3_1_Lexical_Complexity_Binary_Classification_Prediction_Transformers_

April 7, 2025

```
[32]: #@title Install Packages
 []: | !pip install -q transformers
      !pip install -q torchinfo
      !pip install -q datasets
      !pip install -q evaluate
      !pip install -q nltk
      !pip install -q contractions
      !pip install -q hf_xet
      !pip install -q sentencepiece
     Traceback (most recent call last):
       File "/usr/local/lib/python3.11/dist-
     packages/pip/_internal/cli/base_command.py", line 179, in exc_logging_wrapper
         status = run_func(*args)
       File "/usr/local/lib/python3.11/dist-
     packages/pip/_internal/cli/req_command.py", line 67, in wrapper
         return func(self, options, args)
       File "/usr/local/lib/python3.11/dist-
     packages/pip/_internal/commands/install.py", line 447, in run
     ^C
     ^C
     ^C
 []: !sudo apt-get update
      ! sudo apt-get install tree
 []: #@title Imports
      import nltk
      from nltk.tokenize import RegexpTokenizer
      import contractions
      import evaluate
```

```
import transformers
     import torch
     from torchinfo import summary
     from datasets import load_dataset, Dataset, DatasetDict
     from transformers import AutoTokenizer, AutoModel, __
      AutoModelForSequenceClassification, TrainingArguments, Trainer, BertConfig, U
      →BertForSequenceClassification
     import os
     import pandas as pd
     import numpy as np
     import matplotlib.pyplot as plt
     import seaborn as sns
     import sklearn
     import spacy
     from sklearn.feature_extraction.text import TfidfVectorizer
     from sklearn.naive_bayes import MultinomialNB
     from sklearn.metrics import classification_report, __
      →precision_recall_fscore_support, accuracy_score
     import sentencepiece
     from datetime import datetime
[]: # @title Mount Google Drive
[]: from google.colab import drive
     drive.mount('/content/drive')
[]: dir_root = '/content/drive/MyDrive/266-final/'
     # dir_data = '/content/drive/MyDrive/266-final/data/'
     # dir_data = '/content/drive/MyDrive/266-final/data/se21-t1-comp-lex-master/'
     dir_data = '/content/drive/MyDrive/266-final/data/266-comp-lex-master'
     dir_models = '/content/drive/MyDrive/266-final/models/'
     dir_results = '/content/drive/MyDrive/266-final/results/'
[]: wandbai_api_key = "5236444b7e96f5cf74038116d8c1efba161a4310"
[]: !tree /content/drive/MyDrive/266-final/data/266-comp-lex-master/
[]: ||ls -R /content/drive/MyDrive/266-final/data/266-comp-lex-master/
```

[]: !tree /content/drive/MyDrive/266-final/data/266-comp-lex-master/ []: #@title Import Data []: df_names = ["train_single_df", "train_multi_df", "trial_val_single_df", "trial_val_multi_df", "test_single_df", "test_multi_df"] loaded_dataframes = {} for df_name in df_names: if "train" in df_name: subdir = "fe-train" elif "trial_val" in df_name: subdir = "fe-trial-val" elif "test" in df_name: subdir = "fe-test-labels" else: subdir = None if subdir: read_path = os.path.join(dir_data, subdir, f"{df_name}.csv") loaded_df = pd.read_csv(read_path) loaded_dataframes[df_name] = loaded_df print(f"Loaded {df_name} from {read_path}") # for df_name, df in loaded_dataframes.items(): $print(f"\n>>> \{df_name\} shape: \{df.shape\}")$ if 'binary_complexity' in df.columns: print(df['binary_complexity'].value_counts()) # print(df.info()) print(df.head())

• Functional tests pass, we can proceed with Baseline Modeling

print(f"{df_name} loaded into global namespace.")

for df_name, df in loaded_dataframes.items():

globals()[df_name] = df

0.1 Experiments with Transformers Models

```
[]: # def get_model_and_tokenizer(model_name: str):
     #
           Loads the specified pretrained model & tokenizer for classification.
     #
     #
           tokenizer = AutoTokenizer.from_pretrained(model_name)
     #
           model = AutoModelForSequenceClassification.from pretrained(model name)
           return model, tokenizer
     # new prod version to support local model checkpoints, to be used after
      \rightarrow experiment 1.0
     def get model and tokenizer(
         remote_model_name: str = None,
         local_model_path: str = None
     ):
         Loads the model & tokenizer for classification.
         If 'local_model_path' is specified, load from that path.
         Otherwise, fall back to 'remote_model_name'.
         11 11 11
         from transformers import AutoTokenizer, AutoModelForSequenceClassification
         if local model path:
             # Local load
             print(f"Loading from local path: {local_model_path}")
             tokenizer = AutoTokenizer.from_pretrained(local_model_path)
             model = AutoModelForSequenceClassification.
      →from_pretrained(local_model_path)
         elif remote model name:
             # Load from HF Hub
             print(f"Loading from Hugging Face model: {remote model name}")
             tokenizer = AutoTokenizer.from_pretrained(remote_model_name)
             model = AutoModelForSequenceClassification.
      →from_pretrained(remote_model_name)
         else:
             raise ValueError("You must provide either a remote model name or aL
      ⇔local_model_path!")
         return model, tokenizer
```

```
[]: def freeze_unfreeze_layers(model, layers_to_unfreeze=None):
    """

    Toggles requires_grad = False for all parameters
    except for those whose names contain any string in layers_to_unfreeze.
    By default, always unfreeze classifier/heads.
    """
```

```
if layers_to_unfreeze is None:
    layers_to_unfreeze = ["classifier.", "pooler."]

for name, param in model.named_parameters():
    # If any layer substring matches, we unfreeze
    if any(substring in name for substring in layers_to_unfreeze):
        param.requires_grad = True
    else:
        param.requires_grad = False
```

```
[]: def prepare_dataset(df, tokenizer, text_col, label_col, max_length=256):
         Converts a Pandas DataFrame to a Hugging Face Dataset,
         then applies 'encode_examples' to tokenize.
         11 11 11
         # Convert to HF Dataset
         dataset = Dataset.from_pandas(df)
         # Map the encode function
         dataset = dataset.map(
             lambda batch: encode_examples(batch, tokenizer, text_col, max_length),
             batched=True
         )
         # Rename the label column to 'labels' for HF Trainer
         dataset = dataset.rename_column(label_col, "labels")
         # HF often requires removing any columns that cannot be converted or are
      ⇔not needed
         dataset.set_format(type='torch',
                            columns=['input_ids', 'attention_mask', 'labels'])
         return dataset
```

```
[ ]: def compute_metrics(eval_pred):
         Computes classification metrics, including accuracy, precision, recall, and \Box
         11 11 11
         logits, labels = eval_pred
         preds = np.argmax(logits, axis=1)
         metric_accuracy = evaluate.load("accuracy")
         metric_precision = evaluate.load("precision")
         metric_recall = evaluate.load("recall")
                        = evaluate.load("f1")
         metric_f1
         accuracy_result = metric_accuracy.compute(predictions=preds,__
      →references=labels)
         precision_result = metric_precision.compute(predictions=preds,__
      →references=labels, average="binary")
         recall_result
                        = metric_recall.compute(predictions=preds,__
      →references=labels, average="binary")
         f1_result
                          = metric_f1.compute(predictions=preds, references=labels,__
      ⇔average="binary")
         return {
             "accuracy" : accuracy_result["accuracy"],
             "precision": precision_result["precision"],
             "recall" : recall_result["recall"],
             "f1"
                        : f1 result["f1"]
         }
```

0.1.1 Experiment Design

```
named_model = "bert-base-cased"
# named_model = "roberta-base"
# named_model = "bert-large"
# named_model = "roberta-large"
# named_model = "roberta-large"
# named_model = "" # modern bert

# learning_rate = 1e-3
# learning_rate = 1e-4
# learning_rate = 1e-5
# learning_rate = 5e-6
learning_rate = 5e-7
# learning_rate = 5e-8
# num_epochs = 3
```

```
num_epochs = 5
# num_epochs = 10
# num_epochs = 15
# num_epochs = 20
length_max = 128
\# length_max = 256
\# length_max = 348
\# length_max = 512
# size batch = 1
# size_batch = 4
size_batch = 8
# size_batch = 16
# size_batch = 24
# size_batch = 32
regularization_weight_decay = 0
# regularization_weight_decay = 0.1
# regularization_weight_decay = 0.5
# dropout???
# layers to freeze and unfreeze?
y_col = "binary_complexity"
\# y\_col = "complexity"
x_task = "single"
# x_task = "multi"
# x_col = "sentence"
x_col = "sentence_no_contractions"
# x_col = "pos_sequence"
# x_col = "dep_sequence"
# x_col = "morph_sequence"
if x_task == "single":
   df_train = train_single_df
   df_val = trial_val_single_df
   df_test = test_single_df
else:
   df_train = train_multi_df
   df_val = trial_val_multi_df
   df_test = test_multi_df
```

```
[]: def train_transformer_model(
         model,
         tokenizer,
         train_dataset,
         val_dataset,
         output_dir=dir_results,
         num_epochs=num_epochs,
         batch_size=size_batch,
         lr=learning_rate,
         weight_decay=regularization_weight_decay
     ):
         Sets up a Trainer and trains the model for 'num_epochs' using the given ⊔
      \hookrightarrow dataset.
         Returns the trained model and the Trainer object for possible re-use or_{\sqcup}
      \hookrightarrow analysis.
         11 11 11
         training_args = TrainingArguments(
             output_dir=output_dir,
             num_train_epochs=num_epochs,
             per_device_train_batch_size=batch_size,
             per_device_eval_batch_size=batch_size,
             evaluation_strategy="epoch",
             save_strategy="no",
             logging_strategy="epoch",
             learning_rate=lr,
             weight_decay=weight_decay,
             report_to=["none"], # or "wandb"
         )
         trainer = Trainer(
             model=model,
             args=training_args,
             train_dataset=train_dataset,
             eval_dataset=val_dataset,
             tokenizer=tokenizer, # optional
             compute_metrics=compute_metrics
         )
         trainer.train()
         return model, trainer
```

0.1.2 1.0: from pretrained bert-base-cased single task 1 Model Inspection

```
[]: print("model checkpoints:", dir_models)
    !ls /content/drive/MyDrive/266-final/models/
[]: # Load Model & Tokenizer
     \# model, tokenizer = get model and tokenizer(named_model) \# deprecated argument
      \hookrightarrowstructure
    model, tokenizer = get_model_and_tokenizer("/content/drive/MyDrive/266-final/
     →models/....") # proposed argument usage for checkpointed models
    for name, param in model.named_parameters():
        print(name)
    print("=======")
    print(named_model, ":")
    print("======")
    print(model)
    print("=======")
    print(model.config)
    print("======")
    print("num_parameters:", model.num_parameters())
    print("======")
    print("num_trainable_parameters:", model.num_parameters(only_trainable=True))
```

Layer Configuration

```
[]: # Freeze/Unfreeze Layers & Additional Configuration Parameters
     import torch.nn as nn
     layers_to_unfreeze = [
         "bert.encoder.layer.9.",
         "bert.encoder.layer.10.",
         "bert.encoder.layer.11.",
         "pooler.",
         "classifier.",
     1
     freeze_unfreeze_layers(model, layers_to_unfreeze=layers_to_unfreeze)
     bert_config = BertConfig(
         # vocab_size=28996,
        hidden size=768,
         # num_hidden_layers=12,
         # num_attention_heads=12,
         # intermediate_size=3072,
         intermediate_size=6144,
         # max_position_embeddings=512,
```

```
type_vocab_size=2,
   hidden_dropout_prob=0.1,
   attention_probs_dropout_prob=0.1,
   # classifier_dropout=None,
   # initializer_range=0.02,
   # layer_norm_eps=1e-12,
   hidden act="gelu",
   gradient_checkpointing=True,
   position_embedding_type="absolute",
   use_cache=True,
   pad_token_id=0
)
model.bert.pooler.activation = nn.ReLU() # Tanh() replaced as the pooler layer
 ⇔activation function
for name, param in model.named_parameters():
   print(name, "requires_grad=", param.requires_grad)
print("\nLayers that are 'True' are trainable. 'False' are frozen.")
print("=======")
print(named_model, ":")
print("======")
print(model)
print("=======")
print(model.config)
print("======")
print("num_parameters:", model.num_parameters())
print("======")
print("num_trainable_parameters:", model.num_parameters(only_trainable=True))
```

Dataset Preparation

```
train_data_hf = prepare_dataset(
    df_train,
    tokenizer,
    text_col=x_col,
    label_col=y_col,
    max_length=length_max
)

val_data_hf = prepare_dataset(
    df_val,
```

```
tokenizer,
  text_col=x_col,
  label_col=y_col,
  max_length=length_max
)

test_data_hf = prepare_dataset(
  df_test,
  tokenizer,
  text_col=x_col,
  label_col=y_col,
  max_length=length_max
)

print("Datasets prepared. Sample from train_data_hf:\n", train_data_hf[10])
print("Datasets prepared. Sample from train_data_hf:\n", val_data_hf[10])
print("Datasets prepared. Sample from train_data_hf:\n", test_data_hf[10])
```

1.0 Results

```
[]: # Train & Evaluate
     trained_model, trainer_obj = train_transformer_model(
         model=model,
         tokenizer=tokenizer,
         train_dataset=train_data_hf,
         val_dataset=val_data_hf,
         output_dir=dir_results,
         num_epochs=num_epochs,
         batch_size=size_batch,
         lr=learning_rate,
         weight_decay=regularization_weight_decay
     )
     metrics = trainer_obj.evaluate()
     print("Validation metrics:", metrics)
     test_metrics = trainer_obj.evaluate(test_data_hf) if test_data_hf else None
     print("Test metrics:", test_metrics)
```

```
[]: print("Experiment configuration used with this experiment:")
    print("model used:", named_model)
    print("learning rate used:", learning_rate)
    print("number of epochs:", num_epochs)
    print("maximum sequence length:", length_max)
    print("batch size used:", size_batch)
    print("regularization value:", regularization_weight_decay)
```

```
print("outcome variable:", y_col)
print("task:", x_task)
print("input column:", x_col)
```

```
[]: # save model checkpoint

timestamp = datetime.now().strftime("%Y%m%d_%H%M%S")

model_save_path = os.path.join(dir_models,__
of"{x_task}_{named_model}_{y_col}_{timestamp}")

trainer_obj.save_model(model_save_path)
print(f"Model checkpoint saved to: {model_save_path}")
```

0.1.3 Experiment 1.1: from checkpoint bert-base-cased single task 1

```
[]: # Define Experiment Parameters
     named_model = "bert-base-cased"
     # named_model = "roberta-base"
     # named_model = "bert-large"
     # named_model = "roberta-large"
     # named_model = "" # modern bert
     # learning rate = 1e-3
     # learning_rate = 1e-4
     # learning_rate = 1e-5
     # learning_rate = 5e-6
     # learning_rate = 5e-7
     learning_rate = 1e-8
     # num_epochs = 3
     num_epochs = 5
     # num_epochs = 10
     # num_epochs = 15
     # num_epochs = 20
     length_max = 128
     \# length_max = 256
     \# length_max = 348
     \# length_max = 512
     # size_batch = 1
     size batch = 4
     # size_batch = 8
     # size batch = 16
     # size_batch = 24
     # size_batch = 32
```

```
# regularization_weight_decay = 0
    regularization_weight_decay = 0.1
     # regularization_weight_decay = 0.5
    y_col = "binary_complexity"
    \# y\_col = "complexity"
    x_task = "single"
    \# x_task = "multi"
    # x col = "sentence"
    x_col = "sentence_no_contractions"
    # x_col = "pos_sequence"
    # x_col = "dep_sequence"
     # x_col = "morph_sequence"
    if x_task == "single":
        df_train = train_single_df
        df_val = trial_val_single_df
        df_test = test_single_df
    else:
        df_train = train_multi_df
        df_val = trial_val_multi_df
        df_test = test_multi_df
[]: # Load Model & Tokenizer
    model, tokenizer = get_model_and_tokenizer(named_model) # deprecated argument_
     \hookrightarrowstructure
     # model, tokenizer = qet_model_and_tokenizer("/content/drive/MyDrive/266-final/
     -models/bert-base-cased_20250407_232900") # proposed argument usage for
     ⇔checkpointed models
     # for name, param in model.named_parameters():
          print(name)
    print("=======")
    print(named_model, ":")
    print("=======")
    # print(model)
    print("=======")
    print(model.config)
     # print("======")
     # print("num_parameters:", model.num_parameters())
     # print("======"")
     # print("num_trainable_parameters:", model.num_parameters(only_trainable=True))
```

```
[]: # Freeze/Unfreeze Layers & Additional Configuration Parameters
     import torch.nn as nn
     layers_to_unfreeze = [
         "bert.embeddings.",
         "bert.encoder.layer.0.",
         "bert.encoder.layer.1.",
         "bert.encoder.layer.9.",
         "bert.encoder.layer.9.",
         "bert.encoder.layer.10.",
         "bert.encoder.layer.11.",
         "bert.pooler.",
         "classifier.",
     ]
     freeze_unfreeze_layers(model, layers_to_unfreeze=layers_to_unfreeze)
     bert_config = BertConfig(
         # vocab_size=28996,
        hidden_size=768,
         # num_hidden_layers=12,
         # num_attention_heads=12,
         intermediate_size=6144,
         # max_position_embeddings=512,
         type_vocab_size=2,
         hidden_dropout_prob=0.1,
         attention_probs_dropout_prob=0.1,
         # classifier_dropout=None,
         # initializer_range=0.02,
         # layer_norm_eps=1e-12,
         hidden_act="gelu",
         gradient_checkpointing=True,
         position_embedding_type="absolute",
         use_cache=True,
         pad_token_id=0
     )
     model.bert.pooler.activation = nn.ReLU() # Tanh() replaced as the pooler layer
      →activation function
     for name, param in model.named_parameters():
         print(name, "requires_grad=", param.requires_grad)
```

```
[]: # Train & Evaluate
     trained_model, trainer_obj = train_transformer_model(
         model=model,
         tokenizer=tokenizer,
         train_dataset=train_data_hf,
         val_dataset=val_data_hf,
         output_dir=dir_results,
         num_epochs=num_epochs,
         batch_size=size_batch,
         lr=learning_rate,
         weight_decay=regularization_weight_decay
     )
     metrics = trainer_obj.evaluate()
     print("Validation metrics:", metrics)
     test_metrics = trainer_obj.evaluate(test_data_hf) if test_data_hf else None
     print("Test metrics:", test_metrics)
[]: print("Experiment configuration used with this experiment:")
```

```
[]: print("Experiment configuration used with this experiment:")
    print("model used:", named_model)
    print("learning rate used:", learning_rate)
    print("number of epochs:", num_epochs)
    print("maximum sequence length:", length_max)
    print("batch size used:", size_batch)
    print("regularization value:", regularization_weight_decay)
    print("outcome variable:", y_col)
    print("task:", x_task)
    print("input column:", x_col)
```

```
[]: # save model checkpoint
```

0.1.4 Experiment 1.2: from pre-trained bert-base-cased multi task 2

```
[]: # Define Experiment Parameters
     named_model = "bert-base-cased"
     # named model = "roberta-base"
     # named_model = "bert-large"
     # named_model = "roberta-large"
     # named_model = "" # modern bert
     # learning_rate = 1e-3
     # learning_rate = 1e-4
     # learning_rate = 1e-5
     # learning_rate = 5e-6
     # learning_rate = 5e-7
     learning_rate = 1e-8
     # num_epochs = 3
     num_epochs = 5
     # num_epochs = 10
     # num epochs = 15
     # num_epochs = 20
     length_max = 128
     # length max = 256
     \# length_max = 348
     \# length_max = 512
     # size_batch = 1
     size_batch = 4
     # size_batch = 8
     \# size_batch = 16
     # size_batch = 24
     # size_batch = 32
     # regularization_weight_decay = 0
     regularization_weight_decay = 0.1
     # regularization_weight_decay = 0.5
     y_col = "binary_complexity"
```

```
# x_task = "single"
    x_task = "multi"
    # x_col = "sentence"
    x_col = "sentence_no_contractions"
    # x_col = "pos_sequence"
     # x_col = "dep_sequence"
     # x_col = "morph_sequence"
    if x_task == "single":
        df_train = train_single_df
        df_val = trial_val_single_df
        df_test = test_single_df
    else:
        df_train = train_multi_df
        df_val
                = trial_val_multi_df
        df_test = test_multi_df
[]: print("model checkpoints:", dir_models)
    !ls /content/drive/MyDrive/266-final/models/
[]: # Load Model & Tokenizer
    model, tokenizer = get_model_and_tokenizer(named_model) # deprecated argument_
     \hookrightarrow structure
     # model, tokenizer = get_model_and_tokenizer("/content/drive/MyDrive/266-final/
     models/bert-base-cased 20250407 232900") # proposed argument usage for
     ⇔checkpointed models
     # for name, param in model.named_parameters():
          print(name)
    print("=======")
    print(named_model, ":")
    print("=======")
    # print(model)
    print("======")
    print(model.config)
     # print("======")
     # print("num_parameters:", model.num_parameters())
     # print("======"")
     # print("num_trainable_parameters:", model.num_parameters(only_trainable=True))
[]: # Freeze/Unfreeze Layers & Additional Configuration Parameters
    import torch.nn as nn
```

 $\# y_col = "complexity"$

```
layers_to_unfreeze = [
   "bert.embeddings.",
    "bert.encoder.layer.0.",
   "bert.encoder.layer.1.",
   "bert.encoder.layer.9.",
    "bert.encoder.layer.9.",
   "bert.encoder.layer.10.",
   "bert.encoder.layer.11.",
    "bert.pooler.",
    "classifier.",
]
freeze_unfreeze_layers(model, layers_to_unfreeze=layers_to_unfreeze)
bert_config = BertConfig(
    # vocab_size=28996,
   hidden_size=768,
    # num_hidden_layers=12,
   # num_attention_heads=12,
   intermediate_size=6144,
   # max_position_embeddings=512,
   type_vocab_size=2,
   hidden dropout prob=0.1,
   attention_probs_dropout_prob=0.1,
   # classifier_dropout=None,
   # initializer_range=0.02,
   # layer_norm_eps=1e-12,
   hidden_act="gelu",
   gradient_checkpointing=True,
   position_embedding_type="absolute",
   use_cache=True,
   pad_token_id=0
)
model.bert.pooler.activation = nn.ReLU() # Tanh() replaced as the pooler layer_
→activation function
for name, param in model.named_parameters():
   print(name, "requires_grad=", param.requires_grad)
print("\nLayers that are 'True' are trainable. 'False' are frozen.")
print("=======")
```

```
print(named_model, ":")
print("======")
print(model)
print(model.config)
print("========")
print("num_parameters:", model.num_parameters())
print("=======")
print("num_trainable_parameters:", model.num_parameters(only_trainable=True))
```

1.2 Results

```
[]: # Train & Evaluate
     trained_model, trainer_obj = train_transformer_model(
         model=model.
         tokenizer=tokenizer,
         train dataset=train data hf,
         val_dataset=val_data_hf,
         output dir=dir results,
         num_epochs=num_epochs,
         batch_size=size_batch,
         lr=learning_rate,
         weight_decay=regularization_weight_decay
     )
     metrics = trainer_obj.evaluate()
     print("Validation metrics:", metrics)
     test_metrics = trainer_obj.evaluate(test_data_hf) if test_data_hf else None
     print("Test metrics:", test_metrics)
[]: print("Experiment configuration used with this experiment:")
```

```
[]: print("Experiment configuration used with this experiment:")
    print("model used:", named_model)
    print("learning rate used:", learning_rate)
    print("number of epochs:", num_epochs)
    print("maximum sequence length:", length_max)
    print("batch size used:", size_batch)
    print("regularization value:", regularization_weight_decay)
    print("outcome variable:", y_col)
    print("task:", x_task)
    print("input column:", x_col)
```

```
trainer_obj.save_model(model_save_path)
print(f"Model checkpoint saved to: {model_save_path}")
```

0.1.5 Experiment 1.3: from checkpoint 1.0 or 1.1 bert-base-cased MSFT'd single -> multi

```
[]: # Define Experiment Parameters
     named_model = "bert-base-cased"
     # named_model = "roberta-base"
     # named_model = "bert-large"
     # named_model = "roberta-large"
     # named model = "" # modern bert
     # learning rate = 1e-3
     # learning_rate = 1e-4
     # learning_rate = 1e-5
     \# learning_rate = 5e-6
     # learning_rate = 5e-7
     learning_rate = 1e-8
     # num_epochs = 3
     num_epochs = 5
     # num_epochs = 10
     # num_epochs = 15
     # num_epochs = 20
     length_max = 128
     \# length_max = 256
     # length max = 348
     \# length_max = 512
     \# size_batch = 1
     size_batch = 4
     # size_batch = 8
     # size_batch = 16
     # size_batch = 24
     \# size_batch = 32
     # regularization_weight_decay = 0
     regularization_weight_decay = 0.1
     \# regularization\_weight\_decay = 0.5
     y_col = "binary_complexity"
     \# y\_col = "complexity"
```

```
# x_task = "single"
    x_task = "multi"
    # x_col = "sentence"
    x_col = "sentence_no_contractions"
    # x_col = "pos_sequence"
     # x_col = "dep_sequence"
     # x_col = "morph_sequence"
    if x_task == "single":
        df_train = train_single_df
        df_val = trial_val_single_df
        df_test = test_single_df
    else:
        df_train = train_multi_df
        df_val = trial_val_multi_df
        df_test = test_multi_df
[]: print("model checkpoints:", dir_models)
    !ls /content/drive/MyDrive/266-final/models/
[]: # Load Model & Tokenizer
     # model, tokenizer = get_model_and_tokenizer(named_model) # deprecated argument_
    model, tokenizer = get_model_and_tokenizer("/content/drive/MyDrive/266-final/
     →models/....") # proposed argument usage for checkpointed models
     # for name, param in model.named_parameters():
         print(name)
    print("=======")
    print(named model, ":")
    print("======")
    # print(model)
    print("======")
    print(model.config)
    # print("======")
     # print("num_parameters:", model.num_parameters())
     # print("======")
     # print("num_trainable_parameters:", model.num_parameters(only_trainable=True))
[]: | # Freeze/Unfreeze Layers & Additional Configuration Parameters
    import torch.nn as nn
    layers_to_unfreeze = [
        "bert.embeddings.",
```

```
"bert.encoder.layer.0.",
    "bert.encoder.layer.1.",
    "bert.encoder.layer.9.",
    "bert.encoder.layer.9.",
   "bert.encoder.layer.10.",
    "bert.encoder.layer.11.",
    "bert.pooler.",
   "classifier.",
]
freeze_unfreeze_layers(model, layers_to_unfreeze=layers_to_unfreeze)
bert_config = BertConfig(
    # vocab_size=28996,
   hidden_size=768,
    # num_hidden_layers=12,
   # num_attention_heads=12,
   intermediate_size=6144,
    # max_position_embeddings=512,
   type_vocab_size=2,
   hidden_dropout_prob=0.1,
   attention probs dropout prob=0.1,
   # classifier_dropout=None,
   # initializer range=0.02,
   # layer_norm_eps=1e-12,
   hidden_act="gelu",
   gradient_checkpointing=True,
   position_embedding_type="absolute",
   use_cache=True,
   pad_token_id=0
)
model.bert.pooler.activation = nn.ReLU() # Tanh() replaced as the pooler layer_
 ⇔activation function
for name, param in model.named_parameters():
   print(name, "requires_grad=", param.requires_grad)
print("\nLayers that are 'True' are trainable. 'False' are frozen.")
print("======")
print(named model, ":")
print("=======")
print(model)
```

```
print("=======")
print(model.config)
print("========")
print("num_parameters:", model.num_parameters())
print("=========")
print("num_trainable_parameters:", model.num_parameters(only_trainable=True))
```

1.3 Results

```
trained_model, trainer_obj = train_transformer_model(
    model=model,
    tokenizer=tokenizer,
    train_dataset=train_data_hf,
    val_dataset=val_data_hf,
    output_dir=dir_results,
    num_epochs=num_epochs,
    batch_size=size_batch,
    lr=learning_rate,
    weight_decay=regularization_weight_decay
)

metrics = trainer_obj.evaluate()
print("Validation metrics:", metrics)

test_metrics = trainer_obj.evaluate(test_data_hf) if test_data_hf else None
print("Test metrics:", test_metrics)
```

```
[]: print("Experiment configuration used with this experiment:")
    print("model used:", named_model)
    print("learning rate used:", learning_rate)
    print("number of epochs:", num_epochs)
    print("maximum sequence length:", length_max)
    print("batch size used:", size_batch)
    print("regularization value:", regularization_weight_decay)
    print("outcome variable:", y_col)
    print("task:", x_task)
    print("input column:", x_col)
```

```
[]: # save model checkpoint

timestamp = datetime.now().strftime("%Y%m%d_%H%M%S")
model_save_path = os.path.join(dir_models,__
of"{x_task}_{named_model}_{y_col}_{timestamp}")

trainer_obj.save_model(model_save_path)
print(f"Model checkpoint saved to: {model_save_path}")
```

[]:[