

1	Contest
2	Mathematics
3	Data structures
4	Numerical
5	Number theory
6	Combinatorial
7	Graph
8	Geometry
9	Strings
10	Various

Contest (1)

template.cpp	15 lines
<pre>#include <bits/stdc++.h> using namespace std; #define rep(i, a, b) for(int i = a; i < (b); ++i) #define trav(a, x) for(auto& a : x) #define all(x) begin(x), end(x) #define sz(x) (int)(x).size() typedef long long ll; typedef pair<int, int> pii; typedef vector<int> vi; int main() { cin.sync_with_stdio(0); cin.tie(0); cin.exceptions(cin.failbit); }</pre>	
.bashrc	3 lines
<pre>alias c='g++ -Wall -Wconversion -Wfatal-errors -g -std=c ++14 \ -fsanitize=undefined,address' xmodmap -e 'clear lock' -e 'keycode 66=less greater' #caps =◇</pre>	
.vimrc	6 lines
<pre>set cin aw ai is ts=4 sw=4 tm=50 nu noeb bg=dark ru cul sy on im jk <esc> im kj <esc> no ; : " Select region and then type :Hash to hash your selection. " Useful for verifying that there aren't mistypes. ca Hash w !cpp -dD -P -fpreprocessed \ tr -d '[:space:]' \ \ md5sum \ cut -c-6</pre>	
hash.sh	3 lines
<pre># Hashes a file, ignoring all whitespace and comments. Use for # verifying that code was correctly typed.</pre>	

1	cpp -dD -P -fpreprocessed tr -d '[:space:]' md5sum cut -c-6
1	troubleshoot.txt
3	Pre-submit: Write a few simple test cases if sample is not enough. Are time limits close? If so, generate max cases. Is the memory usage fine? Could anything overflow? Make sure to submit the right file.
7	Wrong answer: Print your solution! Print debug output, as well. Are you clearing all data structures between test cases? Can your algorithm handle the whole range of input? Read the full problem statement again. Do you handle all corner cases correctly? Have you understood the problem correctly? Any uninitialized variables? Any overflows? Confusing N and M, i and j, etc.? Are you sure your algorithm works? What special cases have you not thought of? Are you sure the STL functions you use work as you think? Add some assertions, maybe resubmit. Create some testcases to run your algorithm on. Go through the algorithm for a simple case. Go through this list again. Explain your algorithm to a teammate. Ask the teammate to look at your code. Go for a small walk, e.g. to the toilet. Is your output format correct? (including whitespace) Rewrite your solution from the start or let a teammate do it.
10	Runtime error: Have you tested all corner cases locally? Any uninitialized variables? Are you reading or writing outside the range of any vector? Any assertions that might fail? Any possible division by 0? (mod 0 for example) Any possible infinite recursion? Invalidated pointers or iterators? Are you using too much memory? Debug with resubmits (e.g. remapped signals, see Various).
16	Time limit exceeded: Do you have any possible infinite loops? What is the complexity of your algorithm? Are you copying a lot of unnecessary data? (References) How big is the input and output? (consider scanf) Avoid vector, map. (use arrays/unordered_map) What do your teammates think about your algorithm?
20	Memory limit exceeded: What is the max amount of memory your algorithm should need ?
22	Are you clearing all data structures between test cases?

Mathematics (2)

2.1 Equations

$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$
The extremum is given by $x = -b/2a$.

$$\begin{aligned} ax + by = e \quad x &= \frac{ed - bf}{ad - bc} \\ cx + dy = f \quad y &= \frac{af - ec}{ad - bc} \end{aligned} \Rightarrow$$

In general, given an equation $Ax = b$, the solution to a variable x_i is given by

$$x_i = \frac{\det A'_i}{\det A}$$

where A'_i is A with the i 'th column replaced by b .

2.2 Recurrences

If $a_n = c_1a_{n-1} + \dots + c_ka_{n-k}$, and r_1, \dots, r_k are distinct roots of $x^k + c_1x^{k-1} + \dots + c_k$, there are d_1, \dots, d_k s.t.

$$a_n = d_1r_1^n + \dots + d_kr_k^n.$$

Non-distinct roots r become polynomial factors, e.g. $a_n = (d_1n + d_2)r^n$.

2.3 Trigonometry

$$\begin{aligned} \sin(v + w) &= \sin v \cos w + \cos v \sin w \\ \cos(v + w) &= \cos v \cos w - \sin v \sin w \end{aligned}$$

$$\begin{aligned} \tan(v + w) &= \frac{\tan v + \tan w}{1 - \tan v \tan w} \\ \sin v + \sin w &= 2 \sin \frac{v + w}{2} \cos \frac{v - w}{2} \\ \cos v + \cos w &= 2 \cos \frac{v + w}{2} \cos \frac{v - w}{2} \end{aligned}$$

$$(V + W) \tan(v - w)/2 = (V - W) \tan(v + w)/2$$

where V, W are lengths of sides opposite angles v, w .

$$\begin{aligned} a \cos x + b \sin x &= r \cos(x - \phi) \\ a \sin x + b \cos x &= r \sin(x + \phi) \end{aligned}$$

where $r = \sqrt{a^2 + b^2}, \phi = \text{atan2}(b, a)$.

2.4 Geometry

2.4.1 Triangles

Side lengths: a, b, c
Semiperimeter: $p = \frac{a + b + c}{2}$

Area: $A = \sqrt{p(p-a)(p-b)(p-c)}$

Circumradius: $R = \frac{abc}{4A}$

Inradius: $r = \frac{A}{p}$

Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$

Length of bisector (divides angles in two):

$$s_a = \sqrt{bc \left[1 - \left(\frac{a}{b+c} \right)^2 \right]}$$

Law of sines: $\frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$

Law of cosines: $a^2 = b^2 + c^2 - 2bc \cos \alpha$

Law of tangents: $\frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$

2.4.2 Quadrilaterals

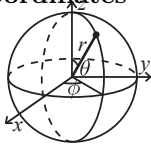
With side lengths a, b, c, d , diagonals e, f , diagonals angle θ , area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2 f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° , $ef = ac + bd$, and

$$A = \sqrt{(p-a)(p-b)(p-c)(p-d)}.$$

2.4.3 Spherical coordinates



$$\begin{aligned} x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \arccos(z / \sqrt{x^2 + y^2 + z^2}) \\ z &= r \cos \theta & \phi &= \operatorname{atan2}(y, x) \end{aligned}$$

2.5 Derivatives/Integrals

$$\frac{d}{dx} \arcsin x = \frac{1}{\sqrt{1-x^2}} \quad \frac{d}{dx} \arccos x = -\frac{1}{\sqrt{1-x^2}}$$
$$\frac{d}{dx} \tan x = 1 + \tan^2 x \quad \frac{d}{dx} \arctan x = \frac{1}{1+x^2}$$
$$\int \tan ax = -\frac{\ln |\cos ax|}{a} \quad \int x \sin ax = \frac{\sin ax - ax \cos ax}{a^2}$$
$$\int e^{-x^2} = \frac{\sqrt{\pi}}{2} \operatorname{erf}(x) \quad \int x e^{ax} dx = \frac{e^{ax}}{a^2} (ax - 1)$$

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

2.6 Sums

$$c^a + c^{a+1} + \dots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$1 + 2 + 3 + \dots + n = \frac{n(n+1)}{2}$$
$$1^2 + 2^2 + 3^2 + \dots + n^2 = \frac{n(2n+1)(n+1)}{6}$$
$$1^3 + 2^3 + 3^3 + \dots + n^3 = \frac{n^2(n+1)^2}{4}$$
$$1^4 + 2^4 + 3^4 + \dots + n^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}$$

2.7 Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots, (-\infty < x < \infty)$$
$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots, (-1 < x \leq 1)$$
$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \dots, (-1 \leq x \leq 1)$$
$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots, (-\infty < x < \infty)$$
$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots, (-\infty < x < \infty)$$

2.8 Probability theory

Let X be a discrete random variable with probability $p_X(x)$ of assuming the value x . It will then have an expected value (mean) $\mu = \mathbb{E}(X) = \sum_x x p_X(x)$ and variance

$$\sigma^2 = V(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \sum_x (x - \mathbb{E}(X))^2 p_X(x)$$

where σ is the standard deviation. If X is instead continuous it will have a probability density function $f_X(x)$ and the sums above will instead be integrals with $p_X(x)$ replaced by $f_X(x)$.

Expectation is linear:

$$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$$

For independent X and Y ,

$$V(aX + bY) = a^2V(X) + b^2V(Y).$$

2.8.1 Discrete distributions

Binomial distribution

The number of successes in n independent yes/no experiments, each which yields success with probability p is $\operatorname{Bin}(n, p)$, $n = 1, 2, \dots$, $0 \leq p \leq 1$.

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$\mu = np, \sigma^2 = np(1-p)$$

$\operatorname{Bin}(n, p)$ is approximately $\operatorname{Po}(np)$ for small p .

First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each wich yields success with probability p is $\operatorname{Fs}(p)$, $0 \leq p \leq 1$.

$$p(k) = p(1-p)^{k-1}, k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$$

Poisson distribution

The number of events occurring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $\operatorname{Po}(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, 2, \dots$$

$$\mu = \lambda, \sigma^2 = \lambda$$

2.8.2 Continuous distributions

Uniform distribution

If the probability density function is constant between a and b and 0 elsewhere it is $\operatorname{U}(a, b)$, $a < b$.

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$

$$\mu = \frac{a+b}{2}, \sigma^2 = \frac{(b-a)^2}{12}$$

Exponential distribution

The time between events in a Poisson process is $\text{Exp}(\lambda)$, $\lambda > 0$.

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\mu = \frac{1}{\lambda}, \sigma^2 = \frac{1}{\lambda^2}$$

Normal distribution

Most real random values with mean μ and variance σ^2 are well described by $\mathcal{N}(\mu, \sigma^2)$, $\sigma > 0$.

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$

2.9 Markov chains

A *Markov chain* is a discrete random process with the property that the next state depends only on the current state. Let X_1, X_2, \dots be a sequence of random variables generated by the Markov process. Then there is a transition matrix $\mathbf{P} = (p_{ij})$, with $p_{ij} = \Pr(X_n = i | X_{n-1} = j)$, and $\mathbf{p}^{(n)} = \mathbf{P}^n \mathbf{p}^{(0)}$ is the probability distribution for X_n (i.e., $p_i^{(n)} = \Pr(X_n = i)$), where $\mathbf{p}^{(0)}$ is the initial distribution.

π is a stationary distribution if $\pi = \pi \mathbf{P}$. If the Markov chain is *irreducible* (it is possible to get to any state from any state), then $\pi_i = \frac{1}{\mathbb{E}(T_i)}$ where $\mathbb{E}(T_i)$ is the expected time between two visits in state i . π_j/π_i is the expected number of visits in state j between two visits in state i .

For a connected, undirected and non-bipartite graph, where the transition probability is uniform among all neighbors, π_i is proportional to node i 's degree.

A Markov chain is *ergodic* if the asymptotic distribution is independent of the initial distribution. A finite Markov chain is ergodic iff it is irreducible and *aperiodic* (i.e., the gcd of cycle lengths is 1). $\lim_{k \rightarrow \infty} \mathbf{P}^k = \mathbf{1}\pi$.

A Markov chain is an A-chain if the states can be partitioned into two sets \mathbf{A} and \mathbf{G} , such that all states in \mathbf{A} are absorbing ($p_{ii} = 1$), and all states in \mathbf{G} leads to an absorbing state in \mathbf{A} . The probability for absorption in state $i \in \mathbf{A}$, when the initial state is j , is $a_{ij} = p_{ij} + \sum_{k \in \mathbf{G}} a_{ik} p_{kj}$. The expected time until absorption, when the initial state is i , is $t_i = 1 + \sum_{k \in \mathbf{G}} p_{ki} t_k$.

Data structures (3)

OrderStatisticTree.h

Description: A set (not multiset!) with support for finding the n'th element, and finding the index of an element. To get a map, change null_type.

Time: $\mathcal{O}(\log N)$

```
#include <bits/extc++.h>
using namespace __gnu_pbds;

template<class T>
using Tree = tree<T, null_type, less<T>, rb_tree_tag,
    tree_order_statistics_node_update>;

void example() {
    Tree<int> t, t2; t.insert(8);
    auto it = t.insert(10).first;
    assert(it == t.lower_bound(9));
    assert(t.order_of_key(10) == 1);
    assert(t.order_of_key(11) == 2);
    assert(*t.find_by_order(0) == 8);
    t.join(t2); // assuming T < T2 or T > T2, merge t2 into t
}
```

HashMap.h

Description: Hash map with the same API as unordered_map, but ~3x faster. Initial capacity must be a power of 2 (if provided).

1443bc, 7 lines

```
#include <bits/extc++.h>
// To use most bits rather than just the lowest ones:
struct chash {
    const uint64_t C = 1l(2e18 * M_PI) + 71; // large odd
    number
    1l operator()(1l x) const { return __builtin_bswap64(x*C)
        ; }
};
__gnu_pbds::gp_hash_table<1l,int,chash> h
    ({}, {}, {}, {}, {1<16});
```

SegmentTree.h

Description: Zero-indexed max-tree. Bounds are inclusive to the left and exclusive to the right. Can be changed by modifying T, f and unit.

Time: $\mathcal{O}(\log N)$

```
struct Tree {
    typedef int T;
    static constexpr T unit = INT_MIN;
    T f(T a, T b) { return max(a, b); } // (any associative fn)
    vector<T> s; int n;
    Tree(int n = 0, T def = unit) : s(2*n, def), n(n) {}
    void update(int pos, T val) {
        for (s[pos += n] = val; pos /= 2;)
            s[pos] = f(s[pos * 2], s[pos * 2 + 1]);
    }
    T query(int b, int e) { // query [b, e)
```

```
T ra = unit, rb = unit;
for (b += n, e += n; b < e; b /= 2, e /= 2) {
    if (b % 2) ra = f(ra, s[b++]);
    if (e % 2) rb = f(s[--e], rb);
}
return f(ra, rb);
};
```

LazySegmentTree.h

Description: Segment tree with ability to add or set values of large intervals, and compute max of intervals. Can be changed to other things. Use with a bump allocator for better performance, and SmallPtr or implicit indices to save memory.

Usage: Node* tr = new Node(v, 0, sz(v));

Time: $\mathcal{O}(\log N)$.

```
"/various/BumpAllocator.h"
34ecf5, 50 lines

const int inf = 1e9;
struct Node {
    Node *l = 0, *r = 0;
    int lo, hi, mset = inf, madd = 0, val = -inf;
    Node(int lo, int hi):lo(lo),hi(hi){} // Large interval of
        -inf
    Node(vi& v, int lo, int hi) : lo(lo), hi(hi) {
        if (lo + 1 < hi) {
            int mid = lo + (hi - lo)/2;
            l = new Node(v, lo, mid); r = new Node(v, mid, hi);
            val = max(l->val, r->val);
        }
        else val = v[lo];
    }
    int query(int L, int R) {
        if (R <= lo || hi <= L) return -inf;
        if (L <= lo && hi <= R) return val;
        push();
        return max(l->query(L, R), r->query(L, R));
    }
    void set(int L, int R, int x) {
        if (R <= lo || hi <= L) return;
        if (L <= lo && hi <= R) mset = val = x, madd = 0;
        else {
            push(), l->set(L, R, x), r->set(L, R, x);
            val = max(l->val, r->val);
        }
    }
    void add(int L, int R, int x) {
        if (R <= lo || hi <= L) return;
        if (L <= lo && hi <= R) {
            if (mset != inf) mset += x;
            else madd += x;
            val += x;
        }
        else {
            push(), l->add(L, R, x), r->add(L, R, x);
            val = max(l->val, r->val);
        }
    }
    void push() {
        if (!l) {
            int mid = lo + (hi - lo)/2;
            l = new Node(lo, mid); r = new Node(mid, hi);
        }
        if (mset != inf)
            l->set(lo,hi,mset), r->set(lo,hi,mset), mset = inf;
        else if (madd)
            l->add(lo,hi,madd), r->add(lo,hi,madd), madd = 0;
    }
};
```

UnionFind.h

Description: Disjoint-set data structure.

Time: $\mathcal{O}(\alpha(N))$

b5bfc3, 14 lines

```
struct UF {
    vi e;
    UF(int n) : e(n, -1) {}
    bool same_set(int a, int b) { return find(a) == find(b); }
    int size(int x) { return -e[find(x)]; }
    int find(int x) { return e[x] < 0 ? x : e[x] = find(e[x]); }
    bool join(int a, int b) {
        a = find(a), b = find(b);
        if (a == b) return false;
        if (e[a] > e[b]) swap(a, b);
        e[a] += e[b]; e[b] = a;
        return true;
    }
};
```

SubMatrix.h

Description: Calculate submatrix sums quickly, given upper-left and lower-right corners (half-open).

Usage: SubMatrix<int> m(matrix);

m.sum(0, 0, 2, 2); // top left 4 elements

Time: $\mathcal{O}(N^2 + Q)$

c59ada, 13 lines

```
template<class T>
struct SubMatrix {
    vector<vector<T>> p;
    SubMatrix(vector<vector<T>>& v) {
        int R = sz(v), C = sz(v[0]);
        p.assign(R+1, vector<T>(C+1));
        rep(r,0,R) rep(c,0,C)
            p[r+1][c+1] = v[r][c] + p[r][c+1] + p[r+1][c] - p[r][c];
    }
    T sum(int u, int l, int d, int r) {
        return p[d][r] - p[d][l] - p[u][r] + p[u][l];
    }
};
```

Matrix.h

Description: Basic operations on square matrices.

Usage: Matrix<int, 3> A;

A.d = {{{{1,2,3}}, {{4,5,6}}, {{7,8,9}}}};

vector<int> vec = {1,2,3};

vec = (A`N) * vec;

c43c7d, 26 lines

```
template<class T, int N> struct Matrix {
    typedef Matrix M;
    array<array<T, N>, N> d{};
    M operator*(const M& m) const {
        M a;
        rep(i,0,N) rep(j,0,N)
            rep(k,0,N) a.d[i][j] += d[i][k]*m.d[k][j];
        return a;
    }
    vector<T> operator*(const vector<T>& vec) const {
        vector<T> ret(N);
        rep(i,0,N) rep(j,0,N) ret[i] += d[i][j] * vec[j];
        return ret;
    }
    M operator^(ll p) const {
        assert(p >= 0);
        M a, b(*this);
        rep(i,0,N) a.d[i][i] = 1;
        while (p) {
            if (p&1) a = a*b;
            b = b*b;
        }
    }
};
```

```
        p >= 1;
    }
    return a;
};
```

LineContainer.h

Description: Container where you can add lines of the form $kx+m$, and query maximum values at points x . Useful for dynamic programming (“convex hull trick”).

Time: $\mathcal{O}(\log N)$

95e223, 30 lines

```
struct Line {
    mutable ll k, m, p;
    bool operator<(const Line& o) const { return k < o.k; }
    bool operator<(ll x) const { return p < x; }
};

struct LineContainer : multiset<Line, less<>> {
    // (for doubles, use inf = 1/.0, div(a,b) = a/b)
    const ll inf = LLONG_MAX;
    ll div(ll a, ll b) { // floored division
        return a / b - ((a ^ b) < 0 && a % b); }
    bool isect(iterator x, iterator y) {
        if (y == end()) { x->p = inf; return false; }
        if (x->k == y->k) x->p = x->m > y->m ? inf : -inf;
        else x->p = div(y->m - x->m, x->k - y->k);
        return x->p >= y->p;
    }
    void add(ll k, ll m) {
        auto z = insert({k, m, 0}), y = z++, x = y;
        while (isect(y, z)) z = erase(z);
        if (x != begin() && isect(--x, y)) isect(x, y = erase(y));
        while ((y = x) != begin() && (--x)->p >= y->p)
            isect(x, erase(y));
    }
    ll query(ll x) {
        assert(!empty());
        auto l = *lower_bound(x);
        return l.k * x + l.m;
    }
};
```

Treap.h

Description: A short self-balancing tree. It acts as a sequential container with log-time splits/joins, and is easy to augment with additional data.

Time: $\mathcal{O}(\log N)$

9556fc, 55 lines

```
struct Node {
    Node *l = 0, *r = 0;
    int val, y, c = 1;
    Node(int val) : val(val), y(rand()) {}
    void recalc();
};

int cnt(Node* n) { return n ? n->c : 0; }
void Node::recalc() { c = cnt(l) + cnt(r) + 1; }
```

```
template<class F> void each(Node* n, F f) {
    if (n) { each(n->l, f); f(n->val); each(n->r, f); }
}
```

```
pair<Node*, Node*> split(Node* n, int k) {
    if (!n) return {};
    if (cnt(n->l) >= k) { // "n->val >= k" for lower_bound(k)
        auto pa = split(n->l, k);
        n->l = pa.second;
        n->recalc();
        return {pa.first, n};
    }
}
```

```
    } else {
        auto pa = split(n->r, k - cnt(n->l) - 1); // and just "k"
        n->r = pa.first;
        n->recalc();
        return {n, pa.second};
    }
}
```

```
Node* merge(Node* l, Node* r) {
    if (!l) return r;
    if (!r) return l;
    if (l->y > r->y) {
        l->r = merge(l->r, r);
        l->recalc();
        return l;
    } else {
        r->l = merge(l, r->l);
        r->recalc();
        return r;
    }
}
```

```
Node* ins(Node* t, Node* n, int pos) {
    auto pa = split(t, pos);
    return merge(merge(pa.first, n), pa.second);
}
```

```
// Example application: move the range [l, r) to index k
void move(Node*& t, int l, int r, int k) {
    Node *a, *b, *c;
    tie(a,b) = split(t, l); tie(b,c) = split(b, r - l);
    if (k <= l) t = merge(ins(a, b, k), c);
    else t = merge(a, ins(c, b, k - r));
}
```

FenwickTree.h

Description: Computes partial sums $a[0] + a[1] + \dots + a[\text{pos} - 1]$, and updates single elements $a[i]$, taking the difference between the old and new value.

Time: Both operations are $\mathcal{O}(\log N)$.

e62fac, 22 lines

```
struct FT {
    vector<ll> s;
    FT(int n) : s(n) {}
    void update(int pos, ll dif) { // a[pos] += dif
        for (; pos < sz(s); pos |= pos + 1) s[pos] += dif;
    }
    ll query(int pos) { // sum of values in [0, pos)
        ll res = 0;
        for (; pos > 0; pos &= pos - 1) res += s[pos-1];
        return res;
    }
    int lower_bound(ll sum) { // min pos st sum of [0, pos] >= sum
        // Returns n if no sum is >= sum, or -1 if empty sum is
        .
        if (sum <= 0) return -1;
        int pos = 0;
        for (int pw = 1 << 25; pw; pw >= 1) {
            if (pos + pw <= sz(s) && s[pos + pw - 1] < sum)
                pos += pw, sum -= s[pos-1];
        }
        return pos;
    }
};
```

FenwickTreeShawn.cpp

835063, 10 lines

```
#define LSB(i) ((i) & -(i)) // zeroes all the bits except the least significant one
```

```
int A[SIZE];
int sum(int i) // Returns the sum from index 1 to i{
    int sum = 0;
    while (i > 0)
        sum += A[i], i -= LSB(i);
    return sum;}
void add(int i, int k) // Adds k to element with index i{
    while (i < SIZE)
        A[i] += k, i += LSB(i);}
```

FenwickTree2d.h

Description: Computes sums a[i,j] for all i<I, j<J, and increases single elements a[i,j]. Requires that the elements to be updated are known in advance (call fakeUpdate() before init()).
Time: $O(\log^2 N)$. (Use persistent segment trees for $O(\log N)$.)

```
"FenwickTree.h"
b28c27, 22 lines

struct FT2 {
    vector<vi> ys; vector<FT> ft;
    FT2(int limx) : ys(limx) {}
    void fakeUpdate(int x, int y) {
        for (; x < sz(ys); x |= x + 1) ys[x].push_back(y);
    }
    void init() {
        trav(v, ys) sort(all(v)), ft.emplace_back(sz(v));
    }
    int ind(int x, int y) {
        return (int)(lower_bound(all(ys[x]), y) - ys[x].begin())
        ); }
    void update(int x, int y, ll dif) {
        for (; x < sz(ys); x |= x + 1)
            ft[x].update(ind(x, y), dif);
    }
    ll query(int x, int y) {
        ll sum = 0;
        for (; x; x &= x - 1)
            sum += ft[x-1].query(ind(x-1, y));
        return sum;
    }
};
```

RMQ.h

Description: Range Minimum Queries on an array. Returns min(V[a], V[a + 1], ... V[b - 1]) in constant time.
Usage: RMQ rmq(values);
rmq.query(inclusive, exclusive);
Time: $O(|V|\log|V|+Q)$

```
template<class T>
struct RMQ {
    vector<vector<T>> jmp;
    RMQ(const vector<T>& V) {
        int N = sz(V), on = 1, depth = 1;
        while (on < N) on *= 2, depth++;
        jmp.assign(depth, V);
        rep(i,0,depth-1) rep(j,0,N)
            jmp[i+1][j] = min(jmp[i][j],
            jmp[i][min(N - 1, j + (1 << i))]);
    }
    T query(int a, int b) {
        assert(a < b); // or return inf if a == b
        int dep = 31 - __builtin_clz(b - a);
        return min(jmp[dep][a], jmp[dep][b - (1 << dep)]);
    }
};
```

Numerical (4)

4.1 Polynomials and recurrences

Polynomial.h

```
c9b7b0, 17 lines

struct Poly {
    vector<double> a;
    double operator()(double x) const {
        double val = 0;
        for(int i = sz(a); i--;) (val *= x) += a[i];
        return val;
    }
    void diff() {
        rep(i,1,sz(a)) a[i-1] = i*a[i];
        a.pop_back();
    }
    void divroot(double x0) {
        double b = a.back(), c; a.back() = 0;
        for(int i=sz(a)-1; i--;) c = a[i], a[i] = a[i+1]*x0+b,
            b=c;
        a.pop_back();
    }
};
```

PolyRoots.h

Description: Finds the real roots to a polynomial.
Usage: poly_roots({{2,-3,1}},-1e9,1e9) // solve $x^2-3x+2 = 0$
Time: $O(n^2 \log(1/\epsilon))$

```
"Polynomial.h"
2cf190, 23 lines

vector<double> poly_roots(Poly p, double xmin, double xmax)
{
    if (sz(p.a) == 2) { return {-p.a[0]/p.a[1]}; }
    vector<double> ret;
    Poly der = p;
    der.diff();
    auto dr = poly_roots(der, xmin, xmax);
    dr.push_back(xmin-1);
    dr.push_back(xmax+1);
    sort(all(dr));
    rep(i,0,sz(dr)-1) {
        double l = dr[i], h = dr[i+1];
        bool sign = p(l) > 0;
        if (sign ^ (p(h) > 0)) {
            rep(it,0,60) { // while (h - l > 1e-8)
                double m = (l + h) / 2, f = p(m);
                if ((f <= 0) ^ sign) l = m;
                else h = m;
            }
            ret.push_back((l + h) / 2);
        }
    }
    return ret;
}
```

PolyInterpolate.h

Description: Given n points $(x[i], y[i])$, computes an $n-1$ -degree polynomial p that passes through them: $p(x) = a[0]*x^0 + \dots + a[n-1]*x^{n-1}$. For numerical precision, pick $x[k] = c*\cos(k/(n-1)*\pi), k = 0 \dots n-1$.
Time: $O(n^2)$

```
08bf48, 13 lines

typedef vector<double> vd;
vd interpolate(vd x, vd y, int n) {
    vd res(n), temp(n);
    rep(k,0,n-1) rep(i,k+1,n)
        y[i] = (y[i] - y[k]) / (x[i] - x[k]);
    double last = 0; temp[0] = 1;
    rep(k,0,n) rep(i,0,n) {
        res[i] += y[k] * temp[i];
        swap(last, temp[i]);
    }
```

```
temp[i] -= last * x[k];
}
return res;
}
```

4.2 Optimization

GoldenSectionSearch.h

Description: Finds the argument minimizing the function f in the interval $[a,b]$ assuming f is unimodal on the interval, i.e. has only one local minimum. The maximum error in the result is ϵ ps. Works equally well for maximization with a small change in the code. See Ternary-Search.h in the Various chapter for a discrete version.
Usage: double func(double x) { return 4+x+.3*x*x; }
double xmin = gss(-1000,1000,func);
Time: $O(\log((b-a)/\epsilon))$

```
31d45b, 14 lines

double gss(double a, double b, double (*f)(double)) {
    double r = (sqrt(5)-1)/2, eps = 1e-7;
    double x1 = b - r*(b-a), x2 = a + r*(b-a);
    double f1 = f(x1), f2 = f(x2);
    while (b-a > eps)
        if (f1 < f2) { //change to > to find maximum
            b = x2; x2 = x1; f2 = f1;
            x1 = b - r*(b-a); f1 = f(x1);
        } else {
            a = x1; x1 = x2; f1 = f2;
            x2 = a + r*(b-a); f2 = f(x2);
        }
    return a;
}
```

HillClimbing.h

Description: Poor man's optimization for unimodal functions.

```
440e33, 16 lines

typedef array<double, 2> P;

double func(P p);

pair<double, P> hillClimb(P start) {
    pair<double, P> cur(func(start), start);
    for (double jmp = 1e9; jmp > 1e-20; jmp /= 2) {
        rep(j,0,100) rep(dx,-1,2) rep(dy,-1,2) {
            P p = cur.second;
            p[0] += dx*jmp;
            p[1] += dy*jmp;
            cur = min(cur, make_pair(func(p), p));
        }
    }
    return cur;
}
```

Integrate.h

Description: Simple integration of a function over an interval using Simpson's rule. The error should be proportional to h^4 , although in practice you will want to verify that the result is stable to desired precision when epsilon changes.

```
4756fc, 7 lines

template<class F>
double quad(double a, double b, F f, const int n = 1000) {
    double h = (b - a) / 2 / n, v = f(a) + f(b);
    rep(i,1,n*2)
        v += f(a + i*h) * (i&1 ? 4 : 2);
    return v * h / 3;
}
```

IntegrateAdaptive.h

Description: Fast integration using an adaptive Simpson's rule.

```
Usage: double sphereVolume = quad(-1, 1, [](double x) {
return quad(-1, 1, [&](double y) {
return quad(-1, 1, [&](double z) {
return x*x + y*y + z*z < 1; });});});};
92dd79, 15 lines
```

```
typedef double d;
#define S(a,b) (f(a) + 4*f((a+b) / 2) + f(b)) * (b-a) / 6

template <class F>
d rec(F& f, d a, d b, d eps, d S) {
    d c = (a + b) / 2;
    d S1 = S(a, c), S2 = S(c, b), T = S1 + S2;
    if (abs(T - S) <= 15 * eps || b - a < 1e-10)
        return T + (T - S) / 15;
    return rec(f, a, c, eps / 2, S1) + rec(f, c, b, eps / 2,
        S2);
}
template<class F>
d quad(d a, d b, F f, d eps = 1e-8) {
    return rec(f, a, b, eps, S(a, b));
}
```

Simplex.h

Description: Solves a general linear maximization problem: maximize $c^T x$ subject to $Ax \leq b$, $x \geq 0$. Returns -inf if there is no solution, inf if there are arbitrarily good solutions, or the maximum value of $c^T x$ otherwise. The input vector is set to an optimal x (or in the unbounded case, an arbitrary solution fulfilling the constraints). Numerical stability is not guaranteed. For better performance, define variables such that $x = 0$ is viable.

```
Usage: vvd A = {{1,-1}, {-1,1}, {-1,-2}};
vvd b = {1,1,-4}, c = {-1,-1}, x;
T val = LPSolver(A, b, c).solve(x);
Time:  $\mathcal{O}(NM * \#pivots)$ , where a pivot may be e.g. an edge relaxation.  $\mathcal{O}(2^n)$  in the general case.
aa8530, 68 lines
```

```
typedef double T; // long double, Rational, double + modP
>...
typedef vector<T> vd;
typedef vector<vd> vvd;
```

```
const T eps = 1e-8, inf = 1/.0;
#define MP make_pair
#define ltj(X) if(s == -1 || MP(X[j],N[j]) < MP(X[s],N[s]))
    s=j
```

```
struct LPSolver {
    int m, n;
    vi N, B;
    vvd D;

    LPSolver(const vvd& A, const vd& b, const vd& c) :
        m(sz(b)), n(sz(c)), N(n+1), B(m), D(m+2, vd(n+2)) {
        rep(i,0,m) rep(j,0,n) D[i][j] = A[i][j];
        rep(i,0,m) { B[i] = n+i; D[i][n] = -1; D[i][n+1] = b[i]
            i; }
        rep(j,0,n) { N[j] = j; D[m][j] = -c[j]; }
        N[n] = -1; D[m+1][n] = 1;
    }
}
```

```
void pivot(int r, int s) {
    T *a = D[r].data(), inv = 1 / a[s];
    rep(i,0,m+2) if (i != r && abs(D[i][s]) > eps) {
        T *b = D[i].data(), inv2 = b[s] * inv;
        rep(j,0,n+2) b[j] -= a[j] * inv2;
        b[s] = a[s] * inv2;
    }
    rep(j,0,n+2) if (j != s) D[r][j] *= inv;
    rep(i,0,m+2) if (i != r) D[i][s] *= -inv;
    D[r][s] = inv;
    swap(B[r], N[s]);
}
```

```
}

bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
        int s = -1;
        rep(j,0,n+1) if (N[j] != -phase) ltj(D[x]);
        if (D[x][s] >= -eps) return true;
        int r = -1;
        rep(i,0,m) {
            if (D[i][s] <= eps) continue;
            if (r == -1 || MP(D[i][n+1] / D[i][s], B[i])
                < MP(D[r][n+1] / D[r][s], B[r])) r = i
                ;
        }
        if (r == -1) return false;
        pivot(r, s);
    }
}
```

```
T solve(vd &x) {
    int r = 0;
    rep(i,1,m) if (D[i][n+1] < D[r][n+1]) r = i;
    if (D[r][n+1] < -eps) {
        pivot(r, n);
        if (!simplex(2) || D[m+1][n+1] < -eps) return -inf;
        rep(i,0,m) if (B[i] == -1) {
            int s = 0;
            rep(j,1,n+1) ltj(D[i]);
            pivot(i, s);
        }
    }
    bool ok = simplex(1); x = vd(n);
    rep(i,0,m) if (B[i] < n) x[B[i]] = D[i][n+1];
    return ok ? D[m][n+1] : inf;
}
};
```

4.3 Matrices

Determinant.h

Description: Calculates determinant of a matrix. Destroys the matrix.
Time: $\mathcal{O}(N^3)$

```
double det(vector<vector<double>>& a) {
    int n = sz(a); double res = 1;
    rep(i,0,n) {
        int b = i;
        rep(j,i+1,n) if (fabs(a[j][i]) > fabs(a[b][i])) b = j;
        if (i != b) swap(a[i], a[b]), res *= -1;
        res *= a[i][i];
        if (res == 0) return 0;
        rep(j,i+1,n) {
            double v = a[j][i] / a[i][i];
            if (v != 0) rep(k,i+1,n) a[j][k] -= v * a[i][k];
        }
    }
    return res;
}
```

IntDeterminant.h

Description: Calculates determinant using modular arithmetics. Modulos can also be removed to get a pure-integer version.
Time: $\mathcal{O}(N^3)$

```
const ll mod = 12345;
ll det(vector<vector<ll>>& a) {
    int n = sz(a); ll ans = 1;
    rep(i,0,n) {
        rep(j,i+1,n) {
            while (a[j][i] != 0) { // gcd step
```

```
            ll t = a[i][i] / a[j][i];
            if (t) rep(k,i,n)
                a[i][k] = (a[i][k] - a[j][k] * t) % mod;
            swap(a[i], a[j]);
            ans *= -1;
        }
    }
    ans = ans * a[i][i] % mod;
    if (!ans) return 0;
}
return (ans + mod) % mod;
}
```

SolveLinear.h

Description: Solves $A * x = b$. If there are multiple solutions, an arbitrary one is returned. Returns rank, or -1 if no solutions. Data in A and b is lost.

Time: $\mathcal{O}(n^2m)$

```
typedef vector<double> vd;
const double eps = 1e-12;
```

```
int solveLinear(vector<vd>& A, vd& b, vd& x) {
    int n = sz(A), m = sz(x), rank = 0, br, bc;
    if (n) assert(sz(A[0]) == m);
    vi col(m); iota(all(col), 0);
```

```
    rep(i,0,n) {
        double v, bv = 0;
        rep(r,i,n) rep(c,i,m)
            if ((v = fabs(A[r][c])) > bv)
                br = r, bc = c, bv = v;
        if (bv <= eps) {
            rep(j,i,n) if (fabs(b[j]) > eps) return -1;
            break;
        }
        swap(A[i], A[br]);
        swap(b[i], b[br]);
        swap(col[i], col[bc]);
        rep(j,0,n) swap(A[j][i], A[j][bc]);
        bv = 1/A[i][i];
        rep(j,i+1,n) {
            double fac = A[j][i] * bv;
            b[j] -= fac * b[i];
            rep(k,i+1,m) A[j][k] -= fac*A[i][k];
        }
        rank++;
    }
}
```

```
x.assign(m, 0);
for (int i = rank; i--;) {
    b[i] /= A[i][i];
    x[col[i]] = b[i];
    rep(j,0,i) b[j] -= A[j][i] * b[i];
}
return rank; // (multiple solutions if rank < m)
}
```

SolveLinear2.h

Description: To get all uniquely determined values of x back from SolveLinear, make the following changes:

"SolveLinear.h" 08e495, 7 lines

```
rep(j,0,n) if (j != i) // instead of rep(j,i+1,n)
    // ... then at the end:
x.assign(m, undefined);
rep(i,0,rank) {
    rep(j,rank,m) if (fabs(A[i][j]) > eps) goto fail;
    x[col[i]] = b[i] / A[i][i];
fail:; }
```

MatrixInverse.h

Description: Invert matrix A. Returns rank; result is stored in A unless singular (rank < n). Can easily be extended to prime moduli; for prime powers, repeatedly set $A^{-1} = A^{-1}(2I - AA^{-1}) \pmod{p^k}$ where A^{-1} starts as the inverse of A mod p, and k is doubled in each step.
Time: $\mathcal{O}(n^3)$

```
ebfff6, 35 lines
int matInv(vector<vector<double>>& A) {
    int n = sz(A); vi col(n);
    vector<vector<double>> tmp(n, vector<double>(n));
    rep(i,0,n) tmp[i][i] = 1, col[i] = i;

    rep(j,0,n) {
        int r = i, c = i;
        rep(j,i,n) rep(k,i,n)
            if (fabs(A[j][k]) > fabs(A[r][c]))
                r = j, c = k;
        if (fabs(A[r][c]) < 1e-12) return i;
        A[i].swap(A[r]); tmp[i].swap(tmp[r]);
        rep(j,0,n)
            swap(A[j][i], A[j][c]), swap(tmp[j][i], tmp[j][c]);
        swap(col[i], col[c]);
        double v = A[i][i];
        rep(j,i+1,n) {
            double f = A[j][i] / v;
            A[j][i] = 0;
            rep(k,i+1,n) A[j][k] -= f*A[i][k];
            rep(k,0,n) tmp[j][k] -= f*tmp[i][k];
        }
        rep(j,i+1,n) A[i][j] /= v;
        rep(j,0,n) tmp[i][j] /= v;
        A[i][i] = 1;
    }

    for (int i = n-1; i > 0; --i) rep(j,0,i) {
        double v = A[j][i];
        rep(k,0,n) tmp[j][k] -= v*tmp[i][k];
    }

    rep(i,0,n) rep(j,0,n) A[col[i]][col[j]] = tmp[i][j];
    return n;
}
```

Number theory (5)

5.1 Modular arithmetic

ModularArithmetic.h

Description: Operators for modular arithmetic. You need to set mod to some number first and then you can use the structure.

```
"euclid.h" 35bf6ea, 18 lines
const ll mod = 17; // change to something else
struct Mod {
    ll x;
    Mod(ll xx) : x(xx) {}
    Mod operator+(Mod b) { return Mod((x + b.x) % mod); }
    Mod operator-(Mod b) { return Mod((x - b.x + mod) % mod); }
    Mod operator*(Mod b) { return Mod((x * b.x) % mod); }
    Mod operator/(Mod b) { return *this * invert(b); }
    Mod invert(Mod a) {
        ll x, y, g = euclid(a.x, mod, x, y);
        assert(g == 1); return Mod((x + mod) % mod);
    }
    Mod operator^(ll e) {
        if (!e) return Mod(1);
        Mod r = *this ^ (e / 2); r = r * r;
        return e&1 ? *this * r : r;
    }
}
```

};

ModInverse.h

Description: Pre-computation of modular inverses. Assumes LIM ≤ mod and that mod is a prime.

```
6f684f, 3 lines
const ll mod = 10000000007, LIM = 200000;
ll* inv = new ll[LIM] - 1; inv[1] = 1;
rep(i,2,LIM) inv[i] = mod - (mod / i) * inv[mod % i] % mod;
```

ModPow.h

```
b83e45, 8 lines
const ll mod = 10000000007; // faster if const
```

```
ll modpow(ll b, ll e) {
    ll ans = 1;
    for (; e; b = b * b % mod, e /= 2)
        if (e & 1) ans = ans * b % mod;
    return ans;
}
```

ModLog.h

Description: Returns the smallest $x \geq 0$ s.t. $a^x = b \pmod m$. a and m must be coprime.

```
Time: O(sqrt(m)) 49d606, 10 lines
ll modLog(ll a, ll b, ll m) {
    assert(__gcd(a, m) == 1);
    ll n = (ll) sqrt(m) + 1, e = 1, x = 1, res = LLONG_MAX;
    unordered_map<ll, ll> f;
    rep(i,0,n) e = e * a % m;
    rep(i,0,n) x = x * e % m, f.emplace(x, i + 1);
    rep(i,0,n) if (f.count(b = b * a % m))
        res = min(res, f[b] * n - i - 1);
    return res;
}
```

ModSum.h

Description: Sums of mod'ed arithmetic progressions.
 $\text{modsum}(to, c, k, m) = \sum_{i=0}^{to-1} (ki + c) \% m$. divsum is similar but for floored division.
Time: $\log(m)$, with a large constant.

```
5c5bc5, 16 lines
typedef unsigned long long ull;
ull sumsq(ull to) { return to / 2 * ((to-1) | 1); }

ull divsum(ull to, ull c, ull k, ull m) {
    ull res = k / m * sumsq(to) + c / m * to;
    k %= m; c %= m;
    if (!k) return res;
    ull to2 = (to * k + c) / m;
    return res + (to - 1) * to2 - divsum(to2, m-1 - c, m, k);
}

ll modsum(ull to, ll c, ll k, ll m) {
    c = ((c % m) + m) % m;
    k = ((k % m) + m) % m;
    return to * c + k * sumsq(to) - m * divsum(to, c, k, m);
}
```

ModMulLL.h

Description: Calculate $a \cdot b \pmod c$ (or $a^b \pmod c$) for $0 \leq a, b < c < 2^{63}$.
Time: $\mathcal{O}(1)$ for mod_mul, $\mathcal{O}(\log b)$ for mod_pow

```
88c37a, 12 lines
typedef unsigned long long ull;
typedef long double ld;
ull mod_mul(ull a, ull b, ull M) {
    ll ret = a * b - M * ull(ld(a) * ld(b) / ld(M));
    return ret + M * (ret < 0) - M * (ret >= (ll)M);
}
```

```
ull mod_pow(ull b, ull e, ull mod) {
    ull ans = 1;
    for (; e; b = mod_mul(b, b, mod), e /= 2)
        if (e & 1) ans = mod_mul(ans, b, mod);
    return ans;
}
```

ModSqrt.h

Description: Tonelli-Shanks algorithm for modular square roots. Finds x s.t. $x^2 = a \pmod p$ (−x gives the other solution).
Time: $\mathcal{O}(\log^2 p)$ worst case, $\mathcal{O}(\log p)$ for most p

```
"ModPow.h" 19a793, 24 lines
ll sqrt(ll a, ll p) {
    a %= p; if (a < 0) a += p;
    if (a == 0) return 0;
    assert(modpow(a, (p-1)/2, p) == 1); // else no solution
    if (p % 4 == 3) return modpow(a, (p+1)/4, p);
    // a^(n+3)/8 or 2^(n+3)/8 * 2^(n-1)/4 works if p % 8 == 5
    ll s = p - 1, n = 2;
    int r = 0, m;
    while (s % 2 == 0)
        ++r, s /= 2;
    while (modpow(n, (p - 1) / 2, p) != p - 1) ++n;
    ll x = modpow(a, (s + 1) / 2, p);
    ll b = modpow(a, s, p), g = modpow(n, s, p);
    for (; r = m) {
        ll t = b;
        for (m = 0; m < r && t != 1; ++m)
            t = t * t % p;
        if (m == 0) return x;
        ll gs = modpow(g, 1LL << (r - m - 1), p);
        g = gs * gs % p;
        x = x * gs % p;
        b = b * g % p;
    }
}
```

5.2 Primality

eratosthenes.h

Description: Prime sieve for generating all primes up to a certain limit. isprime[i] is true iff i is a prime.
Time: $\text{lim}=100'000'000 \approx 0.8$ s. Runs 30% faster if only odd indices are stored.

```
29ed0a, 11 lines
const int MAX_PR = 5'000'000;
bitset<MAX_PR> isprime;
vi eratosthenes_sieve(int lim) {
    isprime.set(); isprime[0] = isprime[1] = 0;
    for (int i = 4; i < lim; i += 2) isprime[i] = 0;
    for (int i = 3; i*i < lim; i += 2) if (isprime[i])
        for (int j = i*i; j < lim; j += i*2) isprime[j] = 0;
    vi pr;
    rep(i,2,lim) if (isprime[i]) pr.push_back(i);
    return pr;
}
```

MillerRabin.h

Description: Deterministic Miller-Rabin primality test. Guaranteed to work for numbers up to 2^{64} ; for larger numbers, extend A randomly.
Time: 7 times the complexity of $a^b \pmod c$.

```
"ModMulLL.h" 6ab8e1, 12 lines
bool isPrime(ull n) {
    if (n < 2 || n % 6 % 4 != 1) return n - 2 < 2;
    ull A[] = {2, 325, 9375, 28178, 450775, 9780504,
        1795265022},
        s = __builtin_ctzll(n-1), d = n >> s;
    trav(a, A) { // ^ count trailing zeroes
        ull p = mod_pow(a, d, n), i = s;
        while (p != 1 && p != n - 1 && a % n && i--)
```

```
        p = mod_mul(p, p, n);
        if (p != n-1 && i != s) return 0;
    }
    return 1;
}
```

Factor.h
Description: Pollard-rho randomized factorization algorithm. Returns prime factors of a number, in arbitrary order (e.g. 2299 -> {11, 19, 11}).
Time: $\mathcal{O}\left(n^{1/4}\right)$ gcd calls, less for numbers with small factors.

```
"ModMullL.h", "MillerRabin.h"                                f5adaa, 18 lines
ull pollard(ull n) {
    auto f = [n](ull x) { return (mod_mul(x, x, n) + 1) % n;
    };
    if (!(n & 1)) return 2;
    for (ull i = 2;; i++) {
        ull x = i, y = f(x), p;
        while ((p = __gcd(n + y - x, n)) == 1)
            x = f(x), y = f(f(y));
        if (p != n) return p;
    }
}
vector<ull> factor(ull n) {
    if (n == 1) return {};
    if (isPrime(n)) return {n};
    ull x = pollard(n);
    auto l = factor(x), r = factor(n / x);
    l.insert(l.end(), all(r));
    return l;
}
```

5.3 Divisibility

euclid.h
Description: Finds two integers x and y , such that $ax+by = \gcd(a,b)$. If you just need gcd, use the built in `__gcd` instead. If a and b are coprime, then x is the inverse of $a \pmod b$.

```
ll euclid(ll a, ll b, ll &x, ll &y) {
    if (b) { ll d = euclid(b, a % b, y, x);
        return y -= a/b * x, d; }
    return x = 1, y = 0, a;
}
```

Euclid.java
Description: Finds {x, y, d} s.t. $ax + by = d = \gcd(a,b)$.

```
static BigInteger[] euclid(BigInteger a, BigInteger b) {
    BigInteger x = BigInteger.ONE, yy = x;
    BigInteger y = BigInteger.ZERO, xx = y;
    while (b.signum() != 0) {
        BigInteger q = a.divide(b), t = b;
        b = a.mod(b); a = t;
        t = xx; xx = x.subtract(q.multiply(xx)); x = t;
        t = yy; yy = y.subtract(q.multiply(yy)); y = t;
    }
    return new BigInteger[]{x, y, a};
}
```

CRT.h
Description: Chinese Remainder Theorem.
`crt(a, m, b, n)` computes x such that $x \equiv a \pmod m$, $x \equiv b \pmod n$. If $|a| < m$ and $|b| < n$, x will obey $0 \leq x < \text{lcm}(m,n)$. Assumes $mn < 2^{62}$.
Time: $\log(n)$

```
"euclid.h"                                04d93a, 7 lines
ll crt(ll a, ll m, ll b, ll n) {
    if (n > m) swap(a, b), swap(m, n);
    ll x, y, g = euclid(m, n, x, y);
```

```
assert((a - b) % g == 0); // else no solution
x = (b - a) % n * x % n / g * m + a;
return x < 0 ? x + m*n/g : x;
}
```

5.3.1 Bézout’s identity
For $a \neq, b \neq 0$, then $d = \gcd(a,b)$ is the smallest positive integer for which there are integer solutions to

$$ax + by = d$$

If (x,y) is one solution, then all solutions are given by

$$\left(x + \frac{kb}{\gcd(a,b)}, y - \frac{ka}{\gcd(a,b)}\right), \quad k \in \mathbb{Z}$$

phiFunction.h
Description: Euler’s ϕ function is defined as $\phi(n) := \#$ of positive integers $\leq n$ that are coprime with n . $\phi(1) = 1$, p prime $\Rightarrow \phi(p^k) = (p-1)p^{k-1}$, m, n coprime $\Rightarrow \phi(mn) = \phi(m)\phi(n)$. If $n = p_1^{k_1}p_2^{k_2}\dots p_r^{k_r}$ then $\phi(n) = (p_1-1)p_1^{k_1-1}\dots(p_r-1)p_r^{k_r-1}$. $\phi(n) = n \cdot \prod_{p|n} (1-1/p)$. $\sum_{d|n} \phi(d) = n$, $\sum_{1 \leq k \leq n, \gcd(k,n)=1} k = n\phi(n)/2, n > 1$.
Euler’s thm: a, n coprime $\Rightarrow a^{\phi(n)} \equiv 1 \pmod n$.
Fermat’s little thm: p prime $\Rightarrow a^{p-1} \equiv 1 \pmod p \ \forall a$.

```
const int LIM = 5000000;
int phi[LIM];

void calculatePhi() {
    rep(i,0,LIM) phi[i] = i&1 ? i : i/2;
    for(int i = 3; i < LIM; i += 2) if(phi[i] == i)
        for(int j = i; j < LIM; j += i) phi[j] -= phi[j] / i;
}
```

5.4 Fractions

FracBinarySearch.h
Description: Given f and N , finds the smallest fraction $p/q \in [0,1]$ such that $f(p/q)$ is true, and $p,q \leq N$. You may want to throw an exception from f if it finds an exact solution, in which case N can be removed.
Usage: `fracBS([](Frac f) { return f.p>=3*f.q; }, 10);` // {1,3}
Time: $\mathcal{O}(\log(N))$

```
struct Frac { ll p, q; };

template<class F>
Frac fracBS(F f, ll N) {
    bool dir = 1, A = 1, B = 1;
    Frac lo{0, 1}, hi{1, 1}; // Set hi to 1/0 to search (0, N
    ]
    if (f(lo)) return lo;
    assert(f(hi));
    while (A || B) {
        ll adv = 0, step = 1; // move hi if dir, else lo
        for (int si = 0; step; (step *= 2) >= si) {
            adv += step;
            Frac mid{lo.p * adv + hi.p, lo.q * adv + hi.q};
            if (abs(mid.p) > N || mid.q > N || dir == !f(mid)) {
                adv -= step; si = 2;
            }
        }
        hi.p += lo.p * adv;
        hi.q += lo.q * adv;
        dir = !dir;
```

```
        swap(lo, hi);
        A = B; B = !!adv;
    }
    return dir ? hi : lo;
}
```

5.5 Pythagorean Triples
The Pythagorean triples are uniquely generated by

$$a = k \cdot (m^2 - n^2), \quad b = k \cdot (2mn), \quad c = k \cdot (m^2 + n^2),$$

with $m > n > 0, k > 0, m \perp n$, and either m or n even.

5.6 Primes

$p = 962592769$ is such that $2^{21} \mid p-1$, which may be useful. For hashing use 970592641 (31-bit number), 31443539979727 (45-bit), 3006703054056749 (52-bit). There are 78498 primes less than 1 000 000.

Primitive roots exist modulo any prime power p^a , except for $p = 2, a > 2$, and there are $\phi(\phi(p^a))$ many. For $p = 2, a > 2$, the group $\mathbb{Z}_{2^a}^\times$ is instead isomorphic to $\mathbb{Z}_2 \times \mathbb{Z}_{2^{a-2}}$.

5.7 Estimates

$$\sum_{d|n} d = \mathcal{O}(n \log \log n).$$

The number of divisors of n is at most around 100 for $n < 5e4$, 500 for $n < 1e7$, 2000 for $n < 1e10$, 200 000 for $n < 1e19$.

Combinatorial (6)

6.1 Permutations

6.1.1 Factorial

n	1	2	3	4	5	6	7	8	9	10
$n!$	1	2	6	24	120	720	5040	40320	362880	3628800
n	11	12	13	14	15	16	17			
$n!$	4.0e7	4.8e8	6.2e9	8.7e10	1.3e12	2.1e13	3.6e14			
n	20	25	30	40	50	100	150	171		
$n!$	2e18	2e25	3e32	8e47	3e64	9e157	6e262	>DBL.MAX		

IntPerm.h
Description: Permutation -> integer conversion. (Not order preserv-ing.) Integer -> permutation can use a lookup table.
Time: $\mathcal{O}(n)$

```
e1b8ea, 6 lines
int permToInt(vi& v) {
    int use = 0, i = 0, r = 0;
    trav(x, v) r = r * ++i + __builtin_popcount(use & -(1 <<
        x)),
        use |= 1 << x;
    // (note: minus, not ~!)
```



```
    return r;
}
```

6.1.2 Cycles

Let $g_S(n)$ be the number of n -permutations whose cycle lengths all belong to the set S . Then

$$\sum_{n=0}^\infty g_S(n) \frac{x^n}{n!} = \exp\left(\sum_{n \in S} \frac{x^n}{n}\right)$$

6.1.3 Derangements

Permutations of a set such that none of the elements appear in their original position.

$$D(n) = (n-1)(D(n-1)+D(n-2)) = nD(n-1)+(-1)^n =$$

6.1.4 Burnside’s lemma

Given a group G of symmetries and a set X , the number of elements of X up to symmetry equals

$$\frac{1}{|G|} \sum_{g \in G} |X^g|,$$

where X^g are the elements fixed by g ($g.x = x$).

If $f(n)$ counts “configurations” (of some sort) of length n , we can ignore rotational symmetry using $G = \mathbb{Z}_n$ to get

$$g(n) = \frac{1}{n} \sum_{k=0}^{n-1} f(\gcd(n, k)) = \frac{1}{n} \sum_{k|n} f(k) \phi(n/k).$$

6.2 Partitions and subsets

6.2.1 Partition function

Number of ways of writing n as a sum of positive integers, disregarding the order of the summands.

$$p(0) = 1, \; p(n) = \sum_{k \in \mathbb{Z} \setminus \{0\}} (-1)^{k+1} p(n - k(3k - 1)/2)$$

$$p(n) \sim 0.145/n \cdot \exp(2.56\sqrt{n})$$

n	0	1	2	3	4	5	6	7	8	9	20	50	100
$p(n)$	1	1	2	3	5	7	11	15	22	30	627	$\sim 2\text{e}5$	$\sim 2\text{e}8$

6.2.2 Binomials

binomialModPrime.h
Description: Lucas’ thm: Let n, m be non-negative integers and p a prime. Write $n = n_k p^k + \dots + n_1 p + n_0$ and $m = m_k p^k + \dots + m_1 p + m_0$. Then $\binom{n}{m} \equiv \prod_{i=0}^k \binom{n_i}{m_i} \pmod{p}$. fact and invfact must hold pre-computed factorials / inverse factorials, e.g. from ModInverse.h.

Time: $\mathcal{O}(\log_p n)$

81845f, 10 lines

```
ll chooseModP(ll n, ll m, int p, vi& fact, vi& invfact) {
    ll c = 1;
    while (n || m) {
        ll a = n % p, b = m % p;
        if (a < b) return 0;
        c = c * fact[a] % p * invfact[b] % p * invfact[a - b] %
            p;
        n /= p; m /= p;
    }
    return c;
}
```

multinomial.h

Description: Computes $\binom{k_1 + \dots + k_n}{k_1, k_2, \dots, k_n} = \frac{(\sum k_i)!}{k_1! k_2! \dots k_n!}$.

a0a312, 6 lines

```
ll multinomial(vi& v) {
    ll c = 1, m = v.empty() ? 1 : v[0];
    rep(i, 1, sz(v)) rep(j, 0, v[i])
        c = c * ++m / (j+1);
    return c;
}
```

6.3 General purpose numbers

6.3.1 Bernoulli numbers

EGF of Bernoulli numbers is $B(t) = \frac{t}{e^t - 1}$ (FFT-able).

$$B[0, \dots] = [1, -\tfrac{1}{2}, \tfrac{1}{6}, 0, -\tfrac{1}{30}, 0, \tfrac{1}{42}, \dots]$$

Sums of powers:

$$\sum_{i=1}^n n^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k \cdot (n+1)^{m+1-k}$$

Euler-Maclaurin formula for infinite sums:

$$\sum_{i=m}^\infty f(i) = \int_m^\infty f(x)dx - \sum_{k=1}^\infty \frac{B_k}{k!} f^{(k-1)}(m)$$

$$\approx \int_m^\infty f(x)dx + \frac{f(m)}{2} - \frac{f'(m)}{12} + \frac{f'''(m)}{720} + O(f^{(5)}(m))$$

6.3.2 Stirling numbers of the first kind

Number of permutations on n items with k cycles.

$$c(n, k) = c(n - 1, k - 1) + (n - 1)c(n - 1, k), \; c(0, 0) = 1$$

$$\sum_{k=0}^n c(n, k) x^k = x(x + 1) \dots (x + n - 1)$$

$$c(8, k) =$$

8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1

$$c(n, 2) =$$

0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, ...

6.3.3 Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k j :s s.t. $\pi(j) > \pi(j + 1)$, $k + 1$ j :s s.t. $\pi(j) \geq j$, k j :s s.t. $\pi(j) > j$.

$$E(n, k) = (n - k)E(n - 1, k - 1) + (k + 1)E(n - 1, k)$$

$$E(n, 0) = E(n, n - 1) = 1$$

$$E(n, k) = \sum_{j=0}^k (-1)^j \binom{n+1}{j} (k+1-j)^n$$

6.3.4 Stirling numbers of the second kind

Partitions of n distinct elements into exactly k groups.

$$S(n, k) = S(n - 1, k - 1) + kS(n - 1, k)$$

$$S(n, 1) = S(n, n) = 1$$

$$S(n, k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

6.3.5 Bell numbers

Total number of partitions of n distinct elements. $B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \dots$. For p prime,

$$B(p^m + n) \equiv mB(n) + B(n + 1) \pmod{p}$$

6.3.6 Labeled unrooted trees

on n vertices: n^{n-2}
on k existing trees of size n_i : $n_1 n_2 \dots n_k n^{k-2}$
with degrees d_i : $(n - 2)! / ((d_1 - 1)! \dots (d_n - 1)!)$

6.3.7 Catalan numbers

$$C_n = \frac{1}{n+1} \binom{2n}{n} = \binom{2n}{n} - \binom{2n}{n+1} = \frac{(2n)!}{(n+1)!n!}$$

$$C_0 = 1, \; C_{n+1} = \frac{2(2n+1)}{n+2} C_n, \; C_{n+1} = \sum C_i C_{n-i}$$

$$C_n = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, \dots$$

- sub-diagonal monotone paths in an $n \times n$ grid.
- strings with n pairs of parenthesis, correctly nested.

- binary trees with with $n + 1$ leaves (0 or 2 children).
- ordered trees with $n + 1$ vertices.
- ways a convex polygon with $n + 2$ sides can be cut into triangles by connecting vertices with straight lines.
- permutations of $[n]$ with no 3-term increasing subseq.

Graph (7)

7.1 Fundamentals

Dijkstra.h

Description: Finds the shortest path from s to all other nodes. AL is an adjacency list.

```
824d98, 16 lines
vi dijkstra(vector<vii> &AL, int s) {
    priority_queue<ii, vector<ii>, greater<ii>> pq;
    vi dist(V, INF); //INF = 0x3f3f3f3f
    dist[s] = 0;
    pq.push({0, s});
    while (!pq.empty()) {
        auto [d, u] = pq.top(); pq.pop();
        if (d > dist[u]) continue;
        for (auto &[v, w] : AL[u]) {
            if (dist[u]+w >= dist[v]) continue;
            dist[v] = dist[u]+w;
            pq.push({dist[v], v});
        }
    }
    return dist;
}
```

BellmanFord2.h

Description: Calculates shortest paths from s in a graph that might have negative edge weights. Dist should be of size $|AL|$ and all values initialized to inf

```
af3e7c, 23 lines
Time:  $\mathcal{O}(VE)$ 
void bellmanFord(vector<vii>& AL, vi &dist, int s) {
    dist[s] = 0;
    int V = AL.size();
    for (int i = 0; i < V-1; ++i) {
        bool modified = false;
        for (int u = 0; u < V; ++u)
            if (dist[u] != INF) // INF = 1e9
                for (auto &[v, w] : AL[u]) {
                    if (dist[u]+w >= dist[v]) continue;
                    dist[v] = dist[u]+w;
                    modified = true;
                }
        if (!modified) break;
    }

    // Return true if negative cycle
    for (int u = 0; u < V; ++u)
        if (dist[u] != INF)
            for (auto &[v, w] : AL[u])
                if (dist[v] > dist[u]+w)
                    return true;
    return false
}
```

FloydWarshall.h

Description: Calculates all-pairs shortest path in a directed graph that might have negative edge weights. Input is an distance matrix m , where $m[i][j] = \text{inf}$ if i and j are not adjacent. As output, $m[i][j]$ is set to the shortest distance between i and j , inf if no path, or -inf if the path goes through a negative-weight cycle.

```
531245, 12 lines
Time:  $\mathcal{O}(N^3)$ 
const ll inf = 1LL << 62;
void floydWarshall(vector<vector<ll>>& m) {
    int n = sz(m);
    rep(i,0,n) m[i][i] = min(m[i][i], 0LL);
    rep(k,0,n) rep(i,0,n) rep(j,0,n)
        if (m[i][k] != inf && m[k][j] != inf) {
            auto newDist = max(m[i][k] + m[k][j], -inf);
            m[i][j] = min(m[i][j], newDist);
        }
    rep(k,0,n) if (m[k][k] < 0) rep(i,0,n) rep(j,0,n)
        if (m[i][k] != inf && m[k][j] != inf) m[i][j] = -inf;
}
```

TopoSort.h

Description: Topological sorting. Given is an oriented graph. Output is an ordering of vertices, such that there are edges only from left to right. If there are cycles, the returned list will have size smaller than n – nodes reachable from cycles will not be returned.

```
22a53d, 14 lines
Time:  $\mathcal{O}(|V| + |E|)$ 
vi topo_sort(const vector<vi>& gr) {
    vi indeg(sz(gr)), ret;
    trav(li, gr) trav(x, li) indeg[x]++;
    queue<int> q; // use priority queue for lexic. smallest ans.
    rep(i,0,sz(gr)) if (indeg[i] == 0) q.push(-i);
    while (!q.empty()) {
        int i = -q.front(); // top() for priority queue
        ret.push_back(i);
        q.pop();
        trav(x, gr[i])
            if (--indeg[x] == 0) q.push(-x);
    }
    return ret;
}
```

7.2 Euler walk

EulerWalk.h

Description: Eulerian undirected/directed path/cycle algorithm. Input should be a vector of (dest, global edge index), where for undirected graphs, forward/backward edges have the same index. Returns a list of nodes in the Eulerian path/cycle with src at both start and end, or empty list if no cycle/path exists. To get edge indices back, add .second to s and ret.

```
648189, 15 lines
Time:  $\mathcal{O}(V + E)$ 
vi eulerWalk(vector<vector<pii>>& gr, int nedges, int src = 0) {
    int n = sz(gr);
    vi D(n), its(n), eu(nedges), ret, s = {src};
    D[src]++; // to allow Euler paths, not just cycles
    while (!s.empty()) {
        int x = s.back(), y, e, &it = its[x], end = sz(gr[x]);
        if (it == end){ ret.push_back(x); s.pop_back();
            continue; }
        tie(y, e) = gr[x][it++];
        if (!eu[e]) {
            D[x]--, D[y]++;
            eu[e] = 1; s.push_back(y);
        }
    }
    trav(x, D) if (x < 0 || sz(ret) != nedges+1) return {};
    return {ret.rbegin(), ret.rend()};
}
```

7.3 Network flow

PushRelabel.h

Description: Push-relabel using the highest label selection rule and the gap heuristic. Quite fast in practice. To obtain the actual flow, look at positive values only.

```
3df61b, 50 lines
Time:  $\mathcal{O}(V^2\sqrt{E})$ 
typedef ll Flow;
struct Edge {
    int dest, back;
    Flow f, c;
};

struct PushRelabel {
    vector<vector<Edge>> g;
    vector<Flow> ec;
    vector<Edge*> cur;
    vector<vi> hs; vi H;
    PushRelabel(int n) : g(n), ec(n), cur(n), hs(2*n), H(n) {}

    void add_edge(int s, int t, Flow cap, Flow rcap=0) {
        if (s == t) return;
        g[s].push_back({t, sz(g[t]), 0, cap});
        g[t].push_back({s, sz(g[s])-1, 0, rcap});
    }

    void add_flow(Edge& e, Flow f) {
        Edge &back = g[e.dest][e.back];
        if (!ec[e.dest] && f) hs[H[e.dest]].push_back(e.dest);
        e.f += f; e.c -= f; ec[e.dest] += f;
        back.f -= f; back.c += f; ec[back.dest] -= f;
    }

    Flow maxflow(int s, int t) {
        int v = sz(g); H[s] = v; ec[t] = 1;
        vi co(2*v); co[0] = v-1;
        rep(i,0,v) cur[i] = g[i].data();
        trav(e, g[s]) add_flow(e, e.c);

        for (int hi = 0;;) {
            while (hs[hi].empty()) if (!hi--) return -ec[s];
            int u = hs[hi].back(); hs[hi].pop_back();
            while (ec[u] > 0) // discharge u
                if (cur[u] == g[u].data() + sz(g[u])) {
                    H[u] = 1e9;
                    trav(e, g[u]) if (e.c && H[u] > H[e.dest]+1)
                        H[u] = H[e.dest]+1, cur[u] = &e;
                    if (++co[H[u]], !--co[hi] && hi < v)
                        rep(i,0,v) if (hi < H[i] && H[i] < v)
                            --co[H[i]], H[i] = v + 1;
                    hi = H[u];
                } else if (cur[u]->c && H[u] == H[cur[u]->dest]+1)
                    add_flow(*cur[u], min(ec[u], cur[u]->c));
                else ++cur[u];
            }
        }
        bool leftOfMinCut(int a) { return H[a] >= sz(g); }
    };
};
```

MinCostMaxFlow.h

Description: Min-cost max-flow. $\text{cap}[i][j] \neq \text{cap}[j][i]$ is allowed; double edges are not. If costs can be negative, call setpi before maxflow, but note that negative cost cycles are not supported. To obtain the actual flow, look at positive values only.

```
6915ce, 81 lines
Time: Approximately  $\mathcal{O}(E^2)$ 
#include <bits/extc++.h>

const ll INF = numeric_limits<ll>::max() / 4;
typedef vector<ll> VL;
```

```
struct MCMF {
    int N;
    vector<vi> ed, red;
    vector<VL> cap, flow, cost;
    vi seen;
    VL dist, pi;
    vector<pii> par;

    MCMF(int N) :
        N(N), ed(N), red(N), cap(N, VL(N)), flow(cap), cost(cap),
        seen(N), dist(N), pi(N), par(N) {}

    void addEdge(int from, int to, ll cap, ll cost) {
        this->cap[from][to] = cap;
        this->cost[from][to] = cost;
        ed[from].push_back(to);
        red[to].push_back(from);
    }

    void path(int s) {
        fill(all(seen), 0);
        fill(all(dist), INF);
        dist[s] = 0; ll di;

        __gnu_pbds::priority_queue<pair<ll, int>> q;
        vector<decltype(q)::point_iterator> its(N);
        q.push({0, s});

        auto relax = [&](int i, ll cap, ll cost, int dir) {
            ll val = di - pi[i] + cost;
            if (cap && val < dist[i]) {
                dist[i] = val;
                par[i] = {s, dir};
                if (its[i] == q.end()) its[i] = q.push({-dist[i], i});
            } else q.modify(its[i], {-dist[i], i});
        };

        while (!q.empty()) {
            s = q.top().second; q.pop();
            seen[s] = 1; di = dist[s] + pi[s];
            trav(i, ed[s]) if (!seen[i])
                relax(i, cap[s][i] - flow[s][i], cost[s][i], 1);
            trav(i, red[s]) if (!seen[i])
                relax(i, flow[i][s], -cost[i][s], 0);
        }
        rep(i,0,N) pi[i] = min(pi[i] + dist[i], INF);
    }

    pair<ll, ll> maxflow(int s, int t) {
        ll totflow = 0, totcost = 0;
        while (path(s), seen[t]) {
            ll fl = INF;
            for (int p,r,x = t; tie(p,r) = par[x], x != s; x = p)
                fl = min(fl, r ? cap[p][x] - flow[p][x] : flow[x][p]);
            totflow += fl;
            for (int p,r,x = t; tie(p,r) = par[x], x != s; x = p)
                if (r) flow[p][x] += fl;
                else flow[x][p] -= fl;
        }
        rep(i,0,N) rep(j,0,N) totcost += cost[i][j] * flow[i][j];
        return {totflow, totcost};
    }
};

// If some costs can be negative, call this before maxflow:
```

```
void setpi(int s) { // (otherwise, leave this out)
    fill(all(pi), INF); pi[s] = 0;
    int it = N, ch = 1; ll v;
    while (ch-- && it--)
        rep(i,0,N) if (pi[i] != INF)
            trav(to, ed[i]) if (cap[i][to])
                if ((v = pi[i] + cost[i][to]) < pi[to])
                    pi[to] = v, ch = 1;
    assert(it >= 0); // negative cost cycle
};
```

EdmondsKarp.h

Description: Flow algorithm with guaranteed complexity $O(VE^2)$. To get edge flow values, compare capacities before and after, and take the positive values only.

979bb9, 35 lines

```
template<class T> T edmondsKarp(vector<unordered_map<int, T>>& graph, int source, int sink) {
    assert(source != sink);
    T flow = 0;
    vi par(sz(graph)), q = par;

    for (;;) {
        fill(all(par), -1);
        par[source] = 0;
        int ptr = 1;
        q[0] = source;

        rep(i,0,ptr) {
            int x = q[i];
            trav(e, graph[x]) {
                if (par[e.first] == -1 && e.second > 0) {
                    par[e.first] = x;
                    q[ptr++] = e.first;
                    if (e.first == sink) goto out;
                }
            }
        }
        return flow;
    out:
        T inc = numeric_limits<T>::max();
        for (int y = sink; y != source; y = par[y])
            inc = min(inc, graph[par[y]][y]);

        flow += inc;
        for (int y = sink; y != source; y = par[y]) {
            int p = par[y];
            if ((graph[p][y] == inc) <= 0) graph[p].erase(y);
            graph[y][p] += inc;
        }
    }
};
```

FordFulkerson.java

Time: $O(V^2 * FLOW)$

7dc63d, 28 lines

```
public class MaxFlowFordFulkerson {
    public static int maxFlow(int[][] cap, int s, int t) {
        for (int flow = 0;;) {
            int df = findPath(cap, new boolean[cap.length], s, t, Integer.MAX_VALUE);
            if (df == 0) return flow;
            flow += df;
        }
    }

    static int findPath(int[][] cap, boolean[] vis, int u, int t, int f) {
        if (u == t) return f;
        vis[u] = true;
        for (int v = 0; v < vis.length; v++)
```

```
        if (!vis[v] && cap[u][v] > 0) {
            int df = findPath(cap, vis, v, t, Math.min(f, cap[u][v]));
            if (df > 0) {
                cap[u][v] -= df;
                cap[v][u] += df;
                return df;
            }
        }
        return 0;
    }

    // Usage example
    public static void main(String[] args) {
        int[][] capacity = { { 0, 3, 2 }, { 0, 0, 2 }, { 0, 0, 0 } };
        System.out.println(4 == maxFlow(capacity, 0, 2));
    }
}
```

MinCut.h

Description: After running max-flow, the left side of a min-cut from s to t is given by all vertices reachable from s , only traversing edges with positive residual capacity.

GlobalMinCut.h

Description: Find a global minimum cut in an undirected graph, as represented by an adjacency matrix.

Time: $O(V^3)$

03261f, 31 lines

```
pair<int, vi> GetMinCut(vector<vi>& weights) {
    int N = sz(weights);
    vi used(N), cut, best_cut;
    int best_weight = -1;

    for (int phase = N-1; phase >= 0; phase--) {
        vi w = weights[0], added = used;
        int prev, k = 0;
        rep(i,0,phase) {
            prev = k;
            k = -1;
            rep(j,1,N)
                if (!added[j] && (k == -1 || w[j] > w[k])) k = j;
            if (i == phase-1) {
                rep(j,0,N) weights[prev][j] += weights[k][j];
                rep(j,0,N) weights[j][prev] = weights[prev][j];
                used[k] = true;
                cut.push_back(k);
                if (best_weight == -1 || w[k] < best_weight) {
                    best_cut = cut;
                    best_weight = w[k];
                }
            } else {
                rep(j,0,N)
                    w[j] += weights[k][j];
                added[k] = true;
            }
        }
    }
    return {best_weight, best_cut};
}
```

7.4 Matching

hopcroftKarp.h

Description: Fast bipartite matching algorithm. Graph g should be a list of neighbors of the left partition, and $btoa$ should be a vector full of -1's of the same size as the right partition. Returns the size of the matching. $btoa[i]$ will be the match for vertex i on the right side, or -1 if it's not matched.

Usage: vi btoa(m, -1); hopcroftKarp(g, btoa);

Time: $\mathcal{O}(\sqrt{VE})$

536939, 42 lines

```
bool dfs(int a, int L, vector<vi>& g, vi& btoa, vi& A, vi& B) {
    if (A[a] != L) return 0;
    A[a] = -1;
    trav(b, g[a]) if (B[b] == L + 1) {
        B[b] = 0;
        if (btoa[b] == -1 || dfs(btoa[b], L + 1, g, btoa, A, B))
            return btoa[b] = a, 1;
    }
    return 0;
}

int hopcroftKarp(vector<vi>& g, vi& btoa) {
    int res = 0;
    vi A(g.size(), B(btoa.size(), cur, next);
    for (;;) {
        fill(all(A), 0);
        fill(all(B), 0);
        cur.clear();
        trav(a, btoa) if(a != -1) A[a] = -1;
        rep(a,0,sz(g)) if(A[a] == 0) cur.push_back(a);
        for (int lay = 1;; lay++) {
            bool islast = 0;
            next.clear();
            trav(a, cur) trav(b, g[a]) {
                if (btoa[b] == -1) {
                    B[b] = lay;
                    islast = 1;
                }
                else if (btoa[b] != a && !B[b]) {
                    B[b] = lay;
                    next.push_back(btoa[b]);
                }
            }
            if (islast) break;
            if (next.empty()) return res;
            trav(a, next) A[a] = lay;
            cur.swap(next);
        }
        rep(a,0,sz(g))
            res += dfs(a, 0, g, btoa, A, B);
    }
}
```

DFSMatching.h

Description: Simple bipartite matching algorithm. Graph g should be a list of neighbors of the left partition, and $btoa$ should be a vector full of -1's of the same size as the right partition. Returns the size of the matching. $btoa[i]$ will be the match for vertex i on the right side, or -1 if it's not matched.

Usage: vi btoa(m, -1); dfsMatching(g, btoa);

Time: $\mathcal{O}(VE)$

6a3472, 22 lines

```
bool find(int j, vector<vi>& g, vi& btoa, vi& vis) {
    if (btoa[j] == -1) return 1;
    vis[j] = 1; int di = btoa[j];
    trav(e, g[di])
        if (!vis[e] && find(e, g, btoa, vis)) {
            btoa[e] = di;
            return 1;
        }
    return 0;
}

int dfsMatching(vector<vi>& g, vi& btoa) {
    vi vis;
    rep(i,0,sz(g)) {
        vis.assign(sz(btoa), 0);
        trav(j,g[i])
```

```
        if (find(j, g, btoa, vis)) {
            btoa[j] = i;
            break;
        }
    }
    return sz(btoa) - (int)count(all(btoa), -1);
}

"DFSMatching.h" d0b3f2, 20 lines

vi cover(vector<vi>& g, int n, int m) {
    vi match(m, -1);
    int res = dfsMatching(g, match);
    vector<bool> lfound(n, true), seen(m);
    trav(it, match) if (it != -1) lfound[it] = false;
    vi q, cover;
    rep(i,0,n) if (lfound[i]) q.push_back(i);
    while (!q.empty()) {
        int i = q.back(); q.pop_back();
        lfound[i] = 1;
        trav(e, g[i]) if (!seen[e] && match[e] != -1) {
            seen[e] = true;
            q.push_back(match[e]);
        }
    }
    rep(i,0,n) if (!lfound[i]) cover.push_back(i);
    rep(i,0,m) if (seen[i]) cover.push_back(n+i);
    assert(sz(cover) == res);
    return cover;
}
```

WeightedMatching.h

Description: Min cost bipartite matching. Negate costs for max cost.

Time: $\mathcal{O}(N^3)$

055ca9, 75 lines

```
typedef vector<double> vd;
bool zero(double x) { return fabs(x) < 1e-10; }
double MinCostMatching(const vector<vd>& cost, vi& L, vi& R) {
    int n = sz(cost), mated = 0;
    vd dist(n), u(n), v(n);
    vi dad(n), seen(n);

    rep(i,0,n) {
        u[i] = cost[i][0];
        rep(j,1,n) u[i] = min(u[i], cost[i][j]);
    }
    rep(j,0,n) {
        v[j] = cost[0][j] - u[0];
        rep(i,1,n) v[j] = min(v[j], cost[i][j] - u[i]);
    }

    L = R = vi(n, -1);
    rep(i,0,n) rep(j,0,n) {
        if (R[j] != -1) continue;
        if (zero(cost[i][j] - u[i] - v[j])) {
            L[i] = j;
            R[j] = i;
            mated++;
            break;
        }
    }

    for (; mated < n; mated++) { // until solution is feasible
        int s = 0;
        while (L[s] != -1) s++;
```

```
        fill(all(dad), -1);
        fill(all(seen), 0);
        rep(k,0,n)
            dist[k] = cost[s][k] - u[s] - v[k];

        int j = 0;
        for (;;) {
            j = -1;
            rep(k,0,n){
                if (seen[k]) continue;
                if (j == -1 || dist[k] < dist[j]) j = k;
            }
            seen[j] = 1;
            int i = R[j];
            if (i == -1) break;
            rep(k,0,n) {
                if (seen[k]) continue;
                auto new_dist = dist[j] + cost[i][k] - u[i] - v[k];
                if (dist[k] > new_dist) {
                    dist[k] = new_dist;
                    dad[k] = j;
                }
            }
        }

        rep(k,0,n) {
            if (k == j || !seen[k]) continue;
            auto w = dist[k] - dist[j];
            v[k] += w, u[R[k]] -= w;
        }
        u[s] += dist[j];

        while (dad[j] >= 0) {
            int d = dad[j];
            R[j] = R[d];
            L[R[j]] = j;
            j = d;
        }
        R[j] = s;
        L[s] = j;
    }

    auto value = vd(1)[0];
    rep(i,0,n) value += cost[i][L[i]];
    return value;
}
```

GeneralMatching.h

Description: Matching for general graphs. Fails with probability N/mod .

Time: $\mathcal{O}(N^3)$

```
    } while (matInv(A = mat) != M);

vi has(M, 1); vector<pii> ret;
rep(it,0,M/2) {
    rep(i,0,M) if (has[i])
        rep(j,i+1,M) if (A[i][j] && mat[i][j]) {
            fi = i; fj = j; goto done;
        } assert(0); done:
    if (fj < N) ret.emplace_back(fi, fj);
    has[fi] = has[fj] = 0;
    rep(sw,0,2) {
        ll a = modpow(A[fi][fj], mod-2);
        rep(i,0,M) if (has[i] && A[i][fj]) {
            ll b = A[i][fj] * a % mod;
            rep(j,0,M) A[i][j] = (A[i][j] - A[fi][j] * b) % mod
                ;
        }
        swap(fi,fj);
    }
}
return ret;
}
```

7.5 DFS algorithms

SCC.h
Description: Finds strongly connected components in a directed graph. If vertices *u,v* belong to the same component, we can reach *u* from *v* and vice versa.
Usage: scc(graph, [&](vi& v) { ... }) visits all components in reverse topological order. comp[i] holds the component index of a node (a component only has edges to components with lower index). ncomps will contain the number of components.
Time: $\mathcal{O}(E + V)$

bb2963, 24 lines

```
vi val, comp, z, cont;
int Time, ncomps;
template<class G, class F> int dfs(int j, G& g, F& f) {
    int low = val[j] = ++Time, x; z.push_back(j);
    trav(e,g[j]) if (comp[e] < 0)
        low = min(low, val[e] ?: dfs(e,g,f));

    if (low == val[j]) {
        do {
            x = z.back(); z.pop_back();
            comp[x] = ncomps;
            cont.push_back(x);
        } while (x != j);
        f(cont); cont.clear();
        ncomps++;
    }
    return val[j] = low;
}
template<class G, class F> void scc(G& g, F f) {
    int n = sz(g);
    val.assign(n, 0); comp.assign(n, -1);
    Time = ncomps = 0;
    rep(i,0,n) if (comp[i] < 0) dfs(i, g, f);
}
```

BiconnectedComponents.h

Description: Finds all biconnected components in an undirected graph, and runs a callback for the edges in each. In a biconnected component there are at least two distinct paths between any two nodes. Note that a node can be in several components. An edge which is not in a component is a bridge, i.e., not part of any cycle.

Usage: int eid = 0; ed.resize(N);
for each edge (a,b) {
 ed[a].emplace_back(b, eid);
 ed[b].emplace_back(a, eid++);
} bicomps([&](const vi& edgelist) {...});
Time: $\mathcal{O}(E + V)$

cca7e6, 33 lines

```
vi num, st;
vector<vector<pii>> ed;
int Time;
template<class F>
int dfs(int at, int par, F& f) {
    int me = num[at] = ++Time, e, y, top = me;
    trav(pa, ed[at]) if (pa.second != par) {
        tie(y, e) = pa;
        if (num[y]) {
            top = min(top, num[y]);
            if (num[y] < me)
                st.push_back(e);
        } else {
            int si = sz(st);
            int up = dfs(y, e, f);
            top = min(top, up);
            if (up == me) {
                st.push_back(e);
                f(vi(st.begin() + si, st.end()));
                st.resize(si);
            }
            else if (up < me) st.push_back(e);
            else { /* e is a bridge */ }
        }
    }
    return top;
}

template<class F>
void bicomps(F f) {
    num.assign(sz(ed), 0);
    rep(i,0,sz(ed)) if (!num[i]) dfs(i, -1, f);
}
```

0911c1, 56 lines

2sat.h

Description: Calculates a valid assignment to boolean variables a, b, c,... to a 2-SAT problem, so that an expression of the type $(a||b)&&(!a||c)&&(d||!b)&&...$ becomes true, or reports that it is unsatisfiable. Negated variables are represented by bit-inversions (~x).
Usage: TwoSat ts(number of boolean variables);
ts.either(0, ~3); // Var 0 is true or var 3 is false
ts.set.value(2); // Var 2 is true
ts.at.most.one({0,~1,2}); // <= 1 of vars 0, ~1 and 2 are true
ts.solve(); // Returns true iff it is solvable
ts.values[0..N-1] holds the assigned values to the vars
Time: $\mathcal{O}(N + E)$, where N is the number of boolean variables, and E is the number of clauses.

```
struct TwoSat {
    int N;
    vector<vi> gr;
    vi values; // 0 = false, 1 = true

    TwoSat(int n = 0) : N(n), gr(2*n) {}

    int add_var() { // (optional)
        gr.emplace_back();
        gr.emplace_back();
        return N++;
    }

    void either(int f, int j) {
        f = max(2*f, -1-2*j);
```

```
        j = max(2*j, -1-2*j);
        gr[f].push_back(j^1);
        gr[j].push_back(f^1);
    }

    void set_value(int x) { either(x, x); }

    void at_most_one(const vi& li) { // (optional)
        if (sz(li) <= 1) return;
        int cur = ~li[0];
        rep(i,2,sz(li)) {
            int next = add_var();
            either(cur, ~li[i]);
            either(cur, next);
            either(~li[i], next);
            cur = ~next;
        }
        either(cur, ~li[1]);
    }

    vi val, comp, z; int time = 0;
    int dfs(int i) {
        int low = val[i] = ++time, x; z.push_back(i);
        trav(e, gr[i]) if (!comp[e])
            low = min(low, val[e] ?: dfs(e));
        if (low == val[i]) do {
            x = z.back(); z.pop_back();
            comp[x] = low;
            if (values[x]>1) == -1)
                values[x]>1 = x&1;
        } while (x != i);
        return val[i] = low;
    }

    bool solve() {
        values.assign(N, -1);
        val.assign(2*N, 0); comp = val;
        rep(i,0,2*N) if (!comp[i]) dfs(i);
        rep(i,0,N) if (comp[2*i] == comp[2*i+1]) return 0;
        return 1;
    }
};
```

7.6 Heuristics

MaximalCliques.h

Description: Runs a callback for all maximal cliques in a graph (given as a symmetric bitset matrix; self-edges not allowed). Callback is given a bitset representing the maximal clique.
Time: $\mathcal{O}(3^{n/3})$, much faster for sparse graphs

b0d5b1, 12 lines

```
typedef bitset<128> B;
template<class F>
void cliques(vector<B>& eds, F f, B P = ~B(), B X={}, B R
    ={}) {
    if (!P.any()) { if (!X.any()) f(R); return; }
    auto q = (P | X).Find_first();
    auto cands = P & ~eds[q];
    rep(i,0,sz(eds)) if (cands[i]) {
        R[i] = 1;
        cliques(eds, f, P & eds[i], X & eds[i], R);
        R[i] = P[i] = 0; X[i] = 1;
    }
}
```

MaximumClique.h

Description: Quickly finds a maximum clique of a graph (given as symmetric bitset matrix; self-edges not allowed). Can be used to find a maximum independent set by finding a clique of the complement graph.
Time: Runs in about 1s for n=155 and worst case random graphs (p=.90). Runs faster for sparse graphs.

fbbef1, 49 lines

```
typedef vector<bitset<200>> vb;
struct Maxclique {
    double limit=0.025, pk=0;
    struct Vertex { int i, d=0; };
    typedef vector<Vertex> vv;
    vb e;
    vv V;
    vector<vi> C;
    vi qmax, q, S, old;
    void init(vv& r) {
        trav(v,r) v.d = 0;
        trav(v, r) trav(j, r) v.d += e[v.i][j.i];
        sort(all(r), [](auto a, auto b) { return a.d > b.d; });
        int mxD = r[0].d;
        rep(i,0,sz(r)) r[i].d = min(i, mxD) + 1;
    }
    void expand(vv& R, int lev = 1) {
        S[lev] += S[lev - 1] - old[lev];
        old[lev] = S[lev - 1];
        while (sz(R)) {
            if (sz(q) + R.back().d <= sz(qmax)) return;
            q.push_back(R.back().i);
            vv T;
            trav(v,R) if (e[R.back().i][v.i]) T.push_back({v.i});
            if (sz(T)) {
                if (S[lev]++ / ++pk < limit) init(T);
                int j = 0, mxk = 1, mnk = max(sz(qmax) - sz(q) + 1, 1);
                C[1].clear(), C[2].clear();
                trav(v, T) {
                    int k = 1;
                    auto f = [&](int i) { return e[v.i][i]; };
                    while (any_of(all(C[k]), f)) k++;
                    if (k > mxk) mxk = k, C[mxk + 1].clear();
                    if (k < mnk) T[j++] .i = v.i;
                    C[k].push_back(v.i);
                }
                if (j > 0) T[j - 1].d = 0;
                rep(k,mnk,mxk + 1) trav(i, C[k])
                    T[j].i = i, T[j++].d = k;
                expand(T, lev + 1);
            } else if (sz(q) > sz(qmax)) qmax = q;
            q.pop_back(), R.pop_back();
        }
    }
    vi maxClique() { init(V), expand(V); return qmax; }
    Maxclique(vb conn) : e(conn), C(sz(e)+1), S(sz(C)), old(S)
    ) {
        rep(i,0,sz(e)) V.push_back({i});
    }
};
```

MaximumIndependentSet.h

Description: To obtain a maximum independent set of a graph, find a max clique of the complement. If the graph is bipartite, see MinimumVertexCover.

7.7 Trees

TreePower.h

Description: Calculate power of two jumps in a tree, to support fast upward jumps and LCAs. Assumes the root node points to itself.

Time: construction $\mathcal{O}(N \log N)$, queries $\mathcal{O}(\log N)$

bfce85, 25 lines

```
vector<vi> treeJump(vi& P){
    int on = 1, d = 1;
    while(on < sz(P)) on *= 2, d++;
    vector<vi> jmp(d, P);
    rep(i,1,d) rep(j,0,sz(P))
        jmp[i][j] = jmp[i-1][jmp[i-1][j]];
```

```
    return jmp;
}

int jmp(vector<vi>& tbl, int nod, int steps){
    rep(i,0,sz(tbl))
        if(steps&(1<<i)) nod = tbl[i][nod];
    return nod;
}

int lca(vector<vi>& tbl, vi& depth, int a, int b) {
    if (depth[a] < depth[b]) swap(a, b);
    a = jmp(tbl, a, depth[a] - depth[b]);
    if (a == b) return a;
    for (int i = sz(tbl); i--;) {
        int c = tbl[i][a], d = tbl[i][b];
        if (c != d) a = c, b = d;
    }
    return tbl[0][a];
}
```

LCA.h

Description: Data structure for computing lowest common ancestors in a tree (with 0 as root). C should be an adjacency list of the tree, either directed or undirected. Can also find the distance between two nodes.

Usage: LCA lca(undirGraph);
lca.query(firstNode, secondNode);
lca.distance(firstNode, secondNode);

Time: $\mathcal{O}(N \log N + Q)$

aa0d4d, 37 lines

```
typedef vector<pii> vpi;
typedef vector<vpi> graph;

struct LCA {
    vi time;
    vector<ll> dist;
    RMQ<pii> rmq;

    LCA(graph& C) : time(sz(C), -99), dist(sz(C)), rmq(dfs(C)
    ) {}

    vpi dfs(graph& C) {
        vector<tuple<int, int, int, ll>> q(1);
        vpi ret;
        int T = 0, v, p, d; ll di;
        while (!q.empty()) {
            tie(v, p, d, di) = q.back();
            q.pop_back();
            if (d) ret.emplace_back(d, p);
            time[v] = T++;
            dist[v] = di;
            trav(e, C[v]) if (e.first != p)
                q.emplace_back(e.first, v, d+1, di + e.second);
        }
        return ret;
    }

    int query(int a, int b) {
        if (a == b) return a;
        a = time[a], b = time[b];
        return rmq.query(min(a, b), max(a, b)).second;
    }

    ll distance(int a, int b) {
        int lca = query(a, b);
        return dist[a] + dist[b] - 2 * dist[lca];
    }
};
```

CompressTree.h

Description: Given a rooted tree and a subset S of nodes, compute the minimal subtree that contains all the nodes by adding all (at most $|S| - 1$) pairwise LCA's and compressing edges. Returns a list of (par, orig_index) representing a tree rooted at 0. The root points to itself.

Time: $\mathcal{O}(|S| \log |S|)$

dabd75, 20 lines

```
"LCA.h"
vpi compressTree(LCA& lca, const vi& subset) {
    static vi rev; rev.resize(sz(lca.dist));
    vi li = subset, &T = lca.time;
    auto cmp = [&](int a, int b) { return T[a] < T[b]; };
    sort(all(li), cmp);
    int m = sz(li)-1;
    rep(i,0,m) {
        int a = li[i], b = li[i+1];
        li.push_back(lca.query(a, b));
    }
    sort(all(li), cmp);
    li.erase(unique(all(li)), li.end());
    rep(i,0,sz(li)) rev[li[i]] = i;
    vpi ret = {pii(0, li[0])};
    rep(i,0,sz(li)-1) {
        int a = li[i], b = li[i+1];
        ret.emplace_back(rev[lca.query(a, b)], b);
    }
    return ret;
}
```

HLD.h

Description: Decomposes a tree into vertex disjoint heavy paths and light edges such that the path from any leaf to the root contains at most $\log(n)$ light edges. The function of the HLD can be changed by modifying T, LOW and f. f is assumed to be associative and commutative.

Usage: HLD hld(G);
hld.update(index, value);
tie(value, lca) = hld.query(n1, n2);

d952a9, 93 lines

```
typedef vector<pii> vpi;

struct Node {
    int d, par, val, chain = -1, pos = -1;
};

struct Chain {
    int par, val;
    vector<int> nodes;
    Tree tree;
};

struct HLD {
    typedef int T;
    const T LOW = -(1<<29);
    void f(T& a, T b) { a = max(a, b); }

    vector<Node> V;
    vector<Chain> C;

    HLD(vector<vpi>& g) : V(sz(g)) {
        dfs(0, -1, g, 0);
        trav(c, C) {
            c.tree = {sz(c.nodes), 0};
            for (int ni : c.nodes)
                c.tree.update(V[ni].pos, V[ni].val);
        }
    }

    void update(int node, T val) {
        Node& n = V[node]; n.val = val;
        if (n.chain != -1) C[n.chain].tree.update(n.pos, val);
    }
};
```

```

int pard(Node& nod) {
    if (nod.par == -1) return -1;
    return V[nod.chain == -1 ? nod.par : C[nod.chain].par].
        d;
}

// query all *edges* between n1, n2
pair<T, int> query(int i1, int i2) {
    T ans = LOW;
    while(i1 != i2) {
        Node n1 = V[i1], n2 = V[i2];
        if (n1.chain != -1 && n1.chain == n2.chain) {
            int lo = n1.pos, hi = n2.pos;
            if (lo > hi) swap(lo, hi);
            f(ans, C[n1.chain].tree.query(lo, hi));
            i1 = i2 = C[n1.chain].nodes[hi];
        } else {
            if (pard(n1) < pard(n2))
                n1 = n2, swap(i1, i2);
            if (n1.chain == -1)
                f(ans, n1.val), i1 = n1.par;
            else {
                Chain& c = C[n1.chain];
                f(ans, n1.pos ? c.tree.query(n1.pos, sz(c.nodes))
                    : c.tree.s[1]);
                i1 = c.par;
            }
        }
    }
    return make_pair(ans, i1);
}

// query all *nodes* between n1, n2
pair<T, int> query2(int i1, int i2) {
    pair<T, int> ans = query(i1, i2);
    f(ans.first, V[ans.second].val);
    return ans;
}

pii dfs(int at, int par, vector<vpi>& g, int d) {
    V[at].d = d; V[at].par = par;
    int sum = 1, ch, nod, sz;
    tuple<int,int,int> mx(-1,-1,-1);
    trav(e, g[at]){
        if (e.first == par) continue;
        tie(sz, ch) = dfs(e.first, at, g, d+1);
        V[e.first].val = e.second;
        sum += sz;
        mx = max(mx, make_tuple(sz, e.first, ch));
    }
    tie(sz, nod, ch) = mx;
    if (2*sz < sum) return pii(sum, -1);
    if (ch == -1) { ch = sz(C); C.emplace_back(); }
    V[nod].pos = sz(C[ch].nodes);
    V[nod].chain = ch;
    C[ch].par = at;
    C[ch].nodes.push_back(nod);
    return pii(sum, ch);
}
};

```

LinkCutTree.h

Description: Represents a forest of unrooted trees. You can add and remove edges (as long as the result is still a forest), and check whether two nodes are in the same tree.

Time: All operations take amortized $\mathcal{O}(\log N)$.

693483, 90 lines

```

struct Node { // Splay tree. Root's pp contains tree's
    parent.
    Node *p = 0, *pp = 0, *c[2];

```

```

    bool flip = 0;
    Node() { c[0] = c[1] = 0; fix(); }
    void fix() {
        if (c[0]) c[0]->p = this;
        if (c[1]) c[1]->p = this;
        // (+ update sum of subtree elements etc. if wanted)
    }
    void push_flip() {
        if (!flip) return;
        flip = 0; swap(c[0], c[1]);
        if (c[0]) c[0]->flip ^= 1;
        if (c[1]) c[1]->flip ^= 1;
    }
    int up() { return p ? p->c[1] == this : -1; }
    void rot(int l, int b) {
        int h = l ^ b;
        Node *x = c[l], *y = b == 2 ? x : x->c[h], *z = b ? y :
            x;
        if ((y->p = p)) p->c[up()] = y;
        c[l] = z->c[l ^ 1];
        if (b < 2) {
            x->c[h] = y->c[h ^ 1];
            z->c[h ^ 1] = b ? x : this;
        }
        y->c[l ^ 1] = b ? this : x;
        fix(); x->fix(); y->fix();
        if (p) p->fix();
        swap(pp, y->pp);
    }
    void splay() {
        for (push_flip(); p; ) {
            if (p->p) p->p->push_flip();
            p->push_flip(); push_flip();
            int c1 = up(), c2 = p->up();
            if (c2 == -1) p->rot(c1, 2);
            else p->p->rot(c2, c1 != c2);
        }
    }
    Node* first() {
        push_flip();
        return c[0] ? c[0]->first() : (splay(), this);
    }
};

struct LinkCut {
    vector<Node> node;
    LinkCut(int N) : node(N) {}

    void link(int u, int v) { // add an edge (u, v)
        assert(!connected(u, v));
        make_root(&node[u]);
        node[u].pp = &node[v];
    }
    void cut(int u, int v) { // remove an edge (u, v)
        Node *x = &node[u], *top = &node[v];
        make_root(top); x->splay();
        assert(top == (x->pp ? x->c[0]));
        if (x->pp) x->pp = 0;
        else {
            x->c[0] = top->p = 0;
            x->fix();
        }
    }
    bool connected(int u, int v) { // are u, v in the same
        tree?
        Node* nu = access(&node[u])->first();
        return nu == access(&node[v])->first();
    }
    void make_root(Node* u) {
        access(u);
        u->splay();

```

```

        if(u->c[0]) {
            u->c[0]->p = 0;
            u->c[0]->flip ^= 1;
            u->c[0]->pp = u;
            u->c[0] = 0;
            u->fix();
        }
    }
    Node* access(Node* u) {
        u->splay();
        while (Node* pp = u->pp) {
            pp->splay(); u->pp = 0;
            if (pp->c[1]) {
                pp->c[1]->p = 0; pp->c[1]->pp = pp; }
            pp->c[1] = u; pp->fix(); u = pp;
        }
        return u;
    }
};

```

DirectedMST.h

Description: Edmonds' algorithm for finding the weight of the minimum spanning tree/arborescence of a directed graph, given a root node. If no MST exists, returns -1.

Time: $\mathcal{O}(E \log V)$

../data-structures/UnionFind.h"

a69883, 48 lines

```

struct Edge { int a, b; ll w; };
struct Node {
    Edge key;
    Node *l, *r;
    ll delta;
    void prop() {
        key.w += delta;
        if (l) l->delta += delta;
        if (r) r->delta += delta;
        delta = 0;
    }
    Edge top() { prop(); return key; }
};
Node *merge(Node *a, Node *b) {
    if (!a || !b) return a ? b;
    a->prop(), b->prop();
    if (a->key.w > b->key.w) swap(a, b);
    swap(a->l, (a->r = merge(b, a->r)));
    return a;
}
void pop(Node*& a) { a->prop(); a = merge(a->l, a->r); }

ll dmst(int n, int r, vector<Edge>& g) {
    UF uf(n);
    vector<Node*> heap(n);
    trav(e, g) heap[e.b] = merge(heap[e.b], new Node{e});
    ll res = 0;
    vi seen(n, -1), path(n);
    seen[r] = r;
    rep(s, 0, n) {
        int u = s, qi = 0, w;
        while (seen[u] < 0) {
            path[qi++] = u, seen[u] = s;
            if (!heap[u]) return -1;
            Edge e = heap[u]->top();
            heap[u]->delta -= e.w, pop(heap[u]);
            res += e.w, u = uf.find(e.a);
            if (seen[u] == s) {
                Node* cyc = 0;
                do cyc = merge(cyc, heap[w = path[--qi]]);
                while (uf.join(u, w));
                u = uf.find(u);
                heap[u] = cyc, seen[u] = -1;
            }
        }
    }
}

```

```

    }
}
return res;
}

```

7.8 Math

7.8.1 Number of Spanning Trees

Create an $N \times N$ matrix `mat`, and for each edge $a \rightarrow b \in G$, do `mat[a][b]--`, `mat[b][b]++` (and `mat[b][a]--`, `mat[a][a]++` if G is undirected). Remove the i th row and column and take the determinant; this yields the number of directed spanning trees rooted at i (if G is undirected, remove any row/column).

7.8.2 Erdős–Gallai theorem

A simple graph with node degrees $d_1 \geq \dots \geq d_n$ exists iff $d_1 + \dots + d_n$ is even and for every $k = 1 \dots n$,

$$\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k).$$

Geometry (8)

8.1 Geometric primitives

Point.h

Description: Class to handle points in the plane. T can be e.g. double or long long. (Avoid int.)

47ec0a, 28 lines

```

template <class T> int sgn(T x) { return (x > 0) - (x < 0); }

template<class T>
struct Point {
    typedef Point P;
    T x, y;
    explicit Point(T x=0, T y=0) : x(x), y(y) {}
    bool operator<(P p) const { return tie(x,y) < tie(p.x,p.y); }
    bool operator==(P p) const { return tie(x,y)==tie(p.x,p.y); }

    P operator+(P p) const { return P(x+p.x, y+p.y); }
    P operator-(P p) const { return P(x-p.x, y-p.y); }
    P operator*(T d) const { return P(x*d, y*d); }
    P operator/(T d) const { return P(x/d, y/d); }
    T dot(P p) const { return x*p.x + y*p.y; }
    T cross(P p) const { return x*p.y - y*p.x; }
    T cross(P a, P b) const { return (a-*this).cross(b-*this); }

    T dist2() const { return x*x + y*y; }
    double dist() const { return sqrt((double)dist2()); }
    // angle to x-axis in interval [-pi, pi]
    double angle() const { return atan2(y, x); }
    P unit() const { return *this/dist(); } // makes dist()==1
    P perp() const { return P(-y, x); } // rotates +90 degrees
    P normal() const { return perp().unit(); }
    // returns point rotated 'a' radians ccw around the origin
    P rotate(double a) const {
        return P(x*cos(a)-y*sin(a), x*sin(a)+y*cos(a)); }
}

```

```

friend ostream& operator<<(ostream& os, P p) {
    return os << "(" << p.x << ", " << p.y << ")"; }
};

```

lineDistance.h

Description:

Returns the signed distance between point p and the line containing points a and b . Positive value on left side and negative on right as seen from a towards b . $a==b$ gives nan. P is supposed to be `Point<T>` or `Point3D<T>` where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long. Using `Point3D` will always give a non-negative distance. For `Point3D`, call `.dist` on the result of the cross product.

"Point.h"

f6bf6b, 4 lines

```

template<class P>
double lineDist(const P& a, const P& b, const P& p) {
    return (double) (b-a).cross(p-a) / (b-a).dist(); }
}

```

SegmentDistance.h

Description:

Returns the shortest distance between point p and the line segment from point s to e .

Usage: `Point<double> a, b(2,2), p(1,1);`
`bool onSegment = segDist(a,b,p) < 1e-10;`

"Point.h"

5c88f4, 6 lines

```

typedef Point<double> P;
double segDist(P& s, P& e, P& p) {
    if (s==e) return (p-s).dist();
    auto d = (e-s).dist2(), t = min(d,max(.0, (p-s).dot(e-s)));
    ;
    return ((p-s)*d-(e-s)*t).dist()/d; }
}

```

SegmentIntersection.h

Description:

If a unique intersection point between the line segments going from $s1$ to $e1$ and from $s2$ to $e2$ exists then it is returned. If no intersection point exists an empty vector is returned. If infinitely many exist a vector with 2 elements is returned, containing the endpoints of the common line segment. The wrong position will be returned if P is `Point<ll>` and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or long long.

Usage: `vector<P> inter = segInter(s1,e1,s2,e2);`
if `(sz(inter)==1)`

`cout << "segments intersect at " << inter[0] << endl;`

"Point.h", "OnSegment.h"

9d57f2, 13 lines

```

template<class P> vector<P> segInter(P a, P b, P c, P d) {
    auto oa = c.cross(d, a), ob = c.cross(d, b),
        oc = a.cross(b, c), od = a.cross(b, d);
    // Checks if intersection is single non-endpoint point.
    if (sgn(oa) * sgn(ob) < 0 && sgn(oc) * sgn(od) < 0)
        return {(a * ob - b * oa) / (ob - oa)};
    set<P> s;
    if (onSegment(c, d, a)) s.insert(a);
    if (onSegment(c, d, b)) s.insert(b);
    if (onSegment(a, b, c)) s.insert(c);
    if (onSegment(a, b, d)) s.insert(d);
    return {all(s)}; }
}

```

lineIntersection.h

Description:

If a unique intersection point of the lines going through $s1,e1$ and $s2,e2$ exists `{1, point}` is returned. If no intersection point exists `{0, (0,0)}` is returned and if infinitely many exists `{-1, (0,0)}` is returned. The wrong position will be returned if P is `Point<ll>` and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or ll.

Usage: `auto res = lineInter(s1,e1,s2,e2);`

if `(res.first == 1)`

`cout << "intersection point at " << res.second << endl;`

"Point.h"

a01f81, 8 lines

```

template<class P>
pair<int, P> lineInter(P s1, P e1, P s2, P e2) {
    auto d = (e1 - s1).cross(e2 - s2);
    if (d == 0) // if parallel
        return {-(s1.cross(e1, s2) == 0), P(0, 0)};
    auto p = s2.cross(e1, e2), q = s2.cross(e2, s1);
    return {1, (s1 * p + e1 * q) / d}; }
}

```

sideOf.h

Description: Returns where p is as seen from s towards e . $1/0/-1 \Leftrightarrow$ left/on line/right. If the optional argument `eps` is given 0 is returned if p is within distance `eps` from the line. P is supposed to be `Point<T>` where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long.

Usage: `bool left = sideOf(p1,p2,q)==1;`

"Point.h"

3af81c, 9 lines

```

template<class P>
int sideOf(P s, P e, P p) { return sgn(s.cross(e, p)); }
}

```

template<class P>

```

int sideOf(const P& s, const P& e, const P& p, double eps)
{
    auto a = (e-s).cross(p-s);
    double l = (e-s).dist()*eps;
    return (a > l) - (a < -l); }
}

```

OnSegment.h

Description: Returns true iff p lies on the line segment from s to e . Use `(segDist(s,e,p)<=epsilon)` instead when using `Point<double>`.

"Point.h"

c597e8, 3 lines

```

template<class P> bool onSegment(P s, P e, P p) {
    return p.cross(s, e) == 0 && (s - p).dot(e - p) <= 0; }
}

```

linearTransformation.h

Description:

Apply the linear transformation (translation, rotation and scaling) which takes line $p0-p1$ to line $q0-q1$ to point r .

"Point.h"

03a306, 6 lines

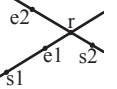
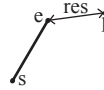
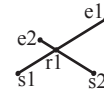
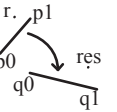
```

typedef Point<double> P;
P linearTransformation(const P& p0, const P& p1,
    const P& q0, const P& q1, const P& r) {
    P dp = p1-p0, dq = q1-q0, num(dp.cross(dq), dp.dot(dq));
    return q0 + P((r-p0).cross(num), (r-p0).dot(num))/dp.
        dist2(); }
}

```

Angle.h

Description: A class for ordering angles (as represented by int points and a number of rotations around the origin). Useful for rotational sweeping. Sometimes also represents points or vectors.



Usage:vector<Angle> v = {w[0], w[0].t360() ...}; // sorted

int j = 0; rep(i,0,n) { while (v[j] < v[i].t180()) ++j; }

// sweeps j such that (j-i) represents the number of positively oriented triangles with vertices at 0 and i

0f602, 35 lines

struct Angle {

int x, y;

int t;

Angle(int x, int y, int t=0) : x(x), y(y), t(t) {}

Angle operator-(Angle b) const { return {x-b.x, y-b.y, t}; }

};

int half() const {

assert(x || y);

return y < 0 || (y == 0 && x < 0);

}

Angle t90() const { return {-y, x, t + (half() && x >= 0)}; }

Angle t180() const { return {-x, -y, t + half()}; }

Angle t360() const { return {x, y, t + 1}; }

};

bool operator<(Angle a, Angle b) {

// add a.dist2() and b.dist2() to also compare distances

return make_tuple(a.t, a.half(), a.y * (1l)b.x) <

make_tuple(b.t, b.half(), a.x * (1l)b.y);

}

// Given two points, this calculates the smallest angle between

// them, i.e., the angle that covers the defined line segment.

pair<Angle, Angle> segmentAngles(Angle a, Angle b) {

if (b < a) swap(a, b);

return (b < a.t180() ?

make_pair(a, b) : make_pair(b, a.t360()));

}

Angle operator+(Angle a, Angle b) { // point a + vector b

Angle r(a.x + b.x, a.y + b.y, a.t);

if (a.t180() < r) r.t--;

return r.t180() < a ? r.t360() : r;

}

Angle angleDiff(Angle a, Angle b) { // angle b - angle a

int tu = b.t - a.t; a.t = b.t;

return {a.x*b.x + a.y*b.y, a.x*b.y - a.y*b.x, tu - (b < a)}

};

}

8.2 Circles

CircleIntersection.h

Description: Computes the pair of points at which two circles intersect. Returns false in case of no intersection.

"Point.h"

84d6d3, 11 lines

typedef Point<double> P;

bool circleInter(P a,P b,double r1,double r2,pair<P, P>* out) {

if (a == b) { assert(r1 != r2); return false; }

P vec = b - a;

double d2 = vec.dist2(), sum = r1+r2, dif = r1-r2,

p = (d2 + r1*r1 - r2*r2)/(d2*2), h2 = r1*r1 - p*p*

d2;

if (sum*sum < d2 || dif*dif > d2) return false;

P mid = a + vec*p, per = vec.perp() * sqrt(fmax(0, h2) /

d2);

*out = {mid + per, mid - per};

return true;

}

CircleTangents.h

Description: Finds the external tangents of two circles, or internal if r2 is negated. Can return 0, 1, or 2 tangents - 0 if one circle contains the other (or overlaps it, in the internal case, or if the circles are the same); 1 if the circles are tangent to each other (in which case .first = .second and the tangent line is perpendicular to the line between the centers). .first and .second give the tangency points at circle 1 and 2 respectively. To find the tangents of a circle with a point set r2 to 0.

"Point.h"

b0153d, 13 lines

template<class P>

vector<pair<P, P>> tangents(P c1, double r1, P c2, double r2) {

P d = c2 - c1;

double dr = r1 - r2, d2 = d.dist2(), h2 = d2 - dr * dr;

if (d2 == 0 || h2 < 0) return {};

vector<pair<P, P>> out;

for (double sign : {-1, 1}) {

P v = (d * dr + d.perp() * sqrt(h2) * sign) / d2;

out.push_back({c1 + v * r1, c2 + v * r2});

}

if (h2 == 0) out.pop_back();

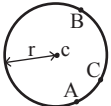
return out;

}

circumcircle.h

Description:

The circumcirle of a triangle is the circle intersecting all three vertices. ccRadius returns the radius of the circle going through points A, B and C and ccCenter returns the center of the same circle.



"Point.h"

1caa3a, 9 lines

typedef Point<double> P;

double ccRadius(const P& A, const P& B, const P& C) {

return (B-A).dist()*(C-B).dist()*(A-C).dist()/

abs((B-A).cross(C-A))/2;

}

P ccCenter(const P& A, const P& B, const P& C) {

P b = C-A, c = B-A;

return A + (b*c.dist2()-c*b.dist2()).perp()/b.cross(c)/2;

}

MinimumEnclosingCircle.h

Description: Computes the minimum circle that encloses a set of points.

Time: expected O(n)

"circumcircle.h"

09dd0a, 17 lines

pair<P, double> mec(vector<P> ps) {

shuffle(all(ps), mt19937(time(0)));

P o = ps[0];

double r = 0, EPS = 1 + 1e-8;

rep(i,0,sz(ps)) if ((o - ps[i]).dist() > r * EPS) {

o = ps[i], r = 0;

rep(j,0,i) if ((o - ps[j]).dist() > r * EPS) {

o = (ps[i] + ps[j]) / 2;

r = (o - ps[i]).dist();

rep(k,0,j) if ((o - ps[k]).dist() > r * EPS) {

o = ccCenter(ps[i], ps[j], ps[k]);

r = (o - ps[i]).dist();

}

}

}

return {o, r};

}

8.3 Polygons

InsidePolygon.h

Description: Returns true if p lies within the polygon. If strict is true, it returns false for points on the boundary. The algorithm uses products in intermediate steps so watch out for overflow.

Usage: vector<P> v = {P{4,4}, P{1,2}, P{2,1}};

bool in = inPolygon(v, P{3, 3}, false);

Time: O(n)

"Point.h", "OnSegment.h", "SegmentDistance.h"

2bf504, 11 lines

template<class P>

bool inPolygon(vector<P> &p, P a, bool strict = true) {

int cnt = 0, n = sz(p);

rep(i,0,n) {

P q = p[(i + 1) % n];

if (onSegment(p[i], q, a)) return !strict;

//or: if (segDist(p[i], q, a) <= eps) return !strict;

cnt ^= ((a.y<p[i].y) - (a.y<q.y)) * a.cross(p[i], q) >

0;

}

return cnt;

}

PolygonArea.h

Description: Returns twice the signed area of a polygon. Clockwise enumeration gives negative area. Watch out for overflow if using int as T!

"Point.h"

f12300, 6 lines

template<class T>

T polygonArea2(vector<Point<T>>& v) {

T a = v.back().cross(v[0]);

rep(i,0,sz(v)-1) a += v[i].cross(v[i+1]);

return a;

}

PolygonCenter.h

Description: Returns the center of mass for a polygon.

Time: O(n)

"Point.h"

9706dc, 9 lines

typedef Point<double> P;

P polygonCenter(const vector<P>& v) {

P res(0, 0); double A = 0;

for (int i = 0, j = sz(v) - 1; i < sz(v); j = i++) {

res = res + (v[i] + v[j]) * v[j].cross(v[i]);

A += v[j].cross(v[i]);

}

return res / A / 3;

}

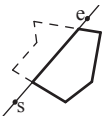
PolygonCut.h

Description:

Returns a vector with the vertices of a polygon with everything to the left of the line going from s to e cut away.

Usage: vector<P> p = ...;

p = polygonCut(p, P(0,0), P(1,0));



"Point.h", "lineIntersection.h"

f2b7d4, 13 lines

typedef Point<double> P;

vector<P> polygonCut(const vector<P>& poly, P s, P e) {

vector<P> res;

rep(i,0,sz(poly)) {

P cur = poly[i], prev = i ? poly[i-1] : poly.back();

bool side = s.cross(e, cur) < 0;

if (side != (s.cross(e, prev) < 0))

res.push_back(lineInter(s, e, cur, prev).second);

if (side)

res.push_back(cur);

}

return res;

}

ConvexHull.h

Description:

Returns a vector of the points of the convex hull in counter-clockwise order. Points on the edge of the hull between two other points are not considered part of the hull.

Time: $\mathcal{O}(n \log n)$

```
"Point.h" 26a0a9, 13 lines

typedef Point<ll> P;
vector<P> convexHull(vector<P> pts) {
    if (sz(pts) <= 1) return pts;
    sort(all(pts));
    vector<P> h(sz(pts)+1);
    int s = 0, t = 0;
    for (int it = 2; it--; s = --t, reverse(all(pts)))
        trav(p, pts) {
            while (t >= s + 2 && h[t-2].cross(h[t-1], p) <= 0) t--;
            h[t++] = p;
        }
    return {h.begin(), h.begin() + t - (t == 2 && h[0] == h[1])};
}
```

HullDiameter.h

Description: Returns the two points with max distance on a convex hull (ccw, no duplicate/colinear points).

```
c571b8, 12 lines

typedef Point<ll> P;
array<P, 2> hullDiameter(vector<P> S) {
    int n = sz(S), j = n < 2 ? 0 : 1;
    pair<ll, array<P, 2>> res({0, {S[0], S[0]}});
    rep(i, 0, j)
        for (; j = (j + 1) % n) {
            res = max(res, {{S[i] - S[j]}.dist2(), {S[i], S[j]}});
            if ((S[(j + 1) % n] - S[j]).cross(S[i + 1] - S[i]) >= 0)
                break;
        }
    return res.second;
}
```

PointInsideHull.h

Description: Determine whether a point t lies inside a convex hull (CCW order, with no colinear points). Returns true if point lies within the hull. If strict is true, points on the boundary aren't included.

Time: $\mathcal{O}(\log N)$

```
"Point.h", "sideOf.h", "OnSegment.h" 71446b, 14 lines

typedef Point<ll> P;

bool inHull(const vector<P>& l, P p, bool strict = true) {
    int a = 1, b = sz(l) - 1, r = !strict;
    if (sz(l) < 3) return r && onSegment(l[0], l.back(), p);
    if (sideOf(l[0], l[a], l[b]) > 0) swap(a, b);
    if (sideOf(l[0], l[a], p) >= r || sideOf(l[0], l[b], p) <= -r)
        return false;
    while (abs(a - b) > 1) {
        int c = (a + b) / 2;
        if (sideOf(l[0], l[c], p) > 0 ? b : a) = c;
    }
    return sgn(l[a].cross(l[b], p)) < r;
}
```



LineHullIntersection.h

Description: Line-convex polygon intersection. The polygon must be ccw and have no colinear points. lineHull(line, poly) returns a pair describing the intersection of a line with the polygon: $\bullet(-1, -1)$ if no collision, $\bullet(i, -1)$ if touching the corner i , $\bullet(i, i)$ if along side $(i, i + 1)$, $\bullet(i, j)$ if crossing sides $(i, i + 1)$ and $(j, j + 1)$. In the last case, if a corner i is crossed, this is treated as happening on side $(i, i + 1)$. The points are returned in the same order as the line hits the polygon. extrVertex returns the point of a hull with the max projection onto a line.

Time: $\mathcal{O}(N + Q \log n)$

```
"Point.h" 758f22, 39 lines

typedef array<P, 2> Line;
#define cmp(i, j) sgn(dir.perp().cross(poly[(i)%n]-poly[(j)%n]))
#define extr(i) cmp(i + 1, i) >= 0 && cmp(i, i - 1 + n) < 0
int extrVertex(vector<P>& poly, P dir) {
    int n = sz(poly), lo = 0, hi = n;
    if (extr(0)) return 0;
    while (lo + 1 < hi) {
        int m = (lo + hi) / 2;
        if (extr(m)) return m;
        int ls = cmp(lo + 1, lo), ms = cmp(m + 1, m);
        (ls < ms || (ls == ms && ls == cmp(lo, m)) ? hi : lo) = m;
    }
    return lo;
}

#define cmpL(i) sgn(line[0].cross(poly[i], line[1]))
array<int, 2> lineHull(Line line, vector<P> poly) {
    int endA = extrVertex(poly, (line[0] - line[1]).perp());
    int endB = extrVertex(poly, (line[1] - line[0]).perp());
    if (cmpL(endA) < 0 || cmpL(endB) > 0)
        return {-1, -1};
    array<int, 2> res;
    rep(i, 0, 2) {
        int lo = endB, hi = endA, n = sz(poly);
        while ((lo + 1) % n != hi) {
            int m = ((lo + hi + (lo < hi ? 0 : n)) / 2) % n;
            (cmpL(m) == cmpL(endB) ? lo : hi) = m;
        }
        res[i] = (lo + !cmpL(hi)) % n;
        swap(endA, endB);
    }
    if (res[0] == res[1]) return {res[0], -1};
    if (!cmpL(res[0]) && !cmpL(res[1]))
        switch ((res[0] - res[1] + sz(poly) + 1) % sz(poly)) {
            case 0: return {res[0], res[0]};
            case 2: return {res[1], res[1]};
        }
    return res;
}
```

8.4 Misc. Point Set Problems

ClosestPair.h

Description: Finds the closest pair of points.

Time: $\mathcal{O}(n \log n)$

```
"Point.h" d31bbf, 17 lines

typedef Point<ll> P;
pair<P, P> closest(vector<P> v) {
    assert(sz(v) > 1);
    set<P> S;
    sort(all(v), [](P a, P b) { return a.y < b.y; });
    pair<ll, pair<P, P>> ret{LLONG_MAX, {P(), P()}};
    int j = 0;
    trav(p, v) {
        P d{1 + (ll)sqrt(ret.first), 0};
        while (v[j].y <= p.y - d.x) S.erase(v[j++]);
        auto lo = S.lower_bound(p - d), hi = S.upper_bound(p + d);
    }
```

```
    for (; lo != hi; ++lo)
        ret = min(ret, {(lo - p).dist2(), {lo, p}});
    S.insert(p);
}
return ret.second;
}
```

kdTree.h

Description: KD-tree (2d, can be extended to 3d)

```
"Point.h" bac5b0, 63 lines

typedef long long T;
typedef Point<T> P;
const T INF = numeric_limits<T>::max();

bool on_x(const P& a, const P& b) { return a.x < b.x; }
bool on_y(const P& a, const P& b) { return a.y < b.y; }

struct Node {
    P pt; // if this is a leaf, the single point in it
    T x0 = INF, x1 = -INF, y0 = INF, y1 = -INF; // bounds
    Node *first = 0, *second = 0;

    T distance(const P& p) { // min squared distance to a point
        T x = (p.x < x0 ? x0 : p.x > x1 ? x1 : p.x);
        T y = (p.y < y0 ? y0 : p.y > y1 ? y1 : p.y);
        return (P(x, y) - p).dist2();
    }

    Node(vector<P>&& vp) : pt(vp[0]) {
        for (P p : vp) {
            x0 = min(x0, p.x); x1 = max(x1, p.x);
            y0 = min(y0, p.y); y1 = max(y1, p.y);
        }
        if (vp.size() > 1) {
            // split on x if width >= height (not ideal...)
            sort(all(vp), x1 - x0 >= y1 - y0 ? on_x : on_y);
            // divide by taking half the array for each child (not
            // best performance with many duplicates in the middle)
            int half = sz(vp)/2;
            first = new Node({vp.begin(), vp.begin() + half});
            second = new Node({vp.begin() + half, vp.end()});
        }
    };

    struct KDTree {
        Node* root;
        KDTree(const vector<P>& vp) : root(new Node({all(vp)})) {}

        pair<T, P> search(Node *node, const P& p) {
            if (!node->first) {
                // uncomment if we should not find the point itself:
                // if (p == node->pt) return {INF, P()};
                return make_pair((p - node->pt).dist2(), node->pt);
            }

            Node *f = node->first, *s = node->second;
            T bfirst = f->distance(p), bsec = s->distance(p);
            if (bfirst > bsec) swap(bsec, bfirst), swap(f, s);

            // search closest side first, other side if needed
            auto best = search(f, p);
            if (bsec < best.first)
                best = min(best, search(s, p));
            return best;
        }
    };
}
```

```
// find nearest point to a point, and its squared
distance
// (requires an arbitrary operator< for Point)
pair<T, P> nearest(const P& p) {
    return search(root, p);
}
};
```

FastDelaunay.h

Description: Fast Delaunay triangulation. Each circumcircle contains none of the input points. There must be no duplicate points. If all points are on a line, no triangles will be returned. Should work for doubles as well, though there may be precision issues in 'circ'. Returns triangles in order {t[0][0], t[0][1], t[0][2], t[1][0], ... }, all counter-clockwise. **Time:** $O(n \log n)$

"Point.h"	bfs7ec, 88 lines
-----------	------------------

```
typedef Point<ll> P;
typedef struct Quad* Q;
typedef __int128_t ll1; // (can be ll if coords are < 2e4)
P arb(LLONG_MAX,LLONG_MAX); // not equal to any other point
```

```
struct Quad {
    bool mark; Q o, rot; P p;
    P F() { return r()->p; }
    Q r() { return rot->rot; }
    Q prev() { return rot->o->rot; }
    Q next() { return r()->prev(); }
};
```

```
bool circ(P p, P a, P b, P c) { // is p in the circumcircle
    ?
    ll1 p2 = p.dist2(), A = a.dist2()-p2,
        B = b.dist2()-p2, C = c.dist2()-p2;
    return p.cross(a,b)*C + p.cross(b,c)*A + p.cross(c,a)*B >
        0;
}
```

```
Q makeEdge(P orig, P dest) {
    Q q[] = {new Quad{0,0,0,orig}, new Quad{0,0,0,arb},
            new Quad{0,0,0,dest}, new Quad{0,0,0,arb}};
    rep(i,0,4)
        q[i]->o = q[-i & 3], q[i]->rot = q[(i+1) & 3];
    return *q;
}
```

```
void splice(Q a, Q b) {
    swap(a->o->rot->o, b->o->rot->o); swap(a->o, b->o);
}
```

```
Q connect(Q a, Q b) {
    Q q = makeEdge(a->F(), b->p);
    splice(q, a->next());
    splice(q->r(), b);
    return q;
}
```

```
pair<Q,Q> rec(const vector<P>& s) {
    if (sz(s) <= 3) {
        Q a = makeEdge(s[0], s[1]), b = makeEdge(s[1], s.back())
            );
        if (sz(s) == 2) return { a, a->r() };
        splice(a->r(), b);
        auto side = s[0].cross(s[1], s[2]);
        Q c = side ? connect(b, a) : 0;
        return {side < 0 ? c->r() : a, side < 0 ? c : b->r() };
    }
}
```

```
#define H(e) e->F(), e->p
#define valid(e) (e->F().cross(H(base)) > 0)
    Q A, B, ra, rb;
    int half = sz(s) / 2;
    tie(ra, A) = rec({all(s) - half});
```

```
tie(B, rb) = rec({sz(s) - half + all(s)});
while ((B->p.cross(H(A)) < 0 && (A = A->next())) ||
    (A->p.cross(H(B)) > 0 && (B = B->r()->o));)
Q base = connect(B->r(), A);
if (A->p == ra->p) ra = base->r();
if (B->p == rb->p) rb = base;
```

```
#define DEL(e, init, dir) Q e = init->dir; if (valid(e)) \
    while (circ(e->dir->F(), H(base), e->F())) { \
        Q t = e->dir; \
        splice(e, e->prev()); \
        splice(e->r(), e->r()->prev()); \
        e = t; \
    }
for (;;) {
    DEL(LC, base->r(), o); DEL(RC, base, prev());
    if (!valid(LC) && !valid(RC)) break;
    if (!valid(LC) || (valid(RC) && circ(H(RC), H(LC))))
        base = connect(RC, base->r());
    else
        base = connect(base->r(), LC->r());
}
return { ra, rb };
}
```

```
vector<P> triangulate(vector<P> pts) {
    sort(all(pts)); assert(unique(all(pts)) == pts.end());
    if (sz(pts) < 2) return {};
    Q e = rec(pts).first;
    vector<Q> q = {e};
    int qi = 0;
    while (e->o->F().cross(e->F(), e->p) < 0) e = e->o;
    #define ADD { Q c = e; do { c->mark = 1; pts.push_back(c->p
        ); \
        q.push_back(c->r()); c = c->next(); } while (c != e); }
    ADD; pts.clear();
    while (qi < sz(q)) if (!(e = q[qi++])->mark) ADD;
    return pts;
}
```

8.5 3D

PolyhedronVolume.h

Description: Magic formula for the volume of a polyhedron. Faces should point outwards.

template<class V, class L> double signed_poly_volume(const V& p, const L& trilst) { double v = 0; trav(i, trilst) v += p[i.a].cross(p[i.b]).dot(p[i.c]); return v / 6; }	1ec4d3, 6 lines
--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------	-----------------

Point3D.h

Description: Class to handle points in 3D space. T can be e.g. double or long long.

template<class T> struct Point3D { typedef Point3D P; typedef const P& R; T x, y, z; explicit Point3D(T x=0, T y=0, T z=0) : x(x), y(y), z(z) {} bool operator<(R p) const { return tie(x, y, z) < tie(p.x, p.y, p.z); } bool operator==(R p) const { return tie(x, y, z) == tie(p.x, p.y, p.z); } P operator+(R p) const { return P(x+p.x, y+p.y, z+p.z); } P operator-(R p) const { return P(x-p.x, y-p.y, z-p.z); } P operator*(T d) const { return P(x*d, y*d, z*d); } P operator/(T d) const { return P(x/d, y/d, z/d); } }	8058ae, 32 lines
--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------	------------------

```
T dot(R p) const { return x*p.x + y*p.y + z*p.z; }
P cross(R p) const {
    return P(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x);
}
T dist2() const { return x*x + y*y + z*z; }
double dist() const { return sqrt((double)dist2()); }
//Azimuthal angle (longitude) to x-axis in interval [-pi,
    pi]
double phi() const { return atan2(y, x); }
//Zenith angle (latitude) to the z-axis in interval [0,
    pi]
double theta() const { return atan2(sqrt(x*x+y*y),z); }
P unit() const { return *this/(T)dist(); } //makes dist()
    =1
//returns unit vector normal to *this and p
P normal(P p) const { return cross(p).unit(); }
//returns point rotated 'angle' radians ccw around axis
P rotate(double angle, P axis) const {
    double s = sin(angle), c = cos(angle); P u = axis.unit
        ();
    return u*dot(u)*(1-c) + (*this)*c - cross(u)*s;
}
};
```

3dHull.h

Description: Computes all faces of the 3-dimension hull of a point set. *No four points must be coplanar*, or else random results will be returned. All faces will point outwards.

"Point3D.h"	c172e9, 49 lines
-------------	------------------

```
typedef Point3D<double> P3;
```

```
struct PR {
    void ins(int x) { (a == -1 ? a : b) = x; }
    void rem(int x) { (a == x ? a : b) = -1; }
    int cnt() { return (a != -1) + (b != -1); }
    int a, b;
};
```

```
struct F { P3 q; int a, b, c; };
```

```
vector<F> hull3d(const vector<P3>& A) {
    assert(sz(A) >= 4);
    vector<vector<PR>> E(sz(A), vector<PR>(sz(A), {-1, -1}));
    #define E(x,y) E[f.x][f.y]
    vector<F> FS;
    auto mf = [&](int i, int j, int k, int l) {
        P3 q = {A[j] - A[i]}.cross({A[k] - A[i]});
        if (q.dot(A[l]) > q.dot(A[i]))
            q = q * -1;
        F f{q, i, j, k};
        E(a,b).ins(k); E(a,c).ins(j); E(b,c).ins(i);
        FS.push_back(f);
    };
    rep(i,0,4) rep(j,i+1,4) rep(k,j+1,4)
        mf(i, j, k, 6 - i - j - k);
```

```
rep(i,4,sz(A)) {
    rep(j,0,sz(FS)) {
        F f = FS[j];
        if (f.q.dot(A[i]) > f.q.dot(A[f.a])) {
            E(a,b).rem(f.c);
            E(a,c).rem(f.b);
            E(b,c).rem(f.a);
            swap(FS[j--], FS.back());
            FS.pop_back();
        }
    }
    int nw = sz(FS);
    rep(j,0,nw) {
```

```
F f = FS[j];
#define C(a, b, c) if (E(a,b).cnt() != 2) mf(f.a, f.b, i, f
.c);
C(a, b, c); C(a, c, b); C(b, c, a);
}
}
trav(it, FS) if ((A[it.b] - A[it.a]).cross(
A[it.c] - A[it.a]).dot(it.q) <= 0) swap(it.c, it.b);
return FS;
};
```

sphericalDistance.h

Description: Returns the shortest distance on the sphere with radius radius between the points with azimuthal angles (longitude) f1 (ϕ_1) and f2 (ϕ_2) from x axis and zenith angles (latitude) t1 (θ_1) and t2 (θ_2) from z axis. All angles measured in radians. The algorithm starts by converting the spherical coordinates to cartesian coordinates so if that is what you have you can use only the two last rows. dx*radius is then the difference between the two points in the x direction and d*radius is the total distance between the points.

611f07, 8 lines

```
double sphericalDistance(double f1, double t1,
double f2, double t2, double radius) {
double dx = sin(t2)*cos(f2) - sin(t1)*cos(f1);
double dy = sin(t2)*sin(f2) - sin(t1)*sin(f1);
double dz = cos(t2) - cos(t1);
double d = sqrt(dx*dx + dy*dy + dz*dz);
return radius*2*asin(d/2);
}
```

Strings (9)

KMP.h

Description: pi[x] computes the length of the longest prefix of s that ends at x, other than s[0...x] itself (abacaba -> 0010123). Can be used to find all occurrences of a string.

Time: $\mathcal{O}(n)$

d4375c, 16 lines

```
vi pi(const string& s) {
vi p(sz(s));
rep(i,1,sz(s)) {
int g = p[i-1];
while (g && s[i] != s[g]) g = p[g-1];
p[i] = g + (s[i] == s[g]);
}
return p;
}
```

```
vi match(const string& s, const string& pat) {
vi p = pi(pat + '0' + s), res;
rep(i,sz(p)-sz(s),sz(p))
if (p[i] == sz(pat)) res.push_back(i - 2 * sz(pat));
return res;
}
```

Zfunc.h

Description: z[x] computes the length of the longest common prefix of s[i:] and s, except z[0] = 0. (abacaba -> 0010301)

Time: $\mathcal{O}(n)$

3ae526, 12 lines

```
vi Z(string S) {
vi z(sz(S));
int l = -1, r = -1;
rep(i,1,sz(S)) {
z[i] = i >= r ? 0 : min(r - i, z[i - 1]);
while (i + z[i] < sz(S) && S[i + z[i]] == S[z[i]])
z[i]++;
if (i + z[i] > r)
l = i, r = i + z[i];
}
```

```
return z;
}
```

Manacher.h

Description: For each position in a string, computes p[0][i] = half length of longest even palindrome around pos i, p[1][i] = longest odd (half rounded down).

Time: $\mathcal{O}(N)$

e7ad79, 13 lines

```
array<vi, 2> manacher(const string& s) {
int n = sz(s);
array<vi,2> p = {vi(n+1), vi(n)};
rep(z,0,2) for (int i=0,l=0,r=0; i < n; i++) {
int t = r-i+!z;
if (i<r) p[z][i] = min(t, p[z][l+t]);
int L = i-p[z][i], R = i+p[z][i]-!z;
while (L>=1 && R+1<n && s[L-1] == s[R+1])
p[z][i]++, L--, R++;
if (R>r) l=L, r=R;
}
return p;
}
```

MinRotation.h

Description: Finds the lexicographically smallest rotation of a string.

Usage: rotate(v.begin(), v.begin()+min_rotation(v), v.end());

Time: $\mathcal{O}(N)$

4bd552, 8 lines

```
int min_rotation(string s) {
int a=0, N=sz(s); s += s;
rep(b,0,N) rep(k,0,N) {
if (a+k == b || s[a+k] < s[b+k]) {b += max(0, k-1);
break;}
if (s[a+k] > s[b+k]) { a = b; break; }
}
return a;
}
```

SuffixArray.h

Description: Builds suffix array for a string. sa[i] is the starting index of the suffix which is i'th in the sorted suffix array. The returned vector is of size n + 1, and sa[0] = n. The lcp array contains longest common prefixes for neighbouring strings in the suffix array: lcp[i] = lcp(sa[i], sa[i-1]), lcp[0] = 0. The input string must not contain any zero bytes.

Time: $\mathcal{O}(n \log n)$

70bdd2, 72 lines

```
struct SuffixArray {
vi sa, lcp;
string str;
SuffixArray(string& s, int lim=256) { // or basic_string<
int>
str = s;
int n = sz(s) + 1, k = 0, a, b;
vi x(all(s)+1), y(n), ws(max(n, lim)), rank(n);
sa = lcp = y, iota(all(sa), 0);
for (int j = 0, p = 0; p < n; j = max(1, j * 2), lim =
p) {
p = j, iota(all(y), n - j);
rep(i,0,n) if (sa[i] >= j) y[p++] = sa[i] - j;
fill(all(ws), 0);
rep(i,0,n) ws[x[i]]++;
rep(i,1,lim) ws[i] += ws[i - 1];
for (int i = n; i--;) sa[--ws[x[y[i]]]] = y[i];
swap(x, y), p = 1, x[sa[0]] = 0;
rep(i,1,n) a = sa[i - 1], b = sa[i], x[b] =
(y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1 : p
++;
}
rep(i,1,n) rank[sa[i]] = i;
```

```
for (int i = 0, j; i < n - 1; lcp[rank[i++]] = k)
for (k && k--, j = sa[rank[i] - 1];
s[i + k] == s[j + k]; k++);
}
```

```
ii stringMatching(string &p) { //  $\mathcal{O}(m \log n)$ 
int lo = 0, hi = sz(sa)-1, mid = lo;
while (lo < hi) { // find lower bound
mid = (lo+hi) / 2;
int res = string_view(str.data()+sa[mid]).compare(
string_view(p.data()));
(res >= 0) ? hi = mid : lo = mid+1;
}
//if (strncmp(T4SA[lo], P, m) != 0) return ii(-1, -1)
;
if (string_view(str.data()+sa[lo]) != string_view(p.
data())) return ii(-1, -1);
ii ans; ans.first = lo;
lo = 0; hi = sz(sa)-1; mid = lo;
while (lo < hi) { // find upper bound
mid = (lo+hi) / 2;
//int res = strncmp(T4SA[mid], P, m);
int res = string_view(str.data()+sa[mid]).compare(
string_view(p.data()));
(res > 0) ? hi = mid : lo = mid+1;
}
//if (strncmp(T4SA[hi], P, m) != 0) --hi;
if (string_view(str.data()+sa[hi]) != string_view(p.
data())) --hi;
ans.second = hi;
return ans;
}
```

```
ii LRS() { // longest repeated substring:  $\mathcal{O}(n)$ 
int i, idx = 0, maxLCP = -1;
for (i = 1; i < sz(lcp); ++i)
if (lcp[i] > maxLCP)
maxLCP = lcp[i], idx = i;
return ii(maxLCP, idx);
}
```

```
// owner describes which string the substring belongs to
// add code to ctor for index of special split character
// the check if idx < index
// int owner(int idx) { return (idx < n-m-1) ? 1 : 2; }
```

```
ii LCS() {
// returns longest common substring between two strings
:  $\mathcal{O}(n)$ 
// assumes strings terminated by different special
characters
int i, idx = 0, maxLCP = -1;
for (i = 1; i < sz(lcp); ++i)
if (owner(sa[i]) != owner(sa[i-1]) && lcp[i] > maxLCP
)
maxLCP = lcp[i], idx = i;
return ii(maxLCP, idx);
}
```

SuffixTree.h

Description: Ukkonen's algorithm for online suffix tree construction. Each node contains indices [l, r] into the string, and a list of child nodes. Suffixes are given by traversals of this tree, joining [l, r] substrings. The root is 0 (has l = -1, r = 0), non-existent children are -1. To get a complete tree, append a dummy symbol – otherwise it may contain an incomplete path (still useful for substring matching, though).

Time: $\mathcal{O}(26N)$

aae0b8, 50 lines

```
struct SuffixTree {
enum { N = 200010, ALPHA = 26 }; //  $N \sim 2*maxlen+10$ 
```

```
int toi(char c) { return c - 'a'; }
string a; // v = cur node, q = cur position
int t[N][ALPHA], l[N], r[N], p[N], s[N], v=0, q=0, m=2;

void ukkadd(int i, int c) { suff:
    if (r[v]<=q) {
        if (t[v][c]==-1) { t[v][c]=m; l[m]=i;
            p[m+]=v; v=s[v]; q=r[v]; goto suff; }
        v=t[v][c]; q=l[v];
    }
    if (q== -1 || c==toi(a[q])) q++; else {
        l[m+]=i; p[m+]=m; l[m]=l[v]; r[m]=q;
        p[m]=p[v]; t[m][c]=m+1; t[m][toi(a[q])]=v;
        l[v]=q; p[v]=m; t[p[m]][toi(a[l[m])]]=m;
        v=s[p[m]]; q=l[m];
        while (q<r[m]) { v=t[v][toi(a[q])]; q+=r[v]-l[v]; }
        if (q==r[m]) s[m]=v; else s[m]=m+2;
        q=r[v]-(q-r[m]); m+=2; goto suff;
    }
}

SuffixTree(string a) : a(a) {
    fill(r,r+N,sz(a));
    memset(s, 0, sizeof s);
    memset(t, -1, sizeof t);
    fill(t[1],t[1]+ALPHA,0);
    s[0] = 1; l[0] = l[1] = -1; r[0] = r[1] = p[0] = p[1] = 0;
    rep(i,0,sz(a)) ukkadd(i, toi(a[i]));
}

// example: find longest common substring (uses ALPHA = 28)
pii best;
int lcs(int node, int i1, int i2, int olen) {
    if (l[node] <= i1 && i1 < r[node]) return 1;
    if (l[node] <= i2 && i2 < r[node]) return 2;
    int mask = 0, len = node ? olen + (r[node] - l[node]) : 0;
    rep(c,0,ALPHA) if (t[node][c] != -1)
        mask |= lcs(t[node][c], i1, i2, len);
    if (mask == 3)
        best = max(best, {len, r[node] - len});
    return mask;
}

static pii LCS(string s, string t) {
    SuffixTree st(s + (char)('z' + 1) + t + (char)('z' + 2));
    st.lcs(0, sz(s), sz(s) + 1 + sz(t), 0);
    return st.best;
}
```

Hashing.h

Description: Self-explanatory methods for string hashing. 8cb5db, 44 lines

```
// Arithmetic mod 2^64-1. 2x slower than mod 2^64 and more
// code, but works on evil test data (e.g. Thue-Morse,
// where
// ABBA... and BAAB... of length 2^10 hash the same mod 2^
// 64).
// "typedef ull H;" instead if you think test data is
// random,
// or work mod 10^9+7 if the Birthday paradox is not a
// problem.
struct H {
    typedef uint64_t ull;
    ull x; H(ull x=0) : x(x) {}
#define OP(O,A,B) H operator O(H o) { ull r = x; asm \
    (A "addq %%rdx, %0\n adcq $0,%0" : "+a"(r) : B); return r
    ; }
```

```
OP(+,, "d"(o.x)) OP(*, "mul %l\n", "r"(o.x) : "rdx")
H operator-(H o) { return *this + ~o.x; }
ull get() const { return x + !~x; }
bool operator==(H o) const { return get() == o.get(); }
bool operator<(H o) const { return get() < o.get(); }
};

static const H C = (1ll)1e11+3; // (order ~ 3e9; random also
ok)

struct HashInterval {
    vector<H> ha, pw;
    HashInterval(string& str) : ha(sz(str)+1), pw(ha) {
        pw[0] = 1;
        rep(i,0,sz(str))
            ha[i+1] = ha[i] * C + str[i],
            pw[i+1] = pw[i] * C;
    }
    H hashInterval(int a, int b) { // hash [a, b)
        return ha[b] - ha[a] * pw[b - a];
    }
};

vector<H> getHashes(string& str, int length) {
    if (sz(str) < length) return {};
    H h = 0, pw = 1;
    rep(i,0,length)
        h = h * C + str[i], pw = pw * C;
    vector<H> ret = {h};
    rep(i,length,sz(str)) {
        ret.push_back(h = h * C + str[i] - pw * str[i-length]);
    }
    return ret;
}

H hashString(string& s) { H h{}; trav(c,s) h=h*C+c; return h; }
```

AhoCorasick.h

Description: Aho-Corasick tree is used for multiple pattern matching. Initialize the tree with create(patterns). find(word) returns for each position the index of the longest word that ends there, or -1 if none. findAll(., word) finds all words (up to $N\sqrt{N}$ many if no duplicate patterns) that start at each position (shortest first). Duplicate patterns are allowed; empty patterns are not. To find the longest words that start at each position, reverse all input.

Time: create is $\mathcal{O}(26N)$ where N is the sum of length of patterns. find is $\mathcal{O}(M)$ where M is the length of the word. findAll is $\mathcal{O}(NM)$. 716ac4, 67 lines

```
struct AhoCorasick {
    enum {alpha = 26, first = 'A'};
    struct Node {
        // (nmatches is optional)
        int back, next[alpha], start = -1, end = -1, nmatches = 0;
        Node(int v) { memset(next, v, sizeof(next)); }
    };
    vector<Node> N;
    vector<int> backp;
    void insert(string& s, int j) {
        assert(!s.empty());
        int n = 0;
        trav(c, s) {
            Node& m = N[n].next[c - first];
            if (m == -1) { n = m = sz(N); N.emplace_back(-1); }
            else n = m;
        }
        if (N[n].end == -1) N[n].start = j;
        backp.push_back(N[n].end);
        N[n].end = j;
        N[n].nmatches++;
    }
}
```

```
AhoCorasick(vector<string>& pat) {
    N.emplace_back(-1);
    rep(i,0,sz(pat)) insert(pat[i], i);
    N[0].back = sz(N);
    N.emplace_back(0);

    queue<int> q;
    for (q.push(0); !q.empty(); q.pop()) {
        int n = q.front(), prev = N[n].back;
        rep(i,0,alpha) {
            int &ed = N[n].next[i], y = N[prev].next[i];
            if (ed == -1) ed = y;
            else {
                N[ed].back = y;
                (N[ed].end == -1 ? N[ed].end : backp[N[ed].start
                    ])
                    = N[y].end;
                N[ed].nmatches += N[y].nmatches;
                q.push(ed);
            }
        }
    }
}

vi find(string word) {
    int n = 0;
    vi res; // ll count = 0;
    trav(c, word) {
        n = N[n].next[c - first];
        res.push_back(N[n].end);
        // count += N[n].nmatches;
    }
    return res;
}

vector<vi> findAll(vector<string>& pat, string word) {
    vi r = find(word);
    vector<vi> res(sz(word));
    rep(i,0,sz(word)) {
        int ind = r[i];
        while (ind != -1) {
            res[i - sz(pat[ind]) + 1].push_back(ind);
            ind = backp[ind];
        }
    }
    return res;
}
};
```

AhoCorasickSimple.java 7082e7, 28 lines

```
import java.util.*;
public class AhoCorasickSimple {
    static final int ALPHABET_SIZE = 26;
    String[] prefixes;
    public int[][] buildAutomata(String[] words) {
        Map<String, Integer> prefixMap = new TreeMap<>();
        for (String s : words) {
            for (int i = 0; i <= s.length(); i++) {
                prefixMap.put(s.substring(0, i), 0);
            }
        }
        prefixes = prefixMap.keySet().toArray(new String
            [0]);
        for (int i = 0; i < prefixes.length; i++) {
            prefixMap.put(prefixes[i], i);
        }
        int[][] transitions = new int[prefixes.length][
            ALPHABET_SIZE];
        for (int i = 0; i < prefixes.length; i++) {
            for (int j = 0; j < ALPHABET_SIZE; j++) {
                String s = prefixes[i] + (char) ('a' + j);
                while (!prefixMap.containsKey(s)) {

```

```

        s = s.substring(1);
    }
    transitions[i][j] = prefixMap.get(s);
}
}
return transitions;
}
}

```

SuffixArray2.java

Time: $\mathcal{O}(n * \log^2(n))$

103346, 36 lines

```

import java.util.*;
public class SuffixArray2 {
    public static Integer[] suffixArray(CharSequence s) {
        int n = s.length();
        Integer[] sa = new Integer[n];
        int[] rank = new int[n];
        for (int i = 0; i < n; i++) {
            sa[i] = i;
            rank[i] = s.charAt(i);
        }
        for (int len = 1; len < n; len *= 2) {
            long[] rank2 = new long[n];
            for (int i = 0; i < n; i++)
                rank2[i] = ((long) rank[i] << 32) + (i + len < n ? rank[i + len] + 1 : 0);
            Arrays.sort(sa, (a, b) -> Long.compare(rank2[a], rank2[b]));
            for (int i = 0; i < n; i++)
                rank[sa[i]] = i > 0 && rank2[sa[i - 1]] == rank2[sa[i]] ? rank[sa[i - 1]] : i;
        }
        return sa;
    }
    // random test
    public static void main(String[] args) {
        Random rnd = new Random(1);
        for (int step = 0; step < 100000; step++) {
            int n = rnd.nextInt(100);
            StringBuilder s = new StringBuilder();
            for (int i = 0; i < n; i++)
                s.append((char) ('\'0' + rnd.nextInt(10)));
            Integer[] sa = suffixArray(s);
            for (int i = 0; i + 1 < n; i++)
                if (s.substring(sa[i]).compareTo(s.substring(sa[i + 1])) >= 0)
                    throw new RuntimeException();
        }
        System.out.println("Test passed");
    }
}

```

Various (10)

10.1 Intervals

IntervalContainer.h

Description: Add and remove intervals from a set of disjoint intervals. Will merge the added interval with any overlapping intervals in the set when adding. Intervals are [inclusive, exclusive).

Time: $\mathcal{O}(\log N)$

edce47, 23 lines

```

set<pii>::iterator addInterval(set<pii>& is, int L, int R)
{
    if (L == R) return is.end();
    auto it = is.lower_bound({L, R}), before = it;
    while (it != is.end() && it->first <= R) {
        R = max(R, it->second);
        before = it = is.erase(it);
    }
}

```

```

}
if (it != is.begin() && (--it)->second >= L) {
    L = min(L, it->first);
    R = max(R, it->second);
    is.erase(it);
}
return is.insert(before, {L, R});
}

```

```

void removeInterval(set<pii>& is, int L, int R) {
    if (L == R) return;
    auto it = addInterval(is, L, R);
    auto r2 = it->second;
    if (it->first == L) is.erase(it);
    else (int&)it->second = L;
    if (R != r2) is.emplace(R, r2);
}

```

IntervalCover.h

Description: Compute indices of smallest set of intervals covering another interval. Intervals should be [inclusive, exclusive). To support [inclusive, inclusive], change (A) to add || R.empty(). Returns empty set on failure (or if G is empty).

Time: $\mathcal{O}(N \log N)$

9e9d8d, 19 lines

```

template<class T>
vi cover(pair<T, T> G, vector<pair<T, T>> I) {
    vi S(sz(I)), R;
    iota(all(S), 0);
    sort(all(S), [&](int a, int b) { return I[a] < I[b]; });
    T cur = G.first;
    int at = 0;
    while (cur < G.second) { // (A)
        pair<T, int> mx = make_pair(cur, -1);
        while (at < sz(I) && I[S[at]].first <= cur) {
            mx = max(mx, make_pair(I[S[at]].second, S[at]));
            at++;
        }
        if (mx.second == -1) return {};
        cur = mx.first;
        R.push_back(mx.second);
    }
    return R;
}

```

ConstantIntervals.h

Description: Split a monotone function on [from, to) into a minimal set of half-open intervals on which it has the same value. Runs a callback g for each such interval.

Usage: constantIntervals(0, sz(v), [&](int x){return v[x];}, [&](int lo, int hi, T val){...});

Time: $\mathcal{O}(k \log \frac{n}{k})$

753a4c, 19 lines

```

template<class F, class G, class T>
void rec(int from, int to, F& f, G& g, int& i, T& p, T q) {
    if (p == q) return;
    if (from == to) {
        g(i, to, p);
        i = to; p = q;
    } else {
        int mid = (from + to) >> 1;
        rec(from, mid, f, g, i, p, f(mid));
        rec(mid+1, to, f, g, i, p, q);
    }
}
template<class F, class G>
void constantIntervals(int from, int to, F f, G g) {
    if (to <= from) return;
    int i = from; auto p = f(i), q = f(to-1);
    rec(from, to-1, f, g, i, p, q);
    g(i, to, q);
}

```

```

}

```

10.2 Misc. algorithms

TernarySearch.h

Description: Find the smallest i in $[a, b]$ that maximizes $f(i)$, assuming that $f(a) < \dots < f(i) \geq \dots \geq f(b)$. To reverse which of the sides allows non-strict inequalities, change the $<$ marked with (A) to $<=$, and reverse the loop at (B). To minimize f , change it to $>$, also at (B).

Usage: int ind = ternSearch(0, n-1, [&](int i){return a[i];});

Time: $\mathcal{O}(\log(b - a))$

9155b4, 11 lines

```

template<class F>
int ternSearch(int a, int b, F f) {
    assert(a <= b);
    while (b - a >= 5) {
        int mid = (a + b) / 2;
        if (f(mid) < f(mid+1)) a = mid; // (A)
        else b = mid+1;
    }
    rep(i, a+1, b+1) if (f(a) < f(i)) a = i; // (B)
    return a;
}

```

LIS.h

Description: Compute indices for the longest increasing subsequence.

Time: $\mathcal{O}(N \log N)$

2932a0, 17 lines

```

template<class I> vi lis(const vector<I>& S) {
    if (S.empty()) return {};
    vi prev(sz(S));
    typedef pair<I, int> p;
    vector<p> res;
    rep(i, 0, sz(S)) {
        // change 0 -> i for longest non-decreasing subsequence
        auto it = lower_bound(all(res), p{S[i], 0});
        if (it == res.end()) res.emplace_back(), it = res.end() - 1;
        *it = {S[i], i};
        prev[i] = it == res.begin() ? 0 : (it-1)->second;
    }
    int L = sz(res), cur = res.back().second;
    vi ans(L);
    while (L-->) ans[L] = cur, cur = prev[cur];
    return ans;
}

```

10.3 Dynamic programming

KnuthDP.h

Description: When doing DP on intervals: $a[i][j] = \min_{i < k < j} (a[i][k] + a[k][j]) + f(i, j)$, where the (minimal) optimal k increases with both i and j , one can solve intervals in increasing order of length, and search $k = p[i][j]$ for $a[i][j]$ only between $p[i][j - 1]$ and $p[i + 1][j]$. This is known as Knuth DP. Sufficient criteria for this are if $f(b, c) \leq f(a, d)$ and $f(a, c) + f(b, d) \leq f(a, d) + f(b, c)$ for all $a \leq b \leq c \leq d$. Consider also: LineContainer (ch. Data structures), monotone queues, ternary search.

Time: $\mathcal{O}(N^2)$

DivideAndConquerDP.h

Description: Given $a[i] = \min_{lo(i) \leq k < hi(i)} (f(i, k))$ where the (minimal) optimal k increases with i , computes $a[i]$ for $i = L..R - 1$.

Time: $\mathcal{O}((N + (hi - lo)) \log N)$

d38d2b, 18 lines

```

struct DP { // Modify at will:
    int lo(int ind) { return 0; }
    int hi(int ind) { return ind; }
    ll f(int ind, int k) { return dp[ind][k]; }
}

```

```
void store(int ind, int k, ll v) { res[ind] = pii(k, v);
}

void rec(int L, int R, int LO, int HI) {
    if (L >= R) return;
    int mid = (L + R) >> 1;
    pair<ll, int> best(LLONG_MAX, LO);
    rep(k, max(LO, lo(mid)), min(HI, hi(mid)))
        best = min(best, make_pair(f(mid, k), k));
    store(mid, best.second, best.first);
    rec(L, mid, LO, best.second+1);
    rec(mid+1, R, best.second, HI);
}

void solve(int L, int R) { rec(L, R, INT_MIN, INT_MAX); }
};
```

10.4 Optimization tricks

10.4.1 Bit hacks

- $x \& -x$ is the least bit in x .
- for (int x = m; x;) { --x &= m; ... }
loops over all subset masks of m (except m itself).
- $c = x \& -x, r = x + c; (((r^x) >> 2) / c) | r$;
is the next number after x with the same number of bits set.
- $\text{rep}(b, 0, K) \text{ rep}(i, 0, (1 \ll K))$
if (i & 1 << b) D[i] += D[i^(1 << b)]
computes all sums of subsets.

FastMod.h
Description: Compute $a\%b$ about 4 times faster than usual, where b is constant but not known at compile time. Fails for $b = 1$.

```
typedef unsigned long long ull;
typedef __uint128_t L;
struct FastMod {
    ull b, m;
    FastMod(ull b) : b(b), m(ull)((L(1) << 64) / b) {}
    ull reduce(ull a) {
        ull q = (ull)((L(m) * a) >> 64), r = a - q * b;
        return r >= b ? r - b : r;
    }
};
```

BumpAllocator.h
Description: When you need to dynamically allocate many objects and don't care about freeing them. "new X" otherwise has an overhead of something like 0.05us + 16 bytes per allocation.

```
// Either globally or in a single class:
static char buf[450 << 20];
void* operator new(size_t s) {
    static size_t i = sizeof buf;
    assert(s < i);
    return (void*)&buf[i -= s];
}
void operator delete(void*) {}
```

```
SmallPtr.h
Description: A 32-bit pointer that points into BumpAllocator memory.
"BumpAllocator.h" 2dd6c9, 10 lines

template<class T> struct ptr {
    unsigned ind;
    ptr(T* p = 0) : ind(p ? unsigned((char*)p - buf) : 0) {
        assert(ind < sizeof buf);
    }
    T& operator*() const { return *(T*)(buf + ind); }
    T* operator->() const { return &*this; }
    T& operator[](int a) const { return (&*this)[a]; }
    explicit operator bool() const { return ind; }
};
```

BumpAllocatorSTL.h
Description: BumpAllocator for STL containers.
Usage: vector<vector<int, small<int>>>> ed(N);

```
char buf[450 << 20] alignas(16);
size_t buf_ind = sizeof buf;

template<class T> struct small {
    typedef T value_type;
    small() {}
    template<class U> small(const U&) {}
    T* allocate(size_t n) {
        buf_ind -= n * sizeof(T);
        buf_ind &= 0 - alignof(T);
        return (T*)(buf + buf_ind);
    }
    void deallocate(T*, size_t) {}
};
```

BitManipulation.h
Description: Various bit operations

```
#define isOn(S, j) (S & (1<<j))
#define setBit(S, j) (S |= (1<<j))
#define clearBit(S, j) (S &= ~(1<<j))
#define toggleBit(S, j) (S ^= (1<<j))
#define lowBit(S) (S & (-S))
#define setAll(S, n) (S = (1<<n)-1)

#define modulo(S, N) ((S) & (N-1)) // returns S % N,
    where N is a power of 2
#define isPowerOfTwo(S) (!(S & (S-1)))
#define nearestPowerOfTwo(S) ((int)pow(2.0, (int)((log((double)S) / log(2.0)) + 0.5)))
#define turnOffLastBit(S) ((S) & (S-1))
#define turnOnLastZero(S) ((S) | (S+1))
#define turnOffLastConsecutiveBits(S) ((S) & (S+1))
#define turnOnLastConsecutiveZeroes(S) ((S) | (S-1))

void printSet(int vS) { // in binary representation
    printf("S = %2d = ", vS);
    stack<int> st;
    while (vS)
        st.push(vS%2), vS /= 2;
    while (!st.empty()) // to reverse the print order
        printf("%d", st.top()), st.pop();
    printf("\n");
}
```

Techniques (A)

techniques.txt

225 lines

Recursion
Divide and conquer
 Finding interesting points in $N \log N$
Algorithm analysis
 Master theorem
 Amortized time complexity
Greedy algorithm
 Scheduling
 Max contiguous subvector sum
 Invariants
 Huffman encoding
Graph theory
 Dynamic graphs (extra book-keeping)
 Breadth first search
 Depth first search
 * Normal trees / DFS trees
 Dijkstra's algorithm
 MST: Prim's algorithm
 Bellman-Ford
 Konig's theorem and vertex cover
 Min-cost max flow
 Lovasz toggle
 Matrix tree theorem
 Maximal matching, general graphs
 Hopcroft-Karp
 Hall's marriage theorem
 Graphical sequences
 Floyd-Warshall
 Euler cycles
 Flow networks
 * Augmenting paths
 * Edmonds-Karp
 Bipartite matching
 Min. path cover
 Topological sorting
 Strongly connected components
 2-SAT
 Cut vertices, cut-edges and biconnected components
 Edge coloring
 * Trees
 Vertex coloring
 * Bipartite graphs (\Rightarrow trees)
 * 3^n (special case of set cover)
 Diameter and centroid
 K'th shortest path
 Shortest cycle
Dynamic programming
 Knapsack
 Coin change
 Longest common subsequence
 Longest increasing subsequence
 Number of paths in a dag
 Shortest path in a dag
 Dynprog over intervals
 Dynprog over subsets
 Dynprog over probabilities
 Dynprog over trees
 3^n set cover
 Divide and conquer
 Knuth optimization
 Convex hull optimizations
 RMQ (sparse table a.k.a 2^k -jumps)
 Bitonic cycle
 Log partitioning (loop over most restricted)
Combinatorics
 Computation of binomial coefficients
 Pigeon-hole principle

Inclusion/exclusion
Catalan number
Pick's theorem
Number theory
 Integer parts
 Divisibility
 Euclidean algorithm
 Modular arithmetic
 * Modular multiplication
 * Modular inverses
 * Modular exponentiation by squaring
 Chinese remainder theorem
 Fermat's little theorem
 Euler's theorem
 Phi function
 Frobenius number
 Quadratic reciprocity
 Pollard-Rho
 Miller-Rabin
 Hensel lifting
 Vieta root jumping
Game theory
 Combinatorial games
 Game trees
 Mini-max
 Nim
 Games on graphs
 Games on graphs with loops
 Grundy numbers
 Bipartite games without repetition
 General games without repetition
 Alpha-beta pruning
Probability theory
Optimization
 Binary search
 Ternary search
 Unimodality and convex functions
 Binary search on derivative
Numerical methods
 Numeric integration
 Newton's method
 Root-finding with binary/ternary search
 Golden section search
Matrices
 Gaussian elimination
 Exponentiation by squaring
Sorting
 Radix sort
Geometry
 Coordinates and vectors
 * Cross product
 * Scalar product
 Convex hull
 Polygon cut
 Closest pair
 Coordinate-compression
 Quadtrees
 KD-trees
 All segment-segment intersection
Sweeping
 Discretization (convert to events and sweep)
 Angle sweeping
 Line sweeping
 Discrete second derivatives
Strings
 Longest common substring
 Palindrome subsequences
 Knuth-Morris-Pratt
 Tries
 Rolling polynomial hashes
 Suffix array

Suffix tree
Aho-Corasick
Manacher's algorithm
Letter position lists
Combinatorial search
 Meet in the middle
 Brute-force with pruning
 Best-first (A^*)
 Bidirectional search
 Iterative deepening DFS / A^*
Data structures
 LCA (2^k -jumps in trees in general)
 Pull/push-technique on trees
 Heavy-light decomposition
 Centroid decomposition
 Lazy propagation
 Self-balancing trees
 Convex hull trick (wcipeg.com/wiki/Convex_hull_trick)
 Monotone queues / monotone stacks / sliding queues
 Sliding queue using 2 stacks
 Persistent segment tree
How to solve an algorithm problem
 1. Floyd-Warshall as a universal graph algorithm for $V \leq 500$, Ford-Bellman, Dijkstra ($E \log V$, V^2), BFS for 0-1 edge weights, DFS, Topological Sorting
 2. Disjoint sets for connected components.
 3. Care to constraints (upper and sometimes lower). Try small examples. Case analysis (e.g. process small and large inputs separately).
 4. Structure of the Answer. Answer can be very constrained (e.g. small sequences, values only from input set). Sometimes no need to give full answer (e.g. only count)
 5. Simplify problem, e.g. consider $d[i] = a[i] - b[i]$ instead of $a[i]$ and $b[i]$, or $d[i] = a[i+1] - a[i]$
 6. Dynamic Programming: shortest path for acyclic graph, knapsack, matrix chain, edit distance, mask, take/don't take, tsp, shape, use \leq instead of $=$, swap argument and value. Optimizations: Segment Trees, Knuth optimization, convex hull, divide and conquer for monotonicity.
 7. Write brute-force solution to find pattern, PolynomialInterpolation($[[[0, 0], [1, 3], [2, 1], [3, 3]], x]$, wolframalpha.com, oeis.org)
 8. Greedy, start with greatest, greedy sequential search, order by a , b , a/b , $a-b$, $a+b$
 9. Merging small tree into a big one, obtaining $O(n \log(n))$ transitions
 10. Unite n lists in $O(n)$
 11. MinCut / MaxFlow (of Min Cost), Max Matching
 12. Brute Force, Precalculation, Precalculation on Prefixes / Suffixes, Bit-level parallelism
 13. Counting Sort
 14. Two Pointers
 15. Meet In The Middle + 2 Pointers
 16. Scan line with events
 17. Binary search (average, median), ternary search, Binary search + Greedy, Binary search + DP, Binary Search + Two Pointers
 18. Union find
 19. SQRT-decomposition, Sparse Table, Query Caching
 20. Segment Tree, Treap, Persistent Tree, Kd-tree
 21. Minimum Spanning Tree, Strongly Connected Components, 2-SAT, Biconnected Components, LCA, Eulerian path, Dilworth's theorem, Transform to Bipartite Graph
 22. Assume that we have decompositions into Strongly Connected Components and Biconnected Components of input graph
 23. Hashing, Suffix Array, KMP, LCP, Suffix Automata, Aho-Corasick
 24. Divide-and-conquer

25. Inclusion-exclusion
26. Put 2 neighbors $(a+1, b)$, $(a, b+1)$ into heap
27. Matrices, Gauss Elimination, Linear algebra for xor - problems
28. Randomized algorithm, Random Search, Shuffle
29. Symmetric strategy
30. Change of Coordinates $X+Y$, $X-Y$. Affine Transformation
($c*x - d*y$, $-a*x + b*y$)
31. Pigeonhole principle
32. Stirling numbers
33. Solve inverse problem (min / max)
34. Simplex algorithm
35. Grundy numbers
36. Traverse tree in dfs-order, subtrees map to segments
37. LIS, fix LIS in sequence and process other elements greedily
38. Max subarray, Marzullo's algorithm
39. Offline query (DQuery)
40. Euler formula: $V - E + F = 2$
41. Counting problems - try to find independent classes, double counting, combinations
42. Tree center
43. Sort-traverse-check
44. Linearity of Expectation
45. Sorting in optimization problems with arbitrary rearranging.
46. Calc smth to the left and to right of element. e.g. $a[i] < a[j] < a[k]$, $i < j < k$
47. In greedy problems try all variants: from the smallest to the biggest, from the biggest to smallest.
48. Orthogonal segments or L1-metric - try use fenwick tree
49. "Incremental DP", e.g. $dp[i][j] = f(dp[i-1][j-1], dp[i][j])$, use $dp[a-b]$ instead of $dp[a][b]$, reverse $dp[x] > answer$ into $dp[answer] \rightarrow x$, push-dp: $dp[i+x] < dp[i]$
50. If there is no optimal substructure - try something else than DP (e.g. greedy)
51. Find solution for $n-1$. Use it to find solution for n .
52. Decompose complicated problem into simple cases
53. Random-restart hill climbing
54. Separate queries into big and small. Cache big queries
55. Solve problem from the end
56. Start with a slow DP, then optimize it.
57. Add edges one by one, maintaining connected components with disjoint sets.
58. For palindromes problems - move from edges to center: $0, n-1$; $1, n-2$; ...
59. Resolve transitivity with Floyd-Warshall
60. Replace minCostMaxflow with maxflow
61. Hierarchic structure with double size: $h[i*2] <- h[i]$
62. At each step process the minimum element and then remove it, if it is independent of the others
63. Calc min, max boundaries, check $min \leq x \leq max$, and prove that any x can be reached
64. Treat row and columns independently (Boomerang Farm)
65. Find tight lower bound and try to prove it is also upper bound.