

ENG EK103: Problem Set 10 (Spring 2025) Due: Before 11:59pm, April 17, 2025

Use MATLAB only to check your answers. **No Explanation = No Credit.** For each problem, all solution steps should be written down and explained clearly.

Bold lowercase letter (such as \mathbf{v}) represents a vector. Uppercase letter (such as A) represents a matrix.

Q1 (Markov Chains)

In this problem, we are interested in exploring a *Markov Chain* for a population \mathcal{P} whose members at any given time k (where $k=0,1,2,\dots$) belong to one of three states: S_1, S_2 or S_3 . Let the state vector for the given Markov Chain at any particular time k be denoted by \mathbf{x}_k .

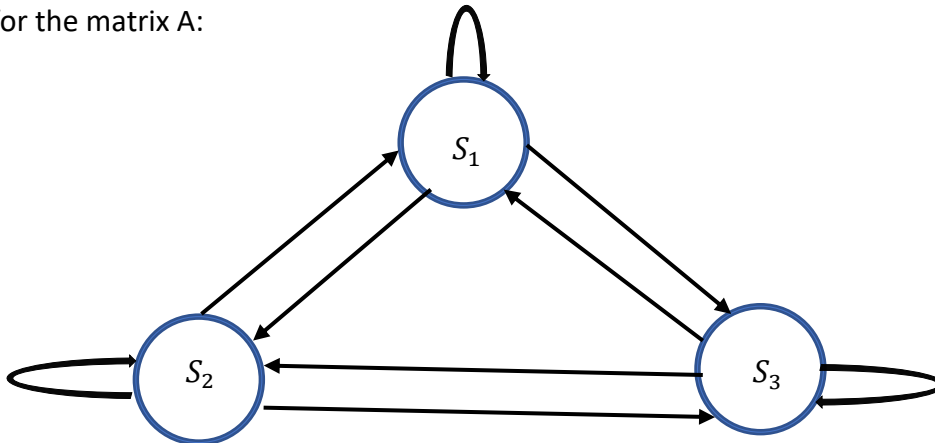
$$\mathbf{x}_k = \begin{bmatrix} a_k \\ b_k \\ c_k \end{bmatrix}$$

Here, a_k denotes the proportion (a real number between 0 and 1) of the population \mathcal{P} that belongs to state S_1 at time k , b_k denotes the proportion of the population \mathcal{P} that belongs to state S_2 at time k , and c_k denotes the **proportion** of the population \mathcal{P} that belongs to state S_3 at time k . Note that since each state vector represents the distribution of the population among the three states, each state vector is a *probability vector* (the sum of its elements is 1).

For our Markov Chain, it is also given that:

$$\mathbf{x}_{k+1} = \begin{bmatrix} 0.6a_k + 0.2b_k + \alpha c_k \\ 0.2a_k + \beta b_k + 0.2c_k \\ \gamma a_k + 0.2b_k + 0.6c_k \end{bmatrix}$$

- (a) Determine the 3×3 *state transition matrix* A for the given Markov Chain, so that $\mathbf{x}_{k+1} = A\mathbf{x}_k$. You may use the constants α, β , and γ as some of the elements within the matrix A .
- (b) For the matrix A you just determined, we can draw a *Markov Diagram* (also known as a state transition diagram) for the given Markov Chain. Here is a first cut at the diagram for the matrix A :



Here, the circles represent the three different states, each arrow represents a transition from a state (at the arrow's tail) at time k to a state (at the arrow's tip) at time $k + 1$. The only thing missing is the labels on the arrows indicating the corresponding transition probabilities. Please complete the diagram by placing the appropriate label near each arrow; You may use the constants α, β , and γ as some of the labels in the diagram.

- (c) Given that the state transition matrix for any Markov Chain is a *stochastic matrix* (whose columns are *probability vectors*), determine the numerical values of the constants α, β , and γ .
- (d) Show that $|A - \lambda I| = (\lambda - 1)(-\lambda^2 + 0.8\lambda - 0.16)$
- (e) Determine all three eigenvalues of A . Note that $\lambda = 1$ is the “dominant” eigenvalue in the sense that it is the one with the largest magnitude among all the eigenvalues of A .
- (f) Explain why the matrix A is diagonalizable and thus can be written as $A = PDP^{-1}$ where the diagonal matrix D holds the eigenvalues of A and the columns of the matrix P are independent eigenvectors of the matrix A .
- (g) What are the eigenvalues of A^k ? (HINT: From lecture, if $A = PDP^{-1}$ then we can conclude that $A^k = PD^kP^{-1}$)
- (h) What happens to the eigenvalues of A^k as $k \rightarrow \infty$? (HINT: all the eigenvalues of A^k go to zero except the dominant eigenvalue. In fact, this property forms a foundation of what is known in linear algebra as the *Power Method* for determining the dominant eigenvalue and the corresponding eigenspace).
- (i) As $k \rightarrow \infty$, determine the fraction of the population \mathcal{P} that ends up in state S_1 . (HINT: You can perform RREF on the matrix $A - I$ and solve for the eigenspace corresponding to the dominant eigenvalue ($\lambda = 1$) of A . Then pick the *only* member of that eigenspace that is also a probability vector. This vector represents the final state vector (as $k \rightarrow \infty$) of the Markov Chain, regardless of the initial state vector x_0).

Q2

In this problem, we are going to explore the *projections* of the vector $v = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ onto two different vector spaces of \mathbb{R}^3 :

- Vector subspace S_1 with a basis set specified as $\left\{ \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \right\}$.
- Vector subspace S_2 with a basis set specified as $\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \right\}$.

- (a) Determine the *Projection Matrix* P_1 that maps any vector in \mathbb{R}^3 onto the vector subspace S_1 .

- (b) Apply the matrix P_1 to the vector \mathbf{v} given at the beginning of this problem to obtain a vector $\mathbf{w}_1 = P_1 \mathbf{v}$.
- (c) What is the *shortest distance* between the (tip of the) vector \mathbf{v} and (the tip of) any vector in the subspace S_1
- (d) Determine the *Projection Matrix* P_2 that maps any vector in \mathbb{R}^3 onto the vector subspace S_2 .
- (e) Apply the matrix P_2 to the vector \mathbf{v} given at the beginning of this problem to obtain a vector $\mathbf{w}_2 = P_2 \mathbf{v}$.
- (f) What is the *shortest distance* between the (tip of the) vector \mathbf{v} and (the tip of) any vector in the subspace S_2 ?

Q3

In this problem, we explore the *projection* of the vectors $\mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 4 \\ 4 \end{bmatrix}$ and $\mathbf{w} = \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$ onto the

vector subspace S that has the basis set specified as $\left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\}$.

- (a) Determine the *Projection Matrix* P that maps any vector in \mathbb{R}^4 onto the vector subspace S .
- (b) Show that the vector \mathbf{v} belongs to the subspace S .
- (c) Apply the matrix P to the vector \mathbf{v} given at the beginning of this problem. Explain how your result makes sense in light of what you showed in the previous part of this problem.
- (d) Show that the vector \mathbf{w} is orthogonal to every vector in the subspace S
- (e) Apply the matrix P to the vector \mathbf{w} given at the beginning of this problem. Explain how your result makes sense in light of what you showed in the previous part of this problem.



See Problem 4 on the next page !!

**** You will need the 2 *.mat data files for Problem 4(b):**

File #1: `AA_test.mat` = Contains 6 matrices of size (3x3)
 = You should use this to test your code out

File #2: `AA_homework.mat` = Contains 100 matrices of size (3x3)
 = Use this for your homework submission

4 Q4: Matlab application

NOTE: PROBLEM 4 REQUIRES TWO SEPARATE CODE SUBMISSIONS, ONE FOR (a) AND ONE FOR (b).

a) Using `eig()` and `rank()` (do not use `inv()`), write a MATLAB function that takes any square matrix and:

- computes its eigenvalues and eigenvectors
- checks if it is diagonalizable
- returns the tuple $(\mathbf{P}, \mathbf{D}, \text{isDiagonalizable})$, where `isDiagonalizable` is `true` if \mathbf{P}^{-1} exists, and `false` otherwise.

Publish this Matlab script (see below for script scaffold).

```
====(BEGIN PUBLISHABLE FUNCTION SCRIPT)====
```

```
[a,b,c] = yourFunctionNameHere(A);
```

```
display(a)
display(b)
display(c)
```

```
% We will count off points if your function name isn't renamed to be appropriate AND if
this boilerplate comment isn't replaced by a descriptive comment.
```

```
function [...] = yourFunctionNameHere(A)
```

end

```
====(END PUBLISHABLE FUNCTION SCRIPT)====
```

b) Using the `*.mat` data files we provided, write a Matlab function which

- calls your prior function from **part (a)** above
- loops over all matrices
- sums together the eigenvalues of **only the diagonalizable** matrices.

(continue on the nest page !!!!)----->>>>>>>

For instance, if the eigenvalues of the first matrix were [1,2], the second were [3,4,5], *but it were not diagonalizable*, and the third were [-1,5,10,22] then the answer would be 39 (i.e. $1+2+(-1)+5+10+22$).

NOTE: You will need to use `cell` notation to extract the individual matrices. This is straightforward: to access the first matrix in the cell array, you'll write `A = AA{1}`, for the second one `A = AA{2}`, and so on...

In a brand new script, copy the code from (a) and adapt it. **Publish this script**, using the code scaffold below.

```
====(BEGIN PUBLISHABLE FUNCTION SCRIPT)====
```

```
runningSum = 0;
```

```
for ..  
:  
end
```

```
display(runningSum)
```

```
% We will count off points if your function name isn't renamed to be appropriate AND if  
this boilerplate comment isn't replaced by a descriptive comment.
```

```
function [...] = yourFunctionNameHere(A)  
:  
end
```

```
====(END PUBLISHABLE FUNCTION SCRIPT)====
```