# Computational Finance



### **Binomial Trees**

## **Setup and Notation**

- Consider a market containing three assets: a risk-free bond with price  $B_t = e^{rt}$ , a stock  $S_t$ , and a (European style) derivative  $C_t$  with maturity T and payoff  $C_T(S_T)$  that we wish to price.
- Split the time interval [0, T] into N parts of length  $\delta t = T/N$  and let  $t_i = i\delta t$ ,  $i = 0, \ldots, N$ , so  $t_0 = 0$  and  $t_N = T$ .
- Write  $\{B_i, S_i, C_i, i = 0, ..., N\}$  for asset prices at time  $t_i = i\delta t$ . E.g.,  $C_1 \equiv C_{\delta t}$ ,  $C_N \equiv C_T$ , and  $B_i = e^{r i\delta t}$ .
- The stock price  $S_i$  either moves up to  $S_{i+1}(u)$  or down to  $S_{i+1}(d)$ . Usually  $S_{i+1}(u) = S_i u$  and  $S_{i+1}(d) = S_i d$  for fixed u and d, often u = 1/d.

#### The One-Period Case: N=1.

• To find  $C_0$ , construct a replicating portfolio  $V_t = \phi S_t + \psi B_t$  in such a way that

$$V_T(u) = \phi S_0 u + \psi B_0 e^{rT} = C(S_0 u) =: c_u,$$
  
$$V_T(d) = \phi S_0 d + \psi B_0 e^{rT} = C(S_0 d) =: c_d.$$

• Solving for  $\phi$  and  $\psi B_0$  yields

$$\phi = \frac{c_u - c_d}{S_0 u - S_0 d}, \quad \psi B_0 = e^{-rT} \left( c_u - \frac{c_u - c_d}{S_0 u - S_0 d} S_0 u \right).$$

ullet  $\phi$  is known as the *hedge ratio*, or *delta* of the derivative.

• Therefore,

$$V_{0} = \phi S_{0} + \psi B_{0}$$

$$= \frac{c_{u} - c_{d}}{u - d} + e^{-rT} \left( c_{u} - \frac{c_{u} - c_{d}}{u - d} u \right)$$

$$= e^{-rT} \left( c_{u} \frac{e^{rT} - d}{u - d} + c_{d} \frac{u - e^{rT}}{u - d} \right)$$

$$= e^{-rT} \left( c_{u} p + c_{d} [1 - p] \right).$$

• In the absence of arbitrage, we must have  $C_0 = V_0$ , and hence  $C_0 = e^{-rT} \left( c_u p + c_d [1-p] \right)$ .

- Interpretation:  $p \in [0, 1]$ , so p is a probability and  $C_0$  is an expectation.
- p and 1-p are known as risk-neutral probabilities. We collect these in the risk-neutral probability measure  $\mathbb{Q}$ , so that  $\mathbb{Q}[u]=1-\mathbb{Q}[d]=p$ .
- We write

$$C_0 = e^{-rT} \mathbb{E}^{\mathbb{Q}}[C_T] = e^{-rT} (c_u p + c_d [1 - p]).$$

• The probabilities are called risk-neutral because if these were the true probabilities, all assets would earn the risk-free rate. E.g., you should verify that

$$\mathbb{E}^{\mathbb{Q}}[S_T] = S_0 e^{rT}.$$

• Note that we do not assume that  $p = \mathbb{P}[u]$ . The actual probability  $\mathbb{P}[u]$  is irrelevant for the value  $C_0$  of the derivative (as long as it is not zero or one).

# The *N*-Period Case

• Next, consider a two-period model (N=2):

$$t = 0 t = \delta t t = T = 2\delta t$$

$$i = 0 i = 1 i = N = 2$$

$$S_0 u S_0 u$$

$$S_0 S_0 u S_0 ud = S_0 du$$

$$S_0 d S_0 dd$$

- This stock price tree is *recombinant*: an up move followed by a down move leads to the same value as a down move followed by an up move. This is a consequence of u and d being fixed and independent of the price.
- Advantage: the number of nodes remains managable (N+1 at the Nth step, rather than  $2^N$ ).
- This leads to a derivative price tree that is also recombinant. Given a recombinant stock price tree, this follows from the fact that  $C_N$  only depends on  $S_N$ .
- Path-dependent derivatives where  $C_N = C(S_i, i \leq N)$  may lead to non-recombinant trees.

$$C_{N}(uu)$$

$$C_{1}(u)$$

$$C_{1}(u)$$

$$C_{N}(ud) = C_{N}(du)$$

$$C_{1}(d)$$

$$C_{N}(dd)$$

- Only the payoffs  $C_N(uu)$ ,  $C_N(ud)$  and  $C_N(dd)$  are known, and we wish to obtain  $C_0$ ,  $C_1(u)$  and  $C_1(d)$ .
- At time  $t = \delta t$  (after one step), we know whether the stock has gone up or down.
- If it has gone up, then only the branch from  $C_1(u)$  to  $C_N(uu)$  or C(ud) is relevant.
- Since this is just a binary model, we can price  $C_1(u)$  (and  $C_1(d)$ ) by no-arbitrage:

$$C_1(u) = e^{-r \,\delta t} \left[ C_N(uu)p + C_N(ud)(1-p) \right] = e^{-r \,\delta t} \mathbb{E}^{\mathbb{Q}} \left[ C_N | S_1 = S_0 u \right],$$
  

$$C_1(d) = e^{-r \,\delta t} \left[ C_N(du)p + C_N(dd)(1-p) \right] = e^{-r \,\delta t} \mathbb{E}^{\mathbb{Q}} \left[ C_N | S_1 = S_0 d \right].$$

• Recall that  $p=\frac{e^{r\,\delta t}-d}{u-d}$ ; in general the risk-neutral probability might depend on  $S_1$ , but in this case it doesn't, because r,u and d are the same at each step.

- The values  $C_1(u)$  and  $C_1(d)$  are the market prices (under the no-arbitrage condition), so the derivative can be sold at this price at time  $t = \delta t$ , depending on whether the stock goes up or down.
- Therefore, at time t=0 we know that the two possible payoffs in the next period are  $C_1(u)$  and  $C_1(d)$ , and so

$$C_{0} = e^{-r \delta t} \left[ C_{1}(u)p + C_{1}(d)(1-p) \right]$$

$$= e^{-rT} \left[ C_{N}(uu)p^{2} + C_{N}(ud)[p(1-p) + (1-p)p] + C_{N}(dd)(1-p)^{2} \right]$$

$$= e^{-rT} \mathbb{E}^{\mathbb{Q}} \left[ C_{N} \right].$$

• In the N-period case, denote by  $\mathcal{F}_t$  the information at time t, i.e., whether the stock went up or down at each  $s \leq t$ . Then, at each step in the tree,

$$C_t = e^{-r\delta t} \mathbb{E}^{\mathbb{Q}}[C_{t+\delta t} | \mathcal{F}_t].$$

- Starting at  $C_T$ , this can be solved backwards until one arrives at the price at t=0.
- At every step in the tree, we have that

$$C_t = e^{-r(T-t)} \mathbb{E}^{\mathbb{Q}}[C_T | \mathcal{F}_t],$$

and in particular

$$C_0 = e^{-rT} \mathbb{E}^{\mathbb{Q}}[C_T].$$

• This is known as the *risk neutral pricing formula*: the price of an attainable European claim equals the expected discounted payoff, but where expectations are under a set of risk-neutral probabilities  $\mathbb{Q}$ .

- It is worth noting that the hedging strategy is dynamic: let  $\phi_{i+1}$  and  $\psi_{i+1}$  denote the number of shares and cash bonds held from  $t_i$  till  $t_{i+1}$ .
- The single-period binary model implies

$$\phi_{i+1} = \frac{C_{i+1}(u) - C_{i+1}(d)}{S_{i+1}(u) - S_{i+1}(d)}.$$

- Between  $t_i$  and  $t_{i+1}$ , the value changes from  $V_i$  to  $\phi_{i+1}S_{i+1} + \psi_{i+1}B_{i+1}$ , after which rebalancing occurs.
- The strategy is replicating: after N steps, the value is  $V_N = \phi_N S_N + \psi_N B_N = C_N$ .
- It can also be verified to be self-financing:

$$V_i = \phi_i S_i + \psi_i B_i = \phi_{i+1} S_i + \psi_{i+1} B_i$$

which may be rewritten as

$$V_{i+1} - V_i = \phi_{i+1}(S_{i+1} - S_i) + \psi_{i+1}(B_{i+1} - B_i).$$

ullet Thus, a dynamic strategy allows us to hedge against more than two states at time T with only two assets.

## Martingales and the FTAP

- A sequence of random variables such as  $\{S_i\}_{i\geq 0}$  is called a *stochastic process*.
- Observe that under Q,

$$\mathbb{E}^{\mathbb{Q}}\left[S_{i+1}|\mathcal{F}_i\right] = S_i\left(up + d(1-p)\right) = S_ie^{r\delta t}.$$

• Define the discounted stock price process  $\tilde{S}_i = S_i e^{-ir\delta t}$ . Then

$$\mathbb{E}^{\mathbb{Q}}\left[\tilde{S}_{i+1}|\mathcal{F}_i\right] = S_i e^{r\delta t} e^{-(i+1)r\delta t} = S_i e^{-ir\delta t} = \tilde{S}_i.$$

This is the defining property of a martingale. Hence, the risk-neutral measure is also called a martingale measure.

- $\mathbb{Q}$  and  $\mathbb{P}$  are equivalent if  $\mathbb{Q}[A] = 0 \iff \mathbb{P}[A] = 0$ .
- Fundamental Theorem of Asset Pricing: if (and only if) the market is arbitrage free, then there exists an equivalent martingale measure  $\mathbb Q$  under which discounted stock prices are martingales, and the risk neutral pricing formula holds.  $\mathbb Q$  is unique if the market is complete.

#### **Tree Calibration**

- We are given  $S_0$ , T (measured in years), and the function  $C_T = C(S_T)$ ; for a European call,  $C(S_T) = \max\{(S_T K), 0\}$ .
- We have to choose the number N of steps, and hence  $\delta t = T/N$ . This involves a trade-off between computational burden and accuracy.
- $r = \log(1 + R)$ , where R is the current value (per annum) of a suitable risk-free interest rate (e.g. LIBOR) over the holding period of the option.
- u and d are chosen to match the stock price volatility: under  $\mathbb{Q}$ ,

$$R_{i+1} \equiv \log(S_{i+1}/S_i) = \begin{cases} \log u & \text{with probability } p, \\ \log d = -\log u & \text{with probability } 1 - p. \end{cases}$$

• Thus,

$$\mathbb{E}^{\mathbb{Q}}[R_{i+1}] = 2p - 1 \quad \text{and}$$

$$\sigma^2 \delta t := \operatorname{var}^{\mathbb{Q}}(R_{i+1}) = (\log u)^2 \left[ 1 - (2p - 1)^2 \right] \approx (\log u)^2.$$

Hence we choose

$$u = e^{\sigma\sqrt{\delta t}}, \qquad d = 1/u = e^{-\sigma\sqrt{\delta t}}.$$

- Possible estimates for  $\sigma$ :
  - Annualized historical volatility (see last week):

$$\sigma = \sqrt{252}\sigma_{t,HIST}$$

• Implied volatility: the value of  $\sigma$  that equates model price and market price (see later).

### **Binomial Trees in Python**

- We will look at several Python implementations and compare their speed.
- The first implementation is a "loopy" version that could be written in a similar way in most imperative programming languages.

```
In [1]: import numpy as np
        def calltree(S0, K, T, r, sigma, N):
             European call price based on an N-step binomial tree.
             0.00
            deltaT = T/float(N)
            u=np.exp(sigma * np.sqrt(deltaT))
            d=1/u
            p=(np.exp(r*deltaT) - d)/(u-d)
            C=np.zeros([N+1, N+1])
            S=np.zeros([N+1,N+1])
            piu=np.exp(-r*deltaT)*p
            pid=np.exp(-r*deltaT)*(1-p)
            for i in xrange(N+1):
                for j in xrange(i, N+1):
                     S[i,j]=S0*u**j*d**(2*i)
            for i in xrange(N+1):
                C[i,N]=max(0, S[i,N]-K)
            for j in xrange(N-1,-1,-1):
                for i in xrange(j+1):
                    C[i,j] = piu * C[i,j+1] + pid * C[i+1,j+1]
             return C[0,0]
```

• Let's see if it works:

```
In [2]: S0=50.;K=50.;T=5.0/12;r=.1;sigma=.4;N=500;
calltree(S0, K, T, r, sigma, N)
Out[2]: 6.1139619792052535
```

• Great. Now let's look at the speed:

```
In [3]: %timeit calltree(S0, K, T, r, sigma, N) #ipython magic for timing things
1 loop, best of 3: 178 ms per loop
```

- Loops tend to be slow in Python. It is often preferable to write code in a vectorized style.
- This means calling NumPy ufuncs on entire vectors of data, so that the looping happens inside NumPy, i.e., in compiled C code (which means it's fast).

- Let's verify that both implementations give the same answer.
- We'll use NumPy's allclose function, which tests if all elements of an array are close to zero.

```
In [5]: np.allclose(calltree(S0, K, T, r, sigma, N), calltree_numpy(S0, K, T, r, sigma, N))
Out[5]: True
```

• Now let's time it:

```
In [6]: %timeit calltree_numpy(S0, K, T, r, sigma, N)
100 loops, best of 3: 4.15 ms per loop
```

- A third option is to use Numba (<u>user guide</u>).
- Numba implements a just in time compiler. It can compile certain (array-heavy) code to native machine code.
- If Numba is able to compile your code, then the speed is often comparable to C.
- All we need to do is import the package, and then add a decorator to our function.
- Other than that, the code is exactly the same as our first attempt.

```
In [7]: from numba import jit
        @jit
        def calltree_numba(S0, K, T, r, sigma, N):
            European call price based on an N-step binomial tree.
            deltaT = T/float(N)
            u=np.exp(sigma * np.sqrt(deltaT))
            d=1/u
            p=(np.exp(r*deltaT) - d)/(u-d)
            C=np.zeros([N+1, N+1])
            S=np.zeros([N+1,N+1])
            piu=np.exp(-r*deltaT)*p
            pid=np.exp(-r*deltaT)*(1-p)
            for i in xrange(N+1):
                for j in xrange(i, N+1):
                     S[i,j]=S0*u**j*d**(2*i)
            for i in xrange(N+1):
                C[i,N]=\max(0, S[i,N]-K)
            for j in xrange(N-1,-1,-1):
                for i in xrange(j+1):
                    C[i,j] = piu * C[i,j+1] + pid * C[i+1,j+1]
             return C[0,0]
```

• Check that it gives the right answer:

```
In [8]: np.allclose(calltree(S0, K, T, r, sigma, N), calltree_numba(S0, K, T, r, sigma, N))
Out[8]: True
```

• The moment of truth:

```
In [9]: %timeit calltree_numba(S0, K, T, r, sigma, N)
100 loops, best of 3: 4.23 ms per loop
```

- Not bad at all. We essentially match our NumPy implementation.
- There's one more thing we might try: what if we JIT-compile the vectorized version?
- Instead of writing out the whole function again, we'll use an alternative way to invoke the JIT compiler:

```
In [10]: calltree_numpy_numba=jit(calltree_numpy)
    np.allclose(calltree(S0, K, T, r, sigma, N), calltree_numpy_numba(S0, K, T, r, sigma, N))
Out[10]: True
In [11]: %timeit calltree_numpy_numba(S0, K, T, r, sigma, N)
    1000 loops, best of 3: 1.1 ms per loop
```

- Wow. On my office machine, it's three times as fast as the pure NumPy version, and 150 times as fast as our naive implementation.
- Looking at the absolute timings, the improvements may seem small, but keep in mind that you may need to call these functions many many times.
- Other tools for compiling Python to native code include Cython and Pythran.

# A Closed Form for European Options

• The price of a European option

$$C_0 = e^{-rT} \mathbb{E}^{\mathbb{Q}} \left[ \max(S_T - K), 0 \right]$$

depends only on  $S_T$ , so there is no need to use a tree explicitly to evaluate it.

• Let k denote the number of up moves of the stock, so that N-k is the number of down moves. Then

$$S_T = S_0 u^k d^{N-k} = S_0 u^{2k-N},$$

where under  $\mathbb{Q}$ ,  $k \sim \text{Bin}(N,p)$ , with  $\text{pmf}f(k;N,p) = \binom{N}{k}p^k(1-p)^{N-k}$ . Thus

$$C_0 = e^{-rT} \sum_{k=0}^{N} f(k; N, p) \max(S_0 u^k d^{N-k} - K, 0).$$

• Let a denote the minimum number of up moves so that  $S_T > K$ , i.e., the smallest integer greater than  $N/2 + \log(K/S_0)/(2\log u)$ . Then

$$C_0 = e^{-rT} \sum_{k=a}^{N} f(k; N, p) \left[ S_0 u^k d^{N-k} - K \right].$$

- The second term is  $[1 F(a 1; N, p)]e^{-rT}K = \bar{F}(a 1; N, p)e^{-rT}K$ , where F is the binomial cdf and  $\bar{F}$  is the survivor function.
- Let  $p_* = e^{-r\delta t} pu$ . The first term is

$$e^{-rT}S_0 \sum_{k=a}^{N} {N \choose k} p^k (1-p)^{N-k} u^k d^{N-k} = S_0 \sum_{k=a}^{N} {N \choose k} p_*^k (1-p_*)^{N-k}.$$

Putting things together,

$$C_0 = S_0 \bar{F}(a-1; N, p_*) - \bar{F}(a-1; N, p)e^{-rT}K$$
  
=  $S_0 \mathbb{Q}^* (S_T > K) - \mathbb{Q}(S_T > K)e^{-rT}K$ 

• You will be implementing this in a homework exercise.

#### The Black-Scholes Formula as Continuous Time Limit

- Let's consider what happens if we let  $N \to \infty$ .
- First, a first-order Taylor expansion, together with l'Hopital's rule, can be used to show that, for small  $\delta t$ ,

$$p \approx \frac{1}{2} \left( 1 + \sqrt{\delta t} \frac{r - \frac{1}{2}\sigma^2}{\sigma} \right).$$

• Similarly,

$$p^* \approx \frac{1}{2} \left( 1 + \sqrt{\delta t} \frac{r + \frac{1}{2}\sigma^2}{\sigma} \right).$$

• Next, Let  $X_T \equiv \log S_T$ . Then, because  $R_i$  is either  $\log u$  or  $\log d = -\log u$ ,

$$X_T = \log S_0 + \sum_{i=1}^{N} R_i = \log S_0 + \sigma \sqrt{\delta t} (2k - N),$$

• As  $k \sim \text{Bin}(N, p)$ , we have  $\mathbb{E}^{\mathbb{Q}}[k] = Np$ ,  $\text{Var}^{\mathbb{Q}}[k] = Np(1-p)$ , and

$$\mathbb{E}^{\mathbb{Q}}[X_T] = \log S_0 + \sigma \sqrt{\delta t} N(2p - 1) \to \log S_0 + (r - \frac{1}{2}\sigma^2)T$$

$$\operatorname{Var}^{\mathbb{Q}}[X_T] = \sigma^2 \delta t 4Np(1 - p) \to \sigma^2 T.$$

• Finally, as  $N \to \infty$ , the distribution of  $X_T$  tends to a normal. This follows from the central limit theorem and the fact that  $X_T$  is the sum of N i.i.d. terms.

• Thus, as  $N \to \infty$ ,

$$\mathbb{Q}(S_T > K) = \mathbb{Q}(X_T > \log K) = \mathbb{Q}\left(\frac{X_T - \mathbb{E}^{\mathbb{Q}}[X_T]}{\sqrt{\operatorname{Var}^{\mathbb{Q}}[X_T]}} > \frac{\log K - \mathbb{E}^{\mathbb{Q}}[X_T]}{\sqrt{\operatorname{Var}^{\mathbb{Q}}[X_T]}}\right)$$
$$= 1 - \Phi\left(\frac{\log K - \mathbb{E}^{\mathbb{Q}}[X_T]}{\sqrt{\operatorname{Var}^{\mathbb{Q}}[X_T]}}\right) =: 1 - \Phi(-d_2) = \Phi(d_2),$$

where  $\Phi$  is the standard normal cdf and

$$d_2 \equiv \frac{\mathbb{E}^{\mathbb{Q}}[X_T] - \log K}{\sqrt{\operatorname{Var}^{\mathbb{Q}}[X_T]}} = \frac{\log(S_0/K) + (r - \frac{1}{2}\sigma^2)T}{\sigma\sqrt{T}}.$$

• The same argument can be used to show that as  $N \to \infty$ ,  $\mathbb{Q}^*(S_T > K) = \Phi(d_1)$ ,

where

$$d_1 \equiv d_2 + \sigma \sqrt{T} = \frac{\log(S_0/K) + (r + \frac{1}{2}\sigma^2)T}{\sigma \sqrt{T}}.$$

• In summary, we have derived the Black-Scholes formula

$$C_0 = S_0 \Phi(d_1) - e^{-rT} K \Phi(d_2)$$
  
=:  $BS(S_0, K, T, r, \sigma)$ .

• Implementation in Python:

Note that as written, the function can operate on arrays of strikes:

```
In [14]: Ks=np.linspace(K/2., 2.*K, 5)
blackscholes(S0, Ks, T, r, sigma)
Out[14]: array([ 26.0260491 , 9.77944137, 2.00056039, 0.27962697, 0.0331146 ])
```

## **American Options**

- Unlike a European call, an American call with price  $C_t^{Am}$  can be exercised at any time before it matures. When exercised at  $t \leq T$ , it pays  $\max(S_t K, 0)$ . Hence the call will be exercised early if at time  $t, S_t K > C_t^{Am}$ .
- Recall put-call parity:  $C_t P_t = S_t e^{-r(T-t)}K$ , which implies (for r>0)  $C_t \geq S_t e^{-r(T-t)}K \geq S_t K,$   $P_t \geq Ke^{-r(T-t)} S_t.$
- As  $C_t^{Am} \ge C_t$ , an American call is therefore never exercised early (in the absence of dividends).
- There is no closed-form expression for the price of an American put option, so numerical methods are needed. Binomial trees are a popular choice.

- This works as follows:
  - At step N, the price of the put is  $P_N^{Am} = \max(K S_N, 0)$ , just like for a European put.
  - At step N-1, the *continuation value* of the option is  $e^{-r\delta t}\mathbb{E}^{\mathbb{Q}}[P_N^{Am}]$ . Early exercise yields  $K-S_{N-1}$ , so

$$P_{N-1}^{Am} = \max(e^{-r\delta t} \mathbb{E}^{\mathbb{Q}}[P_N^{Am} | \mathcal{F}_{N-1}], K - S_{N-1}).$$

- This is iterated backwards until  $P_0^{Am}$ .
- The implementation is part of the homework exercise.

# Implied Volatility

• The implied volatility (IV,  $\sigma_I$ ) of an option is that value of  $\sigma$  which equates the BS model price to the observed market price  $C_0^{obs}$ , i.e., it solves

$$C_0^{obs} = BS(S_0, K, T, r, \sigma_I).$$

- If the BS assumptions were correct, then any option traded on the asset should have the same IV, which should in turn equal historical volatility.
- In practice, options with different strikes K and hence moneyness  $K/S_0$  have different IVs: volatility smile or smirk/skew. Also, options with different times to maturity have different IVs: volatility term structure.
- These phenomena are evidence of a failure of the assumptions of the Black-Scholes model, most importantly that of a constant volatility  $\sigma$ .

- In practice, the BS formula is used as follows: the implied volatility is computed for options that are already traded in the market, for different strikes and maturities. This leads to the *IV surface*.
- When a new option is issued, the implied volatility corresponding to its strike and time to maturity is determined by interpolation on the surface. The BS formula then gives the corresponding price.
- Mathematically, the IV is the *root* (or *zero*) of the function

$$f(\sigma_I) = BS(S_0, K, T, r, \sigma_I) - C_0^{obs}.$$

• In Python, root finding can be done via SciPy's brentq function. In its simplest form, it takes 3 arguments: the unary function  $f(\cdot)$ , and a lower bound L and upper bound U such that [L,U] contains exactly one root of f.

• <u>Tehranchi (2016)</u> shows that for European calls,

$$-\Phi^{-1}\left(\frac{S_0 - C_0^{obs}}{2\min(S_0, e^{-rT}K)}\right) \le \frac{\sqrt{T}}{2}\sigma_I \le -\Phi^{-1}\left(\frac{S_0 - C_0^{obs}}{S_0 + e^{-rT}K}\right).$$

• It remains to transform our objective function into a unary (single argument) function, through partial function application via, e.g., an anonymous function:

#### Volatility Smirk, SPX OTM puts/calls expiring 1/2018

