#### 1 Basics

• General p-norm:  $||x||_p = (\sum_{i=1}^n |x_i|^p)^{1/p}$ 

• Hoelder:  $||uv||_1 \le ||u||_p ||v||_q$ ,  $||u+v||_p \le ||u||_p + ||v||_p$ 

• Triangle:  $||u + v||_p \le ||u||_p + ||v||_p$ 

• Cauchy-Schwarz:  $|\langle u, v \rangle|^2 \le ||u||^2 ||v||^2$ 

• Cauchy-Schwarz:  $|\mathbb{E}[X,Y]|^2 \le \mathbb{E}[X^2]\mathbb{E}[Y^2]$ 

• Taylor:  $f(x) \approx f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots$ 

 $\circ f(\mathbf{x}) \approx f(\mathbf{a}) + \frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} \Big|_{\mathbf{a}} - \frac{1}{2} (\mathbf{x} - \mathbf{a})^{\top} \left( \frac{\partial^2 f(\mathbf{x})}{\partial \mathbf{x} \partial \mathbf{x}^{\top}} \right) \Big|_{\mathbf{a}} (\mathbf{x} - \mathbf{a})$ 

• Power series of exp.:  $\exp(x) := \sum_{k=0}^{\infty} \frac{x^k}{k!}$ 

• Entropy:  $H(X) \equiv H(p_X) = \mathbb{E}_X[-\log \mathbb{P}(X = x)]$ 

 $\circ H(X \mid Y) = \sum_{y} \mathbb{P}(Y = y) H(X \mid Y = y) \le H(X)$ 

 $\circ H(X,Y) = H(X) + H(Y \mid X)$ 

 $\circ\ H(X\mid g(X))\geq 0 \quad \circ H(g(X)\mid X)=0$ 

 $\circ H(cX) \begin{cases} = H(X) & \text{discrete} \\ = H(X) + \log|c| > H(X) & \text{continuou} \end{cases}$ 

• MI: I(X;Y|Z) = H(X|Z) - H(X|Y,Z) (symmetric)

 $\circ \ I(X;Y) = D_{\mathrm{KL}}(p(x,y) \parallel p(x)p(y)) \geq 0$ 

 $I(X_1,...,X_n;Z) = \sum_{i=1}^n I(X_i;Z \mid X_1,...,X_{i-1})$  Markov chain:  $I(X_1;X_2,X_3,...) = I(X_1;X_2)$ 

 $\circ I(X,Y;Z) = I(X;Z) + I(Y;Z \mid X)$ 

• KL-divergence:  $D_{KL}(p \parallel q) = \sum_{x} p(x) \log \left( \frac{p(x)}{q(x)} \right) \ge 0$ 

•  $1-z \le \exp(-z)$ 

• Jensen, f(X) convex:  $f(\mathbb{E}[X]) \le \mathbb{E}[f(X)]$ 

#### 1.1 Calculus

• Partial:  $\int uv' dx = uv - \int u'v dx$  •  $\frac{\partial}{\partial x} \frac{g}{h} = \frac{g'h}{h^2} - \frac{gh'}{h^2}$ 

•  $\frac{\partial}{\partial x}(\|\mathbf{x} - \mathbf{b}\|_2) = \frac{x - \mathbf{b}}{\|\mathbf{x} - \mathbf{b}\|_2}$  •  $\frac{\mathrm{d}}{\mathrm{d}x}|x| = \frac{x}{|x|}$ 

•  $\frac{\partial}{\partial X} \log |X| = X^{-\top}$  •  $|X^{-1}| = |X|^{-1}$ 

•  $\frac{\partial}{\partial x}(b^{\top}x) = \frac{\partial}{\partial x}(x^{\top}b) = b$ 

•  $\frac{\partial}{\partial x}(b^{\top}Ax) = A^{\top}b$  •  $\frac{\partial}{\partial X}(c^{\top}Xb) = cb^{\top}$ 

•  $\frac{\partial}{\partial X}(c^{\top}X^{\top}b) = bc^{\top}$  •  $\frac{\partial}{\partial x}(x^{\top}x) = 2x$ 

•  $\frac{\partial}{\partial x}(x^{\top}Ax) = (A^{\top} + A)x \stackrel{A \text{ sym.}}{=} 2Ax$ 

•  $\frac{\partial}{\partial \mathbf{X}} Tr(\mathbf{X}^{\top} \mathbf{A}) = \mathbf{A}$  • Trace trick:  $\mathbf{x}^{\top} \mathbf{A} \mathbf{x} = \dots$ 

 $\dots \stackrel{\text{inn. prod.}}{=} Tr(\mathbf{x}^{\top} A \mathbf{x}) \stackrel{\text{cycl. permut.}}{=} Tr(\mathbf{x} \mathbf{x}^{\top} A) = Tr(A \mathbf{x} \mathbf{x}^{\top})$ 

## **2 Maximum Entropy Inference**

Sample  $c \sim p(\cdot \mid X)$  s.t.  $H[p(\cdot \mid x)]$  is maximal,

 $\mathbb{E}_{C|X}[R(C,X)] = \mu \text{ and } \sum_{c} p(c \mid X) = 1.$ 

 $\implies$  Gibbs dist.:  $p(c \mid X) = \frac{1}{Z(X)} \exp(-\beta R(c, X))$ 

Free energy:  $F(X) := -\frac{1}{\beta} \log Z(X)$ 

 $\iff p(c \mid X) = \exp(-\beta [R(c, X) - F(X)])$ 

 $\implies$  entropy:  $H[c \mid X] = \beta \underbrace{\mathbb{E}_{C \mid X}[R(C, X)]}_{=\mu} - \beta F(X)$ 

**ME:**  $\max H[c \mid X] \iff \max Z(X) \iff \min F(X)$ 

• Exp. generalisation costs:  $\mathbb{E}_{X''}\mathbb{E}_{X''}\mathbb{E}_{C|X'}[R(c,X'')]$ 

• Min. out-of-sample descr. length per deg. of freedom  $\min_{\substack{p(\cdot|\cdot)\\p(c)}} \mathbb{E}_{X',X''} \mathbb{E}_{C\mid X'} \Big[ -\log \frac{p(c\mid X'')}{p(c)} \Big] \quad p(c) = \mathbb{E}_X \big[ p(c\mid X) \big]$   $\stackrel{\text{Jensen}}{\geq} \min_{p(\cdot|\cdot)} \mathbb{E}_{X',X''} \Big[ -\log \mathbb{E}_{C\mid X'} \big[ p(c\mid X'') \big] \Big] - H[c]$ 

**PA:**  $T^* = \operatorname{arg\,max}_T \kappa(X', X'')$ 

• PA-kernel:  $\kappa(X', X'') := \sum_{c} p(c \mid X') p(c \mid X'')$ 

 $= \max_{n(\cdot,\cdot)} \mathbb{E}_{X',X''}[e^{H[c]} \cdot \kappa(X',X'')]$ 

• combined:  $p(c \mid X', X'') \propto p(c \mid X')p(c \mid X'')$ 

#### 3 Methods for intractable Gibbs distr.

## 3.1 Markov Chains

Mixing time of MC:  $||P^t(c,\cdot) - \pi(\cdot)||_{TV} \le \epsilon$ 

 $t_{mix} \propto \frac{1}{\lambda_1 - \lambda_2}$  where  $1 = \lambda_1 > \lambda_2 \ge \dots$ 

Well behaving Markov Chains are

1. **irreducible:** can go from/to any state (n steps)

2. **aperiodic:** chain doesn't go back & forth forever  $(\forall n > n(c, c')$  (no) path length n w/ non-zero prob.)

 $1. \land 2. \implies$  unique stat. dist.  $p(c') = \sum_{c} \pi(c \mid c') p(c)$ 

 $1. \land 2. \land \text{stat.} \implies \lim_{t \to \infty} \mathbb{P}[X_t = c] = p(c) \land$ 

 $\lim_{t\to\infty} \frac{1}{4} \sum_{s=1}^t f(X_s) = \sum_c p(c) f(c)$ 

DBE  $\pi(c' \mid c)p(c) = \pi(c \mid c')p(c') \implies p \text{ stat.}$ 

**MH:**  $\lambda_2 = \max\left\{1 - \frac{q(y,x)}{p_x}, 1 - \frac{q(x,y)}{p_y}\right\} = 1 - \alpha - \beta$ 

#### 3.2 Sampling and SA

**Metropolis-Hastings:** Assume  $p(c) \propto f(c)$ .

$$\pi(c' \mid c) := \begin{cases} q(c' \mid c) A(c, c') & c \neq c \\ 1 - \sum_{c' \neq c} q(c' \mid c) A(c, c') & \text{otw.} \end{cases}$$

where  $q(c' \mid c)$ : prob. to propose the move  $c \to c'$ , and  $A(c,c') := \min\{1, \frac{q(c \mid c') f(c') / Z}{q(c' \mid c) f(c) / Z}\}$  prob. accept move **Metropolis Algorithm:** Assume  $p(c) \propto f(c)$  and  $q(c' \mid c) = q(c \mid c')$ , i.e. symmetric.

1. Define symmetric  $\{q(\cdot \mid c)\}_{c \in C}$  s.t. graph  $G_q$  is connected and every vertex in  $G_q$  has edge to itself.

2.  $c_0^T \leftarrow \$$  while  $T > \epsilon$  do:

• for t = 1, 2, ..., N, do:

 $\circ \ \tilde{c} \leftarrow q(\cdot \mid c_{t-1}^T)$  // sample

 $\circ b \leftarrow \operatorname{Bern}\left(\min\left\{1, e^{-\frac{1}{T}[R(\tilde{c}, X) - R(c_{t-1}, X)]}\right\}\right)$ 

 $\circ \text{ If } b = 1 \text{ then } c_t^T \leftarrow \tilde{c} \text{ else } c_t^T \leftarrow c_{t-1}.$ 

•  $c_0 \leftarrow c_N^T$ 

•  $T \leftarrow \text{reduce}(T)$ 

•  $c_0^T \leftarrow c_0$ 

**Temperature:** high temperature  $T \to \text{closer}$  to uniform i.e. worse ability to discriminate between good and bad models  $\to$  more likely to accept moves i.e. exploration, not stuck in bad local minima reduce temperature to find better local minima and get stuck there

## **3.3 Laplace's Method** (Least angle clust.)

1. Square the cost:  $e^{-\frac{1}{T}R(c,X)} = const \cdot e^{g(c)^{\top}g(c)}$ 

2. Complete the square:  $\int e^{-\frac{1}{T}(y-g(c))^2} dy = (\pi T)^{d/2}$  $\Rightarrow e^{g(c)^{\top}g(c)} = (\pi T)^{-d/2} \int \exp^{-y^{\top}y+2y^{\top}g(c)} dy$ 

3. Rewrite normalisation constant:

 $Z = \sum_{c} e^{-\frac{1}{T}R(c,X)} = \dots = const \int e^{-\frac{1}{T}f(y)} dy$ 

4. Apply Laplace's method:
If f has unique min.  $y_0$  and Hessian  $H := \frac{\partial^2 f}{\partial y^2}\Big|_{y_0}$   $\left[ e^{-\frac{1}{T}f(y)} dy \stackrel{(T \to 0)}{\approx} e^{-\frac{1}{T}f(y_0)} \Big|_{\frac{2\pi}{T}} \right]^{-1/2}$ 

## 3.4 Mean-field Approximation

**Idea:** Approximate  $p_{\beta}$  (Gibbs) with a "simple", factorisable distribution  $p = p_1 \cdots p_N$ .

**Approach:** Minimise  $D_{KL}(p \parallel p_{\beta})$   $\iff$  Minimise **Gibbs free energy:** 

$$G(p) = \frac{1}{\beta} D_{\mathrm{KL}}(p \parallel p_{\beta}) + F(\beta) = \mathbb{E}_{c \sim p}[R(c)] - \frac{1}{\beta} H[p]$$

Note:  $H[p] = \sum_{i=1}^{N} H[p_i]$  and  $F(\beta) \leq G(p)$ 

**Ising model:**  $R(c \mid J) = -\frac{1}{2} \sum_{i,j} J_{ij} c_i c_j - \sum_i h_i c_i$  where  $J_{ij}$ : interaction between particles,

 $h_i$ : noisy image,  $\sigma_i$ : denoised image

**Problem:**  $\frac{\partial G(p)}{\partial p_{i\ell}} = 0$  s.t.  $\sum_{\ell'} p_{i\ell'} = 1 \ \forall i$ 

**Solution:** with the *mean field*  $h_i = [\cdots h_{i\ell} \cdots]^{\top}$ 

$$h_{i\ell} := \frac{\partial \mathbb{E}[R(c)]}{\partial p_{i\ell}} = \mathbb{E}_{c \sim p_{|i \to \ell}}[R(c)] \leftarrow \text{object } i \text{ chooses}$$

$$\text{class } \ell$$

 $p_{i\ell} = \mathrm{e}^{-\beta h_{i\ell}}/Z_i$ 

**EM-like Algo:** Iteratively 1. Pick random i 2.  $h_i^{\text{new}} \leftarrow p_i^{\text{old}}$  3.  $p_i^{\text{new}} \leftarrow h_i^{\text{new}}$  until converged.

# **3.4.1 Smooth** *k***-means** scr.20 (p. 39)

 $R(c \mid X) = \sum_{i} ||x_{i} - y_{c_{i}}||^{2} + \frac{\lambda}{2} \sum_{i} \sum_{j \in N(i)} \mathbb{I}_{\{c_{i} \neq c_{j}\}}$  where the second term measures #violations of these neighbourhood constraints.

$$\implies h_{i\ell} = ||x_i - y_\ell||^2 + \lambda \sum_{i \in N(i)} p_{i\ell} + const_i$$

# **4 Deterministic Annealing** (*Z* is tractable)

**Lemma:** func's  $\times$  domain  $\rightarrow$  domain  $\times$  co-dom.

$$\mathcal{O}(K^N) \to \sum_{c} \prod_{i} \epsilon_{i,c(i)} = \prod_{i} \sum_{k} \epsilon_{ik} \leftarrow \mathcal{O}(NK)$$

$$p(c \mid \theta, X) = \prod_{i \le N} p_i(c(i) \mid \theta, X)$$

where  $p_i(k \mid \theta, X) \propto \exp(-\frac{1}{T}||x_i - \theta_k||^2)$ 

Max. entr. 
$$\implies \frac{\partial \log Z}{\partial \theta_k} = \frac{\partial \sum_{i \le n} \log \sum_{\nu \le K} \exp(-\|x_i - \theta_\nu\|^2)}{\partial \theta_k} \triangleq$$

$$0 \implies \theta_k^* = \frac{\sum_i p_i(k|\theta^*, X) \cdot x_i}{\sum_i p_i(k|\theta^*, X)}$$

do  
E-step: 
$$p_i(k|\theta^{\text{old}}, X) = \frac{\exp(-\frac{1}{T}||x_i - \theta_k||^2)}{\sum_{j \le K} \exp(-\frac{1}{T}||x_i - \theta_j||^2)}$$
  
M-step:  $\theta_k \leftarrow \frac{\sum_{i \le n} p_{ik} x_i}{\sum_{i \le n} p_{ik}}$   
 $\theta^{\text{old}} \leftarrow \theta$ 

until convergence of  $\theta$ 

 $\theta_k \leftarrow \theta_k + \epsilon$  (noise s.t. centroids can separate)

**Phase transitions:** For  $T \rightarrow \infty$ :  $\theta_k^* = \overline{X} \quad \forall k \leq K$  Once  $T = 2\lambda_{\max}$ , more centroids appear, where  $\lambda_{\max} = \max$  eigenvalue of  $\frac{1}{N}X^{\top}X$ .  $(x_i$ 's row-wise) **DA vs MAP:** 

- 1. MAP can get stuck in local maximum
- 2. MAP not robust against noisy data
- 3. DA guaranteed to obtain global optimum if annealing is slow enough and ergodicity is given
- 4. In DA T>0 gives entropic regularisation

# 5 Histogram Clustering

Least Angle Clust. (LAC): [Idea]

Similarity  $S(\mathbf{x}_i, \mathbf{x}_j) = w_{ij} \cos(\phi_{ij}) = w_{ij} \mathbf{e}_i \cdot \mathbf{e}_j$  with unit vectors  $\mathbf{e}_i \coloneqq \mathbf{x}_i / ||\mathbf{x}_i||$ , e.g. choice  $w_{ij} = ||\mathbf{x}_i|| \cdot ||\mathbf{x}_j||$ . **Dyadic data:**  $\mathcal{Z} = \{(x_{i(r)}, y_{i(r)}); 1 \le r \le \ell\}$ 

- prototype / "centroid":  $q(y_i \mid \alpha)$
- empirical dist.:  $\hat{p}(y_j \mid x_i) = \frac{\hat{p}(x_i, y_j)}{\hat{p}(x_i)} \stackrel{\text{-scr.} (5.10)}{\underset{\text{--scr.} (5.11)}{\leftarrow}}$

Likelihood:  $P(\mathcal{Z} \mid c, q) = \prod_{r \le \ell} p(x_{i(r)}, y_{j(r)} \mid c, q)$ 

 $= {}^{\text{scr.}} \stackrel{(5.12)}{\dots} = \prod_{i} \prod_{j} [q(y_{j}|c(i)) \cdot p(c(i)) \cdot p(x_{i})]^{\ell \hat{p}(x_{i}, y_{i})}$ 

Assume  $p(\alpha) = 1/k$  and  $\hat{p}(x_i) = 1/n$ 

 $\Rightarrow \textbf{Cost:} \, R^{\text{hc}}(c, q, \mathcal{Z}) = \frac{\ell}{m} \sum_{i \le n} D_{\text{KL}}[\hat{p}(\cdot \mid x_i) \parallel q(\cdot \mid c(i))]$ 

Solving the **Gibbs dist.**  $p(c \mid q, \hat{p}) = \prod_{i \le n} P_{i,c(i)}$ 

via Lagrange yields  $q^*(y_j \mid \alpha) = \frac{\sum_{i \le n} P_{i\alpha} \cdot \hat{p}(y_j \mid x_i)}{\sum_{i \le n} P_{i\alpha}}$  Lemma 2 ch.3 p.36

#### 5.1 Information Bottleneck Method

Find efficient code  $X \mapsto \hat{X}$  (codebook vector) and preserve relevant info. about context Y.

**Criterion:**  $R^{\mathrm{IB}}(q(\hat{x} \mid x)) = I(X; \hat{X}) - \beta I(\hat{X}; Y)$ 

 $\begin{aligned} & \textbf{Markov chain: } \hat{X} \xrightarrow{q(\hat{x}|x)} X \xrightarrow{p(y|x)} Y \\ & \textbf{Generation process: } w / \textit{distortion } d(x, \hat{x}) = D_{\text{KL}}[\cdot] \\ & \left\{ \begin{aligned} q_t(\hat{x}|x) & \propto q_t(\hat{x}) \cdot \exp(-\beta D_{\text{KL}}[p(y|x) \parallel p_t(y|\hat{x})]) \\ q_{t+1}(\hat{x}) & = \sum_x p(x) \cdot q_t(\hat{x} \mid x) \\ p_{t+1}(y|\hat{x}) & = \sum_x p(y \mid x) \cdot p(x) \cdot q_t(\hat{x} \mid x) / q_t(\hat{x}) \end{aligned} \right. \end{aligned}$ 

## 5.2 Parametric Distributional Clustering

**Idea:** Use a mixture of Gaussian prototypes, i.e.

$$p(y_j \mid \nu) \equiv p(b \mid \nu) = \sum_{\alpha \leq s} p(\alpha \mid \nu) \ G_{\alpha}(b) \ .$$
 
$$x_i \xrightarrow{c(i) = \nu} \nu \xrightarrow{p(b \mid \nu)} \hat{p}(b \mid i)$$
 *Note*: Feature values  $y_i$  ("bins"  $b$ ) only depend on clus-

*Note:* Feature values  $y_j$  ("bins" b) only depend on cluster index  $\nu$  and not explicitly on the site  $x_i$ !

**Notation:**  $x_i \leftarrow i$ ,  $y_j \leftarrow b$  (bins),  $v \leftarrow$  clusters **Likelihood:** (both equivalent if  $p(i) = \frac{1}{n}$ )

 $P(X \mid c, \theta) = \prod_{i < n} p(c(i)) \prod_{b < m} [p(b \mid c(i))]^{\ell \hat{p}(i,b)},$ 

 $P(X, M \mid \theta) = \prod_{i \le n} \prod_{v \le k} \left[ p(v) \cdot \prod_{b \le m} p(b \mid v)^{n_{ib}} \right]^{M_{iv}}$ 

where  $n_{ib}$ : #occur. an observ. at site i is inside  $I_b$ 

 $M_{i\nu} = p(\nu \mid i) \in \{0, 1\}$  clust. membersh. assign. **Cost (IB):**  $R^{\text{PDC}}(c, p_{\cdot \mid c}) = -\log P(X, M\theta) = \dots$  $\dots = -\sum_{i \le n} \left[ \log p_{c(i)} + \frac{\ell}{n} \sum_{b \le m} \hat{p}(b \mid i) \log p(b \mid c(i)) \right]$ 

**E-step:**  $h_{i\nu} = -\log p_{\nu} - \sum_{b} \frac{\ell}{n} \hat{p}(b \mid i) \log p(b \mid \nu)$  $q_{i\nu} = \mathbb{E}[\mathbb{I}_{\{c(i)=\nu\}}] \propto \exp(-h_{i\nu}/T)$ 

**M-step:**  $p_{\nu} = \frac{1}{n} \sum_{i \leq n} q_{i\nu}$ No closed form sol. for  $p(\alpha \mid \nu)$ . Thus, iteratively optimize pairs s.t.  $\sum_{\alpha} p(\alpha \mid \nu) = 1$ .

## **6 Graph-based Clustering**

**Non-metric relations:** might assume negative values or violate the triangular inequality.

**Setting:** objects  $o_i, o_j \in \mathcal{O}$ ; relations with weights  $\mathcal{D} := \{D_{ij}\}$  on the edges (i, j).

- Cluster  $\alpha$ :  $\mathcal{G}_{\alpha} \equiv \{ \boldsymbol{o} \in \mathcal{O} : c(\boldsymbol{o}) = \alpha \}$
- Inter-cluster edges:  $\mathcal{E}_{\alpha\beta} = \{(i,j) \in \mathcal{E} : o_i \in \mathcal{G}_\alpha \land o_j \in \mathcal{G}_\beta\}$
- $\operatorname{cut}(A,B) = \sum_{i \in A, j \in B} W_{ij} \rightarrow \operatorname{weight} \operatorname{matrix} W$

• assoc $(A, V) = \sum_{i \in A, j \in V} W_{ij} \rightarrow \text{total connection}$ strength from nodes in A to all nodes in the graph

## **Correlation clustering:**

Minimise the sum of *pairwise* intracluster distances.

$$\begin{split} R^{\text{cc}}(c;\mathcal{D}) &= -\sum_{\nu \leq k} \sum_{(i,j) \in \mathcal{E}_{\nu\nu}} S_{ij} + \sum_{\nu \leq k} \sum_{\substack{\mu \leq k \\ \mu \neq \nu}} \sum_{(i,j) \in \mathcal{E}_{\nu\mu}} S_{ij} \\ &= -2 \sum_{\nu \leq k} \sum_{(i,j) \in \mathcal{E}_{\nu\nu}} S_{ij} + \sum_{(i,j)} S_{ij} \\ &\hookrightarrow \text{intra-cluster} \quad \hookrightarrow \text{const} \end{split}$$

up to thresh. 
$$u \stackrel{*}{=} -\frac{1}{2} \sum_{\nu \leq k} \sum_{\substack{(i,j) \in \mathcal{E}_{\nu\nu} \\ \nu \leq k}} (|S_{ij}-u| + S_{ij}-u) + \frac{1}{2} \sum_{\nu \leq k} \sum_{\substack{\mu \leq k \\ u \neq \nu}} (|S_{ij}+u| - S_{ij}-u)$$

\*: altern. def. where  $\frac{1}{2}(|X| \pm X) = \max\{0, \pm X\}$ 

**Graph partitioning:**  $D_{ij} \in \mathbb{R}$ 

$$\begin{split} R^{\mathrm{gp}}(c;\mathcal{D}) &= const - \sum_{\nu \leq k} \mathrm{cut}(\mathcal{G}_{\nu}(\mathcal{D}), \mathcal{V} \setminus \mathcal{G}_{\nu}(\mathcal{D})) \\ &= const + \sum_{\nu \leq k} \mathrm{cut}(\mathcal{G}_{\nu}(\mathcal{S}), \mathcal{V} \setminus \mathcal{G}_{\nu}(\mathcal{S})) \end{split}$$

**Bias in** R(c;D): Cost should scale prop. to #objects,

i.e. 
$$R(c;D) = \mathcal{O}(n)$$
. \*: use  $D_{ij} = D(1 - \delta_{ij})$ 

**Tipp:**  $\frac{\operatorname{cut}(\mathcal{G}_{\alpha}, \mathcal{V} \setminus \mathcal{G}_{\alpha})}{\operatorname{assoc}(\mathcal{G}_{\alpha}, \mathcal{V})} \stackrel{*}{=} \frac{n \cdot p_{\alpha} \cdot n(1 - p_{\alpha}) \cdot D}{n \cdot p_{\alpha} \cdot n \cdot D} = 1 - p_{\alpha}$ 

## **6.1 Pairwise Clustering**

Cost: 
$$R^{\text{pc}}(c; \mathcal{D}) = \sum_{\alpha} \sum_{(i,j) \in \mathcal{E}_{\alpha\alpha}} \frac{D_{ij}}{|\mathcal{G}_{\alpha}|} = \sum_{\alpha} \sum_{(i,j) \in \mathcal{E}_{\alpha\alpha}} |\mathcal{G}_{\alpha}| \frac{D_{ij}}{|\mathcal{E}_{\alpha\alpha}|}$$

**Equivariance to** *k*-means:  $(if D_{ij} = ||x_i - x_j||^2)$ 

$$\sum_{i \le n} ||\boldsymbol{x}_i - \boldsymbol{y}_{c(i)}||^2 = \sum_{i \le n} \sum_{j \le n} \sum_{\alpha \le k} \frac{\mathbb{I}_{\{c(i) = \alpha\}} \mathbb{I}_{\{c(j) = \alpha\}}}{|\mathcal{G}_{\alpha}|} D_{ij}$$

## **Invariance properties:**

- Symmetrisation:  $R^{pc}(c; \mathcal{D}^s) \equiv R^{pc}(c; \mathcal{D})$
- Off-diagonal shift:  $R^{\text{pc}}(c; \tilde{\mathcal{D}}) = R^{\text{pc}}(c; \mathcal{D}) \lambda_{\min} \cdot n$

**Theorem:** If  $S^c$  is p.s.d., then D derives from squared Eucl. space.  $\Longrightarrow$  Make S p.s.d.:  $\tilde{S} := S - \lambda_{\min} \mathbb{I}$ 

#### **Constant Shift Embedding:**

- 1. Symmetrise  $D \to D^s$ :  $D_{ij}^s := \frac{1}{2}(D_{ij} + D_{ji})$
- 2. Centralise *D*, then *S*:  $X^c := QX^sQ^\top$  $Q = \mathbb{I} - \frac{1}{n}e_ne_n^\top$   $S^c = -\frac{1}{2}D^c$

$$X_{ij}^{c} = X_{ij} - \frac{1}{n} \sum_{k} X_{ik} - \frac{1}{n} \sum_{k} X_{kj} + \frac{1}{n^2} \sum_{k,\ell} X_{k\ell}$$

$$\implies \text{sum over column/rows} = 0$$

3. **(Off-)Diagonal shift:** Find  $\lambda_{\min}$  of  $S^c$   $\tilde{S} := S^c - \lambda_{\min} \mathbb{I} \qquad \tilde{D} := D - \lambda_{\min} (\mathbf{1} - \mathbb{I})$   $\tilde{D}_{ii} = \tilde{S}_{ii} + \tilde{S}_{ij} - 2\tilde{S}_{ij} = ||x_i - x_i||^2$ 

#### **Reconstruction:**

- 1. EVD:  $\tilde{S} = V \Lambda V^{\top}$  via  $(\tilde{S} \lambda \mathbb{I}) v \stackrel{!}{=} 0$  (|v| = 1) where  $\Lambda = \operatorname{diag}(\lambda_1 \dots \lambda_n)$  and  $V = [v_1 \dots v_n]$
- 2. Find *p* s.t.  $\lambda_1 \ge \dots \lambda_p > \lambda_{p+1} = \dots = \lambda_n = 0$
- 3.  $\Longrightarrow X_p = V_p(\Lambda_p)^{1/2}$  (each row is a vector)
- 4.  $\Longrightarrow X_t = V_t(\Lambda_t)^{1/2}$  (approx. & denoising)

## Cluster membership of new data:

*Note:*  $S^{\text{new}}$  is def. by  $D_{ij}^{\text{new}} = S_{ii}^{\text{new}} + \tilde{S}_{jj} - 2S_{ij}^{\text{new}}$ 

1. 
$$(S^{\text{new}})^{\text{c}} = -\frac{1}{2} \left[ D^{\text{new}} (\mathbb{I}_n - \frac{1}{n} \boldsymbol{e}_n \boldsymbol{e}_n^{\top}) - \frac{1}{n} \boldsymbol{e}_n \boldsymbol{e}_n^{\top} + \tilde{D} (\mathbb{I}_n - \frac{1}{n} \boldsymbol{e}_n \boldsymbol{e}_n^{\top}) \right]$$

- 2. Project:  $X_p^{\text{new}} = (S^{\text{new}})^c V_p (\Lambda_p)^{-1/2}$
- 3. Assign:  $\hat{c}_i = \arg\min_c ||(x_p^{\text{new}})_i y_{c(i)}||$

## 7 Model Selection for Clustering

What is the appropriate #clusters k for my data? **General approach:** Measure quality (neg. log-likelihood) for different  $k \rightarrow elbow$ .

## 7.1 Complexity-based Model Selection

**Strategy:** add a complexity term to neg. log-likelihood **Attention:** MDL/BIC rely on likelihood optimisation → not generally applicable

**Ocam's razor:** Choose the model that provides the shortest description of the data.

## 7.1.1 Min. Description Length (MDL)

Minimise **descr. length**:  $-\log p(X \mid \theta) - \log p(\theta)$ 

Approx.:  $\hat{k} \in \arg\min_{k} \frac{-\log p(X \mid \hat{\theta}) + \frac{k'}{2} \log n}{n}$ 

## 7.1.2 Bayesian Information Crit. (BIC)

Parametrise likelihood  $p(X \mid M)$  by  $\theta$ :

 $p(X \mid M) = \int_{\Theta_M} \exp(\log p(X \mid M, \theta)) \cdot p(\theta \mid M) d\theta$ 

Assume flat prior  $p(\theta|M) \approx const$  and expand log-likelihood by ML estimator  $\hat{\theta}$ :

 $\overline{\ell}(\theta) = \frac{\ell(\theta)}{n} = \frac{1}{n} \log p(X|M,\theta) \stackrel{\text{i.i.d.}}{=} \frac{1}{n} \sum_{i} \ell(\theta, X_i) \stackrel{\text{Taylor}}{\approx} \dots$   $\implies p(X \mid M) = const_2 \cdot \exp(\frac{\ell(\hat{\theta}) - \frac{k'}{2} \log n}{\log n})$ where k': dimension of (trainable) parameters

#### 8 Model Validation

#### 8.1 Stability-based Validation

**Stability:** Solutions on two data sets drawn from the same source should be similar.

#### 8.2 Information-theoretic Validation

# 8.2.1 Shannon's Channel Coding Thm.

- **Channel:**  $(S, \{p(\cdot \mid s)\}_{s \in S})$ , S: alphabet  $\circ \epsilon$ -noisy binary channel:  $p(\hat{s} \mid s) = \begin{cases} 1-\epsilon & \text{if } \hat{s}=s \\ \epsilon & \text{if } \hat{s}\neq s \end{cases}$
- Capacity:  $cap = max_p I(S; \hat{S}) \rightsquigarrow p_S(s)$
- (M, n)-code: is a pair (Enc, Dec)  $\leftarrow$  scr. p.87 where M: #messages, n: code-length
  - Rate:  $r = \frac{\log_2 M}{n} \Leftrightarrow M = \lfloor 2^{nr} \rfloor$
  - ∘ **Commu. err.:**  $p_{\text{err}} := \max_{i \le M} \mathbb{P}(Dec(\widehat{Enc(i)}) \ne i)$

Goal / Best code:  $\lim_{n\to\infty} \frac{\log M}{n}$  s.t.  $\lim_{n\to\infty} p_{\text{err}} \to 0$ 

# **Asymptotic equiparition property (AEP):**

- $A_{\epsilon}^{(n)}$ : Typical set of sequences  $(s_1, ..., s_n) \in \mathcal{S}^n$  $\left| -\frac{1}{n} \log p_{S^n}(s^n) - H[S] \right| < \epsilon \qquad \leftarrow \text{scr. p.8}$
- $\mathbb{P}\left((S^n, \hat{S}^n) \in A_{\epsilon}^{(n)}\right) \stackrel{n \to \infty}{\to} 1$   $\leftarrow$  scr. p.90
- $p_{\text{err}} \le 2^{-n(\text{cap}-3\epsilon-r)} \stackrel{n\to\infty}{\to} 0 \text{ if } r < \text{cap}$

#### 8.2.2 Algorithm Validation

#### **Assumptions:**

- Exponential solution space, i.e.  $\log |\mathcal{C}| = \mathcal{O}(n)$
- A's output is probabilistic, i.e.  $p(\cdot | X')$

#### **Ideal variant:**

**Messages:**  $\mathcal{M} = \{X'_1, \dots, X'_m\}$ 

Code: 
$$X_i' \xrightarrow{Enc_A} p(\cdot \mid X_i') \xrightarrow{\mathcal{C}_A} p(\cdot \mid X_i'') \xrightarrow{Dec_A} \hat{X}$$
 Empirical variant:

**Messages:**  $\mathcal{M} = \{\tau_1, \dots, \tau_m\}$  drawn u.a.r. from  $\mathbb{T}$ 

• Require 
$$\sum_{\tau} p(c \mid \tau \circ X') \approx \frac{|\mathbb{T}|}{|c|} \pm \rho$$
  $\leftarrow$  scr. p.95

**Code:** 
$$\tau_i \xrightarrow{Enc} p(\cdot \mid \tau_i \circ X') \xrightarrow{\mathcal{C}_A^{\prime}} p(\cdot \mid \tau_i \circ X'') \xrightarrow{Dec} \hat{\tau}$$

• 
$$Enc_{\mathcal{A}}$$
: encodes  $\tau_i \in \mathcal{M}$  as  $p(\cdot \mid \tau_i \circ X')$ 

• 
$$Dec_{\mathcal{A}}$$
: selects  $\hat{\tau} = \arg \max_{\tau} \kappa(\tau_i \circ X'', \tau \circ X')$ 

whereby 
$$\kappa(X'', X') := \sum_{c} p(c \mid X'') p(c \mid X')$$

## **Asymptotic Equipartition Property (AEP):**

AEP fulfilled if 
$$\log \kappa(X', X'') \stackrel{n \to \infty}{\to} \mathcal{E}$$
 whereby  $\mathcal{E} := \mathbb{E}_{X', X''}[\log \kappa(X', X'')]$ 

• 
$$A_{\epsilon}^{(n)}$$
: set of  $(\epsilon, n)$ -typical pairs  $X', X''$   
 $|\log \kappa(X', X'') - \mathcal{E}| < \epsilon$ 

• 
$$p_{\text{err}} \leq P_{(n)} \text{ c.f. scr. } (6.19) \stackrel{n \to \infty}{\to} 0 \text{ if } \frac{\log m}{\log |\mathcal{C}|} < I$$
  
where  $I := \frac{1}{\log |\mathcal{C}|} \mathbb{E}_{X',X''}[\log(|\mathcal{C}|\kappa(X',X''))]$ 

## 8.3 Applications of PA

**PA**: quantifies the amount of information that algorithms extract from phenomena.  $\rightarrow$  quantified by **capacity** (max. # distinguishable messages that can be communicated)

**Temperature:**  $T^* = \arg\max_{T} \kappa(X', X'')$ 

**Cost functions:** Given  $R_1(\cdot, \cdot), \dots, R_s(\cdot, \cdot)$ 

$$\max_{\ell \le s} \kappa_{\ell}(X', X'') = \max_{\ell \le s} \frac{1}{Z_{X'}Z_{X''}} \sum_{c} e^{-\frac{1}{T}R_{\ell}(c, X')} e^{-\frac{1}{T}R_{\ell}(c, X'')}$$

**Algorithms:** Many MST (min. spanning tree) algo's are **contractive** ( $\rightarrow$  sequence of candidate sol's).

#### **Approximation Set Coding (ASC):**

Algorithms: Many MST (min. spanning tree) algo's are **contractive** (
$$\rightarrow$$
 sequence of candidate sol's).   
Approximation Set Coding (ASC): 
$$p^{\text{ASC}}(c \mid X') = \begin{cases} 1/|G_{\gamma}(X')| & \text{if } c \in G_{\gamma}(X') \\ 0 & \text{otw.} \end{cases}$$
•  $\sinh(x) = \frac{e^x - e^{-x}}{2}$ ,  $\frac{d}{dx} \sinh(x) = \cosh(x)$ 
•  $\cosh(x) = \frac{e^x + e^{-x}}{2}$ ,  $\frac{d}{dx} \cosh(x) = \sinh(x)$ 
•  $\tanh(x) = \frac{\sinh(x)}{\cosh(x)} = \frac{e^x - e^{-x}}{e^x + e^{-x}}$ ,  $\cosh^2(x) + \sinh^2(x) = 1$ 

1. Run  $A$  to compute  $G^A(X')$  and  $G^A(X'')$  for all  $t$  •  $\frac{d}{dx} \tanh(x) = 1 - \tanh^2(x) = \frac{1}{\cosh^2(x)} = \operatorname{sech}^2(x)$ 

1. Run  $\mathcal{A}$  to compute  $G_t^{\mathcal{A}}(X')$  and  $G_t^{\mathcal{A}}(X'')$ , for all t

2. 
$$t^* = \arg\max_{t} \kappa(X', X'') = \arg\max_{t} \frac{|G_t^A(X') \cap G_t^A(X'')|}{|G_t^A(X')| \cdot |G_t^A(X'')|}$$

3. 
$$c^* \stackrel{\$ \text{ sample}}{\longleftarrow} \text{Unif}(G_{t^*}^{\mathcal{A}}(X') \cap G_{t^*}^{\mathcal{A}}(X''))$$

# 9 Appendix

#### 9.1 Tips and Tricks

## Complete the square:

If 
$$p(x) \propto \exp(-\frac{1}{2}x^{\mathsf{T}}Ax + x^{\mathsf{T}}b)$$
,

then 
$$p(x) = \mathcal{N}(x \mid A^{-1}b, A^{-1})$$

# **Constrained optimisation:**

primal: 
$$\min_{\mathbf{x}} f(\mathbf{x})$$
 s.t.  $g_i(\mathbf{x}) = 0$ ;  $h_i(\mathbf{x}) \le 0$ 

**Lagrangian:** with each  $\alpha_i \geq 0$ 

$$\mathcal{L}(\mathbf{x}, \lambda, \alpha) = f(\mathbf{x}) + \sum_{i} \lambda_{i} g_{i}(\mathbf{x}) + \sum_{j} \alpha_{j} h_{j}(\mathbf{x})$$

Solve: 
$$\frac{\partial \mathcal{L}}{\partial x} = 0$$
;  $g_i(x) = 0$ ;  $\alpha_i \ge 0$ ;  $h_i(x) \le 0$ 

If **Slater's cond.** holds,  $\exists x : g_i(x) = 0, h_i(x) < 0$ , then we can solve the *dual* instead:

$$\max_{\lambda,\alpha} \{ \min_{x} \mathcal{L}(x,\lambda,\alpha) \}$$
 s.t.  $\alpha_j \ge 0$ 

Solve: 
$$\frac{\partial \mathcal{L}}{\partial x} = 0$$
;  $\frac{\partial \mathcal{L}}{\partial \lambda} = 0$ ;  $\alpha_j h_j(x) = 0$ ;  $\alpha_j \ge 0$ 

**Euler-Lagrange:** Find extrema of functional  $\mathcal{F}[f] =$ 

$$\int G(x, f(x), f(x)) dx, \text{ thus } \frac{\partial \mathcal{F}}{\partial f} \stackrel{!}{=} 0.$$

If *G* is twice diff'able, then

$$\frac{\partial \mathcal{F}}{\partial f} = \frac{\partial G}{\partial f(x)} - \frac{\mathrm{d}}{\mathrm{d}x} \left( \frac{\partial G}{\partial f'(x)} \right) \stackrel{(*)}{=} \frac{\partial G}{\partial f(x)}.$$

(\*): when G does not depend on f'.

## 9.2 Approximations

**Laplace Approximation:**  $\frac{df}{dx}\Big|_{x_0} = 0$ 

$$\implies \int_{\mathbb{R}} e^{Cf(x)} dx \approx \sqrt{2\pi} C \cdot |f''(x_0)| \cdot e^{Cf(x_0)}$$

# **Hyperbolic Functions:**

• 
$$\sinh(x) = \frac{e^x - e^{-x}}{2}$$
,  $\frac{d}{dx} \sinh(x) = \cosh(x)$ 

• 
$$\cosh(x) = \frac{e^x + e^{-x}}{2}$$
,  $\frac{d}{dx} \cosh(x) = \sinh(x)$ 

• 
$$\tanh(x) = \frac{\sinh(x)}{\cosh(x)} = \frac{e^x - e^{-x}}{e^x + e^{-x}}, \cosh^2(x) + \sinh^2(x) = 1$$

• 
$$\frac{d}{dx}\tanh(x) = 1 - \tanh^2(x) = \frac{1}{\cosh^2(x)} = \operatorname{sech}^2(x)$$