Jaehoon Choi

jaehoonc44@gmail.com ● +1-240-264-7719 ● https://jh-choi.github.io

EDUCATION

University of Maryland, College Park

■ Ph.D. in Computer Science

Jan 2021 – Present

Korea Advanced Institute of Technology (KAIST)

M.S. in Electrical EngineeringAdviser: Prof. Changick Kim

Sep 2017 - Dec 2019

Korea Advanced Institute of Technology (KAIST)

■ B.S. in Electrical Engineering

Feb 2011 – Aug 2017

Minor: Business and Technology Management

• Korean Augmentation to the United States Army (mandatory military service)

Oct 2014 - Jul 2016

RESEARCH INTERESTS PUBLICATIONS

Computer Vision, Machine Learning, and Computer Graphics.

INTERNATIONAL CONFERENCES

- [1] **Jaehoon Choi***, Dongki Jung*, Yonghan Lee, Deokhwa Kim, Dinesh Manocha, and Donghwan Lee, "SelfTune: Metrically Scaled Monocular Depth Estimation through Self-Supervised Learning", Accepted to *The IEEE International Conference on Robotics and Automation (ICRA)*, 2022. (* These two authors contributed equally)
- [2] Taekyung Kim, **Jaehoon Choi**, Seokeon Choi, Dongki Jung, and Changick Kim, "Just a Few Points are All You Need for Multi-view Stereo: A Novel Semi-supervised Learning Method for Multi-view Stereo", *International Conference on Computer Vision (ICCV)*, 2021.
- [3] Dongki Jung*, **Jaehoon Choi***, Yonghan Lee, Deokhwa Kim, Changick Kim, Dinesh Manocha, and Donghwan Lee, "DnD: Dense Depth Estimation in Crowded Indoor Dynamic Scenes", *International Conference on Computer Vision (ICCV)*, 2021. (* These two authors contributed equally)
- [4] **Jaehoon Choi**, Dongki Jung, Yonghan Lee, Deokhwa Kim, Dinesh Manocha, and Donghwan Lee, "SelfDeco: Self-Supervised Monocular Depth Completion in Challenging Indoor Environments", *The IEEE International Conference on Robotics and Automation (ICRA)*, 2021.
- [5] **Jaehoon Choi***, Dongki Jung*, Donghwan Lee, and Changick Kim, "SAFENet: Self-Supervised Monocular Depth Estimation with Semantic-Aware Feature Extraction", *Neural Information Processing Systems Workshop (NeurIPSW)* on Machine Learning for Autonomous Driving, Vancouver, Canada, 2020. (* These two authors contributed equally)
- [6] Dongki Jung, Seunghan Yang, **Jaehoon Choi**, and Changick Kim, "Arbitrary Style Transfer Using Graph Instance Normalization", *The 27th IEEE International Conference on Image Processing (ICIP)*, Abu Dhabi, UAE, 2020
- [7] **Jaehoon Choi**, Taekyung Kim, and Changick Kim, "Self-Ensembling with GAN-based Data Augmentation for Domain Adaptation in Semantic Segmentation", *International Conference on Computer Vision (ICCV)*, Seoul, South Korea, 2019
- [8] Seunghyeon Kim, Jaehoon Choi, Taekyung Kim, and Changick Kim, "Self-Training with Adversarial Background Regularization for Unsupervised Domain Adaptive One-Stage Object Detection", *International Conference on Computer Vision (ICCV)*, Seoul, South Korea, 2019 (Oral)
- [9] Jaehoon Choi, Minki Jeong, Taekyung Kim, and Changick Kim, "Pseudo-Labeling Curriculum for Unsupervised Domain Adaptation", British Machine Vision Conference (BMVC), Cardiff, UK, 2019

OTHER PUBLICATIONS

[1] **Jaehoon Choi**, Daeyeong Kim, Dongwon Yang, Junhee Lee, Dokyung Kim, Changick Kim, "Channel Pruning Scaling Factor of Batch Normalization in Compact Networks", *Journal of the Institute of Electronics and Information Engineers*, vol. 56, No. 3, Mar 2019.

PROFESSIONAL EXPERIENCE

■ Research Scientist at NAVER LABS

• Manager: Ph.D. Donghwan Lee

Jan 2022 - Present

• Developing a Neural Rendering algorithm for Augmented Reality platform.

■ **Research Internship** at NAVER LABS

Jun 2021 - Aug 2021

• Manager: Ph.D. Donghwan Lee

• Developed a SLAM algorithm for the mobile robot.

■ **Research Internship** at NAVER LABS

Jan 2020 – Dec 2020

• Manager: Ph.D. Donghwan Lee

Developed a depth estimation algorithm for robotics systems.

PROJECT EXPERIENCE

■ 3D Object Recognition Algorithm for Autonomous Driving

May 2019 - Nov 2019

• Funded by *LG Electronics Co., Ltd*

Aimed at Developing the 2D object detection and depth estimation for stereo RGB images and FIR images.

■ Deep Learning Algorithm on Embedded Systems for Vision Tasks

Jan 2018 - Dec 2018

• Funded by *LIG Nex1 Co., Ltd*

Developed the visual recognition algorithm on the embedded system, which requires light and efficient deep learning.

■ Deep Learning-based Defect Detection

Apr 2017 – Dec 2017

• Funded by Samsung Electronics Co., Ltd

• Aimed at developing the automatic surface defect detection algorithm for mobile phone based on deep learning.

TEACHING

■ University of Maryland College Park, Teaching Assistant

Sep 2021 – Dec 2021

CMSC250 – Discrete Structure

■ University of Maryland College Park, Teaching Assistant

Feb 2021 - May 2021

● CMSC426 – Computer Vision

■ KAIST, Teaching Assistant

Mar 2019 – Jul 2019

EE838 – Special Topics in Image Engineering < Optimization for Computer Vision>

■ KAIST, Student Tutor

Mar 2017 – Jul 2017

Student tutor for foreign students: CS101 – Introduction to Programming

ACADEMIC ACTIVITIES ■ Conference Reviewer

CVPR 2020, WACV 2021, ACCV 2020, AAAI 2021, ICRA 2021, CVPR 2021, AAAI 2022

• Chosen as one of 66 outstanding reviewers of ACCV 2020

OTHER ACTIVITIES ■ Large-scale 3D Shape Reconstruction and Segmentation from Shapenet Core55 Aug 2017 – Oct 2017

• Participated in the 3D shape segmentation from ShapeNet challenge held in ICCV 2017.

■ Korean Augmentation to the United States Army

Oct 2014 - Jul 2016

Served in the 6-52 Air Defense Artillery in U.S.Army as a translator (mandatory military duty).

LANGUAGES

■ Korean: Native language.

■ English: Fluent (speaking, reading, writing).

SKILLS

Python, MATLAB, C, C++, ROS, Docker, LATEX, PyTorch, TensorFlow, Caffe.

REFERENCES

■ Donghwan Lee

Computer Vision Team Leader @ NAVER LABS 8 Gumi-ro, Gumi 1(il)-dong, Bundang-gu, Seongnam-si, Gyeonggi-do, Korea donghwan.lee@naverlabs.com

■ Professor Changick Kim

Professor in School of Electrical Engineering,

Korea Advanced Institute of Science and Technology (KAIST)

changick@kaist.ac.kr

[CV compiled on 2022-02-05]