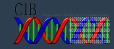
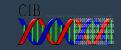


Unit 3: Data Mining Classification: Basic Concepts, Decision Trees, and Model Evaluation



Section 1: Basic Classification



Classification: Definition

- GIVEN A COLLECTION OF RECORDS (TRAINING SET)
 - Each record contains a set of attributes, one of the attributes is the class.
- FIND A MODEL FOR CLASS ATTRIBUTE AS A FUNCTION OF THE VALUES OF OTHER ATTRIBUTES.
- GOAL: <u>PREVIOUSLY UNSEEN</u> RECORDS SHOULD BE ASSIGNED A CLASS AS ACCURATELY AS POSSIBLE.
 - A test set is used to determine the accuracy of the model.
 Usually, the given data set is divided into training and test sets, with training set used to build the model and test set used to validate it.



Illustrating Classification Task

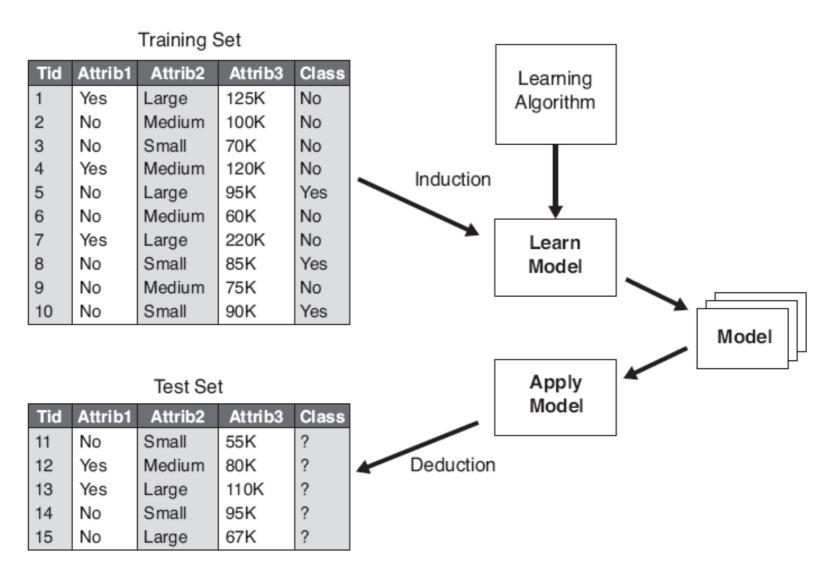
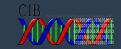


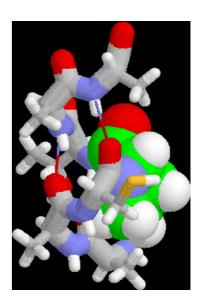
Figure 4.3. General approach for building a classification model.

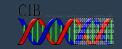


Examples of Classification Task

- PREDICTING TUMOR CELLS AS BENIGN OR MALIGNANT
- CLASSIFYING CREDIT CARD TRANSACTIONS
 AS LEGITIMATE OR FRAUDULENT
- CLASSIFYING SECONDARY STRUCTURES OF PROTEIN AS ALPHA-HELIX, BETA-SHEET, OR RANDOM COIL
- CATEGORIZING NEWS STORIES AS FINANCE, WEATHER, ENTERTAINMENT, SPORTS, ETC







Classification Techniques

- Decision Tree based Methods
- Rule-based Methods
- MEMORY BASED REASONING
- NEURAL NETWORKS
- Naïve Bayes and Bayesian Belief Networks
- Support Vector Machines
- More...

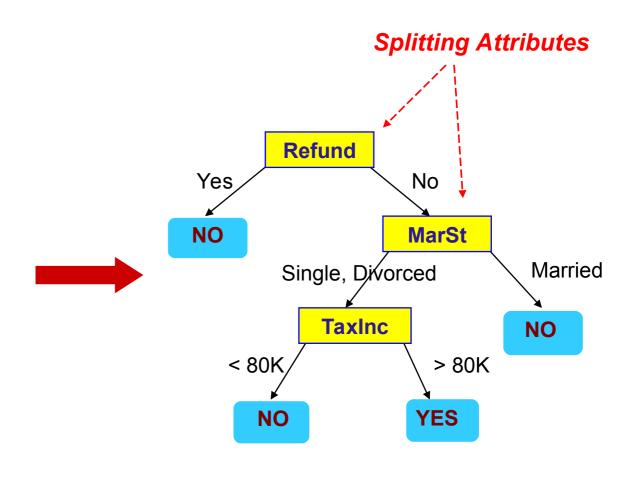


Example of a Decision Tree

categorical continuous

Tid	Refund	Marital Status	Taxable Income	Cheat
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes

Training Data



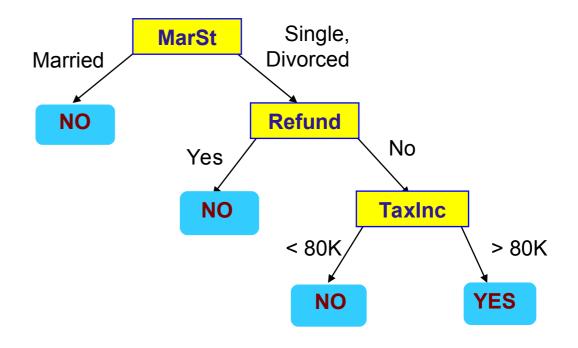
Model: Decision Tree



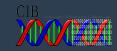
Another Example of Decision Tree

categorical continuous

Tid	Refund	Marital Status	Taxable Income	Cheat
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes



There could be more than one tree that fits the same data!



Decision Tree Classification Task

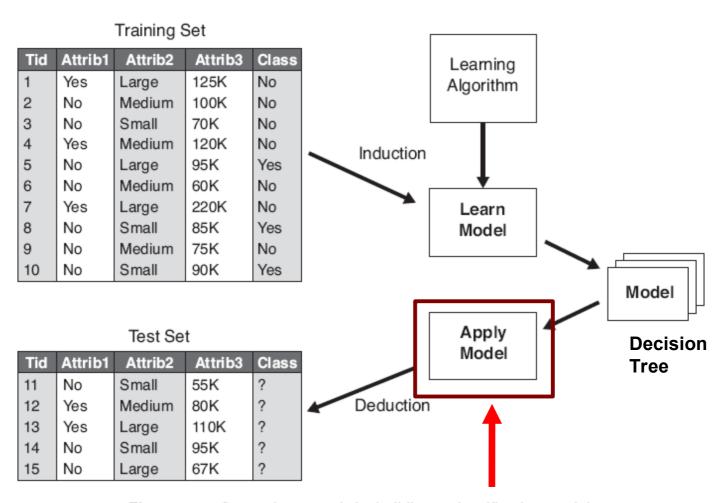
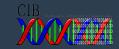
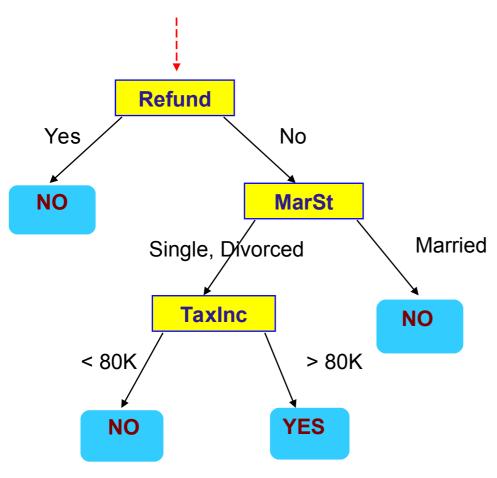


Figure 4.3. General approach for building a classification model.

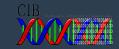


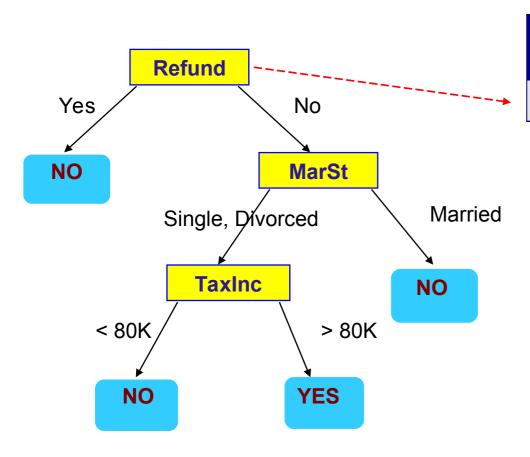
Start from the root of tree.



Test Data

Refund		Taxable Income	Cheat
No	Married	80K	?

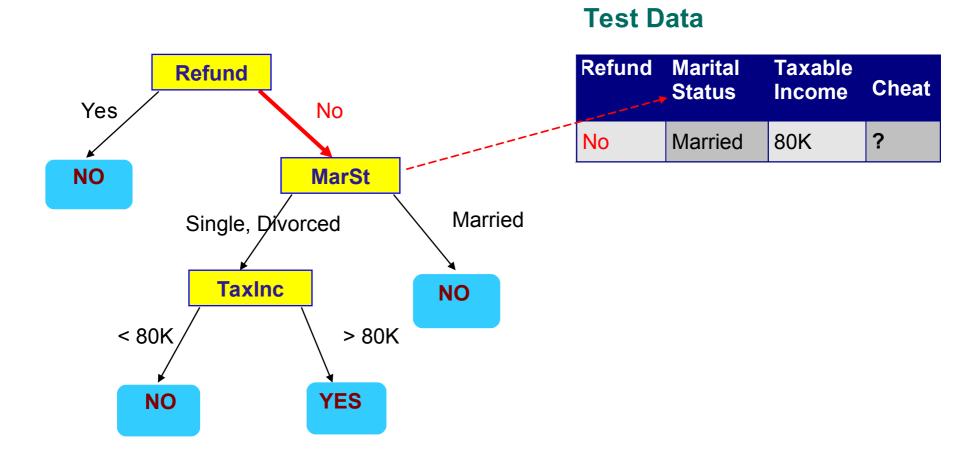




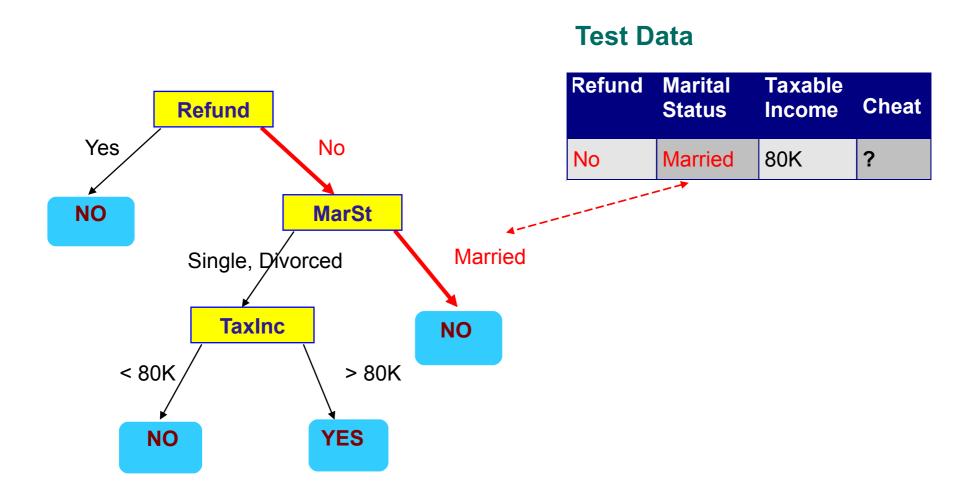
Test Data

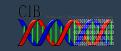
Refund	Marital Status		Cheat
No	Married	80K	?

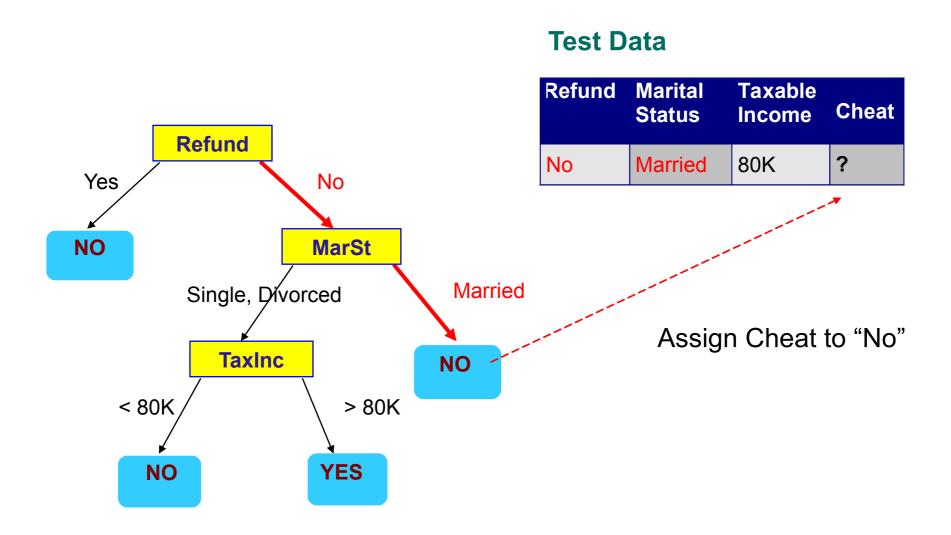














Decision Tree Classification Task

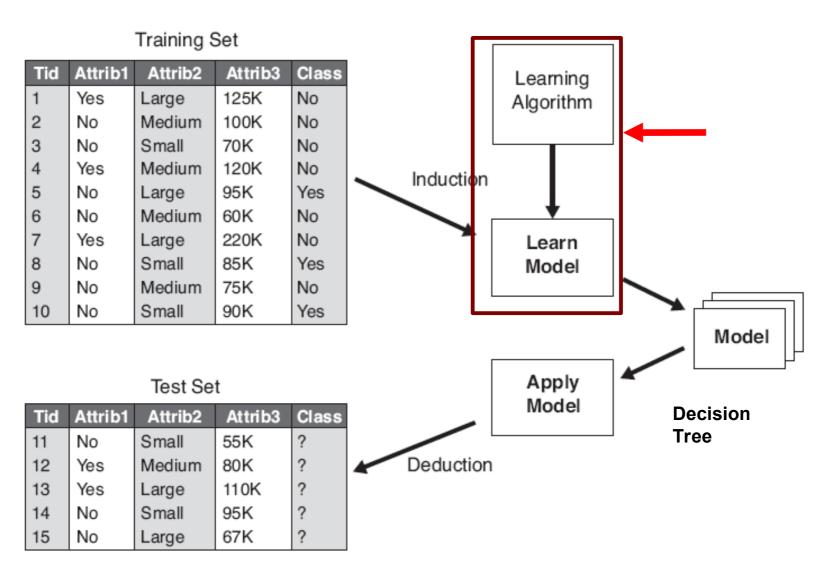
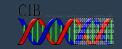


Figure 4.3. General approach for building a classification model.



Decision Tree Induction

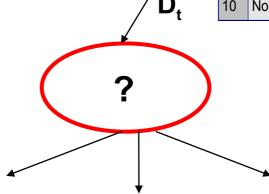
- MANY ALGORITHMS:
 - Hunt's Algorithm (one of the earliest)
 - CART
 - ID3, C4.5
 - SLIQ, SPRINT

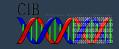


General Structure of Hunt's Algorithm

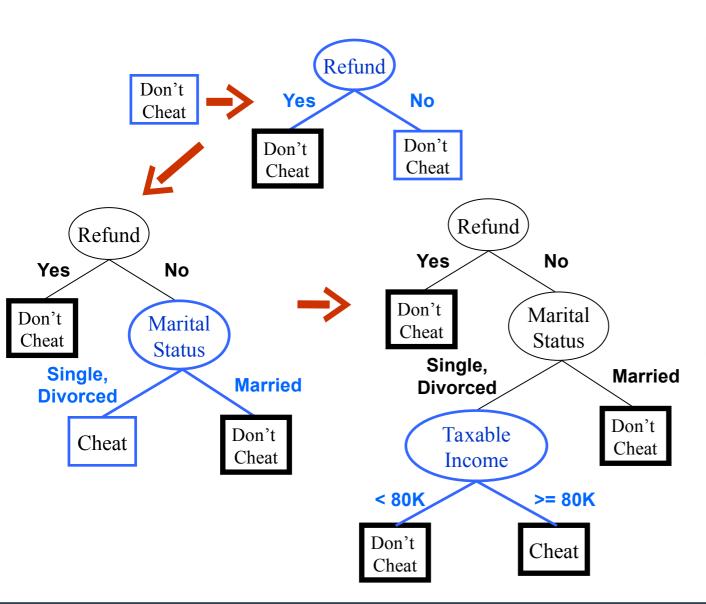
- Let D_T be the set of training records That reach a node T
- GENERAL PROCEDURE:
 - If D_t contains records that belong the same class y_t, then t is a leaf node labeled as y_t
 - If D_t is an empty set, then t is a leaf node labeled by the default class, y_d
 - If D_t contains records that belong to more than one class, use an attribute test to split the data into smaller subsets. Recursively apply the procedure to each subset.

Tid	Refund	Marital Status	Taxable Income	Cheat
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes





Hunt's Algorithm

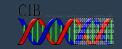


Tid	Refund	Marital Status	Taxable Income	Cheat
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7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes



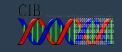
Tree Induction

- GREEDY STRATEGY.
 - Split the records based on an attribute test that optimizes certain criterion.
- Issues
 - Determine how to split the records
 - ◆How to specify the attribute test condition?
 - ◆How to determine the best split?
 - Determine when to stop splitting



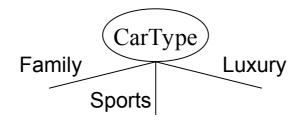
How to Specify Test Condition?

- DEPENDS ON ATTRIBUTE TYPES
 - Nominal
 - Ordinal
 - Continuous
- Depends on number of ways to split
 - 2-way split
 - Multi-way split



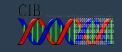
Splitting Based on Nominal Attributes

MULTI-WAY SPLIT: USE AS MANY PARTITIONS AS DISTINCT VALUES.



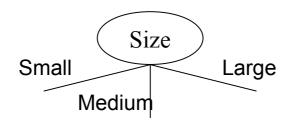
BINARY SPLIT: DIVIDES VALUES INTO TWO SUBSETS.
 NEED TO FIND OPTIMAL PARTITIONING.



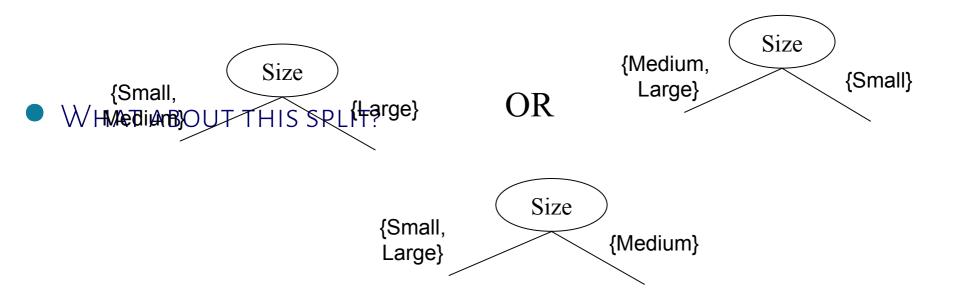


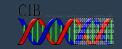
Splitting Based on Ordinal Attributes

Multi-way split: Use as many partitions as distinct values.



BINARY SPLIT: DIVIDES VALUES INTO TWO SUBSETS.
 NEED TO FIND OPTIMAL PARTITIONING.



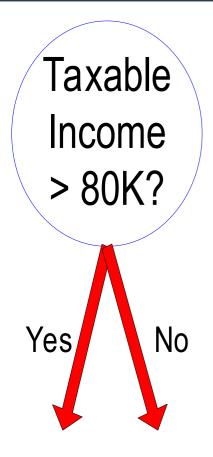


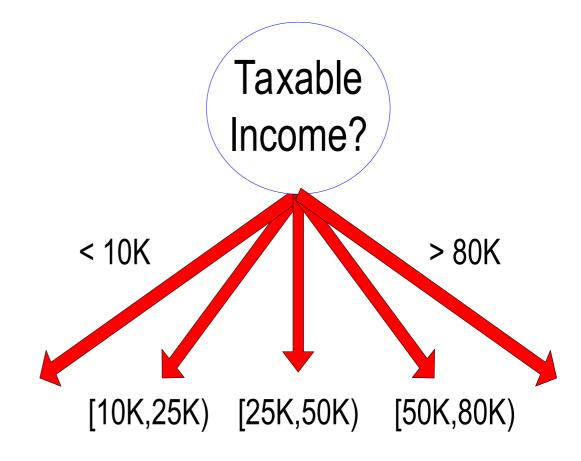
Splitting Based on Continuous Attributes

- DIFFERENT WAYS OF HANDLING
 - Discretization to form an ordinal categorical attribute
 - Static discretize once at the beginning
 - Dynamic ranges can be found by equal interval bucketing, equal frequency bucketing (percentiles), or clustering.
 - Binary decision (consider all vallues): (A < v) or $(A \ge v)$
 - consider all possible splits and finds the best cut
 - can be more compute intensive
 - In some case too many splits



Splitting Based on Continuous Attributes





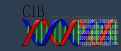
(i) Binary split

(ii) Multi-way split



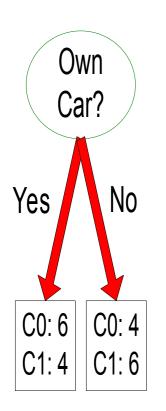
Tree Induction

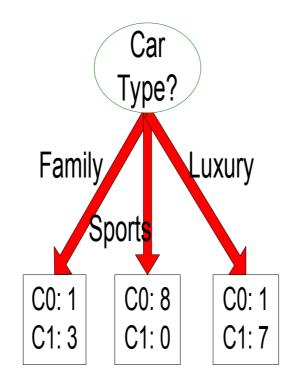
- GREEDY STRATEGY.
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- Issues
 - Determine how to split the records
 - ◆How to specify the attribute test condition?
 - How to determine the best split?
 - Determine when to stop splitting

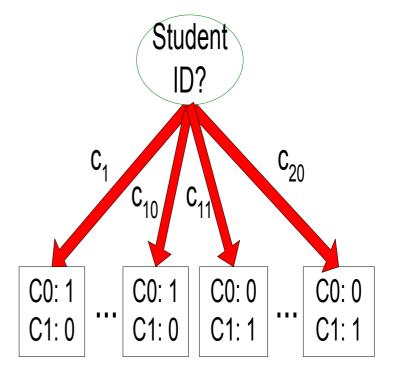


How to determine the Best Split

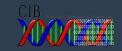
Before Splitting: 10 records of class 0, 10 records of class 1







Which test condition is the best?



How to determine the Best Split

- GREEDY APPROACH:
 - Nodes with homogeneous class distribution are preferred
- NEED A MEASURE OF NODE IMPURITY:

C0: 5

C1: 5

Non-homogeneous,

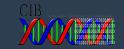
High degree of impurity

C0: 9

C1: 1

Homogeneous,

Low degree of impurity

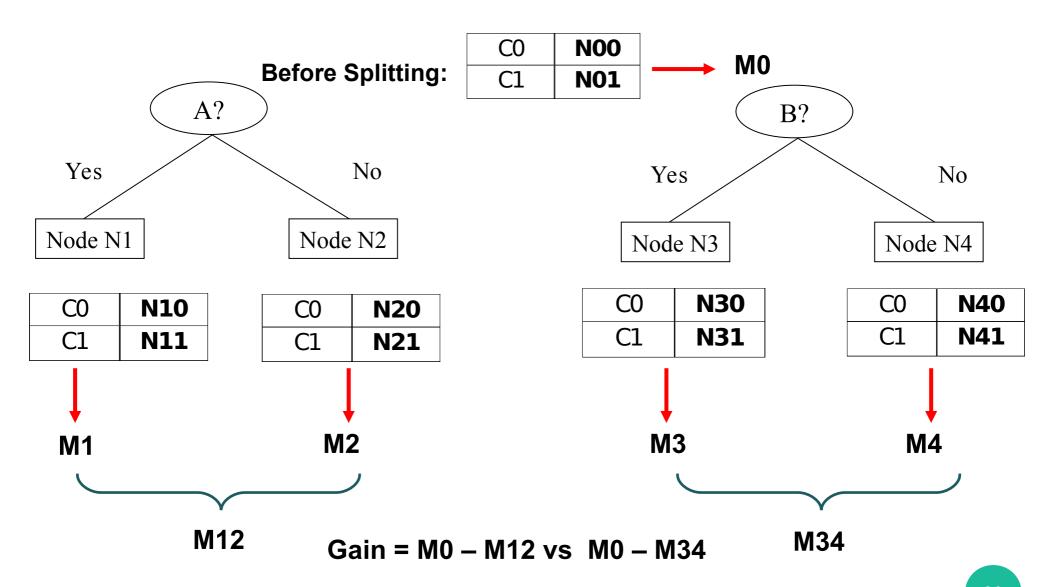


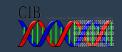
Measures of Node Impurity

- GINI INDEX
- ENTROPY
- MISCLASSIFICATION ERROR



How to Find the Best Split





Measure of Impurity: GINI

GINI INDEX FOR A GIVEN NODE T :

$$GINI(t) = 1 - \sum [p(j|t)]^{2}$$

(NOTE: p(j|t) is the relative frequency of class j at node t).

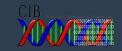
- Maximum (1 $1/n_c$) when records are equally distributed among all classes, implying least interesting information
- Minimum (0.0) when all records belong to one class, implying most interesting information

C1	0
C2	6
Gini=	0.000

Gini=	0.278
C2	5
C1	1

C1	2
C2	4
Gini=	0.444

C1	3
C2	3
Gini=	0.500



Examples for computing GINI

$$GINI(t) = 1 - \sum_{j} [p(j|t)]^{2}$$

C1	0
C2	6

$$P(C1) = 0/6 = 0$$
 $P(C2) = 6/6 = 1$

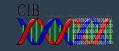
Gini =
$$1 - P(C1)^2 - P(C2)^2 = 1 - 0 - 1 = 0$$

$$P(C1) = 1/6$$
 $P(C2) = 5/6$

Gini =
$$1 - (1/6)^2 - (5/6)^2 = 0.278$$

$$P(C1) = 2/6$$
 $P(C2) = 4/6$

Gini =
$$1 - (2/6)^2 - (4/6)^2 = 0.444$$



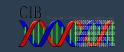
Splitting Based on GINI

- USED IN CART, SLIQ, SPRINT.
- When a node p is split into k partitions (children), the quality of split is computed as,

$$GINI_{split} = \sum_{i=1}^{k} \frac{n_i}{n} GINI(i)$$

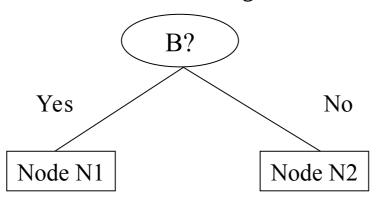
WHERE: $N_1 = NUMBER OF RECORDS AT CHILD I$

N = NUMBER OF RECORDS AT NODE P



Binary Attributes: Computing GINI Index

- Splits into two partitions
- Effect of Weighing partitions:
 - Larger and Purer Partitions are sought for.



	Parent
C1	6
C2	6
Gini = 0.500	

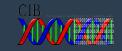
G	iini(N1)
=	$1-(5/7)^2-(2/7)^2$
=	0.401

Gini(N2)
=
$$1 - (1/5)^2 - (4/5)^2$$

= 0.320

	N1	N2
C1	5	1
C2	2	4
Gin	i=0.3	33

Gini(Children) = 7/12 * 0.401 + 5/12 * 0.320 = 0.36752



Categorical Attributes: Computing Gini Index

- FOR EACH DISTINCT VALUE, GATHER COUNTS FOR EACH CLASS IN THE DATASET
- Use the count matrix to make decisions

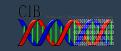
Multi-way split

		CarType									
	Family	Sports	Luxury								
C1	1	2	1								
C2	4	1	1								
Gini	0.393										

Two-way split (find best partition of values)

	CarType								
	{Sports, Luxury}	{Family}							
C1	3	1							
C2	2	4							
Gini	0.400								

	CarType										
	{Sports}	{Family, Luxury}									
C1	2	2									
C2	1	5									
Gini	0.419										

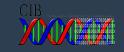


Continuous Attributes: Computing Gini Index

- Use Binary Decisions based on one value
- Several Choices for the splitting value
 - Number of possible splitting values = Number of distinct values
- EACH SPLITTING VALUE HAS A COUNT MATRIX ASSOCIATED WITH IT
 - Class counts in each of the partitions, A < v and A ≥ v
- SIMPLE METHOD TO CHOOSE BEST V
 - For each v, scan the database to gather count matrix and compute its Gini index
 - Computationally Inefficient!
 Repetition of work.



Tid	Refund	Marital Status	Taxable Income	Cheat
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
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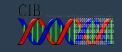


Continuous Attributes: Computing Gini Index...

- FOR EFFICIENT COMPUTATION: FOR EACH ATTRIBUTE,
 - Sort the attribute on values
 - Linearly scan these values, each time updating the count matrix and computing gini index
 - Choose the split position that has the least gini index

Sorted Values Split Positions

	Cheat	ı	No		No		N	0	Ye	s Yes		s	Υe	Yes No		0	No		No		No		
		Taxable Income																					
	→	(60		70		7	5	85	,	90)	9	5	10	00	12	20	12	25		220	
		5	5	6	5	7	2	8	0	8	7	9	2	9	7	11	10	12	22	17	72	23	0
_		<=	>	<=	>	<=	>	<=	>	<=	>	<=	>	<=	>	<=	>	<=	>	<=	>	<=	>
	Yes	0	3	0	3	0	3	0	3	1	2	2	1	3	0	3	0	3	0	3	0	3	0
	No	0	7	1	6	2	5	3	4	3	4	3	4	3	4	4	3	5	2	6	1	7	0
	Gini	0.4	20	0.4	100	0.3	375	0.3	343	43 0.417		0.400		400 <u>0.300</u>		0.34		0.3	375 0.4		100	0.420	



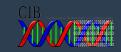
Alternative Splitting Criteria based on INFO

ENTROPY AT A GIVEN NODE T:

$$\text{Entropy}(t) = -\sum_{j} p(j|t) \log p(j|t)$$

(NOTE: p(j | t) is the relative frequency of class j at node t).

- Measures homogeneity of a node.
 - Maximum (log n_c) when records are equally distributed among all classes implying least information
 - Minimum (0.0) when all records belong to one class, implying most information
- Entropy based computations are similar to the GINI index computations



Examples for computing Entropy

$$\text{Entropy}(t) = -\sum_{j} p(j|t) \log_2 p(j|t)$$

C1	0
C2	6

$$P(C1) = 0/6 = 0$$
 $P(C2) = 6/6 = 1$

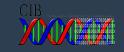
Entropy =
$$-0 \log 0 - 1 \log 1 = -0 - 0 = 0$$

$$P(C1) = 1/6$$
 $P(C2) = 5/6$

Entropy =
$$-(1/6) \log_2 (1/6) - (5/6) \log_2 (1/6) = 0.65$$

$$P(C1) = 2/6$$
 $P(C2) = 4/6$

Entropy =
$$-(2/6) \log_2 (2/6) - (4/6) \log_2 (4/6) = 0.92$$



Splitting Based on INFO...

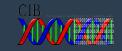
Information Gain:

$$GAIN_{split} = Entropy(p) - \left(\sum_{i=1}^{k} \frac{n_i}{n} Entropy(i)\right)$$

Parent Node, p is split into k partitions;

n_i is number of records in partition i

- Measures Reduction in Entropy achieved because of the split.
 Choose the split that achieves most reduction (maximizes GAIN)
- Used in ID3 and C4.5
- Disadvantage: Tends to prefer splits that result in large number of partitions, each being small but pure.



Splitting Based on INFO...

Gain Ratio:

$$GainRATIO_{split} = \frac{GAIN_{Split}}{SplitINFO}$$

$$SplitINFO = -\sum_{i=1}^{k} \frac{n_i}{n} \log \frac{n_i}{n}$$

Parent Node, p is split into k partitions n_i is the number of records in partition i

- Adjusts Information Gain by the entropy of the partitioning (SplitINFO). Higher entropy partitioning (large number of small partitions) is penalized!
- Used in C4.5
- Designed to overcome the disadvantage of Information Gain



Splitting Criteria based on Classification Error

CLASSIFICATION ERROR AT A NODE T :

$$Error(t) = 1 - max_i P(i|t)$$

- Measures misclassification error made by a node.
 - Maximum (1 $1/n_c$) when records are equally distributed among all classes, implying least interesting information
 - Minimum (0.0) when all records belong to one class, implying most interesting information



Examples for Computing Error

$$Error(t) = 1 - max_i P(i|t)$$

C1	0
C2	6

$$P(C1) = 0/6 = 0$$
 $P(C2) = 6/6 = 1$

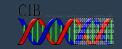
Error =
$$1 - \max(0, 1) = 1 - 1 = 0$$

$$P(C1) = 1/6$$
 $P(C2) = 5/6$

Error =
$$1 - \max(1/6, 5/6) = 1 - 5/6 = 1/6$$

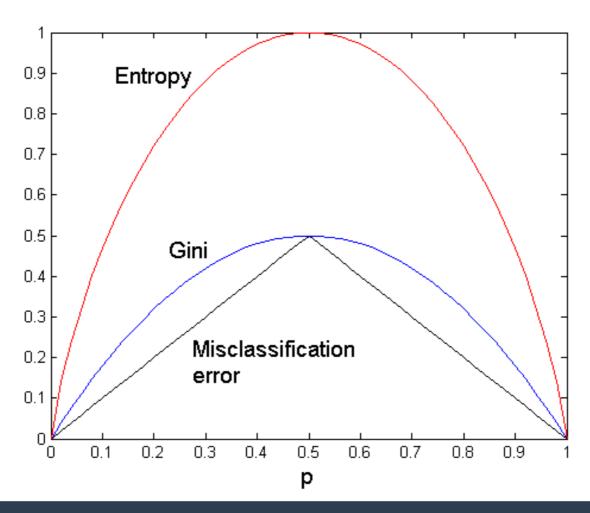
$$P(C1) = 2/6$$
 $P(C2) = 4/6$

Error =
$$1 - \max(2/6, 4/6) = 1 - 4/6 = 1/3$$



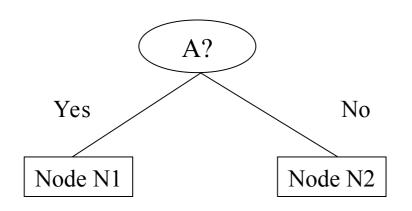
Comparison among Splitting Criteria

For a 2-class problem:





Misclassification Error vs Gini



	Parent	
C1	7	
C2	3	
Gini = 0.42		

Gini(N1)
=
$$1 - (3/3)^2 - (0/3)^2$$

= 0

Gini(N2)
=
$$1 - (4/7)^2 - (3/7)^2$$

= 0.489

	N1	N2	
C1	3	4	
C2	0	3	
Gini=0.361			

Gini(Children)

= 3/10 * 0

+ 7/10 * 0.489

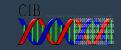
= 0.342

Gini improves!!



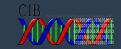
Tree Induction

- Greedy strategy.
 - Split the records based on an attribute test that optimizes certain criterion.
- Issues
 - Determine how to split the records
 - ◆How to specify the attribute test condition?
 - ◆How to determine the best split?
 - Determine when to stop splitting



Stopping Criteria for Tree Induction

- STOP EXPANDING A NODE WHEN ALL THE RECORDS BELONG TO THE SAME CLASS
- STOP EXPANDING A NODE WHEN ALL THE RECORDS HAVE SIMILAR ATTRIBUTE VALUES
- EARLY TERMINATION (TO BE DISCUSSED LATER)



Decision Tree Based Classification

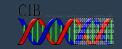
ADVANTAGES:

- Inexpensive to construct
- Extremely fast at classifying unknown records
- Easy to interpret for small-sized trees
- Accuracy is comparable to other classification techniques for many simple data sets
- Unstable



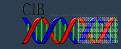
Example: C4.5

- SIMPLE DEPTH-FIRST CONSTRUCTION.
- Uses Information Gain
- Sorts Continuous Attributes at each node.
- NEEDS ENTIRE DATA TO FIT IN MEMORY.
- Unsuitable for Large Datasets.
 - Needs out-of-core sorting.
- YOU CAN DOWNLOAD THE SOFTWARE FROM: http://www.cse.unsw.edu.au/~quinlan/c4.5r8.tar.gz

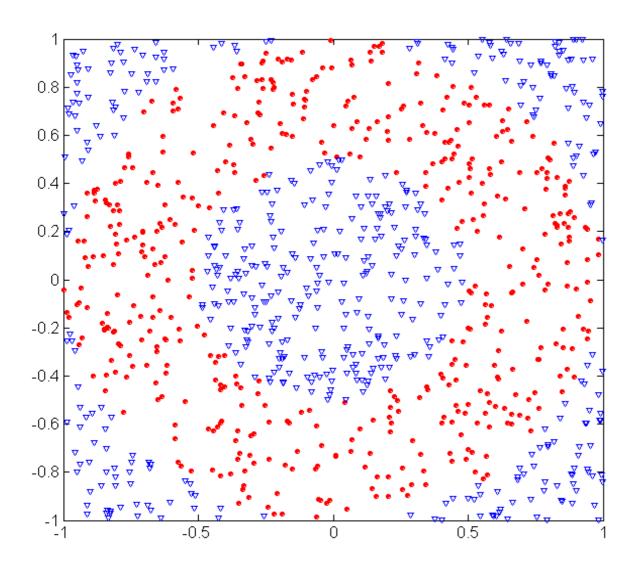


Practical Issues of Classification

- Underfitting and Overfitting
- Missing Values
- Costs of Classification



Underfitting and Overfitting (Example)



500 circular and 500 triangular data points.

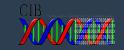
Circular points:

$$0.5 \le \text{sqrt}(x_1^2 + x_2^2) \le 1$$

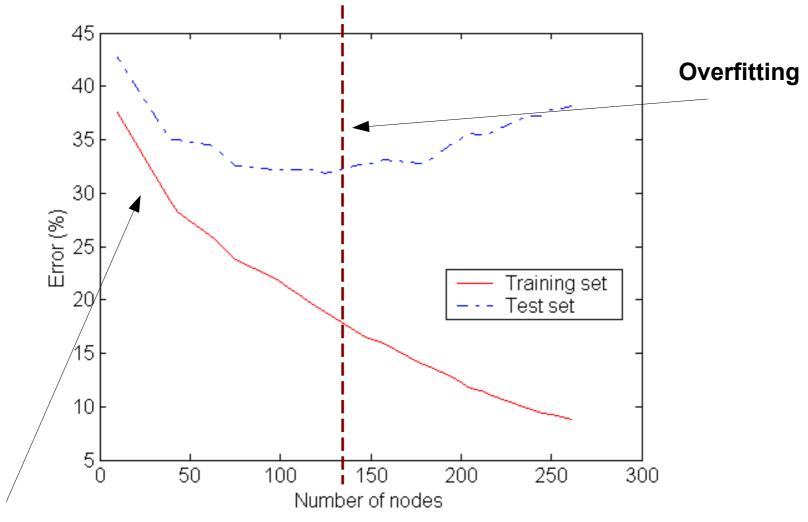
Triangular points:

$$sqrt(x_1^2+x_2^2) > 0.5 or$$

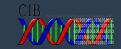
$$sqrt(x_1^2+x_2^2) < 1$$



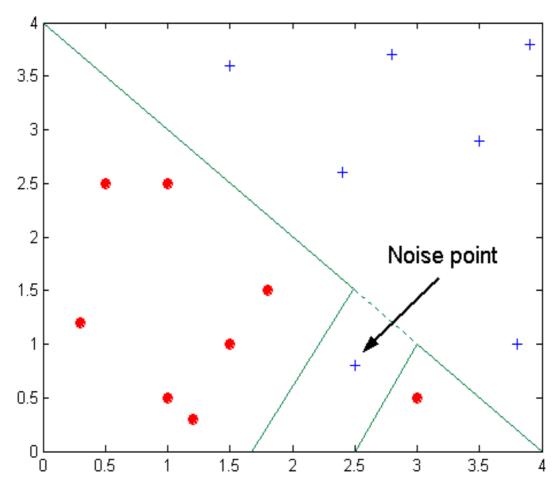
Underfitting and Overfitting



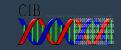
Underfitting: when model is too simple, both training and test errors are large



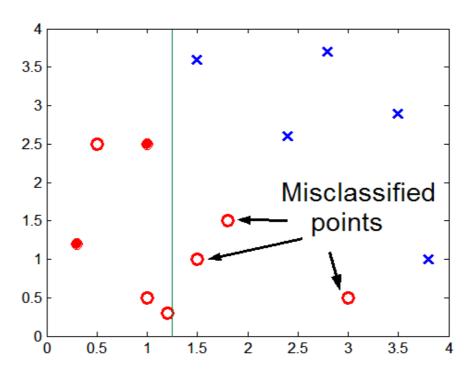
Overfitting due to Noise



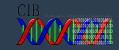
Decision boundary is distorted by noise point



Overfitting due to Insufficient Examples

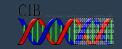


- Lack of data points in the lower half of the diagram makes it difficult to predict correctly the class labels of that region
- Insufficient number of training records in the region causes the decision tree to predict the test examples using other training records that are irrelevant to the classification task



Notes on Overfitting

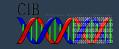
- OVERFITTING RESULTS IN DECISION TREES THAT ARE MORE COMPLEX THAN NECESSARY
- TRAINING ERROR NO LONGER PROVIDES A GOOD ESTIMATE OF HOW WELL THE TREE WILL PERFORM ON PREVIOUSLY UNSEEN RECORDS
- NEED NEW WAYS FOR ESTIMATING ERRORS



Overfitting

XCURSE OF OVERFITTING:

- Related to learning
- Worse when you learning algorithm is better
- No matter who hard you try, it's worse

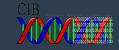


Estimating Generalization Errors

- lacktriangle Re-substitution errors: error on training (Σ e(t))
- GENERALIZATION ERRORS: ERROR ON TESTING $(\Sigma E'(T))$
- METHODS FOR ESTIMATING GENERALIZATION ERRORS:
 - Optimistic approach: e'(t) = e(t)
 - Pessimistic approach (adds model complexity):
 - For each leaf node: e'(t) = (e(t)+0.5)
 - ◆ Total errors: $e'(T) = e(T) + N \times 0.5$ (N: number of leaf nodes)
 - For a tree with 30 leaf nodes and 10 errors on training (out of 1000 instances):

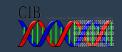
```
Training error = 10/1000 = 1\%
Generalization error = (10 + 30 \times 0.5)/1000 = 2.5\%
```

- Reduced error pruning (REP):
 - uses validation data set to estimate generalization error



Occam's Razor

- GIVEN TWO MODELS OF SIMILAR GENERALIZATION ERRORS, ONE SHOULD PREFER THE SIMPLER MODEL OVER THE MORE COMPLEX MODEL
- FOR COMPLEX MODELS, THERE IS A GREATER CHANCE THAT IT WAS FITTED ACCIDENTALLY BY ERRORS IN DATA
- THEREFORE, ONE SHOULD INCLUDE MODEL COMPLEXITY WHEN EVALUATING A MODEL
- PROBLEM: NOT EASY TO KNOW WHICH IS THE SIMPLER MODEL



Minimum Description Length (MDL)

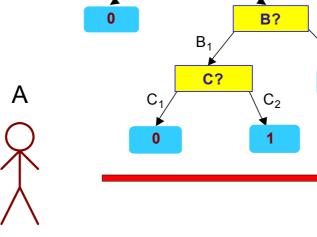
- Cost(Model, Data) = Cost(Data | Model) + Cost(Model)
 - Cost is the number of bits needed for encoding.
 - Search for the least costly model.
- Cost(Data | Model) encodes the misclassification errors.
- COST(MODEL) USES NODE ENCODING (NUMBER OF CHILDREN) PLUS SPLITTING CONDITION ENCODING.

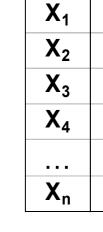
A?

No

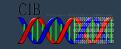
 B_2

X	у
X ₁	1
X ₂	0
X_3	0
X_4	1
X _n	1



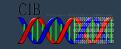


?



How to Address Overfitting

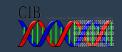
- Pre-Pruning (Early Stopping Rule)
 - Stop the algorithm before it becomes a fully-grown tree
 - Typical stopping conditions for a node:
 - Stop if all instances belong to the same class
 - Stop if all the attribute values are the same
 - More restrictive conditions:
 - Stop if number of instances is less than some user-specified threshold
 - Stop if class distribution of instances are independent of the available features (e.g., using χ^2 test)
 - Stop if expanding the current node does not improve impurity measures (e.g., Gini or information gain).



How to Address Overfitting...

POST-PRUNING

- Grow decision tree to its entirety
- Trim the nodes of the decision tree in a bottom-up fashion
- If validation error improves after trimming, replace sub-tree by a leaf node.
- Class label of leaf node is determined from majority class of instances in the sub-tree
- Can use MDL for post-pruning



Example of Post-Pruning

Class = Yes	20	
Class = No	10	
Frror = 10/30		

Training Error (Before splitting) = 10/30

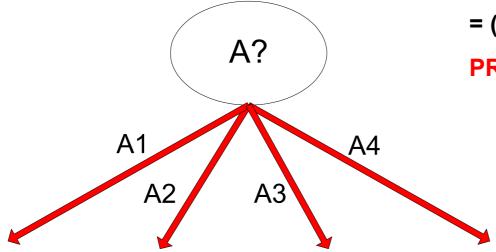
Pessimistic error = (10 + 0.5)/30 = 10.5/30

Training Error (After splitting) = 9/30

Pessimistic error (After splitting)

$$= (9 + 4 \times 0.5)/30 = 11/30$$

PRUNE!

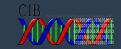


Class = Yes	8
Class = No	4

Class = Yes	3
Class = No	4

Class = Yes	4
Class = No	1

Class = Yes	5
Class = No	1



Examples of Post-pruning

– Optimistic error?

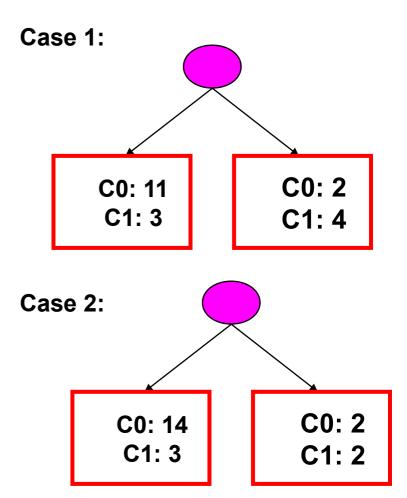
Don't prune for both cases

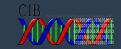
– Pessimistic error?

Don't prune case 1, prune case 2

– Reduced error pruning?

Depends on validation set





Handling Missing Attribute Values

- MISSING VALUES AFFECT DECISION TREE CONSTRUCTION IN THREE DIFFERENT WAYS:
 - Affects how impurity measures are computed
 - Affects how to distribute instance with missing value to child nodes
 - Affects how a test instance with missing value is classified



Computing Impurity Measure

Tid	Refund	Marital Status	Taxable Income	Class
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	?	Single	90K	Yes



Before Splitting:

Entropy(Parent)

$$= -0.3 \log(0.3) - (0.7) \log(0.7) = 0.8813$$

	Class	Class
	= Yes	= No
Refund=Yes	0	3
Refund=No	2	4
Refund=?	1	0

Split on Refund:

Entropy(Refund=Yes) = 0

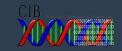
Entropy(Refund=No)

 $= -(2/6)\log(2/6) - (4/6)\log(4/6) = 0.9183$

Entropy(Children)

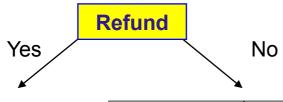
$$= 0.3(0) + 0.6(0.9183) = 0.551$$

Gain =
$$0.9$$
 $(0.8813 - 0.551) = 0.3303$



Distribute Instances

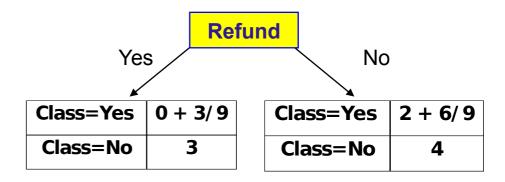
Tid	Refund	Marital Status	Taxable Income	Class
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No



Class=Yes	0
Class=No	3

Cheat=Yes	2
Cheat=No	4

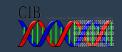
Tid	Refund	Marital Status	Taxable Income	Class
10	?	Single	90K	Yes



Probability that Refund=Yes is 3/9

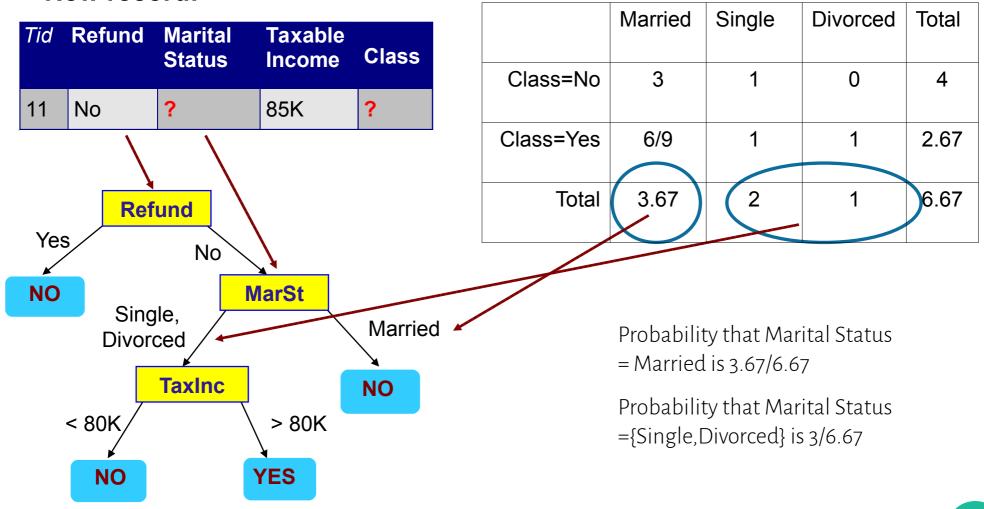
Probability that Refund=No is 6/9

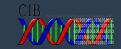
Assign record to the left child with weight = 3/9 and to the right child with weight = 6/9



Classify Instances

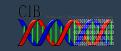
New record:





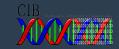
Other Issues

- Data Fragmentation
- SEARCH STRATEGY
- EXPRESSIVENESS
- Tree Replication



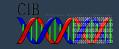
Data Fragmentation

- Number of instances gets smaller as you traverse down the tree
- NUMBER OF INSTANCES AT THE LEAF NODES COULD BE TOO SMALL TO MAKE ANY STATISTICALLY SIGNIFICANT DECISION



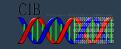
Search Strategy

- FINDING AN OPTIMAL DECISION TREE IS NP-HARD
- THE ALGORITHM PRESENTED SO FAR USES A GREEDY, TOP-DOWN, RECURSIVE PARTITIONING STRATEGY TO INDUCE A REASONABLE SOLUTION
- OTHER STRATEGIES?
 - Bottom-up
 - Bi-directional

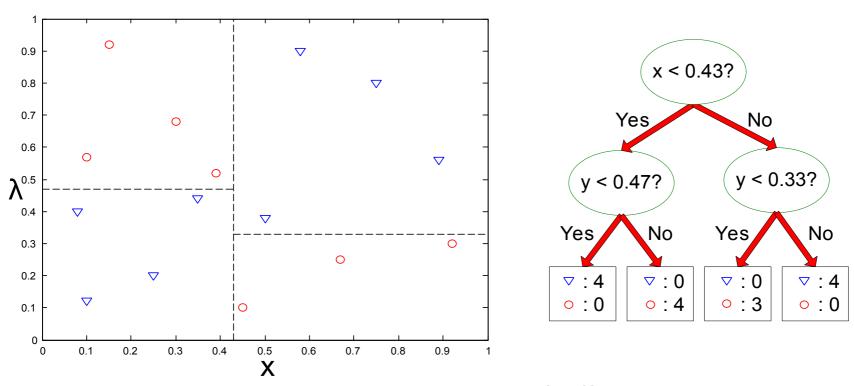


Expressiveness

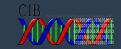
- Decision tree provides expressive representation for learning discretevalued function
 - But they do not generalize well to certain types of Boolean functions
 - Example: parity function:
 - Class = 1 if there is an even number of Boolean attributes with truth value =
 True
 - Class = 0 if there is an odd number of Boolean attributes with truth value =
 True
 - For accurate modeling, must have a complete tree
- Not expressive enough for modeling continuous variables
 - Particularly when test condition involves only a single attribute at-a-time



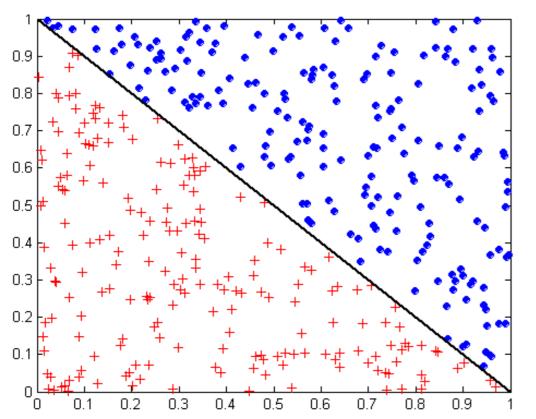
Decision Boundary

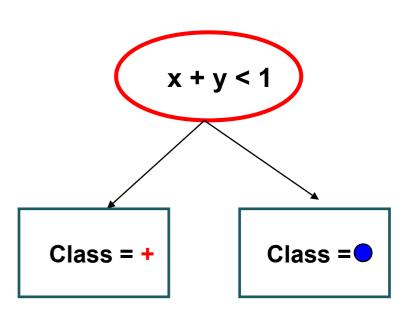


- Border line between two neighboring regions of different classes is known as decision boundary
- Decision boundary is parallel to axes because test condition involves a single attribute at-a-time



Oblique Decision Trees

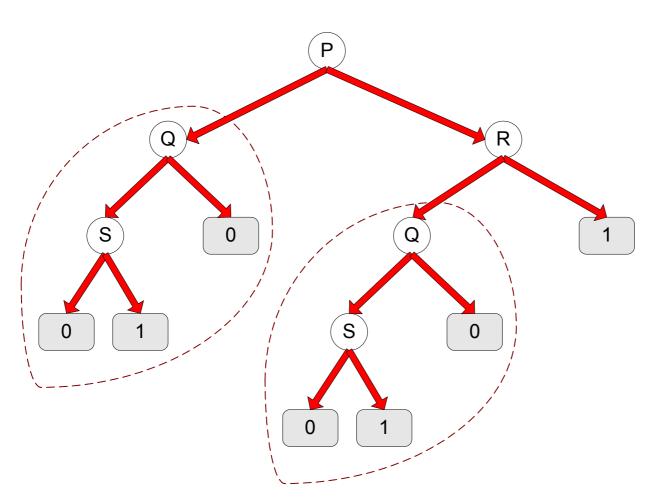




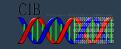
- Test condition may involve multiple attributes
- More expressive representation
- Finding optimal test condition is computationally expensive



Tree Replication

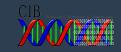


Same subtree appears in multiple branches



Model Evaluation

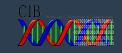
- METRICS FOR PERFORMANCE EVALUATION
 - How to evaluate the performance of a model?
- METHODS FOR PERFORMANCE EVALUATION
 - How to obtain reliable estimates?
- METHODS FOR MODEL COMPARISON
 - How to compare the relative performance among competing models?



Metrics for Performance Evaluation

- Focus on the predictive capability of a model
 - Rather than how fast it takes to classify or build models, scalability, etc.
- CONFUSION MATRIX:

	PREDICTED CLASS			
		Class=Yes	Class=No	
ACTUAL CLASS	Class=Yes	TP	FN	
	Class=No	FP	TN	



Metrics for Performance Evaluation...

	PREDICTED CLASS			
		Class=Yes	Class=No	
ACTUAL CLASS	Class=Yes	a (TP)	b (FN)	
	Class=No	C	d	
	TRIC:	(FP)	(IN)	

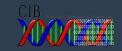
Most wit

Accuracy =
$$\frac{a+d}{a+b+c+d} = \frac{TP+TN}{TP+TN+FP+FN}$$



Limitation of Accuracy

- Consider a 2-class problem
 - Number of Class 0 examples = 9990
 - Number of Class 1 examples = 10
- If model predicts everything to be class 0, accuracy is 9990/10000 = 99.9 %
 - Accuracy is misleading because model does not detect any class 1 example



Cost Matrix

	PREDICTED CLASS			
	C(i j)	Class=Yes	Class=No	
ACTUAL CLASS	Class=Yes	C(Yes Yes)	C(No Yes)	
	Class=No	C(Yes No)	C(No No)	

C(i|j): Cost of misclassifying class j example as class i



Computing Cost of Classification

Cost Matrix	PREDICTED CLASS			
ΛΩΤΙΛΙ	C(i j)	+	-	
ACTUAL CLASS	+	-1	100	
	-	1	0	

Model M ₁	PREDICTED CLASS		
ACTUAL		+	-
CLASS	+	150	40
	-	60	250

Accuracy = 80%Cost = 3910

Model M ₂	PREDICTED CLASS		
ACTUAL		+	-
CLASS	+	250	45
	-	5	200

Accuracy = 90%Cost = 4255



Cost vs Accuracy

Count	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL CLASS	Class=Yes	а	b
	Class=No	С	d

Cost	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL CLASS	Class=Yes	р	q
	Class=No	q	р

Accuracy is proportional to cost if

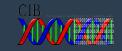
1.
$$C(Yes|No)=C(No|Yes) = q$$

2.
$$C(Yes|Yes)=C(No|No) = p$$

$$N = a + b + c + d$$

Accuracy =
$$(a + d)/N$$

Cost = p (a + d) + q (b + c)
= p (a + d) + q (N - a - d)
= q N - (q - p)(a + d)
= N [q - (q-p)
$$\times$$
 Accuracy]



Cost-Sensitive Measures

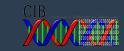
Precision (p) =
$$\frac{a}{a+c}$$

Recall (r) =
$$\frac{a}{a+b}$$

F-measure (F) =
$$\frac{2rp}{r+p} = \frac{2a}{2a+b+c}$$

- Precision is biased towards C(Yes | Yes) & C(Yes | No)
- Recall is biased towards C(Yes | Yes) & C(No | Yes)
- F-measure is biased towards all except C(No No)

Weighted Accuracy =
$$\frac{w_1 a + w_4 d}{w_1 a + w_2 b + w_3 c + w_4 d}$$



Class-imbalanced data measures

*SENSITIVITY (RECALL, TRUE POSITIVE RATE):

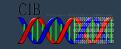
• Sn = TP/(TP+FN)

*****Specificity (True negative rate)

• Sp = TN/(TN+FP)

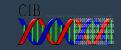
*G-MEAN

$$G$$
-mean= $\sqrt{(Sn \cdot Sp)}$



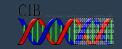
Model Evaluation

- Metrics for Performance Evaluation
 - How to evaluate the performance of a model?
- METHODS FOR PERFORMANCE EVALUATION
 - How to obtain reliable estimates?
- METHODS FOR MODEL COMPARISON
 - How to compare the relative performance among competing models?

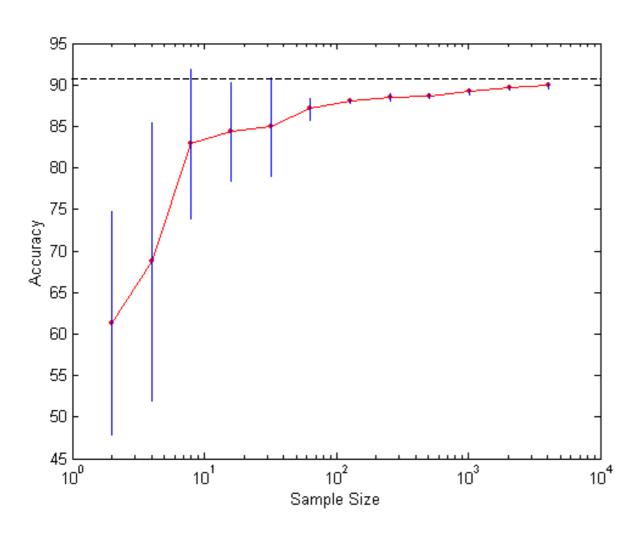


Methods for Performance Evaluation

- HOW TO OBTAIN A RELIABLE ESTIMATE OF PERFORMANCE?
- PERFORMANCE OF A MODEL MAY DEPEND ON OTHER FACTORS BESIDES THE LEARNING ALGORITHM:
 - Class distribution
 - Cost of misclassification
 - Size of training and test sets



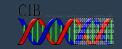
Learning Curve



- Learning curve shows how accuracy changes with varying sample size
- Requires a sampling schedule for creating learning curve:
 - Arithmetic sampling (Langley et al.)
 - Geometric sampling (Provost et al.)

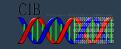
Effect of small sample size:

- Bias in the estimate
- Variance of estimate



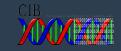
Methods of Estimation

- HOLDOUT
 - Reserve 2/3 for training and 1/3 for testing
- RANDOM SUBSAMPLING
 - Repeated holdout
- Cross validation
 - Partition data into k disjoint subsets
 - k-fold: train on k-1 partitions, test on the remaining one
 - Leave-one-out: k=n
- STRATIFIED SAMPLING
 - oversampling vs undersampling
- BOOTSTRAP
 - Sampling with replacement



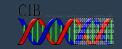
Model Evaluation

- Metrics for Performance Evaluation
 - How to evaluate the performance of a model?
- METHODS FOR PERFORMANCE EVALUATION
 - How to obtain reliable estimates?
- METHODS FOR MODEL COMPARISON
 - How to compare the relative performance among competing models?



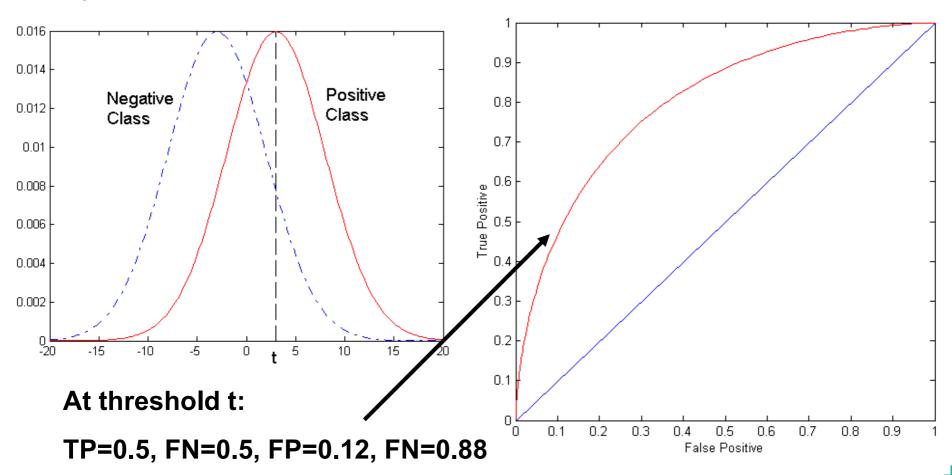
ROC (Receiver Operating Characteristic)

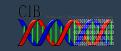
- Developed in 1950s for signal detection theory to analyze noisy signals
 - Characterize the trade-off between positive hits and false alarms
- ROC curve plots TP rate (SN) on the y-axis against FP rate (1-SP) on the x-axis
- PERFORMANCE OF EACH CLASSIFIER REPRESENTED AS A POINT ON THE ROC CURVE
 - changing the threshold of algorithm, sample distribution or cost matrix changes the location of the point



ROC Curve

- 1-dimensional data set containing 2 classes (positive and negative)
- any points located at x > t is classified as positive

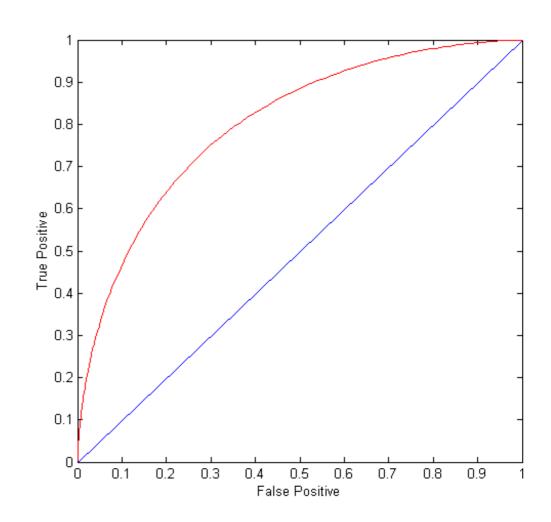


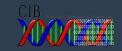


ROC Curve

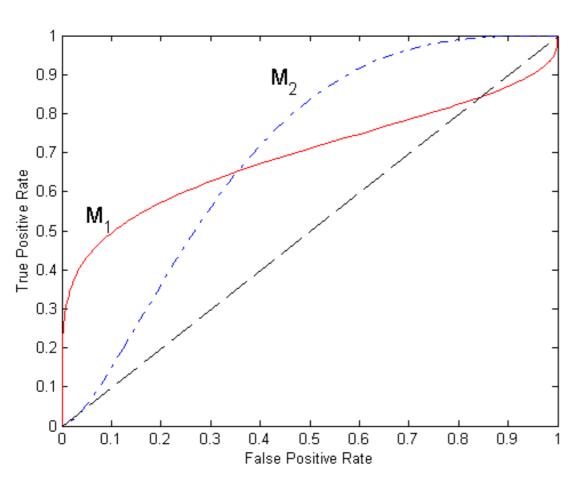
(TP RATE = TP/P, FP RATE = FP/N):

- (0,0): DECLARE EVERYTHING
 TO BE NEGATIVE CLASS
- (1,1): DECLARE EVERYTHING
 TO BE POSITIVE CLASS
- (1,0): IDEAL
- DIAGONAL LINE:
 - Random guessing
 - Below diagonal line:
 - prediction is opposite of the true class

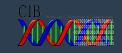




Using ROC for Model Comparison



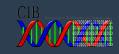
- No model consistently outperform the other
 - M₁ is better for small FPR
 - M₂ is better for large FPR
- Area Under the ROC curve
 - Ideal:
 - Area = 1
 - Random guess:
 - Area = 0.5



How to Construct an ROC curve

Instance	P(+ A)	True Class
1	0.95	+
2	0.93	+
3	0.87	-
4	0.85	-
5	0.85	-
6	0.85	+
7	0.76	-
8	0.53	+
9	0.43	-
10	0.25	+

- Use classifier that produces posterior probability for each test instance P(+|A)
- Sort the instances according to P(+|A) in decreasing order
- Apply threshold at each unique value of P(+|A)
- Count the number of TP, FP,
 TN, FN at each threshold
- TP rate, TPR = TP/(TP+FN)
- FP rate, FPR = FP/(FP + TN)



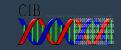
How to construct an ROC curve

Threshold	Class	+	-	+	-	-	-	+	-	+	+	
>=		0.25	0.43	0.53	0.76	0.85	0.85	0.85	0.87	0.93	0.95	1.00
	TP	5	4	4	3	3	3	3	2	2	1	0
	FP	5	5	4	4	3	2	1	1	0	0	0
	TN	0	0	1	1	2	3	4	4	5	5	5
→	FN	0	1	1	2	2	2	2	3	3	4	5
	TPR	1	0.8	0.8	0.6	0.6	0.6	0.6	0.4	0.4	0.2	0
	FPR	1	1	0.8	0.8	0.6	0.4	0.2	0.2	0	0	0
ROC	Curv	e:	0.9 - 0.8 - 0.7 - 0.6 - 0.5 - 0.4 - 0.3 - 0.2 - 0.1 -	0.1 0	2 0.3	0.4	0.5 0.6	6 0.7	0.8 0			



Test of Significance

- GIVEN TWO MODELS:
 - Model M1: accuracy = 85%, tested on 30 instances
 - Model M2: accuracy = 75%, tested on 5000 instances
- CAN WE SAY M1 IS BETTER THAN M2?
 - How much confidence can we place on accuracy of M1 and M2?
 - Can the difference in performance measure be explained as a result of random fluctuations in the test set?



Confidence Interval for Accuracy

- PREDICTION CAN BE REGARDED AS A BERNOULLI TRIAL
 - A Bernoulli trial has 2 possible outcomes
 - Possible outcomes for prediction: correct or wrong
 - Collection of Bernoulli trials has a Binomial distribution:
 - $x \sim Bin(N, p)$ x: number of correct predictions
 - e.g: Toss a fair coin 50 times, how many heads would turn up? Expected number of heads = $N \times p = 50 \times 0.5 = 25$
- GIVEN X (# OF CORRECT PREDICTIONS) OR EQUIVALENTLY, ACC=X/N, AND N (# OF TEST INSTANCES),

CAN WE PREDICT P (TRUE ACCURACY OF MODEL)?



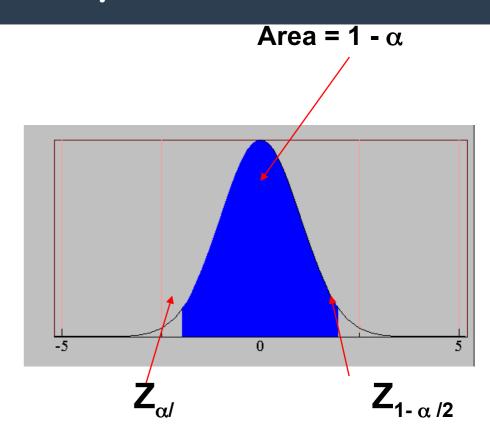
Confidence Interval for Accuracy

- FOR LARGE TEST SETS (N > 30),
 - acc has a normal distribution with mean p and variance p(1-p)/N

$$P\big(Z_{\alpha/2} < \frac{acc - p}{\sqrt{p(1-p)/N}} < Z_{1-\alpha/2}\big)$$

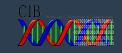
$$1-\alpha$$

CONFIDENCE INTERVAL FOR P:



2

$$p = \frac{2 \times N \times acc + Z_{\alpha/2}^2 \pm \sqrt{Z_{\alpha/2}^2 + 4 \times N \times acc - 4 \times N \times acc^2}}{2\left(N + Z_{\alpha/2}^2\right)}$$



Confidence Interval for Accuracy

- CONSIDER A MODEL THAT PRODUCES AN ACCURACY OF 80% WHEN EVALUATED ON 100 TEST INSTANCES:
 - N=100, acc = 0.8
 - Let $1-\alpha = 0.95$ (95% confidence)
 - From probability table, $Z_{\alpha/2}=1.96$

N	50	100	500	1000	5000
p(lower)	0.670	0.711	0.763	0.774	0.789
p(upper)	0.888	0.866	0.833	0.824	0.811

1-α	Z
0.99	2.58
0.98	2.33
0.95	1.96
0.90	1.65



Comparing Performance of 2 Models

- GIVEN TWO MODELS, SAY M1 AND M2, WHICH IS BETTER?
 - M1 is tested on D1 (size=n1), found error rate = e_1
 - M2 is tested on D2 (size=n2), found error rate = e_2
 - Assume D1 and D2 are independent
 - If n1 and n2 are sufficiently large, then

$$e_1 \sim N\left(\mu_1, \sigma_1\right)$$
 $e_2 \sim N\left(\mu_2, \sigma_2\right)$

– Approximate:

$$\hat{\sigma}_i = \frac{e_i (1 - e_i)}{n_i}$$



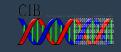
Comparing Performance of 2 Models

- TO TEST IF PERFORMANCE DIFFERENCE IS STATISTICALLY SIGNIFICANT: D = E1 —
 E2
 - $d \sim N(d_t, \sigma_t)$ where d_t is the true difference
 - Since D1 and D2 are independent, their variance adds up:

$$\sigma_t^2 = \sigma_1^2 + \sigma_2^2 \approx \hat{\sigma}_1^2 + \hat{\sigma}_2^2$$

$$\frac{eI(1-eI)}{nI} + \frac{e2(1-e2)}{n2}$$

- At (1- α) confidence level, $d_t = d \pm Z_{\alpha/2} \hat{\sigma}_t$

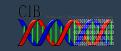


An Illustrative Example

- GIVEN: M1: N1 = 30, E1 = 0.15
 M2: N2 = 5000, E2 = 0.25
- D = |E2 E1| = 0.1 (2-SIDED TEST)

$$\hat{\sigma}_{d} = \frac{0.15(1-0.15)}{30} + \frac{0.25(1-0.25)}{5000} = 0.0043$$
• AT 95% CONFIDENCE LEVEL, $Z_{\alpha/2} = 1.95000$

=> INTERVAL CONTAINS 0=96 X
$$\sqrt{0.0043} = 0.100 \pm 0.128$$
STATISTICALLY SIGNIFICANT



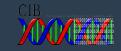
Comparing Performance of 2 Algorithms

- EACH LEARNING ALGORITHM MAY PRODUCE K MODELS:
 - L1 may produce M11 , M12, ..., M1k
 - L2 may produce M21, M22, ..., M2k
- If MODELS ARE GENERATED ON THE SAME TEST SETS D1,D2, ..., DK (E.G., VIA CROSS-VALIDATION)
 - For each set: compute $d_i = e_{1i} e_{2i}$
 - d_i has mean d_t and variance σ_t
 - Estimate:

$$\sum_{t=0}^{k} (d_{j} - \overline{d})^{2}$$

$$\hat{\sigma}_{t}^{2} = \frac{j=1}{k(k-1)}$$

$$d_{t} = d \pm t_{1-\alpha,k-1} \hat{\sigma}_{t}$$



Non parametric tests: 1 vs. 1 over N problems

XWILCOXON'S TEST

x2 algorithms over N problems

 xd_i is the difference of the performance in i -th set

$$R^+ = \sum_{d_i > 0} \operatorname{rank}(d_i) + \frac{1}{2} \sum_{d_i = 0} \operatorname{rank}(d_i) \qquad \qquad R^- = \sum_{d_i < 0} \operatorname{rank}(d_i) + \frac{1}{2} \sum_{d_i = 0} \operatorname{rank}(d_i).$$

Being T the smaller of the sums:

$$z = \frac{T - \frac{1}{4}N(N+1)}{\sqrt{\frac{1}{24}N(N+1)(2N+1)}}$$

is normally distributed.

 $ilde{x}$ A p-value is obtained from the value of z and compared with a critical value α



Non parametric tests: 1 vs. k-1 over N problems

XHOLM'S PROCEDURE

$$R_i = 1/N \sum_j r_j^i$$

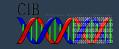
XZ IS NORMALLY DISTRIBUTED

$$z = (R_i - R_j) / \sqrt{\frac{k(k+1)}{6N}}.$$

XTHE CRITICAL VALUE, A

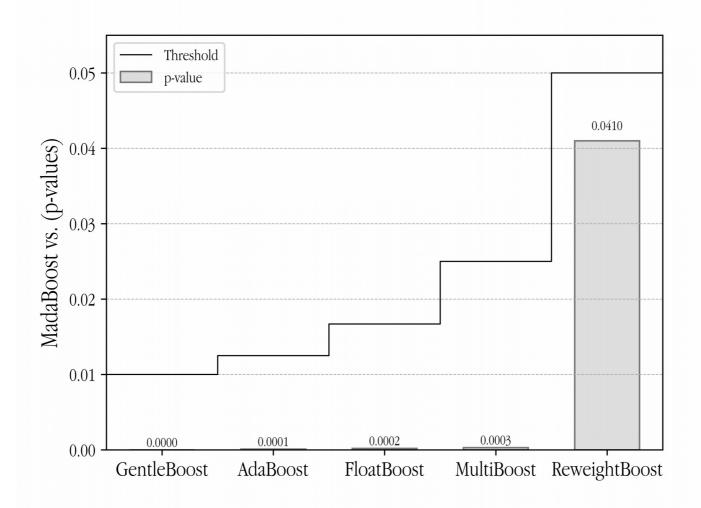
*P VALUES ARE ORDERED AND TESTED IN TURNS

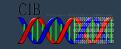
$$\alpha/(k-1)$$



Holm's procedure

XGRAPHICAL REPRESENTATION





Friedman test

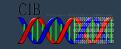
- *MULTIPLE COMPARISON TEST
- *FRIEDMAN TEST

xLet r_i be the rank of the j-th of k algorithms on the i-th of N data sets

*Friedman test compares the average ranks of algorithms R_i

$$\chi_F^2 = \frac{12N}{k(k+1)} \left[\sum_j R_j^2 - \frac{k(k+1)^2}{4} \right]$$

xis distributed according to χ_{F^2} with k-1 degrees of freedom, when N and k are big enough (as a rule of a thumb, N > 10 and k > 5)

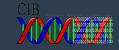


Iman – Davenport test

- *FRIEDMAN TEST IS UNDESIRABLY CONSERVATIVE
- *IMAN AND DAVENPORT DESIGNED A BETTER STATISTIC:

$$F_F = \frac{(N-1)\chi_F^2}{N(k-1) - \chi_F^2}$$

*WHICH IS DISTRIBUTED ACCORDING TO THE F-DISTRIBUTION WITH K-1 AND (K-1)(N-1) DEGREES OF FREEDOM.



Nemenyi test

- *BASED ON FRIEDMAN'S RANKS
- *METHODS SIGNIFICANTLY DIFFERENT IF RANK DIFFERENT ABODE CRITICAL VALUE:

$$CD = q_{\alpha} \sqrt{k(k+1) \frac{6}{N}}$$

k: #methods, N: #datasets, q_{alpha} : critical value (Student t)

