

$$A = QR$$

create example: 2×2

choose $R = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$

choose $Q^T = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$

verify $Q^T Q = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

GIVEN $A = QR$, $Q = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$, $R = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$

FIND THE LEAST SQUARES SOLUTION OF $Ax = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

$$A = \begin{bmatrix} 0 & 0 \\ -1 & -1 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 3 \end{bmatrix} \quad \text{solve } Ax = b \text{ in mean square sense}$$

$$\|Ax - b\|^2 \rightarrow \min_x$$

not mal equation: $A^T A x = A^T b$

$$A^T A = \begin{bmatrix} 0 & -1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -3 \\ -3 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 0 & -1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -3 \\ -3 \end{bmatrix}$$

solution: any x_1, x_2 $x_1 + x_2 = -3$

$$x = x(t) = \begin{bmatrix} t \\ -3-t \end{bmatrix} \quad t \in \mathbb{R}$$

$\min_t \|x(t)\|$ "smallest least squares solution"

$$QRx = b$$

Q size $m \times m$
 R size $m \times m$ $m < n$

$$\|Qx - b\|^2 \rightarrow \min_x$$

$$\|Q u\|^2 = u^T Q^T Q u = u^T I u = u^T u = \|u\|^2$$

$$\|Q^T(QRx - b)\|^2 \rightarrow \min_x$$

$$Q^T Q = I$$

$$\|Rx - b\|^2 \rightarrow \min_x$$

$$\begin{bmatrix} \text{---} \\ \text{---} \end{bmatrix} \quad [x] = \begin{bmatrix} \Phi^T \\ \text{---} \end{bmatrix} b$$

$$\left\| \begin{bmatrix} R_1 \\ 0 \end{bmatrix} [x] - \begin{bmatrix} (Q^T b)_1 \\ (Q^T b)_2 \end{bmatrix} \right\|^2 \rightarrow \min$$

$$A = QR \quad Q = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \quad R = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad A = \begin{bmatrix} 0 \\ -1 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\begin{matrix} Q & R & x & = & b \\ \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} & \begin{bmatrix} 1 \\ 0 \end{bmatrix} & [x] & = & \begin{bmatrix} 2 \\ 3 \end{bmatrix} \end{matrix}$$

$$\begin{matrix} Q^T & Q & R \\ \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} & \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} & \begin{bmatrix} 1 \\ 0 \end{bmatrix} \end{matrix} [x] = \underbrace{\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}}_{= I} \underbrace{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}_{\begin{bmatrix} -3 \\ -2 \end{bmatrix}} \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

"in least squares sense"

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} [x] = \begin{bmatrix} -3 \\ -2 \end{bmatrix} \quad \begin{matrix} x = -3 \\ 0 = -2 \end{matrix} \quad \left\| \begin{matrix} x+3 \\ 2 \end{matrix} \right\|^2 \rightarrow \min$$

$$\min_x (x+3)^2 + 2^2 \Rightarrow x = -3$$

another example $A=QR$ $Ax=b$

$$Q = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad Q^T Q = I$$

$$R = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$$

$$\overset{Q}{\begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}} \overset{R}{\begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}} \overset{x}{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}} = \overset{b}{\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}}$$

$$\overset{Q^T}{\begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}} \overset{Q}{\begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}} \overset{R}{\begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}} \overset{x}{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}} = \overset{b}{\begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}} \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$$

$$R \quad x \quad Q^T b$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2 \\ 4 \\ 3 \end{bmatrix}$$

$$\min 0 \quad \boxed{x_2 = 4}$$

$$\left\| \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} -2 \\ 4 \end{bmatrix} \right\|^2$$

$$\boxed{x_1 = -10 \quad x_2 = 4}$$

$$+ \left\| \begin{bmatrix} 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} 3 \end{bmatrix} \right\|^2 \rightarrow \min$$

always 3^2

$$x_1 + 2x_2 = -2$$

$$x_1 = -2 - 2x_2$$

$$= -2 - 2 \cdot (4) = -10$$

$$-10 + 2 \cdot 4 = -2$$

$$f(x, y) = x^2 + y^2 + \cos(xy) \rightarrow \min_{(x, y)} \quad \text{start } \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$1^\circ \quad \nabla f(x, y) = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} = \begin{bmatrix} 2x - y \sin(xy) \\ 2y - x \sin(xy) \end{bmatrix} = g$$

$$2^\circ \quad \min f\left(\begin{bmatrix} x \\ y \end{bmatrix} - \alpha g\right) \quad \begin{bmatrix} x \\ y \end{bmatrix} - \alpha \begin{bmatrix} 2x - y \sin(xy) \\ 2y - x \sin(xy) \end{bmatrix} \quad \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{solve } \min_{\alpha} f\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} - \alpha \begin{bmatrix} 2 \\ 0 \end{bmatrix}\right)$$

$$g = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$\min_{\alpha} \underbrace{(1 - 2\alpha)^2}_{x^2} + 0 + \underbrace{\cos((1 - 2\alpha) \cdot 0)}_{y^2} \Rightarrow \alpha = \frac{1}{2}$$

$$\text{new} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$f(x, y) = x^2 + y^2 + \cos(xy)$$

$$\nabla f = 0$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} - \underbrace{H_f^{-1}(x, y) \nabla f(x, y)}_u$$

H_f

Solve for
increment u

$$1^0 \quad H_f(x, y) u = \nabla f(x, y)$$

$$2^0 \quad \begin{bmatrix} x \\ y \end{bmatrix} \leftarrow \begin{bmatrix} x \\ y \end{bmatrix} - u$$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} = \begin{bmatrix} 2x - y \sin(xy) \\ 2y - x \sin(xy) \end{bmatrix}$$

$$H_f = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 2 - y^2 \cos(xy) & -x \sin(xy) \\ -x \sin(xy) & 2 - x^2 \cos(xy) \end{bmatrix}$$

1D $x \leftarrow x - \frac{1}{H_f} \nabla f(x)$