view\_frames Result Recorded at time: 1611263185.126 base\_link world Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1611263185.126 sec old) Buffer length: 0.000 sec panda\_link0 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1611263185.027 ( 0.099 sec old) Buffer length: 4.800 sec panda\_link1 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1611263185.027 (0.099 sec old) Buffer length: 4.800 sec panda\_link2 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1611263185.027 ( 0.099 sec old) Buffer length: 4.800 sec panda\_link3 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1611263185.027 ( 0.099 sec old) Buffer length: 4.800 sec panda\_link4 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1611263185.027 (0.099 sec old) Buffer length: 4.800 sec panda\_link5 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1611263185.027 (0.099 sec old) Buffer length: 4.800 sec panda\_link6 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1611263185.027 (0.099 sec old) Buffer length: 4.800 sec panda\_link7 Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1611263185.126 sec old) Buffer length: 0.000 sec panda\_link8 Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1611263185.126 sec old) Buffer length: 0.000 sec panda\_hand Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Average rate: 10.209 Hz Most recent transform: 1611263185.027 (0.099 sec old) Most recent transform: 1611263185.027 (0.099 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec panda\_leftfinger panda\_rightfinger