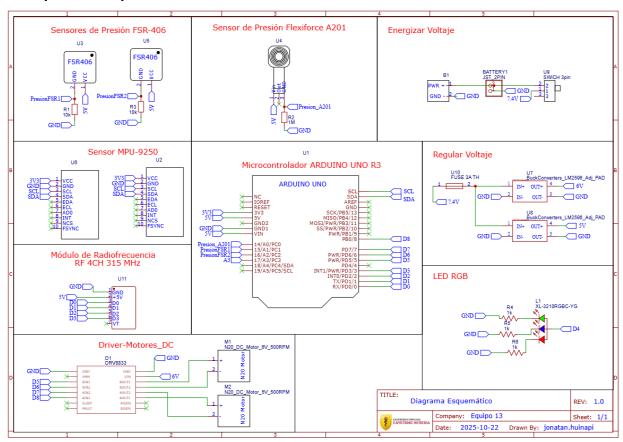
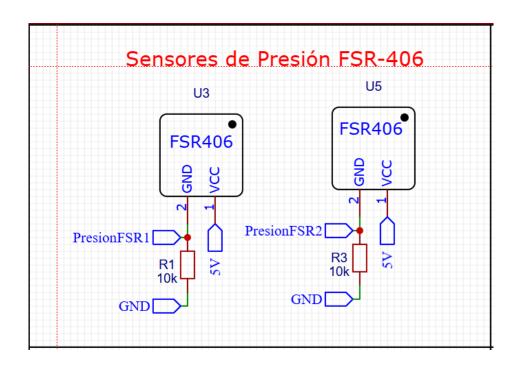
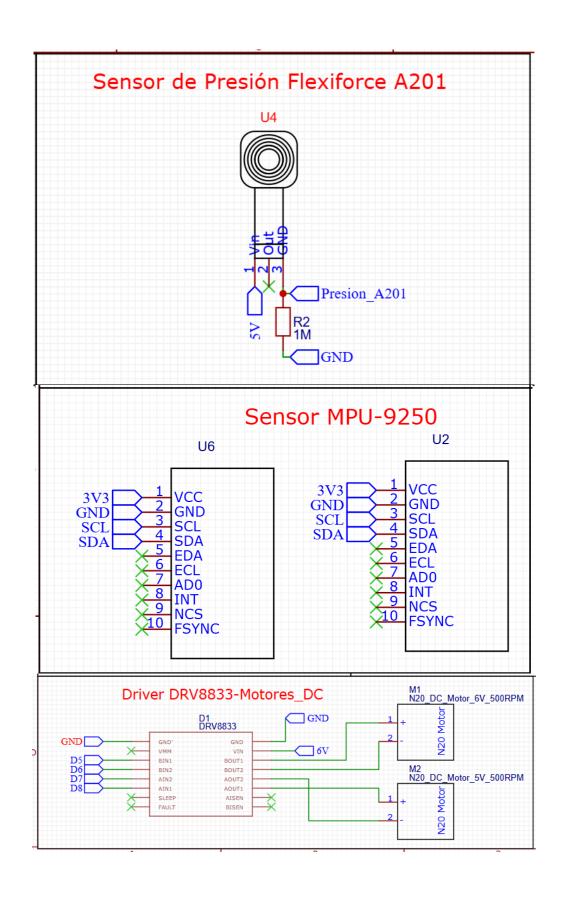
Entregable N°8 Diseño esquemático del prototipo

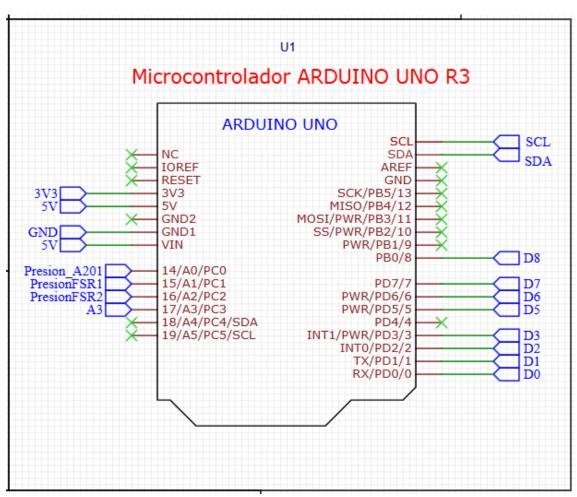
1. Esquema completo

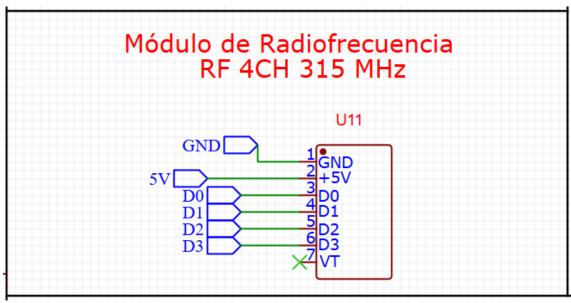


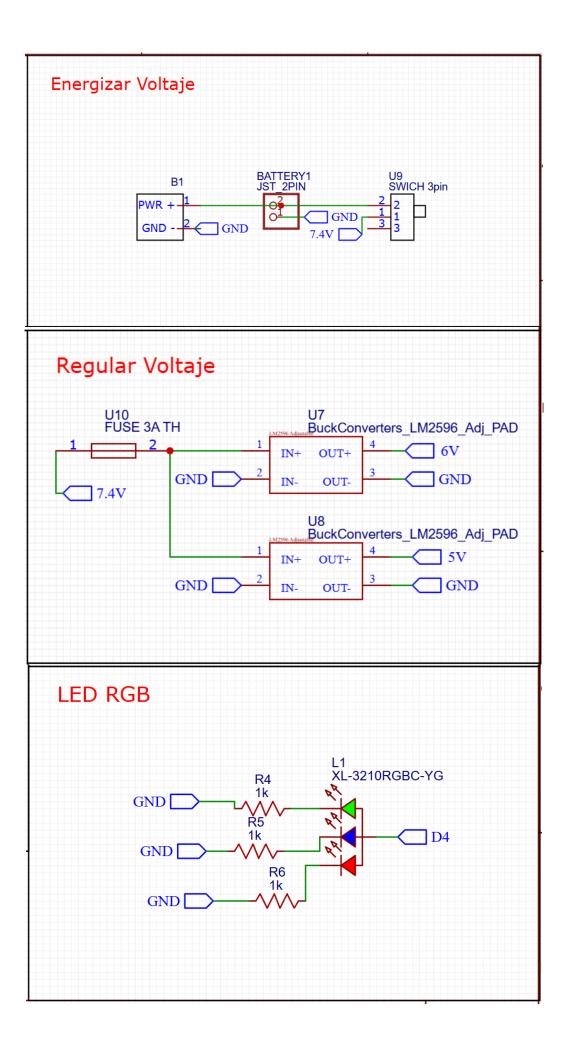
2. Módulos











Modelado 3D de los elementos que conforman su prototipo

Solución completa:

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Componentes:



Arduino uno R3:

https://cad.onshape.com/documents/358e6ee0a7e545cdc13880cc/w/fb00525c6271bd48ed0 090b1



LM 2596:

https://cad.onshape.com/documents/ed9dc76d7d66df3d99825e75/w/e64b5db6f0701456e918e3b2/e/382bef30aee71854fb0a7432



MPU 9250:

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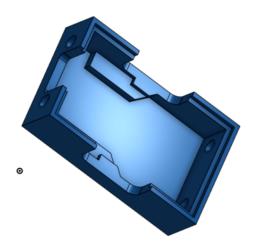
Soporte largo:



Ortesis para ambas piernas:

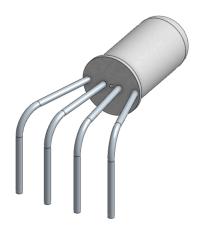
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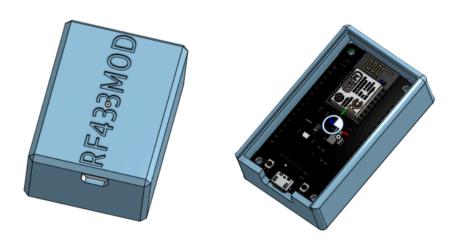
Caja del MPU:

https://cad.onshape.com/documents/ef8435970f178548cabc3745/w/b9355684763af5511d955672/e/771fca0d5232c701341a13ee



Led RGB:

https://cad.onshape.com/documents/a5c90845087c0a5c139f5598/w/abf9460c9576fdc047855b66/e/84628a0daedb5bab544195eb



Módulo de radiofrecuencia RF 433:

https://cad.onshape.com/documents/46bb01dfa372f61e05a1ae57/w/6816e948a11d4f39ffd87c3d/e/570a766bd7e573b261936c9a

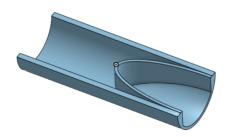
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Parte del bastón canadiense:



Baston candiense:

https://cad.onshape.com/documents/13cb7400194ab0a934fd1462/w/0d99d2ad3d134e4b89628924/e/30bec052ad2776449d337491



Soporte de boton:

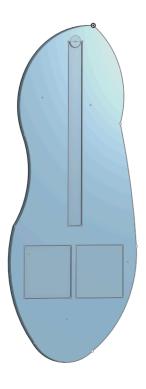
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Bateria Lipo:

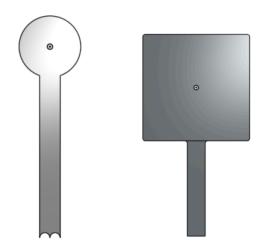
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Partes de la plantilla:



Plantilla:

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Sensores de fuerza:

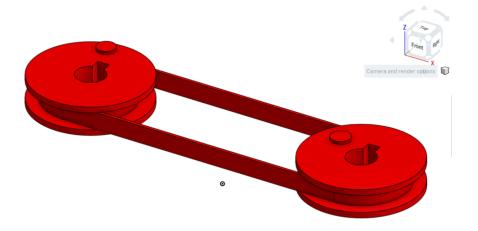
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Partes del sistema de trabe y destrabe:



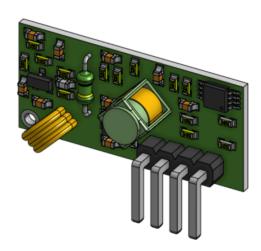
Micromotor N20:

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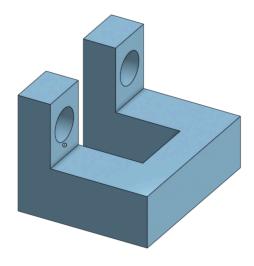
Poleas:

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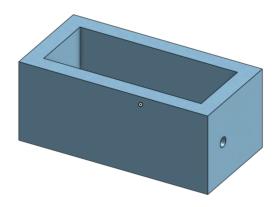
01COM RX RF433 Receiver:

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Gancho para poleas:

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Pieza para trabar:

https://cad.onshape.com/documents/76d2d7c239bdc8f8fa00e4ad/w/cebd49e91c2a0bf198104d18/e/7dd4c7551fcfe9fa7b047bc8?renderMode=0&uiState=68fb032078a1d30a472af800