# JACKSON ISENBERG

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# **EDUCATION**

# Georgia Institute of Technology

Atlanta, GA

M.S. Robotics

- Concentrations: Controls, Artificial Intelligence, Perception

June 2020 – May 2024

August 2024 – Present

- $B.S.\ Computer\ Science,\ Minor\ in\ Robotics$ 
  - Graduated with Highest Honors
  - · Concentrations: Systems & Architecture, Computer Intelligence
  - · Coursework: Linear Controls, Deep Learning, Embedded Systems, Computer Vision, Operating Systems, Signal Processing

#### EXPERIENCE

#### Low-power, Adaptive, and Resilient Systems Lab, Georgia Tech

Atlanta, GA

Undergraduate Research Assistant

 $August\ 2022-May\ 2024$ 

- $\bullet \ \, \text{Trained and tested a deep RL model on the AWS Deep Racer stack for autonomous vehicle pathing with camera input}$
- $\cdot \ \, {\rm Created} \ \, {\rm an \ \, architecture\text{-}agnostic \ \, fault \ \, injection \ \, and \ \, resilience \ \, framework in \ \, TensorFlow \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, resilience \ \, framework \ \, in \ \, TensorFlow \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, resilience \ \, framework \ \, in \ \, TensorFlow \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, resilience \ \, framework \ \, in \ \, TensorFlow \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, resilience \ \, framework \ \, in \ \, TensorFlow \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, resilience \ \, framework \ \, in \ \, TensorFlow \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, for \ \, any \ \, black-box \ \, neural \ \, network \ \, and \ \, how \ \,$

## Georgia Tech Research Institute

Atlanta, GA

Student Research Assistant (TMPO Lab, CIPHER)

May 2021 – May 2024

- Designed and implemented the first real-time operating system in Rust for the ARM Cortex R4 where nearly 100% of Rust's safety features at abstraction levels above the bootloader were utilized to improve upon the critical safety of the system
- · Worked on various FPGA projects related to architecture analysis and bitstream generation (secret clearance)

Research Intern (ATAS)

June – July 2020

- Created a C++ forward and inverse kinematics library for an Arduino-powered robotic arm with 5 degrees of freedom to be used as a teaching tool for introducing younger children to robotics
- $\cdot$  Utilized AprilTags for the robot to detect objects in its vicinity that it could scan with a camera attached to its end effector Research Intern (ATAS)

  June July 2019
  - Improved the design of the battery compartments in the Kennedy Space Center piezoelectric tiles to prevent expansion over time by replacing the neoprene casing with a material that does not absorb and retain heat
  - Developed and presented a liquid waste treament method for the Gates Foundation Reinvented Toilet involving a multi-stage filter and UV-C LED disinfectant system that would have a 99.9% success rate at producing safe drinking water

### PROJECTS

Neuraphonic (HackGT X) — Python, PyTorch, Scikit-Learn, Google Cloud, Twilio, MATLAB, Flask

- · Won 2nd best overall prize (\$3k) out of 189 teams and accepted for the Create-X Startup Launch with \$35k initial funding
- · Voice-based diagnostic assistant for Parkinson's disease using signal processing and a vision transformer pipeline
- · Implemented the website page using Flask and the signal-to-feature conversion with Praat for the neural network input

#### National Characteristics Search (Capstone Project) — Python, SQLite

- Produced a stand-alone application in Python that accesses characteristic data (such as total population, median income, etc.) from the U.S. Census in a way that enables quick and easy access and saves that data to a local database using SQLite
- · Created in partnership with Emory Medicine to find the correlation between neighborhood characteristics and schizoprehnia

# FTCLib — Java, Kotlin, OpenCV

• Founded and led the development of a Java library for FIRST Tech Challenge with pre-built CV pipelines, hardware wrappers, and path following to raise the floor of software for thousands of competing teams' robots across the world

#### **EXTRACURRICULAR**

### **HyTech Racing**

Data Acquisition

- · Designed schematics and fabricated PCBs to retrieve sensor data measuring vehicle motion and power efficiency
- Programmed and tested Arduino/Teensy microcontrollers over a CAN line for messages containing sensor data to be parsed into a useful, readable feedback for the chassis and power systems teams to improve their designs and prevent future failures

#### RoboJackets

IT Coordinator

- · Managed all networks and distributed services maintained by the organization and provided to over 600 members
- · Provided assistance to any members experiencing issues with their provided services, connections, or loaned devices

#### **SKILLS**

Languages Java, Python, C/C++, Rust, Verilog, VHDL, HTML, JavaScript, MATLAB

Frameworks NumPy, PyTorch, TensorFlow, JavaFX, React

Software Git, AWS, Docker, ROS/ROS2, Virtual Machines, Linux