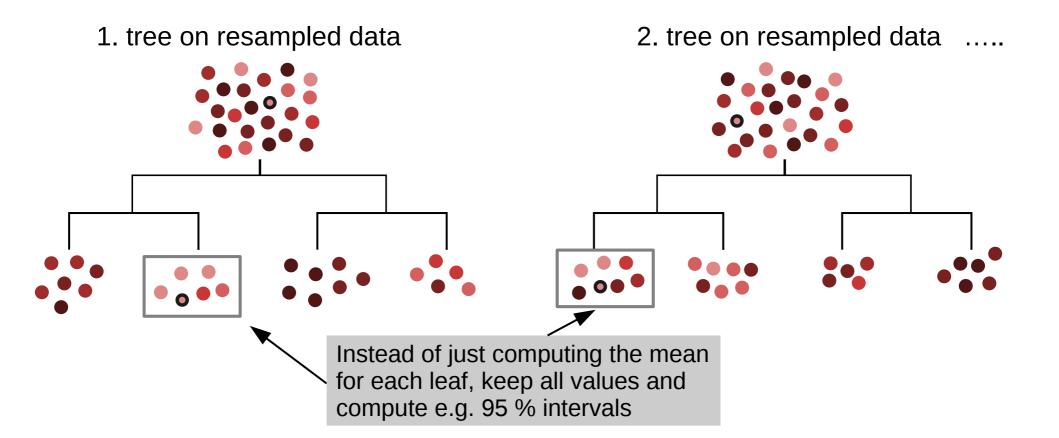
# Simulate predictive distribution non-parametric bootstrapping ("model-free")



# "Quantile regression forest" as non-parametric bootstrap

Citation: Meinshausen N, 2006. Quantile regression forests. Journal of Machine Learning Research, 7, 983–999.

- Bootstrap aggregation in random forest: each tree is fitted to a resampled dataset
- Keep all observations in the final tree leaves
- Get distribution from observations that were in leaves together

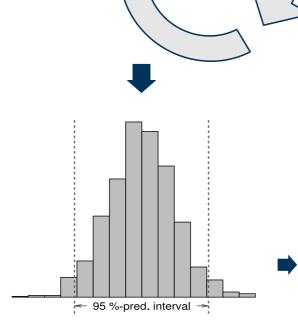


# Simulate predictive distribution by model-based bootstrapping

1. simulate response under the final model

$$Y(s) = \sum f(X, s) + \epsilon$$

2. fit model to simulated response, compute predictions for new observations



1000 x

95 % prediction interval

## **Model-based bootstrapping**

(also "parametric bootstrap")

For 1000 repetitions, do:

1. Simulate new response  $Y^*(s)$  with the fitted value f(x(s)) plus a randomly chosen residual sampled from  $\varepsilon$  (or from normal distribution with same  $\sigma$ ,  $\mu$  as residual distribution):

$$Y(\mathbf{s})^* = \hat{f}(\mathbf{x}(\mathbf{s})) + \epsilon$$

- 2. Fit model to new response  $Y^*(s)$
- 3. Compute prediction error for new location s+ with again randomly sampled  $\epsilon$

$$\delta_+^* = \hat{f}(\mathbf{x}(\mathbf{s}_+))^* - (\hat{f}(\mathbf{x}(\mathbf{s}_+)) + \epsilon)$$

Two-sided prediction intervals: 
$$[\hat{f}(\mathbf{x}(\mathbf{s}_+)) - \delta^*_{+(1-\alpha)}; \hat{f}(\mathbf{x}(\mathbf{s}_+)) - \delta^*_{+(\alpha)}].$$

## Which bootstrap should I use?

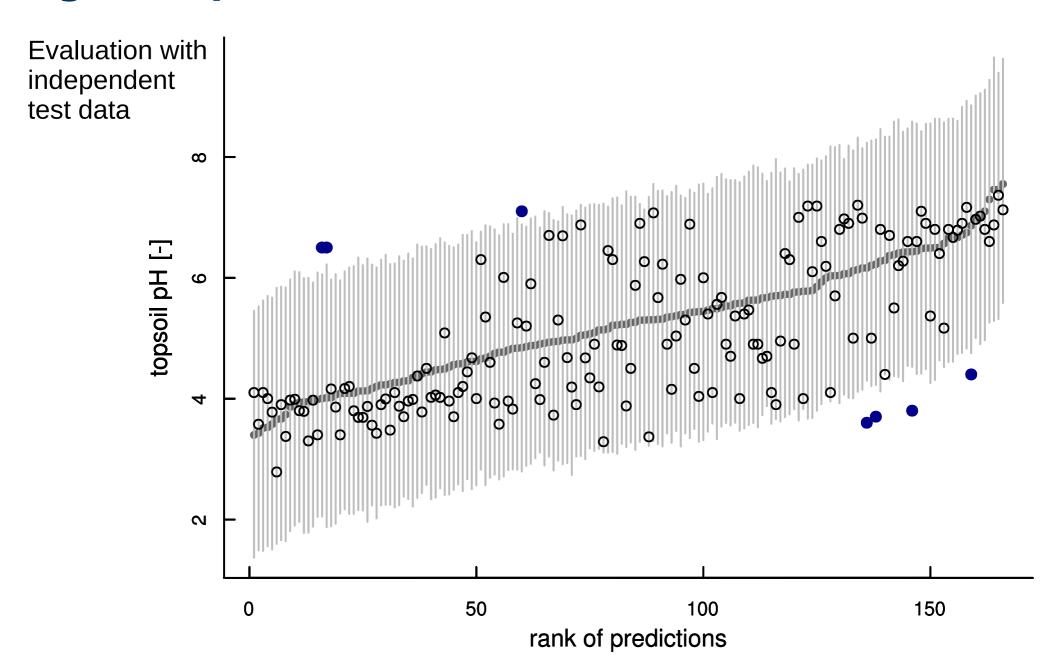
#### non-parametric

- No assumptions about a model or error distributions
- **★** Likely to fail with small datasets:
  - underestimates variance
  - lacks to depict distribution of full population
- mostly no software
- easy to implement
- computationally intensive (mainly CPU)

#### model-based / parametric

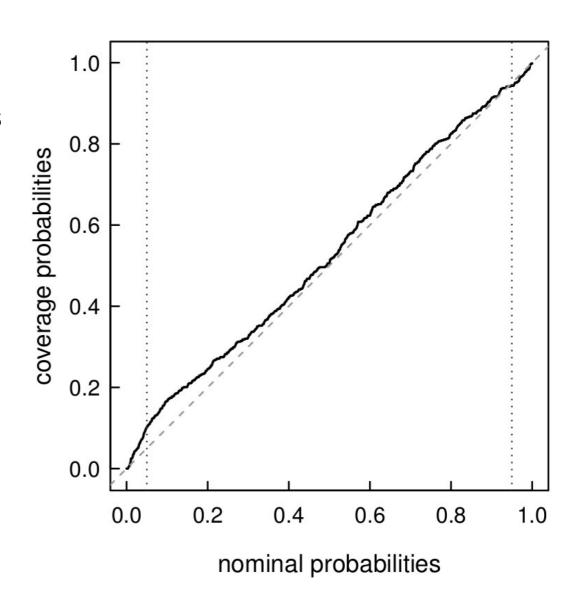
- \* Assumes e.g. Gaussian errors
- Prediction intervals are given this model even if model is wrong
- More suitable for small datasets
- mostly no software
- \* a bit tricky to implement
- computationally intensive (mainly CPU)

# Performance plots for e.g. 95% prediction intervals



# Performance plots for complete predictive distribution

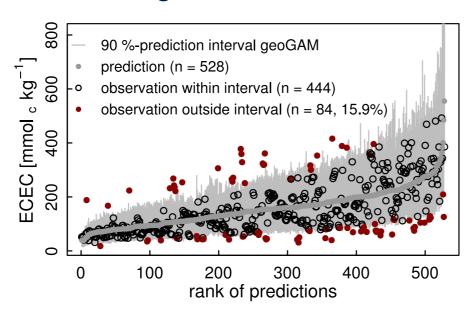
<u>one-sided</u> prediction intervals of bootstrapped distribution against the nominal probabilities



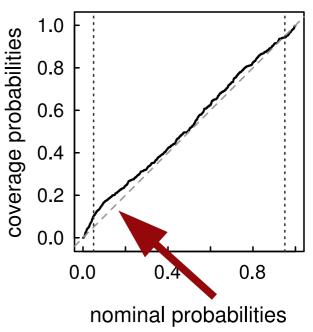
### **Evaluation of prediction intervals**

#### coverage 90 %-intervals

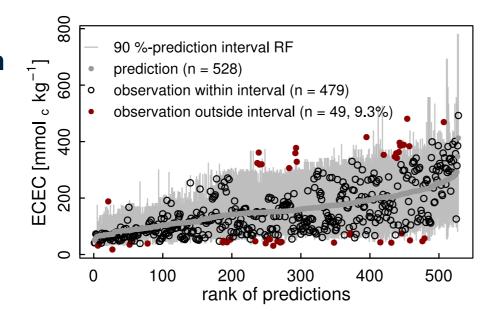
#### geoGAM bootstrap

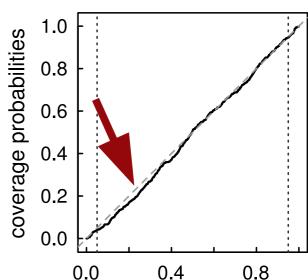


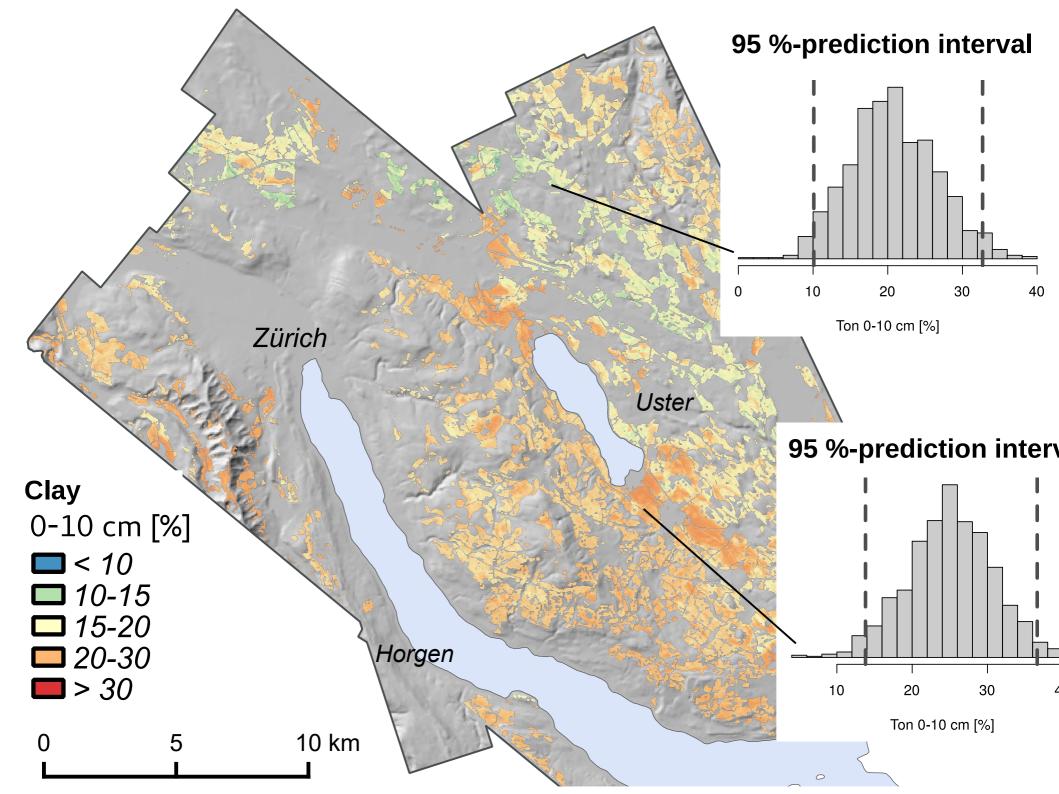
coverage one-sided intervals



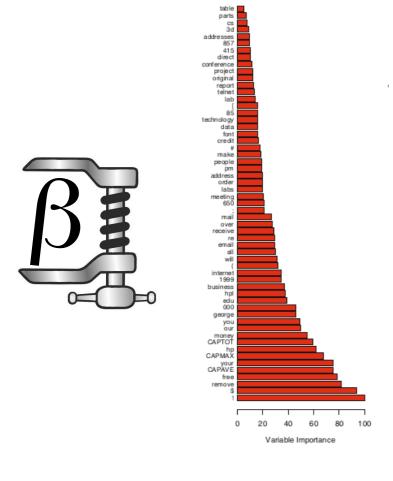
quantile regression forest

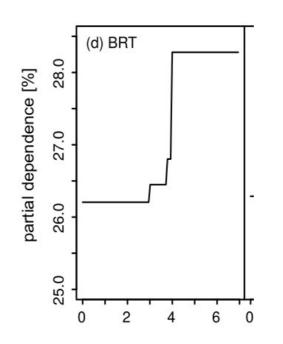


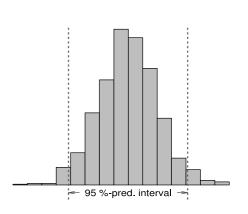




# **Summary of lecture**







# My personal tips for your applied ML modelling career:

- Do not believe there is the ONE solution (e.g. one model that never fails.). So make sure you understand advantages and disadvantages for your application.
- Do not neglect classical statistics. Without understanding linear models you will never master machine learning!
- If a method is hard to understand to you, **please use a simpler one**, that you feel secure with! Your credibility and credibility of your data product is at stake.
- Do not neglect domain knowledge. Most likely consulting an expert of your field might improve your model more than the 100redst tuning of the latest fancy method, e.g. by inlcuding a neglected covariate!

#### Additional literature ....

# Davison & Hinkley 1997, on bootstrap methods, a bit technical though.

Davidson, A. C. and Hinkley, D. V.: Bootstrap Methods and Their Applications, Cambridge University Press, Cambridge, doi:10.1017/cbo9780511802843, 1997.

# Tutz, 2012, very good book on categorical responses, mostly parametric methods, some ML described, comes with many examples and a R package:

Tutz, G.: Regression for Categorical Data, Cambridge University Press, doi:10.1017/cbo9780511842061, 2012.

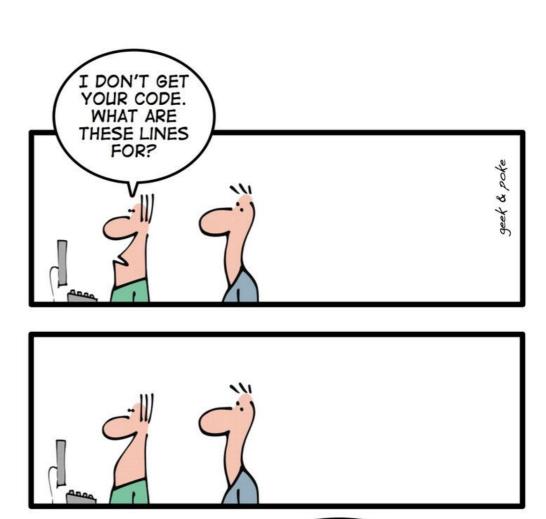
# Wilks 2011, Useful book for validation measures including for uncertainty, see chapter 8 and R package "verification":

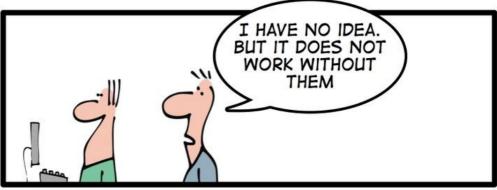
Wilks, D. S.: Statistical Methods in the Atmospheric Sciences, Academic Press, 3 edn., 2011.

### **Practical training**

#### You will learn:

model selection model interpretation and much more!





THE ART OF PROGRAMMING - PART 2: KISS