James Amidei Assignment #2

3.13

$$\left(-\frac{\mathsf{t}^2}{2\mathsf{m}} \nabla^2 + \mathsf{V}\right) \mathcal{V} = i \, \mathsf{h} \, \frac{\partial}{\partial t} \mathcal{V} \, \left(\overline{\mathsf{1.D.8.2.}} \right)$$

 $e^{\frac{(4\hbar\pi^2)^2}{2m_0L_z^2}t} = e^{\frac{(2\pi)^2}{2m_0L_z^2}} = e^{\frac{4\hbar\pi^2}{2m_0L_z^2}}$ him on Sign on Because of this, it will time compenent -> Because of this, it will is vnemy.

$$\frac{\partial \Psi}{\partial t} = i\alpha e^{i\alpha t} \sin(\beta z) \qquad \nabla \Psi = e^{i\alpha t} \beta \cos(\beta z) \rightarrow \nabla \Psi = e^{i\alpha t} (-\beta^2 \sin(\beta z))$$
$$= -e^{i\alpha t} \beta^2 \sin(\beta z)$$

$$-\frac{h^2}{2m_0}\left(-e^{-i\alpha t}\sin(\beta z)\beta^2\right) + Ve^{-i\alpha t}\sin(\beta z) = ih\left(i\alpha e^{-i\alpha t}\sin(\beta z)\right)$$

$$\frac{h^2}{2m_0}\beta^2 e^{i\alpha t} \sin(\beta z) + Ve^{i\alpha t} \sin(\beta z) = -h\alpha e^{i\alpha t} \sin(\beta z)$$

$$\frac{h^{2}}{2m_{o}}\left(\frac{2\pi}{L_{z}}\right)^{2} + V = -\frac{4\pi^{2}\pi^{2}}{2m_{o}L_{z}^{2}}$$

$$-When V = 0 - 4\pi^{2}\pi^{2}$$

$$\frac{4h^{2}\pi^{2}}{2m_{o}L^{2}} = -\frac{4h^{2}\pi^{2}}{2m_{o}L^{2}}$$

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$$V(z,t) = 2e^{-i\left(\frac{\hbar\pi^{2}}{2\pi_{0}L_{z}^{2}}\right)t} = -i\left(\frac{9\hbar\pi^{2}}{2\pi_{0}L_{z}^{2}}\right)t$$

$$= \sqrt{(z,t)} = 2e^{-i\left(\frac{\hbar\pi^{2}}{2\pi_{0}L_{z}^{2}}\right)t} = \sqrt{(z,t)} = 2e^{-i\left(\frac{\pi\pi^{2}}{2\pi_{0}L_{z}^{2}}\right)t} = \sqrt{2\pi_{0}L_{z}^{2}} = \sqrt{2\pi_{0}L_{z}^{2}}$$

$$= \sqrt{2\pi_{0}L_{z}^{2}} + \beta = \frac{\pi}{L_{z}}$$

$$= \sqrt{2$$

$$\nabla \psi = Ze \beta \cos(\beta z) - ie \beta \cos(\beta z)$$

$$-\frac{\hbar^{2}}{2m_{e}}\left(-2e^{-i\alpha t}\beta^{2}\sin(\beta z)+i9e^{-i9\alpha t}\beta^{2}\sin(3\beta z)\right)+V\left(-2e^{-i\alpha t}\beta^{2}\sin(\beta z)+i9e^{-i9\alpha t}\beta^{2}\sin(3\beta z)\right)$$

$$=i\hbar\left(-2i\alpha e^{-i\alpha t}\sin(\beta z)-9\alpha e^{-i9\alpha t}\sin(\beta\beta z)\right)$$

$$\frac{\hbar^2}{2m_0}\beta^2 - V\beta^2 = \hbar d$$

$$\frac{\hbar^2}{2\pi_0} \left(\frac{\pi}{L_z}\right)^2 = \hbar \left(\frac{\hbar \pi^2}{2\pi_0 L_z^2}\right)$$

$$\frac{h^2 \pi^2}{2 n_0 L_z^2} = \frac{h^2 \pi^2}{2 n_0 L_z^2}$$
 is a robotion

radians pea second

... if we make a linear superposition of two energy eigenstates with energies Ea ! E_b , the resulting probability distribution will oscillate at the frequency $\omega_{ab} = |E_a - E_b|_{\frac{1}{4}}$.

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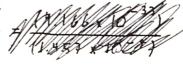
$$= \frac{\pi}{2m} \left(\frac{n \pi}{L_z} \right)^2, \quad n = 1, 2, \dots$$

$$= \frac{1}{2m} \left(\frac{nn}{L_z} \right) , n = 1, 2, \dots$$

 $\underbrace{\left\{\frac{J \cdot s}{l \cdot q \cdot m^2}\right\}}_{\left[\frac{kq \cdot m^2}{s^2}\right]} = \underbrace{\left\{\frac{kq \cdot m^2}{s^2}\right\}}_{\left[\frac{kq \cdot m^2}{s^2}\right]} = \underbrace{\left\{\frac{kq \cdot m^2}{s^2}\right\}}_{\left[\frac{k$

$$\omega_{13} = \frac{|E_{\bullet} - E_{\bullet}|}{t_0} = \frac{t_0^2 - t_0^2}{2mL_2^2} |n_{\alpha}^2 - n_{\delta}^2| \left(\frac{1}{t_0}\right) = \frac{t_0^2}{2mL_2^2} |n_{\alpha}^2 - n_{\delta}^2|$$

$$=\frac{8 \, \text{h} \, \pi^2}{2 \, \text{mLz}^2} = \frac{4 \, \text{h} \, \pi^2}{\text{mLz}^2} = \frac{4 \, (1.055 \times 10^{-34}) \, (3.142)^2}{ \left(9.109 \times 10^{-31}\right) \left(4 \times 10^{-10}\right)^2} + \frac{4 \, \text{h} \, \pi^2}{4 \, \text{h} \, \text{h} \, \text{h}^2}$$





I in radians per see

$$T = c_1 e^{-iE_1t/h} \sin\left(\frac{\pi}{L_*}z\right) + c_2 e^{-iE_2t/h} \sin\left(\frac{2\pi}{L_*}z\right) + c_3 e^{-iE_3t/h} \sin\left(\frac{3\pi}{L_*}z\right)$$

$$E_0 = \frac{\pi^2}{2m} \left(\frac{\pi n}{L_E}\right)^2 = \frac{\pi^2 \pi^2 n^2}{2m L_E^2}$$

$$\frac{1}{2mL_{2}^{2}} = \frac{\hbar^{2}\pi^{2}n^{2}}{2mL_{2}^{2}}$$

$$m_{e} = 9.11 \times 10^{-31} \text{ kg}$$

$$\Delta E_{31} = \hbar (\omega_{3} - \omega_{1})$$

$$3 \rightarrow 2$$
 $2 \rightarrow 1$
 $\Delta E_{32} = \hbar (\omega_3 - \omega_2)$

$$\Delta E_{2} = t_{1} (\omega_{2} - \omega_{1})$$

$$\omega_{31} = \frac{\Delta E_{31}}{\hbar} = \omega_{3} - \omega_{1} = \frac{\hbar \pi^{2}}{2\pi L_{2}^{2}} (3^{2} - 1^{2}) = 8 \frac{\hbar \pi^{2}}{2\pi L_{2}^{2}} \frac{1}{2\pi L_{2}$$

$$\omega_{32} = \frac{\Delta E_{32}}{\hbar} = \omega_3 - \omega_2 = \frac{\hbar \pi^2}{2mL_2^2} (3^2 - 4) = 5 \frac{\hbar \pi^2}{2mL_2^2}$$

$$\omega_{z_1} = \frac{\Delta E_{z_1}}{\hbar} = \omega_2 - \omega_1 = \frac{\hbar \pi^2}{2mL_z^2} \left(2^2 - 1^2 \right) = 3 \frac{\hbar \pi^2}{2mL_z^2} \frac{\hbar \pi^2}{4Nh k Not nown / s}$$

$$\frac{\ln \pi^2}{2mL_{\pi}^2} = 5.71 \times 10^{14} \text{ rads} / 5. \frac{1}{2\pi}$$

$$= 9.10 \times 10^{13} \text{ Hz}$$

$$\omega_{31} = 8(9.10 \times 10^{13} \text{ Hz}) = 7.28 \times 10^{14} \text{ Hz}$$

$$\omega_{32} = 5(9.10 \times 10^{13} \text{ Hz}) = 4.55 \times 10^{14} \text{ Hz}$$

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$$\omega_{21} = \frac{E_2 - E_1}{\hbar} = \frac{1}{\hbar} \left(\frac{\hbar^2 \pi^2 n_a^2}{2m L_z^2} - \frac{\hbar^2 \pi^2 n_b^2}{2m L_z^2} \right) = \frac{\hbar \pi^2}{2m L_z^2} \left(n_u^2 - n_b^2 \right)$$

$$| \omega_{21} = \frac{\pi^2}{\hbar} = \frac{1}{\hbar} \left(\frac{\hbar^2 \pi^2 n_a^2}{2m L_z^2} - \frac{\hbar^2 \pi^2 n_b^2}{2m L_z^2} \right) = \frac{\hbar \pi^2}{2m L_z^2} \left(n_u^2 - n_b^2 \right)$$

$$\hat{\rho} = -i\hbar \nabla$$

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$$\hat{\rho} = \int_{-iE_{+}}^{iE_{+}} \frac{1}{L_{z}} \int_{-iE_{+}}^{iE_{+}} \frac{1}{L$$

$$\begin{split} \left\langle \hat{\rho} \right\rangle &= -\frac{i \ln \pi}{L_{z}} \int_{0}^{L_{z}} sin \left(\frac{\pi}{L_{z}} \right) ds \left(\frac{\pi}{L_{z}} \right) ds - \frac{i \ln \pi}{L_{z}} \int_{0}^{L_{z}} sin \left(\frac{\pi}{L_{z}} \right) e^{-i \ln \pi} \int_{0}^$$

$$\begin{aligned} \langle \hat{p} \rangle &= -\frac{i h \pi}{L_{2}} \left(-\frac{4 L_{2}}{3 \pi} e^{-\frac{i (E_{1} - E_{2}) t / h}{3 \pi}} + \frac{4 L_{2}}{3 \pi} e^{-\frac{i (E_{2} - E_{1}) t / h}{3 \pi}} e^{-\frac{i (E_{2} - E_{1}) t / h}{3 \pi}} \right) \\ &= \frac{4}{3} h i \left(e^{i (E_{1} - E_{2}) t / h} - e^{-i (E_{1} - E_{2}) t / h} \right) - \frac{4}{3} h i \left(2 \sin \left(\frac{E_{1} - E_{2}}{h} t \right) \right) \\ &= \frac{4}{3} h i \left(e^{i (E_{1} - E_{2}) t / h} - e^{-i (E_{1} - E_{2}) t / h} \right) - \frac{4}{3} h i \left(2 \sin \left(\frac{E_{1} - E_{2}}{h} t \right) \right) \end{aligned}$$

$$\langle \hat{p} \rangle = \frac{8\pi}{3} i \sin \left(\frac{E_1 - E_2}{\pi} t \right)$$

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