# Analysis III

## **Homework**

Exercises (homework) can be found in the script at the end of each Chapter.

Chapter I: #3 (only for convex sets), #4 due Th 4-25

Chapter II: # 2,4,5,6 due Th 5-2 Chapter III: # 3c, 4 due Th 5-9 Chapter IV: # 2b, 3, 4, 6 due Th 5-16 Chapter V: # 2,4,6 due Th 5-25 Chapter VI: # 2,3,4 due Th 6-1

## **Key Dates**

Instruction begins: Mo, April 1
Instruction ends: Fr, June 7
Final's week: June 10, 12 (Mo Th

Final's week: June 10-13 (Mo-Th)

Holiday: Mo, May 27

# **April 2, 2024**

No class Thursday, April 04. Makeup class (tentatively) on Friday, April 12 at 10:30. Discussion sections on Fridays (tentatively) at 11:40.

# **Topological Vector Spaces**

# **Definition: Vector Spaces**

V over a field  $\mathbb{F}$  ( $\mathbb{R}$  or  $\mathbb{C}$ ).

# **Definition: Topological Spaces**

 $(X, \tau)$  where  $\tau \subseteq \mathcal{P}(X)$  satisfying

- 1.  $\emptyset, X \in \tau$
- 2.  $A, B \in \tau \implies A \cap B \in \tau$
- 3.  $A_{\omega} \in \tau \implies \bigcup_{\omega} A_{\omega} \in \tau$

Recall:  $A \in \tau \iff A \text{ open } \iff X \setminus A \text{ closed.}$ 

 $A^{\circ} = \bigcup_{\substack{U \subseteq A \\ U \text{ open}}} U$  the set of interior points of A.

 $\overline{A} = \bigcap_{\substack{F \supseteq A \\ F \text{ closed}}} \text{ the closure of } A.$ 

A' limit points of A.

Compact sets.

Locally compact sets.

Recall: *X* is Hausdorff iff  $\forall x, y \in X$ ,  $\exists U, V \in \tau$  such that  $x \in U$ ,  $y \in V$  and  $U \cap V = \emptyset$ .

## **Definition: Bases for Topological Spaces**

Definition: Let  $(X, \tau)$  be a topological space.  $\sigma \subseteq \tau$  is called a base for topology  $\tau$  if  $\forall x \in X, \ \forall U \in \tau, \ x \in U, \ \exists W \in \sigma$  such that  $x \in W \subseteq U$ .

## **Proposition**

 $\sigma \subseteq \tau$  is a base for  $\tau$  if and only if every  $U \in \tau$  is the union of certain sets taken from  $\sigma$ .

$$(*) \quad \tau = \left\{ \bigcup_{\omega \in \Omega} W_{\omega} : \{W_{\omega}\}_{\omega \in \Omega} \subseteq \sigma, \Omega \right\}$$

#### **Proof**

(⇐=) ✓

 $(\Longrightarrow)$  Take  $U \in \tau$  and let  $x \in U$ ,  $\leadsto$  find  $W_x \in \sigma$ ,  $x \in W_x \subseteq U$ .

$$U = \bigcup_{x \in U} \{x\} \subseteq \bigcup_{x \in U} W_x \subseteq U$$

Therefore  $\bigcup_{x \in U} W_x = U$ .

## **Proposition**

If  $\sigma$  is a base for some topology  $\tau$  on X, then

- 1.  $\forall x \in X, \exists W \in \sigma \text{ such that } x \in W.$
- 2.  $\forall U, V \in \sigma$ ,  $\forall x \in U \cap V$ ,  $\exists W \in \sigma$  such that  $x \in W \subseteq U \cap V$ .

Conversely, if  $\sigma \in \mathcal{P}(X)$  ( $\varnothing \notin \sigma$ ) satisfies (1) and (2), then  $\sigma$  is the base for a topology  $\tau$  (and  $\tau$  is given by (\*)). Note that  $U, V \in \tau \implies U \cap V \in \tau$  (requires (2)). If  $U = \bigcup U_{\alpha}$  and  $V = \bigcup V_{\beta}$ , then  $U \cap V = \bigcup_{\alpha,\beta} (U_{\alpha} \cap V_{\beta}) = \bigcup_{\alpha,\beta} \bigcup_{x \in U} W_{\alpha,\beta,x}$ .

# **Example: Metric Spaces**

(X, d) is a metric space if  $d: X \times X \to [0, +\infty)$  satisfies

- 1. d(x, y) = 0 if and only if x = y.
- 2. d(x, y) = d(y, x).
- 3.  $d(x,z) \le d(x,y) + d(y,z)$  (triangle inequality).

# **Definition: Epsilon Neighborhoods**

$$B_{\varepsilon}(x) = \{ y \in x : d(x, y) < \varepsilon \}$$

 $A \subseteq X$  is open if and only if  $\forall x \in A, \exists \varepsilon > 0$  such that  $B_{\varepsilon}(x) \subseteq A. \ x \in B_{\varepsilon}(x)$ .

 $\tau$  = set of all open sets.

$$\sigma_1 = \{B_{\varepsilon}(x) : x \in X, ; \varepsilon > 0\}$$

is a base for the topology  $\tau$ .

$$\sigma_2 = \left\{ B_{1/n}(x) : x \in X, \ n \in \mathbb{N} \right\}$$

is also a base for  $\tau$ .

## **Definition: Direct Product - Product Topology**

Let  $(X_1, \tau_1)$  and  $(X_2, \tau_2)$  be topological spaces. Consider  $X = X_1 \times X_2$ . The product topology  $\tau$  on X is given by the base

$$\sigma = \{U_1 \times U_2 : U_1 \in \tau_1, U_2 \in \tau_2\}$$

More explicitly,

$$\tau = \left\{ \bigcup_{\omega} U_{1,\omega} \times U_{2,\omega} : U_{i,\omega} \in \tau_i \right\}$$

 $(X_{\omega}, \tau_{\omega})$  topological spaces  $(\omega \in \Omega)$ 

$$X = \prod_{\omega \in \Omega} = \{(x_{\omega})_{\omega \in \Omega} : x_{\omega} \in X_{\omega}\}$$

Formally,  $f \cong (x_{\omega})_{\omega \in \Omega}$ ,  $x_{\omega} = f(\omega)$ ,  $f : \Omega \to \bigcup_{\omega \in \Omega} X_{\omega}$  such that  $f(\omega) \in X_{\omega}$ .  $[x \neq \emptyset \longleftarrow X_{\omega} \neq \emptyset \text{ axiom of choice}]$ 

$$\sigma = \left\{ \prod_{\omega \in \Omega} U_{\omega} \, : \, U_{\omega} \in \tau_{\omega} \text{ and all but finitely many } U_{\omega} = X_{\omega} \right\}$$

# **Definition: Subspace Topology**

Given  $(X, \tau)$  and  $Y \subseteq X$ , then  $(Y, \tau_Y)$  is also a topological space where

$$\tau_Y\{U\cap Y:U\in\tau\}$$

# **Definition: Local Bases for Topological Spaces**

A collection  $\gamma \subseteq \tau$  is called a local base at  $x \in X$  if

- 1.  $\forall U \in \tau$ ,  $x \in U$ ,  $\exists W \in \gamma$  such that  $x \in W \subseteq U$ .
- 2.  $\forall W \in \gamma, x \in W$

## **Example**

Let (X, d) be a metric space.

$$\gamma_x = \{B_{\varepsilon}(x) : \varepsilon > 0\}$$

is a local base at x. Similarly,

$$\tilde{\gamma}_x = \{B_{1/n} : n \in \mathbb{N}\}$$

is a countable local base.

## **Proposition**

If  $\gamma_x$  ( $x \in X$ ) are local bases for  $\tau$  at X, then

$$\sigma = \bigcup_{x \in X} \gamma_x$$

is a bse for  $\tau$ .

## **Proposition**

 $\{\gamma_x\}_{x\in X}$  are local bases at x for some topology  $\tau$  if and only if

- 1.  $\forall x \in X$ ,  $\gamma_x$  is a non-empty collection of subsets containing x.
- 2. If  $U \in \gamma_x$ ,  $V \in \gamma_y$ , and  $z \in U \cap V$ , then  $\exists W \in \gamma_z$  such that  $z \in W \subseteq U \cap V$ .

# **Definition: Topological Vector Spaces**

Suppose V is a vector space over  $\mathbb{F} = \mathbb{R}$ ,  $\mathbb{C}$  and let  $\tau$  be a topology on V. Then V is a topological vector space (TVS) if

- 1.  $\forall x \in V$ ,  $\{x\}$  is closed.
- 2. The functions f, g (i.e. algebraic operations) are continuous.

$$f: V \times V \to V, f(x, y) = x + y$$
  
 $g: \mathbb{F} \times V \to V, g(\lambda, x) = \lambda \cdot x$ 

### **Notation**

For  $A_1, A_2 \subseteq V$  and  $B \subseteq \mathbb{F}$ ,

$$A_1 + A_2 = \{ a_1 + a_2 : a_1 \in A_1, a_2 \in A_2 \}$$

$$a + A_1 = \{ a + \alpha : \alpha \in A \}$$

$$B \cdot A = \{ \beta \cdot a : \beta \in B, a \in A \}$$

$$\alpha \cdot A = \{ \alpha \cdot a : a \in A \}$$

## Lemma

Let V be a TVS. Then

- 1.  $\forall x, y \in V$ ,  $\forall$  open  $U_{x+y} \ni x + y$ ,  $\exists$  open  $U_x \ni x$ , open  $U_y \ni y$  such that  $U_x + U_y \subseteq U_{x+y}$ .
- 2.  $\forall x \in V, \alpha \in \mathbb{F}, \forall \text{ open } U_{\alpha x} \ni \alpha x, \exists \text{ open } U_x \ni x, U_\alpha \ni \alpha \text{ such that } U_\alpha \cdot U_x \subseteq U_{\alpha x}.$

#### Proof of 1

Given  $x, y \in X$ ,  $x + y \in U_{x+y}$  open.

$$f(x,y) = x + y \in U_{x+y}$$

and  $(x,y) \in f^{-1}(U_{x+y})$  open. In the product topology

$$(x,y) \in U_x \times U_y \subseteq f^{-1}(U_{x+y})$$

which implies  $x \in U_x$  and  $y \in U_y$ , both open, and  $U_x + U_y \le U_{x+y}$ .

# **April 9, 2024**

Office Hours: Th 11:30 AM - 1:00 PM

Makeup Class: Friday, April 12 at 11:00 AM.

## Lemma 1

Let V be a TVS

- 1.  $\forall x, y \in V, \ \forall U_{x+y} \ni x+y \ \text{open}, \ \exists U_x \ni x, U_y \ni y \ \text{such that} \ U_x + U_y \subseteq U_{x+y}.$
- 2.  $\forall \alpha \in F, \ \forall U_{\alpha x} \ni \alpha x \text{ open, } \exists U_{\alpha} \ni \alpha \text{ open in } F, \ U_{x} \ni x \text{ such that } U_{\alpha} \cdot U_{x} \subseteq U_{\alpha x}.$

For 2. with  $\alpha = 0$ ,  $\forall x \in X$ ,  $\forall U \ni 0$  open,  $\exists \delta > 0$ ,  $U_x \ni x$  open such that  $B_\delta(0) \cdot U_x \subseteq U$ . That is,  $\beta U_x \subseteq U$ ,  $\forall |\beta| < \delta$ .

# **Proposition**

In a TVS, the maps

- 1. Translation:  $T_a: x \in V \mapsto X + a \in V \ (a \in V)$
- 2. Multiplication:  $M_{\lambda}: x \in V \mapsto \lambda \cdot x \in V \ (\lambda \in \mathbb{F}, \ \lambda \neq 0)$

are continuous (in fact, homeomorphic).

#### **Proof**

We know  $(x, y) \mapsto x + y$  and  $(\lambda, x) \mapsto \lambda \cdot x$  are continuous.

#### **Inversions**

 $T_a \circ T_{-a} = \mathrm{id}, \ T_{-a} \circ T_a = \mathrm{id}, \ M_\lambda \circ M_{1/\lambda} = \mathrm{id}, \ \mathrm{and} \ M_{1/\lambda} \circ M_\lambda = \mathrm{id}.$ 

Therefore they are bijective and the inverses are continuous.

## Remark

If U is open, then a + U is also open.

If  $\gamma_0$  is a local base at 0, then  $\gamma_x = \{x + U : U \in \gamma_0\} = x + \gamma_0$  is a local base at x.

Recall that  $\gamma_x$  is a local base at x if  $\forall W \ni x$  open,  $\exists U \in \gamma_x$  such that  $x \in U \subseteq W$ .

That is, in a TVS only local base at 0 are needed. We may interpret "local base" as "local base at 0".

$$\sigma = \bigcup_{x \in V} (x + \gamma_0)$$

is a base for the TVS.

# **Types of Topologial Vector Spaces**

## **Normed Spaces / Banach Spaces**

A normed space is a vector space over  $\mathbb{F}$  together with a norm  $||\cdot||$ , i.e. a map  $||\cdot||: x \in V \mapsto ||x|| \in [0, \infty)$  such that

- 1.  $||x|| = 0 \iff x = 0$ .
- 2.  $||x + y|| \le ||x|| + ||y||$ .
- 3.  $||\lambda x|| = |\lambda| \cdot ||x||$ .

#### Remarks

A normed space is a metric space with d(x, y) = ||x - y||.

A local base (at 0) is given by  $\varepsilon$ -neighborhoods:

$$\gamma_0 = \{B_{\varepsilon}(0) : \varepsilon > 0\}$$

where

$$B_{\varepsilon}(0) = \{ x \in V : ||x|| < \varepsilon \}$$

(open ball with radius  $\varepsilon > 0$ ).

## **Convergence in Normed Space**

A sequence  $\{x_n\}$   $(x_n \in V)$  converges to  $\lambda \in V$  if  $\lim_{n\to\infty} ||x_n - x|| = 0$ .

A sequence  $\{x_n\}$  is Cauchy if  $\forall \varepsilon > 0$ ,  $\exists N$  such that  $\forall j, k \ge N$ ,  $||x_j - x_k|| < \varepsilon$ .

A normed space is complete if  $\{x_n\}$  Cauchy implies  $\exists x \in V$  such that  $x_n \to x$ .

Complete normed spaces are called Banach spaces.

#### **Example 1**

 $\ell^p(\mathbb{N})$ ,  $1 \le p < \infty$ , the set of all sequences  $\{x_n\}_{n=1}^{\infty} = x$  such that

$$||x|| = \left(\sum_{n=1}^{\infty} |x_n|^p\right)^{1/p} < +\infty$$

Recall  $\{x_n\}+\{y_n\}=\{x_n+y_n\}$  and  $\lambda\{x_n\}=\{\lambda x_n\}$ .  $\ell^p$  spaces are complete and therefore Banach. If  $\{x_n\}\in\ell^p$  and  $\{y_n\}\in\ell^q$ , then  $\{x_ny_n\}\in\ell^r$ ,  $\frac{1}{p}+\frac{1}{q}=\frac{1}{r}\in[0,1]$  (e.g.  $\ell^2\cdot\ell^2\leq\ell^1$ )

#### Example 2

 $\ell^{\infty}(\mathbb{N})$ , the set of all bounded sequences

$$||x|| = \sup_{n \in \mathbb{N}} |x_n| < +\infty$$

#### Example 3

 $C_0(\mathbb{N}) \subseteq \ell^p(\mathbb{N})$ , the set of all sequences  $\{x_n\}$ 

$$\lim_{n\to\infty} x_n = 0$$

 $C_0$  is a closed subspace, and both are Banach.

## Example 4

 $L^p(\Omega)$ ,  $1 \le p < \infty$ ,  $\Omega \subseteq \mathbb{R}^d$  a Lebesgue measurable set with  $m(\Omega) > 0$ , the space of all equivalence classes of Lebesgue measurable functions  $f: \Omega \to \mathbb{F}$  such that

$$||f|| = \left(\int_{\Omega} |f(x)|^p dx\right)^{1/p} < +\infty$$

#### Example 5

 $L^{\infty}(\Omega)$ , the measurable and essentially bounded functions

$$\begin{split} ||f|| &= \inf_{\substack{N \subseteq \Omega \\ m(N) = 0}} \sup_{x \in \Omega \backslash N} |f(x)| < + \infty \\ &= \operatorname{ess\ sup}_{x \in \Omega} |f(x)| \end{split}$$

 $L^p(\Omega)$  spaces,  $1 \le p \le \infty$ , are Banach.

#### Example 6

For  $\Omega \neq \emptyset$ , let  $B(\Omega)$  the set of all bounded functions  $f: \Omega \to \mathbb{F}$  with

$$||f|| = \sup_{x \in \Omega} |f(x)|$$

is a Banach space.

 $f_n \to f$  in  $B(\Omega)$  if and only if  $f_n$  converges uniformly on  $\Omega$  to f.

#### Example 7

Let  $\Omega$  be a topological space and  $BC(\Omega)$  the set of all bounded, continuous functions  $f:\Omega\to\mathbb{F}$ .

Then  $BC(\Omega) \subseteq B(\Omega)$  is a closed Banach subspace under the same norm.

That is, the uniform limit of continuous functions is a continuous function.

$$f_n \to f \Longrightarrow f \in B(\Omega)$$

### **Example 8**

Let K be a compact, Hausdorff space.

Then C(K) is the set of all continous functions  $f: K \to \mathbb{F}$  and C(K) = BC(K).

## F Spaces / pre-F Spaces

A pre-*F*-space is a TVS where the topology is given by some invariant metric d(x+z,y+z)=d(x,y) or d(x,y)=d(x-y,0).

An *F*-space is a complete pre-*F*-space.

A local base (at 0) is given by

$$\gamma_0 = \{B_{\varepsilon}(0) : \varepsilon > 0\}, \quad B_{\varepsilon}(x) = \{y \in V : d(x, y) < \varepsilon\}$$

### **Example 1**

 $\ell^p(\mathbb{N}), 0 , the set of all <math>\{x_n\}_{n=1}^{\infty}$  such that

$$\sum_{n=1}^{\infty} |x_n|^p < +\infty$$

with

$$d(x,y) = \sum_{n=1}^{\infty} |x_n - y_n|^p$$

Note that this obeys the triangle inequality specifically because it has not been raised to 1/p.

$$d(\lambda x, \lambda y) = |\lambda|^p \cdot d(x, y)$$

means that d(z,0) is not a norm.

Here,  $B_{\varepsilon}(x)$  are not convex sets.

#### Side Remark

Given  $\mathbb{R}^2$ , the  $\ell^p$  norm for  $1 \le p \le \infty$  is given by

$$||(x_1, x_2)|| = (|x_1|^p + |x_2|^p)^{1/p}$$

and the distance for 0 by

$$d((x_1, x_2))) = |x_1|^p + |x_2|^p$$

The  $\varepsilon$  neighborhoods for p=1 are diamonds, p=2 circles,  $p=\infty$  squares with smooth transition between them. However, for 0 , we have concave diamond shapes.

These norms and metrics are all equivalent on  $\mathbb{R}^2$  in the sense that they give the same topology.

### **Locally Convex TVS**

A TVS which has a local base  $\gamma$  at 0 consisting of open neighborhoods of 0 which are all convex.

#### **Definition: Convex Set**

A set  $A \subseteq V$  is convex if  $\forall x, y \in A, \lambda \in [0,1]$ , then  $\lambda x + (1-\lambda)y \in A$ Alternatively, the line segment between x and y is contained in A ( $[x, y] \subseteq A$ ).

### Fréchet Spaces and pre-Fréchet Spaces

A pre-Fréchet space is locally convex. A Fréchet space is a locally convex *F*-space.

## **April 11, 2024**

## Fréchet Spaces

### Example

 $S = \{\{\{x_n\}_{n=1}^{\infty} \text{ the space of all sequences } x_n \in \mathbb{F}.$ 

$$d(\{x_n\},\{y_n\}) = \sum_{n=1}^{\infty} \frac{1}{2^n} \cdot \frac{|x_n - y_n|}{1 + |x_n - y_n|} < +\infty$$

Triangle inequality:

$$\frac{a+b}{1+a+b} \le \frac{a}{1+a} + \frac{b}{1+b}, \quad a, b \ge 0$$

invariant metric, complete.

 $\gamma_0 = \{B_{\varepsilon}(0) : \varepsilon > 0 \text{ is a local base.}$ 

 $\hat{\gamma}_0 = \{U_{\varepsilon,N} : \varepsilon > 0, N \in \mathbb{N}\}.$ 

 $U_{\varepsilon,N} = \{\{x_n\}_{n=1}^{\infty} : |x|_n < \varepsilon, \forall n = 1, \dots, n\}.$ 

 $\forall \varepsilon > 0, \exists \hat{\varepsilon} > 0, N \text{ such that } U_{\hat{\varepsilon},N} \subseteq B_{\varepsilon}(0).$ 

 $\forall \hat{\varepsilon} > 0, N, \exists \varepsilon > 0 \text{ such that } B_{\varepsilon}(0) \subseteq U_{\hat{\varepsilon},N}.$ 

 $x^{(m)} \to x \text{ in metric of } \mathcal{S} \text{ as } m \to \infty.$   $x^{(m)} = \{x_n^{(m)}\}_{n=1}^{\infty}, \ x = \{x_n\}_{n=1}^{\infty} \text{ if and only if } \forall n \in \mathbb{N}, \ x_n^{(m)} \to x_n \text{ as } m \to \infty \text{ (pointwise, componentwise convergence)}.$ 

#### **Example**

 $C(\mathbb{R}^d)$ , the set of continuous functions  $f:\mathbb{R}^d\to\mathbb{F}$ .

$$|||f|||_N = \sup_{\substack{x \in \mathbb{R}^d \\ ||x|| \le N}} |f(x)|$$

$$d(f,g) = \sum_{N=1}^{\infty} \frac{1}{2^N} \cdot \frac{|||f - g|||_N}{1 + |||f - g|||_N}$$

Complete Fréchet space.

"Locally uniform congergence" such that  $f_n \to f$  in metric of  $C(\mathbb{R}^d)$  if and only if  $\forall$  compact set  $K \subseteq \mathbb{R}^d$ ,  $f_n$  converges to f uniformly on K.

## **Example**

 $C^{\infty}[0,1]$  the set of infinitely differentiable functions  $f:[0,1] \to \mathbb{F}$ .

$$|||f|||_n = \sup_{x \in [0,1]} |f^{(n)}(x)|$$

$$d(f,g) = \sum_{n=0}^{\infty} \frac{1}{2^n} \cdot \frac{|||f - g|||_n}{1 - |||f - g|||_n}$$

Fréchet space.

 $f_m \to f$  in  $C^{\infty}[0,1]$  as  $m \to \infty$  if and only if for every  $m \in \{0,1,\ldots\}, f_m^{(n)} \to f^{(n)}$  uniformly on [0,1] as  $m \to \infty$ .

## **Proposition**

Every TVS is Huasdorff.

#### **Proof**

Let  $x, y \in V$ ,  $x \neq y$ .

For  $U = V \setminus \{0\}$ , and open set,  $x - y \in U$ . Using the continuity of  $(x^2, y^2) \mapsto x^2 - y^2$  and Lemma 1, there exist  $U_x \ni x$  and  $U_y \ni y$  open such that  $U_x - U_y \subseteq U$ . Note that  $U_x \cap U_y = \emptyset$ , otherwise there would exist  $z \in U_x \cap U_y$  such that  $0 = z - z \in U_x - U_y \subseteq U$  a contradiction.

## **Definition: Balancedness**

A subset *U* of a vector space *V* is called balanced if  $\forall \lambda \in \mathbb{F}$ ,  $|\lambda| \le 1$ ,  $\lambda U \subseteq U$ .

#### **Example**

For  $V = \mathbb{R}^2$ ,  $\mathbb{F} = \mathbb{R}$ , an ellipse is convex and balanced.

Note that since  $\lambda = 0$  is a valid choice, 0 is always in a balanced set.

A retangle, offset from the origin, is convex but not balanced.

A concave diamond centered at 0 may be balanced.

An annulus is neither.

#### **Exercise**

Show that for  $V = \mathbb{C}$ ,  $\mathbb{F} = \mathbb{C}$ , the balanced, convex sets are the open and closed disks along with the entire plane.

# **Proposition**

- 1. Every TVS has a balanced, local base.
- 2. Every locally convex TVS has a balanced and convex local base.

#### Proof of A

e.g.  $\gamma = \{U : U \text{ open, } 0 \in U\}.$ 

For every  $U \in \gamma$ , construct another  $\hat{U}$  open,  $0 \in \hat{U} \subseteq U$  balanced.

Then  $\hat{\gamma} = {\hat{U} : U \text{ taken from } \gamma}$  is a local base.

Use Lemma 1 again and the continuity of  $(\lambda, x') \mapsto \lambda \cdot x'$  at  $\lambda = 0$ , x' = 0.

Given open  $U \ni 0$ , find  $\delta > 0$  and open  $U_0 \ni 0$  such that  $B_{2\delta}(0) \cdot U_0 \subseteq U$ .

Then for  $\alpha \in \mathbb{F}$ ,  $|\alpha| \leq \delta$ ,  $\alpha \cdot U_0 \subseteq U$ . Take

$$\hat{U} = \bigcup_{\substack{\alpha \in \mathbb{F} \\ |\alpha| \le \delta}} \alpha \cdot U_0$$

Therefore  $\hat{U}$  is a union of open sets and  $0 \in \hat{U} \subseteq U$ . Finally, for  $|\lambda| \le 1$ ,

$$\lambda \cdot \hat{U} = \bigcup_{\substack{\alpha \in \mathbb{F} \\ |\alpha| < \delta}} \lambda \cdot \alpha \cdot U_0 = \bigcup_{\substack{\beta \\ |\beta| \le |\lambda| \cdot \delta \le \delta}} \beta U_0 = \hat{U}$$

#### Proof of B

We have a local base  $\gamma=\{U_\omega\},\ U_\omega\ni 0$  open and convex. We want to construct  $\hat{\gamma}=\{\hat{U}_\omega\},\ \hat{U}_\omega\ni 0$  open, convex and balanced. Given U convex, define

$$\hat{U} = \bigcap_{|\alpha| \le \delta} \alpha U$$

convex and balanced.

Need to show that  $\hat{U} \ni 0$  is an open neighbrhood.

Rest of the owl left to the reader.

### Recall

The intrinsic characterization of a base for a topological space or a local base for a topological space X,  $\{\gamma_x\}_{x\in X}$ .

- $\forall x \in X, U \in \gamma_x, x \in U$
- $\forall x, y \in X, U \in \gamma_x, V \in \gamma_y, z \in U \cap V, \exists W \in \gamma_z, W \subseteq U \cap V.$

# **Proposition**

A balanced, local base  $\gamma$  (at 0) of a TVS V has the following properties:

- 1.  $\gamma$  is a nonempty collection of subsets of V containing 0.
- 2.  $\forall U_1, U_2 \in \gamma$ ,  $\exists U \in \gamma$  such that  $U \subseteq U_1 \cap U_2$ .
- 3.  $\forall U \in \gamma, x \in U, \exists W \in \gamma \text{ such that } x + W \subseteq U.$

- 4.  $\forall U \in \gamma$ ,  $\exists W \in \gamma$  such that  $W + W \subseteq U$  (continuity of  $(x, y) \mapsto x + y$  at (x = y = 0).
- 5.  $\forall U \in \gamma, \ \forall x \in V, \ \exists t > 0, \ x \in t \cdot U$  (continuty of scalar multiplication  $(\lambda, x') \mapsto \lambda x'$  at  $\lambda = 0, \ x' = x$ ).

$$\frac{1}{t} \cdot x \in U, \ \frac{\delta}{2} \cdot x \subset B_{\delta}(0) \cdot \hat{U} \subseteq U.$$

6.  $\forall x \in V, x \neq 0, \exists U \in \gamma, x \notin U (\{x\} \text{ closed}; 0 \in V \setminus \{x\} \text{ open}; 0 \in U \subseteq V \setminus \{x\}).$  (Hausdorff)

#### Converse

Conversely, if  $\gamma$  satisfies properties 1-6, then there exists a unique topology on V such that  $\gamma$  is a balanced, local base for V and V with this topology is a TVS.

## Theorem:

Any two TVS of finite dimension d (over  $\mathbb{F} = \mathbb{R}$  or  $\mathbb{F} = \mathbb{C}$ ) are homeomorphic to eachother.

#### **Proof**

Let V be a TVS with  $\dim(V) = d$ . We want to show that  $V \cong \mathbb{F}^d$ . We have

$$V = \lim\{v_1, \dots, v_d\}$$

a basis and

$$f:(\lambda_1,\ldots,\lambda_n)\in\mathbb{F}^d\mapsto\sum_{i=1}^d\lambda_i\nu_i\in V$$

an isomorphism between  $\mathbb{F}^d$  and V as vector spaces. Further, f is continuous. Consider  $\mathbb{F}^d$  equipped with the product topology and the continuity of addition and scalar multiplication.

We need only that  $f^{-1}$  is continuous at 0 which is equivalent to  $\forall U \ni 0$  open in  $\mathbb{F}^d$ ,  $\exists W \ni 0$  open in V such that  $W \subseteq f(U)$   $((f^{-1})^{-1}(U))$ .

# **April 12, 2024**

### Lemma

 $\forall U \ni 0$  open in  $\mathbb{F}^d$ ,  $\exists W \ni 0$  open such that  $f(U) \supseteq W$ . That is, 0 is an interior point of f(U).

#### **Proof**

 $f: \mathbb{F}^d \to V$ , continuous.

We may assume without loss of generality that  $U = B_1(0)$ .

Let  $S = \{\lambda \in \mathbb{F}^d : ||\lambda|| = 1\}$ , a compact set.

Since f continuous, f(S) is compact in V. Since V is Hausdorff, f(S) is closed.

Take  $\hat{U} = V \setminus f(S) \ni 0$  open (because  $0 \notin f(S)$  else  $f(\lambda) = 0$  would imply  $||\lambda|| = 1$ )

Now, there exists a balanced, open set  $0 \in W \subseteq \hat{U}$ . Therefore,  $W \subseteq f(U)$ .

Otherwise,  $x \in W$ ,  $x \notin f(U)$ ,  $x = f(\lambda)$ ,  $\lambda \notin U$ ,  $||\lambda|| \ge 1$  would give  $\frac{\hat{x}}{||\lambda||} = \frac{1}{||\lambda||} \cdot f(\lambda) = f\left(\frac{\lambda}{||\lambda||}\right) \in f(S)$ .

But,  $\frac{x}{||\lambda||} \in W \subseteq \hat{U}$  because  $x \in W$ ,  $\frac{1}{||\lambda|} \in [0,1]$  and W is balanced shows a contradiction.

## **Theorem**

Any finite-dimensional subspace in a TVS is closed.

## **Theorem**

Every locally compact TVS is finite-dimensional.

# **Definition: Locally Compact**

V is locally compact if  $\forall x \in V$ ,  $\exists U \ni x$  open and  $K \subseteq V$  such that  $U \subseteq K$ . For Hausdorff spaces,  $\forall x \in V$ ,  $\exists U \ni x$  open such that  $\overline{U}$  compact.

## **Example**

Let V be a normed space,  $\dim(V) = +\infty$ . Then  $\overline{B_1(0)}\{x \in V : ||x|| \le 1\}$  is not compact.

## **Definition: Semi-norm**

A semi-norm on a metric space V (over  $\mathbb{F} = \mathbb{R}$ ,  $\mathbb{C}$ ) is a map

$$p: V \to [0, +\infty)$$

such that

1. 
$$p(x+y) \le p(x) + p(y)$$

2. 
$$p(\lambda x) = |\lambda| \cdot p(x)$$
.

Note that p(0) = 0 and  $(p(x - y) \ge |p(x) - p(y)|$ .

$$N_p = \{x \in V : p(x) = 0\}$$

is a linear subspace of  $V: x, y \in N$  such that  $p(x+y) \le p(x) + p(y) = 0$ ,  $p(\lambda x) = 0$ . A semi-norm on V induces a norm on the quotient space  $V/N_p$ .

$$||[x]_{N_p}|| = p(x) \quad [x]_N = \{x + z : z \in N\} = x + N$$

# **Definition: Absorbing**

A set  $A \subseteq V$  is called absorbing if  $\forall x \in V$ ,  $\exists \lambda > 0$  such that  $\lambda x \in A$ . Equivalently,  $\bigcup_{\lambda > 0} \frac{1}{\lambda} A = V$ .

There is a relationhip between semi-norms on V and balanced, convex and absorbing subsets of V.

# **Proposition**

If p is a semi-norm on a vector space V, then

$$A = \{x \in V : p(x) < 1\}$$

is balanced, convex and absorbing.

#### **Proof**

Convex:  $x, y \in A, p(x) < 1, p(y) < 1,$ 

$$p(\lambda x + (1 - \lambda)y) \le \lambda \cdot p(x) + (1 - \lambda)p(y) < 1$$

Balanced:  $x \in A$ ,  $|\lambda| \le 1$ , p(x) < 1,

$$p(\lambda x) = |\lambda| \cdot p(x) < 1$$

Absorbing:  $x \in V$ . If p(x) = 0, then  $x \in A$   $(\lambda = 1)$ . If p(x) > 0,  $\lambda = \frac{1}{2p(x)}$  gives  $p(\lambda x) = |\lambda| \cdot p(x) = \frac{1}{2} < 1$ .

## **Example**

Let  $V = \mathbb{R}^2$  and  $\mathbb{F} = \mathbb{R}$ .

An ellipse is balanced, convex and absorbing.

A band is also balanced, convex and absorbing.

An open interval along the axis is balanced and convex, but it is not absorbing.

# **Proposition**

Each open neighborhood of 0 in a TVS is absorbing.

#### **Proof**

Continuity of the map  $(\lambda, x) \mapsto \lambda x'$  at  $\lambda = 0$  and x' = x. Given  $x \in V$ ,  $U \ni 0$  open,  $\exists \delta > 0$ ,  $W \ni x$  such that  $B_r(0) \cdot W \subseteq U$  and  $\frac{\delta}{2} \cdot x \in U$ .

### **Definition: Minkowski Functional**

Let A be a subset in a vector space V.

If A is absorbing, one can define the Minkowski functional

$$\mu_A(x) = \inf\left\{\lambda > 0 \ : \ \frac{x}{\lambda} \in A\right\} = \inf\{\lambda > 0 \ : \ x \in \lambda \cdot A\}$$

# **Proposition**

If A is convex, balanced and absorbing, then  $\mu_A$  is a semi-norm.

#### **Proof**

Absorbing  $\rightarrow \mu_A$  is well defined,  $\mu_A(x) \in [0, +\infty)$ . For  $\alpha \neq 0$ ,

$$\begin{split} \mu_A(\lambda x) &= \inf \left\{ \lambda > 0 \ : \ \frac{\alpha \cdot x}{\lambda} \in A \right\} \\ &= \inf \left\{ |\alpha| \cdot \lambda > 0 \ : \ \frac{\alpha \cdot x}{|\alpha| \cdot \lambda} \in A \right\} \quad (\lambda \mapsto |\alpha| \cdot \lambda) \\ &= |\alpha| \cdot \inf \left\{ \lambda > 0 \ : \ \frac{x}{\lambda} \in \frac{|\alpha|}{\alpha} A \right\} \\ &= |\alpha| \cdot \inf \left\{ \lambda > 0 \ : \ \frac{x}{\lambda} \in A \right\} \\ &= |\alpha| \cdot \mu_A(x) \end{split}$$

since A is balanced,  $\frac{\alpha}{|\alpha|}A = A$ .

Note that  $\mu_A(0) = 0$  since  $0 \in A$  balanced.

Given  $x, y \in V$  and  $\varepsilon > 0$ , let  $s = \mu_A(x) + \varepsilon$  and  $t = \mu_A(y) + \varepsilon$ . Then, since A is balanced,  $\frac{x}{s}, \frac{y}{t} \in A$ . By convexity,

$$\frac{x+y}{t+s} = \underbrace{\frac{s}{t+s}}_{(1-\sigma)} \cdot \underbrace{\frac{\epsilon A}{s}}_{s} + \underbrace{\frac{t}{t+s}}_{\sigma} \cdot \underbrace{\frac{\epsilon A}{y}}_{t} \in A$$

Therefore,  $\mu_A(x+y) \le t+s$  which implies  $\mu_A(x+y) \le \mu_A(x) + \mu_A(y) + 2\varepsilon$  for all  $\varepsilon > 0$ .

## **Equivalence between Semi-norm and ABC Sets**

 $p \rightsquigarrow A = \{x : p(x) < 1\} \rightsquigarrow \mu_a = p.$ 

A bounded, convex, absorbing  $\rightarrow \mu_A \rightarrow \tilde{A} = \{x : \mu_A(x) < 1\}$  where  $\tilde{A} \subseteq A$  differing possibly by the boundary.

## Question: which TVS are normable?

That is a norm such that the topology is vien by this norm.

### **Definition: Bounded Sets**

A subset *A* in a TVS is bounded if  $\forall U \ni 0$  open,  $\exists \delta > 0$  such that  $A \subseteq t \cdot U$ ,  $\forall t > \delta$ .

### Theorem:

A TVS is normable if and only if there exists a bounded, convex, balanced, open neighborhood of 0.

#### Proof (Sketch)

Suppose V is a normed space with norm  $||\cdot||$ .

$$B = \{x \in V : ||x|| < 1\} = B_1(0)$$

is convex, balanced, and an open neighborhood of 0.

B is bounded, since given  $U \ni 0$  open,  $B_{\varepsilon}(0) \subseteq U$ , so  $B = \frac{1}{\varepsilon} \cdot B_{\varepsilon}(0) \subseteq \lambda B_{\varepsilon}(0) \subseteq \lambda \cdot U$  for  $\lambda \ge \frac{1}{\varepsilon}$ .

Now, let *B* be a bounded, convex, balanced, open neighborhood of 0 in a TVS.

Therefore B is absorbing (as an open neighborhood of 0).

It follows that the semi-norm  $\mu_B(x)$  may be defined.

Then  $\mu_B(x) = 0 \implies x = 0$  since B is bounded, otherwise  $0 \in U = V \setminus \{x\}$  open gives  $B \subseteq t \cdot U$ ,  $\forall t > \delta$  and  $\frac{1}{t}B \subseteq U$ ,  $\forall t > \delta$ .

Thus,  $||x|| = \mu_B(x)$  is a norm on V.

One need only demonstrate that the norm topology is the same as the original topology on V.

That is,  $\forall U \ni 0$  open,  $\exists \varepsilon > 0$  such that  $\varepsilon \cdot B \subseteq U$ .

 $\forall \varepsilon > 0, \exists \hat{U} \ni 0$  open such that  $\hat{U} \subseteq \varepsilon B$ .

# April 16, 2024

#### Recall

Given p a semi-norm,

$$A = \{x \in V : p(x) < 1\}$$

a convex, balanced absorbing set gives the Minkowski formula for a seminorm  $\mu_a$ . The TVS V is normable if and only if there exist bounded, convex, balanced, open  $U \ni 0$ .

## **Definition: Separating Family of Semi-norms**

Let V be a vector space.

A family of semi-norms  $\{p_{\omega}\}_{{\omega}\in\Omega}$  is called separating if  $\forall x\in V, x\neq 0, \exists {\omega}\in\Omega$  such that  $p_{\omega}(x)\neq 0$ . Equivalently,

$$\{x \in V : \forall \omega \in \Omega, \ p_{\omega}(x) = 0\} = \{0\}$$

or

$$\bigcap_{\omega\in\Omega}N_{p_\omega}=\bigcap_{\omega\in\Omega}\{x\in V\,:\,p(x)=0\}=\{0\}.$$

For a given separating family of semi-norms, define

$$U_{n,\omega} = \left\{ x \in V : p_{\omega}(x) < \frac{1}{n} \right\}$$

$$U_{n,\omega_1,\dots,\omega_N} = \left\{ x \in V : p_{\omega_i}(x) < \frac{1}{n \ i = 1,\dots,N} \right\} = \bigcap_{i=1}^N U_{n,\omega_i}$$

and put

$$\gamma = \{U_{n,\omega_1,\dots,\omega_N} : n \in \mathbb{N}, \omega_1,\dots,\omega_N \in \Omega, N \in \mathbb{N}\}.$$

One can show by earlier propositions that  $\gamma$  is a local base at at 0 for some topology  $\tau$ . Perhaps unsurprisingly, if  $\{p_\omega\}$  is separating, then this locally convex TVS is Hausdorff.

### Theorem:

Let  $\{p_{\omega}\}$  be a separating family of semi-norms on a vector space V. Then with local base  $\gamma$  defined above, V becomes a locally convex TVS, and all  $p_{\omega}: V \to [0, +\infty)$  continuous.

#### **Example**

$$S = \{\{x_n\}_{n=1}^{\infty} \text{ all sequences}\}\$$

with 
$$p_n(x) = |x_n|, x = \{x_n\}_{n=1}^{\infty}, d(x, y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \frac{|x_n - y_n|}{1 + |x_n - y_n|}$$

#### Remark

Local base at x

$$\gamma_x = x + \gamma = \{U_{n,\omega_1,\dots,\omega_N}[x] : n, N \in \mathbb{N}, \, \omega_1,\dots,\omega_N \in \Omega\}$$

$$U_{n,\omega_1,...,\omega_N}[x] = \left\{ y \in V : p_{\omega_i}(x-y) < \frac{1}{n}, \ i = 1,...,N \right\}$$

### Theorem:

Let V be a locally convex TVS. Then there exists a separating family of semi-norms  $\{p_{\omega}\}_{{\omega}\in\Omega}$  on V such that the topology defined by  $\{p_{\omega}\}$  coincides with the original toplogy.

### **Proof (Sketch)**

V is locally convex, so it has a convex, balanced, local base at 0

$$\hat{\gamma} = \{U_{\omega}\}_{{\omega} \in \Omega}$$

where  $U_{\omega} \ni 0$  are open, convex, balanced, and absorbing.

Put  $p_{\omega} = \mu_{U_{\omega}}$  (i.e. set the Minkowski functional to be the semi-norm).

Then we need to show that these are separating.

Then define  $U_{n,\omega_1,...,\omega_N}$ ,  $\gamma = \{U_{n,\omega_1,...,\omega_N}\}$ ,  $U_\omega = U_{1,\omega}$ ,  $\hat{\gamma} \subseteq \gamma$  and show that  $\gamma$  and  $\hat{\gamma}$  induce the same topology.

## Theorem:

A TVS V is a pre-Fréchet space if and only if V has a countable, convex, balanced local base.

#### **Proof**

 $(\Longrightarrow)$  Assume that V is a pre-Fréchet space.

Then we have an invariant metric d and

$$B_{\varepsilon}(x) = \{ y \in V : d(x, y) < \varepsilon \}.$$

It follows that  $\gamma_1 = \{B_{1/n}(0) : n \in \mathbb{N}\}$  is a local base.

The fact that V is locally convex means that  $\gamma_2 = \{U_\omega : \omega \in \Omega\}$  with  $U_\omega \ni 0$  open, convex and balanced is a convex, balanced local base.

To every  $n \in \mathbb{N}$ ,  $B_{1/n}(0)$  is an open neighborhood of 0, and there exists  $\omega_n \in \Omega$ ,  $0 \in U_{\omega_n} \subseteq B_{1/n}(0)$ . Put

$$\gamma_3 = \{U_{\omega_n} : n \in \mathbb{N}\}$$

a countable, convex, balanced collection.

Then, for any  $U \ni 0$  open,  $\exists n$  such that  $U_{\omega_n} \subseteq B_{1/n}(0) \subseteq U$ . So  $\gamma_3$  is a local base.

 $(\longleftarrow)$  Assume a TVS V has a countable, convex, balanced local base:

$$\gamma = \{U_n : n \in \mathbb{N}\}$$

Without loss of generality, we may assume that  $U_{n+1} \subseteq U_n$ . Otherwise, we may take  $\hat{U}_n = U_1 \cap \cdots \cap U_n \subseteq U_n$  such that  $\{\hat{U}_n : n \in \mathbb{N}\}$  is also a local base where  $\hat{U}_{n+1} \subseteq \hat{U}_n$ .

Then, since  $U_n$  are open, they are absorbing and  $p_n = \mu_{U_n}$  gives a separating semi-norm from the Minkowski functional. Define a metric

$$d(x,y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \frac{p_n(x-y)}{1 + p_n(x-y)}$$

where  $d(x, y) = 0 \implies x = y$  since  $\{p_n\}$  are separating.

Claim: the metric topology (local base  $\tilde{\gamma}$ ) is the same as the original topology (local base  $\gamma$ ). Write

$$\tilde{\gamma} = \{B_{1/2^m}(0) : m \in \mathbb{N}\}$$

Then for all  $m \in \mathbb{N}$ ,

$$\frac{1}{2^{m+1}}U_{m+1}\subseteq B_{1/2^m}(0)$$

there exists  $n \in \mathbb{N}$  such that  $U_n \subseteq \frac{1}{2^{m+1}}U_{m+1}$ .

Also,  $\forall n, B_{1/2^{n+1}}(0) \subseteq U_n$ . Then  $\tilde{V}$  is locally convex  $(\gamma)$  and has an invariant metric  $(\tilde{\gamma})$ . That is, V is pre-Fréchet space.

### Corollary

In a pre-Fréchet space, the metric can always be defined by

$$\forall n, \quad B_{1/2^{n+1}}(0) \subseteq U_n$$

where  $\{p_n\}$  are separating family of semi-norms.

A separating family of semi-norms leads to a locally convex TVS.

A countable, separating family of semi-norms leads to a pre-Fréchet space.

A finite, separating family of semi-norms leads to a normed space.

## **Quotient Spaces**

For a vector space X and a linear subspace  $N \subseteq X$ ,  $X/N = \{[x]_N : x \in X\}$ ,  $[x]_N = x + N$ .  $\pi: X \to X/N$  is the quotient map to the vector space X/N.

For a TVS  $X, N \subseteq X$  a subspace,  $\pi: X \to X/N$  where  $\tau$  is the topology of X and  $\hat{\tau}$  is the topology of X/N given by

$$\hat{\tau} = \{ \pi(U) : U \in \tau \}.$$

N is closed if and only if X/N is Hausdorff.

#### **Thoerem:**

For *X* a TVS and  $N \subseteq X$  a linear subspace, X/N is a TVS and  $\pi: X \to X/N$  is open and continuous.

#### Normed / Banach

For X a normed (Banach) space, X/N is a normed (Banach) space where  $||[x]||_{X/N} = \inf_{z \in N} ||x + z||$ .

#### Pre-Fréchet / Fréchet

For X a (pre-)Fréchet space, X/N is a (pre-)Fréchet space where  $d_{X/N}(x,y) = \inf_{z \in N} d(x+z,y) = \inf_{z_1,z_2} d(x+z_1,y+z_2)$ .

# **Definition: Linear Operator**

A map  $T: V \to W$  between vector spaces V, W is linear (or a linear operator) if

$$T(x+y) = Tx + Ty$$
 and  $T(\alpha x) = \alpha(Tx)$ 

#### **Notation**

M(V, W) is the set of all linear operators.

$$M(V,V)=M(V).$$

 $V' = M(V, \mathbb{F})$  (linear functionals) is the algebraic dual of V.

Note that M(V, W) is a vector space.

$$(T_1 + T_2)(x) := T_1 x + T_2 x$$
 and  $(\lambda T)(x) := \lambda (Tx)$ 

If  $T_1$ ,  $T_2$  are linear, then  $T_1 + T_2$  is linear; likewise,  $\lambda T$  is linear precisely when T is linear.

# **Definition: Continuous Linear Operator**

For V, W TVS, T is a continuous linear operator if  $T \in M(V, W)$  and T is continuous with respect to the topologies.

#### **Notation**

L(V, W) is the set of all continuous linear operators.

$$L(V,V) = L(V).$$

 $V^* = L(V, \mathbb{F})$ , the set of continuous linear functionals on V, is the dual space of V.

# **Example**

Let  $V = \mathbb{R}^n$ ,  $W = \mathbb{R}^m$ .

$$M(V,W) = L(V,W).$$

To an  $m \times n$  matrix  $A = (a_{ij})_{i=1,j=1}^{m,n}$ , one associates the linear operator  $T_A$ 

$$T_A: (x_j)_{j=1}^n \mapsto (y_i)_{i=1}^m, \quad y_i = \sum_{j=1}^n a_{ij} x_j$$

 $V' = V^*$ . Given  $\phi = (\phi_1, \dots, \phi_n) \in \mathbb{R}^n$  (a row vector),

$$\phi(x) = \phi \cdot x = \sum_{j=1}^{n} \phi_j x_j$$

In this case,  $V^* \cong \mathbb{R}^n$ .

# **Defiition: Image or Range**

For  $T \in M(V, W)$ ,  $T : V \to W$ ,

$$\operatorname{im} T = R(t) = \{Tx : x \in V\}$$

# **Definition: Kernel or Nullspace**

$$\ker T = N(T) = \{x \in V : Tx = 0\}$$

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## Remarks

R(T) is a linear subspace of W while N(T) is a linear subspace of V.

*T* is injective if and only if  $N(t) = \{0\}$ .

If T is inective, then one has an inverse map  $T^{-1}: R(T) \to V$ .  $T^{-1}$  is linear.

T is invertible if and only if T is injective and surjective if and only if  $N(T) = \{0\}$  and R(T) = W.

## **April 18, 2024**

# **Proposition**

Let V, W be TVS.

- 1. a linear operator  $T: V \to W$  is continuous if and only if T is continuous at some  $x_0 \in V$ .
- 2. if T is a continuous linear operator, then  $N(T) = \ker(T)$  is a closed, linear subspace of V.

## **Proof of A**

 $(\Longrightarrow)$  continuous at all points imply continuous at  $x_0$ .

( $\iff$ ) Write  $f(x) = T(x + x_0 - x_1) - T(x_0 - x_1)$  and assume T is continuous at  $x = x_0$ .

Then  $T(x + x_0 - x_1)$  is continuous at  $x = x_1$ .

#### Proof of B

We have that  $ker(T) = \{x \in V : Tx = 0\} = T^{-1}(\{0\})$  where  $\{0\}$  is closed and so must be its preimage.

# **Definition: Bounded Linear Operator**

Let V, W be normed spaces with norms  $||\cdot||_V$ ,  $||\cdot||_W$ .

A linear operator  $T: V \to W$  is called bounded if there exists some  $c \ge 0$  such that

$$||Tx||_W < c \cdot ||x||_V, \quad \forall x \in V$$

# **Proposition:**

A linear operator  $T: V \to W$  (V, W normed spaces) is continuous if and only if it is bounded.

#### **Proof**

( $\iff$ ) We know that  $||Tx||_W \le c \cdot ||x||_V$ ,  $\forall x$ . Consider  $\{x_n\}$ ,  $x_n \to a$  in V. Then

$$\lim_{n\to\infty} ||x_n - a|| = 0$$

so  $||Tx_n - Ta||_W \le c \cdot ||x_n - a||_V$ ,  $||Tx_n - Ta||_W = 0$ , and  $Tx_n \to Ta$  in W.  $(\Longrightarrow)$  For every  $n \in \mathbb{N}$ , find  $x_n \in W$  such that

$$||Tx_n||_W > n \cdot ||x_n||_V$$

Then  $y_n = \frac{x_n}{||Tx_n||}$ , since  $||y_n|| = \frac{||x_n||}{||Tx_n||} < \frac{1}{n}$  it must be  $y_n \to 0$ . Hence,  $Ty_n \to T0 = 0$  (*T* continuous)  $\Longrightarrow Ty_n = \frac{Tx_n}{||Tx_n||}$ . But  $||Ty_n|| = 1$ , so  $Ty_n \rightarrow 0$  a contradiction.

### Remark

The following statements are equivalent

- *T* is continuous.
- T is bounded.
- $Tx_n \to 0$  whenever  $x_n \to 0$ .
- $\{Tx_n\}$  is bounded whenever  $\{x_n\}$  is bounded.

## **Definition: Operator Norm**

For V, W normed spaces.

For  $T:V\to W$  a bounded linear operator, we define

$$||T|| = \sup_{\substack{x \in V \\ x \neq 0}} \frac{||Tx||_W}{||x||_V}$$

the operator norm of T.

#### Remark

 $||T|| \in [0, +\infty)$  and it is equal to the smallest  $c \ge 0$  such that  $||Tx||_W \le c \cdot ||x||_V$ ,  $\forall x \in V$ . Indeed, if this holds for some  $c \ge 0$ , then  $||T|| \le c$ .

Conversely, from the definition  $||Tx||_W \le ||T|| \cdot ||x||_V$ .

That is,  $||T|| = \min\{c \ge 0 : ||Tx||_W \le c \cdot ||x||_V, \forall x\}.$ 

#### Remark

$$||T|| = \sup_{\substack{x \in V \\ ||x|| = 1}} ||Tx|| = \sup_{\substack{x \in V \\ ||x|| \le 1}} ||Tx||$$

Note that

$$\sup_{x \neq 0} \frac{||Tx||_{W}}{||x||_{V}} = \sup_{x \neq 0} \left| \left| T\left(\frac{x}{||x||_{V}}\right) \right| \right|_{W} = \sup_{||z||_{V} = 1} \left| |Tz||_{W}$$

### Remark

M(V, W) and L(V, W) are linear spaces,

$$(T+S)(x) = Tx + TS$$
$$(\lambda T)(x) = \lambda (Tx)$$

If T, S are continuous, linear operators, then T+S and  $\lambda T$  are continuous linear operators.

## **Further Properties**

- ||T|| = 0 if and only if T = 0 (i.e.  $Tx = 0, \forall x \in V$ ).
- $||T + S|| \le ||T|| + ||S||$ , because

$$||(T+S)x||_{W} = ||Tx+Ts||_{W} \leq ||Tx||_{W} + ||Sx||_{W} \leq ||T|| \cdot ||x||_{V} + ||S|| \cdot ||x||_{V} \leq (\underbrace{||T|| + ||S||}_{c}) \cdot ||x||_{V}$$

Since T + S is bounded.  $\frac{||(T+S)x||_W}{||x||_V} \le ||T|| + ||S||$ , etc.

- $||\alpha T|| = |\alpha| \cdot ||T||$ .
- if  $T \in L(U, V)$  and  $S \in L(V, W)$ , then  $ST \in L(U, W)$  and

$$||ST|| \le ||S|| \cdot ||T||$$

## **Proposition**

Let *V*, *W* be normed spaces.

Then L(V, W) is a normed space with the operator norm. If, in addition, W is Banach, then L(V, W) is also Banach.

#### **Proof**

#### Part A

 $||\cdot||$  is a norm.

### Part B

Let W be a Banach space, and let  $T_n \in L(V,W)$  be such that  $\{T_n\}$  is a Cauchy sequence in the operator norm. Then,  $\forall \varepsilon > 0$ ,  $\exists N \in \mathbb{N}$  such that  $\forall j,k \geq N, ||T_j - T_k|| < \varepsilon$ . So  $\forall x \in V, \{T_n x\}$  is Cauchy in W.

$$||T_j x - T_k x|| = ||(T_j - T_k)x|| \le ||T_j - T_k|| \cdot ||x|| \le \varepsilon \cdot ||x||$$

By completeness, for every  $x \in V$ ,  $T_n x$  converges in W. Define

$$Tx = \lim_{n \to \infty} T_n x$$

such that  $||Tx - T_nx|| \to 0$  as  $n \to \infty$ .

We need to show that T is a linear operator:

$$T(x+y) = \lim_{n\to\infty} T_n(x+y) = \lim_{n\to\infty} T_n x + \lim_{n\to\infty} T_n y = Tx + Ty.$$
  
 $T(\lambda x) = \lambda \cdot Tx.$ 

We need also show that T is bounded:

$$\frac{||Tx||_W}{||x||_V} = \lim_{n \to \infty} \frac{||T_nx||_W}{||x||_V} = \liminf_{n \to \infty} ||T_n||$$

Since  $\{T_n\}$  is Cauchy, it is bounded and  $\liminf_{n\to\infty}||T_n||\leq c$  for some c.

We have that  $\lim_{n\to\infty} ||Tx - T_nx|| = 0$  such that  $T_n$  converges pointwise.

We need that  $\lim_{n\to\infty} ||T-T_n|| = 0$ .

For given  $\varepsilon > 0$ , we find N such that  $\forall j, k \ge N, x \in V$ :

$$||T_i x - T_k x|| \le \varepsilon \cdot ||x||$$

Then

$$||T_{i}x - Tx|| = ||T_{i}x - T_{k}x + T_{k}x - Tx|| \le \varepsilon \cdot ||x|| + ||T_{k}x - Tx||$$

and sending  $k \to 0$  sends  $T_k x - Tx$  to 0.

Therefore,  $||T_j x - Tx|| \le \varepsilon \cdot ||x||$ ,  $\forall j \ge N$ ,  $\forall x \in V$ . It follows that

$$\frac{||T_j x - Tx||}{||x||} \le \varepsilon$$

and, taking the supremum over x, that  $||T_j - T|| \le \varepsilon$ ,  $\forall j \ge N$ ,  $\forall x \in V$ .

Hence,  $\lim_{n\to\infty} ||T_n - T|| = 0$ .

That is, L(V, W) is complete.

## Corollary

The dual space of a normed space is a Banach space. Recall  $V^* = L(V, \mathbb{F})$ , and both  $\mathbb{R}$  and  $\mathbb{C}$  are complete.

## **Notation**

Read  $\dot{+}$  as a direct sum implied to be between components of a larger space.

Read  $lin\{v_1,...,v_n\}$  as the linear combinations of  $v_1,...,v_n$ .

## **Definition: Codimension**

If V is a vector space and W is a subspace, we say that W has codimension n in V if there exists a subspace  $\hat{W} \subseteq V$  such that

$$V = W + \hat{W}$$

and dim( $\hat{W}$ ) = n.

Equivalently,  $\dim(V/W) = n$ ,  $V/W = \inf\{[e_1], \dots [e_n]\}$  basis and  $\hat{W} = \inf\{e_1, \dots, e_n\}$  implies  $V = W \dotplus \hat{W}$ .

# **Proposition:**

Let *V* be a vector space and  $\phi \neq V'$ ,  $\phi \neq 0$ . Then  $\ker(\phi)$  is a subspace of *V* of codimension 1.

#### **Proof**

 $\phi \neq 0$ . Find  $x_0 \in V$  such that  $\phi(x_0) = 1$ .

Claim:  $V = \ker(\phi) + \lim\{x_0\}.$ 

Indeed, for  $x \in V$  write

$$x = \underbrace{x - \phi(x) \cdot x_0}_{ker(\phi)} + \underbrace{\phi(x)}_{\in lin\{x_0\}} \cdot x_0$$

SO

$$\phi(x - \phi(x) \cdot x_0) = \phi(x) - \phi(\phi(x) \cdot x_0) = \phi(x) - \phi(x) \cdot \phi(x_0) = 0$$

and

 $\ker(\phi) \cap \lim\{x_0\} = \{0\}$  which means  $z = \lambda \cdot x_0 \in \ker(\phi)$ . Therefore

$$0 = \phi(\lambda x_0) = \lambda \cdot 1$$

so  $\lambda = 0$  and z = 0.

## **Proposition:**

Let V be a normed space and  $\phi \in V'$ .

Then  $\phi$  is bounded if and only if  $\ker(\phi)$  is closed in V.

#### **Proof**

- $(\Longrightarrow) \phi$  continuous, as a linear operator, implies  $\ker(\phi) = \phi^{-1}(\{0\})$  is closed.
- $(\longleftarrow)$  assume that  $\ker(\phi)$  is closed. Then

$$V = \ker(\phi) + \lim\{x_0\}$$

for some  $x_0 \in V$  and  $x_0 \notin \ker(\phi)$ .

Without loss of generality, we may assume  $\phi(x_0) = 1$ .

Claim:  $\inf_{x \in \ker(\phi)} ||x_0 - x|| = \operatorname{dist}(\ker(\phi), x_0) > 0.$ 

Otherwise, there would exist some sequence  $\{x_n\} \subseteq \ker(\phi)$  such that  $||x_0 - x_n|| \to 0$ .

From the assumption of closure, this would mean  $x_0 \in \ker(\phi)$  a contradiction.

Therefore,  $\exists c > 0$  such that  $||x_0 - x|| \ge c$ ,  $\forall x \in \ker(\phi)$ . So

$$||\lambda x_0 - \lambda x|| \ge c \cdot |\lambda|$$
  
$$||\lambda x_0 - u|| \ge c \cdot |\lambda|, \quad \forall u \in \ker(\phi)$$

Write 
$$y \in V$$
 as  $y = \underbrace{-u}_{\in \ker(\phi)} + \underbrace{\lambda x_0}_{\in \lim\{x_0\}}$ . So  $\phi(y) = 0 + \lambda \cdot \phi(x_0) = \lambda$ .

Thus,  $\forall x \in V$ ,  $||x|| \ge c \cdot |\phi(x)|$  and  $|\phi(x)| \le \frac{1}{c} \cdot ||x||$  and  $\phi$  is bounded.