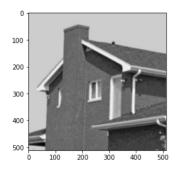
Name: Jay Goyal Roll no.: C017 Semester: VI Program: B.Tech Branch: EXTC Date of performance: 19th March Date of Submission: 26th March Experiment Number: 7 Aim: To write a program in PYTHON to highlight horizontal, vertical and diagonal edges of an image Sobel Operator -1 -2 -1 000 121 Horizontal edge Fx -1 0 1 -202 -1 0 1 Vertical Edge Fy • Convolve Fx mask to the original image to obtain the x gradient of the image • Convolve Fy mask to the original image to obtain the y gradient of the image • Add the results of the above two steps 012 -1 0 1 -2 -1 0 Diagonal Edge Laplacian operator 010 1 -4 1 010 Conclusion: We learnt about the significance of filter masks for edge enhancement and Implemented Sobel and Laplacian operators import numpy as np import matplotlib.pyplot as plt

from scipy import signal import cv2

img= cv2.imread("/content/house.tif",0) #Read the image plt.imshow(img, cmap="gray", vmin=0, vmax=255) m,n= img.shape



#Detect horizontal edges using in built convolution function sobel\_h= np.array([[-1,-2,-1], [0,0,0], [1,2,1]]) img\_h= signal.convolve(img,sobel\_h,mode='same') plt.imshow(img\_h,cmap="gray", vmin=0, vmax=255)

```
<matplotlib.image.AxesImage at 0x7f54df9c2b50>
100
```

```
200
300
400
```

```
#Detect horizontal edges without using in built convolution function
mask= np.array([[-1,-2,-1], [0,0,0], [1,2,1]])
img_new_h=np.zeros([m,n])
for i in range(1,m-1):
```

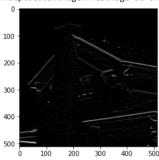
for j in range(1,n-1):

temp= img[i-1,j-1]\*mask[0,0]+img[i-1,j]\*mask[0,1]+img[i-1,j+1]\*mask[0,2]+img[i,j-1]\*mask[1,0]+img[i,j]\*mask[1,1]+img[i,j+1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,j-1]\*mask[1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+img[i+1,2]+i

img\_new\_h[i,j]=temp

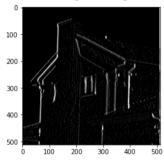
plt.imshow(img\_new\_h, cmap="gray", vmin=0)

<matplotlib.image.AxesImage at 0x7f54df949310>



#Detect vertical edges using inbuilt function for convolution  $sobel\_v= np.array([[-1,0,1],\ [-2,0,2],\ [-1,0,1]])$ img\_v= signal.convolve(img,sobel\_v,mode='same') plt.imshow(img\_v,cmap="gray", vmin=0, vmax=255)

<matplotlib.image.AxesImage at 0x7f54df927e50>



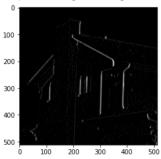
#Detect vertical edges without using in built convolution function mask\_v= np.array([[-1,0,1], [-2,0,2], [-1,0,1]]) img\_new\_v=np.zeros([m,n]) for i in range(1,m-1): for j in range(1,n-1):

 $\texttt{temp= img[i-1,j-1]*mask\_v[0,0]+img[i-1,j]*mask\_v[0,1]+img[i-1,j+1]*mask\_v[0,2]+img[i,j-1]*mask\_v[1,0]+img[i,j]*mask\_v[1,1]+img[i,j+1]*mask\_v[1,2]+img[i+1,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[1,0]+img[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask\_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i,j+1]*mask_v[i$ 

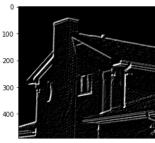
img\_new\_v[i,j]=temp

plt.imshow(img\_new\_v, cmap="gray", vmin=0)

<matplotlib.image.AxesImage at 0x7f54df89f110>

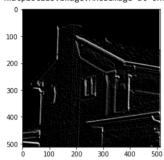


#Detecting vertical and horizontal edges img\_hv= img\_h+img\_v plt.imshow(img\_hv, cmap="gray", vmin=0, vmax=255) <matplotlib.image.AxesImage at 0x7f54df7ff590>



# Detecting Diagonal with inbuilt convolve
sobel\_d= np.array([[0,1,2], [-1,0,1], [-2,-1,0]])
img\_d= signal.convolve(img,sobel\_d,mode='same')
plt.imshow(img\_d, cmap="gray", vmin=0, vmax=255)

<matplotlib.image.AxesImage at 0x7f54df7e4c50>



# Detecting Diagonal without inbuilt convolve function  $mask\_d=np.array([[0,1,2], [-1,0,1], [-2,-1,0]])$   $img\_new\_d=np.zeros([m,n])$  for i in range(1,m-1):

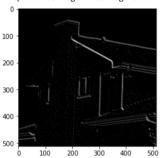
for j in range(1,n-1):

 $temp = img[i-1,j-1]*mask\_d[0,0] + img[i-1,j]*mask\_d[0,1] + img[i-1,j+1]*mask\_d[0,2] + img[i,j-1]*mask\_d[1,0] + img[i,j]*mask\_d[1,1] + img[i,j+1]*mask\_d[1,2] + img[i+1,j+1]*mask\_d[1,0] + img[i+1,0] + img[i+1,0]$ 

img\_new\_d[i,j]=temp

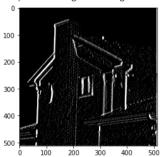
plt.imshow(img\_new\_d, cmap="gray", vmin=0)

<matplotlib.image.AxesImage at 0x7f54df87ca10>



#Horizontal, vertical and diagonal edges
img\_hvd= img\_h+img\_v+img\_d
plt.imshow(img\_hvd, cmap="gray", vmin=0, vmax=255)

<matplotlib.image.AxesImage at 0x7f54dfe806d0>



#centre 0 row in horizontal and centre column 0 for vertical  $% \left( 1\right) =\left( 1\right) \left( 1\right)$ 

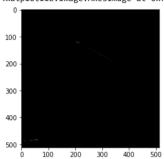
## Horizontal edges variation

#Detect horizontal edges using in built convolution function
sobel\_h\_1= np.array([[-1,-4,-1], [0,0,0], [1,2,1]])
img\_h\_1= signal.convolve(img,sobel\_h\_1,mode='same')
plt.imshow(img\_h\_1,cmap="gray", vmin=0, vmax=255)

```
cmatplotlib.image.AxesImage at 0x7f54ddf17a90>
0
100 -
200 -
300 -
```

#Detect horizontal edges using in built convolution function
sobel\_h\_2= np.array([[-1,-6,-1], [0,0,0], [1,2,1]])
img\_h\_2= signal.convolve(img,sobel\_h\_2,mode='same')
plt.imshow(img\_h\_2,cmap="gray", vmin=0, vmax=255)

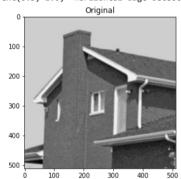
<matplotlib.image.AxesImage at 0x7f54ddd678d0>

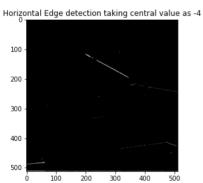


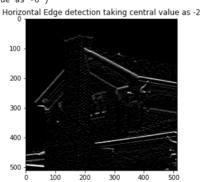
plt.figure(figsize=(15,15))

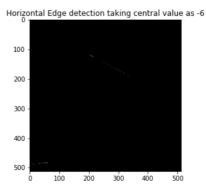
```
plt.subplot(3,2,1)
plt.imshow(img, cmap="gray")
plt.title("Original")
plt.subplot(3,2,2)
plt.title("Horizontal Edge detection taking central value as -2")
plt.imshow(img_new_h, cmap="gray",vmin=0, vmax=255)
plt.subplot(3,2,3)
plt.title("Horizontal Edge detection taking central value as -4")
plt.imshow(img_h_1, cmap="gray",vmin=0, vmax=255)
plt.subplot(3,2,4)
plt.imshow(img_h_2, cmap="gray",vmin=0, vmax=255)
plt.title("Horizontal Edge detection taking central value as -6")
```

Text(0.5, 1.0, 'Horizontal Edge detection taking central value as -6')







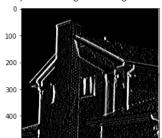


#Horizontal Detection as we increase the values the horizontal values becomes more and more clear

## Vertical edges variation

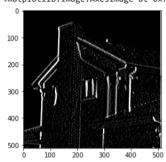
```
#Detect vertical edges using inbuilt function for convolution
sobel_v_1= np.array([[-1,0,1], [-8,0,8], [-1,0,1]])
img_v_1= signal.convolve(img,sobel_v_1,mode='same')
plt.imshow(img_v_1,cmap="gray", vmin=0, vmax=255)
```

<matplotlib.image.AxesImage at 0x7f54dde538d0>



#Detect vertical edges using inbuilt function for convolution
sobel\_v\_2= np.array([[-1,0,1], [-5,0,5], [-1,0,1]])
img\_v\_2= signal.convolve(img,sobel\_v\_2,mode='same')
plt.imshow(img\_v\_2,cmap="gray", vmin=0, vmax=255)

<matplotlib.image.AxesImage at 0x7f54dd8abf50>

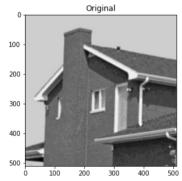


plt.figure(figsize=(15,15))

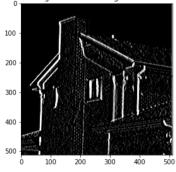
```
plt.subplot(3,2,1)
plt.imshow(img, cmap="gray")
plt.title("Original")
plt.subplot(3,2,2)
plt.title("Vertical Edge detection taking central value as 2")
plt.imshow(img_new_v, cmap="gray",vmin=0, vmax=255)
plt.subplot(3,2,3)
plt.title("Vertical Edge detection taking central value as 8")
plt.imshow(img_v_1, cmap="gray",vmin=0, vmax=255)
plt.subplot(3,2,4)
plt.imshow(img_v_2, cmap="gray",vmin=0, vmax=255)
```

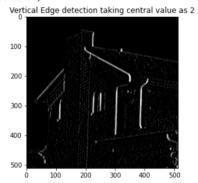
plt.title("Vertical Edge detection taking central value as 5")

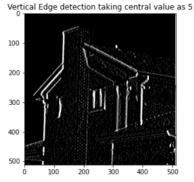
Text(0.5, 1.0, 'Vertical Edge detection taking central value as 5')



Vertical Edge detection taking central value as 8







#Vertical Detection as we increase the values the vertical values becomes less and less clear