

Practical session



Image Resize.

```
import cv2
import imutils
img = cv2.imread('sample2.jpg')
resizedImg = imutils.resize(img, width=500)
cv2.imwrite('resizedImage.jpg', resizedImg)
```

Gaussian Blur - Smoothening.

import cv2

img = cv2.imread('sample2.jpg')
grayImg = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
#dst = cv2.GaussianBlur(src, (kernel),borderType)
gaussianImg = cv2.GaussianBlur(grayImg, (21, 21), 0)
cv2.imwrite("GaussianBlur.jpg", gaussianImg)



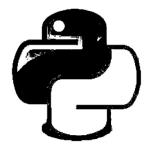
threshold.

#dst = cv2.threshold(src, threshold, maxValueForThreshold,binary,type)[1]
import cv2

img=cv2.imread("sample.jpg")
grayImg = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
gaussBlur = cv2.GaussianBlur(grayImg,(21,21),0)
thresholdImg = cv2.threshold(grayImg,150,255,cv2.THRESH_BINARY)[1]
cv2.imwrite("threshold.jpg",thresholdImg)







Drawing Rectangle.

#cv2.rectangle(src,startpoint,endpoint,color,thickness)

cv2.rectangle(img, (x, y), (x + w, y + h), (0, 255, 0), 2)

Putting Text in Image.

#cv2.putText(src, text, position,font,fontSize,color,thickness)

cv2.putText(img, text, (10, 20), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 255), 2)

findContours.

Reading frame from camera — video streaming.

Moving Object Detection.

 Moving object detection is a technique used in computer vision and image processing. Multiple consecutive frames from a video are compared by various methods to determine if any moving object is detected.



Moving Object detection.

import imutils import time import cv2

vs = cv2.VideoCapture(0) firstFrame = None area=500

```
while True:
              _{\text{-,img}} = \text{vs.read()}
              text = "Normal"
              img = imutils.resize(img, width=500)
              grayImg = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
              grayImg = cv2.GaussianBlur(grayImg, (21, 21), 0)
              if firstFrame is None:
                               firstFrame = grayImg
                               continue
              imgDiff = cv2.absdiff(firstFrame, grayImg)
              threshImg = cv2.threshold(imgDiff, 25, 255, cv2.THRESH_BINARY)[1]
              threshImg = cv2.dilate(threshImg, None, iterations=2)
              cnts = cv2.findContours(threshImg.copy(), cv2.RETR_EXTERNAL,
                               cv2.CHAIN_APPROX_SIMPLE)
              cnts = imutils.grab_contours(cnts)
              for c in cnts:
                               if cv2.contourArea(c) < area:
                                                continue
                               (x, y, w, h) = cv2.boundingRect(c)
                               cv2.rectangle(img, (x, y), (x + w, y + h), (0, 255, 0), 2)
                               text = "Moving Object detected"
                               print(text)
              cv2.putText(img, text, (10, 20),
                               cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 255), 2)
              cv2.imshow("VideoStream", img)
              cv2.imshow("Thresh", threshImg)
              cv2.imshow("Image Difference", imgDiff)
              key = cv2.waitKey(1) & 0xFF
              if key == ord("q"):
                               break
vs.release()
cv2.destroyAllWindows()
```

Today's Short Bytes – Tech News

Elon Musk's Starlink Satellites Beam Internet Into Remote Chilean Fishing Hamlet

It is one of two places in Chile to be chosen for a pilot project run by Musk to receive free Internet for a year.









Thanks!

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Course:

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Tomorrow session

Real-Time Face Detection & Tracking