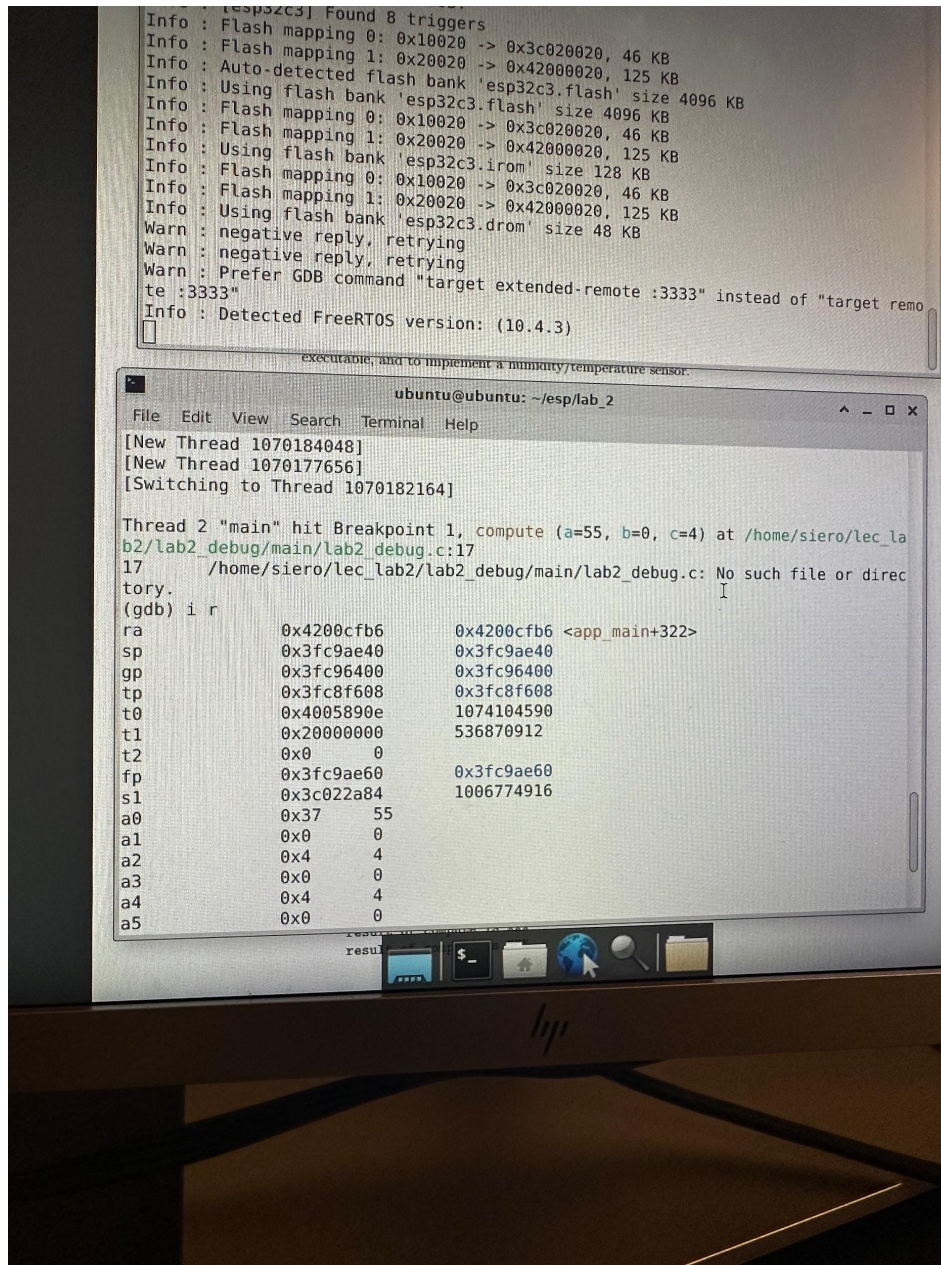


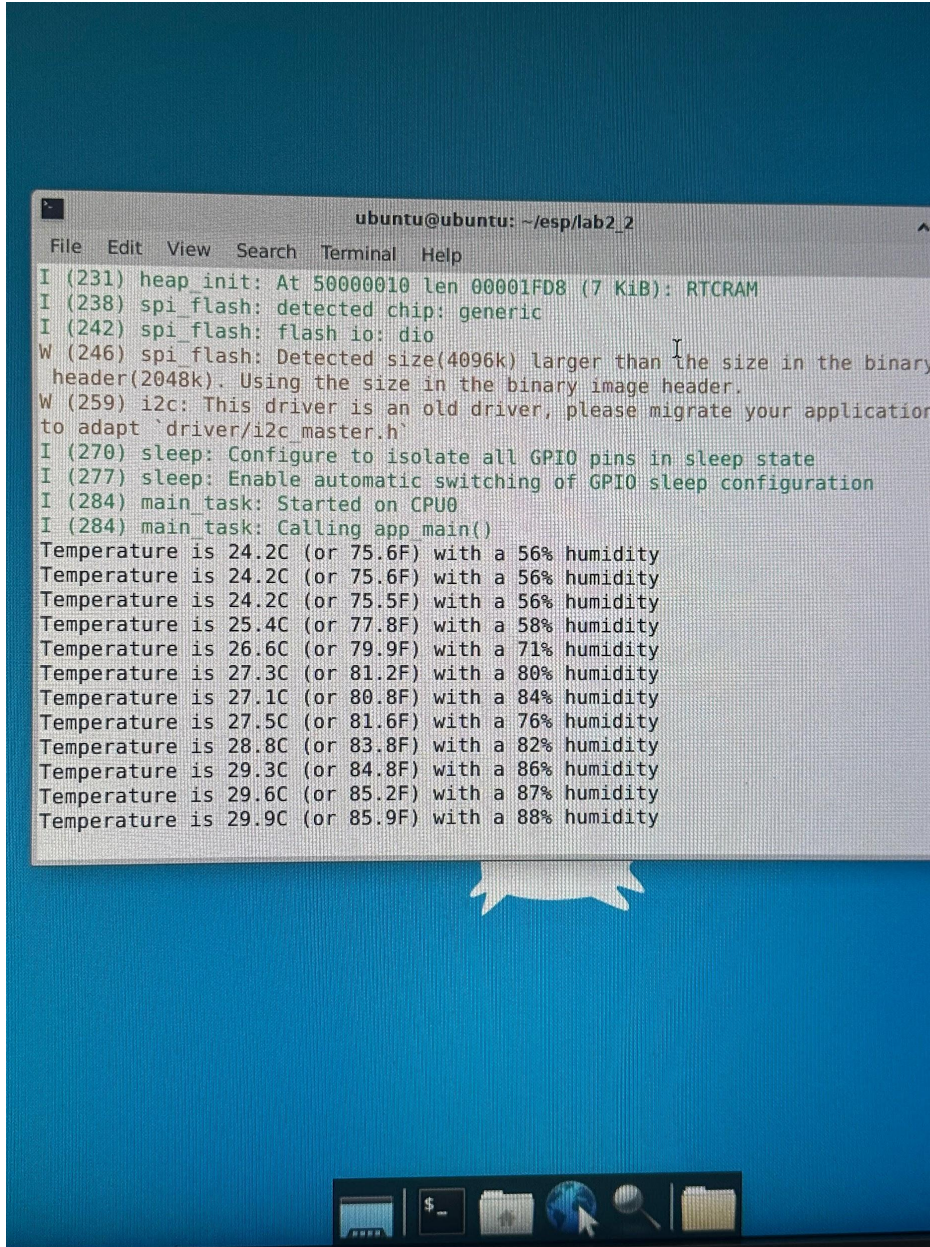
## CSE121 Lab 2

For part one of this lab, I used an esptool.py to convert an elf file to a bin file. Then I enforced the 60openocd rules found online. Running gdp, I used breakpoints to read the lines until finally it decoded the elf file to retrieve said values shown in the picture:  $a = 55$ ,  $b = 0$ , and  $c = 4$ . The commands I used on gdp were “target remote :3333, b compute, c, and i r” to retrieve said values. Most of the process I looked up on ChatGPT or on the internet, shown below.





For part 2 of this lab, I used the i2c and shtc on the esp32c3 to detect the temperature and humidity of the environment, as shown in the picture below. Most of this was also looked up on ChatGPT or on the internet, all cited below.



```
ubuntu@ubuntu: ~/esp/lab2_2
File Edit View Search Terminal Help
I (231) heap_init: At 50000010 len 00001FD8 (7 KiB): RTCRAM
I (238) spi_flash: detected chip: generic
I (242) spi_flash: flash io: dio
W (246) spi_flash: Detected size(4096k) larger than the size in the binary header(2048k). Using the size in the binary image header.
W (259) i2c: This driver is an old driver, please migrate your application to adapt `driver/i2c master.h`
I (270) sleep: Configure to isolate all GPIO pins in sleep state
I (277) sleep: Enable automatic switching of GPIO sleep configuration
I (284) main task: Started on CPU0
I (284) main task: Calling app.main()
Temperature is 24.2C (or 75.6F) with a 56% humidity
Temperature is 24.2C (or 75.6F) with a 56% humidity
Temperature is 24.2C (or 75.5F) with a 56% humidity
Temperature is 25.4C (or 77.8F) with a 58% humidity
Temperature is 26.6C (or 79.9F) with a 71% humidity
Temperature is 27.3C (or 81.2F) with a 80% humidity
Temperature is 27.1C (or 80.8F) with a 84% humidity
Temperature is 27.5C (or 81.6F) with a 76% humidity
Temperature is 28.8C (or 83.8F) with a 82% humidity
Temperature is 29.3C (or 84.8F) with a 86% humidity
Temperature is 29.6C (or 85.2F) with a 87% humidity
Temperature is 29.9C (or 85.9F) with a 88% humidity
```

Resources:

ChatGPT

[chat.openai.com](https://chat.openai.com)

<https://docs.espressif.com/projects/esp-matter/en/latest/esp32/faq.html>

APACHE license:

<https://drive.google.com/drive/u/1/folders/15uqJ8zO42qNE-cszcmcdxg0Aig6x94aC>

OpenOCD Rules:

<https://github.com/arduino/OpenOCD/blob/master/contrib/60-openocd.rules>

Other:

<https://esp32.com/viewtopic.php?t=3528>

<https://unix.stackexchange.com/questions/39370/how-to-reload-udev-rules-without-reboot>

<https://docs.espressif.com/projects/esp-idf/en/latest/esp32c3/api-guides/jtag-debugging/configure-builtin-jtag.html>

<https://stackoverflow.com/questions/41066653/openocd-error-libusb-open-failed-with-libusb-error-not-supported>

<https://stackoverflow.com/questions/72616674/error-libusb-open-failed-with-libusb-error-access-visual-studio-code>

## Chatgpt resources:

how do you use esptool to convert an elf file to a 0x10000 bin file

`esptool.py` is a utility to communicate with the ROM bootloader in Espressif ESP8266 & ESP32 chips. If you want to convert an ELF file to a binary (BIN) format suitable for flashing at a certain address, you can follow these steps:

### 1. Install esptool (if you haven't already):

bash

Copy code

```
pip install esptool
```

### 2. Generate the BIN file from ELF:

You can use `esptool.py` to extract various sections from the ELF file and create the BIN files.

bash

Copy code

```
esptool.py elf2image --output ./output_path/ your_file.elf
```

This command will generate two BIN files usually:

- \* `your_file.elf-0x00000.bin`
- \* `your_file.elf-0x10000.bin`

The addresses (`0x00000` and `0x10000`) are where these sections are meant to be flashed on the ESP8266. If you're using ESP32 or a different configuration of ESP8266, the addresses might be different.

### 3. Flash the BIN file:

Once you have the BIN files, you can flash them to the ESP using `esptool.py`.

For ESP8266:

bash

Copy code

```
esptool.py --port /dev/ttyUSB0 write_flash 0x00000 your_file.elf-0x00000.bi
```

Adjust the `/dev/ttyUSB0` port according to your system. It might be different on Windows (e.g., `COM3`) or macOS (e.g., `/dev/tty.SLAB_USBtoUART`).

### 4. Additional Details:

If you have specific requirements about memory regions and you know what you're doing, you can extract specific segments manually using `objcopy`. This is a more advanced topic and requires detailed understanding of the ELF file and the ESP memory layout.

**Note:** Always ensure you understand the memory layout and the purpose of each BIN file when working with ESP chips. Flashing incorrect or corrupted BIN files can render the device non-operational until you re-flash it correctly.


how to invoke the 60-openocd.rules

To enforce the "60-openocd.rules" Udev rule, you can follow these steps to ensure it is applied when you connect your OpenOCD device:

#### Create or Edit the Udev Rule File:

First, create or edit the "60-openocd.rules" file using a text editor with administrative privileges. You can use a command like `sudo nano` or `sudo vi` to create or edit the file:

bash


 Copy code

```
sudo nano /etc/udev/rules.d/60-openocd.rules
```

#### Add the Udev Rule:

In the text editor, add the Udev rule that grants the necessary permissions to your OpenOCD device. For example, to set permissions for a device with VID "303a" and PID "1001" to "0666," you can use the following rule:

makefile

 Copy code

```
SUBSYSTEM=="usb", ATTRS{idVendor}=="303a", ATTRS{idProduct}=="1001", MODE="
```

Modify the VID, PID, and permissions as needed for your specific device.

#### Save the File and Exit:


Save your changes in the text editor and exit. In nano, you can press `Ctrl + O` to save and `Ctrl + X` to exit.

#### Reload or Restart Udev:

After creating or modifying the Udev rule, you may need to reload or restart the Udev service to apply the changes. You can use one of the following commands:

To reload Udev rules without rebooting (works on most systems):

bash


 Copy code

```
sudo udevadm control --reload-rules
```

OR

To restart the Udev service (may require a reboot on some systems):

bash

 Copy code

```
sudo service udev restart
```

```
Running openocd -f board/esp32c3-builtin.cfg -c "program_esp lab2_debug.bin 0x10000
verify exit", gives me the error message, Error: libusb_open() failed with
LIBUSB_ERROR_ACCESS
Error: esp_usb_jtag: could not find or open device!
** OpenOCD init failed **
shutdown command invoked
/home/ubuntu/.espressif/tools/openocd-esp32/v0.12.0-esp32-20230419/openocd-
esp32/share/openocd/scripts/target/esp_common.cfg:4: Error:
at file "/home/ubuntu/.espressif/tools/openocd-esp32/v0.12.0-esp32-20230419/openocd-
esp32/share/openocd/scripts/target/esp_common.cfg", line 4
```

The error message you're seeing is indicative of a permissions problem related to the USB device you're trying to access. This is a common issue when trying to access USB devices without sufficient permissions on Linux systems.

Here are steps you can take to resolve the issue:

#### 1. Run as Root:

One quick way to test if permissions are the issue is to run the command as the root user using `sudo`:

```
bash
Copy code

sudo openocd -f board/esp32c3-builtin.cfg -c "program_esp lab2_debug.bin 0x
```

If this works, then permissions are definitely the issue. However, running as root regularly isn't recommended due to potential security risks.

#### 2. Add User to Dialout and/or Plugdev Groups:

Many times, USB serial devices require that the user be part of the  `dialout`  and/or  `plugdev`  groups:

```
bash
Copy code

sudo usermod -a -G dialout $USER
sudo usermod -a -G plugdev $USER
```

After adding yourself to the groups, you'll need to log out and log back in (or restart) for the changes to take effect.

#### 3. Create Udev Rules:

For more granular control or if the above solutions do not work, you can add udev rules to give the necessary permissions:

- Create or edit a file in  `/etc/udev/rules.d/` , for example,  `99-esp.rules` .

```
bash
Copy code

sudo nano /etc/udev/rules.d/99-esp.rules
```

- Add the following rule to grant access to ESP devices:

```
makefile
Copy code

SUBSYSTEM=="usb", ATTR{idVendor}=="1a86", MODE="0666"
```

- Reload the udev rules:

```
bash
Copy code

sudo udevadm control --reload-rules
sudo udevadm trigger
```

#### 4. Check USB Device:

Make sure the USB device is properly connected. You can check connected USB devices with:

```
bash
Copy code

lsusb
```

i have an esp32c3 with an SHTC sensor, please use i2c to initiate the byte reads, give me the C program for it

Certainly! To read data from the SHTC sensor using I2C on an ESP32-C3, you'd first need to setup the I2C communication. Below is a basic C program outline that does this:

```
c Copy code

#include "esp_log.h"
#include "driver/i2c.h"

#define I2C_MASTER_NUM      I2C_NUM_0    // I2C port number
#define I2C_MASTER_SDA_IO   21           // GPIO number for I2C master d
#define I2C_MASTER_SCL_IO   22           // GPIO number for I2C master c
#define I2C_MASTER_FREQ_HZ  100000      // I2C master clock frequency
#define SHTC_I2C_ADDRESS    0x44        // Default I2C address for SHTC

#define WRITE_BIT            I2C_MASTER_WRITE
#define READ_BIT             I2C_MASTER_READ
#define ACK_CHECK_EN         true
#define ACK_CHECK_DIS        false
#define ACK_VAL               0x0
#define NACK_VAL              0x1

esp_err_t i2c_master_init(void) {
    i2c_config_t conf = {
        .mode = I2C_MODE_MASTER,
        .sda_io_num = I2C_MASTER_SDA_IO,
        .sda_pullup_en = GPIO_PULLUP_ENABLE,
        .scl_io_num = I2C_MASTER_SCL_IO,
        .scl_pullup_en = GPIO_PULLUP_ENABLE,
        .master.clk_speed = I2C_MASTER_FREQ_HZ,
    };
    return i2c_param_config(I2C_MASTER_NUM, &conf);
}

esp_err_t read_shtc_sensor(uint8_t *data_h, uint8_t *data_l) {
    if (!data_h || !data_l) {
        return ESP_ERR_INVALID_ARG;
    }

    i2c_cmd_handle_t cmd = i2c_cmd_link_create();
    i2c_master_start(cmd);
    i2c_master_write_byte(cmd, (SHTC_I2C_ADDRESS << 1) | READ_BIT, ACK_CHECK_EN);
    i2c_master_read_byte(cmd, data_h, ACK_VAL);
    i2c_master_read_byte(cmd, data_l, NACK_VAL);
    i2c_master_stop(cmd);
    esp_err_t ret = i2c_master_cmd_begin(I2C_MASTER_NUM, cmd, pdMS_TO_TICKS(1000));
    i2c_cmd_link_delete(cmd);

    return ret;
}

void app_main() {
    ESP_ERROR_CHECK(i2c_driver_install(I2C_MASTER_NUM, I2C_MODE_MASTER, 0, 0, ESP_ERROR_CHECK(i2c_master_init()));

    uint8_t data_h, data_l;
    while (1) {
        if (read_shtc_sensor(&data_h, &data_l) == ESP_OK) {
            ESP_LOGI("SHTC", "Data: %02x %02x", data_h, data_l);
        } else {
            ESP_LOGE("SHTC", "Failed to read data");
        }
        vTaskDelay(pdMS_TO_TICKS(1000));
    }
}
```

This is a very basic code to initiate the byte reads from the sensor. Here are some things to note:

Regen



riscv32-esp-elf-gdb: command not found

The error message "riscv32-esp-elf-gdb: command not found" suggests that the RISC-V GDB (GNU Debugger) toolchain for ESP (likely Espressif) is not installed or not available in the system's PATH.

Here are the steps you can take to resolve the issue:

1. **Install the Toolchain:**

If you haven't already installed the RISC-V toolchain for Espressif, you need to do so. Espressif provides detailed setup instructions for their development environment. Make sure you follow the instructions relevant to your platform (Linux, macOS, or Windows).

2. **Add to PATH:**

If the toolchain is already installed, it might just not be in your system's PATH. Here's how you can add it:

• **Linux/macOS:**

```
bash
export PATH=$PATH:/path/to/riscv32-esp-elf/bin
```

• **Windows (using Command Prompt):**

```
bash
set PATH=%PATH%;C:\path\to\riscv32-esp-elf\bin
```

Or, if using PowerShell:

```
powershell
$env:PATH += ";C:\path\to\riscv32-esp-elf\bin"
```

Replace `/path/to/riscv32-esp-elf/bin` or `C:\path\to\riscv32-esp-elf\bin` with the actual path where the toolchain is installed.

3. **Check Installation:**

After installing and adding the toolchain to your PATH, you can verify the installation by typing:

```
bash
riscv32-esp-elf-gdb --version
```

This should display the version details of the GDB installation.

4. **Persistent PATH Modification:**

Note that the commands given above to modify the PATH will only affect the current terminal session. To make the changes permanent, you'll need to add them to the appropriate startup file:

- On Linux, add the `export` command to `~/.bashrc` or `~/.zshrc` (based on your shell).
- On macOS, if using bash, add it to `~/.bash_profile` or `~/.zshrc` if using zsh.
- On Windows, you can add it through the Environment Variables settings in the System Properties.

5. **Alternative Tools:**

If you continue to face issues, consider checking if there's an alternative installation method or tool provided by Espressif or the community. Sometimes, there might be updates or newer tools that address common issues.

6. **Dependencies:**

Ensure all dependencies for the RISC-V GDB toolchain are installed. Sometimes, the tool might not run due to missing libraries or other software.

7. **Permissions:**

Ensure that the binary has the necessary execute permissions. On Linux/macOS, you can use:

```
bash
chmod +x /path/to/riscv32-esp-elf-gdb
```



riscv32-esp-elf-gdb lab2\_debug.elf  
riscv32-esp-elf-gdb: command not found

how do i run this command in ubuntu

If you're seeing the message "**riscv32-esp-elf-gdb: command not found**", it means the **riscv32-esp-elf-gdb** binary is not found in your system's PATH.

The **riscv32-esp-elf-gdb** is the GDB (GNU Debugger) toolchain for debugging RISC-V based chips, specifically for Espressif's ESP32-C3 and similar chips.

Here's how you can address the issue:

1. **Install the Toolchain:** If you haven't already installed the RISC-V toolchain for ESP32, follow Espressif's official documentation to install it. Typically, this involves downloading and extracting the toolchain, and then adding it to your system's PATH.
2. **Add to PATH:** If you have installed the toolchain but haven't added it to the PATH:
  - 2.1. Determine the directory where **riscv32-esp-elf-gdb** is located. You might have placed it in a directory when you downloaded and extracted the toolchain.
  - 2.2. Add that directory to your **PATH**:

```
bash Copy code

export PATH=$PATH:/path/to/riscv32-esp-elf-gdb-directory
```

Replace **/path/to/riscv32-esp-elf-gdb-directory** with the actual path to the directory containing the **riscv32-esp-elf-gdb** binary.

- 2.3. To make this change permanent, you can add the above **export** line to your **~/.bashrc** or **~/.profile** file.
3. **Run with Full Path:** Alternatively, you can run the **riscv32-esp-elf-gdb** command using its full path:

```
bash Copy code

/path/to/riscv32-esp-elf-gdb-directory/riscv32-esp-elf-gdb lab2_debug.elf
```

Again, replace **/path/to/riscv32-esp-elf-gdb-directory** with the actual path.

4. **Verify Installation:** To check if the toolchain binaries are correctly installed and accessible, you can type:

```
bash Copy code

which riscv32-esp-elf-gdb
```

This command should return the path to the binary if it's found.

5. **Installation via Package Manager:** In some cases, there might be a package available through a package manager like **apt**. You can search for the package using:

```
bash Copy code

sudo apt search riscv32-esp-elf-gdb
```

If it's available, you can install it using **sudo apt install**.

By following the above steps, you should be able to run **riscv32-esp-elf-gdb** on your Ubuntu machine. If the problem persists, please provide more details about your setup, and I'll be happy to help further!