

## 1 Basics

- General p-norm:  $\|x\|_p = (\sum_{i=1}^n |x_i|^p)^{1/p}$
- Hoelder:  $\|uv\|_1 \leq \|u\|_p \|v\|_q$ ,  $\|u+v\|_p \leq \|u\|_p + \|v\|_p$
- Triangle:  $\|u+v\|_p \leq \|u\|_p + \|v\|_p$
- Cauchy-Schwarz:  $|\langle u, v \rangle|^2 \leq \|u\|^2 \|v\|^2$
- Cauchy-Schwarz:  $|\mathbb{E}[X, Y]|^2 \leq \mathbb{E}[X^2] \mathbb{E}[Y^2]$
- Taylor:  $f(x) \approx f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots$ 
  - $f(x) \approx f(a) + \frac{\partial f(x)}{\partial x} \Big|_a - \frac{1}{2}(x-a)^\top \left( \frac{\partial^2 f(x)}{\partial x \partial x^\top} \Big|_a \right) (x-a)$
  - Power series of exp.:  $\exp(x) := \sum_{k=0}^{\infty} \frac{x^k}{k!}$
- Entropy:  $H(X) \equiv H(p_X) = \mathbb{E}_X[-\log \mathbb{P}(X=x)]$ 
  - $H(X|Y) = \sum_y \mathbb{P}(Y=y) H(X|Y=y) \leq H(X)$
  - $H(X, Y) = H(X) + H(Y|X)$
  - $H(X|g(X)) \geq 0$     $H(g(X)|X) = 0$
  - $H(cX) \begin{cases} = H(X) & \text{discrete} \\ = H(X) + \log|c| > H(X) & \text{continuous} \end{cases}$
- MI:  $I(X; Y|Z) = H(X|Z) - H(X|Y, Z)$  (symmetric)
  - $I(X; Y) = D_{\text{KL}}(p(x, y) \| p(x)p(y)) \geq 0$
  - $I(X_1, \dots, X_n; Z) = \sum_{i=1}^n I(X_i; Z | X_1, \dots, X_{i-1})$
  - Markov chain:  $I(X_1; X_2, X_3, \dots) = I(X_1; X_2)$
  - $I(X, Y; Z) = I(X; Z) + I(Y; Z | X)$
- KL-divergence:  $D_{\text{KL}}(p \| q) = \sum_x p(x) \log \left( \frac{p(x)}{q(x)} \right) \geq 0$
- $1 - z \leq \exp(-z)$
- Jensen,  $f(X)$  convex:  $f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)]$

### 1.1 Calculus

- Partial:  $\int uv' dx = uv - \int u'v dx$     $\frac{\partial}{\partial x} \frac{g}{h} = \frac{g'h - gh'}{h^2}$
- $\frac{\partial}{\partial x} (\|x-b\|_2) = \frac{x-b}{\|x-b\|_2}$     $\frac{d}{dx} |x| = \frac{x}{|x|}$
- $\frac{\partial}{\partial X} \log|X| = X^{-\top}$     $|X^{-1}| = |X|^{-1}$
- $\frac{\partial}{\partial x} (b^\top x) = \frac{\partial}{\partial x} (x^\top b) = b$
- $\frac{\partial}{\partial x} (b^\top Ax) = A^\top b$     $\frac{\partial}{\partial X} (c^\top Xb) = cb^\top$
- $\frac{\partial}{\partial X} (c^\top X^\top b) = bc^\top$     $\frac{\partial}{\partial x} (x^\top x) = 2x$
- $\frac{\partial}{\partial x} (x^\top Ax) = (A^\top + A)x \stackrel{\text{A sym.}}{=} 2Ax$
- $\frac{\partial}{\partial X} \text{Tr}(X^\top A) = A$    Trace trick:  $x^\top Ax = \dots$ 
  - $\dots \stackrel{\text{inn. prod.}}{=} \text{Tr}(x^\top Ax) \stackrel{\text{cycl. perm.}}{=} \text{Tr}(xx^\top A) = \text{Tr}(Axx^\top)$

## 2 Maximum Entropy Inference

Sample  $c \sim p(\cdot | X)$  s.t.  $H[p(\cdot | x)]$  is maximal,  
 $\mathbb{E}_{C|X}[R(C, X)] = \mu$  and  $\sum_c p(c | X) = 1$ .

$$\Rightarrow \text{Gibbs dist.: } p(c | X) = \frac{1}{Z(X)} \exp(-\beta R(c, X))$$

**Free energy:**  $F(X) := -\frac{1}{\beta} \log Z(X)$

$$\Leftrightarrow p(c | X) = \exp(-\beta[R(c, X) - F(X)])$$

$$\Rightarrow \text{entropy: } H[c | X] = \beta \underbrace{\mathbb{E}_{C|X}[R(C, X)]}_{=\mu} - \beta F(X)$$

$$\text{ME: } \max H[c | X] \Leftrightarrow \max Z(X) \Leftrightarrow \min F(X)$$

- Exp. generalisation costs:  $\mathbb{E}_{X''} \mathbb{E}_{C|X'} [R(c, X'')]$
- Min. out-of-sample descr. length per deg. of freedom  

$$\min_{p(\cdot)} \mathbb{E}_{X', X''} \mathbb{E}_{C|X'} \left[ -\log \frac{p(c|X'')}{p(c)} \right] \quad p(c) = \mathbb{E}_X[p(c | X)]$$

$$\stackrel{\text{Jensen}}{\geq} \min_{p(\cdot)} \mathbb{E}_{X', X''} \left[ -\log \mathbb{E}_{C|X'} [p(c | X'')] \right] - H[c]$$

$$= \max_{p(\cdot)} \mathbb{E}_{X', X''} [e^{H[c]} \cdot \kappa(X', X'')]$$

$$\text{PA: } T^* = \arg \max_T \kappa(X', X'')$$

- PA-kernel:  $\kappa(X', X'') := \sum_c p(c | X') p(c | X'')$
- combined:  $p(c | X', X'') \propto p(c | X') p(c | X'')$

## 3 Methods for intractable Gibbs distr.

### 3.1 Markov Chains

**Mixing time of MC:**  $\|P^t(c, \cdot) - \pi(\cdot)\|_{TV} \leq \epsilon$

$t_{\text{mix}} \propto \frac{1}{\lambda_1 - \lambda_2}$  where  $1 = \lambda_1 > \lambda_2 \geq \dots$

Well behaving **Markov Chains** are

- irreducible:** can go from/to any state (n steps)
- aperiodic:** chain doesn't go back & forth forever  
 $(\forall n > n(c, c'))$  (no) path length n w/ non-zero prob.)

$$1. \wedge 2. \Rightarrow \text{unique stat. dist. } p(c') = \sum_c \pi(c | c') p(c)$$

$$1. \wedge 2. \wedge \text{stat.} \Rightarrow \lim_{t \rightarrow \infty} \mathbb{P}[X_t = c] = p(c) \wedge$$

$$\lim_{t \rightarrow \infty} \frac{1}{t} \sum_{s=1}^t f(X_s) = \sum_c p(c) f(c)$$

$$\text{DBE } \pi(c' | c) p(c) = \pi(c | c') p(c') \Rightarrow \text{p stat.}$$

$$\text{MH: } \lambda_2 = \max \left\{ 1 - \frac{q(y, x)}{p_x}, 1 - \frac{q(x, y)}{p_y} \right\} = 1 - \alpha - \beta$$

## 3.2 Sampling and SA

**Metropolis-Hastings:** Assume  $p(c) \propto f(c)$ .

$$\pi(c' | c) := \begin{cases} q(c' | c) A(c, c') & c \neq c' \\ 1 - \sum_{c' \neq c} q(c' | c) A(c, c') & \text{otw.} \end{cases}$$

where  $q(c' | c)$ : prob. to propose the move  $c \rightarrow c'$ ,  
 and  $A(c, c') := \min \left\{ 1, \frac{q(c|c') f(c') / Z}{q(c'|c) f(c) / Z} \right\}$  prob. accept move

**Metropolis Algorithm:** Assume  $p(c) \propto f(c)$  and  
 $q(c' | c) = q(c | c')$ , i.e. symmetric.

- Define symmetric  $\{q(\cdot | c)\}_{c \in \mathcal{C}}$  s.t. graph  $G_q$  is connected and every vertex in  $G_q$  has edge to itself.
- $c_0^T \leftarrow \$$  while  $T > \epsilon$  do:
  - for  $t = 1, 2, \dots, N$ , do:
    - $\tilde{c} \leftarrow q(\cdot | c_{t-1}^T)$  // sample
    - $b \leftarrow \text{Bern} \left( \min \left\{ 1, e^{-\frac{1}{T} [R(\tilde{c}, X) - R(c_{t-1}, X)]} \right\} \right)$
    - If  $b = 1$  then  $c_t^T \leftarrow \tilde{c}$  else  $c_t^T \leftarrow c_{t-1}^T$ .
  - $c_0 \leftarrow c_N^T$
  - $T \leftarrow \text{reduce}(T)$
  - $c_0^T \leftarrow c_0$

**Temperature:** high temperature  $T \rightarrow$  closer to uniform i.e. worse ability to discriminate between good and bad models  $\rightarrow$  more likely to accept moves i.e. exploration, not stuck in bad local minima  
 reduce temperature to find better local minima and get stuck there

### 3.3 Laplace's Method (Least angle clust.)

- Square the cost:  $e^{-\frac{1}{T} R(c, X)} = \text{const} \cdot e^{g(c)^\top g(c)}$
- Complete the square:  $\int e^{-\frac{1}{T} (y - g(c))^2} dy = (\pi T)^{d/2}$   
 $\Rightarrow e^{g(c)^\top g(c)} = (\pi T)^{-d/2} \int \exp^{-y^\top y + 2y^\top g(c)} dy$
- Rewrite normalisation constant:  
 $Z = \sum_c e^{-\frac{1}{T} R(c, X)} = \dots = \text{const} \int e^{-\frac{1}{T} f(y)} dy$
- Apply Laplace's method:  
 If  $f$  has unique min.  $y_0$  and Hessian  $H := \frac{\partial^2 f}{\partial y^2} \Big|_{y_0}$   

$$\int e^{-\frac{1}{T} f(y)} dy \stackrel{(T \rightarrow 0)}{\approx} e^{-\frac{1}{T} f(y_0)} \left| \frac{H}{2\pi T} \right|^{-1/2}$$

### 3.4 Mean-field Approximation

**Idea:** Approximate  $p_\beta$  (Gibbs) with a “simple”, factorisable distribution  $p = p_1 \cdots p_N$ .

**Approach:** Minimise  $D_{\text{KL}}(p \parallel p_\beta)$

$\iff$  Minimise **Gibbs free energy**:

$$G(p) = \frac{1}{\beta} D_{\text{KL}}(p \parallel p_\beta) + F(\beta) = \mathbb{E}_{c \sim p}[R(c)] - \frac{1}{\beta} H[p]$$

Note:  $H[p] = \sum_{i=1}^N H[p_i]$  and  $F(\beta) \leq G(p)$

**Ising model:**  $R(c | J) = -\frac{1}{2} \sum_{i,j} J_{ij} c_i c_j - \sum_i h_i c_i$   
where  $J_{ij}$ : interaction between particles,

$h_i$ : noisy image,  $\sigma_i$ : denoised image

**Problem:**  $\frac{\partial G(p)}{\partial p_{i\ell}} = 0$  s.t.  $\sum_{\ell'} p_{i\ell'} = 1 \forall i$

**Solution:** with the *mean field*  $h_i = [\cdots h_{i\ell} \cdots]^\top$

$$h_{i\ell} := \frac{\partial \mathbb{E}[R(c)]}{\partial p_{i\ell}} = \mathbb{E}_{c \sim p_{i \rightarrow \ell}}[R(c)] \leftarrow \text{object } i \text{ chooses class } \ell$$

$$p_{i\ell} = e^{-\beta h_{i\ell}} / Z_i$$

**EM-like Algo:** Iteratively 1. Pick random  $i$   
2.  $h_i^{\text{new}} \leftarrow p_j^{\text{old}}$  3.  $p_i^{\text{new}} \leftarrow h_i^{\text{new}}$  until converged.

#### 3.4.1 Smooth k-means scr.20 (p. 39)

$R(c | X) = \sum_i \|x_i - y_{c_i}\|^2 + \frac{\lambda}{2} \sum_i \sum_{j \in N(i)} \mathbb{I}_{\{c_i \neq c_j\}}$   
where the second term measures **#violations** of these neighbourhood constraints.

$$\implies h_{i\ell} = \|x_i - y_\ell\|^2 + \lambda \sum_{j \in N(i)} p_{j\ell} + \text{const}_i$$

### 4 Deterministic Annealing (Z is tractable)

**Lemma:** func's  $\times$  domain  $\rightarrow$  domain  $\times$  co-dom.

$$\mathcal{O}(K^N) \rightarrow \sum_c \prod_i \epsilon_{i,c(i)} = \prod_i \sum_k \epsilon_{ik} \leftarrow \mathcal{O}(NK)$$

$$p(c | \theta, X) = \prod_{i \leq N} p_i(c(i) | \theta, X)$$

where  $p_i(k | \theta, X) \propto \exp(-\frac{1}{T} \|x_i - \theta_k\|^2)$

$$\text{Max. entr.} \implies \frac{\partial \log Z}{\partial \theta_k} = \frac{\partial \sum_{i \leq n} \log \sum_{v \leq K} \exp(-\|x_i - \theta_v\|^2)}{\partial \theta_k} \triangleq$$

$$0 \implies \theta_k^* = \frac{\sum_i p_i(k | \theta^*, X) \cdot x_i}{\sum_i p_i(k | \theta^*, X)}$$

do  
**E-step:**  $p_i(k | \theta^{\text{old}}, X) = \frac{\exp(-\frac{1}{T} \|x_i - \theta_k\|^2)}{\sum_{j \leq K} \exp(-\frac{1}{T} \|x_i - \theta_j\|^2)}$   
**M-step:**  $\theta_k \leftarrow \frac{\sum_{i \leq n} p_{ik} x_i}{\sum_{i \leq n} p_{ik}}$   
 $\theta^{\text{old}} \leftarrow \theta$   
until convergence of  $\theta$   
 $\theta_k \leftarrow \theta_k + \epsilon$  (noise s.t. centroids can separate)

**Phase transitions:** For  $T \rightarrow \infty$ :  $\theta_k^* = \bar{X} \forall k \leq K$

Once  $T = 2\lambda_{\text{max}}$ , more centroids appear, where  $\lambda_{\text{max}} = \text{max. eigenvalue of } \frac{1}{N} X^\top X$ . ( $x_i$ 's row-wise)

**DA vs MAP:**

1. MAP can get stuck in local maximum
2. MAP not robust against noisy data
3. DA guaranteed to obtain global optimum if annealing is slow enough and ergodicity is given
4. In DA  $T > 0$  gives entropic regularisation

### 5 Histogram Clustering

**Least Angle Clust. (LAC):** [Idea]

Similarity  $S(x_i, x_j) = w_{ij} \cos(\phi_{ij}) = w_{ij} e_i \cdot e_j$  with unit vectors  $e_i := x_i / \|x_i\|$ , e.g. choice  $w_{ij} = \|x_i\| \cdot \|x_j\|$ .

**Dyadic data:**  $\mathcal{Z} = \{(x_{i(r)}, y_{j(r)}); 1 \leq r \leq \ell\}$

- prototype / “centroid”:  $q(y_j | \alpha)$
  - empirical dist.:  $\hat{p}(y_j | x_i) = \frac{\hat{p}(x_i, y_j)}{\hat{p}(x_i)} \leftarrow \text{scr. (5.10)}$   
 $\hat{p}(x_i) \leftarrow \text{scr. (5.11)}$
- Likelihood:  $P(\mathcal{Z} | c, q) = \prod_{r \leq \ell} p(x_{i(r)}, y_{j(r)} | c, q)$   
 $\stackrel{\text{scr. (5.12)}}{=} \prod_i \prod_j [q(y_j | c(i)) \cdot p(c(i)) \cdot p(x_i)]^{\ell \hat{p}(x_i, y_i)}$

Assume  $p(\alpha) = 1/k$  and  $\hat{p}(x_i) = 1/n$

$\implies$  **Cost:**  $R^{\text{hc}}(c, q, \mathcal{Z}) = \frac{\ell}{n} \sum_{i \leq n} D_{\text{KL}}[\hat{p}(\cdot | x_i) \parallel q(\cdot | c(i))]$

Solving the **Gibbs dist.**  $p(c | q, \hat{p}) = \prod_{i \leq n} P_{i,c(i)}$

via Lagrange yields  $q^*(y_j | \alpha) = \frac{\sum_{i \leq n} P_{i\alpha} \cdot \hat{p}(y_j | x_i)}{\sum_{i \leq n} P_{i\alpha}}$  Lemma 2 ch.3 p.36

#### 5.1 Information Bottleneck Method

Find efficient code  $X \mapsto \hat{X}$  (codebook vector) and preserve relevant info. about context  $Y$ .

**Criterion:**  $R^{\text{IB}}(q(\hat{x} | x)) = I(X; \hat{X}) - \beta I(\hat{X}; Y)$

**Markov chain:**  $\hat{X} \xrightarrow{q(\hat{x}|x)} X \xrightarrow{p(y|x)} Y$

**Generation process:** w/ *distortion*  $d(x, \hat{x}) = D_{\text{KL}}[\cdot]$

$$\begin{cases} q_t(\hat{x}|x) \propto q_t(\hat{x}) \cdot \exp(-\beta D_{\text{KL}}[p(y|x) \parallel p_t(y|\hat{x})]) \\ q_{t+1}(\hat{x}) = \sum_x p(x) \cdot q_t(\hat{x} | x) \\ p_{t+1}(y|\hat{x}) = \sum_x p(y | x) \cdot p(x) \cdot q_t(\hat{x} | x) / q_t(\hat{x}) \end{cases}$$

### 5.2 Parametric Distributional Clustering

**Idea:** Use a mixture of Gaussian prototypes, i.e.

$$p(y_j | v) \equiv p(b | v) = \sum_{\alpha \leq s} p(\alpha | v) G_\alpha(b).$$

$$x_i \xrightarrow{c(i)=v} v \xrightarrow{p(b|v)} \hat{p}(b | i)$$

Note: Feature values  $y_j$  (“bins”  $b$ ) only depend on cluster index  $v$  and not explicitly on the site  $x_i$ !

**Notation:**  $x_i \leftarrow i$ ,  $y_j \leftarrow b$  (bins),  $v \leftarrow$  clusters

**Likelihood:** (both equivalent if  $p(i) = \frac{1}{n}$ )

$$P(X | c, \theta) = \prod_{i \leq n} p(c(i)) \prod_{b \leq m} [p(b | c(i))]^{\ell \hat{p}(i,b)},$$

$$P(X, M | \theta) = \prod_{i \leq n} \prod_{v \leq k} [p(v) \cdot \prod_{b \leq m} p(b | v)^{n_{ib}}]^{M_{iv}}$$

where  $n_{ib}$ : #occur. an observ. at site  $i$  is inside  $I_b$

$$M_{iv} = p(v | i) \in \{0, 1\} \text{ clust. membersh. assign.}$$

**Cost (IB):**  $R^{\text{PDC}}(c, p_{\cdot|c}) = -\log P(X, M | \theta) = \dots$

$$\dots = -\sum_{i \leq n} \left[ \log p_{c(i)} + \frac{\ell}{n} \sum_{b \leq m} \hat{p}(b | i) \log p(b | c(i)) \right]$$

**E-step:**  $h_{iv} = -\log p_v - \sum_b \frac{\ell}{n} \hat{p}(b | i) \log p(b | v)$

$$q_{iv} = \mathbb{E}[\mathbb{I}_{\{c(i)=v\}}] \propto \exp(-h_{iv}/T)$$

**M-step:**  $p_v = \frac{1}{n} \sum_{i \leq n} q_{iv}$

No closed form sol. for  $p(\alpha | v)$ . Thus, iteratively optimize pairs s.t.  $\sum_\alpha p(\alpha | v) = 1$ .

### 6 Graph-based Clustering

**Non-metric relations:** might assume negative values or violate the triangular inequality.

**Setting:** objects  $\mathbf{o}_i, \mathbf{o}_j \in \mathcal{O}$ ; relations with weights  $\mathcal{D} := \{D_{ij}\}$  on the edges  $(i, j)$ .

- Cluster  $\alpha$ :  $\mathcal{G}_\alpha \equiv \{\mathbf{o} \in \mathcal{O} : c(\mathbf{o}) = \alpha\}$
- Inter-cluster edges:  $\mathcal{E}_{\alpha\beta} = \{(i, j) \in \mathcal{E} : \mathbf{o}_i \in \mathcal{G}_\alpha \wedge \mathbf{o}_j \in \mathcal{G}_\beta\}$
- $\text{cut}(A, B) = \sum_{i \in A, j \in B} W_{ij} \rightarrow$  weight matrix  $W$

**Messages:**  $\mathcal{M} = \{X'_1, \dots, X'_m\}$

**Code:**  $X'_i \xrightarrow{Enc_A} p(\cdot | X'_i) \xrightarrow{C_A} p(\cdot | X''_i) \xrightarrow{Dec_A} \hat{X}$

**Empirical variant:**

**Messages:**  $\mathcal{M} = \{\tau_1, \dots, \tau_m\}$  drawn u.a.r. from  $\mathbb{T}$

• Require  $\sum_{\tau} p(c | \tau \circ X') \approx \frac{|\mathbb{T}|}{|\mathcal{C}|} \pm \rho \leftarrow \text{scr. p.95}$

**Code:**  $\tau_i \xrightarrow{Enc} p(\cdot | \tau_i \circ X') \xrightarrow{C_A} p(\cdot | \tau_i \circ X'') \xrightarrow{Dec} \hat{\tau}$

•  $Enc_A$ : encodes  $\tau_i \in \mathcal{M}$  as  $p(\cdot | \tau_i \circ X')$

•  $Dec_A$ : selects  $\hat{\tau} = \arg \max_{\tau} \kappa(\tau_i \circ X'', \tau \circ X')$

whereby  $\kappa(X'', X') := \sum_c p(c | X'') p(c | X')$

**Asymptotic Equipartition Property (AEP):**

AEP fulfilled if  $\log \kappa(X', X'') \xrightarrow{n \rightarrow \infty} \mathcal{E}$

whereby  $\mathcal{E} := \mathbb{E}_{X', X''}[\log \kappa(X', X'')]$

•  $A_{\epsilon}^{(n)}$ : set of  $(\epsilon, n)$ -typical pairs  $X', X''$

$|\log \kappa(X', X'') - \mathcal{E}| < \epsilon$

•  $p_{\text{err}} \leq P_{(n)}$  c.f. scr. (6.19)  $\xrightarrow{n \rightarrow \infty} 0$  if  $\frac{\log m}{\log |\mathcal{C}|} < I$

where  $I := \frac{1}{\log |\mathcal{C}|} \mathbb{E}_{X', X''}[\log(|\mathcal{C}| \kappa(X', X''))]$

### 8.3 Applications of PA

**PA:** quantifies the amount of information that algorithms extract from phenomena.  $\rightarrow$  quantified by **capacity** (max. # distinguishable messages that can be communicated)

**Temperature:**  $T^* = \arg \max_T \kappa(X', X'')$

**Cost functions:** Given  $R_1(\cdot, \cdot), \dots, R_s(\cdot, \cdot)$

$\max_{\ell \leq s} \kappa_{\ell}(X', X'') = \max_{\ell \leq s} \frac{1}{Z_{X', X''}} \sum_c e^{-\frac{1}{T} R_{\ell}(c, X')} e^{-\frac{1}{T} R_{\ell}(c, X'')}$

**Algorithms:** Many MST (min. spanning tree) algo's are **contractive** ( $\rightarrow$  sequence of candidate sol's).

**Approximation Set Coding (ASC):**

$p^{\text{ASC}}(c | X') = \begin{cases} 1/|G_{\gamma}(X')| & \text{if } c \in G_{\gamma}(X') \\ 0 & \text{otw.} \end{cases}$

$G_{\gamma}(X') := \left\{ c \in \mathcal{C} : R(c, X') - \min_{c \in \mathcal{C}} R(c, X') \leq \gamma \right\}$

1. Run  $\mathcal{A}$  to compute  $G_t^A(X')$  and  $G_t^A(X'')$ , for all  $t$

2.  $t^* = \arg \max_t \kappa(X', X'') = \arg \max_t \frac{|G_t^A(X') \cap G_t^A(X'')|}{|G_t^A(X')| \cdot |G_t^A(X'')|}$

3.  $c^* \xleftarrow{\$ \text{ sample}} \text{Unif}(G_{t^*}^A(X') \cap G_{t^*}^A(X''))$

## 9 Appendix

### 9.1 Tips and Tricks

**Complete the square:**

If  $p(\mathbf{x}) \propto \exp(-\frac{1}{2} \mathbf{x}^T \mathbf{A} \mathbf{x} + \mathbf{x}^T \mathbf{b})$ ,

then  $p(\mathbf{x}) = \mathcal{N}(\mathbf{x} | \mathbf{A}^{-1} \mathbf{b}, \mathbf{A}^{-1})$

**Constrained optimisation:**

*primal:*  $\min_{\mathbf{x}} f(\mathbf{x})$  s.t.  $g_i(\mathbf{x}) = 0; h_j(\mathbf{x}) \leq 0$

**Lagrangian:** with each  $\alpha_j \geq 0$

$\mathcal{L}(\mathbf{x}, \lambda, \alpha) = f(\mathbf{x}) + \sum_i \lambda_i g_i(\mathbf{x}) + \sum_j \alpha_j h_j(\mathbf{x})$

Solve:  $\frac{\partial \mathcal{L}}{\partial \mathbf{x}} = 0; g_i(\mathbf{x}) = 0; \alpha_j \geq 0; h_j(\mathbf{x}) \leq 0$

If **Slater's cond.** holds,  $\exists \mathbf{x} : g_i(\mathbf{x}) = 0, h_j(\mathbf{x}) < 0$ , then we

can solve the *dual* instead:

$\max_{\lambda, \alpha} \{ \min_{\mathbf{x}} \mathcal{L}(\mathbf{x}, \lambda, \alpha) \}$  s.t.  $\alpha_j \geq 0$

Solve:  $\frac{\partial \mathcal{L}}{\partial \mathbf{x}} = 0; \frac{\partial \mathcal{L}}{\partial \lambda} = 0; \alpha_j h_j(\mathbf{x}) = 0; \alpha_j \geq 0$

**Euler-Lagrange:** Find extrema of functional  $\mathcal{F}[f] =$

$\int G(x, f(x), f'(x)) dx$ , thus  $\frac{\partial \mathcal{F}}{\partial f} \stackrel{!}{=} 0$ .

If  $G$  is twice diff'able, then

$\frac{\partial \mathcal{F}}{\partial f} = \frac{\partial G}{\partial f(x)} - \frac{d}{dx} \left( \frac{\partial G}{\partial f'(x)} \right) \stackrel{(*)}{=} \frac{\partial G}{\partial f(x)}$ .

(\*) : when  $G$  does not depend on  $f'$ .

### 9.2 Approximations

**Laplace Approximation:**  $\frac{df}{dx} \Big|_{x_0} = 0$

$\Rightarrow \int_{\mathbb{R}} e^{Cf(x)} dx \approx \sqrt{2\pi} C \cdot |f''(x_0)| \cdot e^{Cf(x_0)}$

**Hyperbolic Functions:**

•  $\sinh(x) = \frac{e^x - e^{-x}}{2}, \quad \frac{d}{dx} \sinh(x) = \cosh(x)$

•  $\cosh(x) = \frac{e^x + e^{-x}}{2}, \quad \frac{d}{dx} \cosh(x) = \sinh(x)$

•  $\tanh(x) = \frac{\sinh(x)}{\cosh(x)} = \frac{e^x - e^{-x}}{e^x + e^{-x}}, \quad \cosh^2(x) + \sinh^2(x) = 1$

•  $\frac{d}{dx} \tanh(x) = 1 - \tanh^2(x) = \frac{1}{\cosh^2(x)} = \text{sech}^2(x)$