

COURSE NAME:

Signal Processing for mm Wave communication for 5G and beyond

Assignment- week 9

Type of Questions: MCQ

Number of Questions: 10

Total Marks:10*1=10

1. The baseband equalizer in mmwave MIMO system data detection is not required for
- a) ML based detection algorithm.
 - b) LMMSE based equalizer design.
 - c) Least square based equalizer design.
 - d) MRC based equalizer design.

Correct option: a)

Detailed solution: lecture 48.

2. Which of the following is not a design parameter?
- a) Digital precoder in transmitter.
 - b) RF equalizer in the receiver.
 - c) RF precoder in the transmitter.
 - d) Wireless channel parameters between transmitter antenna and receiver antenna. Correct Option: d)

Detailed Solution: lecture 47

3. The parameters in mm wave channel estimation are
- a) Angle of arrival.
 - b) Angle of departure.
 - c) Channel coefficients in a particular beam.
 - d) All of the above.

Correct option: d)

Detailed solution: lecture 47.

4. Suppose we are sending a digital data stream \mathbf{s} . The elements of \mathbf{s} vector is coming from 5 different independent input data source. The diagonal entries of covariance matrix \mathbf{R}_{ss} are
- a) 1.
 - b) 0.
 - c) Inner product of $\mathbf{s}\mathbf{s}^T$.
 - d) 5.

Correct option: b)

Detailed solution: lecture 47

5. For a MIMO system, the data model is $\mathbf{y}=\mathbf{H}\mathbf{x}+\mathbf{w}$, where \mathbf{H} is the channel matrix. $\mathbf{y}, \mathbf{x}, \mathbf{w}$ are respectively received signal vector, input signal vector and AWGN noise vector. \mathbf{H}^p denotes the pseudo inverse of the channel matrix. $\mathbf{R}_{yy}, \mathbf{R}_{xx}$ and \mathbf{R}_{xy} is the respective covariance matrix denoted by the vectors. The LMMSE based equalizer depends on
- a) \mathbf{R}_{yy} and \mathbf{H}^p .
 - b) \mathbf{R}_{xy} and \mathbf{H}^p .
 - c) \mathbf{R}_{yy} and \mathbf{R}_{xy} .
 - d) \mathbf{R}_{yy} and \mathbf{R}_{xx} .

Correct option: c)

Detailed solution: Lecture 47

6. Which of the following is true for MSE?
- a) We are minimizing the cost function based on 2- norm only.
 - b) We are minimizing the cost function which is the expectation value of 2 norm cost function.
 - c) We are minimizing the expected value of 2 norm with the assumption that the estimated value will be a linear function of observed value.
 - d) None of the above.

Correct Option: b)

Detailed solution: lecture 48.

7. What is the unit of channel capacity for unit bandwidth?
- i) Bits.
 - ii) Bits/hertz.
 - iii) (Bits/second)/hertz.
 - iv) Bits*hertz.

Correct option: iii)

Detailed solution:

Channel capacity= data rate/bandwidth= (Bits/second)/Hertz.

Unit of data rate=Bits/second . Unit of Bandwidth=Hertz.

8. For a MIMO system, the data model is $\mathbf{y}=\mathbf{H}\mathbf{x}+\mathbf{w}$, where \mathbf{H} is the channel matrix of dimension 5×4 . $\mathbf{y}, \mathbf{x}, \mathbf{w}$ are respectively received signal vector, input signal vector and AWGN noise vector. \mathbf{H}^p denotes the pseudo

inverse of the channel matrix. \mathbf{R}_{yy} , \mathbf{R}_{xx} and \mathbf{R}_{xy} is the respective covariance matrix denoted by the vectors. The least square based equalizer depends on

- a) \mathbf{H}^{-1} .
- b) \mathbf{H}^p .
- c) \mathbf{R}_{yy} and \mathbf{H}^p .
- d) \mathbf{R}_{yy} and \mathbf{R}_{xx} .

Correct option: b)

Detailed solution: \mathbf{H} matrix is rank deficient matrix, so for least square (a non Bayesian equalizer) it only depends on pseudo inverse as inverse does not exist.

For a MIMO system, the data model is $\mathbf{y}=\mathbf{Hx}+\mathbf{w}$, where \mathbf{H} is the channel matrix. $\mathbf{y}, \mathbf{x}, \mathbf{w}$ are respectively received signal vector, input signal vector and AWGN noise vector. \mathbf{R}_{yy} , \mathbf{R}_{xx} , \mathbf{R}_{xy} and \mathbf{R}_{ww} is the respective covariance matrix denoted by the vectors.

9. The covariance matrix \mathbf{R}_{xy} depends on

- a) \mathbf{R}_{xx} , \mathbf{R}_{ww} and \mathbf{H} .
- b) \mathbf{R}_{ww} and \mathbf{H} .
- c) \mathbf{R}_{xx} and \mathbf{H} .
- d) \mathbf{R}_{ww} and \mathbf{R}_{xx} .

Correct Option: c)

Detailed solution: $\mathbf{R}_{xy} = \mathbf{E}[\mathbf{x}(\mathbf{Hx} + \mathbf{w})^*] = \mathbf{R}_{xx}\mathbf{H}^*$.

10. The covariance matrix \mathbf{R}_{yy} depends on

- a) \mathbf{R}_{xx} , \mathbf{R}_{ww} and \mathbf{H} .
- b) \mathbf{R}_{ww} and \mathbf{H} .
- c) \mathbf{R}_{xx} and \mathbf{H} .
- d) \mathbf{R}_{ww} and \mathbf{R}_{xx} .

Correct option: a)

Detailed solution: $\mathbf{R}_{yy} = \mathbf{E}[(\mathbf{Hx} + \mathbf{w})(\mathbf{Hx} + \mathbf{w})^*]$. Calculate the expectation to see all the terms in option **a)** are in the covariance matrix.