

CIFAR-10

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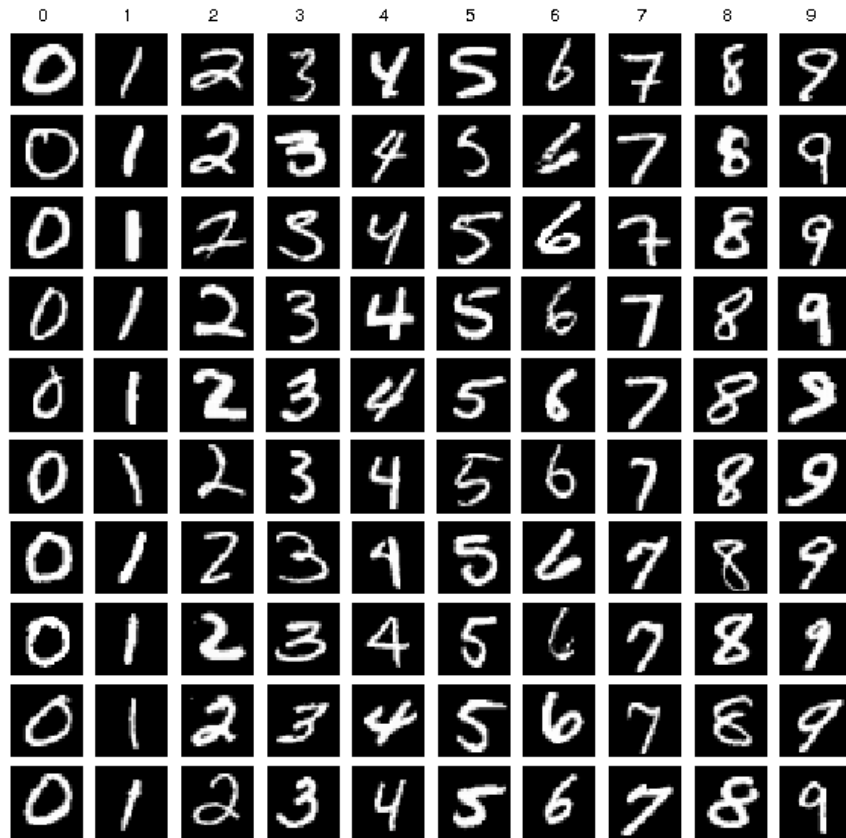
Class Lab – 기초 과제 일정

1. XOR (~4/05)

2. MNIST (~4/19)

3. CIFAR-10 (~5/03)

MNIST Review

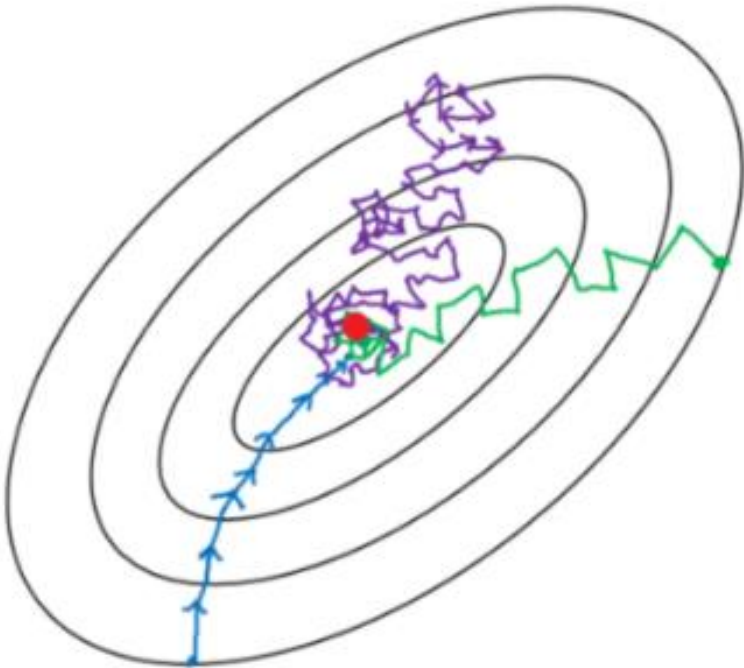


- The database contains 60,000 training images, 10,000 validation images, and 10,000 testing images with 10 classes.
- Shape of each data : [28, 28]
- Range : 0.0 to 1.0

MNIST Review

- **Mini-Batch**

- Batch gradient descent (batch size = n)
- Mini-batch gradient Descent ($1 < \text{batch size} < n$)
- Stochastic gradient descent (batch size = 1)



- **Weight Initialization**

(1) Xavier Normal Initialization

$$W \sim N(0, Var(W))$$

$$Var(W) = \sqrt{\frac{2}{n_{in} + n_{out}}}$$

(2) He Normal Initialization

$$W \sim N(0, Var(W))$$

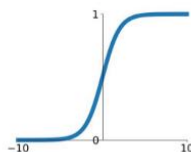
$$Var(W) = \sqrt{\frac{2}{n_{in}}}$$

MNIST Review

• Activation Function

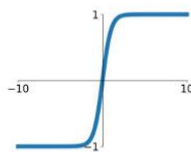
Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



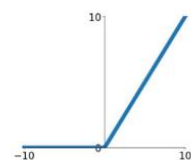
tanh

$$\tanh(x)$$



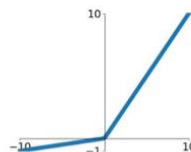
ReLU

$$\max(0, x)$$



Leaky ReLU

$$\max(0.1x, x)$$

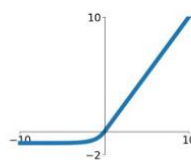


Maxout

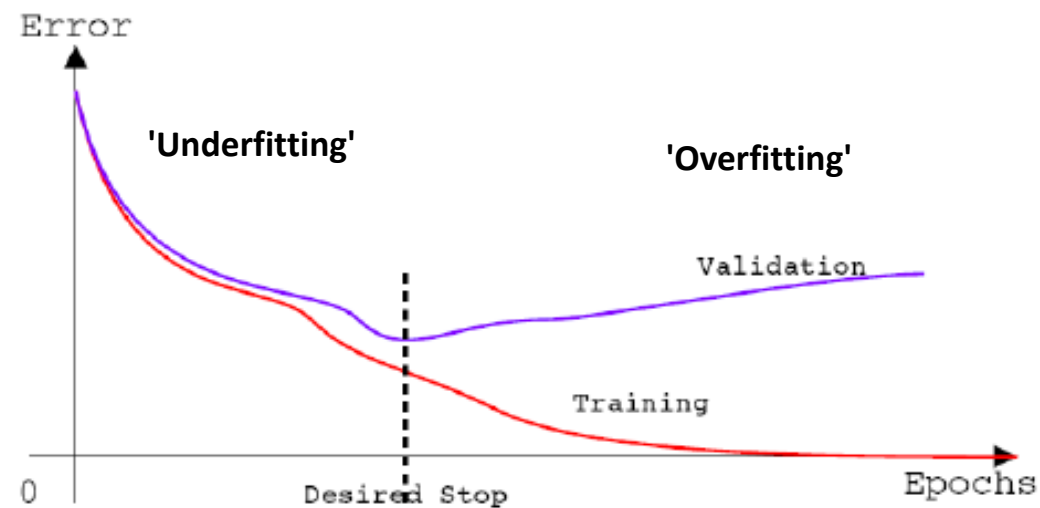
$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

ELU

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



• Early Stopping



MNIST Review

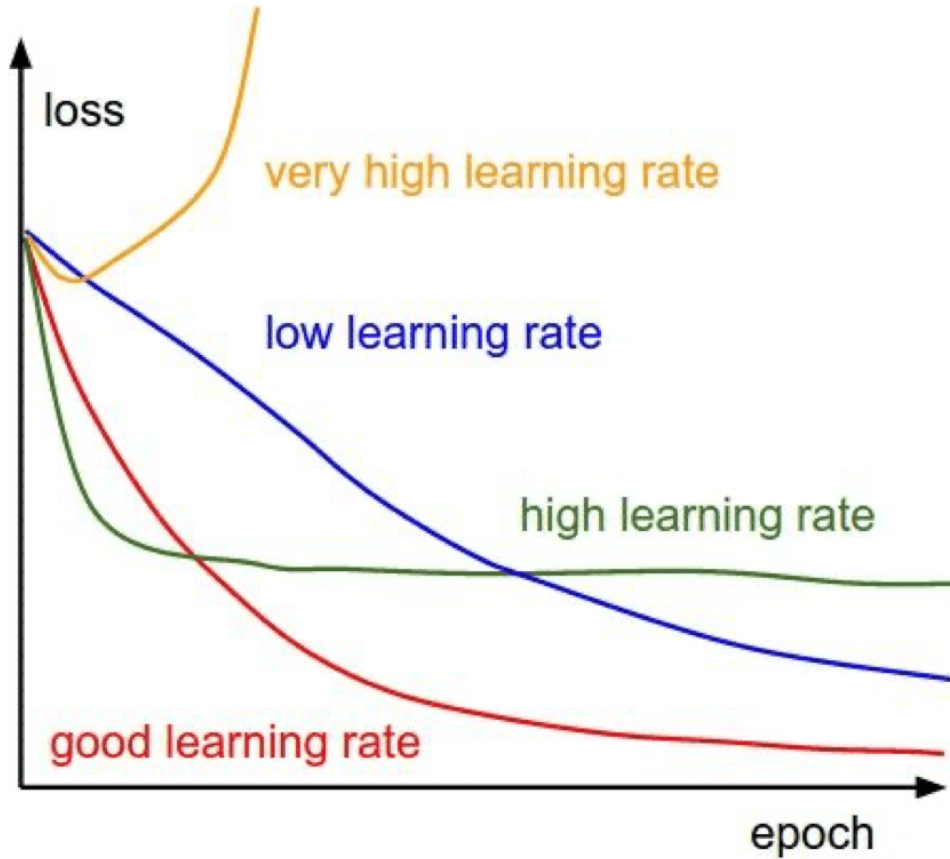
- Parameter Norm Penalties

Weight decay: $E_t = \frac{1}{N_t} \sum_{n \in D_t} E_n + \frac{\lambda}{2} \underbrace{||\mathbf{w}||^2}_{\text{L2-norm}}$

$$\mathbf{w}^{t+1} = \mathbf{w}^t - \epsilon \left(\frac{1}{N_t} \sum \nabla E_n + \lambda \mathbf{w}^t \right)$$

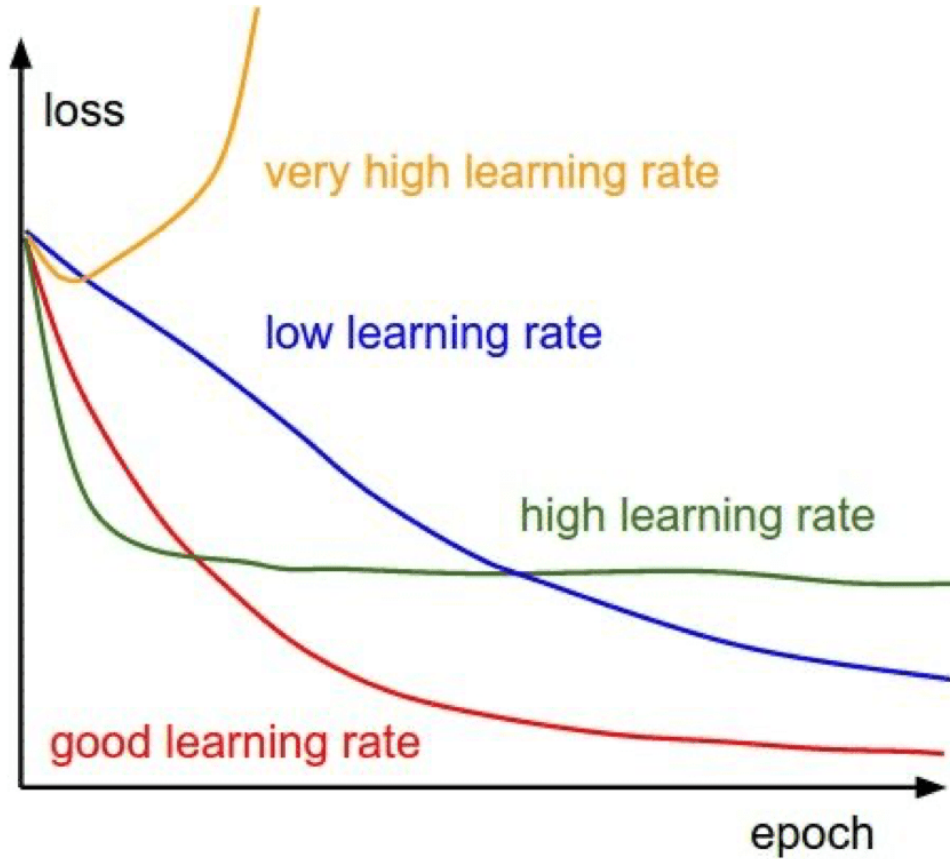
Weight restriction: $||\mathbf{w}||^2 < \mathbf{c}$

Learning Rate Decay



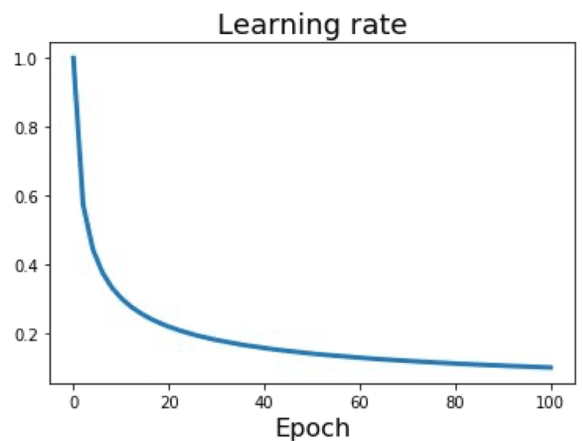
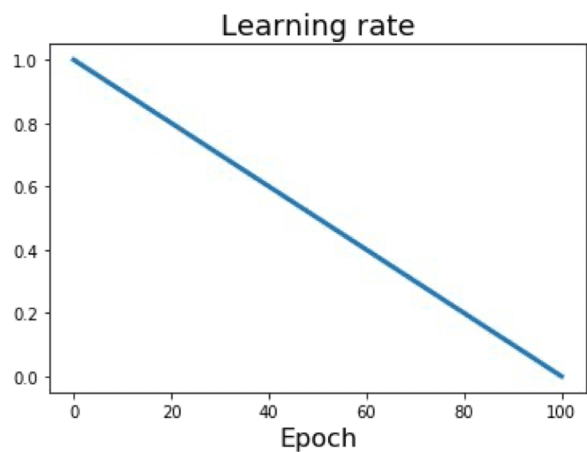
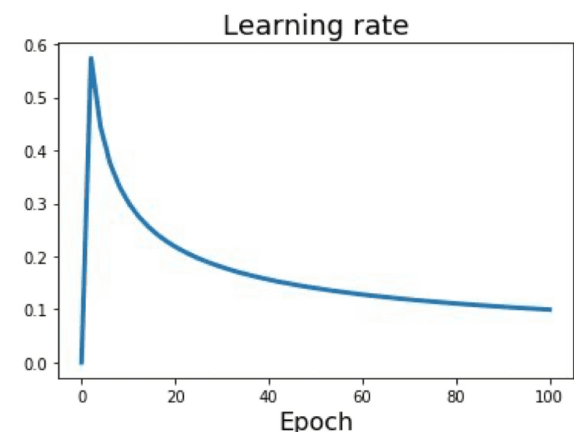
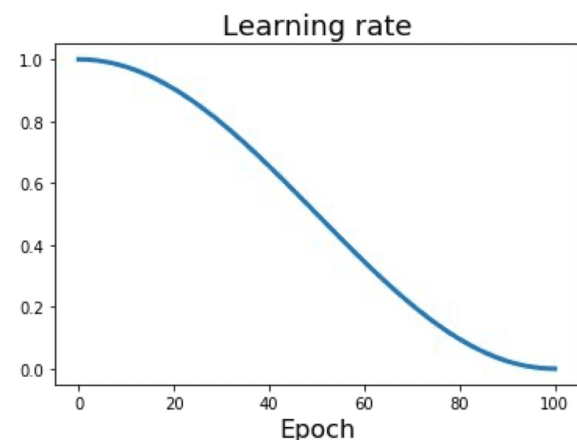
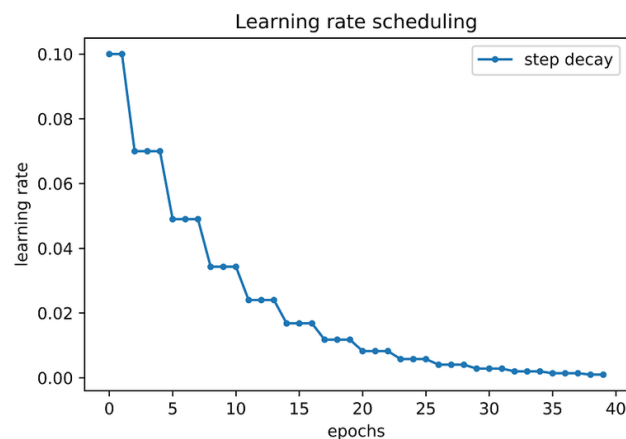
We should choose proper learning rate to find global optimum.

Choosing Proper Learning Rate

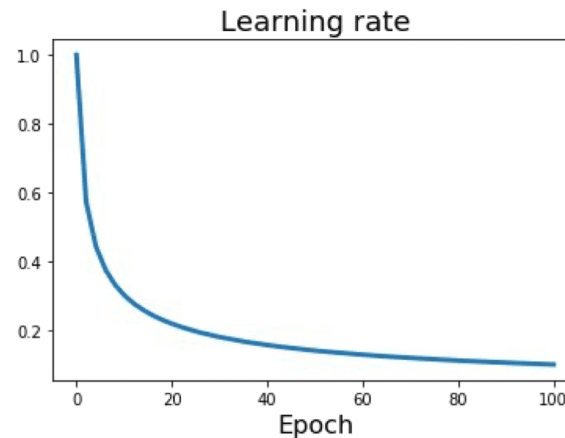
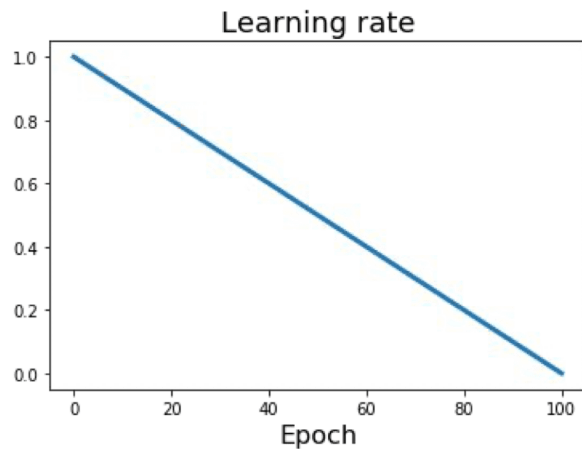
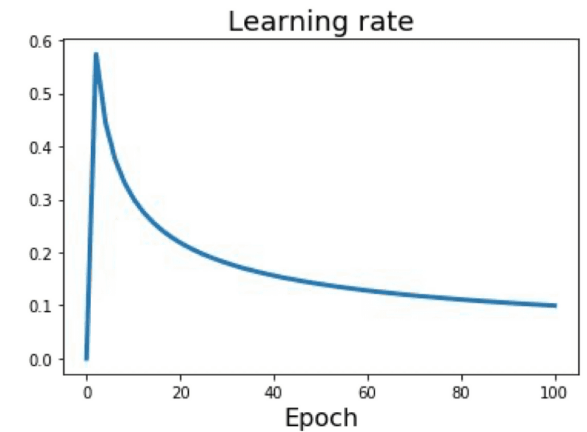
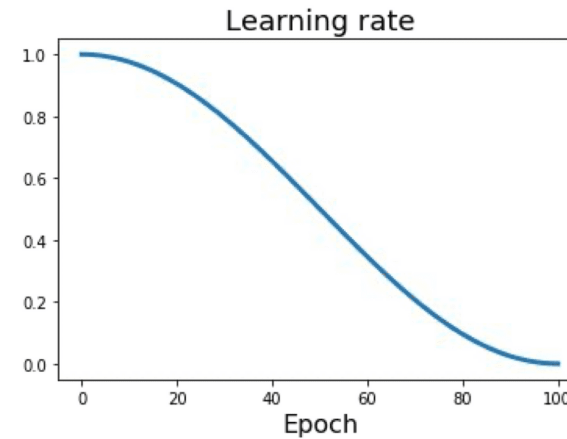
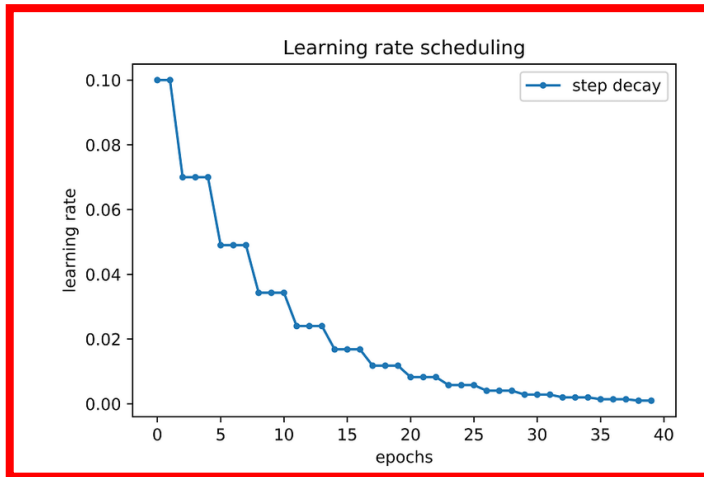


We should choose proper learning rate to find global optimum.

Learning Rate Scheduling (Learning Rate Decay)



Learning Rate Scheduling (Learning Rate Decay)



We use step decay method in training ResNet32.

Assignment #3 : CIFAR-10

airplane



automobile



bird



cat



deer



dog



frog



horse



ship



truck



Assignment #3 : CIFAR-10

• Introduction

- CIFAR-10 : Canadian Institute For Advanced Research
- This is a collection of images that are commonly used to train machine learning and computer vision algorithms.
- The database is also widely used for training and testing in the field of machine learning.
- The database contains 50,000 32×32 training images, 10,000 validation images, and 10,000 testing images with 10 classes.

airplane



automobile



bird



cat



deer



dog



frog



horse



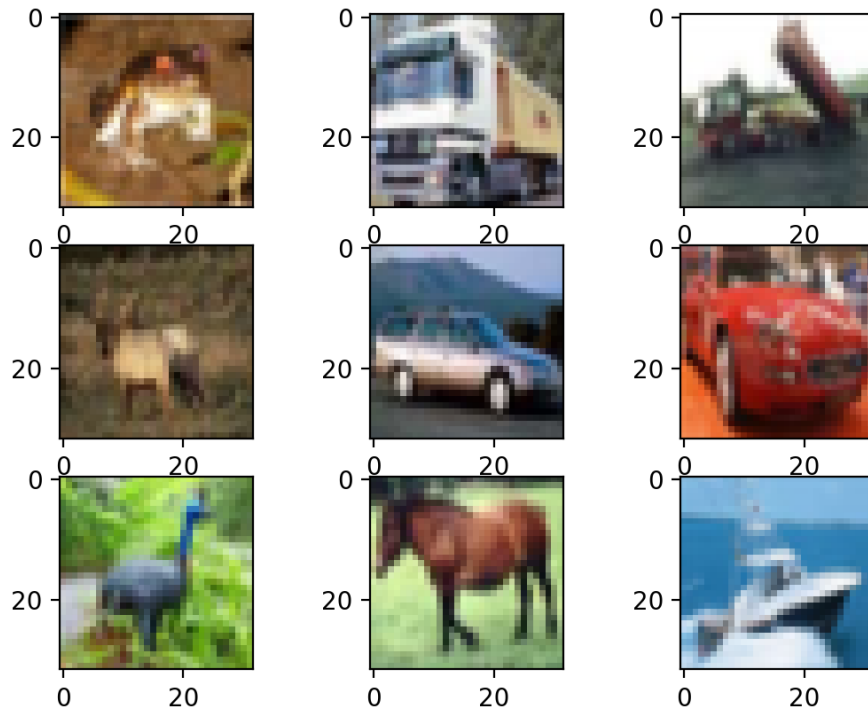
ship



truck



Assignment #3 : CIFAR-10



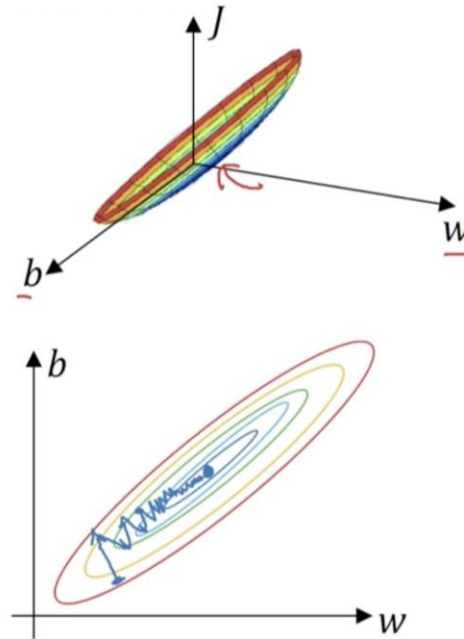
- Shape of each data : [3, 32, 32]
- Range : 0 to 255
- You can see the image of each data.
(available in the assignment code)

Standardization

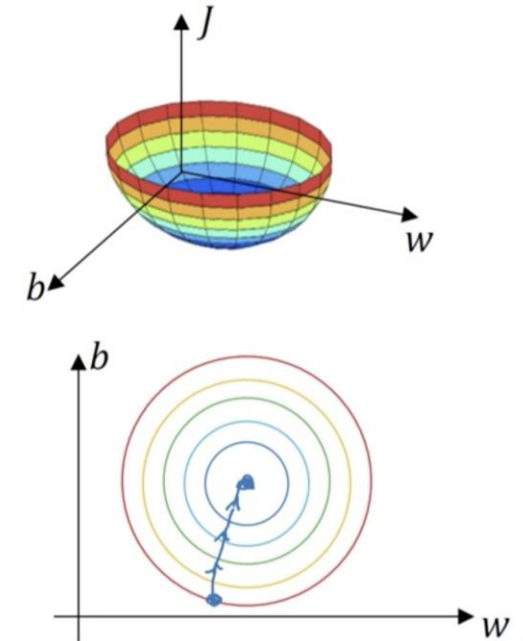
- Standardize the input data.

$$\mu = \frac{1}{m} \sum_{i=1}^m x^{(i)}$$
$$x := x - \mu$$
$$\sigma^2 = \frac{1}{m} \sum_{i=1}^m (x^{(i)} - \mu)^2$$

Unstandardized



Standardized



- We use standardization to apply gradient descent algorithm easily.

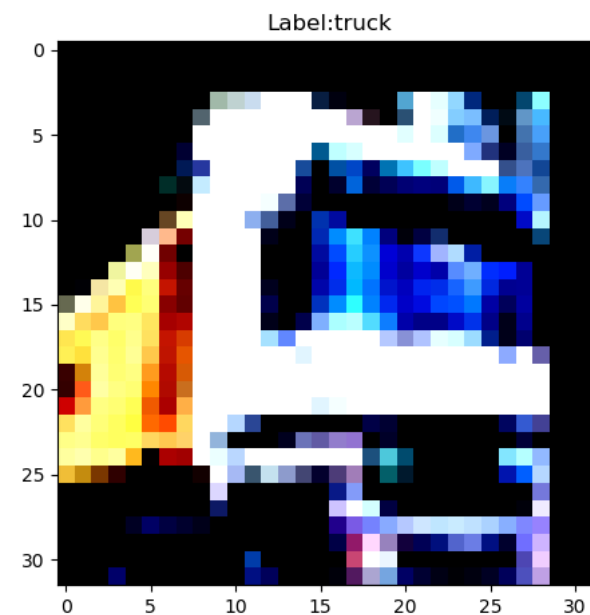
Standardization



$$\mu = \frac{1}{m} \sum_{i=1}^m x^{(i)}$$

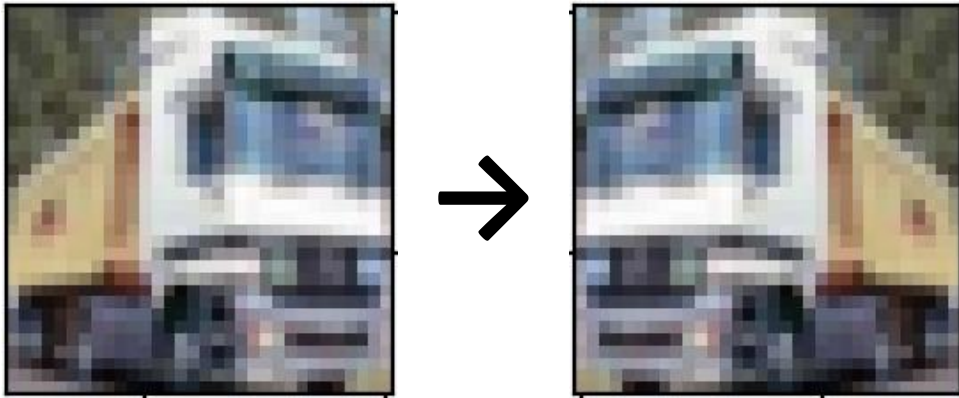
$$x := x - \mu$$

$$\sigma^2 = \frac{1}{m} \sum_{i=1}^m (x^{(i)} - \mu)^2$$



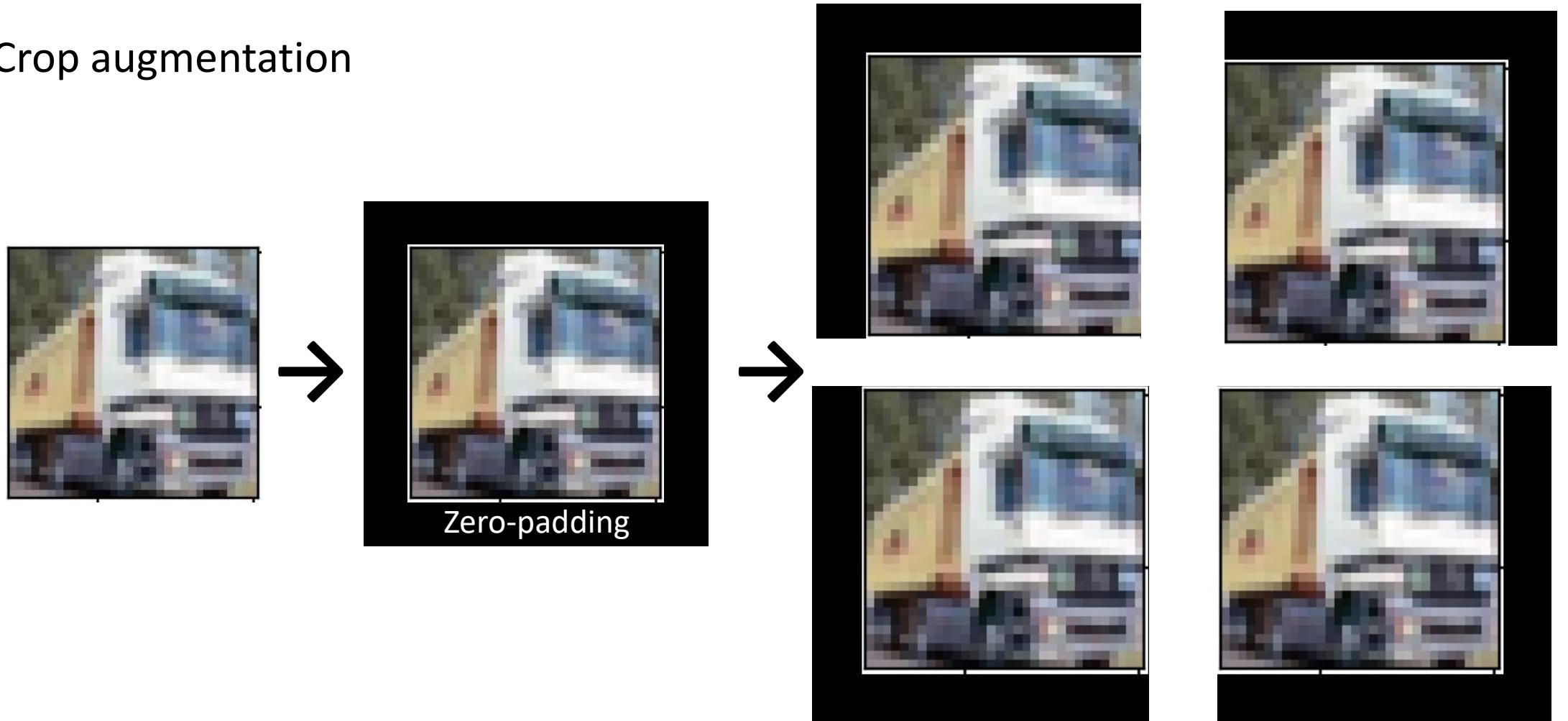
Data Augmentation

1) Flip augmentation

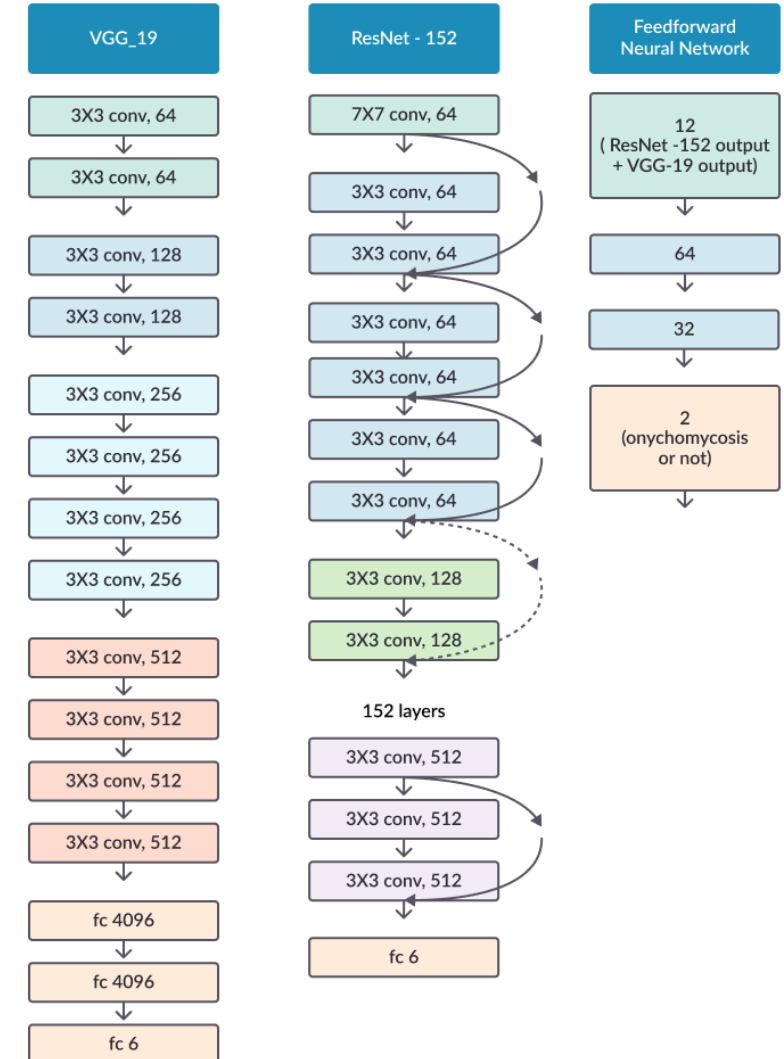
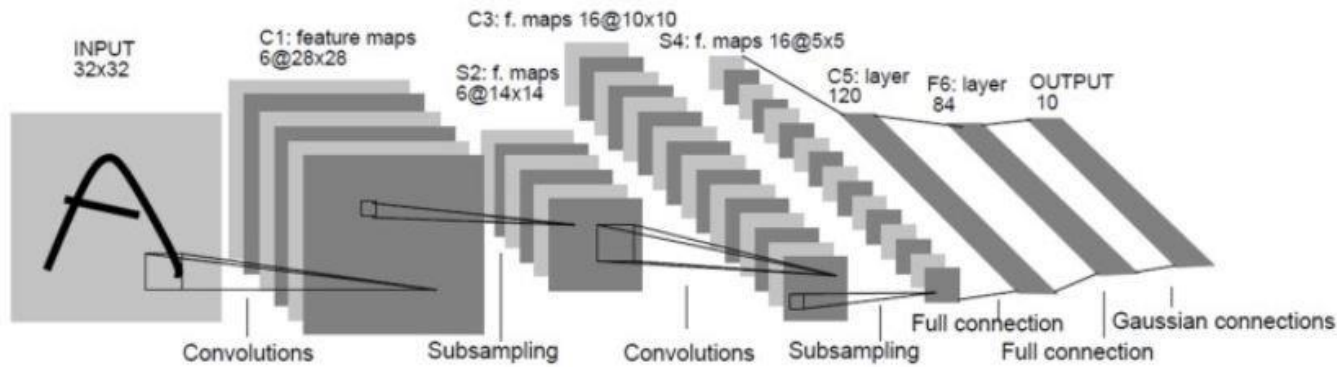


Data Augmentation

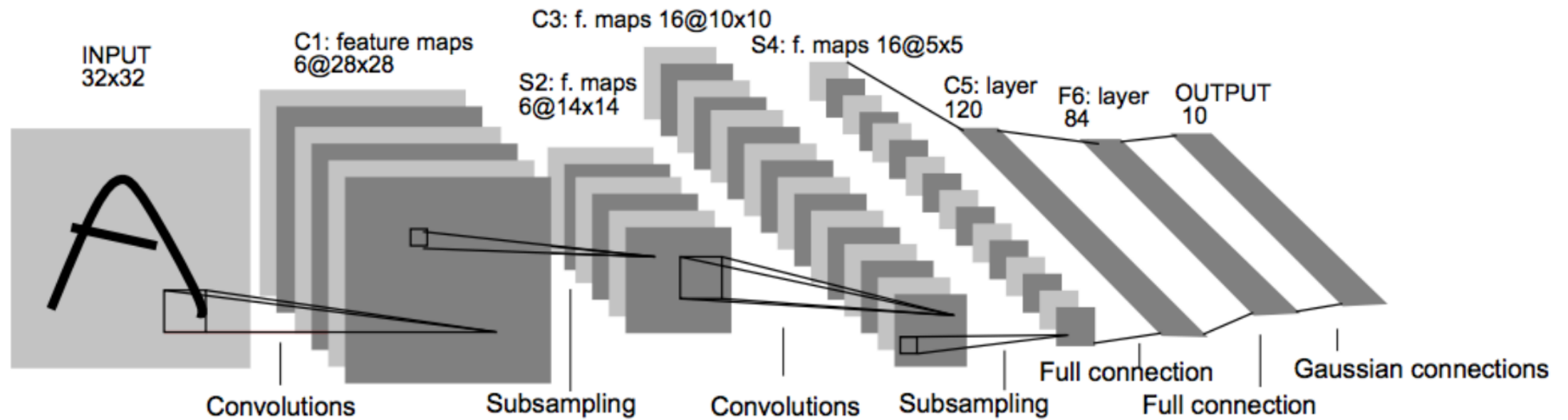
2) Crop augmentation



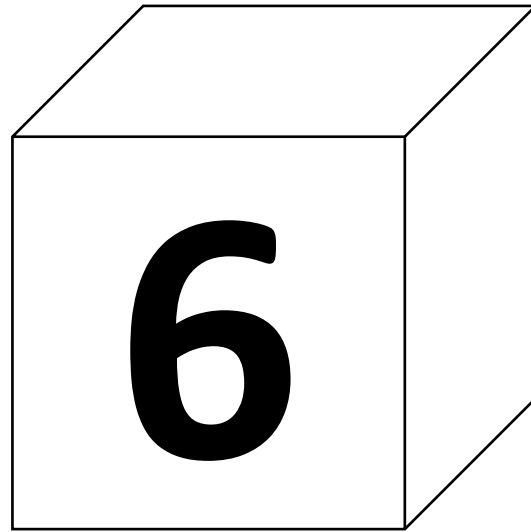
Convolutional Neural Network



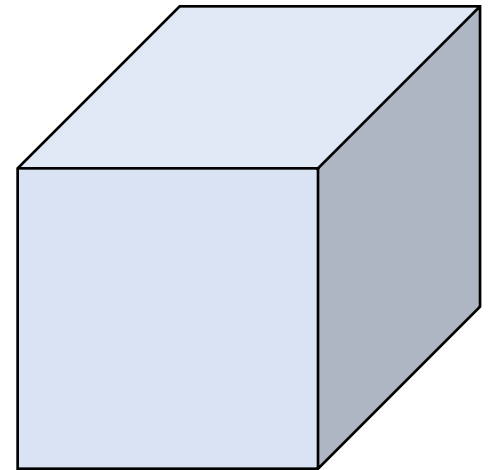
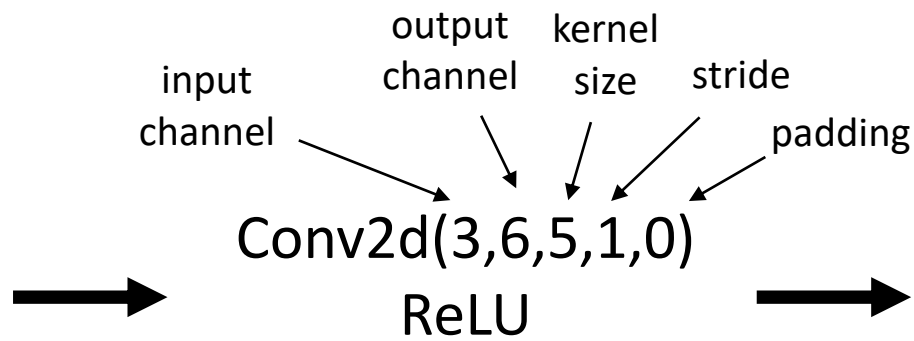
[1. LeNet-5¹]



[1. LeNet-5]

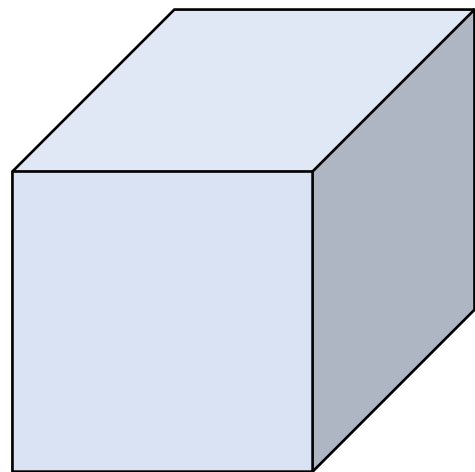


[3, 32, 32]



[6, 28, 28]

[1. LeNet-5]



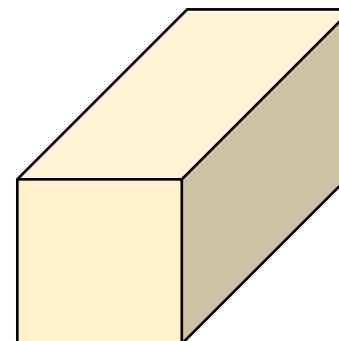
[6, 28, 28]



Pooling(2,2)

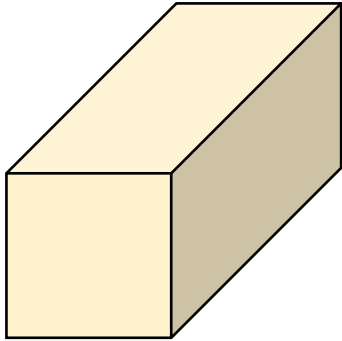
kernel
size

stride



[6, 14, 14]

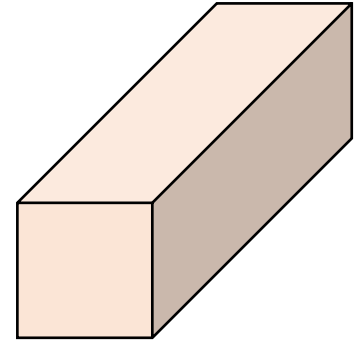
[1. LeNet-5]



[6, 14, 14]

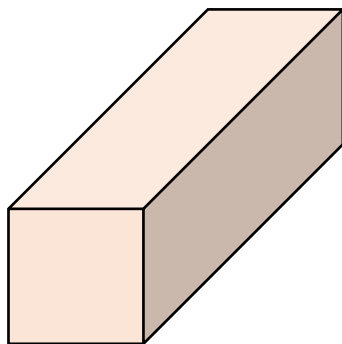


Conv2d(6,16,5,1,0)
ReLU



[16, 10, 10]

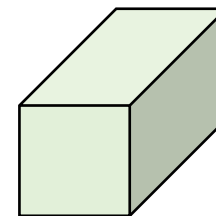
[1. LeNet-5]



[16, 10, 10]

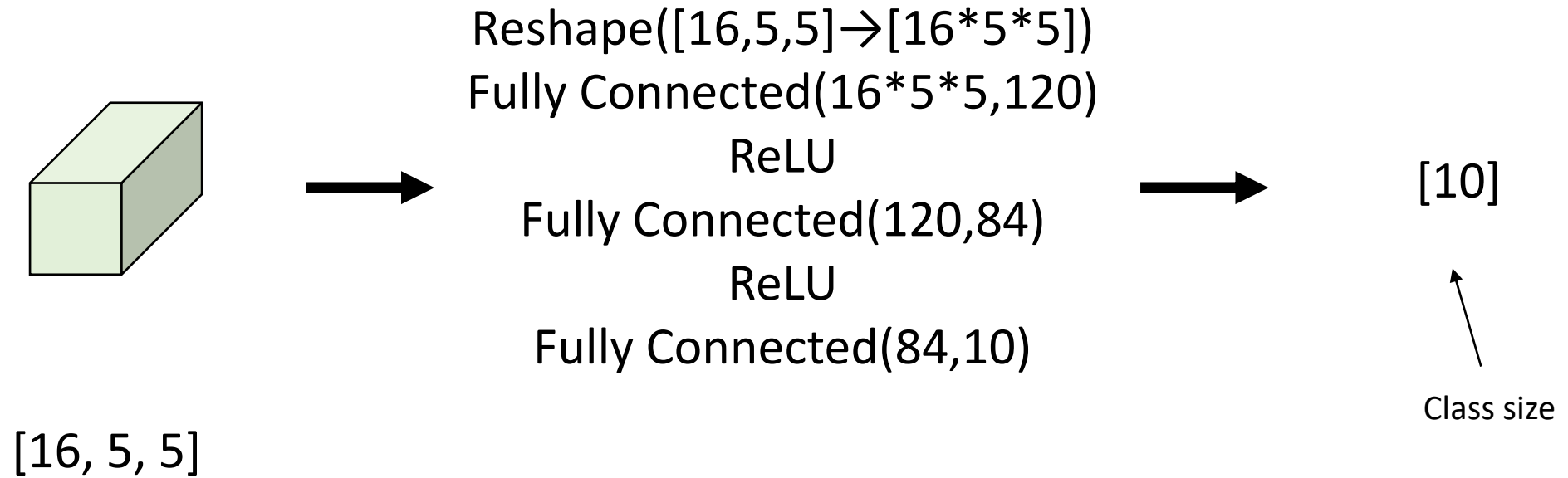


Pooling(2, 2)

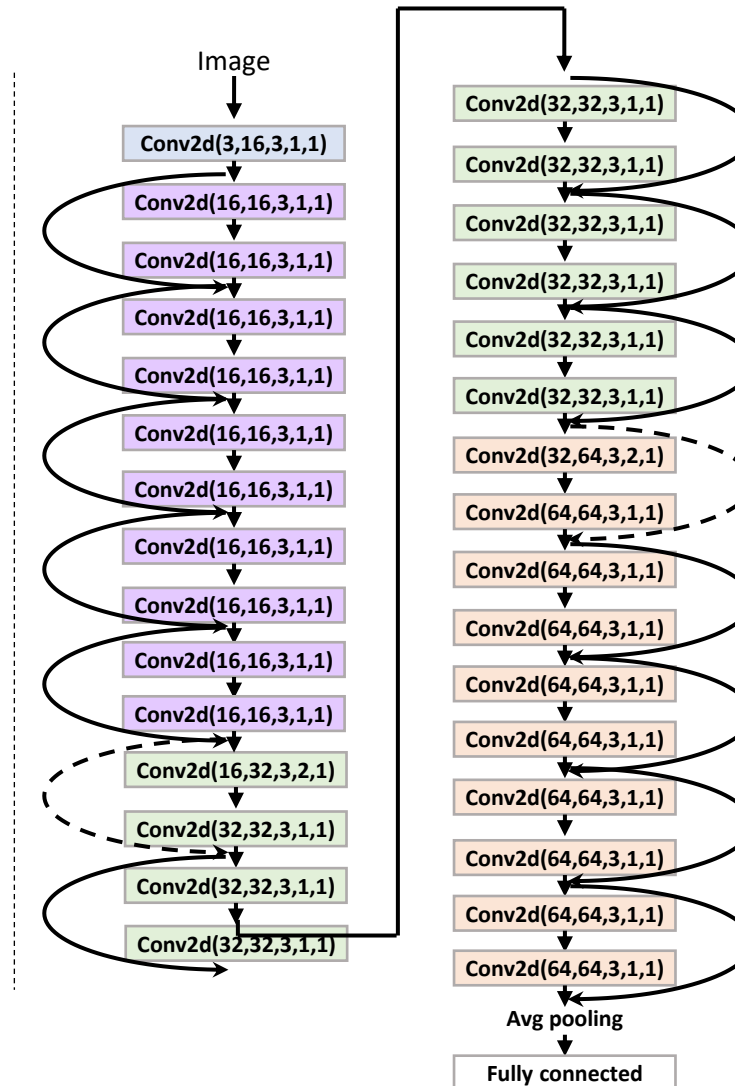


[16, 5, 5]

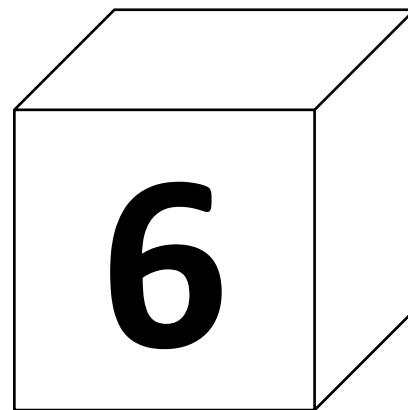
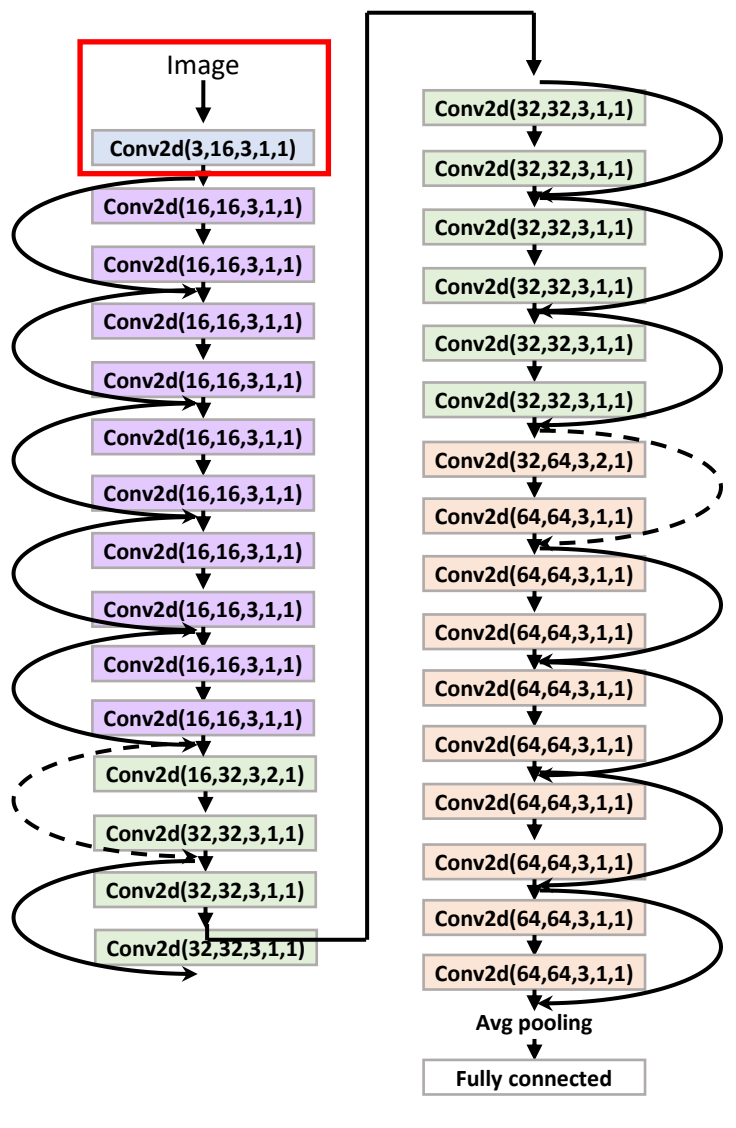
[1. LeNet-5]



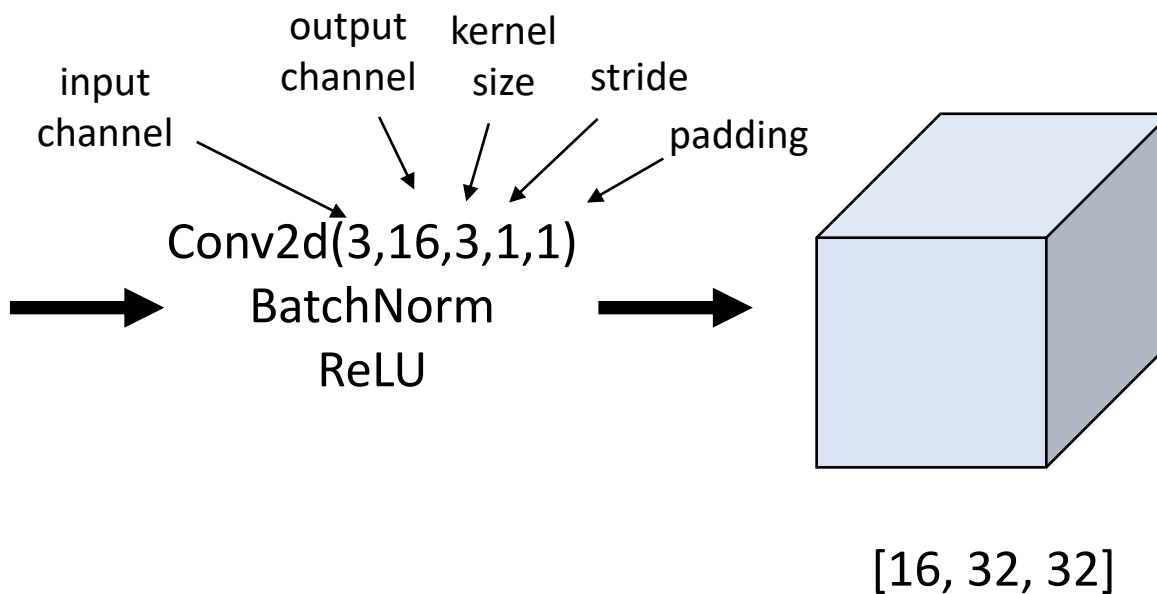
[2. ResNet-32]



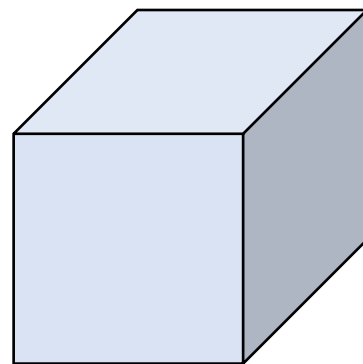
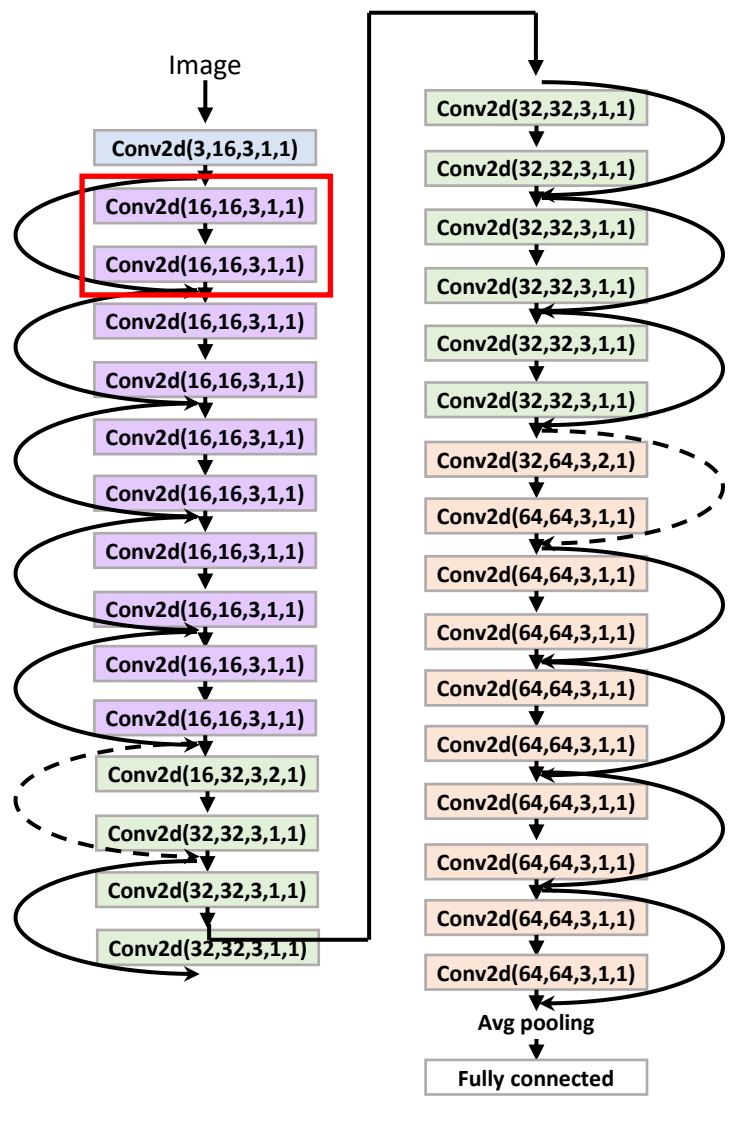
[2. ResNet-32]



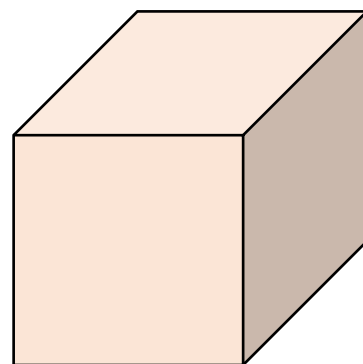
[3, 32, 32]



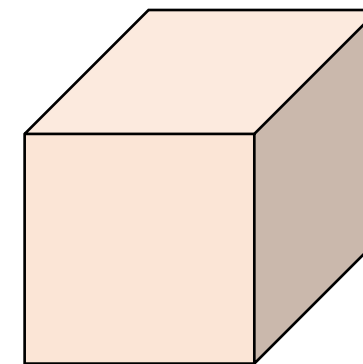
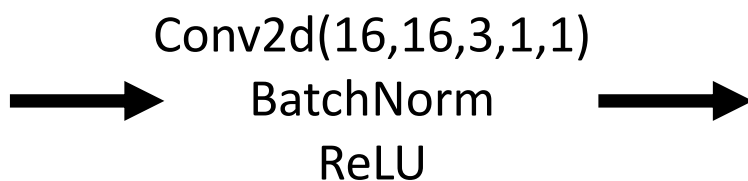
[2. ResNet-32]



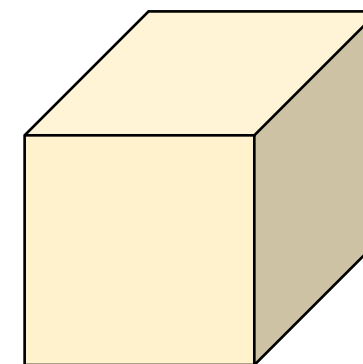
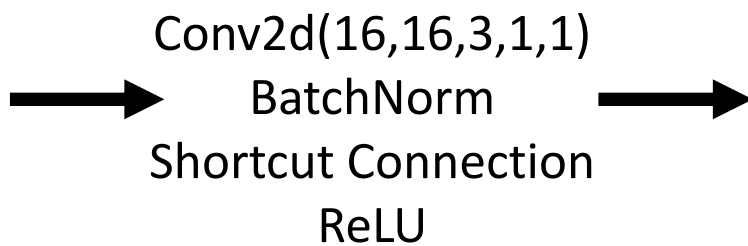
$[16, 32, 32]$



$[16, 32, 32]$

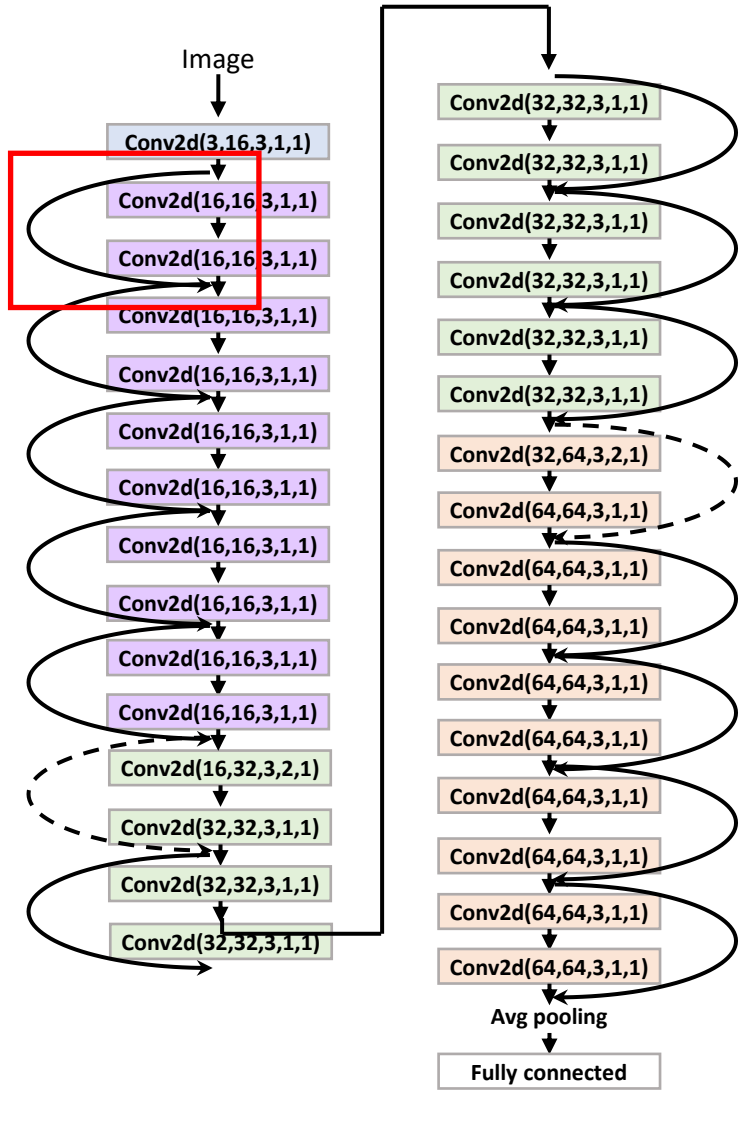


$[16, 32, 32]$

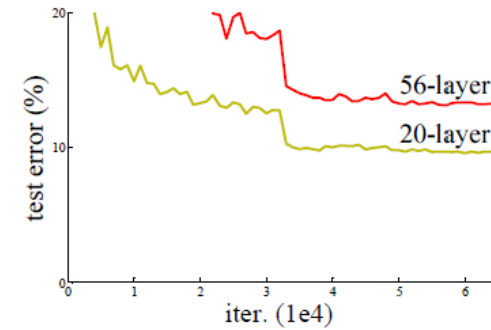
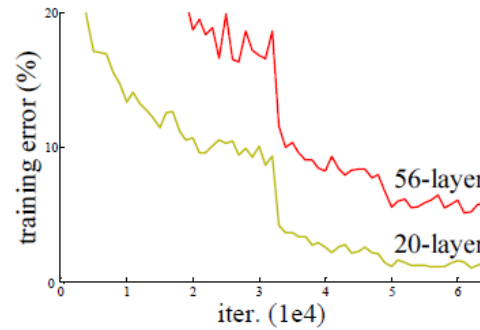


$[16, 32, 32]$

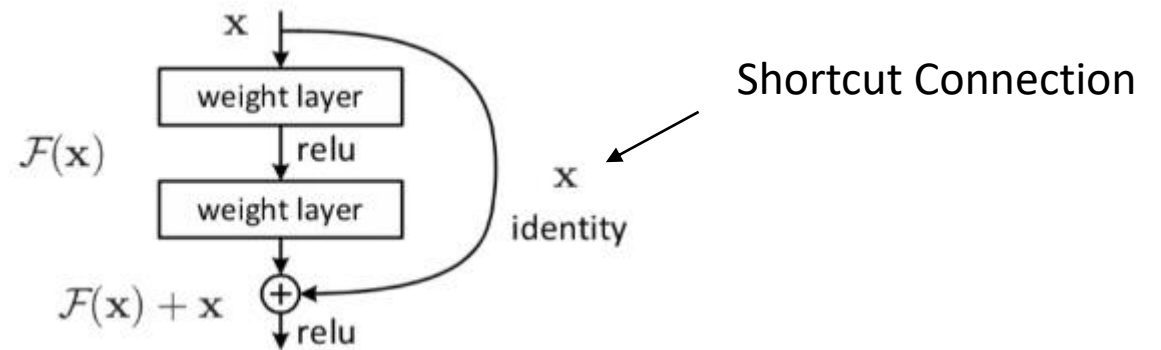
[2. ResNet-32]



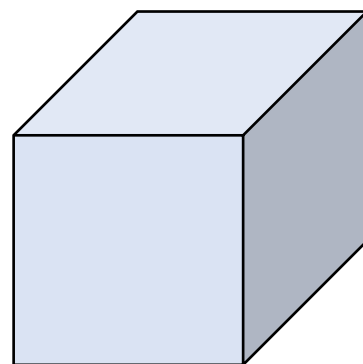
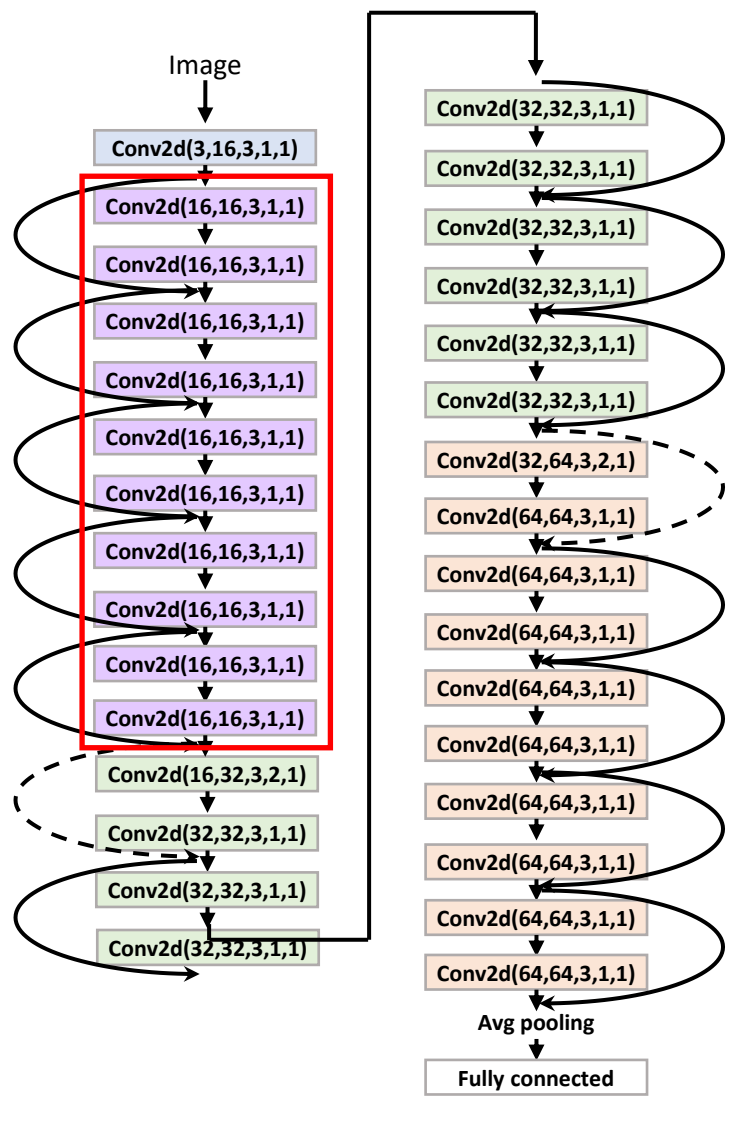
- Deeper network does not gives higher accuracy, Due to Gradient Vanishing and degradation.



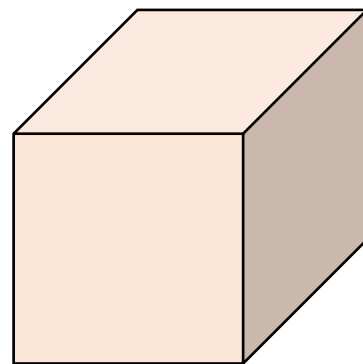
[Residual Learning]



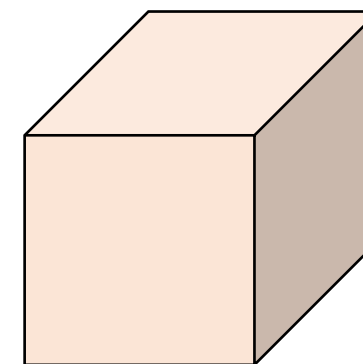
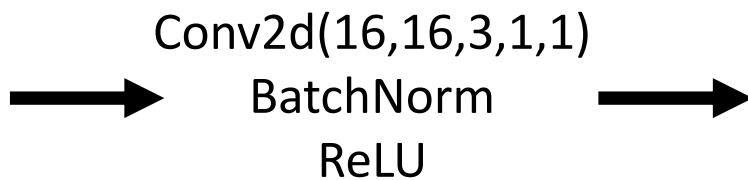
[2. ResNet-32]



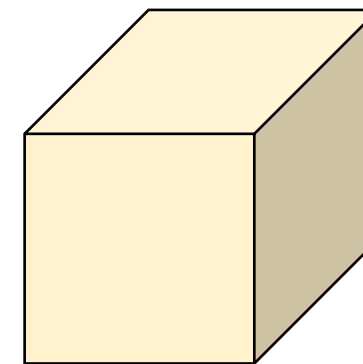
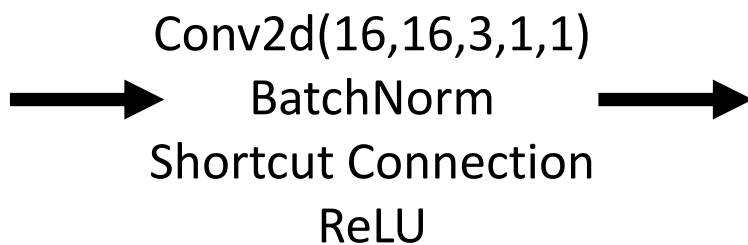
[16, 32, 32]



[16, 32, 32]

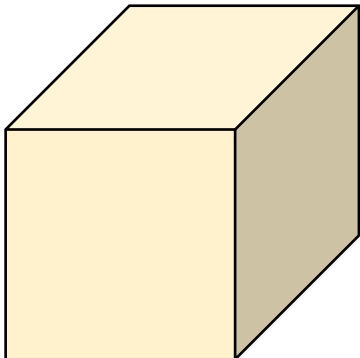
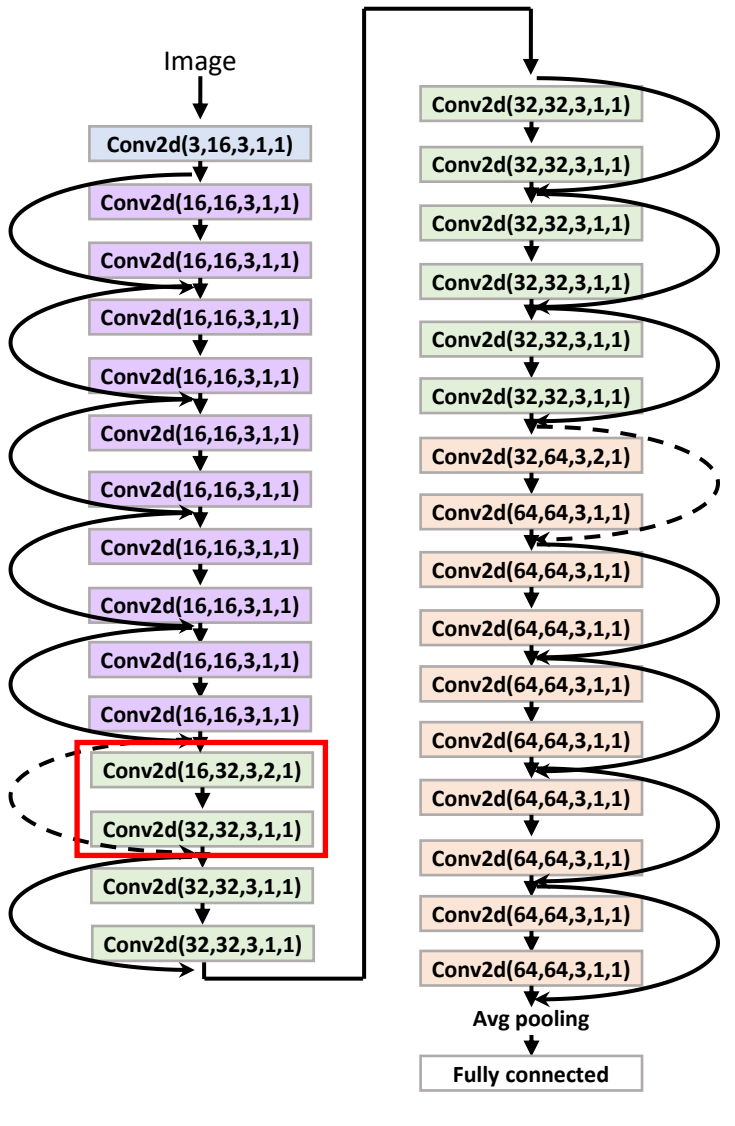


[16, 32, 32]

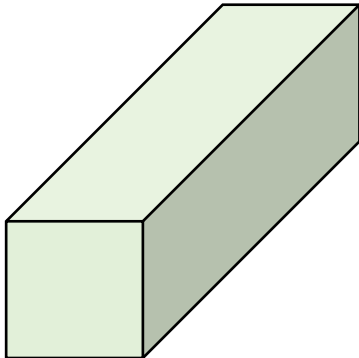


[16, 32, 32]

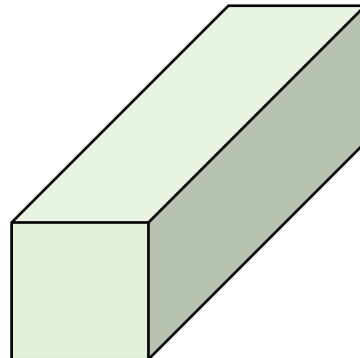
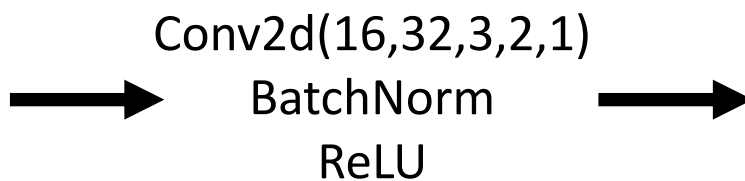
[2. ResNet-32]



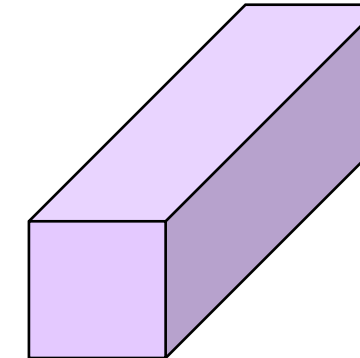
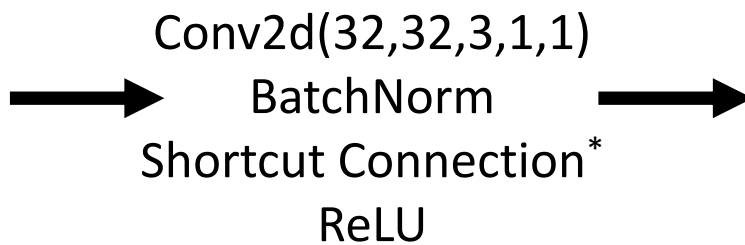
[16, 32, 32]



[32, 16, 16]

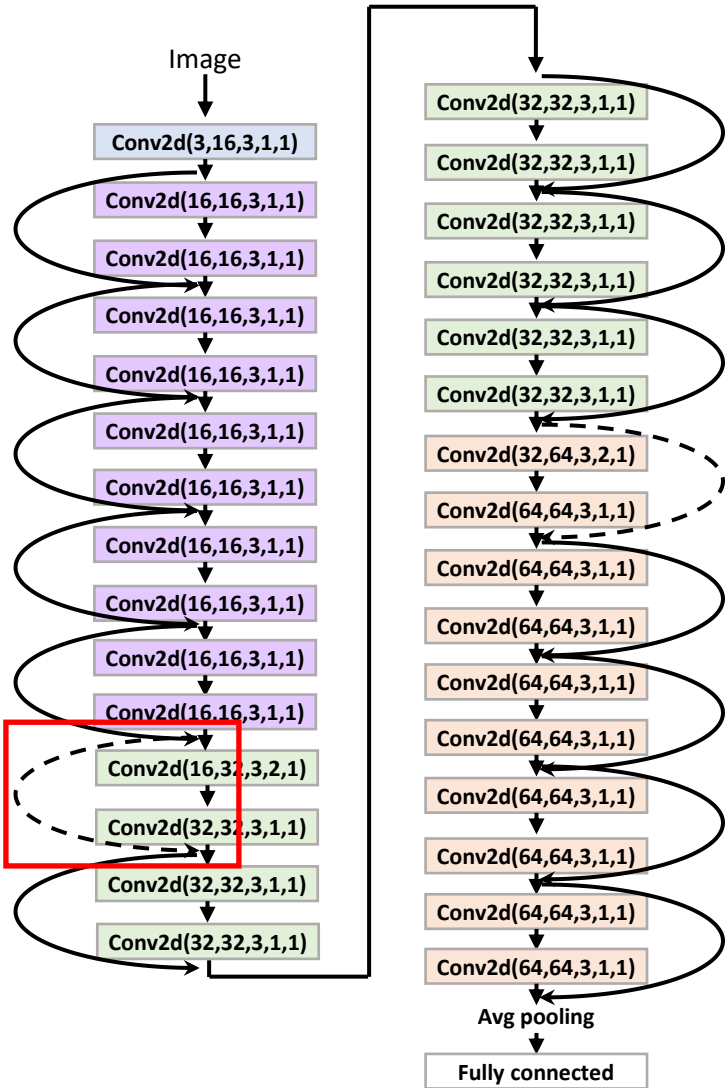


[32, 16, 16]

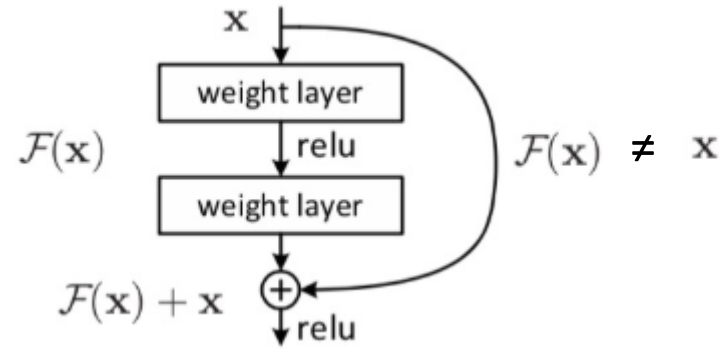


[32, 16, 16]

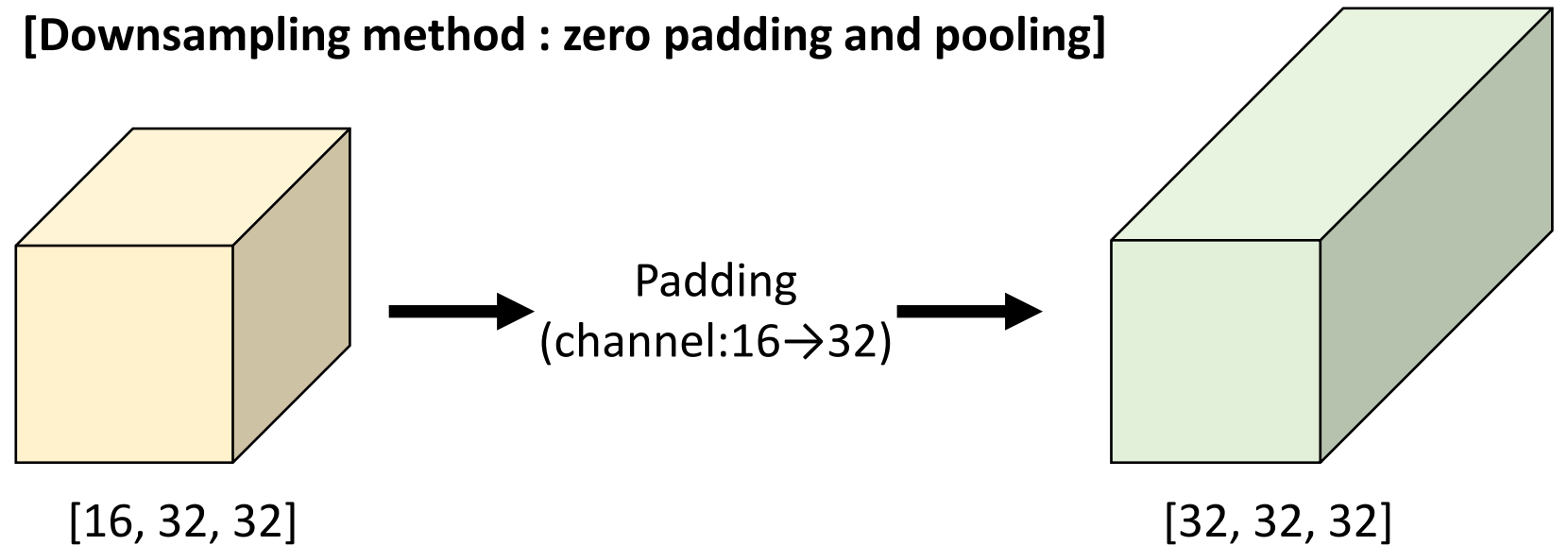
[2. ResNet-32]



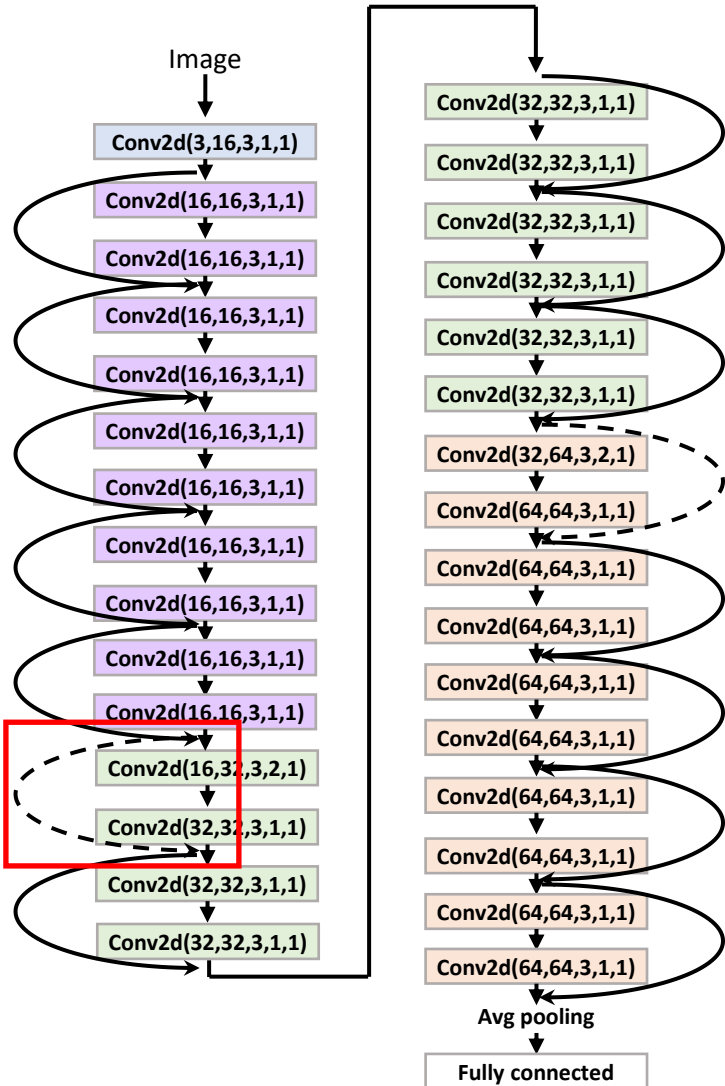
[Shortcut Connection with different shape]



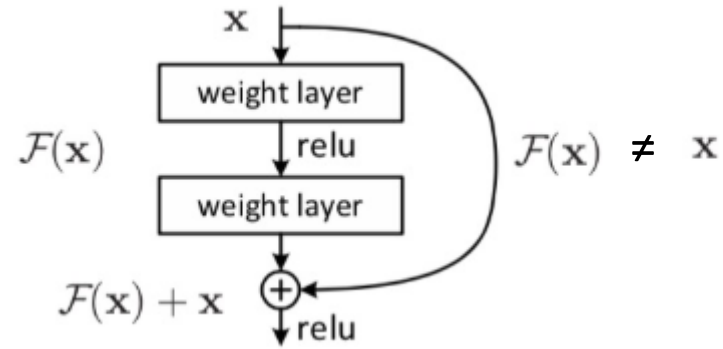
[Downsampling method : zero padding and pooling]



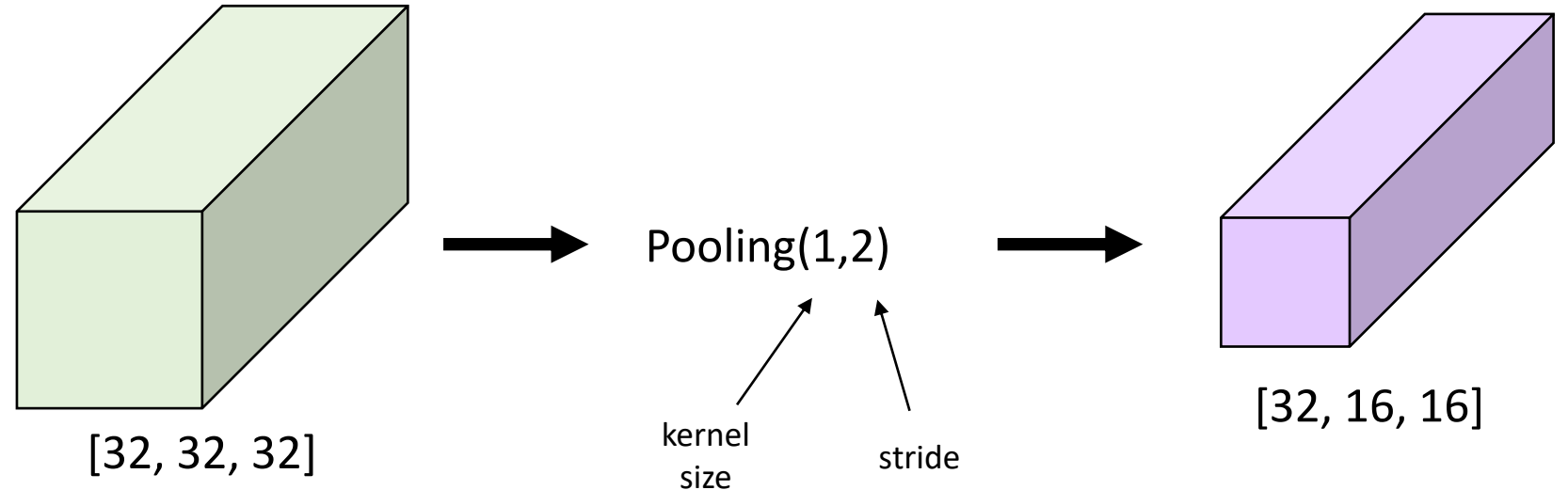
[2. ResNet-32]



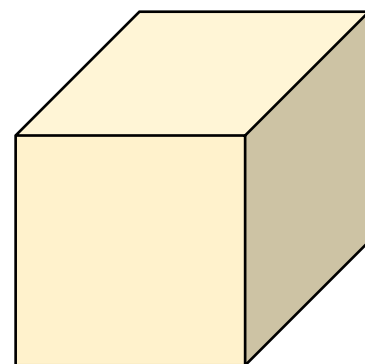
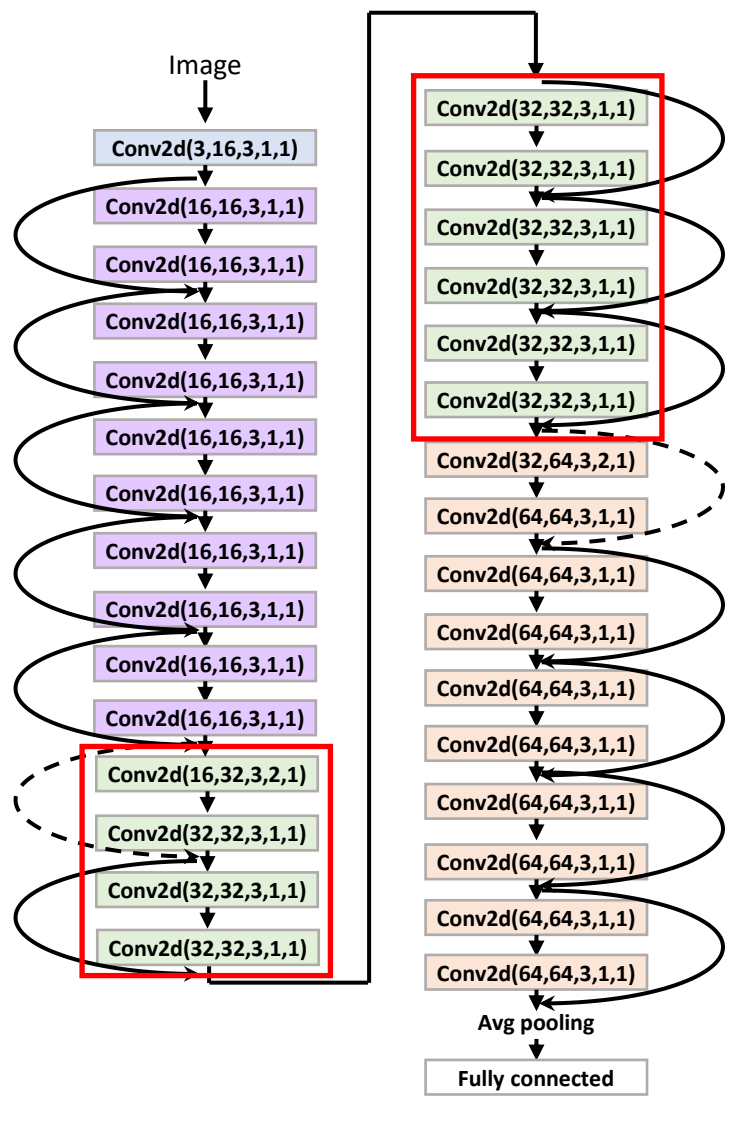
[Shortcut Connection with different shape]



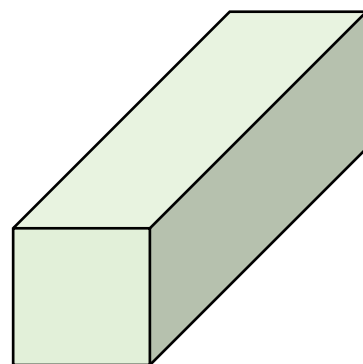
[Downsampling method : zero padding and pooling]



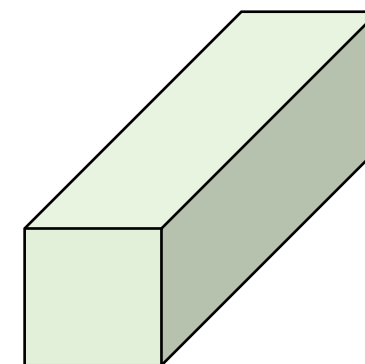
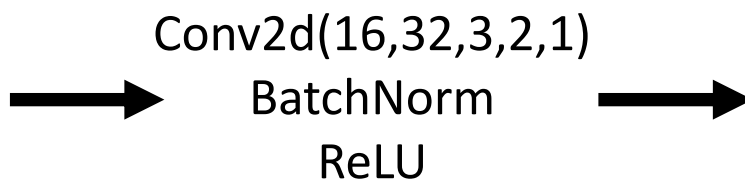
[2. ResNet-32]



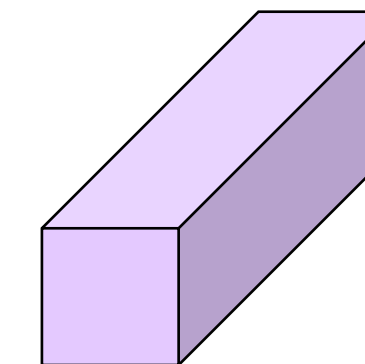
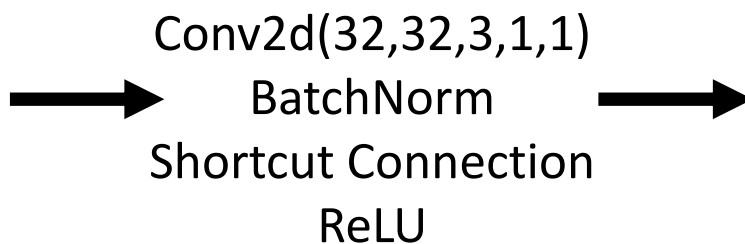
$[16, 32, 32]$



$[32, 16, 16]$

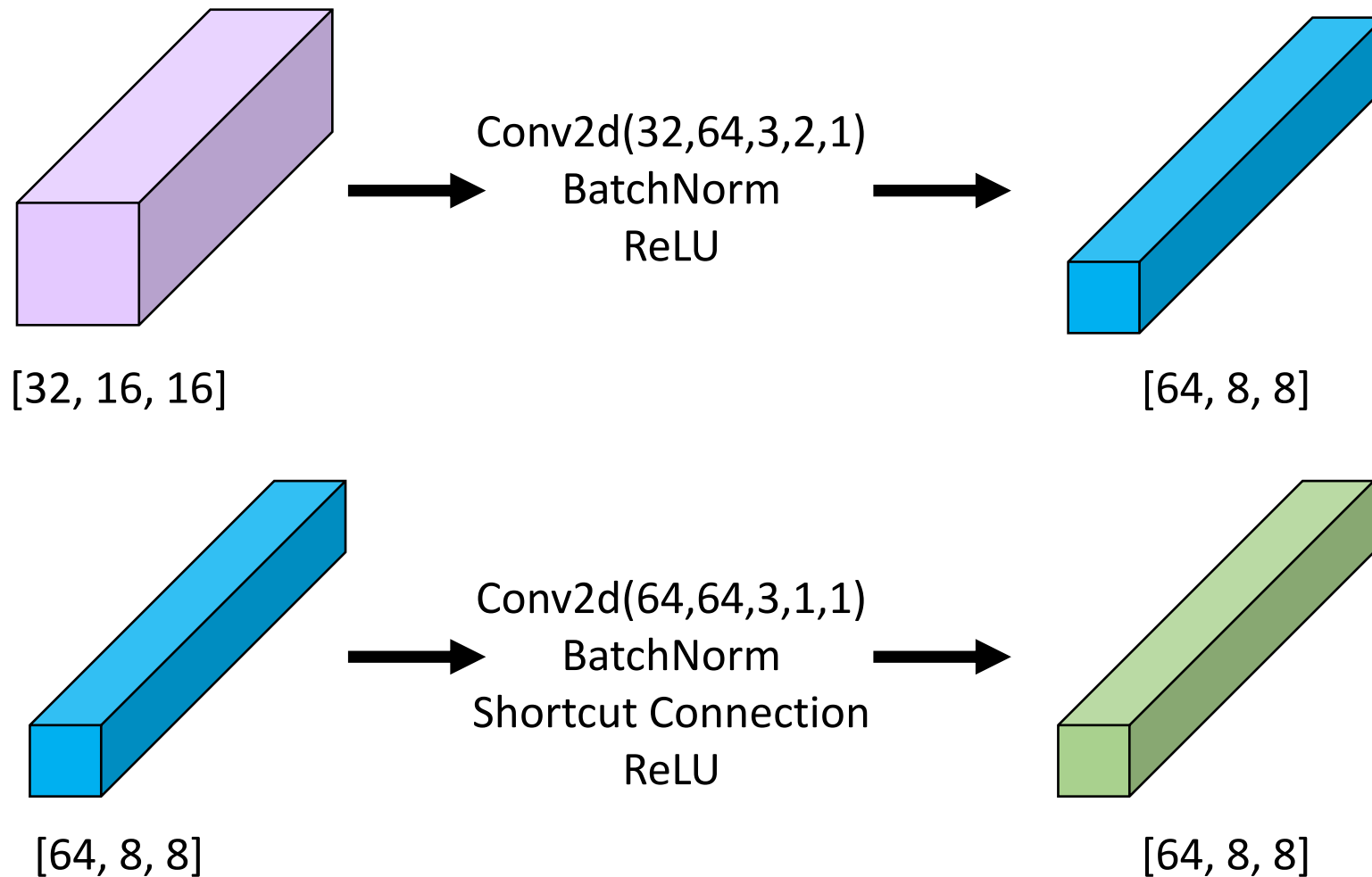
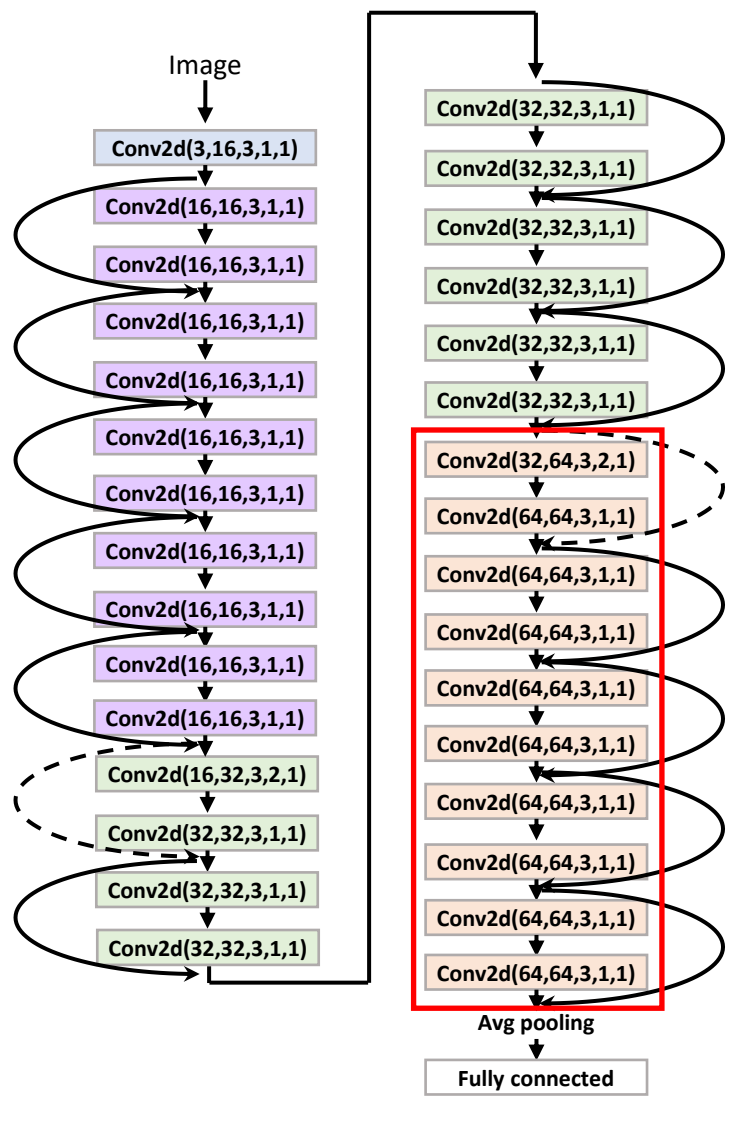


$[32, 16, 16]$

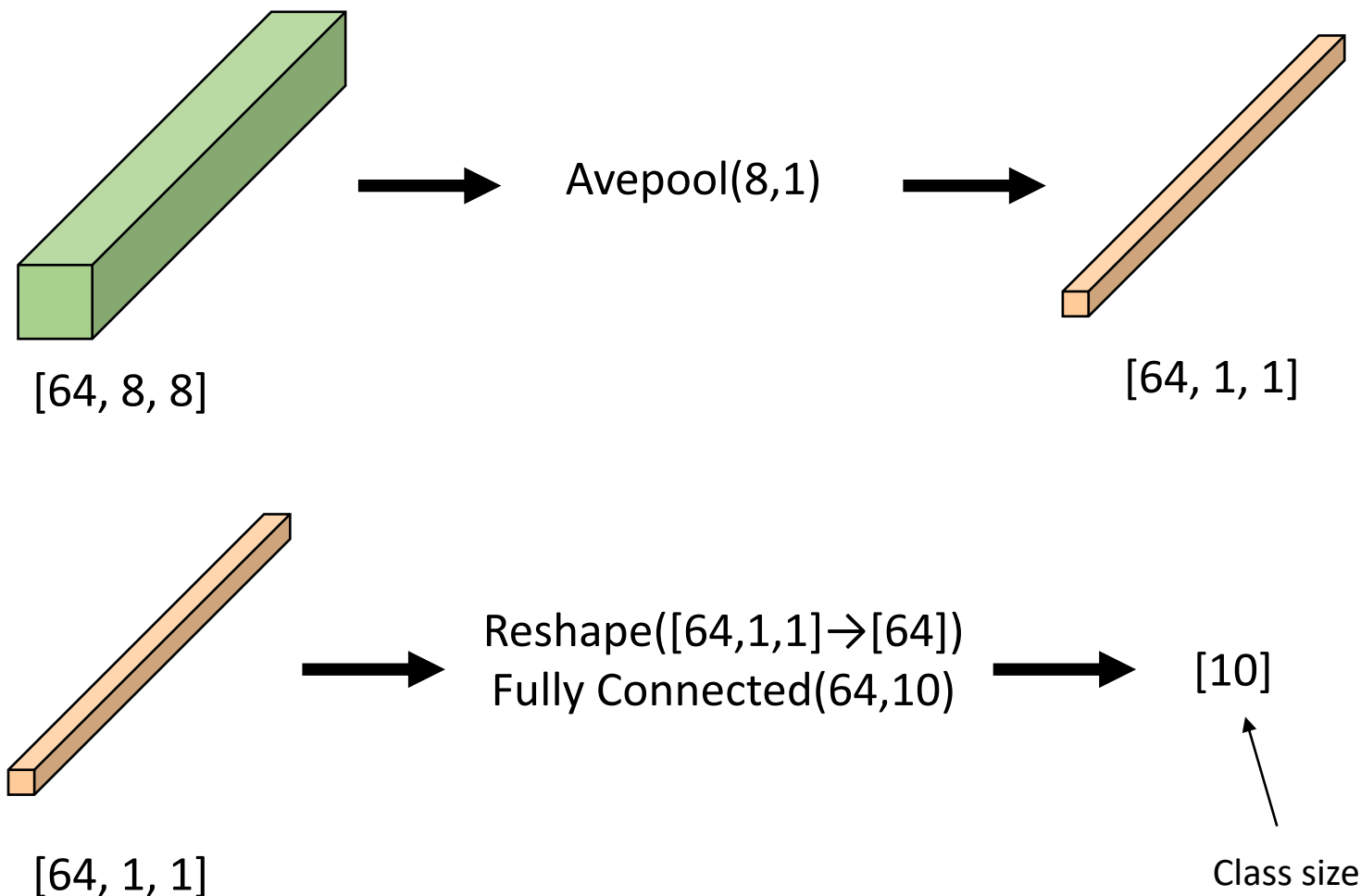
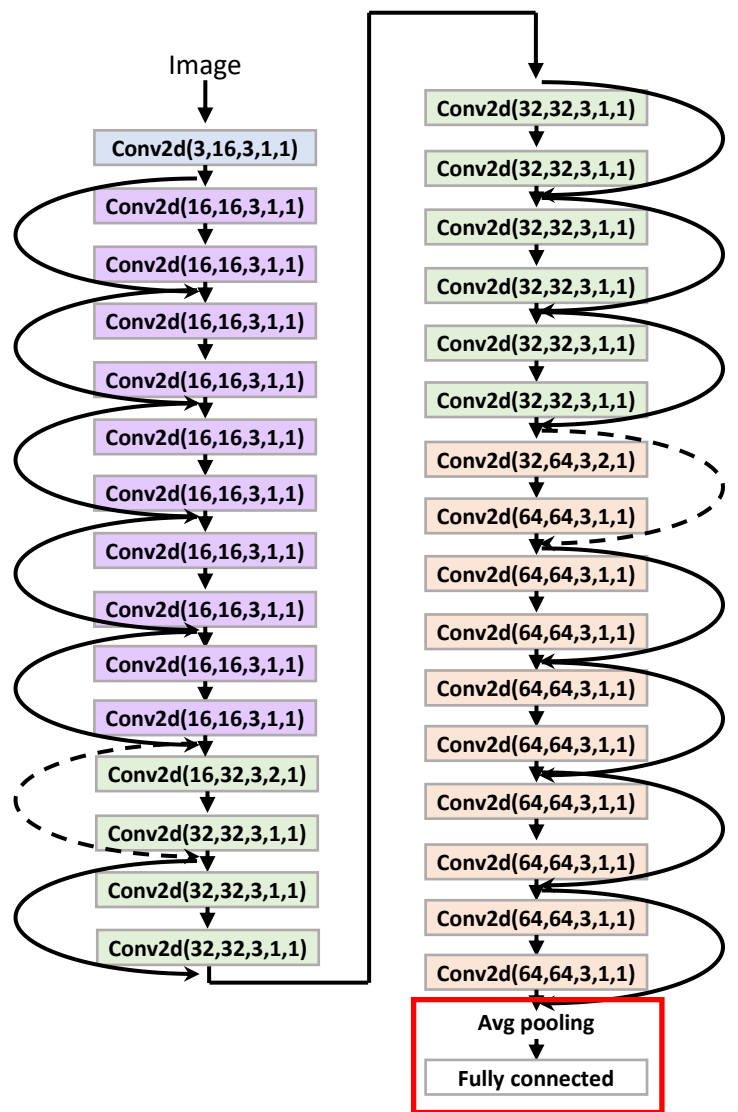


$[32, 16, 16]$

[2. ResNet-32]



[2. ResNet-32]



Code review

[Objective]

Your model should classify the images into 10 classes.

[Classes]

```
classes = ('plane', 'car', 'bird', 'cat', 'deer',  
          'dog', 'frog', 'horse', 'ship', 'truck')
```

[Code structure]

- CIFAR10_configuration.py
- CIFAR10_evaluation.py
- CIFAR10_train.py
- LeNet5_model.py
- MLP_model.py
- ResNet_model.py

[CIFAR10_train.py]

```
def data_load():
    # train data augmentation : 1) 데이터 좌우반전(2배). 2) size 4만큼 패딩 후 32의 크기로 random cropping
    transforms_train = transforms.Compose([
        transforms.RandomCrop(32, padding=4),
        transforms.RandomHorizontalFlip(),
        transforms.ToTensor(),
        transforms.Normalize((0.4914, 0.4822, 0.4465), (0.2023, 0.1994, 0.2010)),
    ])
    transforms_val = transforms.Compose([
        transforms.ToTensor(),
        transforms.Normalize((0.4914, 0.4822, 0.4465), (0.2023, 0.1994, 0.2010)),
    ])

    # CIFAR10 dataset 다운로드
    train_data = datasets.CIFAR10(root='./dataset/', train=True, transform=transforms_train, download=True)
    val_data = datasets.CIFAR10(root="./dataset/", train=False, transform=transforms_val, download=True)

    return train_data, val_data
```

[illegible]

Code review

[MLP_model.py]

[illegible]

Code review

[LeNet5_model.py]

```
import torch
import torch.nn as nn
import torch.nn.functional as F

class LeNet5_model(nn.Module):
    def __init__(self):
        super().__init__()
        #####
        #                TODO : LeNet5 모델 생성                #
        #####
        pass
        #####
        #                END OF YOUR CODE                #
        #####

    def forward(self, x):
        #####
        #                TODO : forward path 수행, 결과를 x에 저장                #
        #####
        pass
        #####
        #                END OF YOUR CODE                #
        #####
        return x
```

Code review

[ResNet32_model.py]

You should find correct number or variable for X1~X10.

```
def forward(self, x):
    x = self.conv1(x)
    x = self.bn1(x)
    x = self.relu(x)
    x = self.layers_2n(x)
    x = self.layers_4n(x)
    x = self.layers_6n(x)
    x = self.pool(x)
    x = x.view(x.size(0), -1)
    x = self.fc_out(x)
    return x
```

```
class ResNet(nn.Module):

    def __init__(self, num_layers, block, num_classes=10):
        super().__init__()
        # input img : [3, 32, 32]
        self.num_layers = num_layers
        self.conv1 = nn.Conv2d(in_channels=X7, out_channels=X8,
                                kernel_size=X9, padding=X10, bias=False)
        self.bn1 = nn.BatchNorm2d(16)
        self.relu = nn.ReLU(inplace=True)

        # feature map size = [16,32,32]
        self.layers_2n = self.get_layers(block, 16, 16, stride=1)
        # feature map size = [32,16,16]
        self.layers_4n = self.get_layers(block, 16, 32, stride=2)
        # feature map size = [64,8,8]
        self.layers_6n = self.get_layers(block, 32, 64, stride=2)

        # output layers
        self.pool = nn.AvgPool2d(8, stride=1)
        self.fc_out = nn.Linear(64, num_classes)

        for m in self.modules():
            if isinstance(m, nn.Conv2d):
                nn.init.kaiming_normal_(m.weight, mode='fan_out', nonlinearity='relu')
            if isinstance(m, nn.BatchNorm2d):
                nn.init.constant_(m.weight, 1)
                nn.init.constant_(m.bias, 0)

    def get_layers(self, block, in_channels, out_channels, stride):
        if stride == 2:
            down_sample = True
        else:
            down_sample = False

        layers_list = nn.ModuleList([block(in_channels, out_channels, stride, down_sample)])

        for _ in range(self.num_layers - 1):
            layers_list.append(block(out_channels, out_channels))

        return nn.Sequential(*layers_list)
```

Code review

[ResNet32_model.py]

You should find correct number or variable for X1~X10.

```
class IdentityPadding(nn.Module):
    def __init__(self, in_channels, out_channels, stride):
        super().__init__()
        self.pooling = nn.MaxPool2d(kernel_size=1, stride=stride)
        self.add_channels = out_channels - in_channels

    def forward(self, x):
        x = F.pad(x, [0, 0, 0, 0, 0, self.add_channels])
        x = self.pooling(x)
        return x
```

```
class ResidualBlock(nn.Module):
    def __init__(self, in_channels, out_channels, stride=1, down_sample=False):
        super().__init__()

        self.conv1 = nn.Conv2d(in_channels, out_channels,
                                kernel_size=X1, stride=X2,
                                padding=X3, bias=False)
        self.bn1 = nn.BatchNorm2d(out_channels)
        self.relu = nn.ReLU(inplace=True)

        self.conv2 = nn.Conv2d(out_channels, out_channels,
                                kernel_size=X4, stride=X5,
                                padding=X6, bias=False)
        self.bn2 = nn.BatchNorm2d(out_channels)
        self.stride = stride
        if down_sample:
            self.down_sample = IdentityPadding(in_channels, out_channels, stride)
        else:
            self.down_sample = None

    def forward(self, x):
        shortcut = x
        x = self.conv1(x)
        x = self.bn1(x)
        x = self.relu(x)

        x = self.conv2(x)
        x = self.bn2(x)

        if self.down_sample is not None:
            shortcut = self.down_sample(shortcut)

        x += shortcut
        x = self.relu(x)
        return x
```


Evaluation Report

CIFAR-10 Evaluation Report													
	Model	GPU(O/X)	Batch_size	Activation function	Weight initialization	Optimizer	Learning rate	Momentum	Weight decay	LR decay	training time (m)	Early stopping epoch	Accuracy
Setting #1	MLP												
Setting #2	Lenet5												
Setting #3	ResNet32		128	ReLU	He_normal	SGD	0.1	0.9	O	O			
Validation dataset accuracy plot													
Setting #1				Setting #2				Setting #3					
[결과 정리]													

Evaluation Report

Fill in these cells.

CIFAR-10 Evaluation Report													
	Model	GPU(O/X)	Batch_size	Activation function	Weight initialization	Optimizer	Learning rate	Momentum	Weight decay	LR decay	training time (m)	Early stopping epoch	Accuracy
Setting #1	MLP												
Setting #2	Lenet5												
Setting #3	ResNet32		128	ReLU	He_normal	SGD	0.1	0.9	O	O			
Validation dataset accuracy plot													
Setting #1				Setting #2				Setting #3					
[결과 정리]													

Evaluation Report

Plot an accuracy plot of the validation dataset for each setting.

CIFAR-10 Evaluation Report													
	Model	GPU(O/X)	Batch_size	Activation function	Weight initialization	Optimizer	Learning rate	Momentum	Weight decay	LR decay	training time (m)	Early stopping epoch	Accuracy
Setting #1	MLP												
Setting #2	Lenet5												
Setting #3	ResNet32		128	ReLU	He_normal	SGD	0.1	0.9	O	O			
Validation dataset accuracy plot													

Setting #1

Setting #2

Setting #3

[결과 정리]

Evaluation Report

CIFAR-10 Evaluation Report													
	Model	GPU(O/X)	Batch_size	Activation function	Weight initialization	Optimizer	Learning rate	Momentum	Weight decay	LR decay	training time (m)	Early stopping epoch	Accuracy
Setting #1	MLP												
Setting #2	Lenet5												
Setting #3	ResNet32		128	ReLU	He_normal	SGD	0.1	0.9	O	O			
Validation dataset accuracy plot													

Setting #1

Setting #2

Setting #3

Summarize the report of each experimental setting.



[결과 정리]

Assignment #3 : CIFAR-10

- **Objective**

Your model should classify the images into 10 classes.

- **Requirements**

1. Implement multi-layer perceptron with Pytorch or Tensorflow.

(Basic Pytorch code is provided)

(Find the best hyperparameters condition)

2. Implement LeNet5 model.

(Find the best hyperparameters condition)

3. Find the correct $X1 \sim X10$ values in ResNet32 model and complete the code.

4. Implement with 3 settings stated in the evaluation report, and report the result of each settings.

5. You should attach the plot of the validation dataset accuracy plot. (implemented in pytorch code)

6. You should report the experimental results.

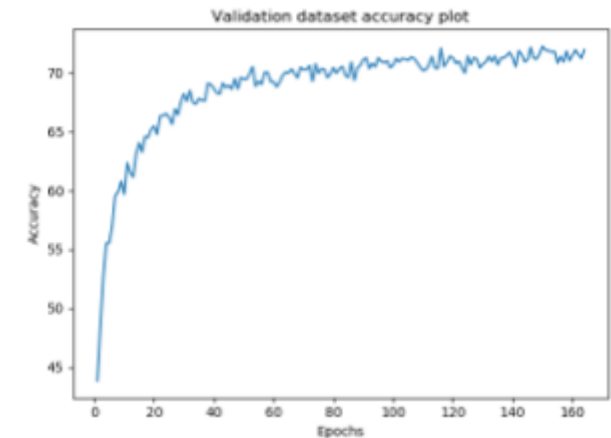
(all kinds of additional experiments are recommended)



↓ model

"Truck"

[Validation dataset accuracy plot]



- **Evaluation Criteria**

Simplicity	How concisely did you write the code?
Performance	How well did the results of the code perform?
Brevity and Clarity	How concisely and clearly did you explain the results?

Assignment #3 : CIFAR-10

- Due to : ~ **5.3(Sun)**
- Submission : Online submission on blackboard
- Your submission should contain
 - 1) The whole code of your implementation
 - 2) The evaluation report
- You must implement the components yourself!
- File name : StudentID_Name.zip

Q & A

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