

WBL Statistik 2024 — Nonlinear Regression

A Powerful Tool With Considerable Complexity

Half-Day 1: Estimation and Standard Inference

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Outline:

- Half-Day 1 Estimation and Standard Inference
 - The Nonlinear Regression Model
 - Iterative Estimation Model Fitting
 - Inference Based on Linear Approximations
- Half-Day 2 Improved Inference and Visualisation
 - Likelihood Based Inference
 - Profile t Plot and Profile Traces
 - Parameter Transformations
- Half-Day 3 Bootstrap, Prediction and Calibration
 - Bootstrap
 - Prediction
 - Calibration

Outlook

Your Lecturer



Name: Andreas Ruckstuhl
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Education: Dr. sc. math. ETH

Position: Professor of Statistical Data Analysis, ZHAW Winterthur

Lecturer, WBL Applied Statistics, ETH Zürich

Expierence:

1987 – 1991 Statistical Consulting and Teaching Assistant,

Seminar für Statistik, ETHZ

1991 – 1996 PhD, Teaching Assistant, Lecturer in NDK/WBL, ETHZ

1996 Post-Doc, Texas A&M University, College Station, TX, USA

1996 – 1999 Lecturer, ANU, Canberra, Australia

Since 1999 Institute of Data Analysis and Process Design, ZHAW

1.1 The Nonlinear Regression Model

The regression model

$$Y_i = h \left\langle x_i^{(1)}, \dots, x_i^{(m)}; \ \theta_1, \theta_2, \dots, \theta_p \right\rangle + E_i \quad \text{with E_i indep. \mathcal{N}} \left\langle 0, \sigma^2 \right\rangle$$

In case of the linear regression model

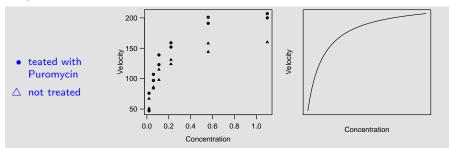
$$h\left\langle x_{i}^{(1)},\dots,x_{i}^{(m)};\; \theta_{1},\theta_{2},\dots,\theta_{p} \right\rangle = \theta_{1}\cdot 1 + \theta_{2}x_{i}^{(2)} + \dots + \theta_{p}x_{i}^{(p)}$$
 (i.e., $m=p$)

Examples of nonlinear regression function:

$$\begin{split} h\langle x_i;\underline{\theta}\rangle &= \frac{\theta_1 x_i^{\theta_3}}{\theta_2 + x_i^{\theta_3}} \\ h\langle x;\underline{\theta}\rangle &= \exp\left\langle \theta_1 \left(x_i^{(1)} \right)^{\theta_3} \exp\left\langle -\frac{\theta_2}{x_i^{(2)}} \right\rangle \right\rangle \end{split}$$

Example: Puromycin

The Michaelis-Menten model for enzyme kinetics relates the initial "velocity" of an enzymatic reaction to the substrate concentration

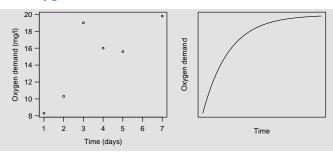


$$Y_i = \frac{\theta_1 \cdot x_i}{\theta_2 + x_i} + E_i$$
 with E_i i.i.d. $\sim \mathcal{N} \langle 0, \sigma^2 \rangle$ (Michaelis-Menten model)

x substrate concentration [ppm]
Y initial "velocity" [((number of counts)/min)/min]

Example: Biochemical Oxygen Demand (BOD)

Biochemical oxygen demand of stream water

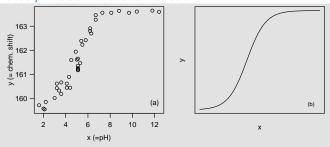


$$Y_i = \theta_1 \cdot (1 - e^{\theta_2 \cdot x_i}) + E_i \quad \text{mit } E_i \text{ i.i.d. } \sim \mathcal{N} \langle 0, \sigma^2 \rangle$$

where Y is the biochemical oxygen demand (BOD) $[mg/\ell]$ and x the incubation time [days]

Example: Cellulose Membrane

Ratio of protonated to deprotonated carboxyl groups within the pore of celluose membrane versus pH value x of the bulk solution



Theoretically, this relation is described by the Henderson-Hasselbalch equation,

$$Y_i = \frac{\theta_1 + \theta_2 \cdot 10^{\theta_3 + \theta_4 x_i}}{1 + 10^{\theta_3 + \theta_4 x_i}} + E_i \qquad i = 1, \dots, n, \quad \text{with } E_i \text{ i.i.d. } \sim \mathcal{N}\left\langle 0, \sigma^2 \right\rangle.$$

Transformably Linear Models

$$h\langle x, \underline{\theta} \rangle = \theta_1 \cdot \exp\left\langle \frac{\theta_2}{x} \right\rangle$$

Applying the log-transformation, we obtain

$$\begin{split} \log \left\langle h \left\langle x, \, \underline{\theta} \right\rangle \right\rangle &= \log \left\langle \theta_1 \cdot \exp \left\langle \frac{\theta_2}{x} \right\rangle \right\rangle \\ &= \log \left\langle \theta_1 \right\rangle + \log \left\langle \exp \left\langle \frac{\theta_2}{x} \right\rangle \right\rangle \\ &= \log \left\langle \theta_1 \right\rangle + \theta_2 \cdot \frac{1}{x} \end{split}$$

Hence

$$\log\left\langle h\left\langle x,\,\underline{\beta}\right\rangle \right\rangle = \beta_1 + \beta_2 \widetilde{x}$$

The "complete" transformably linear regression model is

$$\log \left\langle Y_{i}\right\rangle =\beta_{1}+\beta_{2}\widetilde{x_{i}}+E_{i}\;,\quad E_{i}\;i.i.d.\;\sim\mathcal{N}\left\langle 0,\;\sigma^{2}\right\rangle$$

The error term is additive

In the original representation, the regression model transforms to

$$Y_i = \exp\left\langle \beta_1 + \beta_2 \widetilde{x}_i + E_i \right\rangle$$
$$= \theta_1 \cdot \exp\left\langle \frac{\theta_2}{x} \right\rangle \cdot \widetilde{E}_i$$

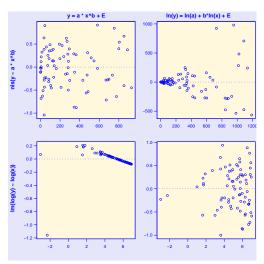
i.e., \widetilde{E}_i is log-normally distributed and the error is multiplicative.

Conclusion:

Transform to a linear regression model only if required by the error structure.

Check assumptions on error term by residual analysis.

If there is a deterministic model $y=\theta_1\cdot x^{\theta_2}$, the random component may be either additiv or multiplicativ. – The Tukey-Anscombe plot of the fitted model will show clearly which model is more adequate for the data.



A selection of transformably linear models

$$h\langle x, \theta \rangle = 1/(\theta_1 + \theta_2 \exp\langle -x \rangle)$$

$$\longrightarrow$$

$$1/h\langle x, \underline{\theta}\rangle = \theta_1 + \theta_2 \exp\langle -x \rangle$$

$$h\langle x, \underline{\theta} \rangle = \theta_1 x / (\theta_2 + x)$$

$$1/h\langle x, \underline{\theta}\rangle = 1/\theta_1 + \theta_2/\theta_1 \frac{1}{x}$$

$$h\langle x, \underline{\theta} \rangle = \theta_1 x^{\theta_2}$$

$$\longrightarrow$$

$$\ln \langle h \langle x, \underline{\theta} \rangle \rangle = \ln \langle \theta_1 \rangle + \theta_2 \ln \langle x \rangle$$

$$h\langle x, \underline{\theta} \rangle = \theta_1 \exp \langle \theta_2 g \langle x \rangle \rangle$$

$$\ln\langle h\langle x,\,\underline{\theta}\rangle\rangle = \ln\langle \theta_1\rangle + \theta_2 g\langle x\rangle$$

$$h\langle x,\underline{\theta}\rangle = \exp\left\langle -\theta_1 x^{(1)} \exp\left\langle -\theta_2 / x^{(2)} \right\rangle \right\rangle \iff \ln\left\langle \ln\left\langle h\langle x,\underline{\theta}\rangle\right\rangle \right\rangle = \ln\left\langle -\theta_1 \right\rangle + \ln\left\langle x^{(1)} \right\rangle - \theta_2 / x^{(2)}$$

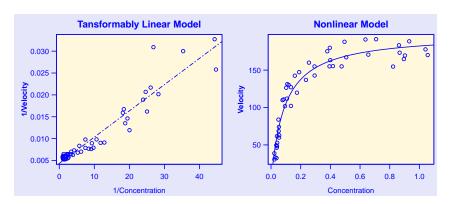
$$h\langle x, \underline{\theta} \rangle = \theta_1 \left(x^{(1)} \right)^{\theta_2} \left(x^{(2)} \right)^{\theta_3}$$

$$\longleftrightarrow \ln \langle h \langle x, \underline{\theta} \rangle \rangle = \ln \langle \theta_1 \rangle + \theta_2 \ln \langle x^{(1)} \rangle + \theta_3 \ln \langle x^{(2)} \rangle$$

Note that

it is not sufficient to examine the fit in a scatter plot of response versus exploratory variable,

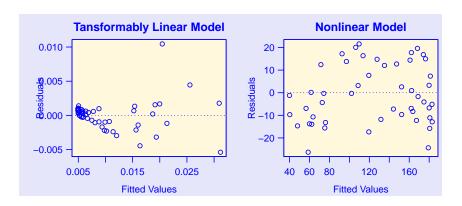
since the nonlinearity of the fitted curve prevents an assessment of the specified error structure.



Which model fits the data better?

Use Tukey-Anscombe plot to check whether

- the expectation of the error is zero
- the variability of the error is constant



1.2 Model Fitting Using an Iterative Algorithm

The method of least squares:

Find the minimum of

$$S\langle\underline{\theta}\rangle = \sum_{i=1}^{n} (y_i - \eta_i \langle\underline{\theta}\rangle)^2 \quad \text{mit } \eta_i \langle\underline{\theta}\rangle = h\langle\underline{\theta},\underline{x}_i\rangle .$$

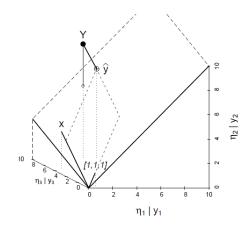
Key steps for minimising:

- approximate the surface $\underline{\eta} \langle \underline{\theta} \rangle$ at a temporarily best value $\underline{\theta}^{(\ell)}$ by a tangent plane where $\eta \langle \underline{\theta}^{(\ell)} \rangle$ is the point of contact.
- **search the point on the plane**, which is closest to <u>Y</u> (that is a linear regression fitting problem).
- The new point lies on the plain but not on the surface. However, it defines a parameter vector $\theta^{(\ell+1)}$ which will be used in the next iteration step.

Geometrical Illustration

Geometric illustration of the least squares fit in the case of *linear* regression with three observations (y_i, x_i) , i = 1, 2, 3.

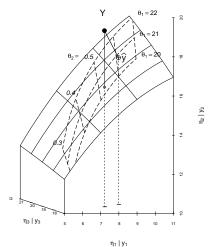
We can calculate the three model values $\eta_i \left\langle \underline{\beta} \right\rangle = \beta_0 + \beta_1 x_i$ and represent the corresponding vector $\underline{\eta} \left\langle \underline{\beta} \right\rangle = \beta_0 \underline{1} + \beta_1 \underline{x}$ as a point depending on given parameters β_0 and β_1 .



Geometrical Illustration

Geometric illustration of the least squares fit in the case of *nonlinear* regression with three observations (y_i, x_i) , i = 1, 2, 3.

We can calculate the three model values $\eta_i \left\langle \underline{\beta} \right\rangle = \theta_1 \exp \left\langle 1 - \theta_2 x_i \right\rangle$ and represent the corresponding vector $\underline{\eta} \left\langle \underline{\beta} \right\rangle = \left[\eta_1 \left\langle \underline{\beta} \right\rangle, \eta_2 \left\langle \underline{\beta} \right\rangle, \eta_3 \left\langle \underline{\beta} \right\rangle \right]^T$ as a point depending on given parameters θ_1 and θ_2 .



Algebraically formulated Gauss-Newton Algorithm

1 Linear approximation of $\eta_i \langle \underline{\theta} \rangle$ at $\underline{\theta}^{(\ell)}$:

$$\underline{\eta}_i \langle \underline{\theta} \rangle \approx \underline{\eta}_i \langle \underline{\theta}^{(\ell)} \rangle + \mathbf{A}^{(\ell)} \left(\underline{\theta} - \underline{\theta}^{(\ell)} \right) ,$$

where $\mathbf{A}^{(\ell)}$ defines the tangent plane in the ℓ -th iteration step, i.e., $\mathbf{A}^{(\ell)} = \mathbf{A} \left\langle \underline{\theta}^{(\ell)} \right\rangle$ is the derivative matrix of $\eta \left\langle \underline{\theta} \right\rangle$ at $\underline{\theta}^{(\ell)}$.

2 (Locally) linear regression model

$$\begin{split} & \underline{\widetilde{Y}}^{(\ell)} \approx \mathbf{A}^{(\ell)} \, \underline{\beta}^{(\ell)} + \underline{\mathbf{E}} \\ & \text{where} \quad \underline{\widetilde{Y}}^{(\ell)} = \underline{Y} - \underline{\eta} \, \big\langle \underline{\theta}^{(\ell)} \big\rangle \quad \text{and} \quad \underline{\beta}^{(\ell)} = \underline{\theta} - \underline{\theta}^{(\ell)} \end{split}$$

3 Least-squares estimation for $\beta^{(\ell)} \to \widehat{\beta}^{(\ell)}$.

Set
$$\theta^{(\ell+1)} = \theta^{(\ell)} + \widehat{\beta}^{(\ell)}$$
.

4 Repeat steps 1 to 3 until the procedure converges.

result $\widehat{\theta} = \theta^{(\ell+1)}$

Starting Values

- interpret the behaviour of the regression function in terms of the parameter analytically or graphically
- transform the regression function to obtain simpler, preferably linear, behaviour
- use your knowledge from previous or similar experiments

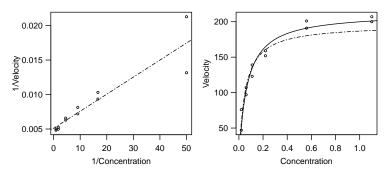
Example Puromycin (2) - using transformation

$$y \approx h \langle x, \underline{\theta} \rangle = \frac{\theta_1 \cdot x_i}{\theta_2 + x_i}$$
 transform to linearity
$$\widetilde{y} = \frac{1}{y} \approx \frac{1}{h \langle x, \underline{\theta} \rangle} = \frac{\theta_2}{\theta_1} \cdot \frac{1}{x} + \frac{1}{\theta_1}$$
 that is
$$\widetilde{y} \approx \beta_1 \widetilde{x} + \beta_0$$

linear regression (robustly estimated) ($\widehat{\beta} = (0.005, 0.00025)^T$

starting values:
$$\widehat{\theta}_1^0 = \frac{1}{\widehat{\beta}_0} \approx 196$$
 $\widehat{\theta}_2^0 = \frac{\widehat{\beta}_1}{\widehat{\beta}_0} \approx 0.048$

Example Puromycin (3)



Left: Regression line used for determining the starting values θ_1 and θ_2 .

Right: Regression function $h\langle x;\underline{\theta}\rangle$ based on the starting values $\underline{\theta}=\underline{\theta}^{(0)}$ (----) and based on the least-squares estimation $\underline{\theta}=\widehat{\underline{\theta}}$ (-----), respectively.

Example: Cellulose membrane (2) - starting values

$$h\langle x;\underline{\theta}\rangle = \frac{\theta_1 + \theta_2 \cdot 10^{\theta_3 + \theta_4 x}}{1 + 10^{\theta_3 + \theta_4 x}}$$

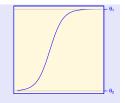
 $\mathsf{mit}\;\theta_{\mathsf{4}}<\mathsf{0}$

We know:

$$h\langle x;\underline{\theta}\rangle \longrightarrow \theta_1 \qquad \text{for } x \to \infty$$

$$h\langle x; \underline{\theta} \rangle \longrightarrow \theta_2 \qquad \text{for } x \to -\infty$$

From data, we obtain $\theta_1^{(0)} = 163.7$ und $\theta_2^{(0)} = 159.5$

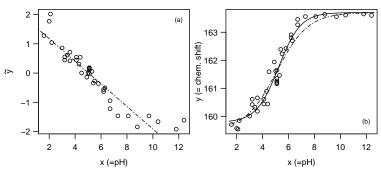


Let
$$\widetilde{y}_i = \log_{10} \left\langle \frac{\theta_1^{(0)} - y_i}{y_i - \theta_2^{(0)}} \right\rangle,$$
hence
$$\widetilde{y}_i = \theta_3 + \theta_4 x_i.$$

Simple linear regression results in starting values for both θ_3 and θ_4

$$\theta_3^{(0)} = 1.83$$
 and $\theta_4^{(0)} = -0.36$.

Example: Cellulose membrane (3)



- (a) Regression line used for determining the starting values $heta_3$ and $heta_4$.
- (b) Regression function $h\langle x; \underline{\theta} \rangle$ based on the starting values $\underline{\theta} = \underline{\theta}^{(0)}$ (----) and based on the least-squares estimation $\underline{\theta} = \widehat{\underline{\theta}}$ (-----), respectively.

Self-Starter Function

- For repeated use of the same nonlinear regression model
 use an automated way of providing starting values.
- Basically, collect all the manual steps which are necessary to obtain the initial values for a nonlinear regression model into a function.
- Self-starter functions are specific for a given mean function and calculates starting values for a given dataset.
- Let SSmicmen() (c.f. next slide) be the self-starter function for the Michaelis-Menton model. You can then run the fitting process as nls(rate ~ SSmicmen(conc, Vm, K), data=D.minor)
- How to write your own self-starter functions see help or, e.g., Ritz & Streibig (2008), Sec 3.2
- With the standard installation of R, the following self-starter functions are implemented:

Self-Starter Functions in the Standard Installation

Model	Mean Function	Name of Self-Starter Function
Biexponential	$A1 \cdot e^{-x \cdot e^{lrc1}} + A2 \cdot e^{-x \cdot e^{lrc2}}$	SSbiexp(x, A1, lrc1, A2, lrc2)
Asymptotic regression	$Asym + (R0 - Asym) \cdot e^{-x \cdot e^{lrc}}$	SSasymp(x, Asym, RO, 1rc)
Asymptotic regression with offset c0	$Asym \cdot (1 - e^{-(x-c0) \cdot e^{lrc}})$	SSasympOff(x, Asym, 1rc, c0)
Asymptotic regression $(c0 = 0)$	$Asym \cdot (1 - e^{-x \cdot e^{lrc}})$	SSasympOrig(x, Asym, 1rc)
First-order	$\times 1 \cdot \frac{e^{IKe + IKa - ICI}}{e^{IKa} - e^{IKe}}$	SSfol(x1, x2, 1Ke, 1Ka, 1C1)
compartment	$\cdot (e^{-x2\cdot e^{lKe}} - e^{-x2\cdot e^{lKa}})$	
Gompertz	$Asym \cdot e^{-b2 \cdot b3x}$	SSgompertz(x, Asym, b2, b3)
Logistic	$A + \frac{B-A}{1+e^{(xmid-x)/scal}}$	SSfpl(x, A, B, xmid, scal)
Logistic (A = 0)	$\frac{Asym}{1+e^{(xmid-x)/scal}}$	SSlogis(x, Asym, xmid, scal)
Michaelis-Menten	$Vm \cdot \frac{x}{K+x}$	SSmicmen(x, Vm, K)
Weibull	$Asym-Drop\cdot e^{-e^{lrc}\cdot xpwr}$	SSweibull(x, Asym, Drop, lrc, pwr)

3 Inference Based on Linear Approximations

As a look on the summary output of the Example "Cellulose Membrane" shows it look very similar to the summary output of a fitted linear regression model:

```
> Mem.fit <- nls(delta \sim (T1 + T2*10^(T3+T4*pH))/(10^(T3+T4*pH)+1),
            D.membran, start=list(T1=163.7, T2=159.5, T3=1.83, T4=-0.36))
> summary(Mem.fit)
Formula: delta \sim (T1 + T2 * 10^{\circ}(T3 + T4 * pH))/(10^{\circ}(T3 + T4 * pH) + 1)
 Parameters:
       Value Std. Error t value Pr(>|t|)
 \theta_1
     163.706
                  0.1262 \quad 1297.26 \quad < 2e-16
                                                ***
 \theta_2 = 159.785
                  0.1594 1002.19 < 2e-16 ***
 \theta_3 2.675 0.3813 7.02 3.65e-08
                                                ***
 \theta_{4} -0.512 0.0703 -7.28 1.66e-08
                                                ***
```

Residual standard error: 0.293137 on 35 degrees of freedom

Number of iterations to convergence: 7
Achieved convergence tolerance: 3.652e-06

The Asymptotic Properties

The asymptotic properties are based on the local linearization of the model (cf. iterative estimation procedure, SLIDE 16, step 2)

$$\underline{Y} = \eta \langle \underline{\theta} \rangle + \mathbf{A} \widehat{\beta} + \underline{E}$$

where $\mathbf{A}\langle\theta\rangle$ is the $n\times p$ matrix of partial derivatives.

If the estimation procedure has converged, then $\widehat{\beta} = \underline{\mathbf{0}}$.

Asymptotic Distribution of the Least Squares Estimator

$$\widehat{\underline{\theta}} \stackrel{\text{a}}{\sim} \mathcal{N} \langle \underline{\theta}, \mathbf{V} \langle \underline{\theta} \rangle \rangle$$

with asymptotic covariance matrix

$$\mathbf{V} \langle \underline{\theta} \rangle = \sigma^2 (\mathbf{A} \langle \underline{\theta} \rangle^T \mathbf{A} \langle \underline{\theta} \rangle)^{-1}$$

Application in Practise

To explicitly determine the covariance matrix $V\langle\underline{\theta}\rangle$, we plug-in estimates instead of true parameters:

- $\mathbf{A} \langle \theta \rangle$ is calculated using $\widehat{\theta} \bowtie \widehat{\mathbf{A}}$.
- For the error variance σ^2 we plug-in the usual estimation.

Hence.

$$\widehat{\mathbf{V}} = \widehat{\sigma}^2 \, \left(\widehat{\mathbf{A}}^T \widehat{\mathbf{A}} \right)^{-1}$$

where

$$\widehat{\sigma}^2 = \frac{S\left\langle \widehat{\underline{\theta}} \right\rangle}{n-p} = \frac{1}{n-p} \sum_{i=1}^n \left(y_i - \eta_i \left\langle \widehat{\underline{\theta}} \right\rangle \right)^2 \quad \text{and} \quad \widehat{\boldsymbol{A}} = \boldsymbol{A} \left\langle \widehat{\underline{\theta}} \right\rangle.$$

Approximate 95%-confidence interval

Hence, an approximate 95%-confidence interval for β_k is

$$\widehat{\theta}_k \pm \widehat{\operatorname{se}} \left\langle \widehat{\beta}_k \right\rangle \cdot q_{0.975}^{t_{n-p}},$$

where $\widehat{\mathsf{se}}\left\langle \widehat{\beta}_{k}\right\rangle$ is the square root of the kth diagonal element of $\widehat{m{V}}$.

Note: Theoretically correct is to use the quantiles of the Gaussian distribution. In practise, however, t quantiles are preferred.

Example "Cellulose Membrane"

From the summary output

Parameters:

	Value	Std. Error	t value	$\Pr(> t)$	
$ heta_1$	163.706	0.1262	1297.26	< 2e-16	***
θ_2	159.785	0.1594	1002.19	< 2e-16	***
θ_3	2.675	0.3813	7.02	3.65e-08	***
θ_4	-0.512	0.0703	-7.28	1.66e-08	***

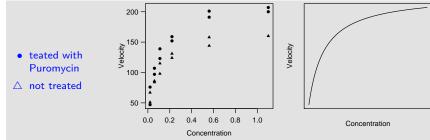
Residual standard error: 0.293137 on 35 degrees of freedom

we can calculate the 95% confidence interval for θ_1 :

$$163.71 \pm 0.13 \cdot q_{0.975}^{t_{35}} = 163.71 \pm 0.26$$

Example: Puromycin - back to the initial data set

The Michaelis-Menten model for enzyme kinetics relates the initial "velocity" of an enzymatic reaction to the substrate concentration



$$Y_i = \frac{\theta_1 \cdot x_i}{\theta_2 + x_i} + E_i$$
 with E_i i.i.d. $\sim \mathcal{N} \langle 0, \sigma^2 \rangle$ (Michaelis-Menten model)

x substrate concentration [ppm]

Y initial "velocity" [(number/min)/min]

1 44

Example: Puromycin (4)

Modell:
$$Y_i = \frac{\theta_1 x_i}{\theta_2 + x_i} + E_i$$
.

Model with and without treatment (all data):

$$Y_i = \frac{(\theta_1 + \theta_3 z_i)x_i}{\theta_2 + \theta_4 z_i + x_i} + E_i .$$
where $z_i = \begin{cases} 1 & \text{for "with"} \\ 0 & \text{for "without"} \end{cases}$

Working hypothesis: **Only** the asymptotic velocity θ_1 is influenced by adding Puromycin. Hence

Null hypothesis: $\theta_4 = 0$

R output for the example Puromycin

Parameters:							
	Value	Std. Error	t value	Pr(> t)			
θ_1	160.286	6.8964	23.24	2.04e-15			
θ_2	0.048	0.0083	5.76	1.50e-05			
θ_3	52.398	9.5513	5.49	2.71e-05			

0.0114

Residual standard error: 10.4 on 19 df

0.016

Since the P-value of 0.167 is larger than the level of 5%

the null hypothesis is not rejected on the 5% level.

95% confidence interval for θ_4 : $0.016 \pm 0.0114 \cdot q_{0.975}^{t_{19}} =$ [-0.0079, 0.0399]

0.167

Inference for the expected value $E\langle Y|x_o\rangle=h\langle x_o;\underline{\theta}\rangle$ at x_o

Linear Regression

$$h\langle \underline{x}_o, \underline{\beta} \rangle = \underline{x}_o^T \underline{\beta}$$
 is estimated by

$$\widehat{\eta}_o = \underline{x}_o^T \widehat{\underline{\beta}} .$$

 $(1-\alpha)\cdot 100\%$ confidence interval for $h\langle \underline{x}_o, \beta \rangle$ is

$$\widehat{\eta}_o \pm q_{1-lpha/2}^{t_{n-p}} \cdot \operatorname{se}\langle \widehat{\eta}_o
angle$$

with
$$\operatorname{se}\langle \widehat{\eta}_o \rangle = \widehat{\sigma} \sqrt{\underline{x}_o^T (\boldsymbol{X}^T \boldsymbol{X})^{-1} \underline{x}_o}$$

Nonlinear Regression

 $h\langle \underline{x}_o, \underline{\theta} \rangle$ is estimated by

$$\widehat{\eta}_o = h\left\langle \underline{x}_o, \widehat{\underline{\theta}} \right\rangle$$
.

 $(1-lpha)\cdot 100\%$ confidence interval for $h\langle \underline{x}_o,\underline{\theta}
angle$ is

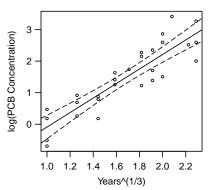
$$h\left\langle x_{o},\widehat{\underline{\theta}}\right
angle \pm q_{1-lpha/2}^{t_{n-p}}\cdot\operatorname{se}\left\langle \widehat{\eta}_{o}
ight
angle$$

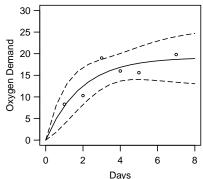
$$\begin{split} & \text{with} \quad \sec \left\langle \widehat{\eta}_o \right\rangle = \widehat{\sigma} \, \sqrt{\widehat{\underline{a}}_o{}^T \big(\widehat{\pmb{A}}^T \widehat{\pmb{A}}\big)^{-1} \widehat{\underline{a}}_o} \\ & \text{and} \quad \widehat{\underline{a}}_o = \frac{\partial h \left\langle \mathbf{x}_o, \underline{\theta} \right\rangle}{\partial \theta} \big|_{\theta = \widehat{\theta}} \, . \end{split}$$

Confidence Band

Left: Confidence band (i.g., pointwise confidence intervals) for a fitted straight line (linear regression model).

Right: Confidence band for the fitted curve $h\langle x,\underline{\theta}\rangle$ of the example 'Biochemical Oxygen Demand'.





Variable Selection

How about variable selection in nonlinear regression?

- There is no one-to-one correspondence between predictor variables and parameter as in linear regression!
 the number of variables may differ from the number of parameters.
- There are hardly ever problems, where some of the variables are in question because model is derived from subject matter theory!
- However, there are problems where a nested submodel may be adequat to describe the data;
 - cf. Example Puromycin, SLIDE 28.
- Model Selection: If we have a collection of candidate models
 - which need not to be nested submodels of each other and
 - the subject matter is somehow indifferent to this models,
 - but we want to find the most appropriate model for the data

one can use Akaike's information criterion (AIC) to select the best model and run a residual analysis to confirm the selection.

Take Home Message Half-Day 1

• In nonlinear regression,

$$Y_i = h\langle \mathbf{x}_i, \underline{\theta} \rangle + E_i$$

functions h are analysed which are not linear functions of the unknown parameters θ .

Such models are often derived from the subject matter theory.

- The flexibility of this model class is bought by a more complex estimation and inference theory.
 - Parameter estimation is done by an iterative procedure which needs appropriate starting values.
 - Inference is based on an asymptotic theory.
 For finite sample size the results just hold approximately
 - Model assumptions are assessed like in linear regression modelling.