

Q1

A

$$\begin{aligned}
\begin{bmatrix} 0 & 0 & 1 & 1 & 2 & 4 \\ 1 & 1 & 2 & 3 & 4 & 11 \\ 1 & 1 & -3 & -2 & -6 & -9 \end{bmatrix} &\xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} 1 & 1 & -3 & -2 & -6 & -9 \\ 1 & 1 & 2 & 3 & 4 & 11 \\ 0 & 0 & 1 & 1 & 2 & 4 \end{bmatrix} \xrightarrow{R_2 = R_2 - R_1} \begin{bmatrix} 1 & 1 & -3 & -2 & -6 & -9 \\ 0 & 0 & 5 & 5 & 10 & 20 \\ 0 & 0 & 1 & 1 & 2 & 4 \end{bmatrix} \\
&\xrightarrow{R_3 = R_3 - \frac{1}{5}R_2} \begin{bmatrix} 1 & 1 & -3 & -2 & -6 & -9 \\ 0 & 0 & 5 & 5 & 10 & 20 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} = REF(A')
\end{aligned}$$

B

$$\begin{bmatrix} \textcircled{1} & 1 & -3 & -2 & -6 & -9 \\ 0 & 0 & \textcircled{5} & 5 & 10 & 20 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Column	Type
1	Pivot
2	Free Variable
3	Pivot
4	Free Variable
5	Free Variable

C

$$\xrightarrow{R_2 = \frac{1}{5}R_2} \begin{bmatrix} 1 & 1 & -3 & -2 & -6 & -9 \\ 0 & 0 & 1 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 = R_1 + 3R_2} \begin{bmatrix} 1 & 1 & 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} = RREF(A')$$

D

Assigning free variables to free columns:

$$x_2 = t_2$$

$$x_4 = t_4$$

$$x_5 = t_5$$

Then from $RREF(A')$

$$x_1 = 3 - t_2 - t_4$$

$$x_3 = 4 - t_3 - 2t_5$$

So the complete solution is

$$\vec{x}_c = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 4 \\ 0 \\ 0 \end{bmatrix} + t_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + t_4 \begin{bmatrix} -1 \\ 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} + t_5 \begin{bmatrix} 0 \\ 0 \\ -2 \\ 0 \\ 1 \end{bmatrix}$$

E

Since there are 3 linearly independent vectors in \mathbb{R}^5 corresponding to 3 free variables in the homogeneous part of the solution, the set of all possible solutions \vec{x}_c spans a 3 dimensional solid or subspace in \mathbb{R}^5 .

F

Any given 3×5 matrix B where $B\vec{x} = \vec{b}$ is consistent will yield an infinite set of solutions, since the number of pivots cannot exceed the number of rows, which is 3 in this case, which implies that the solution will have a minimum of 2 free variables, and therefore a non-unique solution set.

Q2

A

One solution to $A\vec{x} = 0$ is always $\vec{x} = \vec{0}$, which is the trivial solution. So yes, regardless of the value of p , it will have at least one solution, the trivial one.

B

$$\begin{aligned}
 R_2 &= R_2 + \frac{5}{3}R_1 \\
 R_3 &= R_3 - \frac{8}{3}R_1 \\
 R_4 &= R_4 + \frac{1}{3}R_1
 \end{aligned}
 \begin{bmatrix} 3 & 0 & 1 & 5 \\ -5 & 1 & 1 & -2 \\ 8 & -1 & 0 & 7 \\ -1 & 2 & p & 11 \end{bmatrix}
 \xrightarrow{\quad}
 \begin{bmatrix} 3 & 0 & 1 & 5 \\ 0 & 1 & \frac{8}{3} & \frac{19}{3} \\ 0 & 0 & 0 & 0 \\ 0 & 2 & p + \frac{1}{3} & \frac{38}{8} \end{bmatrix}
 \xrightarrow{R_4=R_4-2R_2}
 \begin{bmatrix} 3 & 0 & 1 & 5 \\ 0 & 1 & \frac{8}{3} & \frac{19}{3} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & p-5 & 0 \end{bmatrix}
 \xrightarrow{R_3 \leftrightarrow R_4}
 \begin{bmatrix} 3 & 0 & 1 & 5 \\ 0 & 1 & \frac{8}{3} & \frac{19}{3} \\ 0 & 0 & p-5 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

C

If $A\vec{x} = b$ is consistent and \vec{x}_c is a line in \mathbb{R}^3 , then the SLE must have one free variable. Therefore

$$\begin{aligned}
 p - 5 &= 0 \\
 p &= 5
 \end{aligned}$$

Then the new $REF(A')$ is

$$\begin{bmatrix} 3 & 0 & 1 & 5 \\ 0 & 1 & \frac{8}{3} & \frac{19}{3} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

D

$$\xrightarrow{R_1 = \frac{1}{3}R_1}
 \begin{bmatrix} 1 & 0 & \frac{1}{3} & \frac{5}{3} \\ 0 & 1 & \frac{8}{3} & \frac{19}{3} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

E

Since there is a free variable column for x_3 we assign it to the scalar t_3 . Then the solutions are

$$\begin{aligned}
 x_1 &= \frac{5}{3} - \frac{1}{3}t_3 \\
 x_2 &= \frac{19}{3} - \frac{8}{3}t_3 \\
 x_3 &= t_3
 \end{aligned}$$

And therefore the complete solution, a line in \mathbb{R}^3 , is

$$x_c = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{5}{3} \\ \frac{19}{3} \\ 0 \end{bmatrix} + t_3 \begin{bmatrix} -\frac{1}{3} \\ -\frac{8}{3} \\ 1 \end{bmatrix}$$

2

F

No, $B\vec{x} = b$ is not guaranteed to have an infinite number of solutions as there can be one pivot per column in the B matrix, and therefore only a particular solution