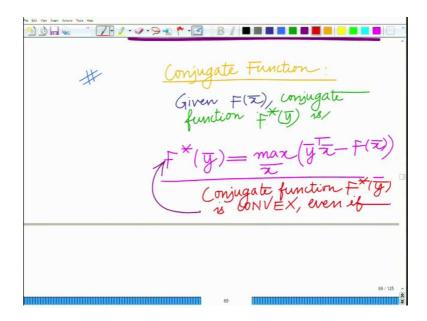
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Lecture - 30 Conjugate Function and Examples to prove Convexity of various Functions

Hello, welcome to another module in this massive open online course. Let us now focus on some examples to understand the concepts discussed later.

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So, the first example is the conjugate function of function $F(\bar{x})$ which is denoted by $F^*(\bar{y})$. It is this is given as

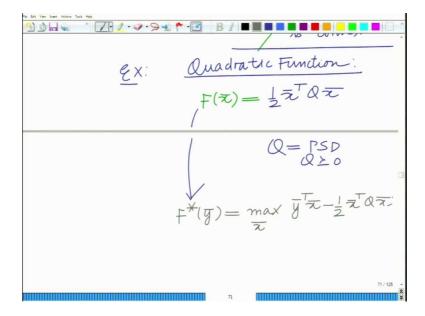
$$F^{*}(\overline{y}) = \max_{\overline{x}} (\overline{y}^{T} \overline{x} - F(\overline{x}))$$

This conjugate function $F^*(\overline{y})$ is defined such that it is convex irrespective of the convexity of $F(\overline{x})$. It is the interesting aspect of this conjugate function.

So corresponding to any function $F(\bar{x})$ being convex or non-convex, one can construct an associated convex function which is a conjugate function.

For instance, $\overline{y}^T \overline{x} - F(\overline{x})$ is a linear function in \overline{y} for each value of \overline{x} . So the maximum of a set of convex functions is also convex.

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For example consider the quadratic function.

$$F\left(\overline{x}\right) = \frac{1}{2}\overline{x}^{T}Q\overline{x}$$

Q is a symmetric positive semi definite matrix. This means

$$Q \ge 0$$

So the conjugate function is constructed as,

$$F^*(\overline{y}) = \max_{\overline{x}} \left(\overline{y}^T \overline{x} - \frac{1}{2} \overline{x}^T Q \overline{x} \right)$$

Let us say

$$g(\overline{x}) = \left(\overline{y}^T \overline{x} - \frac{1}{2} \overline{x}^T Q \overline{x}\right)$$

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Now to maximize this, differentiate $g(\bar{x})$ with respect to \bar{x} and make it equal to zero.

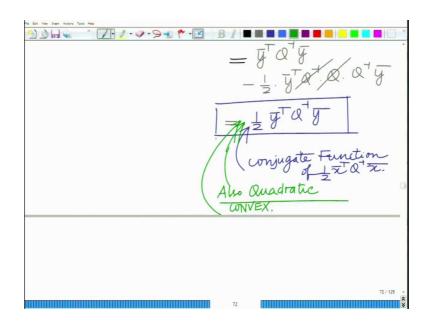
$$\nabla_{\overline{x}} g(\overline{x}) = 0$$

$$\overline{y}^{T} - \frac{2Q\overline{x}}{2} = 0$$

$$\overline{y}^{T} - Q\overline{x} = 0$$

$$\overline{x} = Q^{-1}\overline{y}$$

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Therefore the conjugate function is

$$F^*(\overline{y}) = \overline{y}^T (Q^{-1}\overline{y}) - \frac{1}{2} (Q^{-1}\overline{y})^T Q(Q^{-1}\overline{y})$$

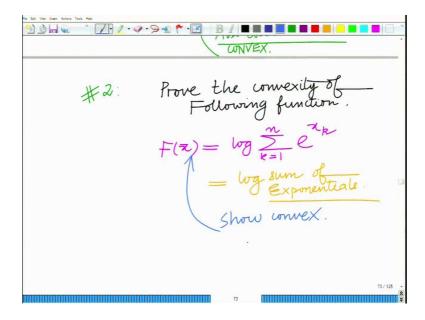
$$= \overline{y}^T Q^{-1} \overline{y} - \frac{1}{2} \overline{y}^T Q^{-1} Q Q^{-1} \overline{y}$$

$$= \overline{y}^T Q^{-1} \overline{y} - \frac{1}{2} \overline{y}^T Q^{-1} \overline{y}$$

$$= \frac{1}{2} \overline{y}^T Q^{-1} \overline{y}$$

Here it can be seen that this conjugate function is also quadratic. Hence this is convex because Q is positive semi definite which implies inverse of this matrix Q is also positive semi definite.

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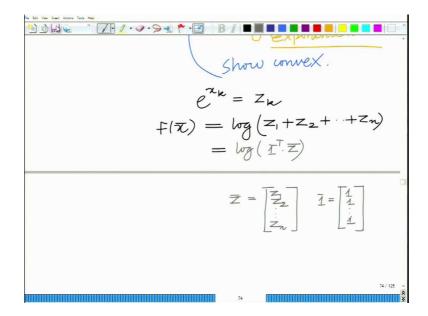


Next example is to prove the convexity of the log of sum of exponentials which is as follows.

$$F(\overline{x}) = \log \left| \sum_{k=1}^{n} e^{x_k} \right|$$

This function arises in several applications.

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To prove that this function is convex, consider

$$z_k = e^{x_k}$$

Thus the function can be represented as

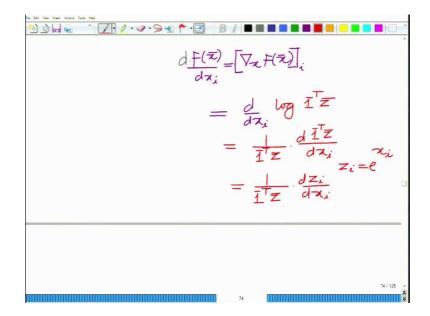
$$F(\overline{x}) = \log |z_1 + z_2 + ... + z_n|$$
$$= \log |\overline{1}^T \overline{z}|$$

Where \overline{z} and $\overline{1}$ are $n \times 1$ matrices and are defined as follows.

$$\overline{z} = \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix} \text{ and } \overline{1} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

So, if the Hessian of this function is a positive semi definite matrix then this function would be a convex function.

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So, the first order derivative of this function is

$$\frac{dF(\overline{x})}{dx_i} = \left[\nabla_x F(\overline{x})\right]_i$$

$$= \frac{d}{dx_i} \log \left|\overline{1}^T \overline{z}\right|$$

$$= \frac{1}{\overline{1}^T \overline{z}} \frac{d\left|\overline{1}^T \overline{z}\right|}{dx_i}$$

$$= \frac{1}{\overline{1}^T \overline{z}} \frac{dz_i}{dx_i}$$

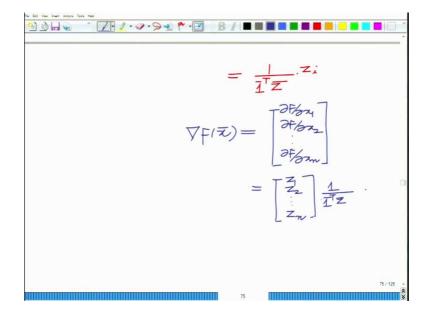
As $z_i = e^{x_i}$ thus the differentiation of z_i with respect to x_i is

$$\frac{dz_i}{dx_i} = e^{x_i} = z_i$$

Therefore

$$\frac{dF(\overline{x})}{dx_i} = \frac{1}{\overline{1}^T \overline{z}} z_i$$

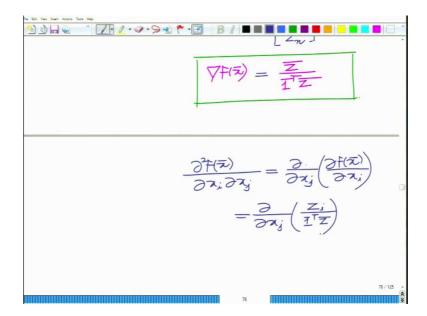
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So, the gradient of above function can be expanded as

$$\nabla_{x} F(\overline{x}) = \begin{bmatrix} \frac{\partial F}{\partial x_{1}} \\ \frac{\partial F}{\partial x_{2}} \\ \vdots \\ \frac{\partial F}{\partial x_{n}} \end{bmatrix} = \begin{bmatrix} z_{1} \\ z_{2} \\ \vdots \\ z_{n} \end{bmatrix} \frac{1}{\overline{1}^{T} \overline{z}}$$

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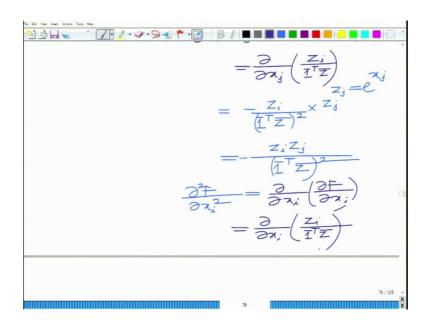
Therefore one can write it as

$$\nabla F(\overline{x}) = \frac{\overline{z}}{\overline{1}^T \overline{z}}$$

Similarly the second order derivative (Hessian) of the function is

$$\frac{\partial^{2} F(\overline{x})}{\partial x_{i} \partial x_{j}} = \frac{\partial}{\partial x_{j}} \left(\frac{\partial F(\overline{x})}{\partial x_{i}} \right)$$
$$= \frac{\partial}{\partial x_{i}} \left(\frac{z_{i}}{\overline{1}^{T} \overline{z}} \right)$$

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As $z_j = e^{x_j}$ therefore

$$\frac{\partial^{2} F(\overline{x})}{\partial x_{i} \partial x_{j}} = \frac{\partial}{\partial x_{j}} \left(\frac{z_{i}}{\overline{1}^{T} \overline{z}} \right)$$
$$= -\frac{z_{i} z_{j}}{\left(\overline{1}^{T} \overline{z} \right)^{2}}$$

Also if comparing this second order derivative with $\frac{\partial^2 F(\overline{x})}{\partial x_i^2}$ then

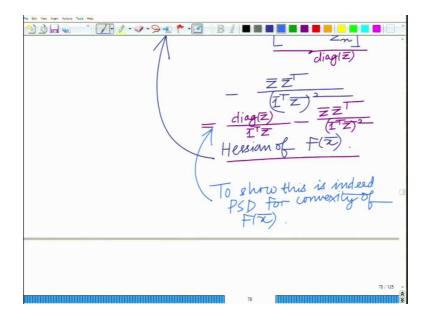
$$\frac{\partial^{2} F(\overline{x})}{\partial x_{i}^{2}} = \frac{\partial}{\partial x_{i}} \left(\frac{\partial F(\overline{x})}{\partial x_{i}} \right)$$

$$= \frac{\partial}{\partial x_{i}} \left(\frac{z_{i}}{\overline{1}^{T} \overline{z}} \right)$$

$$= \frac{z_{i}}{\overline{1}^{T} \overline{z}} - \frac{z_{i}^{2}}{\left(\overline{1}^{T} \overline{z}\right)^{2}}$$

So, here one can observe that the first term of this derivative i.e. $\frac{Z_i}{\overline{1}^T \overline{z}}$ is only present in the second order derivative form of function with respect to x_i and are not present in the second order derivative form of the function with respect to $x_i x_j$.

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Hence the Hessian of this function $F(\bar{x})$ is of the following form.

$$\nabla^{2}F(\overline{x}) = \begin{bmatrix} \frac{\partial^{2}F}{\partial x_{1}^{2}} & \frac{\partial^{2}F}{\partial x_{1}\partial x_{2}} \\ \frac{\partial^{2}F}{\partial x_{1}\partial x_{2}} & \frac{\partial^{2}F}{\partial x_{2}^{2}} \\ & \ddots \end{bmatrix}$$

So the Hessian of this function $F(\bar{x})$ is

$$\nabla^{2} F(\overline{x}) = \frac{1}{\overline{1}^{T} \overline{z}} \begin{bmatrix} z_{1} & & \\ & z_{2} & \\ & & \ddots & \\ & & z_{n} \end{bmatrix} - \frac{\overline{z} \overline{z}^{T}}{(\overline{1}^{T} \overline{z})^{2}}$$

$$= \frac{\operatorname{diag}(\overline{z})}{\overline{1}^{T} \overline{z}} - \frac{\overline{z} \overline{z}^{T}}{(\overline{1}^{T} \overline{z})^{2}}$$

The matrix $\operatorname{diag}(\overline{z})$ is the diagonal matrix of function \overline{z} . So this is the Hessian of the given function and we need to prove that this is positive semi definite to show that the given function $F(\overline{x})$ is convex. This we will do in the subsequent module.