

hw4

March 3, 2023

```
[1]: %matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
import torch
import torchvision
import torchvision.transforms as transforms
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
```

Prepare for Dataset

```
[2]: transform = transforms.Compose(
    [transforms.ToTensor(),
     transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                          shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified

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```
[3]: # The function to show an image.
def imshow(img):
    img = img / 2 + 0.5     # Unnormalize.
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
    plt.show()
```

```
# Get some random training images.
dataiter = iter(trainloader)
images, labels = next(dataiter)
# Show images.
imshow(torchvision.utils.make_grid(images))
# Print labels.
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```



ship horse plane frog

Choose a Device

```
[4]: # If there are GPUs, choose the first one for computing. Otherwise use CPU.
device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")
print(device)
# If 'cuda:0' is printed, it means GPU is available.
```

cpu

Network Definition

```
[5]: class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        ##### Fill the blank here #####
        self.conv1 = nn.Conv2d(3, 10, kernel_size=3, padding=1)

        self.relu1 = nn.ReLU()

        self.pool1 = nn.AvgPool2d(kernel_size=2, stride=2)

        self.conv2 = nn.Conv2d(10, 20, kernel_size=3, padding=1)

        self.relu2 = nn.ReLU()

        self.pool2 = nn.AvgPool2d(kernel_size=2, stride=2)
```

```

        self.conv3 = nn.Conv2d(20, 30, kernel_size=3, padding=1)

        self.relu3 = nn.ReLU()

        self.pool3 = nn.AvgPool2d(kernel_size=2, stride=2)

        self.fc1 = nn.Linear(30 * 4 * 4, 100)

        self.relu4 = nn.ReLU()

        self.fc2 = nn.Linear(100, 10)

    def forward(self, x):
        ##### Fill the blank here #####
        x = self.pool1(self.relu1(self.conv1(x)))
        x = self.pool2(self.relu2(self.conv2(x)))
        x = self.pool3(self.relu3(self.conv3(x)))
        x = x.view(-1, 30 * 4 * 4)
        x = self.relu4(self.fc1(x))
        x = self.fc2(x)
        return x

net = Net()      # Create the network instance.
net.to(device)  # Move the network parameters to the specified device.

```

```

[5]: Net(
  (conv1): Conv2d(3, 10, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (relu1): ReLU()
  (pool1): AvgPool2d(kernel_size=2, stride=2, padding=0)
  (conv2): Conv2d(10, 20, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (relu2): ReLU()
  (pool2): AvgPool2d(kernel_size=2, stride=2, padding=0)
  (conv3): Conv2d(20, 30, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (relu3): ReLU()
  (pool3): AvgPool2d(kernel_size=2, stride=2, padding=0)
  (fc1): Linear(in_features=480, out_features=100, bias=True)
  (relu4): ReLU()
  (fc2): Linear(in_features=100, out_features=10, bias=True)
)

```

Optimizer and Loss Function

```
[15]: # We use cross-entropy as loss function.
loss_func = nn.CrossEntropyLoss()
# We use stochastic gradient descent (SGD) as optimizer.
opt = optim.SGD(net.parameters(), lr=0.0005, momentum=0.9)
```

Training Procedure

```
[16]: avg_losses = []    # Avg. losses.
epochs = 10            # Total epochs.
print_freq = 100       # Print frequency.

for epoch in range(epochs): # Loop over the dataset multiple times.
    running_loss = 0.0      # Initialize running loss.
    for i, data in enumerate(trainloader, 0):
        # Get the inputs.
        inputs, labels = data

        # Move the inputs to the specified device.
        inputs, labels = inputs.to(device), labels.to(device)

        # Zero the parameter gradients.
        opt.zero_grad()

        # Forward step.
        outputs = net(inputs)
        loss = loss_func(outputs, labels)

        # Backward step.
        loss.backward()

        # Optimization step (update the parameters).
        opt.step()

        # Print statistics.
        running_loss += loss.item()
        if i % print_freq == print_freq - 1: # Print every several mini-batches.
            avg_loss = running_loss / print_freq
            print('[epoch: {}], i: {:5d}] avg mini-batch loss: {:.3f}'.format(
                epoch, i, avg_loss))
            avg_losses.append(avg_loss)
            running_loss = 0.0

print('Finished Training.')
```

```
[epoch: 0, i:    99] avg mini-batch loss: 0.763
[epoch: 0, i:   199] avg mini-batch loss: 0.700
[epoch: 0, i:   299] avg mini-batch loss: 0.722
[epoch: 0, i:   399] avg mini-batch loss: 0.708
```

[epoch: 0, i: 499] avg mini-batch loss: 0.574
[epoch: 0, i: 599] avg mini-batch loss: 0.657
[epoch: 0, i: 699] avg mini-batch loss: 0.647
[epoch: 0, i: 799] avg mini-batch loss: 0.600
[epoch: 0, i: 899] avg mini-batch loss: 0.599
[epoch: 0, i: 999] avg mini-batch loss: 0.617
[epoch: 0, i: 1099] avg mini-batch loss: 0.579
[epoch: 0, i: 1199] avg mini-batch loss: 0.628
[epoch: 0, i: 1299] avg mini-batch loss: 0.580
[epoch: 0, i: 1399] avg mini-batch loss: 0.573
[epoch: 0, i: 1499] avg mini-batch loss: 0.565
[epoch: 0, i: 1599] avg mini-batch loss: 0.601
[epoch: 0, i: 1699] avg mini-batch loss: 0.582
[epoch: 0, i: 1799] avg mini-batch loss: 0.654
[epoch: 0, i: 1899] avg mini-batch loss: 0.560
[epoch: 0, i: 1999] avg mini-batch loss: 0.498
[epoch: 0, i: 2099] avg mini-batch loss: 0.497
[epoch: 0, i: 2199] avg mini-batch loss: 0.503
[epoch: 0, i: 2299] avg mini-batch loss: 0.639
[epoch: 0, i: 2399] avg mini-batch loss: 0.587
[epoch: 0, i: 2499] avg mini-batch loss: 0.606
[epoch: 0, i: 2599] avg mini-batch loss: 0.571
[epoch: 0, i: 2699] avg mini-batch loss: 0.604
[epoch: 0, i: 2799] avg mini-batch loss: 0.546
[epoch: 0, i: 2899] avg mini-batch loss: 0.614
[epoch: 0, i: 2999] avg mini-batch loss: 0.625
[epoch: 0, i: 3099] avg mini-batch loss: 0.468
[epoch: 0, i: 3199] avg mini-batch loss: 0.580
[epoch: 0, i: 3299] avg mini-batch loss: 0.526
[epoch: 0, i: 3399] avg mini-batch loss: 0.623
[epoch: 0, i: 3499] avg mini-batch loss: 0.562
[epoch: 0, i: 3599] avg mini-batch loss: 0.650
[epoch: 0, i: 3699] avg mini-batch loss: 0.443
[epoch: 0, i: 3799] avg mini-batch loss: 0.564
[epoch: 0, i: 3899] avg mini-batch loss: 0.518
[epoch: 0, i: 3999] avg mini-batch loss: 0.536
[epoch: 0, i: 4099] avg mini-batch loss: 0.483
[epoch: 0, i: 4199] avg mini-batch loss: 0.515
[epoch: 0, i: 4299] avg mini-batch loss: 0.599
[epoch: 0, i: 4399] avg mini-batch loss: 0.488
[epoch: 0, i: 4499] avg mini-batch loss: 0.524
[epoch: 0, i: 4599] avg mini-batch loss: 0.421
[epoch: 0, i: 4699] avg mini-batch loss: 0.534
[epoch: 0, i: 4799] avg mini-batch loss: 0.455
[epoch: 0, i: 4899] avg mini-batch loss: 0.476
[epoch: 0, i: 4999] avg mini-batch loss: 0.492
[epoch: 0, i: 5099] avg mini-batch loss: 0.461
[epoch: 0, i: 5199] avg mini-batch loss: 0.530

[epoch: 0, i: 5299] avg mini-batch loss: 0.566
[epoch: 0, i: 5399] avg mini-batch loss: 0.472
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[epoch: 0, i: 5599] avg mini-batch loss: 0.500
[epoch: 0, i: 5699] avg mini-batch loss: 0.491
[epoch: 0, i: 5799] avg mini-batch loss: 0.486
[epoch: 0, i: 5899] avg mini-batch loss: 0.517
[epoch: 0, i: 5999] avg mini-batch loss: 0.566
[epoch: 0, i: 6099] avg mini-batch loss: 0.537
[epoch: 0, i: 6199] avg mini-batch loss: 0.558
[epoch: 0, i: 6299] avg mini-batch loss: 0.540
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[epoch: 1, i: 8499] avg mini-batch loss: 0.444
[epoch: 1, i: 8599] avg mini-batch loss: 0.530
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[epoch: 1, i: 8799] avg mini-batch loss: 0.519
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[epoch: 1, i: 11999] avg mini-batch loss: 0.484
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[epoch: 1, i: 12399] avg mini-batch loss: 0.453
[epoch: 1, i: 12499] avg mini-batch loss: 0.495
[epoch: 2, i: 99] avg mini-batch loss: 0.443
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[epoch: 2, i: 299] avg mini-batch loss: 0.463
[epoch: 2, i: 399] avg mini-batch loss: 0.403
[epoch: 2, i: 499] avg mini-batch loss: 0.361
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[epoch: 2, i: 799] avg mini-batch loss: 0.406
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[epoch: 7, i: 11199] avg mini-batch loss: 0.323
[epoch: 7, i: 11299] avg mini-batch loss: 0.392
[epoch: 7, i: 11399] avg mini-batch loss: 0.278
[epoch: 7, i: 11499] avg mini-batch loss: 0.286
[epoch: 7, i: 11599] avg mini-batch loss: 0.291
[epoch: 7, i: 11699] avg mini-batch loss: 0.403
[epoch: 7, i: 11799] avg mini-batch loss: 0.282
[epoch: 7, i: 11899] avg mini-batch loss: 0.315
[epoch: 7, i: 11999] avg mini-batch loss: 0.361
[epoch: 7, i: 12099] avg mini-batch loss: 0.383
[epoch: 7, i: 12199] avg mini-batch loss: 0.280
[epoch: 7, i: 12299] avg mini-batch loss: 0.351
[epoch: 7, i: 12399] avg mini-batch loss: 0.374
[epoch: 7, i: 12499] avg mini-batch loss: 0.349
[epoch: 8, i: 99] avg mini-batch loss: 0.247
[epoch: 8, i: 199] avg mini-batch loss: 0.308
[epoch: 8, i: 299] avg mini-batch loss: 0.339
[epoch: 8, i: 399] avg mini-batch loss: 0.276
[epoch: 8, i: 499] avg mini-batch loss: 0.316
[epoch: 8, i: 599] avg mini-batch loss: 0.304
[epoch: 8, i: 699] avg mini-batch loss: 0.260
[epoch: 8, i: 799] avg mini-batch loss: 0.379
[epoch: 8, i: 899] avg mini-batch loss: 0.337
[epoch: 8, i: 999] avg mini-batch loss: 0.258
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[epoch: 8, i: 1299] avg mini-batch loss: 0.281

[epoch: 8, i: 1399] avg mini-batch loss: 0.248
[epoch: 8, i: 1499] avg mini-batch loss: 0.314
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[epoch: 8, i: 1799] avg mini-batch loss: 0.290
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[epoch: 8, i: 1999] avg mini-batch loss: 0.246
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[epoch: 8, i: 5899] avg mini-batch loss: 0.337
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[epoch: 8, i: 6099] avg mini-batch loss: 0.357

[epoch: 8, i: 6199] avg mini-batch loss: 0.320
[epoch: 8, i: 6299] avg mini-batch loss: 0.363
[epoch: 8, i: 6399] avg mini-batch loss: 0.318
[epoch: 8, i: 6499] avg mini-batch loss: 0.304
[epoch: 8, i: 6599] avg mini-batch loss: 0.302
[epoch: 8, i: 6699] avg mini-batch loss: 0.362
[epoch: 8, i: 6799] avg mini-batch loss: 0.322
[epoch: 8, i: 6899] avg mini-batch loss: 0.335
[epoch: 8, i: 6999] avg mini-batch loss: 0.333
[epoch: 8, i: 7099] avg mini-batch loss: 0.324
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[epoch: 8, i: 7799] avg mini-batch loss: 0.390
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[epoch: 8, i: 8599] avg mini-batch loss: 0.325
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[epoch: 8, i: 10899] avg mini-batch loss: 0.264

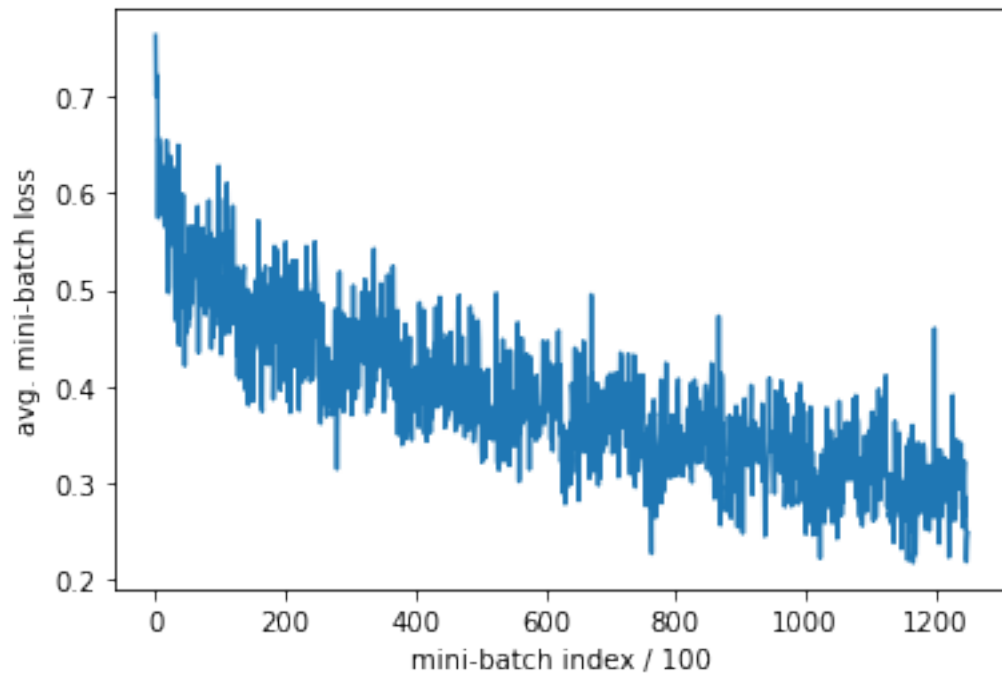
[epoch: 8, i: 10999] avg mini-batch loss: 0.309
[epoch: 8, i: 11099] avg mini-batch loss: 0.294
[epoch: 8, i: 11199] avg mini-batch loss: 0.307
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[epoch: 9, i: 299] avg mini-batch loss: 0.303
[epoch: 9, i: 399] avg mini-batch loss: 0.264
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[epoch: 9, i: 699] avg mini-batch loss: 0.285
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[epoch: 9, i: 999] avg mini-batch loss: 0.309
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[epoch: 9, i: 10399] avg mini-batch loss: 0.274
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[epoch: 9, i: 10599] avg mini-batch loss: 0.295
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[epoch: 9, i: 10899] avg mini-batch loss: 0.319
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[epoch: 9, i: 11999] avg mini-batch loss: 0.322
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[epoch: 9, i: 12199] avg mini-batch loss: 0.285
[epoch: 9, i: 12299] avg mini-batch loss: 0.218
[epoch: 9, i: 12399] avg mini-batch loss: 0.241
[epoch: 9, i: 12499] avg mini-batch loss: 0.248
Finished Training.

Training Loss Curve

```
[17]: plt.plot(avg_losses)
plt.xlabel('mini-batch index / {}'.format(print_freq))
plt.ylabel('avg. mini-batch loss')
plt.show()
```



Evaluate on Test Dataset

```
[18]: # Check several images.
dataiter = iter(testloader)
images, labels = next(dataiter)
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))
outputs = net(images.to(device))
_, predicted = torch.max(outputs, 1)

print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                               for j in range(4)))
```



GroundTruth: cat ship ship plane
 Predicted: dog ship ship plane

```
[19]: # Get test accuracy.
correct = 0
total = 0
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to(device), labels.to(device)
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()

print('Accuracy of the network on the 10000 test images: %d %%' % (
    100 * correct / total))
```

Accuracy of the network on the 10000 test images: 70 %

```
[20]: # Get test accuracy for each class.
class_correct = list(0. for i in range(10))
class_total = list(0. for i in range(10))
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to(device), labels.to(device)
        outputs = net(images)
        _, predicted = torch.max(outputs, 1)
        c = (predicted == labels).squeeze()
        for i in range(4):
            label = labels[i]
            class_correct[label] += c[i].item()
            class_total[label] += 1
```



```

for i in range(10):
    print('Accuracy of %5s : %2d %%' % (
        classes[i], 100 * class_correct[i] / class_total[i]))

```

```

Accuracy of plane : 77 %
Accuracy of  car : 82 %
Accuracy of  bird : 57 %
Accuracy of  cat : 49 %
Accuracy of  deer : 64 %
Accuracy of  dog : 62 %
Accuracy of  frog : 79 %
Accuracy of horse : 75 %
Accuracy of  ship : 80 %
Accuracy of truck : 80 %

```

```

[ ]: # One of the changes I made was that I added another layer in the network
# that takes the output from the second convolutional layer, applies ReLU
    ↪ activation,
# and passes it through a 2x2 AvgPool layer to capture more relationships.
# I also reduced the learning rate of the optimizer to half (0.0005) which
# which allowed the optimizer to take smaller steps towards the minimum of
# the loss function which might allow for a better chance of finding the global
    ↪ min of loss.

```

hw4

March 3, 2023

```
[1]: %matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
import torch
import torchvision
import torchvision.transforms as transforms
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
```

Prepare for Dataset

```
[2]: transform = transforms.Compose(
    [transforms.ToTensor(),
     transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                          shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Downloading <https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz> to
./data/cifar-10-python.tar.gz

0%| | 0/170498071 [00:00<?, ?it/s]

Extracting ./data/cifar-10-python.tar.gz to ./data
Files already downloaded and verified

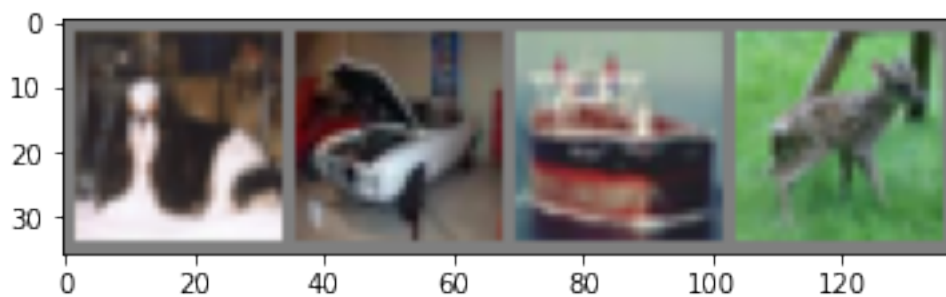
```
[3]: # The function to show an image.
def imshow(img):
```

```

img = img / 2 + 0.5      # Unnormalize.
npimg = img.numpy()
plt.imshow(np.transpose(npimg, (1, 2, 0)))
plt.show()

# Get some random training images.
dataiter = iter(trainloader)
images, labels = next(dataiter)
# Show images.
imshow(torchvision.utils.make_grid(images))
# Print labels.
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))

```



dog car ship deer

Choose a Device

```

[4]: # If there are GPUs, choose the first one for computing. Otherwise use CPU.
device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")
print(device)
# If 'cuda:0' is printed, it means GPU is available.

```

cpu

Network Definition

```

[5]: class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        ##### Fill the blank here #####
        self.conv1 = nn.Conv2d(3, 10, kernel_size=3, padding=1)

        self.relu1 = nn.ReLU()

        self.pool1 = nn.AvgPool2d(kernel_size=2, stride=2)

        self.conv2 = nn.Conv2d(10, 20, kernel_size=3, padding=1)

```

```

        self.relu2 = nn.ReLU()

        self.pool2 = nn.AvgPool2d(kernel_size=2, stride=2)

        self.fc1 = nn.Linear(20 * 8 * 8, 100)

        self.relu3 = nn.ReLU()

        self.fc2 = nn.Linear(100, 10)

    def forward(self, x):
        ##### Fill the blank here #####
        x = self.pool1(self.relu1(self.conv1(x)))

        x = self.pool2(self.relu2(self.conv2(x)))

        x = x.view(-1, 20 * 8 * 8)

        x = self.relu3(self.fc1(x))

        x = self.fc2(x)

        return x

net = Net()      # Create the network instance.
net.to(device)  # Move the network parameters to the specified device.

```

```

[5]: Net(
  (conv1): Conv2d(3, 10, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (relu1): ReLU()
  (pool1): AvgPool2d(kernel_size=2, stride=2, padding=0)
  (conv2): Conv2d(10, 20, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (relu2): ReLU()
  (pool2): AvgPool2d(kernel_size=2, stride=2, padding=0)
  (fc1): Linear(in_features=1280, out_features=100, bias=True)
  (relu3): ReLU()
  (fc2): Linear(in_features=100, out_features=10, bias=True)
)

```

Optimizer and Loss Function

```

[6]: # We use cross-entropy as loss function.
loss_func = nn.CrossEntropyLoss()

```

```
# We use stochastic gradient descent (SGD) as optimizer.
opt = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

Training Procedure

```
[7]: avg_losses = []    # Avg. losses.
     epochs = 10       # Total epochs.
     print_freq = 100  # Print frequency.

     for epoch in range(epochs): # Loop over the dataset multiple times.
         running_loss = 0.0      # Initialize running loss.
         for i, data in enumerate(trainloader, 0):
             # Get the inputs.
             inputs, labels = data

             # Move the inputs to the specified device.
             inputs, labels = inputs.to(device), labels.to(device)

             # Zero the parameter gradients.
             opt.zero_grad()

             # Forward step.
             outputs = net(inputs)
             loss = loss_func(outputs, labels)

             # Backward step.
             loss.backward()

             # Optimization step (update the parameters).
             opt.step()

             # Print statistics.
             running_loss += loss.item()
             if i % print_freq == print_freq - 1: # Print every several mini-batches.
                 avg_loss = running_loss / print_freq
                 print('[epoch: {}, i: {:5d}] avg mini-batch loss: {:.3f}'.format(
                     epoch, i, avg_loss))
                 avg_losses.append(avg_loss)
                 running_loss = 0.0

     print('Finished Training.')
```

```
[epoch: 0, i:    99] avg mini-batch loss: 2.298
[epoch: 0, i:   199] avg mini-batch loss: 2.304
[epoch: 0, i:   299] avg mini-batch loss: 2.301
[epoch: 0, i:   399] avg mini-batch loss: 2.295
[epoch: 0, i:   499] avg mini-batch loss: 2.289
[epoch: 0, i:   599] avg mini-batch loss: 2.278
```

[epoch: 0, i: 699] avg mini-batch loss: 2.263
[epoch: 0, i: 799] avg mini-batch loss: 2.228
[epoch: 0, i: 899] avg mini-batch loss: 2.161
[epoch: 0, i: 999] avg mini-batch loss: 2.119
[epoch: 0, i: 1099] avg mini-batch loss: 2.070
[epoch: 0, i: 1199] avg mini-batch loss: 2.027
[epoch: 0, i: 1299] avg mini-batch loss: 2.004
[epoch: 0, i: 1399] avg mini-batch loss: 2.072
[epoch: 0, i: 1499] avg mini-batch loss: 2.025
[epoch: 0, i: 1599] avg mini-batch loss: 1.985
[epoch: 0, i: 1699] avg mini-batch loss: 1.937
[epoch: 0, i: 1799] avg mini-batch loss: 1.979
[epoch: 0, i: 1899] avg mini-batch loss: 1.878
[epoch: 0, i: 1999] avg mini-batch loss: 1.843
[epoch: 0, i: 2099] avg mini-batch loss: 1.884
[epoch: 0, i: 2199] avg mini-batch loss: 1.903
[epoch: 0, i: 2299] avg mini-batch loss: 1.871
[epoch: 0, i: 2399] avg mini-batch loss: 1.790
[epoch: 0, i: 2499] avg mini-batch loss: 1.906
[epoch: 0, i: 2599] avg mini-batch loss: 1.847
[epoch: 0, i: 2699] avg mini-batch loss: 1.795
[epoch: 0, i: 2799] avg mini-batch loss: 1.755
[epoch: 0, i: 2899] avg mini-batch loss: 1.823
[epoch: 0, i: 2999] avg mini-batch loss: 1.799
[epoch: 0, i: 3099] avg mini-batch loss: 1.786
[epoch: 0, i: 3199] avg mini-batch loss: 1.812
[epoch: 0, i: 3299] avg mini-batch loss: 1.775
[epoch: 0, i: 3399] avg mini-batch loss: 1.742
[epoch: 0, i: 3499] avg mini-batch loss: 1.831
[epoch: 0, i: 3599] avg mini-batch loss: 1.781
[epoch: 0, i: 3699] avg mini-batch loss: 1.752
[epoch: 0, i: 3799] avg mini-batch loss: 1.743
[epoch: 0, i: 3899] avg mini-batch loss: 1.663
[epoch: 0, i: 3999] avg mini-batch loss: 1.764
[epoch: 0, i: 4099] avg mini-batch loss: 1.669
[epoch: 0, i: 4199] avg mini-batch loss: 1.682
[epoch: 0, i: 4299] avg mini-batch loss: 1.604
[epoch: 0, i: 4399] avg mini-batch loss: 1.641
[epoch: 0, i: 4499] avg mini-batch loss: 1.621
[epoch: 0, i: 4599] avg mini-batch loss: 1.620
[epoch: 0, i: 4699] avg mini-batch loss: 1.671
[epoch: 0, i: 4799] avg mini-batch loss: 1.639
[epoch: 0, i: 4899] avg mini-batch loss: 1.648
[epoch: 0, i: 4999] avg mini-batch loss: 1.630
[epoch: 0, i: 5099] avg mini-batch loss: 1.693
[epoch: 0, i: 5199] avg mini-batch loss: 1.582
[epoch: 0, i: 5299] avg mini-batch loss: 1.614
[epoch: 0, i: 5399] avg mini-batch loss: 1.594

[epoch: 0, i: 5499] avg mini-batch loss: 1.545
[epoch: 0, i: 5599] avg mini-batch loss: 1.573
[epoch: 0, i: 5699] avg mini-batch loss: 1.575
[epoch: 0, i: 5799] avg mini-batch loss: 1.598
[epoch: 0, i: 5899] avg mini-batch loss: 1.567
[epoch: 0, i: 5999] avg mini-batch loss: 1.603
[epoch: 0, i: 6099] avg mini-batch loss: 1.563
[epoch: 0, i: 6199] avg mini-batch loss: 1.535
[epoch: 0, i: 6299] avg mini-batch loss: 1.552
[epoch: 0, i: 6399] avg mini-batch loss: 1.560
[epoch: 0, i: 6499] avg mini-batch loss: 1.596
[epoch: 0, i: 6599] avg mini-batch loss: 1.589
[epoch: 0, i: 6699] avg mini-batch loss: 1.486
[epoch: 0, i: 6799] avg mini-batch loss: 1.575
[epoch: 0, i: 6899] avg mini-batch loss: 1.591
[epoch: 0, i: 6999] avg mini-batch loss: 1.580
[epoch: 0, i: 7099] avg mini-batch loss: 1.531
[epoch: 0, i: 7199] avg mini-batch loss: 1.488
[epoch: 0, i: 7299] avg mini-batch loss: 1.582
[epoch: 0, i: 7399] avg mini-batch loss: 1.482
[epoch: 0, i: 7499] avg mini-batch loss: 1.482
[epoch: 0, i: 7599] avg mini-batch loss: 1.468
[epoch: 0, i: 7699] avg mini-batch loss: 1.541
[epoch: 0, i: 7799] avg mini-batch loss: 1.566
[epoch: 0, i: 7899] avg mini-batch loss: 1.532
[epoch: 0, i: 7999] avg mini-batch loss: 1.427
[epoch: 0, i: 8099] avg mini-batch loss: 1.538
[epoch: 0, i: 8199] avg mini-batch loss: 1.465
[epoch: 0, i: 8299] avg mini-batch loss: 1.486
[epoch: 0, i: 8399] avg mini-batch loss: 1.530
[epoch: 0, i: 8499] avg mini-batch loss: 1.476
[epoch: 0, i: 8599] avg mini-batch loss: 1.495
[epoch: 0, i: 8699] avg mini-batch loss: 1.453
[epoch: 0, i: 8799] avg mini-batch loss: 1.506
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[epoch: 0, i: 9599] avg mini-batch loss: 1.437
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[epoch: 1, i: 3799] avg mini-batch loss: 1.261
[epoch: 1, i: 3899] avg mini-batch loss: 1.254
[epoch: 1, i: 3999] avg mini-batch loss: 1.249
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[epoch: 1, i: 4699] avg mini-batch loss: 1.236
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[epoch: 1, i: 5299] avg mini-batch loss: 1.236
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[epoch: 1, i: 6299] avg mini-batch loss: 1.284
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[epoch: 1, i: 6899] avg mini-batch loss: 1.368
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[epoch: 1, i: 7799] avg mini-batch loss: 1.245
[epoch: 1, i: 7899] avg mini-batch loss: 1.215
[epoch: 1, i: 7999] avg mini-batch loss: 1.193
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[epoch: 1, i: 8199] avg mini-batch loss: 1.123
[epoch: 1, i: 8299] avg mini-batch loss: 1.159
[epoch: 1, i: 8399] avg mini-batch loss: 1.173
[epoch: 1, i: 8499] avg mini-batch loss: 1.321
[epoch: 1, i: 8599] avg mini-batch loss: 1.256
[epoch: 1, i: 8699] avg mini-batch loss: 1.201
[epoch: 1, i: 8799] avg mini-batch loss: 1.285
[epoch: 1, i: 8899] avg mini-batch loss: 1.230
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[epoch: 1, i: 9199] avg mini-batch loss: 1.121
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[epoch: 1, i: 9399] avg mini-batch loss: 1.226
[epoch: 1, i: 9499] avg mini-batch loss: 1.156
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[epoch: 1, i: 9699] avg mini-batch loss: 1.373
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[epoch: 1, i: 9899] avg mini-batch loss: 1.300
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[epoch: 1, i: 10299] avg mini-batch loss: 1.188
[epoch: 1, i: 10399] avg mini-batch loss: 1.281
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[epoch: 1, i: 10599] avg mini-batch loss: 1.226
[epoch: 1, i: 10699] avg mini-batch loss: 1.199
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[epoch: 1, i: 10899] avg mini-batch loss: 1.230
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[epoch: 1, i: 11599] avg mini-batch loss: 1.242
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[epoch: 1, i: 11799] avg mini-batch loss: 1.088
[epoch: 1, i: 11899] avg mini-batch loss: 1.285
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[epoch: 1, i: 12499] avg mini-batch loss: 1.205
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[epoch: 2, i: 299] avg mini-batch loss: 1.100
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[epoch: 2, i: 499] avg mini-batch loss: 1.115
[epoch: 2, i: 599] avg mini-batch loss: 1.116
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[epoch: 2, i: 999] avg mini-batch loss: 1.134
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[epoch: 2, i: 1999] avg mini-batch loss: 1.095
[epoch: 2, i: 2099] avg mini-batch loss: 1.121
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[epoch: 2, i: 2299] avg mini-batch loss: 1.072
[epoch: 2, i: 2399] avg mini-batch loss: 1.060
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[epoch: 2, i: 3299] avg mini-batch loss: 1.112
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[epoch: 2, i: 3499] avg mini-batch loss: 1.104
[epoch: 2, i: 3599] avg mini-batch loss: 1.012
[epoch: 2, i: 3699] avg mini-batch loss: 1.125
[epoch: 2, i: 3799] avg mini-batch loss: 1.098
[epoch: 2, i: 3899] avg mini-batch loss: 1.133
[epoch: 2, i: 3999] avg mini-batch loss: 1.153
[epoch: 2, i: 4099] avg mini-batch loss: 1.132
[epoch: 2, i: 4199] avg mini-batch loss: 1.091
[epoch: 2, i: 4299] avg mini-batch loss: 1.038
[epoch: 2, i: 4399] avg mini-batch loss: 1.112

[epoch: 2, i: 4499] avg mini-batch loss: 1.100
[epoch: 2, i: 4599] avg mini-batch loss: 1.122
[epoch: 2, i: 4699] avg mini-batch loss: 0.987
[epoch: 2, i: 4799] avg mini-batch loss: 1.152
[epoch: 2, i: 4899] avg mini-batch loss: 1.176
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[epoch: 2, i: 5199] avg mini-batch loss: 1.115
[epoch: 2, i: 5299] avg mini-batch loss: 1.134
[epoch: 2, i: 5399] avg mini-batch loss: 1.139
[epoch: 2, i: 5499] avg mini-batch loss: 1.060
[epoch: 2, i: 5599] avg mini-batch loss: 1.134
[epoch: 2, i: 5699] avg mini-batch loss: 1.220
[epoch: 2, i: 5799] avg mini-batch loss: 1.059
[epoch: 2, i: 5899] avg mini-batch loss: 1.094
[epoch: 2, i: 5999] avg mini-batch loss: 1.109
[epoch: 2, i: 6099] avg mini-batch loss: 1.018
[epoch: 2, i: 6199] avg mini-batch loss: 1.096
[epoch: 2, i: 6299] avg mini-batch loss: 1.135
[epoch: 2, i: 6399] avg mini-batch loss: 1.071
[epoch: 2, i: 6499] avg mini-batch loss: 1.048
[epoch: 2, i: 6599] avg mini-batch loss: 1.111
[epoch: 2, i: 6699] avg mini-batch loss: 1.113
[epoch: 2, i: 6799] avg mini-batch loss: 1.049
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[epoch: 8, i: 3099] avg mini-batch loss: 0.587
[epoch: 8, i: 3199] avg mini-batch loss: 0.569
[epoch: 8, i: 3299] avg mini-batch loss: 0.679
[epoch: 8, i: 3399] avg mini-batch loss: 0.649
[epoch: 8, i: 3499] avg mini-batch loss: 0.616
[epoch: 8, i: 3599] avg mini-batch loss: 0.598
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[epoch: 8, i: 3799] avg mini-batch loss: 0.524
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[epoch: 8, i: 4199] avg mini-batch loss: 0.675
[epoch: 8, i: 4299] avg mini-batch loss: 0.652
[epoch: 8, i: 4399] avg mini-batch loss: 0.625
[epoch: 8, i: 4499] avg mini-batch loss: 0.636
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[epoch: 8, i: 5199] avg mini-batch loss: 0.545
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[epoch: 8, i: 5399] avg mini-batch loss: 0.650
[epoch: 8, i: 5499] avg mini-batch loss: 0.558
[epoch: 8, i: 5599] avg mini-batch loss: 0.606
[epoch: 8, i: 5699] avg mini-batch loss: 0.625
[epoch: 8, i: 5799] avg mini-batch loss: 0.657
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[epoch: 8, i: 6299] avg mini-batch loss: 0.646

[epoch: 8, i: 6399] avg mini-batch loss: 0.695
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[epoch: 8, i: 6599] avg mini-batch loss: 0.698
[epoch: 8, i: 6699] avg mini-batch loss: 0.604
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[epoch: 8, i: 9599] avg mini-batch loss: 0.726
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[epoch: 8, i: 11099] avg mini-batch loss: 0.632

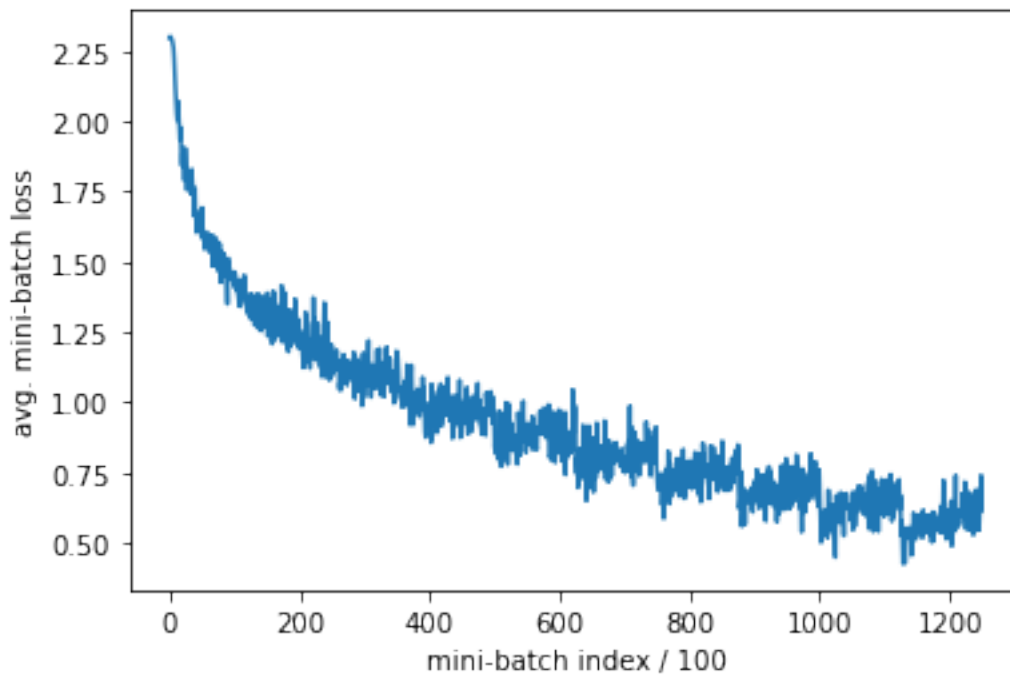
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[epoch: 8, i: 11399] avg mini-batch loss: 0.658
[epoch: 8, i: 11499] avg mini-batch loss: 0.593
[epoch: 8, i: 11599] avg mini-batch loss: 0.616
[epoch: 8, i: 11699] avg mini-batch loss: 0.650
[epoch: 8, i: 11799] avg mini-batch loss: 0.685
[epoch: 8, i: 11899] avg mini-batch loss: 0.639
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[epoch: 9, i: 699] avg mini-batch loss: 0.427
[epoch: 9, i: 799] avg mini-batch loss: 0.484
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[epoch: 9, i: 4399] avg mini-batch loss: 0.550
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[epoch: 9, i: 6399] avg mini-batch loss: 0.603
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[epoch: 9, i: 6899] avg mini-batch loss: 0.531
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[epoch: 9, i: 11999] avg mini-batch loss: 0.634
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[epoch: 9, i: 12299] avg mini-batch loss: 0.668
[epoch: 9, i: 12399] avg mini-batch loss: 0.739
[epoch: 9, i: 12499] avg mini-batch loss: 0.614
Finished Training.

Training Loss Curve

```
[8]: plt.plot(avg_losses)
plt.xlabel('mini-batch index / {}'.format(print_freq))
plt.ylabel('avg. mini-batch loss')
plt.show()
```



Evaluate on Test Dataset

```
[9]: # Check several images.
dataiter = iter(testloader)
images, labels = next(dataiter)
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))
outputs = net(images.to(device))
_, predicted = torch.max(outputs, 1)

print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                                for j in range(4)))
```




GroundTruth: cat ship ship plane
 Predicted: cat ship ship plane

```
[10]: # Get test accuracy.
correct = 0
total = 0
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to(device), labels.to(device)
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()

print('Accuracy of the network on the 10000 test images: %d %%' % (
    100 * correct / total))
```

Accuracy of the network on the 10000 test images: 67 %

```
[11]: # Get test accuracy for each class.
class_correct = list(0. for i in range(10))
class_total = list(0. for i in range(10))
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to(device), labels.to(device)
        outputs = net(images)
        _, predicted = torch.max(outputs, 1)
        c = (predicted == labels).squeeze()
        for i in range(4):
            label = labels[i]
            class_correct[label] += c[i].item()
            class_total[label] += 1
```

```
for i in range(10):  
    print('Accuracy of %5s : %2d %%' % (  
        classes[i], 100 * class_correct[i] / class_total[i]))
```

```
Accuracy of plane : 71 %  
Accuracy of   car : 80 %  
Accuracy of  bird : 55 %  
Accuracy of   cat : 49 %  
Accuracy of  deer : 63 %  
Accuracy of   dog : 60 %  
Accuracy of  frog : 68 %  
Accuracy of horse : 73 %  
Accuracy of  ship : 75 %  
Accuracy of truck : 72 %
```