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COEN 242 HW 1: Dijkstra's Algorithm

Code:

```
def Dijkstra(G, start, end=None):
    D = {} # Distance vec
    P = {} # Predecessor Vec
    Q = priorityDictionary() # estimated distances of non-final vertices
    Q[start] = 0

    for v in Q:
        D[v] = Q[v]
        if v == end:
            break

        for x in G[v]:
            length = D[v] + G[v][x]
            if x in D:
                if length < D[x]:
                    raise ValueError("Already found better path to final
vertex")
            elif x not in Q or length < Q[x]:
                Q[x] = length
                P[x] = v

    return (f'D: {D}, P: {P}')
```

Code for Priority Dictionary
Source: <https://code.activestate.com/recipes/117228/>

```
class priorityDictionary(dict):
    def __init__(self):
        self.__heap = []
        dict.__init__(self)

    def smallest(self):
        if len(self) == 0:
            raise IndexError
        heap = self.__heap
```

```

while heap[0][1] not in self or self[heap[0][1]] != heap[0][0]:
    lastItem = heap.pop()
    insertionPoint = 0
    while 1:
        smallChild = 2*insertionPoint+1
        if smallChild+1 < len(heap) and \
            heap[smallChild] > heap[smallChild+1]:
            smallChild += 1
        if smallChild >= len(heap) or lastItem <=
heap[smallChild]:
            heap[insertionPoint] = lastItem
            break
        heap[insertionPoint] = heap[smallChild]
        insertionPoint = smallChild
    return heap[0][1]

def __iter__(self):
    def iterfn():
        while len(self) > 0:
            x = self.smallest()
            yield x
            del self[x]
    return iterfn()

def __setitem__(self, key, val):
    dict.__setitem__(self, key, val)
    heap = self.__heap
    if len(heap) > 2 * len(self):
        self.__heap = [(v, k) for k, v in self.iteritems()]
        self.__heap.sort()
    else:
        newPair = (val, key)
        insertionPoint = len(heap)
        heap.append(None)
        while insertionPoint > 0 and \
            newPair < heap[(insertionPoint-1)//2]:
            heap[insertionPoint] = heap[(insertionPoint-1)//2]
            insertionPoint = (insertionPoint-1)//2
        heap[insertionPoint] = newPair

```

```

def setdefault(self, key, val):
    if key not in self:
        self[key] = val
    return self[key]

# Output
G = {'1': {'2':1, '3':2},
     '2': {'3':5, '4':7},
     '3': {'4':1, '5':2},
     '4': {'6':2},
     '5': {'3':8, '4':3, '6':5},
     '6': {'4': 9}}

print(Dijkstra(G, '1'))

```

Output:

```

D: {'1': 0, '2': 1, '3': 2, '4': 3, '5': 4, '6': 5}
P: {'2': '1', '3': '1', '4': '3', '5': '3', '6': '4'}

```