# **Optimal Plans**

Problem 1 optimal plan (from levelsum heuristic):

| Load(C1, P1, SFO)      |
|------------------------|
| Fly(P1, SFO, JFK)      |
| Load(C2, P2, JFK)      |
| Fly(P2, JFK, SFO)      |
| Unload(C1, P1, JFK)    |
| Unload(C2, P2,<br>SFO) |

Problem 2 optimal plan (from levelsum heuristic):

| Load(C1, P1, SFO)      |
|------------------------|
| Fly(P1, SFO, JFK)      |
| Load(C2, P2, JFK)      |
| Fly(P2, JFK, SFO)      |
| Load(C3, P3, ATL)      |
| Fly(P3, ATL, SFO)      |
| Unload(C1, P1, JFK)    |
| Unload(C2, P2,<br>SFO) |
| Unload(C3, P3,<br>SFO) |

Problem 3 optimal plan (from levelsum heuristic):

| Load(C2, P2, JFK) |
|-------------------|
| Fly(P2, JFK, ORD) |
| Load(C4, P2, ORD) |
| Fly(P2, ORD, SFO) |
| Load(C1, P1, SFO) |
| Fly(P1, SFO, ATL) |
| Load(C3, P1, ATL) |
| Fly(P1, ATL, JFK) |
|                   |

Unload(C1, P1, JFK)
Unload(C2, P2,
SFO)
Unload(C3, P1, JFK)
Unload(C4, P2,
SFO)

# Non-Heuristic Compare and Contrast

Below is a list of results for uninformed searches and false (h\_1) heuristic searches:

|                              | Air Cargo 1    | Air Cargo 2      | Air Cargo 3      |
|------------------------------|----------------|------------------|------------------|
| BFS-node expansions          | 43             | 3343             | 14663            |
| BFS-# goal tests             | 56             | 4609             | 18098            |
| BFS-# new nodes              | 180            | 3059             | 129631           |
| BFS-plan length              | 6              | 9                | 12               |
| BFS-time elapsed             | 0.03086357901  | 14.72629713      | 128.4447374      |
| BFS-optimality of solutions  | optimal        | optimal          | optimal          |
| DFGS-node expansions         | 12             | 476              | 1511             |
| DFGS-# goal tests            | 13             | 477              | 1512             |
| DFGS-# new nodes             | 48             | 4253             | 12611            |
| DFGS-plan length             | 12             | 466              | 1442             |
| DFGS-time elapsed            | 0.007452471997 | 2.348740683      | 13.94696688      |
| DFGS-optimality of solutions | non-optimal    | very non-optimal | very non-optimal |
| UCS-node expansions          | 55             | 4780             | 17532            |
| UCS-# goal tests             | 57             | 4782             | 17534            |
| UCS-# new nodes              | 224            | 43381            | 153777           |
| UCS-plan length              | 6              | 9                | 12               |
| UCS-time elapsed             | 0.03847271297  | 11.44945664      | 53.32030594      |
| UCS-optimality of solutions  | optimal        | optimal          | optimal          |
|                              |                |                  |                  |

| GBFGS h_1-node expansions         | 7              | 598            | 3373           |
|-----------------------------------|----------------|----------------|----------------|
| GBFGS h_1-# goal tests            | 9              | 600            | 3375           |
| GBFGS h_1-# new nodes             | 28             | 5382           | 30072          |
| GBFGS h_1-plan length             | 6              | 21             | 27             |
| GBFGS h_1-time elapsed            | 0.004918675986 | 1.623863283    | 10.9601263     |
| GBFGS h_1-optimality of solutions | optimal        | almost optimal | almost optimal |
|                                   |                |                |                |
| AS h_1-node expansions            | 55             | 4780           | 17532          |
| AS h_1-# goal tests               | 57             | 4782           | 17534          |
| AS h_1-# new nodes                | 224            | 43381          | 152777         |
| AS h_1-plan length                | 6              | 9              | 12             |
| AS h_1-time elapsed               | 0.03980848694  | 12.84616444    | 51.13964145    |
| AS h_1-optimality of solutions    | optimal        | optimal        | optmial        |

#### Summary of Results

The table below lists the performance of each search:

| Rank | Node<br>Expansions | Average | Goal<br>Tests | Average | New<br>Nodes | Averag<br>e | Plan<br>Length | Average | Time<br>Elapsed | Average |
|------|--------------------|---------|---------------|---------|--------------|-------------|----------------|---------|-----------------|---------|
| 1    | DFGS               | 666.333 | DFGS          | 667.333 | DFGS         | 5637.33     | BFS            | 9       | GBFGS<br>h_1    | 4.19630 |
| 2    | GBFGS h_1          | 1326    | GBFGS<br>h_1  | 1328    | GBFGS<br>h_1 | 11827.3     | UCS            | 9       | DFGS            | 5.43438 |
| 3    | BFS                | 6016.33 | UCS           | 7457.66 | BFS          | 44290       | AS h_1         | 9       | AS h_1          | 21.3418 |
| 4    | UCS                | 7455.66 | AS h_1        | 7457.66 | AS h_1       | 65460.6     | GBFGS<br>h_1   | 18      | UCS             | 21.6027 |
| 5    | AS h_1             | 7455.66 | BFS           | 7587.66 | UCS          | 65794       | DFGS           | 640     | BFS             | 47.7339 |

In general, DFGS performed the best by far for node expansions, goal tests, and new nodes (and therefore required memory), however it resulted in very non-optimal plan length. This is expected due to the nature of depth first search and the fact that many solutions exist for these

problems. BFS, UCS, and AS h\_1 all resulted in optimal planning length, but were also on average the slowest searches and required the most memory. UCS and AS h\_1 are essentially the same search due to the simplified h\_1 heuristic provided to A\*. Both take advantage of more complexity and memory requirements to guide the search to find an optimal solution at a faster rate than BFS. The table below ranks each search based on weighted normalized scores for each category (where W is weight):

| Search       | Node<br>Expansions | w   | Goal<br>Tests |     | New<br>Nodes | w   | Plan<br>Length | w | Time<br>Elapsed | w    | Weighted Score |
|--------------|--------------------|-----|---------------|-----|--------------|-----|----------------|---|-----------------|------|----------------|
| GBFGS<br>h_1 | 0.902              | 0.2 | 0.904         | 0.2 | 0.8971       | 0.2 | 0.98573        | 1 | 1               | 0.75 | 2.276631392    |
| AS h_1       | 0                  | 0.2 | 0.018         | 0.2 | 0.0055       | 0.2 | 1              | 1 | 0.606189        | 0.75 | 1.459507736    |
| UCS          | 0                  | 0.2 | 0.018         | 0.2 | 0            | 0.2 | 1              | 1 | 0.600198        | 0.75 | 1.453905588    |
| DFGS         | 1                  | 0.2 | 1             | 0.2 | 1            | 0.2 | 0              | 1 | 0.971562        | 0.75 | 1.328672192    |
| BFS          | 0.211              | 0.2 | 0             | 0.2 | 0.3574       | 0.2 | 1              | 1 | 0               | 0.75 | 1.113893166    |

The highest weight was given to the plan length (or optimality) of the plan, followed by the time elapsed, with node expansions, goal tests, and new nodes weighted the lowest. The weights were based on the value and scalability of each metric.

Overall, GBFGS h\_1 ranked the highest due to its high performance metrics and semi-optimal plan length. GBFGS h\_1 is a balanced method since it approximates the next best node in the path without taking the path cost into consideration. Out of the optimal solutions, AS h\_1 and UCS ranked the highest with almost identical scores.

### Heuristic Compare and Contrast

Below is a list of results for heuristic searches:

|                                  | Air Cargo 1 | Air Cargo 2 | Air Cargo 3 | Average     |
|----------------------------------|-------------|-------------|-------------|-------------|
| AS h_IG-node expansions          | 41          | 1450        | 5022        | 2171        |
| AS h_IG-# goal tests             | 43          | 1452        | 5024        | 2173        |
| AS h_IG-# new nodes              | 170         | 13303       | 44764       | 19412.33333 |
| AS h_IG-plan length              | 6           | 9           | 12          | 9           |
| AS h_IG-time elapsed             | 0.029407158 | 3.962436823 | 16.21032731 | 6.734057097 |
| AS h_IG-optimality of solutions  | optimal     | optimal     | optimal     |             |
|                                  |             |             |             |             |
| AS h_PGL-node expansions         | 11          | 88          | 318         | 139         |
| AS h_PGL-# goal tests            | 13          | 88          | 320         | 140.3333333 |
| AS h_PGL-# new nodes             | 50          | 841         | 2937        | 1276        |
| AS h_PGL-plan length             | 6           | 9           | 12          | 9           |
| AS h_PGL-time elapsed            | 0.865093192 | 75.79139761 | 370.0041738 | 148.8868882 |
| AS h_PGL-optimality of solutions | optimal     | optimal     | optimal     |             |

### Summary of Results

The table below lists the performance of each search:

|      | Node       |         | Goal    |          | New     | Averag | Plan   |         | Time    |          |
|------|------------|---------|---------|----------|---------|--------|--------|---------|---------|----------|
| Rank | Expansions | Average | Tests   | Average  | Nodes   | е      | Length | Average | Elapsed | Average  |
|      |            |         | AS      | 140.3333 | AS      |        | AS     |         |         | 6.734057 |
| 1    | AS h_PGL   | 139     | h_PGL   | 333      | h_PGL   | 2937   | h_IG   | 9       | AS h_IG | 097      |
|      |            |         |         |          |         |        | AS     |         | AS      | 148.8868 |
| 2    | AS h_IG    | 2171    | AS h_IG | 2173     | AS h_IG | 44764  | h_PGL  | 9       | h_PGL   | 882      |

While both searches produce optimal solutions, they are polar opposites in terms of memory and speed. The table below ranks the heuristic searches in comparison with the non-heuristic searches:

|           | Node       |     | Goal  |     | New    |     | Plan    |   | Time     |      |                |
|-----------|------------|-----|-------|-----|--------|-----|---------|---|----------|------|----------------|
| Search    | Expansions | W   | Tests | W   | Nodes  | W   | Length  | W | Elapsed  | W    | Weighted Score |
| GBFGS h_1 | 0.83776765 | 0.2 | 0.840 | 0.2 | 0.8585 | 0.2 | 0.98573 | 1 | 1        | 0.75 | 2.243107882    |
| AS h_IG   | 0.72227790 | 0.2 | 0.727 | 0.2 | 0.3345 | 0.2 | 1       | 1 | 0.982460 | 0.75 | 2.093627212    |
| AS h_1    | 0          | 0.2 | 0.017 | 0.2 | 0.0053 | 0.2 | 1       | 1 | 0.881501 | 0.75 | 1.665678168    |
| UCS       | 0          | 0.2 | 0.017 | 0.2 | 0      | 0.2 | 1       | 1 | 0.879698 | 0.75 | 1.663265328    |
| BFS       | 0.19671981 | 0.2 | 0     | 0.2 | 0.3421 | 0.2 | 1       | 1 | 0.699098 | 0.75 | 1.632089558    |
| AS h_PGL  | 1          | 0.2 | 1     | 0.2 | 1      | 0.2 | 1       | 1 | 0        | 0.75 | 1.6            |
| DFGS      | 0.92792710 | 0.2 | 0.929 | 0.2 | 0.9570 | 0.2 | 0       | 1 | 0.991443 | 0.75 | 1.306423139    |

Using the same weights as before, GBFGS h\_1 still scores the highest overall, however AS h\_IG takes a close 2nd, and indeed would be the best overall method if optimality is required. Comparing the three AS searches provides a good insight into the power of heuristics. Although the "ignore preconditions" heuristic is quite simple and a rough approximation, it greatly improves the search performance over the constant "h\_1" heuristic in both memory and processing requirements. On the other hand, the "levelsum" heuristic provides a much better approximation to the goal, resulting in less exploration and less memory required for a solution, at the cost of extra processing for the planning graph. The time performance for the levelsum heuristic could be improved with a more efficient implementation of the planning graph. If there were a situation where memory was scarce and time/processing power were abundant, then AS h\_PGL would by far be the best choice.