## PILOT Midterm 2 Review

## **Differential Equations**

Johns Hopkins University

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As you prepare for the midterm, please consider the following resources:

- PILOT webpage for ODEs: https://jhu-ode-pilot.github.io/SP25/
  - Problem sets 5 to 9 will be associated with this midterm. (Except for the first three question on PSet 5 and last question in PSet 9.)
  - Find the review problem set for midterm 2.
  - Extra material: Spring Break Extra Practice Set (Harder).
- Review the *homework sets* provided by the instructor.
- Join the PILOT Midterm 2 Review Session. (You are here.)



## Plan for today:

- **I** Go over all contents that we have covered for this semester so far.
- 2 In the end, we will open the poll to you. Please indicate which problems from the PSets or Review Set that you want us to go over.



#### Contents:

- 1 Second Order ODEs
  - Linear Homogeneous Cases
  - Linear Independence
  - Existence and Uniqueness Theorem
  - Superposition Theorem
  - Abel's Formula
  - Reduction of Order
  - Non-homogeneous Cases
- 2 Higher Order ODEs
  - Existence and Uniqueness Theorem
  - Homogeneous Cases
  - Linear Independence
  - Abel's Formula
  - Non-Homogeneous Cases
- 3 Review Problems



## **Part 1**: Contents Review

We will get through all contents over this semester.

- Feel free to download the slide deck from the webpage and annotate on it.
- If you have any questions, ask by the end of each chapter.

Consider the linear homogeneous ODE:

$$y'' + py' + qy = 0.$$

Its characteristic equation is:

$$r^2 + pr + q = 0.$$

With solutions  $r_1$  and  $r_2$ , the general solution is:

$$y(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}.$$

If the solutions  $r_1$  and  $r_2$  are complex, by Euler's Formula  $(e^{it} = \cos t + i \sin t)$ , it can be written as  $r_1 = \lambda + i\beta$  and  $r_2 = \lambda - i\beta$ , then the solution is:

$$y(t) = c_1 e^{\lambda t} \cos(\beta t) + c_2 e^{\lambda t} \sin(\beta t).$$

If the solutions  $r_1$  and  $r_2$  are repeated, the solution is:

$$y(t) = c_1 e^{rt} + c_2 t e^{rt}.$$



To form a fundamental set of solutions, the solutions need to be linearly independent, in which the Wronskian (*W*) must be non-zero, meaning that:

$$W[y_1, y_2] = \det \begin{pmatrix} y_1 & y_2 \\ y_1' & y_2' \end{pmatrix}.$$

Consider IVP in form:

$$\begin{cases} y'' + p(t)y' + q(t)y = g(t), \\ y(t_0) = y_1, y'(t_0) = y_2. \end{cases}$$

The interval I containing  $t_0$  has p(t), q(t), and g(t) continuous on it. Then, there is a unique solution y(t) and twice differentiable on the interval I.

If  $y_1(t)$  and  $y_2(t)$  are solutions to l[y] = 0, then the solution  $c_1y_1(t) + c_2y_2(t)$  are also solutions for all constants  $c_1, c_2 \in \mathbb{R}$ .

Consider the equation y'' + py' + qy = 0, the Wronskian for the solutions are:

$$W[y_1, y_2] = C \exp\left(-\int p dt\right),\,$$

where C is independent of t but depends on  $y_1$  and  $y_2$ .

For non-linear second order homogeneous ODEs, when one solution  $y_1(t)$  is given, the other solution is in form:

$$y_2(t) = u(t) \times y_1(t).$$



Let the differential equation be:

$$Ay''(t) + By'(t) + Cy(t) = g(t),$$

where g(t) is a smooth function. Let  $y_1(t)$  and  $y_2(t)$  be the two homogeneous solutions, then the non-homogeneous cases can be solved by the following approaches:

■ Undetermined Coefficient: A guess of particular solution will be made based on the terms appearing in the non-homogeneous part, or g(t). Some brief strategies are:

Non-homogeneous Comp. in $g(t)$		Guess
Polynomials:	$\sum_{i=0}^d a_i t^i$	$\sum_{i=0}^{d} C_i t^i$
Trig.:	$\sin(at)$ and $\cos(at)$	$C_1\sin(ax) + C_2\sin(ax)$
Exp.:	$e^{at}$	Ce <sup>at</sup>

Note that the guess are additive and multiplicative. Moreover, if the non-homogeneous part is already appearing in the homogeneous solutions, an extra *t* needs to be multiplied on the non-homogeneous case.

■ Variation of Parameters: The particular solution is:

$$y_p = y_1(t) \int \frac{-y_2(t) \times g(t)}{W} dt + y_2(t) \int \frac{y_1(t) \times g(t)}{W} dt.$$

For higher order IVP in form:

$$\begin{cases} y^{(n)} + P_{n-1}(t)y^{(n-1)} + \dots + P_1(t)y' + P_0(t)y = g(t), \\ y(t_0) = y_0, \ y'(t_0) = y_1, \ \dots, y^{(n-1)}(t_0) = y_{n-1}. \end{cases}$$

If  $P_0(t)$ ,  $P_1(t)$ ,  $\cdots$ ,  $P_{n-1}(t)$ , and g(t) are continuous on an interval I containing  $t_0$ . Then there exists a unique solution for y(t) on I.

The higher order homogeneous ODEs are in form:

$$y^{(n)} + a_{n-1}y^{(n-1)} + \dots + a_1y' + a_0y = 0.$$

By computing the characteristic equation:

$$r^{n} + a_{n-1}r^{n-1} + \dots + a_{1}r + a_{0} = 0.$$

With solutions  $r_1$ ,  $r_2$ ,  $\cdots$ ,  $r_n$ , the general solution is:

$$y(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t} + \dots + c_n e^{r_n t}.$$

Note that the complex solutions can still be converted to sines and cosines, while repeated roots multiply a *t* on the repeated solutions.

To obtain the fundamental set of solutions, the Wronskian (*W*) must be non-zero, where Wronskian is:

$$W[y_1, y_2, \cdots, y_n] = \det \begin{pmatrix} y_1 & y_2 & \cdots & y_n \\ y'_1 & y'_2 & \cdots & y'_n \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n)} & y_2^{(n)} & \cdots & y_n^{(n)} \end{pmatrix}.$$

Alternation to the Wronskian: By definition of linear independence,  $f_1, f_2, \dots, f_n$  are independent on I is equivalent to the expression where  $k_1f_1 + k_2f_2 + \dots + k_nf_n = 0$  if and only if  $k_i = 0$ .

For higher order ODEs in the form of:

$$\begin{cases} y^{(n)} + P_{n-1}(t)y^{(n-1)} + \dots + P_1(t)y' + P_0(t)y = g(t), \\ y(t_0) = y_0, \ y'(t_0) = y_1, \ \dots, y^{(n-1)}(t_0) = y_{n-1}. \end{cases}$$

Its Wronskian is:

$$W[y_1, y_2, \cdots, y_n] = Ce^{\int P_{n-1}(t)dt},$$

where *C* is independent of *t* but depend on  $y_1, y_2, \dots, y_n$ .

Let the differential equation be:

$$L[y^{(n)}(t), y^{(n-1)}(t), \cdots, y(t)] = g(t),$$

where g(t) is a smooth function. Let  $y_1(t), y_2(t), \dots, y_n(t)$  be all homogeneous solutions, then the non-homogeneous cases can be solved by the following approaches:

■ Undetermined Coefficient: Same as in degree 2, a guess of particular solution will be made based on the terms appearing in the non-homogeneous part, or g(t). Some brief strategies are:

Non-homogeneous Comp. in $g(t)$		Guess
Polynomials:	$\sum_{i=0}^{d} a_i t^i$	$\sum_{i=0}^{d} C_i t^i$
Trig.:	sin(at) and $cos(at)$	$C_1\sin(ax) + C_2\sin(ax)$
Exp.:	$e^{at}$	Ce <sup>at</sup>

Note that the guess are additive and multiplicative. Moreover, if the non-homogeneous part is already appearing in the homogeneous solutions, an extra *t* needs to be multiplied on the non-homogeneous case.

Variation of Parameters: The particular solution is:

$$y_p = y_1(t) \int \frac{W_1g}{W} dt + y_2(t) \int \frac{W_2g}{W} dt + \dots + y_n(t) \int \frac{W_ng}{W} dt$$
, where  $W_i$  is defined to be the Wronskian with the *i*-th

column alternated into 
$$\begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$$
.

# **Part 2**: Open Poll

## We will work out some sample questions.

- If you have a problem that you are interested with, tell us now.
- Otherwise, we will work through the practice problem set sequentially.
- We are also open to conceptual questions with the course.

- Solve the following second order differential equations for y = y(x):
  - (a) y'' + y' 132y = 0.
  - (b) y'' 4y' = -4y.
  - (c) y'' 2y' + 3y = 0.
- 2 Given a differential equation for y = y(t) being:

$$t^3y'' + ty' - y = 0.$$

- 1 Verify that  $y_1(t) = t$  is a solution to the differential equation.
- 2 Find the full set of solutions using reduction of order.
- 3 Show that the set of solutions from part (b) is linearly independent.



3 Given the following second order initial value problem:

$$\begin{cases} \frac{d^2y}{dx^2} + \cos(1-x)y = x^2 - 2x + 1, \\ y(1) = 1, & \frac{dy}{dx}(1) = 0. \end{cases}$$

Prove that the solution y(x) is symmetric about x = 1, *i.e.*, satisfying that y(x) = y(2 - x).

*Hint:* Consider the interval in which the solution is unique.

4 Solve the general solution for y = y(t) to the following second order non-homogeneous ODEs.

(a) 
$$y'' + 2y' + y = e^{-t}$$
.

(b) 
$$y'' + y = \tan t$$
.

**5** Solve for the general solution to the following higher order ODE.

(a) 
$$4\frac{d^4y}{dx^4} - 24\frac{d^3y}{dx^3} + 45\frac{d^2y}{dx^2} - 29\frac{dy}{dx} + 6y = 0.$$

$$(b) \qquad \frac{d^4y}{dx^4} + y = 0.$$

*Hint:* Consider the 8-th root of unity, *i.e.*,  $\zeta_8$ , and verify which roots satisfies the polynomial.

**6** Let a third order differential equation be as follows:

$$\ell[y(t)] = y^{(3)}(t) + 3y''(t) + 3y'(t) + y(t).$$

Let  $\ell[y(t)] = 0$  be trivial initially.

- 1 Find the set of all linearly independent solutions. Then, assume that  $\ell[y(t)]$  is non-trivial.
- 2 Find the particular solution to  $\ell[y(t)] = \sin t$ .
- 3 Find the particular solution to  $\ell[y(t)] = e^{-t}$ .
- **4** Suppose that  $\ell[y_1(t)] = f(t)$  and  $\ell[y_2(t)] = g(t)$  where f(t) and g(t) are "good" functions. Find an expression to  $y_3(t)$  such that  $\ell[y_3(t)] = f(t) + g(t)$ .

