Elliptic curves in Nemo

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Context

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Conclusion

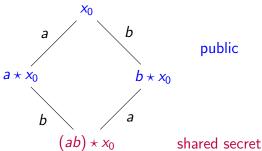
Let G be an abelian group acting on a set X with some given point x_0 . If the action is

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Context

• hard to invert (exponential time?),

then there is an analogue of the Diffie–Hellman key exchange [2].





Conclusion

The Couveignes-Rostovtsev-Stolbunov scheme

Question

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Answer [2], [3]

Use the action of a class group on a set of isogenous elliptic curves.

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Goals

- Explain what this means
- Describe the computations needed
- Discuss our EllipticCurves module for Nemo.

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Elliptic curves over k

• *Elliptic curves* over a field *k* are algebraic curves that have an abelian group structure, e.g.

$$E_1$$
: $y^2 + a_1xy = x^3 + a_2x^2 + a_4x + a_6$
 E_2 : $y^2 = x^3 + ax + b$
 E_3 : $By^2 = x^3 + Ax^2 + x$.

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• *Isogenies* are nonzero morphisms. Our isogenies will be defined over *k*. As rational maps, they have *degrees*.

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If we know this *kernel polynomial*, we can easily find E' using Vélu's formulas.

Action of the class group

Proposition

Let E/\mathbb{F}_p be an ordinary elliptic curve.

- The ring End(E) is isomorphic to a quadratic order O.
- For each prime number ℓ, there are either 2 (split case), 1 (ramified case) or 0 (inert case) ideals in O of norm ℓ.
 From now on, ℓ will always be prime, odd and split.
- Ideal of norm $\ell = \text{tuple } (\ell, v)$, $v \in \mathbb{Z}/\ell\mathbb{Z}$.
- There is an action on the set of elliptic curves with CM by \mathcal{O} . Ideals of norm ℓ act as ℓ -isogenies.
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How can we compute this action ?



Main algorithm

Problem

Given E/\mathbb{F}_p and a prime $\ell \neq p$, how can we compute the curves linked to E by an ℓ -isogeny?

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Most general idea

Let $\Phi_{\ell}(X,Y)$ be the ℓ^{th} classical modular polynomial. The two roots j_1,j_2 of

$$\Phi_{\ell}(j(E), Y)$$

are the *j*-invariants of the neighbors of E. To choose the one corresponding to an ideal (ℓ, ν) :

- ullet compute the kernel K(x) of the isogeny $E o j_1$
- check if the Frobenius acts on it as scalar mult. by v: $(x^p, y^p) \stackrel{?}{=} [v] \cdot (x, y) \mod K(x)$ and curve equation.

Question

How can we compute the kernel K(x) of ϕ : $E \rightarrow j_1$?

Bostan-Morain-Salvy-Schost [1]

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How can we compute the kernel K(x) of $\phi: E \to j_1$?

Idea

If ϕ is normalized, the rational fraction defining it satisfies a simple differential equation.

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Question

How can we compute the kernel K(x) of ϕ : $E \rightarrow j_1$?

Idea

If ϕ is *normalized*, the rational fraction defining it satisfies a simple differential equation.

Algorithm

- Normalize ϕ (involves evaluating modular polynomials)
- Solve this ODE in power series up to a certain precision with a Newton iteration
- Recover K(x) using the Berlekamp–Massey rational reconstruction algorithm.

Another solution

Problem

Given E/\mathbb{F}_p and a prime $\ell \neq p$, how can we compute the curves linked to E by an ℓ -isogeny?

Finding roots of modular polynomials is costly : $\Phi_{\ell}(X, Y)$ has degree $\ell+1$ in both variables.

Problem

Given E/\mathbb{F}_p and a prime $\ell \neq p$, how can we compute the curves linked to E by an ℓ -isogeny?

Finding roots of modular polynomials is costly : $\Phi_{\ell}(X, Y)$ has degree $\ell + 1$ in both variables.

More specific idea

Suppose that for some d, K is the only subgroup of order ℓ in E whose points are defined over \mathbb{F}_{p^d} .

- Look for ℓ -torsion points over this field to find K, using scalar multiplications
- Compute the curve E/K using Vélu's formulas.

The isogeny $E \to E/K$ has degree ℓ .

Context

This second method is only efficient with small-degree extensions.

Not every curve satisfies the conditions before for small d: we have to look for adequate curves.

In practice, we have to use both algorithms, general and specific.

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What we would like Nemo to do

In the general method:

Context

- Define elliptic curves over finite fields and general rings
- Define isogenies, sacalar multiplication and isomorphisms
- Find roots of polynomials over finite fields
- Solve ODEs in power series with Newton iterations
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In the specific method:

- Define points on elliptic curves
- Arithmetic operations on elliptic curves
- Extensions of finite fields.

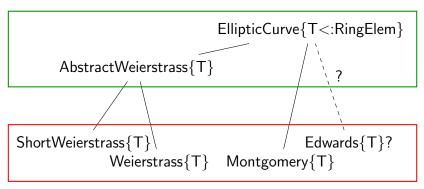


Types for curves

We want both Weierstrass models (all curves have one) and Montgomery models (efficient arithmetic).

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E.g. j-invariant is defined for the EllipticCurve type, while a-invariants is only defined for AbstractWeierstrass.



Types for maps

Maps can be isomorphisms between different models (evaluate on points), isogenies (compute image and kernels), scalar multiplications (both?).

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```
\begin{tabular}{ll} \hline Map\{T<:RingElem\} \\ \hline ExplicitMap\{T\} & Isogeny\{T\} \\ \hline \end{tabular}
```

```
\label{eq:continuous_transform} \begin{array}{lll} \text{immutable ExplicitMap}\{T\} & : & \text{Map}\{T\} & \text{immutable Isogeny}\{T\} <: & \text{Map}\{T\} \\ \text{domain::EllipticCurve}\{T\} & \text{domain::EllipticCurve}\{T\} \\ \text{image::EllipticCurve}\{T\} & \text{degree::Integer} \\ \text{map::Function} & \text{kernel::PolyElem}\{T\} \\ \text{end} & \text{image::EllipticCurve}\{T\} \\ \end{array}
```

Types for points

- Should points be attached with a curve?
- Arithmetic on Montgomery curves is much more efficient using only x-coordinates.

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```
ProjectivePoint{T<:RingElem}
     EllipticPoint{T}
                                  XonlyPoint\{T\}
type EllipticPoint{T} <:</pre>
                                     type XonlyPoint{T} <:</pre>
ProjectivePoint{T}
                                     ProjectivePoint{T}
X::T
                                     X::T
Y::T
                                     Z::T
7.::T
                                     curve::MontgomeryCurve{T}
curve::EllipticCurve{T}
                                     end
end
```

- Define curves, points and maps, check for equality and validity
- Basic functions such as invariants.
- Compute isomorphisms between different models
- Generic arithmetic on Weierstrass/Montgomery curves
- Efficient x-only arithmetic on Montgomery curves
- Division polynomials for ShortWeierstrass
- Isogeny computations: Vélu's formulas and the BMSS algorithm for short Weierstrass and Montgomery curves
- Modular polynomials (for small ℓ 's)
- Over finite fields: random points, torsion points, computation of Frobenius eigenvalues.



Context

In finite fields :

- Multiplicative orders
- Random elements
- Square roots
- Roots of polynomials and irreducible polynomials
- Field extensions over *prime* fields

Others:

• Derivatives of multivariate polynomials



Further possible development

- Call (system) PARI to compute the cardinality of curves over finite fields
- Compute modular polynomials/equations on the fly?
- Zeta functions?
- Have p-adic numbers to compute isogenies in small characteristic?
- Go down the arithmetic route for elliptic curves over number fields or local fields?

end

Three ways to compute roots over \mathbb{F}_p

At present, there is no direct way to do this in Nemo.

Sol. 1 (Nemo)

```
function roots(P)
A = parent(P)
X = gen(A)
R = ResidueRing(A, P)
Frob = R(X)^BigInt(p)
Frob = data(Frob)
g = gcd(Frob - X, P)
fact = factor(g)
... # recover roots
```

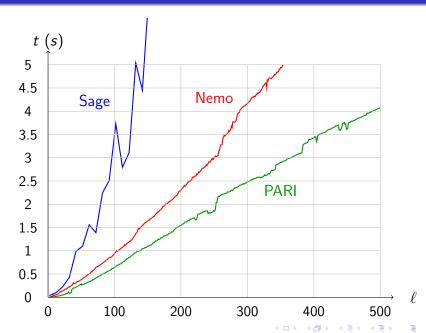
Sol. 2 (Sage/PARI)

```
def roots(P):
Q = pari(P)
rts = Q.polrootsmod(p)
return rts.sage()
```

Sol. 3 (Sage)

```
def roots(P):
A = P.parent()
X = A.gen()
R = A.quotient(P)
Frob = R(X)**p
Frob = Frob.lift()
g = gcd(Frob, P)
return g.roots()
```

Timing results



Three ways to compute scalar multiplications

Sol. 1 (Nemo)

```
E = Weierstrass(...)
Fext, _ = FiniteField(p^d, alpha)
Eext = base_extend(E, Fext)
P = random(Eext)
times(p^d, P)
```

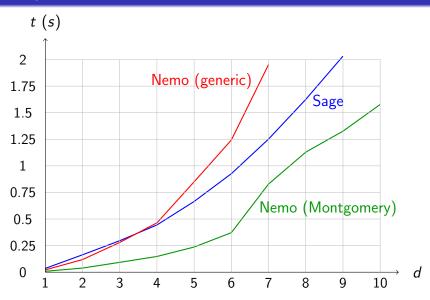
Sol. 2 (Nemo)

```
E = Montgomery(...)
Fext, _ = FiniteField(p, d, alpha)
Eext = base_extend(E, Fext)
P = randomXonly(Eext)
times(p^d, P)
```

Sol. 3 (Sage)

```
E = EllipticCurve(...)
Fext = FiniteField(p**d, "alpha")
Eext = E.base_extend(Fext)
P = Eext.random_element()
C = p**d
C * P
```

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Questions

- Can we do better to compute roots of polynomials over finite fields?
- Can we do better for non-prime finite fields?



Conclusion

Take home messages

• . . .

Thank you!

References



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- J.-M. Couveignes.
 Hard homogeneous spaces.
 preprint, 2006.
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