JACKSON ISENBERG

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EDUCATION

Georgia Institute of Technology

Atlanta, GA

Master of Science in Robotics

August 2024 – Present

• GPA: 4.0/4.0

Bachelor of Science in Computer Science, Minor in Robotics

June 2020 - May 2024

- · Graduated with Highest Honors
- · Concentrations: Systems & Architecture, Computer Intelligence
- · Coursework: Control Theory, Deep Learning, Compilers, Processor Design, Operating Systems, Signal Processing

EXPERIENCE

Low-power, Adaptive, and Resilient Systems Lab

Atlanta, GA

Undergraduate Research Assistant

August 2022 – May 2024

- · Trained and tested DNN-based RL model on the AWS DeepRacer stack for autonomous vehicle pathing with camera input
- $\cdot \ \, {\rm Created} \ \, {\rm an \ \, architecture\hbox{-}agnostic \ \, fault \ \, injection \ \, and \ \, resilience \ \, framework \ \, in \ \, TensorFlow \ \, for \ \, any \ \, black\hbox{-}box \ \, neural \ \, network \ \, and \ \, resilience \ \, framework \ \, in \ \, TensorFlow \ \, for \ \, any \ \, black\hbox{-}box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black\hbox{-}box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black\hbox{-}box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black\hbox{-}box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black\hbox{-}box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black\hbox{-}box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black \ \, and \ \, black \ \, black \ \, and \ \, black \ \, and \ \, black \ \, black \ \, and \ \, black \ \, black \ \, and \ \, black \ \, bl$

Georgia Tech Research Institute

Atlanta, GA

Student Research Assistant (TMPO Lab, CIPHER)

May 2021 – May 2024

- \cdot Designed and implemented the first real-time operating system in Rust for the Cortex R4 where nearly 100% of Rust's safety features at abstraction levels above the bootloader were utilized to improve upon the critical safety of the system
- · Worked on various FPGA projects related to architecture analysis and bitstream generation (secret clearance)

Research Intern (ATAS)

June - July 2020

- · Worked and modeled a 5 degree-of-freedom Arduino-powered arm and developed a C++ library for the arm's inverse kinematics
- · Researched various OpenCV-extendable libraries such as AprilTags for detecting visual orientation of the end effector

Research Intern (ATAS)

June - July 2019

- Improved the design of the battery compartments in the Kennedy Space Center piezoelectric tiles to prevent expansion over time due to trapped heat
- · Was the sole researcher of UV-C LED liquid waste treatment for the Gates Foundation Reinvented Toilet

PROJECTS

Neuraphonic (HackGT X) — Python, PyTorch, Scikit-Learn, Google Cloud, Twilio, MATLAB

- Developed a diagnostic assistant for Parkinson's disease utilizing a vision transformer and signal processing techniques to extract various features from audio samples uploaded to a website hosted on Google Cloud or through telephone
- Won 2nd place best overall project out of 189 total teams with a cash prize of \$3k and was accepted for the Create-X Startup Launch with initial funding of \$35k

National Characteristics Search (Capstone Project) — Python, SQLite

- Produced a stand-alone application in Python that accesses characteristic data (such as total population, median income, etc.) from the U.S. Census in a way that enables quick and easy access and saves that data to a local database using SQLite
- · Created in partnership with the Emory University School of Medicine for research into the correlation between neighborhood characteristics and the development of schizophrenia

FTCLib — Java, Kotlin, OpenCV

• Founded and led the development of a Java library for FIRST Tech Challenge used by hundreds of teams internationally to enhance their software efficiency and experience

EXTRACURRICULAR

HyTech Racing

Data Acquisition

- · Designed schematics and fabricated PCBs to retrieve sensor data
- Programmed and tested Arduino/Teensy microcontrollers over a CAN line for messages containing sensor data to be parsed into a useful, readable format for debugging and testing

RoboJackets

IT Coordinator

- · Managed all networks and distributed services maintained by the organization and provided to over 600 members
- · Provided assistance to any members experiencing issues with their provided services, connections, or loaned devices

SKILLS

Languages Java, Python, C/C++, Rust, Verilog, VHDL, HTML, JavaScript, MATLAB

Frameworks NumPy, PyTorch, TensorFlow, JavaFX, React Software Git, AWS, Docker, ROS/ROS2, Virtual Machines