

NUMERICAL METHODS HOMEWORK 2

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1. The source code is available [here](#). I did it in a script as it was easier for me to work with. I used the following packages: Printf, LaTeXStrings, CairoMakie, HCubature, SphericalHarmonics, LegendrePolynomials, and DifferentialEquations.
 - (a) I use the spherical harmonics package to determine the spherical harmonics and then hcubature to determine the coefficients of the function expansion.

```
expandSphericalHarmonics2(f, l_max) = hcubature(  
  x -> sin(x[1]) * f(x[1], x[2]) .* conj(flattenSHArray(computeYlm(x[1], x[2],  
    l_max = l_max)))  
  , [0, 0], [π, 2 * π]  
)
```

Where I wrote a function to convert the output of spherical harmonic function into a flat array:

```
function flattenSHArray(shArray, l_max)  
  l = 0  
  m = 0  
  coeffVector::Array{ComplexF64} = []  
  for a in 0:l_max * (l_max + 2)  
    push!(coeffVector, shArray[(l, m)])  
    if m == l  
      l+=1  
      m = -l  
    else  
      m+=1  
    end  
  end  
  end  
  coeffVector  
end
```

- (b) I will use these initial conditions for the wave equation:

```
φ₀(θ, φ) = exp( - θ^2 / 0.4);  
ψ₀(θ, φ) = 0;
```

And next I will detail the more technical details of the numerical solver. I wrote this function to differentiate an array of spherical harmonic coefficients from an expansion.

```
function LaplacianSphericalCoefficientsArrays(coeffs)  
  l = 0  
  m = 0  
  coeffVector::Array{ComplexF64} = []  
  for a in coeffs  
    push!(coeffVector, - l * (l + 1) * a) #multiply coefficient by correct  
    factor  
    if m == l  
      l+=1  
    end  
  end  
end
```

```

        m = -l
    else
        m+=1
    end
end
end
coeffVector
end

```

Now we have all the ingredients to write a function that will solve the wave equation:

```

function waveSystem(U)
    half = Int(size(U)[1] // 2)
     $\phi$  = U[begin:half] #split the state vector in two
     $\psi$  = U[half + 1:end]
    vcat( $\psi$ , LaplacianSphericalCoefficientsArrays( $\phi$ )) #concatenate the two
end

function solveWaveEquation( $\phi_0$ ,  $\psi_0$ , N,  $t_0$ ,  $t_1$ )
     $\phi_0$ SphericalCoeffs = expandSphericalHarmonics2( $\phi_0$ , N)[1]; #get expansion of
     $\psi_0$ SphericalCoeffs = expandSphericalHarmonics2( $\psi_0$ , N)[1]; # initial conditions

    alg = DP5()
    U0 = vcat(  $\phi_0$ SphericalCoeffs,  $\psi_0$ SphericalCoeffs) #I solve this with an
    prob = ODEProblem((U,p,t) -> waveSystem(U), U0, ( $t_0$ ,  $t_1$ ))# an integrator from
        a pacakage
    solve(prob, alg)
end

```

As can be seen from the above code I use a solver in the DifferentialEquations package. And do some accounting to keep track of the different arrays for ϕ and ψ . And lastly we need a function that will give us a function from these coefficients:

```

function functionFromSphericalCoefficients(coeffs)
    l = 0
    m = 0
    lmax = 0
    for a in 1:size(coeffs)[1]
        lmax = l
        if m == l
            l+=1
            m = -l
        else
            m+=1
        end
    end
    end
    function f( $\theta$ ,  $\phi$ )
        harmonics = flattenSHArray(computeYlm( $\theta$ ,  $\phi$ , lmax = lmax))
        harmonics' * coeffs
    end
end

```

(c) This part is now easy since we have all the ingredients.

```

 $\phi_0$ ( $\theta$ ,  $\phi$ ) = exp( -  $\theta^2$  / 0.4);
 $\psi_0$ ( $\theta$ ,  $\phi$ ) = 0;
sol = solveWaveEquation( $\phi_0$ ,  $\psi_0$ , lmax, 0, 10)

```

And I use this solution to reconstruct the function for the solution.

```

sizA = Int(size(sol.u[1])[1] / 2)

firstprofileWhole = sol[1][begin:sizA]
myFuncFirst = functionFromSphericalCoefficients(firstprofileWhole)

```

(d) Below are figures of the solution at different times. The plots show the solutions of the wave equations as function of θ for the $\phi = \pi/2$. I found these graphs the easiest to

interpret. I might have gone overboard with the testing—I did five different solutions for cut-offs $l_{\max} = 2, 4, 6, 8, 10$. As Figure 1 shows, in particular the first subfigure, for $l_{\max} = 2$, the expansion does not capture the profile of the initial conditions very well, but the problem can still be evolved and a solution obtained.. As Figure 2 shows, for $l_{\max} = 4$, the motion of the wave is clearer, but there are some ripples in the solution that are not apparent in the true solution. The ripples present for the cut-off $l_{\max} = 4$ slowly become smaller for larger cut-offs, which is indicative of a convergent solution. This coverage can be qualitatively seen by comparing Figures 3, 4 and 5, keeping in mind that the profiles are printed for slightly different times.

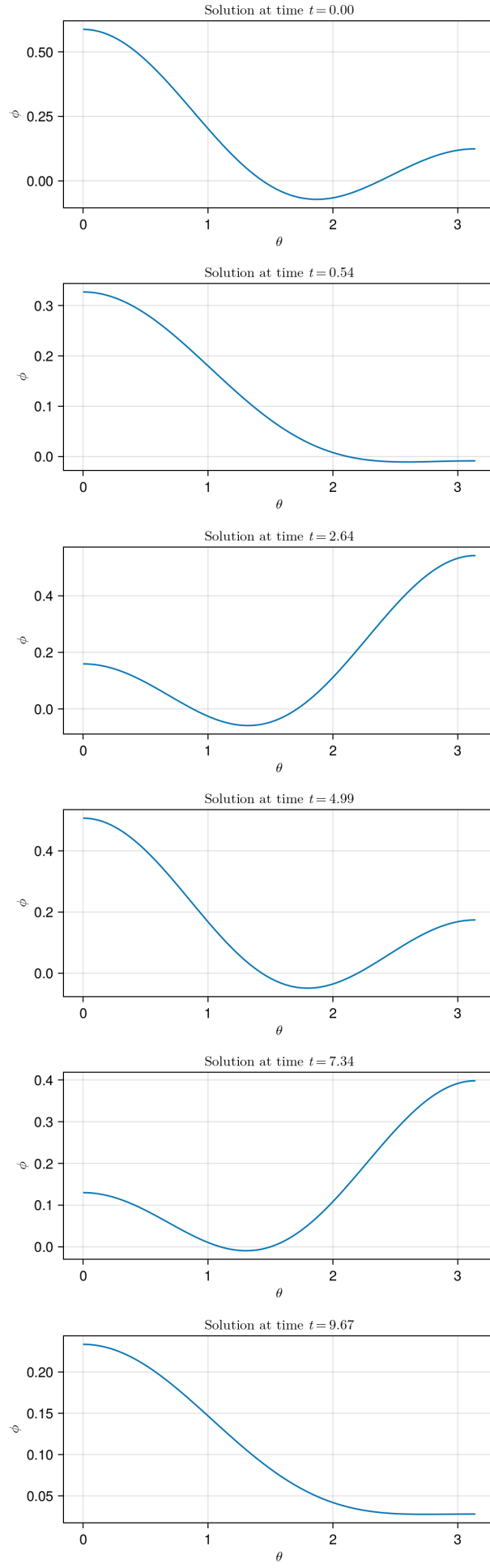


Figure 1: Solution of the wave equation with cut-off $l_{\max} = 2$

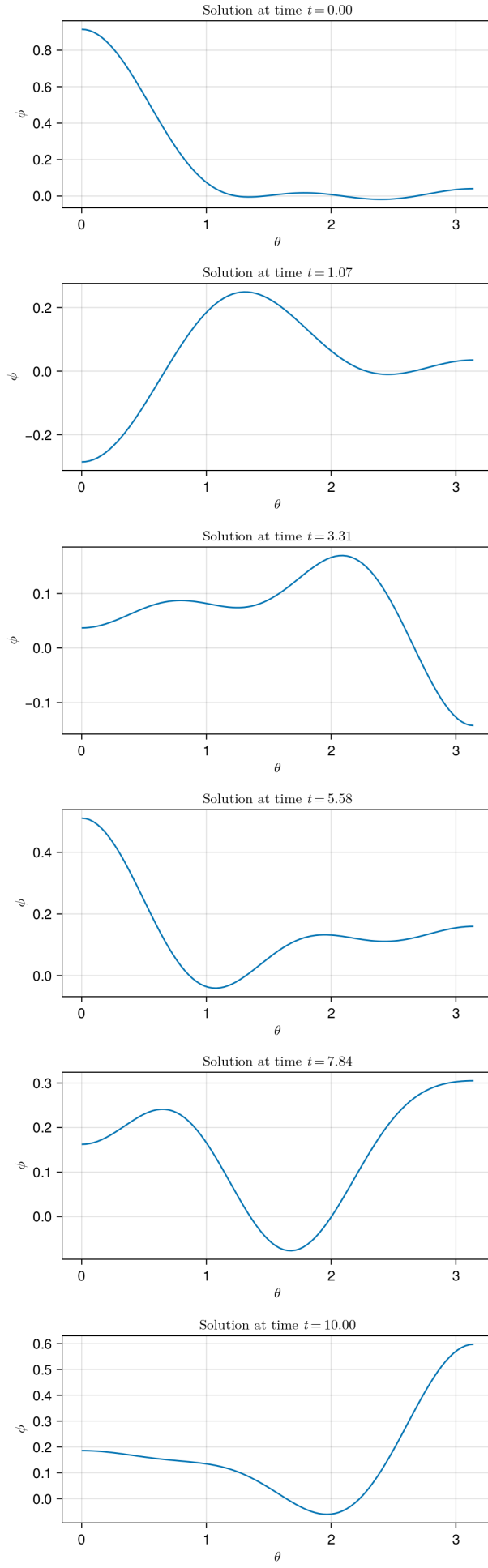


Figure 2: Solution of the wave equation with cut-off $l_{\max} = 4$

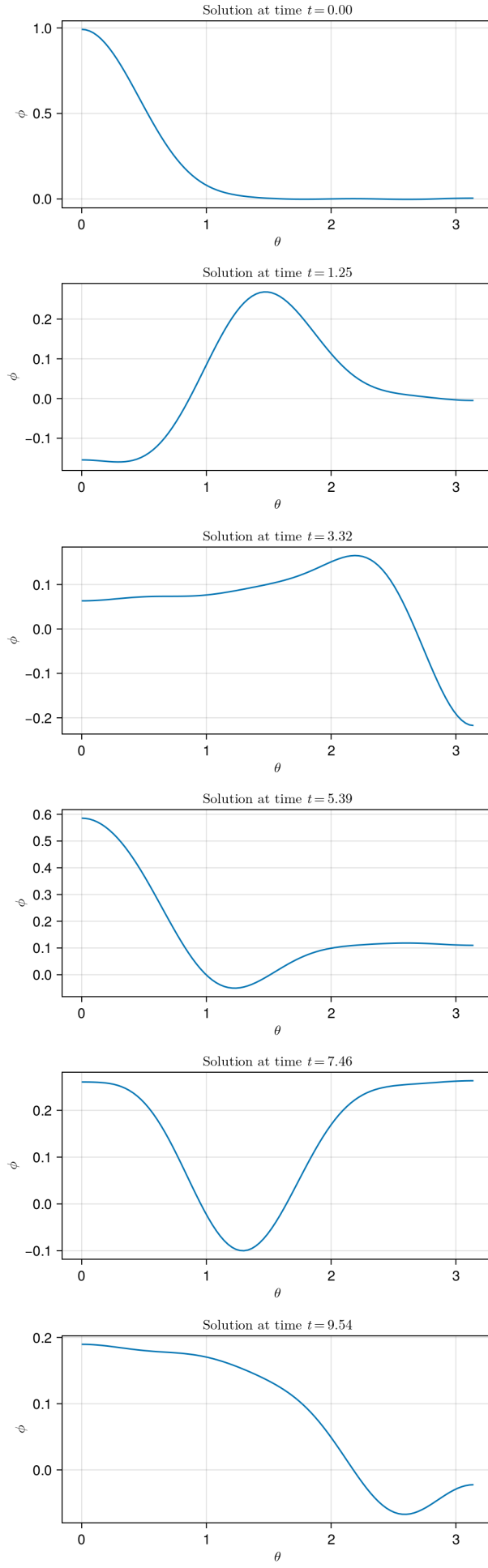


Figure 3: Solution of the wave equation with cut-off $l_{\max} = 6$

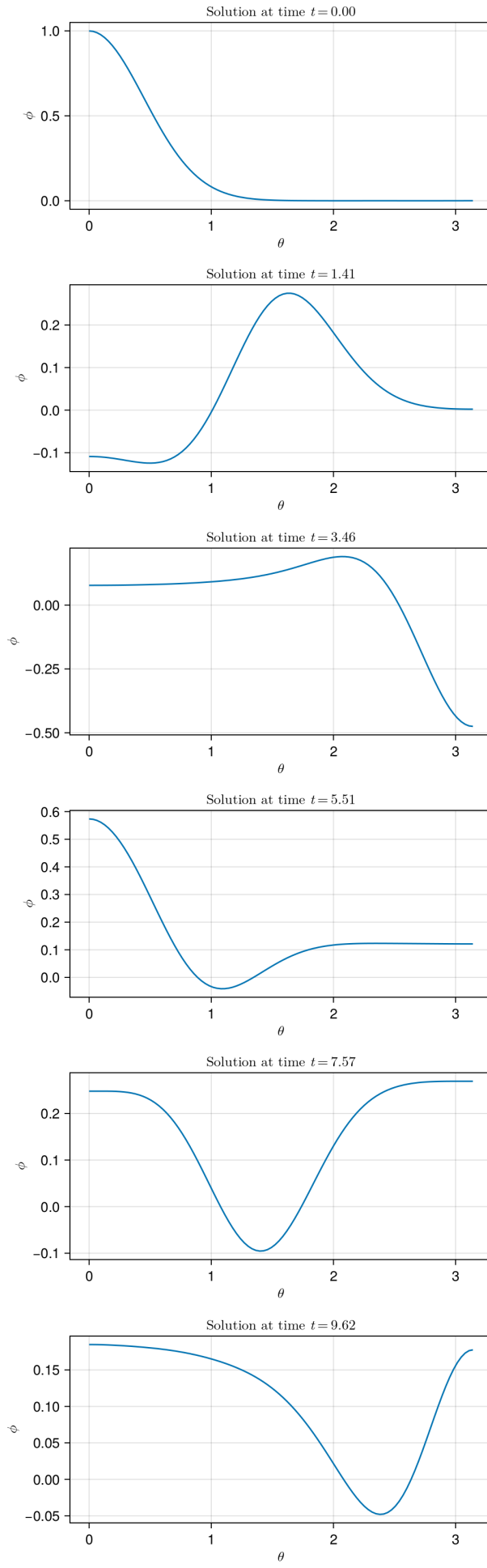


Figure 4: Solution of the wave equation with cut-off $l_{\max} = 8$

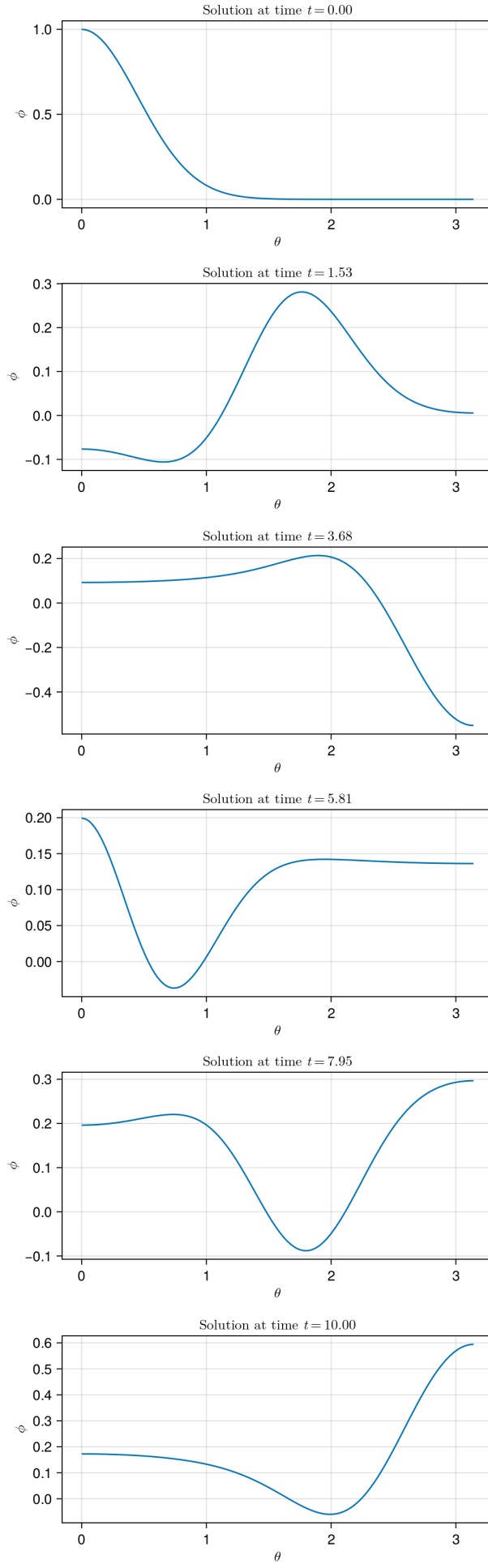


Figure 5: Solution of the wave equation with cut-off $l_{\max} = 10$

2. I also did the heat equation out of interest.

```
function heat(U)
    LaplacianSphericalCoefficientsArrays(U)
end

 $\phi_0(\theta, \phi) = \exp(-\theta^2)$ 
U0 = flattenSHArray(expandSphericalHarmonics2( $\phi_0$ , 15)[1])
prob = ODEProblem((U,p,t) -> heat(U), U0, (0.0, 10.0))

alg = Rodas5(autodiff = false)
solheat = solve(prob, alg);
```

Figure 6 shows the numerical solution of the heat equation with the heat dispersing over the sphere.

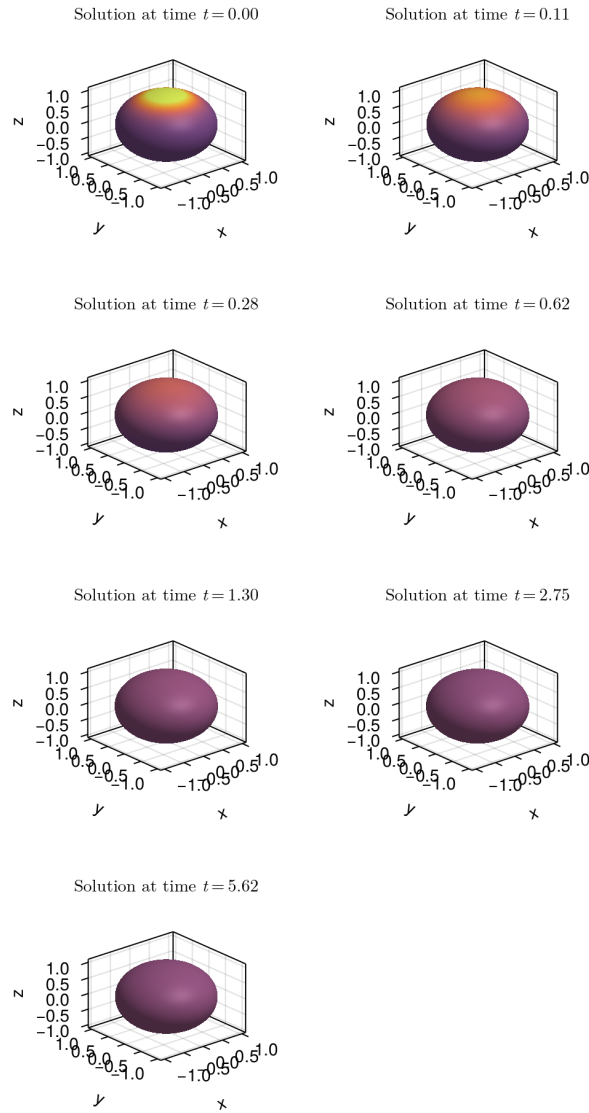


Figure 6: Solution of the heat equation with cut-off $l_{\max} = 15$