#### 1 Basics

• General p-norm:  $||x||_p = (\sum_{i=1}^n |x_i|^p)^{1/p}$ 

• Hoelder:  $||uv||_1 \le ||u||_p ||v||_q$ ,  $||u+v||_p \le ||u||_p + ||v||_p$ 

• Triangle:  $||u + v||_p \le ||u||_p + ||v||_p$ 

• Cauchy-Schwarz:  $|\langle u, v \rangle|^2 \le ||u||^2 ||v||^2$ 

• Cauchy-Schwarz:  $|\mathbb{E}[X,Y]|^2 \le \mathbb{E}[X^2]\mathbb{E}[Y^2]$ 

• Taylor:  $f(x) \approx f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots$ 

 $\circ f(\mathbf{x}) \approx f(\mathbf{a}) + \frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} \Big|_{\mathbf{a}} - \frac{1}{2} (\mathbf{x} - \mathbf{a})^{\top} \left( \frac{\partial^2 f(\mathbf{x})}{\partial \mathbf{x} \partial \mathbf{x}^{\top}} \right) \Big|_{\mathbf{a}} (\mathbf{x} - \mathbf{a})$ 

• Power series of exp.:  $\exp(x) := \sum_{k=0}^{\infty} \frac{x^k}{k!}$ 

• Entropy:  $H(X) \equiv H(p_X) = \mathbb{E}_X[-\log \mathbb{P}(X = x)]$ 

 $\circ H(X \mid Y) = \sum_{y} \mathbb{P}(Y = y) H(X \mid Y = y) \le H(X)$ 

 $\circ H(X,Y) = H(X) + H(Y \mid X)$ 

 $\circ\ H(X\mid g(X))\geq 0 \quad \circ H(g(X)\mid X)=0$ 

 $\circ H(cX) \begin{cases} = H(X) & \text{discrete} \\ = H(X) + \log|c| > H(X) & \text{continuou} \end{cases}$ 

• MI: I(X;Y|Z) = H(X|Z) - H(X|Y,Z) (symmetric)

 $\circ \ I(X;Y) = D_{\mathrm{KL}}(p(x,y) \parallel p(x)p(y)) \geq 0$ 

 $I(X_1,...,X_n;Z) = \sum_{i=1}^n I(X_i;Z \mid X_1,...,X_{i-1})$  Markov chain:  $I(X_1;X_2,X_3,...) = I(X_1;X_2)$ 

 $\circ I(X,Y;Z) = I(X;Z) + I(Y;Z \mid X)$ 

• KL-divergence:  $D_{KL}(p \parallel q) = \sum_{x} p(x) \log \left( \frac{p(x)}{q(x)} \right) \ge 0$ 

•  $1-z \le \exp(-z)$ 

• Jensen, f(X) convex:  $f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)]$ 

#### 1.1 Calculus

• Partial:  $\int uv' dx = uv - \int u'v dx$  •  $\frac{\partial}{\partial x} \frac{g}{h} = \frac{g'h}{h^2} - \frac{gh'}{h^2}$ 

•  $\frac{\partial}{\partial x}(\|\mathbf{x} - \mathbf{b}\|_2) = \frac{x - \mathbf{b}}{\|\mathbf{x} - \mathbf{b}\|_2}$  •  $\frac{\mathrm{d}}{\mathrm{d}x}|x| = \frac{x}{|x|}$ 

•  $\frac{\partial}{\partial X} \log |X| = X^{-\top}$  •  $|X^{-1}| = |X|^{-1}$ 

•  $\frac{\partial}{\partial x}(b^{\top}x) = \frac{\partial}{\partial x}(x^{\top}b) = b$ 

•  $\frac{\partial}{\partial x}(b^{\top}Ax) = A^{\top}b$  •  $\frac{\partial}{\partial X}(c^{\top}Xb) = cb^{\top}$ 

•  $\frac{\partial}{\partial X}(c^{\top}X^{\top}b) = bc^{\top}$  •  $\frac{\partial}{\partial x}(x^{\top}x) = 2x$ 

•  $\frac{\partial}{\partial x}(x^{\top}Ax) = (A^{\top} + A)x \stackrel{A \text{ sym.}}{=} 2Ax$ 

•  $\frac{\partial}{\partial \mathbf{X}} Tr(\mathbf{X}^{\top} \mathbf{A}) = \mathbf{A}$  • Trace trick:  $\mathbf{x}^{\top} \mathbf{A} \mathbf{x} = \dots$ 

 $\dots \stackrel{\text{inn. prod.}}{=} Tr(\mathbf{x}^{\top} A \mathbf{x}) \stackrel{\text{cycl. permut.}}{=} Tr(\mathbf{x} \mathbf{x}^{\top} A) = Tr(A \mathbf{x} \mathbf{x}^{\top})$ 

## **2 Maximum Entropy Inference**

Sample  $c \sim p(\cdot \mid X)$  s.t.  $H[p(\cdot \mid x)]$  is maximal,

 $\mathbb{E}_{C|X}[R(C,X)] = \mu \text{ and } \sum_{c} p(c \mid X) = 1.$ 

 $\implies$  Gibbs dist.:  $p(c \mid X) = \frac{1}{Z(X)} \exp(-\beta R(c, X))$ 

Free energy:  $F(X) := -\frac{1}{\beta} \log Z(X)$ 

 $\iff p(c \mid X) = \exp(-\beta [R(c, X) - F(X)])$ 

 $\implies$  entropy:  $H[c \mid X] = \beta \underbrace{\mathbb{E}_{C \mid X}[R(C, X)]}_{=\mu} - \beta F(X)$ 

**ME:**  $\max H[c \mid X] \iff \max Z(X) \iff \min F(X)$ 

• Exp. generalisation costs:  $\mathbb{E}_{X''}\mathbb{E}_{X''}\mathbb{E}_{C|X'}[R(c,X'')]$ 

• Min. out-of-sample descr. length per deg. of freedom  $\min_{\substack{p(\cdot|\cdot)\\p(c)}} \mathbb{E}_{X',X''} \mathbb{E}_{C\mid X'} \Big[ -\log \frac{p(c\mid X'')}{p(c)} \Big] \quad p(c) = \mathbb{E}_X \big[ p(c\mid X) \big]$   $\stackrel{\text{Jensen}}{\geq} \min_{p(\cdot|\cdot)} \mathbb{E}_{X',X''} \Big[ -\log \mathbb{E}_{C\mid X'} \big[ p(c\mid X'') \big] \Big] - H[c]$ 

**PA:**  $T^* = \operatorname{arg\,max}_T \kappa(X', X'')$ 

• PA-kernel:  $\kappa(X', X'') := \sum_{c} p(c \mid X') p(c \mid X'')$ 

 $= \max_{n(\cdot,\cdot)} \mathbb{E}_{X',X''}[e^{H[c]} \cdot \kappa(X',X'')]$ 

• combined:  $p(c \mid X', X'') \propto p(c \mid X')p(c \mid X'')$ 

#### 3 Methods for intractable Gibbs distr.

## 3.1 Markov Chains

Mixing time of MC:  $||P^t(c,\cdot) - \pi(\cdot)||_{TV} \le \epsilon$ 

 $t_{mix} \propto \frac{1}{\lambda_1 - \lambda_2}$  where  $1 = \lambda_1 > \lambda_2 \ge \dots$ 

Well behaving Markov Chains are

1. **irreducible:** can go from/to any state (n steps)

2. **aperiodic:** chain doesn't go back & forth forever  $(\forall n > n(c, c')$  (no) path length n w/ non-zero prob.)

 $1. \land 2. \implies$  unique stat. dist.  $p(c') = \sum_{c} \pi(c \mid c') p(c)$ 

 $1. \land 2. \land \text{stat.} \implies \lim_{t \to \infty} \mathbb{P}[X_t = c] = p(c) \land$ 

 $\lim_{t\to\infty} \frac{1}{4} \sum_{s=1}^t f(X_s) = \sum_c p(c) f(c)$ 

DBE  $\pi(c' \mid c)p(c) = \pi(c \mid c')p(c') \implies p \text{ stat.}$ 

**MH:**  $\lambda_2 = \max\left\{1 - \frac{q(y,x)}{p_x}, 1 - \frac{q(x,y)}{p_y}\right\} = 1 - \alpha - \beta$ 

#### 3.2 Sampling and SA

**Metropolis-Hastings:** Assume  $p(c) \propto f(c)$ .

$$\pi(c' \mid c) := \begin{cases} q(c' \mid c) A(c, c') & c \neq c \\ 1 - \sum_{c' \neq c} q(c' \mid c) A(c, c') & \text{otw.} \end{cases}$$

where  $q(c' \mid c)$ : prob. to propose the move  $c \to c'$ , and  $A(c,c') := \min\{1, \frac{q(c \mid c') f(c') / Z}{q(c' \mid c) f(c) / Z}\}$  prob. accept move **Metropolis Algorithm:** Assume  $p(c) \propto f(c)$  and  $q(c' \mid c) = q(c \mid c')$ , i.e. symmetric.

1. Define symmetric  $\{q(\cdot \mid c)\}_{c \in C}$  s.t. graph  $G_q$  is connected and every vertex in  $G_q$  has edge to itself.

2.  $c_0^T \leftarrow \$$  while  $T > \epsilon$  do:

• for t = 1, 2, ..., N, do:

 $\circ \ \tilde{c} \leftarrow q(\cdot \mid c_{t-1}^T)$  // sample

 $\circ b \leftarrow \operatorname{Bern}\left(\min\left\{1, e^{-\frac{1}{T}[R(\tilde{c}, X) - R(c_{t-1}, X)]}\right\}\right)$ 

 $\circ \text{ If } b = 1 \text{ then } c_t^T \leftarrow \tilde{c} \text{ else } c_t^T \leftarrow c_{t-1}.$ 

•  $c_0 \leftarrow c_N^T$ 

•  $T \leftarrow \text{reduce}(T)$ 

•  $c_0^T \leftarrow c_0$ 

**Temperature:** high temperature  $T \to \text{closer}$  to uniform i.e. worse ability to discriminate between good and bad models  $\to$  more likely to accept moves i.e. exploration, not stuck in bad local minima reduce temperature to find better local minima and get stuck there

## **3.3 Laplace's Method** (Least angle clust.)

1. Square the cost:  $e^{-\frac{1}{T}R(c,X)} = const \cdot e^{g(c)^{\top}g(c)}$ 

2. Complete the square:  $\int e^{-\frac{1}{T}(y-g(c))^2} dy = (\pi T)^{d/2}$  $\Rightarrow e^{g(c)^{\top}g(c)} = (\pi T)^{-d/2} \int \exp^{-y^{\top}y+2y^{\top}g(c)} dy$ 

3. Rewrite normalisation constant:

 $Z = \sum_{c} e^{-\frac{1}{T}R(c,X)} = \dots = const \int e^{-\frac{1}{T}f(y)} dy$ 

4. Apply Laplace's method:
If f has unique min.  $y_0$  and Hessian  $H := \frac{\partial^2 f}{\partial y^2}\Big|_{y_0}$   $\left[ e^{-\frac{1}{T}f(y)} dy \stackrel{(T \to 0)}{\approx} e^{-\frac{1}{T}f(y_0)} \Big|_{\frac{2\pi}{T}} \right]^{-1/2}$ 

# 3.4 Mean-field Approximation

**Approach:** Minimise  $D_{KL}(p \parallel p_{\beta})$ 

← Minimise Gibbs free energy:

$$G(p) = \frac{1}{\beta} D_{\mathrm{KL}}(p \parallel p_{\beta}) + F(\beta) = \mathbb{E}_{c \sim p}[R(c)] - \frac{1}{\beta} H[p]$$

Note: 
$$H[p] = \sum_{i=1}^{N} H[p_i]$$
 and  $F(\beta) \leq G(p)$ 

**Ising model:** 
$$E(\sigma|h) = -\frac{\beta}{2} \sum_{i} \frac{h_i}{|N_i|} \sum_{j \in N_i} h_j - \lambda \sum_{i} h_i \sigma_i$$

$$E(\sigma \mid h) = -\sum_{i}^{p} h_{i} \sigma_{i} - \lambda \sum_{i}^{p-r} \sigma_{i} \sigma_{i+r}$$
  

$$E(\sigma \mid h) = -\sum_{i} h_{i} \sigma_{i} - \lambda \sum_{i,j} J_{ij} \sigma_{i} \sigma_{j}$$

where  $J_{ij}$ : interaction between particles,

 $h_i$ : noisy image,  $\sigma_i$ : denoised image

**Problem:** 
$$\frac{\partial G(p)}{\partial p_u \alpha} = 0$$
 s.t.  $\sum_{v \le K} p_{iv} = 1 \ \forall i$ 

**Solution:** with the mean field  $h_u = [\cdots h_{u\alpha} \cdots]^{\top}$ 

$$h_{u\alpha} := \frac{\partial \mathbb{E}[R(c)]}{\partial p_{u\alpha}} = \mathbb{E}_{c \sim p_{|u \to \ell}}[R(c)] \leftarrow \text{object } u \text{ chooses } class \, \alpha$$

E: 
$$p_{u\alpha} = \frac{e^{-\beta h_{u\alpha}}}{\sum_{v \le K} e^{-\beta h_{uv}}}$$
 1. Pick random

$$i \ 2. \ h_i^{\text{new}} \leftarrow p_j^{\text{old}} \ 3. \ p_i^{\text{new}} \leftarrow h_i^{\text{new}}$$

**M:** 
$$h_{u\alpha} = \sum_{c} \prod_{i=1, i\neq u}^{N} p_i(c(i)) \mathbb{I}_{\{c(u)=\alpha\}} R(c, x)$$
,

$$-H[P] = \sum_{i \le N} \sum_{c \in \{i\}} \prod_{j \le N} p_j(c(j)) \sum_{c(i) \in \{1,...,K\}} p_i(c(i)) \log p_i(c(i)) \lambda_{\max} = \max. \text{ eigenvalue of } \frac{1}{N} X^\top X. \quad (\mathbf{x}_i\text{'s row-wise})$$
**DA vs MAP:**

$$= \sum_{i=1}^N \sum_{\nu=1}^K p_i(\nu) \log p_i(\nu)$$

$$\begin{aligned} & \mathbf{Minimum \, cond.:} \, \frac{\partial^2}{\partial p_u^2(\alpha)} \mathcal{B} = \frac{1}{\beta p_u(\alpha)} > 0 \\ & \frac{\partial^2 \mathcal{B}}{\partial p_u(\alpha) \partial p_v(\gamma)} = \frac{\partial h_u(\alpha)}{\partial p_v(\gamma)} = \\ & \sum_{c} \prod_{\substack{i=1 \\ i \neq u, v}} p_i(c(i)) \mathbb{I}_{\substack{\{c(u) = \alpha \\ c(v) = \gamma\}}} R(c, X) > 0 \text{ for } R(c, X) \geq 0 \end{aligned}$$

#### **3.4.1** Smooth *k*-means scr.20 (p. 39)

 $R(c \mid X) = \sum_{i} ||x_{i} - y_{c_{i}}||^{2} + \frac{\lambda}{2} \sum_{i} \sum_{j \in N(i)} \mathbb{I}_{\{c_{i} \neq c_{j}\}}$ where the second term measures #violations of these neighbourhood constraints.

$$\implies h_{i\ell} = ||x_i - y_\ell||^2 + \lambda \sum_{j \in N(i)} p_{j\ell} + const_i$$

## **4 Deterministic Annealing**

**Lemma:** func's  $\times$  domain  $\rightarrow$  domain  $\times$  co-dom.

(Z is tractable)

$$\mathcal{O}(K^N) \to \frac{\sum_{c} \prod_{i} \epsilon_{i,c(i)} = \prod_{i} \sum_{k} \epsilon_{ik}}{\leftarrow} \mathcal{O}(NK)$$

$$p(c \mid \theta, X) = \prod_{i \le N} p_i(c(i) \mid \theta, X)$$

where 
$$p_i(k \mid \theta, X) \propto \exp(-\frac{1}{T}||x_i - \theta_k||^2)$$

$$\theta_k^* = \arg\max_{\theta_k} \left\{ \frac{\mathbb{E}[R]}{T} + \sum_{i \le n} \log \sum_{\nu \le K} \exp(-\frac{1}{T} ||x_i - \theta_{\nu}||^2) \right\} \exp(-\frac{1}{T} ||x_i - \theta_{\nu}||^2)$$

$$\exp(-\frac{1}{T} ||x_i - \theta_{\nu}||^2) \exp(-\frac{1}{T} ||x_i - \theta_{\nu}||^2)$$

**⇒** Maximize Entropy

$$\implies \frac{\partial \log Z}{\partial \theta_k} = \frac{\partial \sum_{i \le n} \log \sum_{\nu \le K} \exp(-\|x_i - \theta_{\nu}\|^2)}{\partial \theta_k} \stackrel{\triangle}{=} 0 \implies$$

$$\theta_k^* = \frac{\sum_i p_i(k|\theta^*, X) \cdot x_i}{\sum_i p_i(k|\theta^*, X)}$$

do  
**E-step:** 
$$p_i(k|\theta^{\text{old}}, X) = \frac{\exp(-\frac{1}{T}||x_i - \theta_k||^2)}{\sum_{j \le K} \exp(-\frac{1}{T}||x_i - \theta_j||^2)}$$
  
**M-step:**  $\theta_k \leftarrow \frac{\sum_{i \le n} p_{ik} x_i}{\sum_{i \le n} p_{ik}}$ 

until convergence of  $\theta$ 

$$\theta_k \leftarrow \theta_k + \epsilon$$
 (noise s.t. centroids can separate)

**Phase transitions:** For  $T \rightarrow \infty$ :  $\theta_k^* = \overline{X} \ \forall k \leq K$ 

Once  $T = 2\lambda_{\text{max}}$ , more centroids appear, where

#### DA vs MAP:

- 1. MAP can get stuck in local maximum
- 2. MAP not robust against noisy data
- 3. DA guaranteed to obtain global optimum if annealing is slow enough and ergodicity is given
- 4. In DA T>0 gives entropic regularisation

## **Limiting Behaviour:**

- $\lim_{T\to\infty}$ :  $P(c(i)=k)\to \frac{1}{K}; \theta_k^*\to \frac{1}{N}\sum_i x_i$
- $\lim_{T\to 0}$ :  $P(c(i) = k) \to$  $\begin{cases} 1 & \text{if } k = \arg\min_{j} ||x_i - \theta_j|| \\ 0 & \text{otw.} \end{cases}; \theta_k^* \to \frac{\sum_{i \in X_k} x_i}{|X_k|}$

## 5 Histogram Clustering

Least Angle Clust. (LAC): [Idea]

Similarity  $S(\mathbf{x}_i, \mathbf{x}_i) = w_{ij} \cos(\phi_{ij}) = w_{ij} \mathbf{e}_i \cdot \mathbf{e}_j$  with unit vectors  $e_i := x_i/||x_i||$ , e.g. choice  $w_{ij} = ||x_i|| \cdot ||x_j||$ . **Dyadic data:**  $\mathcal{Z} = \{(x_{i(r)}, y_{i(r)}); 1 \leq r \leq \ell\}$ 

- prototype / "centroid":  $q(y_i \mid \alpha)$
- joint dist.:  $\hat{p}(x_i, y_j) = \frac{1}{\ell} \sum_{r \le \ell} \Delta_{x_i, x_{i(r)}} \Delta_{y_i, y_{j(r)}}$

Likelihood:  $P(\mathcal{Z} \mid c, q) = \prod_{r \leq \ell} p(x_{i(r)}, y_{i(r)} \mid c, q)$ 

$$= \overset{\text{scr.}}{\dots} \overset{(5.12)}{\dots} = \prod_i \prod_i [q(y_i|c(i)) \cdot p(c(i)) \cdot p(x_i)]^{\ell \hat{p}(x_i, y_i)}$$

Assume  $p(\alpha) = 1/k$  and  $\hat{p}(x_i) = 1/n$ 

 $\mathbf{Cost:} R^{\mathrm{hc}}(c, q, \mathcal{Z}) = \frac{\ell}{n} \sum_{i \le n} D_{\mathrm{KL}} [\hat{p}(\cdot \mid x_i) \parallel q(\cdot \mid c(i))]$  $nll = -\sum_{i \le n} \sum_{j \le m} \ell \hat{p}(x_i, y_j) \log(q(y_j | c(i)) p(c(i)) p(x_i)) +$ 

$$\sum_{i \le n} \sum_{j \le m} \ell \hat{p}(x_i, y_j) \log \hat{p}(y_j | x_i) = \hat{p}(y_i | x_i)$$

 $\ell \sum_{i \le n} \sum_{j \le m} \hat{p}(x_i, y_j) \log \frac{\hat{p}(y_j | x_i)}{a(v_i | c(i))} + K$ Solving the **Gibbs dist.**  $p(c \mid q, \hat{p}) = \prod_{i \le n} P_{i,c(i)}$ 

via Lagrange yields 
$$q^*(y_j \mid \alpha) = \frac{\sum_{i \le n} P_{i\alpha} \cdot \hat{p}(y_j \mid x_i)}{\sum_{i \le n} P_{i\alpha}}$$
 Lemma 2 ch.3 p.36

where  $\frac{\partial H}{\partial \theta} = -\frac{1}{T} \mathbb{E}_{C(\cdot|\theta,X)} \left[ \frac{\partial R(C,\theta,X)}{\partial \theta} \right]$ **Generative Model:** 

- 1. pick random object  $x_i \in \mathcal{X}$  according to  $p(x_i)$
- 2. select its cluster membership c(i) of  $x_i$
- 3. select a feature value  $y_i$  according to  $q(y_i \mid c(i))$

#### 5.1 Information Bottleneck Method

 $I(X,\widehat{X})$ Rate dist. theory: R(D) = $p(\widehat{X}|X):\mathbb{E}_{\widehat{Y}}[d(X,\widehat{X})]< D$ 

$$\frac{\partial}{\partial p(\widehat{x}|x')} (I(x,\hat{x}) + \beta \sum_{x} \sum_{\hat{x}} p(\hat{x} \mid x) p(x) d(x,\hat{x}) + \sum_{x} \lambda(x) (\sum_{\hat{x}} p(\hat{x} \mid x) - 1)$$

$$\implies p(\hat{x} \mid x) = \frac{p(\hat{x})}{Z(x,\beta)} exp(-\beta d(x,\hat{x}))$$

Find efficient code  $X \mapsto \hat{X}$  (codebook vector) and preserve relevant info. about context *Y* .

**Criterion:**  $R^{\mathrm{IB}}(q(\hat{x} \mid x)) = I(X; \hat{X}) - \beta I(\hat{X}; Y)$ 

**Markov chain:**  $\hat{X} \xrightarrow{q(\hat{x}|x)} X \xrightarrow{p(y|x)} Y$ 

Generation process: 
$$w/$$
 distortion  $d(x,\hat{x}) = D_{\text{KL}}[\cdot]$ 

$$\begin{cases} q_t(\hat{x}|x) &= \frac{q_t(\hat{x})}{Z_t(x,\beta)} \cdot \exp(-\beta D_{\text{KL}}[p(y|x) \parallel p_t(y|\hat{x})]) \\ q_{t+1}(\hat{x}) &= \sum_x p(x) \cdot q_t(\hat{x} \mid x) \\ p_{t+1}(y|\hat{x}) &= \sum_x p(y \mid x) \cdot p(x) \cdot q_t(\hat{x} \mid x) / q_t(\hat{x}) \\ p_{t+1}(y|\hat{x}) &= \sum_x p(y \mid x) \cdot p(x) \cdot q_t(\hat{x} \mid x) / q_t(\hat{x}) \\ \frac{\partial q(\hat{x})}{\partial q(\hat{x} \mid x)} &= p(x') \Delta_{\hat{x},\hat{x}}, \quad \frac{\partial p(\hat{x} \mid y)}{\partial q(\hat{x} \mid x)} = p(x' \mid y) \Delta_{\hat{x},\hat{x}}, \\ \mathcal{L}(q(\hat{x} \mid x)) &= \sum_x \sum_{\hat{x}} q(\hat{x} \mid x) p(x) \log \frac{q(\hat{x} \mid x)}{q(\hat{x})} + \\ \lambda \sum_{\hat{x},y} p(y) p(\hat{x} \mid y) \log \frac{p(\hat{x} \mid y)}{q(\hat{x})} - \sum_x \mu(x) \sum_{\hat{x}} (q(\hat{x} \mid x) - 1) \\ &= p(x') \left( \log \frac{q(\hat{x}' \mid x)}{q(\hat{x}')} + \lambda D^{KL}(p(y \mid x') || p(y \mid \hat{x}')) - \tilde{\mu}(x') \right) \end{cases}$$

Som-metric relations: might assume negative values or violate the triangular inequality. Setting: objects  $o_i, o_j \in \mathcal{O}$ ; relations with weights  $\mathcal{D} := \{D_{ij}\} \text{ on the edges } (i,j).$ 

• Cluster  $\alpha: \mathcal{G}_{\alpha} \equiv \{o \in \mathcal{O}: c(o) = \alpha\}$ 
• Inter-cluster edges:  $\mathcal{E}_{\alpha\beta} = \{(i,j) \in \mathcal{E}: o_i \in \mathcal{G}_{\alpha} \wedge o_j \in \mathcal{G}_{\alpha} \setminus o$ 

## **5.2 Parametric Distributional Clustering**

Idea: Use a mixture of Gaussian prototypes, i.e.

$$p(y_j \mid \nu) \equiv p(b \mid \nu) = \sum_{\alpha \le s} p(\alpha \mid \nu) G_{\alpha}(b).$$
$$x_i \xrightarrow{c(i) = \nu} \nu \xrightarrow{p(b \mid \nu)} \hat{p}(b \mid i)$$

*Note:* Feature values  $y_i$  ("bins" b) only depend on cluster index  $\nu$  and not explicitly on the site  $x_i$ !

**Notation:**  $x_i \leftarrow i$ ,  $y_i \leftarrow b$  (bins),  $v \leftarrow$  clusters

**Likelihood:** (both equivalent if 
$$p(i) = \frac{1}{n}$$
)
$$P(X \mid c, \theta) = \prod_{i \leq n} p(c(i)) \prod_{b \leq m} [p(b \mid c(i))]^{\ell \hat{p}(i,b)},$$

$$P(X, M \mid \theta) = \prod_{i \leq n} \prod_{v \leq k} [p(v) \cdot \prod_{b \leq m} p(b \mid v)^{n_{ib}}]^{M_{iv}}$$
where  $n_{ib}$ : #occur. an observ. at site  $i$  is inside  $I_b$ 

$$M_{iv} = p(v \mid i) \in \{0,1\} \quad \text{clust. membersh. assign.}$$

$$\text{Cost (IB): } R^{\text{PDC}}(c, p_{\cdot \mid c}) = -\log P(X, M\theta) = \dots$$

$$\dots = -\sum_{i \leq n} \left[\log p_{c(i)} + \frac{\ell}{n} \sum_{b \leq m} \hat{p}(b \mid i) \log p(b \mid c(i))\right]$$

**E-step:** 
$$h_{i\nu} = -\log p_{\nu} - \sum_{b} \frac{\ell}{n} \hat{p}(b \mid i) \log p(b \mid \nu)$$
  
 $q_{i\nu} = \mathbb{E}[\mathbb{I}_{\{c(i)=\nu\}}] \propto \exp(-h_{i\nu}/T)$ 

**M-step:** 
$$p_{\nu} = \frac{1}{n} \sum_{i \leq n} q_{i\nu}$$
  
No closed form sol. for  $p(\alpha \mid \nu)$ . Thus, iteratively optimize pairs s.t.  $\sum_{\alpha} p(\alpha \mid \nu) = 1$ .

#### 6 Graph-based Clustering

Non-metric relations: might assume negative values or violate the triangular inequality.

**Setting:** objects  $o_i, o_i \in \mathcal{O}$ ; relations with weights  $\mathcal{D} := \{D_{ij}\}$  on the edges (i, j).

- Cluster  $\alpha$ :  $\mathcal{G}_{\alpha} \equiv \{ o \in \mathcal{O} : c(o) = \alpha \}$
- Inter-cluster edges:  $\mathcal{E}_{\alpha\beta} = \{(i,j) \in \mathcal{E} : o_i \in \mathcal{G}_\alpha \land o_j \in \mathcal{G}_\beta\}$
- $\operatorname{cut}(A, B) = \sum_{i \in A, i \in B} W_{ij} \to \operatorname{weight} \operatorname{matrix} W$
- assoc $(A, V) = \sum_{i \in A, i \in V} W_{ij} \rightarrow \text{total connection}$ strength from nodes in A to all nodes in the graph

## **Correlation clustering:**

$$R^{cc}(c;\mathcal{D}) = -\sum_{\nu \leq k} \sum_{(i,j) \in \mathcal{E}_{\nu\nu}} S_{ij} + \sum_{\nu \leq k} \sum_{\substack{\mu \leq k \\ \mu \neq \nu}} \sum_{(i,j) \in \mathcal{E}_{\nu\mu}} S_{ij}$$

$$= -2\sum_{\nu \leq k} \sum_{(i,j) \in \mathcal{E}_{\nu\nu}} S_{ij} + \sum_{(i,j)} S_{ij}$$

$$\hookrightarrow \text{intra-cluster} \hookrightarrow \text{const}$$

$$\text{up to} \quad \stackrel{*}{=} -\frac{1}{2} \sum_{\nu \leq k} \sum_{(i,j) \in \mathcal{E}_{\nu\nu}} (|S_{ij} - u| + S_{ij} - u)$$

$$+ \frac{1}{2} \sum_{\nu \leq k} \sum_{\mu \leq k} \sum_{(i,j) \in \mathcal{E}_{\nu\mu}} (|S_{ij} + u| - S_{ij} - u)$$

\*: altern. def. where  $\frac{1}{2}(|X| \pm X) = \max\{0, \pm X\}$ 

**Graph partitioning:**  $D_{ii} \in \mathbb{R}$ 

$$\begin{split} R^{\mathrm{gp}}(c;\mathcal{D}) &= const - \sum_{\nu \leq k} \mathrm{cut}(\mathcal{G}_{\nu}(\mathcal{D}), \mathcal{V} \setminus \mathcal{G}_{\nu}(\mathcal{D})) \\ &= const + \sum_{\nu \leq k} \mathrm{cut}(\mathcal{G}_{\nu}(\mathcal{S}), \mathcal{V} \setminus \mathcal{G}_{\nu}(\mathcal{S})) \end{split}$$

**Bias in** R(c;D): Cost should scale prop. to #objects,

i.e. 
$$R(c;D) = \mathcal{O}(n)$$
. \*: use  $D_{ij} = D(1 - \delta_{ij})$   
**Tipp:**  $\frac{\text{cut}(\mathcal{G}_{\alpha}, \mathcal{V} \setminus \mathcal{G}_{\alpha})}{\text{assoc}(\mathcal{G}_{\alpha}, \mathcal{V})} \stackrel{*}{=} \frac{n \cdot p_{\alpha} \cdot n(1 - p_{\alpha}) \cdot D}{n \cdot p_{\alpha} \cdot n \cdot D} = 1 - p_{\alpha}$ 

## **6.1 Pairwise Clustering**

**Invariance properties:** 

Cost: 
$$R^{\text{pc}}(c; \mathcal{D}) = \sum_{\alpha} \sum_{(i,j) \in \mathcal{E}_{\alpha\alpha}} \frac{D_{ij}}{|\mathcal{G}_{\alpha}|} = \sum_{\alpha} \sum_{(i,j) \in \mathcal{E}_{\alpha\alpha}} |\mathcal{G}_{\alpha}| \frac{D_{ij}}{|\mathcal{E}_{\alpha\alpha}|}$$
Equivariance to  $k$ -means:  $(\text{if } D_{ij} = ||x_i - x_j||^2)$ 

$$\sum_{i \leq n} ||x_i - y_{c(i)}||^2 = \sum_{i \leq n} \sum_{j \leq n} \sum_{\alpha \leq k} \frac{\mathbb{I}_{\{c(i) = \alpha\}} \mathbb{I}_{\{c(j) = \alpha\}}}{|\mathcal{G}_{\alpha}|} D_{ij}$$

- Symmetrisation:  $R^{pc}(c; \mathcal{D}^s) \equiv R^{pc}(c; \mathcal{D})$
- Off-diagonal shift:  $R^{\text{pc}}(c; \tilde{\mathcal{D}}) = R^{\text{pc}}(c; \mathcal{D}) \lambda_{\min} \cdot n$

**Theorem:** If  $S^c$  is p.s.d., then D derives from squared Eucl. space.  $\Longrightarrow$  Make S **p.s.d.**:  $\tilde{S} := S - \lambda_{\min} \mathbb{I}$ 

#### **Constant Shift Embedding:**

- 1. Symmetrise  $D \to D^s$ :  $D_{ij}^s := \frac{1}{2}(D_{ij} + D_{ji})$
- 2. Centralise D, then S:  $X^c := QX^sQ^T$  $Q = \mathbb{I} - \frac{1}{n} e_n e_n^{\mathsf{T}}$   $S^{\mathsf{c}} = -\frac{1}{2} D^{\mathsf{c}}$  $X_{ij}^{c} = X_{ij} - \frac{1}{n} \sum_{k} X_{ik} - \frac{1}{n} \sum_{k} X_{kj} + \frac{1}{n^2} \sum_{k,\ell} X_{k\ell}$  $\implies$  sum over column/rows = 0
- 3. (Off-)Diagonal shift: Find  $\lambda_{\min}$  of  $S^c$  $\tilde{S} := S^{c} - \lambda_{\min} \mathbb{I}$   $\tilde{D} := D - \lambda_{\min} (1 - \mathbb{I})$  $\tilde{D}_{ij} = \tilde{S}_{ii} + \tilde{S}_{ij} - 2\tilde{S}_{ij} = ||x_i - x_i||^2$

#### **Reconstruction:**

- 1. EVD:  $\tilde{S} = V \Lambda V^{\top}$  via  $(\tilde{S} \lambda \mathbb{I})v \stackrel{!}{=} 0$  (|v| = 1)where  $\Lambda = \operatorname{diag}(\lambda_1 \dots \lambda_n)$  and  $V = [v_1 \dots v_n]$
- 2. Find *p* s.t.  $\lambda_1 \ge \dots \ge \lambda_p > \lambda_{p+1} = \dots = \lambda_n = 0$
- 3.  $\Longrightarrow X_p = V_p(\Lambda_p)^{1/2}$  (each row is a vector)
- 4.  $\Longrightarrow X_t = V_t(\Lambda_t)^{1/2}$  (approx. & denoising)

#### **Cluster membership of new data:**

*Note*:  $S^{\text{new}}$  is def. by  $D_{ij}^{\text{new}} = S_{ii}^{\text{new}} + \tilde{S}_{jj} - 2S_{ij}^{\text{new}}$ 

1. 
$$(S^{\text{new}})^{\text{c}} = -\frac{1}{2} \left[ D^{\text{new}} (\mathbb{I}_n - \frac{1}{n} \boldsymbol{e}_n \boldsymbol{e}_n^{\top}) - \frac{1}{n} \boldsymbol{e}_n \boldsymbol{e}_n^{\top} + \tilde{D} (\mathbb{I}_n - \frac{1}{n} \boldsymbol{e}_n \boldsymbol{e}_n^{\top}) \right]$$

- 2. Project:  $X_p^{\text{new}} = (S^{\text{new}})^c V_p (\Lambda_p)^{-1/2}$
- 3. Assign:  $\hat{c}_i = \arg\min_c \|(x_n^{\text{new}})_i y_{c(i)}\|$

#### 7 Model Selection for Clustering

What is the appropriate # clusters k for my data? General approach: Measure quality (neg. loglikelihood) for different  $k \rightarrow elbow$ .

## 7.1 Complexity-based Model Selection

Strategy: add a complexity term to neg. log-likelihood **Attention:** MDL/BIC rely on likelihood optimisation

## $\rightarrow$ not generally applicable

Ocam's razor: Choose the model that provides the shortest description of the data.

## 7.1.1 Min. Description Length (MDL)

Minimise **descr. length**:  $-\log p(X \mid \theta) - \log p(\theta)$ 

Approx.:  $\hat{k} \in \arg\min_{k} -\log p(X \mid \hat{\theta}) + \frac{k'}{2} \log n$ 

## 7.1.2 Bayesian Information Crit. (BIC)

Parametrise likelihood  $p(X \mid M)$  by  $\theta$ :

$$p(X \mid M) = \int_{\Theta_M} \exp(\log p(X \mid M, \theta)) \cdot p(\theta \mid M) d\theta$$

Assume flat prior  $p(\theta|M) \approx const$  and

expand log-likelihood by ML estimator  $\hat{\theta}$ :  $\overline{\ell}(\theta) = \frac{\ell(\theta)}{n} = \frac{1}{n} \log p(X|M,\theta) \stackrel{\text{i.i.d.}}{=} \frac{1}{n} \sum_{i} \ell(\theta, X_i) \stackrel{\text{Taylor}}{\approx} \dots$ 

 $\implies p(X \mid M) = const_2 \cdot \exp(\ell(\hat{\theta}) - \frac{k'}{2} \log n)$ 

where k': dimension of (trainable) parameters

#### 8 Model Validation

## 8.1 Stability-based Validation

Stability: Solutions on two data sets drawn from the same source should be similar.

#### 8.2 Information-theoretic Validation

## 8.2.1 Shannon's Channel Coding Thm.

- Channel:  $(S, \{p(\cdot \mid s)\}_{s \in S})$ , S: alphabet •  $\epsilon$ -noisy binary channel:  $p(\hat{s} \mid s) = \begin{cases} 1 - \epsilon & \text{if } \hat{s} = s \\ \epsilon & \text{if } \hat{s} \neq s \end{cases}$
- Capacity:  $cap = max_p I(S; \hat{S}) \rightsquigarrow p_S(s)$
- (M, n)-code: is a pair (Enc, Dec)← scr. p.87 where *M*: #messages, *n*: code-length
- Rate:  $r = \frac{\log_2 M}{n} \Leftrightarrow M = \lfloor 2^{nr} \rfloor$
- Commu. err.:  $p_{\text{err}} := \max_{i < M} \mathbb{P}(Dec(Enc(i)) \neq i)$

Goal / Best code:  $\lim_{n\to\infty} \frac{\log M}{n}$  s.t.  $\lim_{n\to\infty} p_{\text{err}} \to 0$ 

## 8.2.2 Algorithm Validation

**Assumptions:** 

- Exponential solution space, i.e.  $\log |\mathcal{C}| = \mathcal{O}(n)$
- A's output is probabilistic, i.e.  $p(\cdot \mid X')$

#### **Ideal variant:**

Messages:  $\mathcal{M} = \{X'_1, \dots, X'_m\}$ 

**Code:**  $X'_i \xrightarrow{Enc_A} p(\cdot \mid X'_i) \xrightarrow{\mathcal{C}_A} p(\cdot \mid X''_i) \xrightarrow{Dec_A} \hat{X}$ 

**Empirical variant:** 

**Messages:**  $\mathcal{M} = \{\tau_1, \dots, \tau_m\}$  drawn u.a.r. from  $\mathbb{T}$ 

• Require  $\sum_{\tau} p(c \mid \tau \circ X') \approx \frac{|\mathbb{T}|}{|C|} \pm \rho$ 

**Code:**  $\tau_i \xrightarrow{Enc} p(\cdot \mid \tau_i \circ X') \xrightarrow{\mathcal{C}_A} p(\cdot \mid \tau_i \circ X'') \xrightarrow{Dec} \hat{\tau}$ 

- $Enc_A$ : encodes  $\tau_i \in \mathcal{M}$  as  $p(\cdot \mid \tau_i \circ X')$
- $Dec_{\mathcal{A}}$ : selects  $\hat{\tau} = \arg \max_{\tau} \kappa(\tau_i \circ X'', \tau \circ X')$

whereby  $\kappa(X'', X') := \sum_{c} p(c \mid X'') p(c \mid X')$ 

**Approximate Sorting:**  $R^{Sort}(\pi \mid \mathbf{X}) = \sum_{i,j} x_{ij} \mathbb{I}_{\{\pi_i > \pi_i\}}$ 

**Approx. cap.:**  $\max_{R} \mathcal{I} = \frac{1}{n} \log |\mathcal{T}| + 1$ 

 $\max_{\beta} \left\{ \frac{1}{n} \sum_{i \le n} \log \sum_{k \le n} \exp(-\beta (\mathcal{E}_{ik}^{(1)} + \mathcal{E}_{ik}^{(1)})) \right\}$  $-\frac{1}{n}\sum_{i\leq n}\log(\sum_{k\leq n}\exp(-\beta\mathcal{E}_{ik}^{(1)})\sum_{k\leq n}\exp(-\beta\mathcal{E}_{ii}^{(2)}))\}$ 

 $R^{mfs}(M \mid \mathcal{E}) = \sum_{i \le nk \le n} M_{ik} \mathcal{E}_{ik} + \sum_{k \le n} \mu_k (\sum_{i \le n} M_{ik} - 1)$   $q_{ik} = \frac{\exp(-\beta(\mathcal{E}_{ik} + \mu_k))}{\sum_{k'} \exp(-\beta(\mathcal{E}_{ik'} + \mu_{k'}))}, \qquad \mathcal{E}_{ik} = \mathbb{E}_{Q_{i \to k}}[R^{Sort}]$ 

## 8.3 Applications of PA

**PA**: quantifies the amount of information that algorithms extract from phenomena.  $\rightarrow$  quantified by **capacity** (max. # distinguishable messages that can be communicated)

**Temperature:**  $T^* = \arg\max_T \kappa(X', X'')$ 

**Cost functions:** Given  $R_1(\cdot, \cdot), \dots, R_s(\cdot, \cdot)$  $\max_{\ell < s} \kappa_{\ell}(X', X'') = \max_{\ell < s} \frac{1}{Z_{X'}Z_{X''}} \sum_{s} e^{-\frac{1}{T}R_{\ell}(c, X')} e^{-\frac{1}{T}R_{\ell}(c, X'')}$ 

**Algorithms:** Many MST (min. spanning tree) algo's are **contractive** ( $\rightarrow$  sequence of candidate sol's).

**Approximation Set Coding (ASC):** 

$$p^{\text{ASC}}(c \mid X') = \begin{cases} 1/\left|G_{\gamma}(X')\right| & \text{if } c \in G_{\gamma}(X') \\ 0 & \text{otw.} \end{cases}$$
$$G_{\gamma}(X') := \left\{ c \in \mathcal{C} : R(c, X') - \min_{c \in \mathcal{C}} R(c, X') \le \gamma \right\}$$

- 1. Run  $\mathcal{A}$  to compute  $G_t^{\mathcal{A}}(X')$  and  $G_t^{\mathcal{A}}(X'')$ , for all t
- 2.  $t^* = \arg\max_t \kappa(X', X'') = \arg\max_t \frac{|G_t^A(X') \cap G_t^A(X'')|}{|G_t^A(X')| \cdot |G_t^A(X'')|}$
- 3.  $c^* \stackrel{\text{\$ sample}}{\longleftarrow} \text{Unif}(G_{t^*}^{\mathcal{A}}(X') \cap G_{t^*}^{\mathcal{A}}(X''))$

## 9 Appendix

## 9.1 Tips and Tricks

## **Complete the square:**

If  $p(x) \propto \exp(-\frac{1}{2}x^{\mathsf{T}}Ax + x^{\mathsf{T}}b)$ ,

then  $p(x) = \mathcal{N}(x \mid A^{-1}b, A^{-1})$ 

**Constrained optimisation:** primal:  $\min_{\mathbf{x}} f(\mathbf{x})$  s.t.  $g_i(\mathbf{x}) = 0$ ;  $h_i(\mathbf{x}) \le 0$ 

**Lagrangian:** with each  $\alpha_i \geq 0$ 

 $\mathcal{L}(\mathbf{x}, \lambda, \alpha) = f(\mathbf{x}) + \sum_{i} \lambda_{i} g_{i}(\mathbf{x}) + \sum_{i} \alpha_{i} h_{i}(\mathbf{x})$ 

Solve:  $\frac{\partial \mathcal{L}}{\partial x} = 0$ ;  $g_i(x) = 0$ ;  $\alpha_j \ge 0$ ;  $h_j(x) \le 0$ 

**Euler-Lagrange:** Find extrema of functional  $\mathcal{F}[f] =$ 

 $\int G(x, f(x), f(x)) dx, \text{ thus } \frac{\partial \mathcal{F}}{\partial f} \stackrel{!}{=} 0.$ If *G* is twice diff'able, then

 $\frac{\partial \mathcal{F}}{\partial f} = \frac{\partial G}{\partial f(x)} - \frac{\mathrm{d}}{\mathrm{d}x} \left( \frac{\partial G}{\partial f'(x)} \right) \stackrel{(*)}{=} \frac{\partial G}{\partial f(x)}.$ 

## 9.2 Approximations

**Laplace Approximation:**  $\frac{df}{dx}\Big|_{y_0} = 0$ 

 $\implies \int_{\mathbb{R}} e^{Cf(x)} dx \approx \sqrt{2\pi} C \cdot |f''(x_0)| \cdot e^{Cf(x_0)}$ 

**Hyperbolic Functions:** 

- $\sinh(x) = \frac{e^x e^{-x}}{2}$ ,  $\frac{d}{dx} \sinh(x) = \cosh(x)$   $\cosh(x) = \frac{e^x + e^{-x}}{2}$ ,  $\frac{d}{dx} \cosh(x) = \sinh(x)$   $\tanh(x) = \frac{\sinh(x)}{\cosh(x)} = \frac{e^x e^{-x}}{e^x + e^{-x}}$ ,  $\cosh^2(x) + \sinh^2(x) = 1$
- $\frac{d}{dx} \tanh(x) = 1 \tanh^2(x) = \frac{1}{\cosh^2(x)} = \operatorname{sech}^2(x)$