

ENG EK 103: Computational Linear Algebra: Problem set 8

**** Remember:** You can use matlab to check all of your handwritten answers !!! =>

Matlab commands

- To check your eigenvalues / eigenvectors :

```
[V, LAMBDA] = eig(A)
```



This commands is uber-useful for your engineering career !! =>



Note: The purpose of problems 1 thru 4

Each of those 4 matrices A , B , C , and D exhibit different, subtle “flavors,” such the # of repeated eigenvalues present in the problem, whether you need synthetic division to solve for them, the different kinds of reduced-row echelon forms you might see when you’re solving for the eigenvectors, etc...

*It may seem like a lot of busy-work, but we would like yall to get used to solving for the eigenvalues / eigenvectors such that **these kinds of problems will become “second nature” for you** when you’re taking both midterm #2 and the final exam ! =>*

Problem 1: Suppose you were given matrix A :

$$A = \begin{bmatrix} 2 & -1 & -2 \\ 0 & 1 & -2 \\ 0 & -2 & 1 \end{bmatrix}$$

(a) Find the eigenvalues and their corresponding eigenvectors for this matrix.

*Hint: Depending on how you're evaluating the determinant $[A - \lambda I]$, you might have to use **synthetic division** to find the eigenvalues. If that's the case, here is a website that will teach you how to do this !*

https://www.wtamu.edu/academic/anns/mps/math/mathlab/col_algebra/col_alg_tut37_syndiv.htm



(b) Hand-calculate the determinant of A .

(c) On paper, verify this really cool property (it is true for any square matrix A of any size):

$$\det(A) = \text{The product of the eigenvalues of } A$$

(d) If you had used matlab's `[V, D] = eig(A)` command to calculate the eigenvalues and eigenvectors of matrix A , matlab will give you this answer:

$$V = \begin{bmatrix} 1. & 0.5774 & 0.5774 \\ 0 & 0.5774 & 0.5774 \\ 0 & -0.5774 & 0.5774 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

- Do the columns within the eigenvector matrix V match your hand-calculated eigenvectors ?
- Using 1 or 2 sentences, explain why matlab reported each eigenvectors in a decimal format like this (as opposed to giving you whole number entries).

Problem 2: Suppose you were given matrix B :

$$B = \begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 2 & -1 & 0 \end{bmatrix}$$

(a) Find the eigenvalues and their corresponding eigenvectors for this matrix.

(b) If you had used matlab's `[V, D] = eig(B)` command to calculate the eigenvalues and eigenvectors of matrix B , matlab will give you this answer:

$$V = \begin{bmatrix} -0.5774 & -0.1348 & 0.2487 \\ -0.5774 & -0.8224 & -0.3894 \\ -0.5774 & -0.5527 & -0.8868 \end{bmatrix}, \quad D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

- Does the columns within the eigenvector matrix V match your hand-calculated eigenvectors? If there are eigenvectors do match your hand-written answers, identify those vectors (and tell me which eigenvalue(s) are associated with those eigenvectors).
- What about the eigenvectors that do not match your hand-written answers? Which eigenvalue(s) are associated with those eigenvectors?

**** Moral of the story:** 1) When you have **repeated eigenvalues**
 2) You want to be careful on trusting matlab's answers for those eigenvectors !! =\



Problem 3: Suppose you were given matrix C :

$$C = \begin{bmatrix} -2 & 7 & 1 \\ 2 & 0 & -2 \\ -8 & 11 & 7 \end{bmatrix}$$

Find the eigenvalues and their corresponding eigenvectors for this matrix.

Hint #1: Again, if you were unlucky and picked a difficult row or column to perform cofactor expansions, you might need synthetic division to evaluate the eigenvalues.

Hint #2: For this homework, you can also use matlab's `roots()` function to find the roots of the cubic polynomial.

Problem 4: Suppose you were given matrix D :

$$D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

(a) Find the eigenvalues and their corresponding eigenvectors for this matrix.

(b) If you had used matlab's `[V, D] = eig(D)` function to calculate the eigenvalues and eigenvectors of matrix D , matlab will give you this answer:

$$V = \begin{bmatrix} 1.0000 & 0 & 0 \\ 0 & 1.0000 & -1.0000 \\ 0 & 0 & 0.0000 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

- So apparently, matlab says matrix D possess 3 eigenvectors. Does the number of eigenvectors matches what you got from your hand-derived calculations ?

**** Moral of the story:**

- 1) *Matlab's `eig()` command will sometimes give you super-weird + unexpected results !! =(=(*
- 2) *Trivia: You don't have to know this, but matlab is giving you 3 "eigenvectors" because it is calculating the eigenvectors of a cousin of matrix D sometimes called the "Jordan form" of matrix D . Google this if you want to know more about it =)*
- 3) ***You REALLY need to be careful** when you're using the `eig()` function !! Never trust it 100% without first thinking about the computer-derived answers.*

Problem 5: Eigenvalues, eigenvectors, and geometrical transformations

Download the matlab file called `Problem5_transformation.m` . This script will generate a 3D plot of the following:

Given: Transformation matrix A and an unit cube X , where X is a matrix containing the x, y, z-coordinates of the 8 vertices of the cube (with 3 of the 6 faces shaded in *opaque* yellow, green, and blue)

Output: The script will plot the original cube X and the post-transformed image $Y = AX$ (with the 3 corresponding faces shaded in *semi-transparent* yellow, blue, and green).

(a) Run the code with the default transformation:

$$A = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

and observe the shape of the post-transformed object $Y = AX$. Feel free to explore by zooming in and rotate the object in the output figure! You don't have to publish the results from part (a), but you will have to publish the results from part (b) below.

(b) Then, in the code, **change matrix A** (Lines 8 thru 10 in the code) into this one:

$$A = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

Rotate the object such that it is in a presentable 3D orientation. **Publish the plot, the matlab code, and the command window outputs** and turn it in with your homework.

(c) In 2 or 3 sentences, tell me: Why does the post-transformed object looks like a **"flattened 2D pancake"** in 3D space?

Hint: In your matlab command window, examine the reported eigenvalues + the eigenvectors of A carefully... =)