



## Problem Set 7: Solutions (Fall Break Special)

### Differential Equations

Fall 2024

**Regular Questions:** Review of course contents.

1. (Variation of Parameters). Solve the following third order differential equation of  $y = y(t)$ :

$$y''' - 4y' = e^{-2t}.$$

**Solution:**

First, we find the homogeneous case, that is:

$$y''' - 4y' = 0,$$

whose characteristic equation is  $r^3 - 4r = 0$ , so the roots are  $r = 0, 2, -2$ , hence the homogeneous solution is:

$$y(t) = C_1 + C_2 e^{2t} + C_3 e^{-2t}.$$

Given that the non-homogeneous part already exists in the equation, then our guess should be  $y_p(t) = Ate^{-2t}$ , which the derivatives as:

$$y'_p(t) = Ae^{-2t} - 2Ate^{-2t},$$

$$y''_p(t) = -4Ae^{-2t} + 4Ate^{-2t},$$

$$y'''_p(t) = 12Ae^{-2t} - 8Ate^{-2t}.$$

Note that when we plug into our equation, we have:

$$(12Ae^{-2t} - 8Ate^{-2t}) - 4(Ae^{-2t} - 2Ate^{-2t}) = e^{-2t}.$$

Note that the  $te^{-2t}$  term vanishes (why?), we now have:

$$8Ae^{-2t} = e^{-2t},$$

so we have that  $A = 1/8$ , so our general solution is:

$$y(t) = \boxed{C_1 + C_2 e^{2t} + C_3 e^{-2t} + \frac{1}{8}te^{-2t}}.$$

We invite diligent readers to attempt solving this problem using variation of parameters, as well, namely:

$$y_p(t) = y_1(t) \int_0^t \frac{W_1(s)g(s)}{W(s)} ds + y_2(t) \int_0^t \frac{W_2(s)g(s)}{W(s)} ds + y_3(t) \int_0^t \frac{W_3(s)g(s)}{W(s)} ds.$$

2. (Eigenvalues & Eigenvectors). Find all eigenvectors and eigenvalues of the following matrix:

(a) 
$$A = \begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix},$$

(b) 
$$B = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{pmatrix}.$$

**Solution:**

(a) Here, we find the characteristic equation as:

$$0 = \begin{vmatrix} 5-\lambda & -1 \\ 3 & 1-\lambda \end{vmatrix} = (5-\lambda)(1-\lambda) - (-1) \cdot 3 = 8 - 6\lambda + \lambda^2 = (\lambda - 2)(\lambda - 4).$$

Hence, the eigenvalues are 2 and 4, and the eigenvectors, respectively, are:

i. For  $\lambda_1 = \boxed{2}$ , we have  $A - 2\text{Id}$  as  $\begin{pmatrix} 3 & -1 \\ 3 & -1 \end{pmatrix}$ , we want find  $\xi^{(1)}$  such that  $\begin{pmatrix} 3 & -1 \\ 3 & -1 \end{pmatrix} \cdot \xi^{(1)} = 0$ ,

that is  $3\xi_1^{(1)} - \xi_2^{(1)} = 0$ , so we have  $\xi_2^{(1)} = 3\xi_1^{(1)}$ , so we have  $\xi^{(1)} = \boxed{\begin{pmatrix} 1 \\ 3 \end{pmatrix}}.$

ii. For  $\lambda_2 = \boxed{4}$ , we have  $A - 4\text{Id}$  as  $\begin{pmatrix} 1 & -1 \\ 3 & -3 \end{pmatrix}$ , we want find  $\xi^{(2)}$  such that  $\begin{pmatrix} 1 & -1 \\ 3 & -3 \end{pmatrix} \cdot \xi^{(2)} = 0$ ,

that is  $\xi_1^{(1)} - \xi_2^{(1)} = 0$ , so we have  $\xi_2^{(1)} = \xi_1^{(1)}$ , so we have  $\xi^{(1)} = \boxed{\begin{pmatrix} 1 \\ 1 \end{pmatrix}}.$

(b) Here, we also find the characteristic equation as:

$$0 = \begin{vmatrix} 1-\lambda & 0 & 0 \\ 2 & 1-\lambda & -2 \\ 3 & 2 & 1-\lambda \end{vmatrix} = (1-\lambda)^3 - (1-\lambda)(-4) = (1-\lambda)((1-\lambda)^2 + 4).$$

Hence, the eigenvalues are 1,  $1 + 2i$  and  $1 - 2i$ , and the eigenvectors, respectively, are:

i. For  $\lambda_1 = \boxed{1}$ , we have  $B - \text{Id}$  as  $\begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & -2 \\ 3 & 2 & 0 \end{pmatrix}$ , we want find  $\xi^{(1)}$  such that

$\begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & -2 \\ 3 & 2 & 0 \end{pmatrix} \cdot \xi^{(1)} = 0$ , that is  $\xi_1^{(1)} - \xi_3^{(1)} = 0$  and  $3\xi_1^{(1)} + 2\xi_2^{(1)} = 0$ , so we have

$\xi^{(1)} = \boxed{\begin{pmatrix} 2 \\ -3 \\ 2 \end{pmatrix}}.$

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ii. For  $\lambda_2 = \boxed{1 + 2i}$ , we have  $B - (1 + 2i) \text{Id}$  as  $\begin{pmatrix} -2i & 0 & 0 \\ 2 & -2i & -2 \\ 3 & 2 & -2i \end{pmatrix}$ , we want find  $\xi^{(2)}$  such

that  $\begin{pmatrix} -2i & 0 & 0 \\ 2 & -2i & -2 \\ 3 & 2 & -2i \end{pmatrix} \cdot \xi^{(2)} = \mathbf{0}$ , that is  $\xi_1^{(2)} = 0$  and  $i\xi_2^{(2)} + \xi_3^{(2)} = 0$ , so we have  $\xi^{(2)} =$

$$\boxed{\begin{pmatrix} 0 \\ 1 \\ -i \end{pmatrix}}.$$

iii. For  $\lambda_3 = \boxed{1 - 2i}$ , we have  $B - (1 - 2i) \text{Id}$  as  $\begin{pmatrix} 2i & 0 & 0 \\ 2 & 2i & -2 \\ 3 & 2 & 2i \end{pmatrix}$ , we want find  $\xi^{(3)}$  such that

$$\begin{pmatrix} 2i & 0 & 0 \\ 2 & 2i & -2 \\ 3 & 2 & 2i \end{pmatrix} \cdot \xi^{(3)} = \mathbf{0}, \text{ that is } \xi_1^{(3)} = 0 \text{ and } i\xi_2^{(3)} - \xi_3^{(3)} = 0, \text{ so we have } \xi^{(3)} = \boxed{\begin{pmatrix} 0 \\ 1 \\ i \end{pmatrix}}.$$

3. (Linear Systems). Let  $\mathbf{x} \in \mathbb{R}^2$ , find the general solution of  $\mathbf{x}$  if  $\mathbf{x}$  satisfies:

$$\mathbf{x}' = \begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix} \cdot \mathbf{x}.$$

**Solution:**

Some readers might notice that this is the same matrix in the previous problem, we recall that the eigenvalues and eigenvectors, respectively, are:

$$\lambda_1 = 2, \quad \zeta^{(1)} = \begin{pmatrix} 1 \\ 3 \end{pmatrix},$$

$$\lambda_2 = 4, \quad \zeta^{(2)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

Hence, the solution to the linear system is:

$$\mathbf{x} = C_1 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{2t} + C_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t}.$$

**Additional Questions:** More challenging and fun problems related with the course.

1. (PDEs: Wave Equation). The following system of partial differential equations portraits the propagation of waves on a segment of the 1-dimensional string of length  $L$ , the displacement of string at  $x \in [0, L]$  at time  $t \in [0, \infty)$  is described as the function  $u = u(x, t)$ :

$$\left\{ \begin{array}{ll} \text{Differential Equation:} & \frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0, \quad \text{where } x \in (0, L) \text{ and } t \in [0, \infty); \\ \text{Initial Conditions:} & u(x, 0) = \sin\left(\frac{2\pi x}{L}\right), \\ & \frac{\partial u}{\partial t}(x, 0) = \sin\left(\frac{5\pi x}{L}\right), \quad \text{where } x \in [0, L]; \\ \text{Boundary Conditions:} & u(0, t) = u(L, t) = 0, \quad \text{where } t \in [0, \infty); \end{array} \right.$$

where  $c$  is a constant and  $g(x)$  has "good" behavior. Apply the method of separation, i.e.,  $u(x, t) = v(x) \cdot w(t)$ , and attempt to obtain a general solution that is *non-trivial*.

*Hint:* Use the fact that  $\{\sin(n\pi x/L), \cos(n\pi x/L)\}_{n \in \mathbb{Z}^+}$  forms an orthonormal basis (cf. §5.2).

**Solution:**

With the method of separation, we insert the separations back to the system of equation to obtain:

$$v(x)w''(t) = c^2 v''(x)w(t).$$

Now, we apply the separation and set the common ratio to be  $\lambda$ :

$$\frac{v''(x)}{v(x)} = \frac{1}{c^2} \cdot \frac{w''(t)}{w(t)} = \lambda.$$

Reformatting the boundary condition gives use the following initial value problem:

$$\left\{ \begin{array}{l} v''(x) - \lambda v(x) = 0, \\ v(0) = v(L) = 0. \end{array} \right.$$

As a second order linear ordinary differential equation, we discuss all following cases:

- If  $\lambda = 0$ , then  $v(x) = a + Bx$  and by the initial condition,  $A = B = 0$ , which gives the trivial solution, i.e.,  $v(x) = 0$ ;
- If  $\lambda = \mu^2 > 0$ , then we have  $v(x) = Ae^{-\mu x} + Be^{\mu x}$  and again giving that  $A = B = 0$ , or the trivial solution;
- Eventually, if  $\lambda = -\mu^2 < 0$ , then we have the solution as:

$$v(x) = A \sin(\mu x) + B \cos(\mu x),$$

and the initial conditions gives us that:

$$\left\{ \begin{array}{l} v(0) = B = 0, \\ v(L) = A \sin(\mu L) + B \cos(\mu L) = 0, \end{array} \right.$$

where  $A$  is arbitrary,  $B = 0$ , and  $\mu L = m\pi$  positive integer  $m$ .

Overall, the only non-trivial solution would be:

$$v_m(x) = A \sin(\mu_m x), \text{ where } \mu_m = \frac{m\pi}{L}.$$

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Eventually, by inserting back  $\lambda = -\mu_m^2$ , we have  $\lambda = -m^2\pi^2/L^2$ , giving the solution to  $w_m(t)$ , another second order linear ordinary differential equation, as:

$$w_m(t) = C \cos(\mu_m ct) + D \sin(\mu_m ct), \text{ with } C, D \in \mathbb{R}.$$

By the *principle of superposition*, we can have our solution in the form:

$$u(x, t) = \sum_{m=1}^{\infty} [a_m \cos(\mu_m ct) + b_m \sin(\mu_m ct)] \sin(\mu_m x),$$

where our coefficients  $a_m$  and  $b_m$  have to be chosen to satisfy the initial conditions for  $x \in [0, L]$ :

$$u(x, 0) = \sum_{m=1}^{\infty} a_m \sin(\mu_m x) = \sin\left(\frac{2\pi x}{L}\right),$$

$$\frac{\partial u}{\partial t}(x, 0) = \sum_{m=1}^{\infty} c\mu_m b_m \sin(\mu_m x) = \sin\left(\frac{5\pi x}{L}\right).$$

Since we are hinted that  $\{\sin(n\pi x/L), \cos(n\pi x/L)\}_{n \in \mathbb{Z}^+}$  forms an orthonormal basis, we now know that except for the following:

$$a_2 = 1 \text{ and } c\mu_5 b_5 = 1,$$

all the other coefficients are zero, so we have:

$$u(x, t) = \left[ \cos\left(\frac{2\pi ct}{L}\right) \sin\left(\frac{2\pi x}{L}\right) + \frac{L}{5\pi c} \sin\left(\frac{5\pi ct}{L}\right) \sin\left(\frac{5\pi x}{L}\right) \right].$$

2. (Putnam 2023: First Positive Root). Determine the smallest positive real number  $r$  such that there exists differentiable functions  $f : \mathbb{R} \rightarrow \mathbb{R}$  and  $g : \mathbb{R} \rightarrow \mathbb{R}$  satisfying:

- $f(0) > 0$ ,
- $g(0) = 0$ ,
- $|f'(x)| \leq |g(x)|$  for all  $x$ ,
- $|g'(x)| \leq |f(x)|$  for all  $x$ , and
- $f(r) = 0$ .

You may give an answer without a rigorous proof, as the proof is out of scope of the course.

*Hint:* Assume that the function “moves” the fastest when the cap of the derivatives are “moving” the fastest, then think of constructing a dynamical system relating  $f$  and  $g$ .

**Solution:**

Here, we first provide a “simplified” case, *i.e.*, we are constructing a dynamical system in which we pick equality for the inequality, that is:

$$\begin{cases} |f'(x)| = |g(x)|, \text{ and} \\ |g'(x)| = |f(x)|. \end{cases}$$

Without loss of generality, we may assume that  $f$  and  $g$  are non-negative before  $r$ , so the system becomes:

$$\begin{cases} f' = -g \\ g' = f \end{cases},$$

or equivalently,  $\mathbf{y} = \begin{pmatrix} f \\ g \end{pmatrix}$  that  $\mathbf{y}' = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \mathbf{y}$ . Clearly, we observe the eigenvalues are  $\pm i$  as the polynomial is  $\lambda^2 + 1 = 0$ . Moreover, the eigenvectors for  $\lambda_1 = i$  is when  $\begin{pmatrix} -i & -1 \\ 1 & -i \end{pmatrix} \boldsymbol{\xi} = \mathbf{0}$ , in which

we have  $\boldsymbol{\xi} = y \begin{pmatrix} i \\ 1 \end{pmatrix}$ , and that solution is:

$$\mathbf{y} = \begin{pmatrix} i \\ 1 \end{pmatrix} e^{ix} = \begin{pmatrix} i \\ 1 \end{pmatrix} (\cos x + i \sin x) = \begin{pmatrix} -\sin x \\ \cos x \end{pmatrix} + i \begin{pmatrix} \cos x \\ \sin x \end{pmatrix}$$

and by conjugation, the solution should be:

$$\begin{pmatrix} f \\ g \end{pmatrix} = C_1 \begin{pmatrix} -\sin x \\ \cos x \end{pmatrix} + C_2 \begin{pmatrix} \cos x \\ \sin x \end{pmatrix}.$$

Note that with the given initial condition that  $g(0) = 0$ , this enforces  $C_1 = 0$ , thus  $f(x) = C \cos x$  and  $g(x) = C \sin x$ , and we know that  $f(r)$  is zero first at  $r = \boxed{\pi/2}$ .

*The above version has some reasoning, but is not a rigorous proof at all, since this does not consider if  $r$  could be smaller than  $\pi/2$ . For students with interests, we provide the complete proof from the Putnam competition from Victor Lie, as follows.*

*Proof.* Without loss of generality, we assume  $f(x) > 0$  for all  $x \in [0, r)$  as it is the first positive zero. By the fundamental theorem of calculus, we have:

$$|f'(x)| \leq |g(x)| \leq \left| \int_0^x g(s) ds \right| \leq \int_0^x |g(s)| ds \leq \int_0^t |f(s)| ds.$$

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Now, as we denote  $F(x) = \int_0^x f(s)ds$ , we have:

$$f'(x) + F(x) \geq 0 \text{ for } x \in [0, r].$$

For the sake of contradiction, we suppose  $r < \pi/2$ , then we have:

$$f'(x) \cos x + F(x) \cos x \geq 0 \text{ for } x \in [0, r].$$

Notice that the left hand side is the derivative of  $f(x) \cos x + F(x) \sin x$ , so an integration on  $[y, r]$  gives:

$$F(r) \sin r \geq f(y) \cos y + F(y) \sin(y).$$

With some rearranging, we can have:

$$F(r) \sin r \sec^2 y \geq f(y) \sec y + F(y) \sin y \sec^2 y$$

Again, we integrate both sides with respect to  $y$  on  $[0, r]$ , which gives:

$$F(r) \sin^2 r \geq F(r),$$

and this is impossible, so we have a contradiction.

Hence we must have  $r \geq \pi/2$ , and since we have noted the solution  $f(x) = C \cos x$  and  $g(x) = C \sin x$ , we have proven that  $r = \pi/2$  is the smallest case.  $\square$



3. (Nilpotent Operator). Let  $M$  be a square matrix,  $M$  is defined to be *nilpotent* if:

$$M^k = 0 \text{ for some positive integer } k.$$

Similar to how we defined the exponential function analytically, the exponential function is also defined for matrices, let  $A$  be a square matrix, we define:

$$\exp(A) = \sum_{i=0}^{\infty} \frac{1}{i!} A^i.$$

- (a) Show that  $N = \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$  is nilpotent, then write down the result of  $\exp(N)$ .

Now, suppose that  $N \in \mathcal{L}(\mathbb{R}^n)$  is a square matrix and is *nilpotent*.

- (b) Suppose that  $\text{Id}_n \in \mathcal{L}(\mathbb{R}^n)$  is the identity matrix, prove that  $\text{Id}_n + N$  is invertible.

*Hint:* Use the differences of squares for matrices.

- (c) If all the entries in  $N$  are rational, show that  $\exp(N)$  has rational entries.

**Solution:**

- (a) *proof of  $N$  is nilpotent.* Here, we want to do the matrix multiplication:

$$N^2 = \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix},$$

$$N^3 = \begin{pmatrix} 0 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Now, we have shown that  $N^3 = 0$ , or the zero matrix, hence  $N$  is nilpotent. □

Then, we want to calculate the matrix exponential, that is:

$$\exp(N) = \sum_{k=0}^{\infty} \frac{1}{k!} N^k = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \boxed{\begin{pmatrix} 1 & 2 & 4 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}}.$$

- (b) *Proof.* Here, we recall the differences of squares still works when commutativity for multiplications fails, hence the we can still use it for matrix multiplication, namely, for all  $m \in \mathbb{Z}^+$ :

$$(\text{Id}_n + N) \cdot (\text{Id}_n - N) \cdot (\text{Id}_n + N^2) \cdots (\text{Id}_n + N^{2^m}) = \text{Id}_n - N^{2^{m+1}}$$

Since  $N$  is *nilpotent*, this implies that we have some  $k$  such that  $N^\ell = 0$  for all  $\ell \geq k$ . Meanwhile, note that  $2^\ell \geq \ell$  for all positive integer  $\ell$ . (This can be proven by induction.) Therefore, we select  $m + 1 \geq k$  so that  $N^{2^{m+1}} = 0$ , and we have:

$$(\text{Id}_n + N) \cdot [(\text{Id}_n - N) \cdot (\text{Id}_n + N^2) \cdots (\text{Id}_n + N^{2^m})] = \text{Id}_n,$$

thus  $\text{Id}_n + N$  is invertible. □

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- (c) *Proof.* By the definition that  $N$  is nilpotent, we know that  $N^m = 0$  for some finite positive integer  $m$ , hence, we can make the (countable) infinite sum into a finite sum:

$$\exp(N) = \sum_{k=0}^{\infty} \frac{1}{k!} N^k = \sum_{k=0}^m \frac{1}{k!} N^k,$$

thus all the entries are sum and non-zero divisions of rational numbers, while rational numbers are closed under addition and non-zero divisions, hence, all entries of  $\exp(N)$  is rational.  $\square$

Note that the elements of all  $n$ -by- $n$  matrices can be considered as a *ring*, while *nilpotent* can be defined more generally for *rings*. We invite capable readers to investigate more properties of *nilpotent* elements of *rings* in the discipline of *Modern Algebra*.

4. (Convergence of Series.) As we dive into fundamentals of mathematics, it is inevitable to encounter *sequences* and their sums. Discuss about the following sequences if they converge or not. If they converge, find the explicit sum.

- (a)  $\sum_{k=0}^{\infty} \frac{1}{k}.$
- (b)  $\sum_{k=0}^{\infty} \frac{1}{k!}.$
- (c)  $\sum_{k=0}^{\infty} \frac{1}{(4k+1)!}.$

**Solution:**

- (a) Diligent readers should observe that  $\sum_{k=0}^{\infty} 1/k$  is a harmonic series, hence it diverges.

Otherwise, we can simply notice that:

$$\begin{aligned} \sum_{k=0}^{\infty} \frac{1}{k} &= \frac{1}{1} + \frac{1}{2} + \frac{1}{3} + \frac{1}{4} + \frac{1}{5} + \frac{1}{6} + \frac{1}{7} + \frac{1}{8} + \frac{1}{9} + \dots \\ &\geq \frac{1}{1} + \frac{1}{2} + \frac{1}{4} + \frac{1}{4} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \frac{1}{16} + \dots \\ &= \frac{1}{1} + \frac{1}{2} + \left(\frac{1}{4} + \frac{1}{4}\right) + \left(\frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8}\right) + \left(\frac{1}{16} + \dots\right) + \dots \\ &= \frac{1}{1} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \dots, \end{aligned}$$

which diverges, hence our sequence  $\sum_{k=0}^{\infty} 1/k$  must diverge.

- (b) Here, we recall that the Taylor expansion of  $e^x$  at 0 is:

$$e^x = \sum_{k=0}^{\infty} \frac{1}{k!} e^0 (x-0)^k = \sum_{k=0}^{\infty} \frac{1}{k!} x^k.$$

Evaluating the above equation at 1 gives that:

$$\sum_{k=0}^{\infty} \frac{1}{k!} = e^1 = \boxed{e},$$

in which the sequence converges.

- (c) For this part, we want to note the Taylor series of  $e^x$ ,  $e^{-x}$ ,  $\sin x$  and  $\cos x$  at 0 evaluated at  $x = 1$  are, respectively:

$$\begin{aligned} e^1 &= +\frac{1}{0!} + \frac{1}{1!} + \frac{1}{2!} + \frac{1}{3!} + \frac{1}{4!} + \frac{1}{5!} + \dots \\ e^{-1} &= +\frac{1}{0!} - \frac{1}{1!} + \frac{1}{2!} - \frac{1}{3!} + \frac{1}{4!} - \frac{1}{5!} + \dots \\ \sin 1 &= \quad +\frac{1}{1!} \quad \quad -\frac{1}{3!} \quad \quad +\frac{1}{5!} \quad -\dots \\ \cos 1 &= +\frac{1}{0!} \quad \quad -\frac{1}{2!} \quad \quad +\frac{1}{4!} \quad \quad -\dots \end{aligned}$$

Since the first series converges, we know that the later three series converges *absolutely*, so we are free to move around terms. Thus comparing vertically gives us that:

$$\sum_{k=0}^{\infty} \frac{1}{(4k+3)!} = \boxed{\frac{e^1 - e^{-1}}{4} + \frac{\sin 1}{2}}.$$