

EDUCATION	<i>University of California Santa Barbara</i> <b>PhD</b> in Electrical and Computer Engineering <b>Awards:</b> Fulbright Scholarship – renounced	<i>Santa Barbara, CA, USA</i> GPA: 3.85 / 4.0 Expected: 2021
	<i>Poznan University of Technology</i> <b>MS</b> in Mechatronics <b>Awards:</b> Dean's Scholarship (2014)	<i>Poznan, Poland</i> GPA: 4.68 / 5.0 2014 – 2015
	<i>Poznan University of Technology</i> <b>BS</b> in Mechatronics <b>Awards:</b> Award for the Best Freshman, Dean's Scholarship (2011, 2012, 2013)	<i>Poznan, Poland</i> GPA: 4.63 / 5.0 2010 – 2014
	<i>Online education</i> <ul style="list-style-type: none"><li>PyTorch Scholarship Challenge – Facebook (Udacity)</li><li>Neural networks for machine learning – University of Toronto (Coursera)</li><li>Artificial intelligence for robotics – Stanford (Udacity)</li><li>Artificial intelligence – UC Berkeley (EdX)</li></ul>	
PROFESSIONAL EXPERIENCE	<i>Microsoft Research</i> <b>Research Software Development Engineer</b> <ul style="list-style-type: none"><li>Research in long-tail and imbalanced classification leading towards patent and publication</li></ul>	<i>Redmond, WA, USA</i> Oct '19 – Jan '20
	<i>Microsoft Research</i> <b>Computer Vision Research Intern</b> <ul style="list-style-type: none"><li>Research in large-scale long-tail image recognition</li><li>Utilized adversarial training for imbalance datasets</li></ul>	<i>Redmond, WA, USA</i> Jun '19 – Sep '19
	<i>University of California, Santa Barbara</i> <b>Graduate Student Researcher – Four Eyes Lab</b> <ul style="list-style-type: none"><li>Research in machine learning algorithms for computer vision applications</li><li>Developed novel object classification algorithms for tasks with insufficient training data</li><li>Deep transfer learning for One-Shot / Few-Shot One-Class image recognition</li></ul>	<i>Santa Barbara, CA, USA</i> Sep '16 – Jun '19
	<i>Samsung Research America</i> <b>Computer Vision Intern – Think Tank Team</b> <ul style="list-style-type: none"><li>Object detection and tracking from stereo vision for autonomous driving applications</li><li>Experimental stereo vision setups for autonomous driving applications</li><li>Deep learning for stereo matching and scene segmentation</li></ul>	<i>Mountain View, CA, USA</i> Apr '18 – Sep '18
	<i>FLIR Systems</i> <b>Deep Learning Engineer</b> <ul style="list-style-type: none"><li>Responsible for creating deep learning methods for pedestrian re-identification from camera images</li><li>Developed deep networks for semantically meaningful people and clothing descriptors</li><li>Deep pose estimation for better pedestrian re-identification</li></ul>	<i>Santa Barbara, CA, USA</i> Jun '17 – Sep '17
	<i>Autodesk</i> <b>Machine Learning Intern</b> <ul style="list-style-type: none"><li>Developed supervised learning algorithms to reflect user preferences in architectural documentation</li><li>Worked on automated object placement in a 2D space</li><li>Unsupervised clustering of architectural views</li></ul>	<i>Boston, MA, USA</i> Jun '16 – Sep '16
	<i>University of California, Santa Barbara</i> <b>Graduate Student Researcher – Intelligent and Predictive Systems Lab</b> <ul style="list-style-type: none"><li>Team leader in National Library of Medicine “Pill Image Recognition Challenge”</li><li>Developed machine learning algorithms for network data prediction</li><li>Performed unsupervised feature selection and classification of medical data sets</li></ul>	<i>Santa Barbara, CA, USA</i> Oct '15 – Sep '16
	<i>Institute of Biocybernetics and Biomedical Engineering</i> <b>Research Intern</b> <ul style="list-style-type: none"><li>Performed scientific evaluation of the clinical usefulness of the designed devices</li><li>Completed 70+ page report analyzing patients data on Huntington Disease</li></ul>	<i>Poznan, Poland</i> Jun '12 – Jul '12
TEACHING EXPERIENCE	<i>Stanford University</i> <b>Voluntary Section Leader – CS 106A Code in Place</b> <ul style="list-style-type: none"><li>Leading weekly live practical coding sections for students</li><li>Creating challenging problems for students</li></ul>	<i>Stanford, CA, USA</i> Apr '20 – Now

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TEACHING  
EXPERIENCE  
continued

*University of California, Santa Barbara*

*Santa Barbara, CA, USA*

**Teaching Associate – CS 32 Object Oriented Design and Implementation**

*Mar '20 – Now*

- The lead instructor for the CS 32
- Leading lectures, course organization, course materials preparation

**Teaching Assistant – CS/ECE 181 Introduction to Computer Vision**

*Jan '20 – Mar '20*

- Led discussion sections to explain novel concepts in machine learning
- Helped students with practical implementations of algorithms and their theoretical understanding

**Teaching Assistant – CS 165B Machine Learning**

*Jan '19 – Mar '19*

- Led discussion sections to explain novel concepts in machine learning
- Helped students with practical implementations of algorithms and their theoretical understanding

**Teaching Assistant – ECE 152A Digital Design Principles**

*Jan '16 – Mar '16*

- Led computer labs classes where student designed and implemented electronic circuits
- Created and graded homework assignments and practice exercises

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GIVEN TALKS

“Explaining concepts visually: a novel approach for general object recognition” – at UCSB Dynamical Neuroscience seminar, Nov 2018

“Explaining concepts visually: continuous AI learning” – at UCSB CS Summit, Mar 2018

„SVM Transfer Learning for Object Recognition” – at UCSB Society for Industrial and Applied Mathematics, Mar 2017

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PUBLICATIONS

- [1] CLEAR: Cumulative LEARning for one-shot one-class image recognition  
**J. Kozera** and M. Turk  
IEEE Conference on Computer Vision and Pattern Recognition (**CVPR**), 2018
- [2] HALT: Hallucinating Adversarial Images for Long-Tailed Datasets  
**J. Kozera**, V. Frago, N. Karianakis, G. Mittal, M. Turk and M. Chen  
In Submission

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SKILLS

Python, PyTorch, Caffe, TensorFlow, OpenCV, Linux, C++, C, Git