

January 25, 2018

## Abstract

### 1 Problem

$$AX - XB = C; A, B, C, X \in \mathbb{R}^{n \times n} \quad (1)$$

Check correctness with:

$$\|AX - XB - C\|_{\mathbb{F}} = 0 \quad (2)$$

Steps:

You can decompose  $B$  as follows:

$$B = QTQ^T; QQ^T = I, T \in \text{upper triang} \quad (3)$$

Then:

$$AX - XB = C = AX - XQTQ^T \quad (4)$$

$$(AX - XQTQ^T)Q = CQ \quad (5)$$

$$= AXQ - XQTQ^TQ = CQ \quad (6)$$

$$= AXQ - XQT = CQ \quad (7)$$

$$(8)$$

If we consider  $XQ = Y$  and  $CQ = D$ , we get:

$$AY - YT = D \quad (9)$$

At this point, there are two options:

1.  $T$  is upper triangular.
2.  $T$  is in Schur form.

## 1.1 Option 1: T is upper triangular

In the first case:

$$AY_{.,1} - Y_{.,1}t_{1,1} = D_1 \quad (10)$$

$$(A - t_{1,1}I)Y_{.,1} = D_1 \quad (11)$$

$$(12)$$

Where  $(A - t_{1,1}I)$  is a known matrix, and then it becomes:

$$Zx = b \quad (13)$$

Where  $Z = (A - t_{1,1}I)$ ,  $x = Y_{.,1}$  and  $b = D_1$ .

After solving it, we can continue as follows:

$$AY_{.,2} - t_{1,2}Y_{.,1} - t_{2,2}Y_{.,2} = D_2 \quad (14)$$

$$(A - t_{2,2}I)Y_{.,2} = D_2 + t_{1,2}Y_{.,1} \quad (15)$$

$$(16)$$

Where  $(A - t_{2,2}I)$  is a known matrix, and then it becomes:

TO DO

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ a_{3,1} & a_{3,2} & a_{3,3} & a_{3,4} \\ a_{4,1} & a_{4,2} & a_{4,3} & a_{4,4} \end{pmatrix} \begin{pmatrix} y_{1,1} & y_{1,2} & y_{1,3} & y_{1,4} \\ y_{2,1} & y_{2,2} & y_{2,3} & y_{2,4} \\ y_{3,1} & y_{3,2} & y_{3,3} & y_{3,4} \\ y_{4,1} & y_{4,2} & y_{4,3} & y_{4,4} \end{pmatrix} - \begin{pmatrix} y_{1,1} & y_{1,2} & y_{1,3} & y_{1,4} \\ y_{2,1} & y_{2,2} & y_{2,3} & y_{2,4} \\ y_{3,1} & y_{3,2} & y_{3,3} & y_{3,4} \\ y_{4,1} & y_{4,2} & y_{4,3} & y_{4,4} \end{pmatrix} \begin{pmatrix} t_{1,1} & t_{1,2} & t_{1,3} & t_{1,4} \\ 0 & t_{2,2} & t_{2,3} & t_{2,4} \\ 0 & 0 & t_{3,3} & t_{3,4} \\ 0 & 0 & 0 & t_{4,4} \end{pmatrix} = \begin{pmatrix} d_{1,1} & d_{1,2} & d_{1,3} & d_{1,4} \\ d_{2,1} & d_{2,2} & d_{2,3} & d_{2,4} \\ d_{3,1} & d_{3,2} & d_{3,3} & d_{3,4} \\ d_{4,1} & d_{4,2} & d_{4,3} & d_{4,4} \end{pmatrix} \quad (17)$$

$$AY_{,1} - Y_{,1} \begin{pmatrix} t_{1,1} & t_{1,2} & t_{1,3} & t_{1,4} \\ 0 & t_{2,2} & t_{2,3} & t_{2,4} \\ 0 & t_{3,2} & t_{3,3} & t_{3,4} \\ 0 & 0 & 0 & t_{4,4} \end{pmatrix} = D_{,1} \quad (18)$$

$$AY_{,1} - Y_{,1}t_{1,1} = D_{,1} \quad (19)$$

$$\begin{pmatrix} y_{1,1} & y_{1,2} & y_{1,3} & y_{1,4} \\ y_{2,1} & y_{2,2} & y_{2,3} & y_{2,4} \\ y_{3,1} & y_{3,2} & y_{3,3} & y_{3,4} \\ y_{4,1} & y_{4,2} & y_{4,3} & y_{4,4} \end{pmatrix} \begin{pmatrix} t_{1,1} & t_{1,2} & t_{1,3} & t_{1,4} \\ 0 & t_{2,2} & t_{2,3} & t_{2,4} \\ 0 & t_{3,2} & t_{3,3} & t_{3,4} \\ 0 & 0 & 0 & t_{4,4} \end{pmatrix} = \begin{pmatrix} y_{1,1}t_{1,1} & y_{1,1}t_{1,2} + y_{1,2}t_{2,2} + y_{1,3}t_{3,2} & t_{1,3} & t_{1,4} \\ 0 & y_{2,1}t_{1,2} + y_{2,2}t_{2,2} + y_{2,3}t_{3,2} & t_{2,3} & t_{2,4} \\ 0 & y_{3,1}t_{1,2} + y_{3,2}t_{2,2} + y_{3,3}t_{3,2} & t_{3,3} & t_{3,4} \\ 0 & y_{4,1}t_{1,2} + y_{4,2}t_{2,2} + y_{4,3}t_{3,2} & 0 & t_{4,4} \end{pmatrix} \quad (20)$$

$$AY_{,2} - Y_{,1} \begin{pmatrix} t_{1,1} & t_{1,2} & t_{1,3} & t_{1,4} \\ 0 & t_{2,2} & t_{2,3} & t_{2,4} \\ 0 & t_{3,2} & t_{3,3} & t_{3,4} \\ 0 & 0 & 0 & t_{4,4} \end{pmatrix} = D_{,1} \quad (21)$$

$$\begin{pmatrix} y_{1,1} & y_{1,2} & y_{1,3} & y_{1,4} \\ y_{2,1} & y_{2,2} & y_{2,3} & y_{2,4} \\ y_{3,1} & y_{3,2} & y_{3,3} & y_{3,4} \\ y_{4,1} & y_{4,2} & y_{4,3} & y_{4,4} \end{pmatrix} \begin{pmatrix} t_{1,1} & t_{1,2} & t_{1,3} & t_{1,4} \\ 0 & t_{2,2} & t_{2,3} & t_{2,4} \\ 0 & t_{3,2} & t_{3,3} & t_{3,4} \\ 0 & 0 & 0 & t_{4,4} \end{pmatrix} = \begin{pmatrix} y_{1,1}t_{1,1} & \cdots & y_{1,1}t_{1,3} + y_{2,2}t_{2,3} + y_{3,3}t_{3,3} & t_{1,4} \\ 0 & \cdots & y_{2,1}t_{1,3} + y_{2,2}t_{2,3} + y_{3,3}t_{3,3} & t_{2,4} \\ 0 & \cdots & y_{3,1}t_{1,3} + y_{2,2}t_{2,3} + y_{3,3}t_{3,3} & t_{3,4} \\ 0 & \cdots & y_{4,1}t_{1,3} + y_{2,2}t_{2,3} + y_{3,3}t_{3,3} & t_{4,4} \end{pmatrix} \quad (22)$$

$$Y_{,1}t_{1,2} + Y_{,2}t_{2,2} + Y_{,3}t_{3,2} = \begin{pmatrix} y_{1,1}t_{1,1} & y_{1,1}t_{1,2} + y_{1,2}t_{2,2} + y_{1,3}t_{3,2} & t_{1,3} & t_{1,4} \\ 0 & y_{2,1}t_{1,2} + y_{2,2}t_{2,2} + y_{2,3}t_{3,2} & t_{2,3} & t_{2,4} \\ 0 & y_{3,1}t_{1,2} + y_{3,2}t_{2,2} + y_{3,3}t_{3,2} & t_{3,3} & t_{3,4} \\ 0 & y_{4,1}t_{1,2} + y_{4,2}t_{2,2} + y_{4,3}t_{3,2} & 0 & t_{4,4} \end{pmatrix} \rightarrow D_2 \quad (23)$$

$$Y_{,1}t_{1,3} + Y_{,2}t_{2,3} + Y_{,3}t_{3,3} \rightarrow \begin{pmatrix} y_{1,1}t_{1,1} & \cdots & y_{1,1}t_{1,3} + y_{1,2}t_{2,3} + y_{1,3}t_{3,3} & t_{1,4} \\ 0 & \cdots & y_{2,1}t_{1,3} + y_{2,2}t_{2,3} + y_{3,3}t_{3,3} & t_{2,4} \\ 0 & \cdots & y_{3,1}t_{1,3} + y_{2,2}t_{2,3} + y_{3,3}t_{3,3} & t_{3,4} \\ 0 & \cdots & y_{4,1}t_{1,3} + y_{2,2}t_{2,3} + y_{3,3}t_{3,3} & t_{4,4} \end{pmatrix} \rightarrow D_3 \quad (24)$$

$$AY_{,2} - Y_{,1}t_{1,2} - Y_{,2}t_{2,2} - Y_{,3}t_{3,2} = D_2 \quad (25)$$

$$AY_{,3} - Y_{,1}t_{1,3} - Y_{,2}t_{2,3} - Y_{,3}t_{3,3} = D_3 \quad (26)$$

$$(A - t_{2,2}I)Y_{,2} - Y_{,1}t_{1,2} - Y_{,3}t_{3,2} = D_2 \quad (27)$$

$$AY_{,3} - Y_{,1}t_{1,3} - Y_{,2}t_{2,3} - Y_{,3}t_{3,3} = D_3 \quad (28)$$

$$(A - t_{2,2}I)Y_{.,2} - Y_{.,1}t_{1,2} - D_2 = Y_{.,3}t_{3,2} \quad (29)$$

$$AY_{.,3} - Y_{.,1}t_{1,3} - Y_{.,2}t_{2,3} - Y_{.,3}t_{3,3} = D_3 \quad (30)$$

$$Y_{.,3} = \frac{(A - t_{2,2}I)Y_{.,2} - Y_{.,1}t_{1,2} - D_2}{t_{3,2}} \quad (31)$$

$$AY_{.,3} - Y_{.,1}t_{1,3} - Y_{.,2}t_{2,3} - Y_{.,3}t_{3,3} = D_3 \quad (32)$$

$$Y_{.,3} = \frac{(A - t_{2,2}I)Y_{.,2}}{t_{3,2}} - \frac{Y_{.,1}t_{1,2}}{t_{3,2}} - \frac{D_2}{t_{3,2}} \quad (33)$$

$$Y_{.,3} = KY_{.,2} - S \quad (34)$$

$$K = \frac{(A - t_{2,2}I)}{t_{3,2}} \quad (35)$$

$$S = \frac{Y_{.,1}t_{1,2}}{t_{3,2}} - \frac{D_2}{t_{3,2}} \quad (36)$$

$$(37)$$

$$AY_{.,3} - Y_{.,1}t_{1,3} - Y_{.,2}t_{2,3} - Y_{.,3}t_{3,3} = D_3 \quad (38)$$

$$A(KY_{.,2} - S) - Y_{.,1}t_{1,3} - Y_{.,2}t_{2,3} - (KY_{.,2} - S)t_{3,3} = D_3 \quad (39)$$

$$AKY_{.,2} - AS - Y_{.,1}t_{1,3} - Y_{.,2}t_{2,3} - KY_{.,2}t_{3,3} - St_{3,3} = D_3 \quad (40)$$

$$(AK - Kt_{3,3} - t_{1,3}I)Y_{.,2} - AS - Y_{.,1}t_{1,3} - St_{3,3} = D_3 \quad (41)$$

$$(AK - Kt_{3,3} - t_{1,3}I)Y_{.,2} = D_3 + AS + Y_{.,1}t_{1,3} + St_{3,3} \quad (42)$$

$$(43)$$